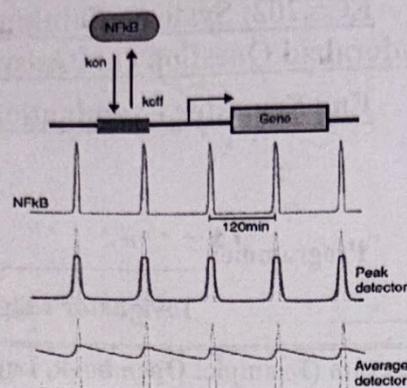


1. NFkB (shown in orange) is a transcriptional factor activating gene G (shown in green). Under what parametric condition, there will be peak detection and average detection. [2 marks]



$k_{on} > k_{off} \rightarrow$ Average detector

$k_{off} > k_{on} \rightarrow$ Peak detector

2. Name the process: [1.5 marks]

- (a) DNA to mRNA: Transcription
(b) mRNA to Protein: Translation
(c) DNA to DNA: Duplication

3. Which of the following forms of human communication are similar to paracrine, endocrine, and synaptic signaling by cells? [1.5 marks]

- (a) A telephone conversation: Synaptic
(b) Talking to people at a cocktail party: paracrine
(c) A radio announcement: endocrine

4. Why NAR is robust compared to a simple system. [2 marks]

$$G(X) \quad X_{ss} = K \iff \frac{dx}{dt} = \beta \cdot \frac{K^n}{K^n + x^n} - \alpha \cdot x$$

K is fixed for the system and it does not change (hardware)

β, α are Variable/noisy

5. A dynamic system is represented by the differential equation [3 marks]

$$\tau \frac{dy(t)}{dt} + y(t) = r(t)$$

The system is given the sinusoidal input $r(t) = \sin \omega t$. The value of ω at which magnitude of the output $y(t)$ is $1/\sqrt{2}$ at steady state, is given by (in terms of τ)

$$\tau s y(s) + y(s) = r(s)$$

$$\Rightarrow y(t) = |G(j\omega)| \cdot \sin(\omega t + \phi)$$

$$G(s) = \frac{y(s)}{r(s)} = \frac{1}{\tau s + 1} = \frac{1}{\sqrt{2}} \sin(\omega t + \phi)$$

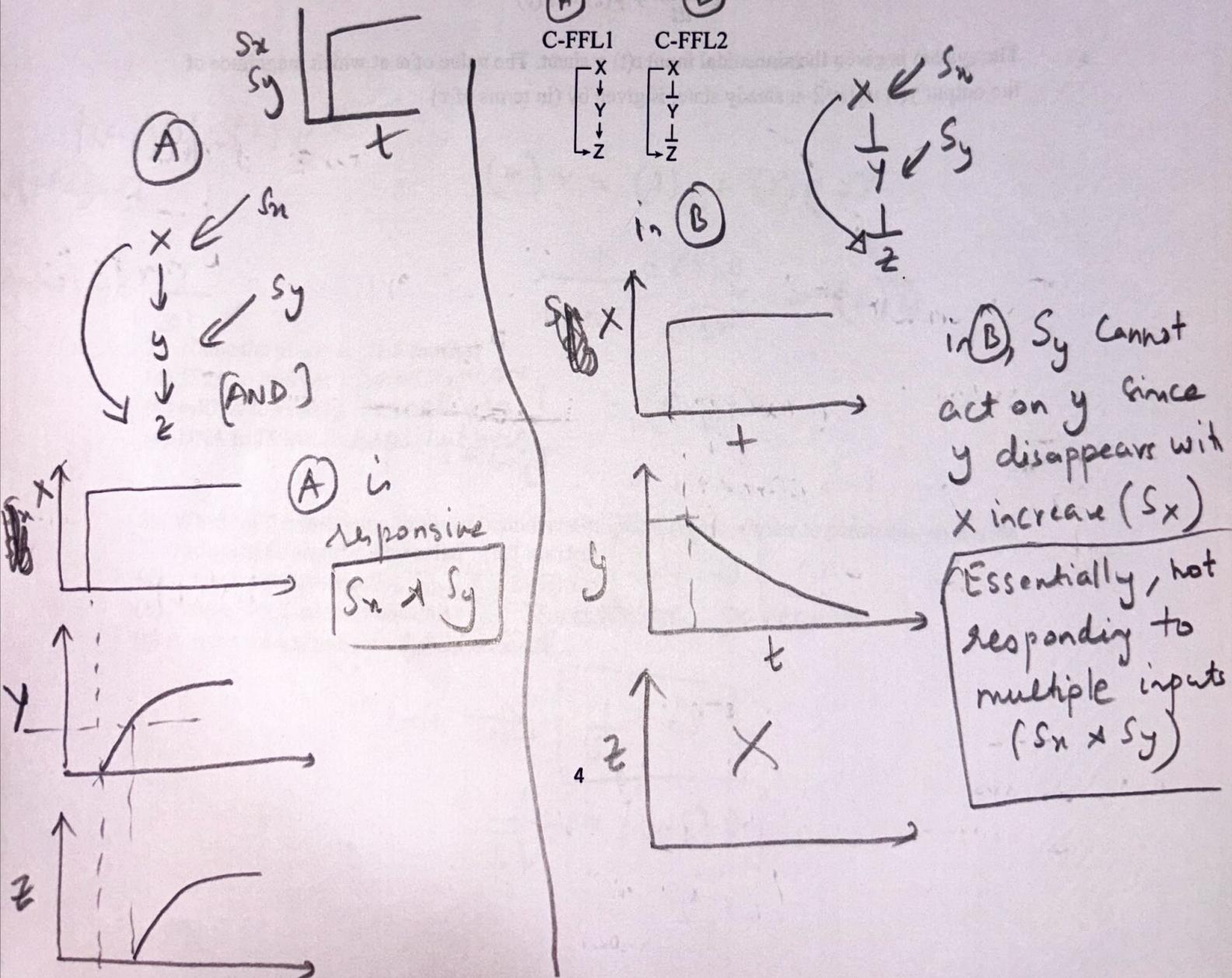
$$G(j\omega) = \frac{1}{\tau j\omega + 1}$$

$$|G(j\omega)| = \frac{1}{\sqrt{\tau^2 \omega^2 + 1}}$$

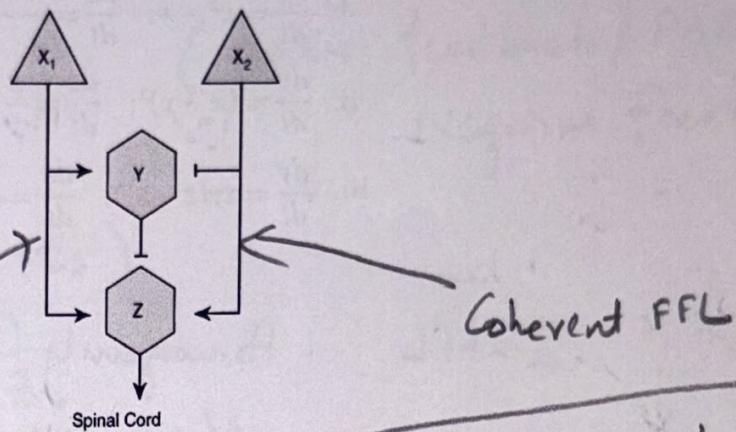
$$\boxed{\omega = \frac{1}{\tau}} \Leftarrow \text{Ans}$$

$$|G(j\omega)| = \frac{1}{\sqrt{2}}$$

6. What might explain the difference in occurrence of C-FFL1 vs C-FFL2 in transcription networks? Draw and explain using S_x and S_y as inputs to the motif. [4 marks]



7. Multi-input circuit occurs in the neurons for human pain sensation (X_1, X_2, Y, Z are neurons). Identify the circuit. This circuit explains why there are two types of pain (say after an insect bite). Explain how the pain works based on the circuit. [4 marks]

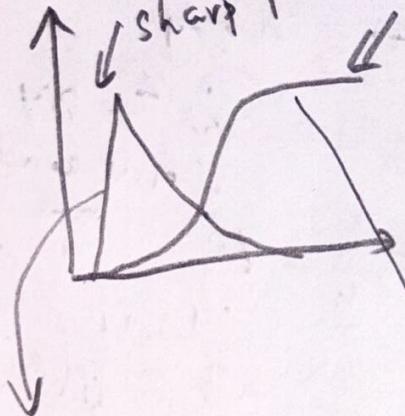


Coherent FFL

Incoherent FFL

sharp pain

continuous
pain
comes with
delay



Circuit explain two types of
Pain

Think what you feel when
Something bites / or
similar situation.

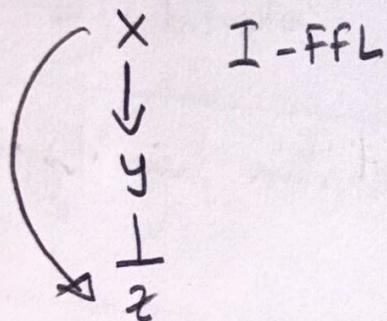
I-FFL
(driven by
neuron X_1)
(plus generator)

C-FFL
(driven by
neuron X_2)
(Sign sensitive
delay)

8. What is the homogeneity condition that you can use to check equations for fold change detection (FCD) property? Which circuits (equation given below) have FCD? The input is x , the internal variable is y and the output is z . Draw each model circuit diagram and comment about it. [6 marks]

- $\frac{dy}{dt} = x^2 - y; \quad \frac{dz}{dt} = \frac{x}{y} - z$
- $\frac{dy}{dt} = (x - y)^2; \quad \frac{dz}{dt} = \frac{x}{y} - z$
- $\frac{dy}{dt} = zy(z - z_0); \quad \frac{dz}{dt} = \frac{x}{y} - z$

i.



Homogeneity Condition for FCD

$$f(\lambda x, \lambda y, z) = \lambda f(x, y, z) \quad \textcircled{1}$$

$$g(\lambda x, \lambda y, z) = g(x, y, z) \quad \textcircled{2}$$

$$\begin{aligned} \cancel{f(\lambda x, \lambda y, z)} &= \cancel{\lambda} y & f(x, y, z) &= x^2 - y \\ & & f(\lambda x, \lambda y, z) &= \lambda x^2 - \lambda y \quad \textcircled{X} \\ & & & \text{(First condition not satisfied)} \end{aligned}$$

$$\frac{dy}{dt} = f(x, y, z)$$

$$\frac{dz}{dt} = g(x, y, z)$$

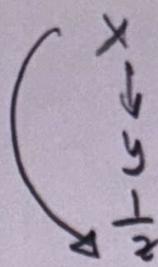
$$g(x, y, z) = \frac{x}{y} - z$$

$$g(\lambda x, \lambda y, z) = \frac{\lambda x}{\lambda y} - z = g(x, y, z)$$

Not a FCD circuit since $\textcircled{1}$ is not satisfied

$$\text{ii) } f(x, y, z) = (x - y)^2$$

$$g(x, y, z) = \frac{x}{y} - z$$



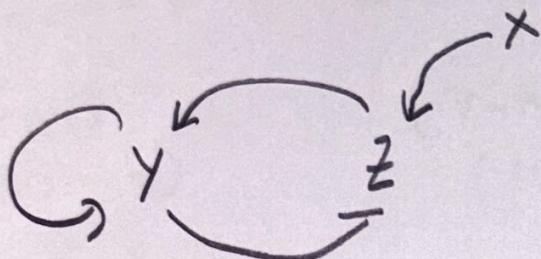
I - FFL

$$f(\lambda x, \lambda y, z) = (\lambda x - \lambda y)^2 \quad (1 \text{ is not satisfied})$$

$$g(\lambda x, \lambda y, z) = \frac{\lambda x}{\lambda y} - z = g(x, y, z) \quad (2 \text{ is satisfied})$$

Not F&D

(iii)



Amplified Negative feedback loop
(positive feedback / PAR +
negative feedback)

$$f(x, y, z) = zy(z - z_0)$$

$$g(x, y, z) = \frac{x}{y} - z$$

$$f(\lambda x, \lambda y, z) = \lambda zy(z - z_0) = \lambda f(x, y, z) \quad \checkmark$$

$$g(\lambda x, \lambda y, z) = \frac{\lambda x}{\lambda y} - z = g(x, y, z) \quad \checkmark$$

F&D Condition Satisfied

9. Show that the model given below exhibit periodic behaviour.

[8 marks]

$$\frac{dU}{dt} = U(1 - V)$$

$$\frac{dV}{dt} = \alpha V(U - 1)$$

α is a kinetic parameter (analyze the eigen values). Draw the circuit and phase plane. Why this model shows periodic behaviour? How this circuit can be modified to do FCD with respect to S input (no FFL strategy)?

(a)

$$J = \begin{bmatrix} \frac{\partial f}{\partial u} & \frac{\partial f}{\partial v} \\ \frac{\partial g}{\partial u} & \frac{\partial g}{\partial v} \end{bmatrix} = \begin{bmatrix} 1-v & -u \\ \alpha v & \alpha u - \alpha \end{bmatrix}$$

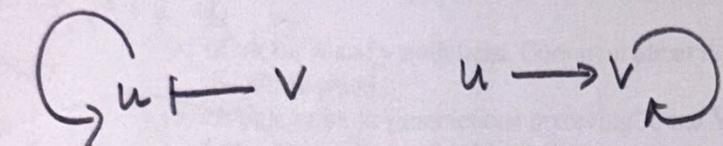
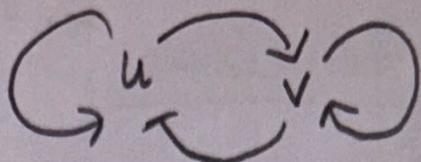
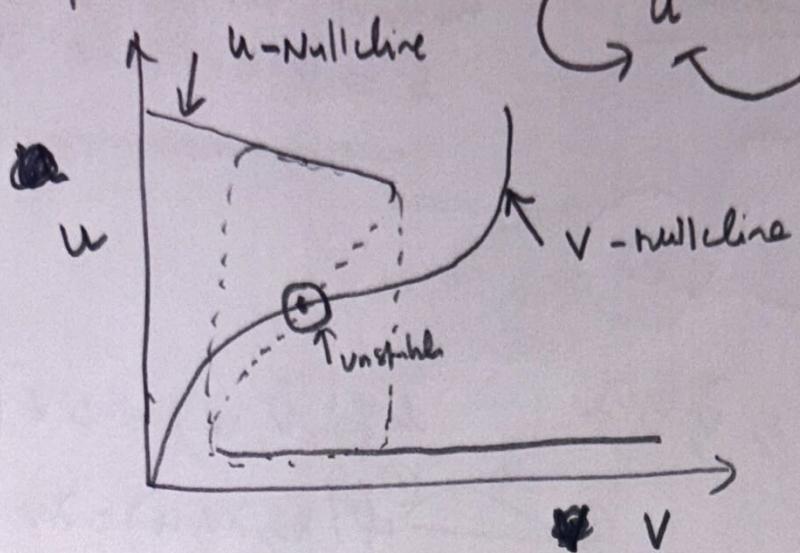
$$[u, v]_{ss} = [1, 1] = \begin{bmatrix} 0 & -1 \\ \alpha & 0 \end{bmatrix}_{(1,1)} \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

(eigen values)

$$\lambda_1 = \frac{a+d \pm \sqrt{(a+d)^2 - 4(ad-bc)}}{2} = 0 \pm \sqrt{0 - 4(0 - (-\alpha))}$$

Eigen Values are imaginary
So periodic ($\alpha > 0$) = $\frac{\sqrt{-4\alpha}}{2}$

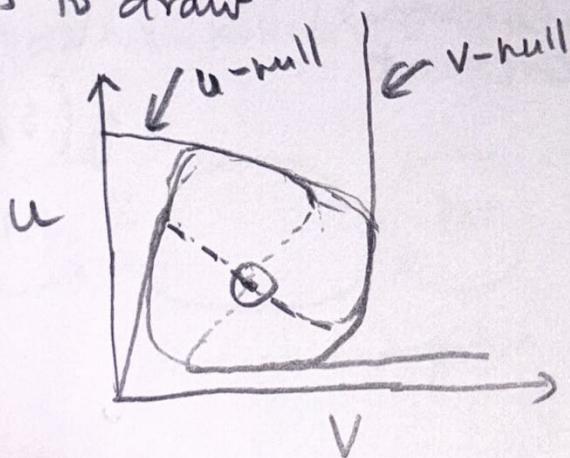
b) Phase plane



$(u\text{-null})$
(Bistable)

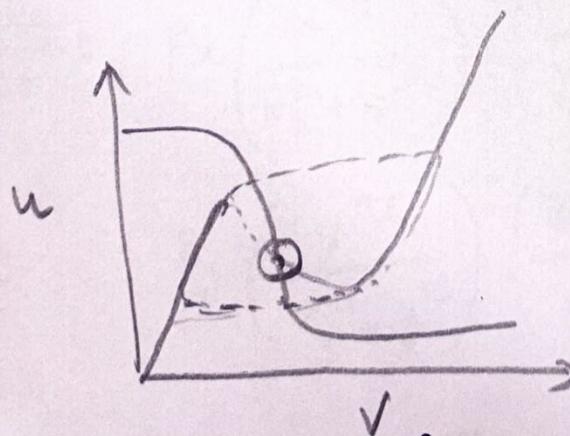
$(v\text{-null})$
(switch-like)

Other ways to draw



$u\text{-null}$
(bistable)

$v\text{-null}$
(Bistable)



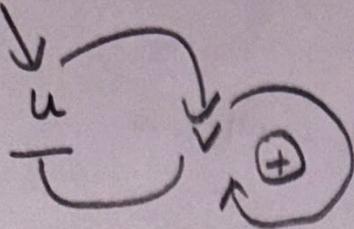
$u\text{-null}$
(switch)

$v\text{-null}$
(Bistable)

Check → They may have changed x -axis or y -axis \Rightarrow so
phase plane will be tilted accordingly

(C)

Modifications for FCD . Remove NAR from u
s will activate u



$$\frac{dv}{dt} = f(s, v, u)$$

$$f(s, v, u) = \alpha v(u-1)$$

$$\frac{du}{dt} = g(s, v, u)$$

$$\begin{aligned} f(\lambda s, \lambda v, u) &= \lambda v \cdot \alpha(u-1) \\ &= \lambda f(s, v, u) \end{aligned}$$

$$g(\lambda s, v, u) = \frac{s}{v}(1-u)$$

$$= \frac{\lambda s}{\lambda v} = (1-u)$$

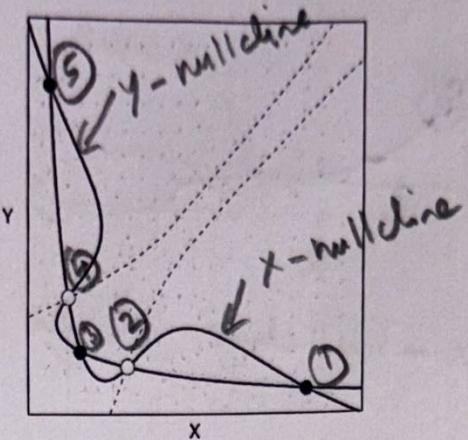
$$= g(s, v, u)$$

This eqn is
Changed
accordingly
from the given
equation otherwise
no FCD

FCD Conditions
are met

10. A phase-plane diagram is given below.

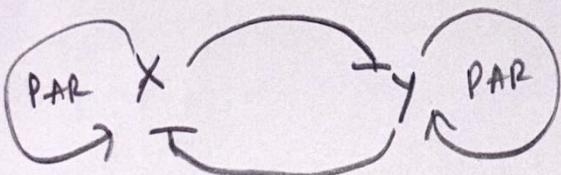
[8 marks]



- (a) Mark the x and y nullclines. Comment about the shape of the nullclines, steady states and the phase plane.
- (b) Design a circuit (interactions involving X and Y) that can give rise to this phase plane.
- (c) Write the equations for this circuit.
- (d) How can we change the phase plane to obtain only three stable steady states?

(a) ①, ③, ⑤ stable, ②, ④ unstable
 Both x-nullcline & y-nullcline are bistable

(b)



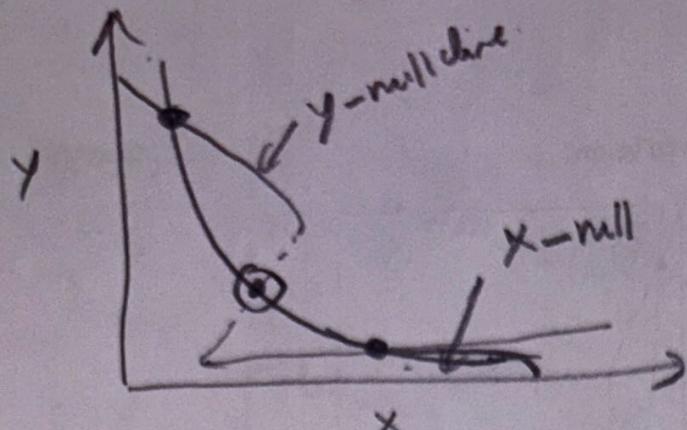
Mutual antagonism.

(c)

$$\frac{dx}{dt} = \beta_x \left(\frac{x^{n_1}}{K_{x1}^{n_1} + x^{n_1}} \right) \left(\frac{\frac{K_{ix}}{y^{n_2}}}{y^{n_2} + K_{ix}^{n_2}} \right) - d_x \cdot x$$

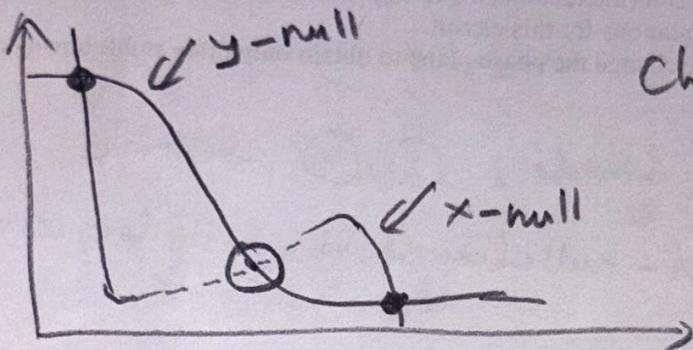
$$\frac{dy}{dt} = \beta_y \left(\frac{y^{n_2}}{K_{y2}^{n_2} + y^{n_2}} \right) \left(\frac{\frac{K_{iy}}{x^{n_1}}}{x^{n_1} + K_{iy}^{n_1}} \right) - d_y \cdot y$$

(d) =



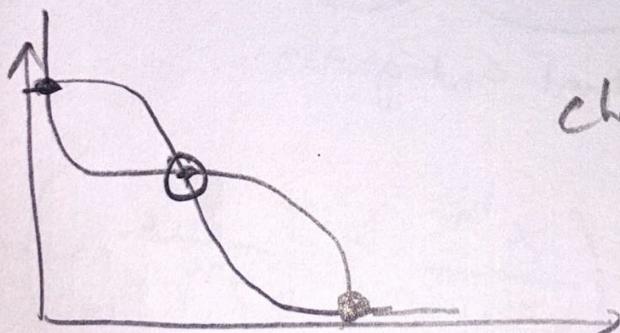
Changing x-nullcline Shape

OR



Change y-nullcline
Shape

OR



changing both x & y
nullclines
Shape