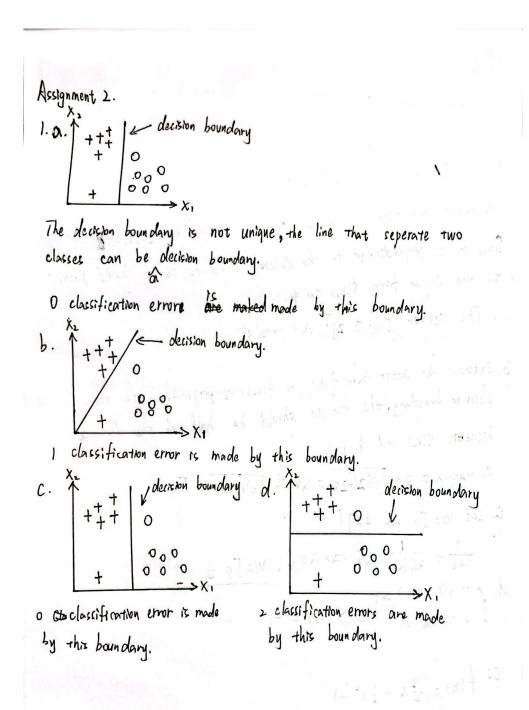
Assignment2 Report

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Contents

Part1: Written Questions



2. α. φ(x,)=[4,0,0]^T, φ(x,)=[1,2,2]^T

A vector from $\phi(x_1)$ to $\phi(x_2)$ can be represent by: $[0,2,2]^T$ Since w is perpendicular to the decision boundary, so it should parallel to the vector from $\phi(x_1)$ to $\phi(x_2)$.

.. The vector [0 2 2] is parallel to w.

b. Because the vector from $\phi(x_i)$ to $\phi(x_i)$ is perpendicular to the decision boundary, the margin should be half of the distance between $\phi(x_i)$ and $\phi(x_i)$.

: margin = 1x 1042 = ME = x 102+22+22 = 12

C. Let W=[0 22 22]].

1 = 1 = 1 = 2 = 2 = 4, W=[0 1 +]T

 $d. \int_{2}^{1} - (0 + w_{0}) = 1$ $1 + w_{0} = 1$ $W_{0} = -1$

e. f(x) = \frac{1}{2}\lambda + \frac{1}{2}\lambda^2 - 1

3. Yes. Since the dataset is linearly soparable, we can always find a hyperplane that separate the data.

That is, the problem min fluxif L.t. 1-yillwix; 4) =0, 4; is feasible and has a

optimal solution w*. Now consider min flux1 + C \(\vec{z}\)\(\vec{

consider its objective flux12+ C \$\frac{1}{2}\is since C > 0. then flux12+ \lambda \frac{1}{2}\is \frac{1}{2}\i

.. The resulting boundary guaranteed to separate the classes.

4.

So We can write it as: max 2,+2,+2,+2,+2,=2,-12,-12,-12,-2,2,-2,24

1.t. -2,-2,+2,+2,+2,=0
2:>0

Then we have:
$$\nabla 3.f = 1-2. -35 = 0$$

$$\nabla 3.f = 1-2. -24 = 0$$

 $W = \frac{\pi}{2} a_i y_i X_i = (-1, -1), b = \frac{1}{4} \frac{\pi}{2} (y_i - w^T x_i) = 0$

.. The sym classifier is fix) = -X1 - X2 for this data set.

(2) The data points with 2 >0 are the support vectors.

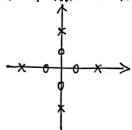
:. The data points (10), (01), (-10), (0-1) are support vectors.

(3) fix=-1-2=-3 <0

:. The label of [1; 2] wis predicted as class -1.

5.

(1) Let first take a look on the graph:



We can see that the data set is not linearly separable. And we can't find such a sym classifier without slack variable to make every points satisfy the constrain $x_{V}(a_{V} - y_{v}) = 0$. So we can not find a sym classifier (with linear kernel, without slack variable) for the data set.

However if we use kernels, we may find one, as we do in the next problem. (plx)= [x12; x2]).

(2) After the expanding, the new data is: class 4: [(1 0)] and closs +1: [(4 p)]

: The olumb problem is: max 2+2, +2, +2, -12, -12, -12, -12, -12, +42,2, +42,2, .

s.t. -2, -2, +2, +2, =0.

2: >0. +:.

 $\nabla 2.f = 1-2.742$, =0 $\nabla 2.f = 1-2.742$ =0 $\nabla 2.f = 1-162.742$ =0

1 Choose pair a, 2, W(a, 2)= 2,+2, - 12, -823 74212, + t - 12 - 1 + 4

And
$$\lambda_1 = \lambda_2 \Rightarrow W(\lambda_1) = \lambda_1 - \frac{9}{2}\lambda_1^2 + constant$$
.

$$\nabla W = 2 - \frac{1}{2}\lambda_1 = 0. \Rightarrow \lambda_1 + \frac{9}{2}\lambda_2^2 = \frac{2}{9}$$

Choose pair 22,24, we can also update that $dx=d4=\frac{4}{9}$

1) Now choose pair 2., 22.

W(0.,21)= 2, +21 - 12, - - 12, - - 122 + 400 \$ \$ 2, + 4 2, + 6 mstant

(, Wa)= # - + 2: - = (4-2) + confort

VW= -1, +(q-2,) =0 → 2, =02 = == 2, 22 dresn4 change

4 Choose, 23, 24:

W(2), 2, 1 = 2, + 2x - 82; -82; + 1/2

1 Choose 3,,24.

 $W_{(21,3k)} = 3.+24 - \frac{1}{6}3.^{\frac{1}{6}} \frac{1}{6}24^{\frac{1}{6}} + \frac{1}{6}2. + \frac{1}{6}24 + constant}$ and 3.=24 $\Rightarrow W_{(21,3k)} = \frac{1}{6}\frac{1}{6}2. - \frac{17}{2}2.^{\frac{1}{6}}$ $\nabla W = 0 \Rightarrow 2.= 2k = \frac{1}{6}. 2.24 \text{ Act change}$ $G \text{ (hoose 22,3s. Also get 21=2s=\frac{1}{6}, 2,3s not change.}$

So now the sequence converge, and we get $\lambda_1 = \lambda_2 = \lambda_3 = \lambda_4 = \frac{1}{9}$, $W = \begin{cases} \frac{4}{5} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{cases} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3$

: The dedision decision boundary is whentb=0 => = x12+3x2+==0.

The SVm is for: withouth = = 1 x1 + 1 x2 4-3.

i The point [1;2] has the function value $f([1;2]) = \frac{1}{1} > 0$. i. We predict it as class: +1.

At the optimal point, we'll have:

$$\nabla a_i f = 1 - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} a_n t_n t_m k(x_n, x_m) - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} a_m t_n t_m k(x_n, x_m)$$

Then, sum all the equations and we can get:

By the stationarity condition of the lagrange function, we have.

11 White W2 = \(\int \int \alpha \an \an \an \tan \tan \kappa (\chi_n, \chi_m).

And we also know that the margin $\gamma = \frac{1}{hwil}$

$$\frac{1}{y^2} = W^2 = \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_n \gamma_m t_n t_m k(\chi_n, \chi_m) = \sum_{n=1}^{N} \alpha_n$$

Part2: Programming Questions

One vs Rest Strategy Implementation

I directly use the OneVsRestClassifier in sklearn package to implement the one vs rest strategy.

Question1

We are solving the linear SVM problem without slack in this question, and we can derive it as following:

The performance of this model on the datasets is: training_error = 0.041666666666666664 and testing_error = 0.0 .

We can know that all the three classes are linearly separable with SVM without slack and we can know it because for each class the SVM problem without slack is feasible which means we can find a linear hyperplane that separate this class with the other two. Hence all the three classes are linearly separable.

Question2

We are solving the linear SVM problem with slack in this question, and we can derive it as following:

```
The performance of this model on the datasets is:
C=0.1:training_error:0.125. testing_error:0.23333333333333333334
C=0.2:training_error:0.05833333333333333334
      testing_error:0.13333333333333333333
C=0.3:training_error:0.05.
                        testing_error:0.1
C=0.4:training_error:0.05.
C=0.5:training_error:0.05.
                        testing_error:0.1
C=0.6:training_error:0.05.
                        testing_error:0.1
                        testing error:0.1
C=0.7:training_error:0.05.
C=0.8:training_error:0.05. testing_error:0.1
                        testing_error:0.06666666666666667
C=0.9:training_error:0.05.
C=1.0:training_error:0.05.
```

Question3

We are solving the linear SVM problem with kernel functions and slack variables in this question, and we can derive it as following:

```
Question 3.
             The only difference between question 2 and 3 is question 3 use a
                      korrel function k(x:,xi) to replace the term Y: TX; in gnestion 2.
                    So we can write a general problem for ghestion 3:
                                Dual: max $\frac{1}{2} ai - $\frac{1}{2} aight \frac{1}{2} \did i di gi yi yi k(xi, xi)
                                                                                               St. हेश्या 20.
                                                                                                                                          0=2i=C, Vi.
                3.(a) The socond-order polynomial kernel: k(x;, X;)= (X; Xí)
                            So we've solving the problem:
                                                                                               max Pai - Paidiyiy; (XiTX;) The state of the control of the contro
   3. (b) The third - order polynomial ternel: k(xi, Xi)= (xi Txi)
            And Wewelte solving: max $\frac{m}{2}; - \frac{m}{2} \dagger_{i,j} \dagger_{i,j} \frac{y}{2} \langle \frac
3.(c) kernel: k(x, xi)=exp(==1|Xi-xi|t), 6=1 3.(d) kernel: k(x, Xi)= 1+exp(-xixi)
       Problem: max (2) - + (3) idjyiy; exp(-+||xi-xj||) G=1, b=0.

S-t. (3) - + (3) idjyiy; exp(-+||xi-xj||) Problem: max (3) idjyiy; exp(-+||xi-xj||)

S-t. (3) idjyiy; exp(-+||xi-xj||)
                                                                                   052160
                                                                                                                                                                                                                                                                                                                                                                                                  0<2; = C. Vi
```

The performance of this model on the datasets is:

- (b) 3rd-order polynomial kernel: training_error:0.025. testing_error:0.0