

# Artificial Intelligence Machine Learning – Neural Networks/Deep learning Luís Paulo Reis

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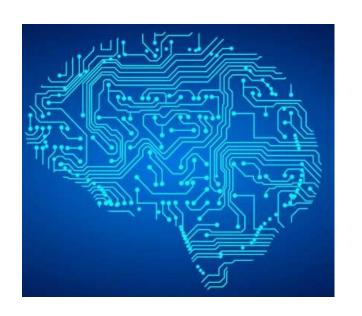
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**President of APPIA – Portuguese Association for Artificial Intelligence** 



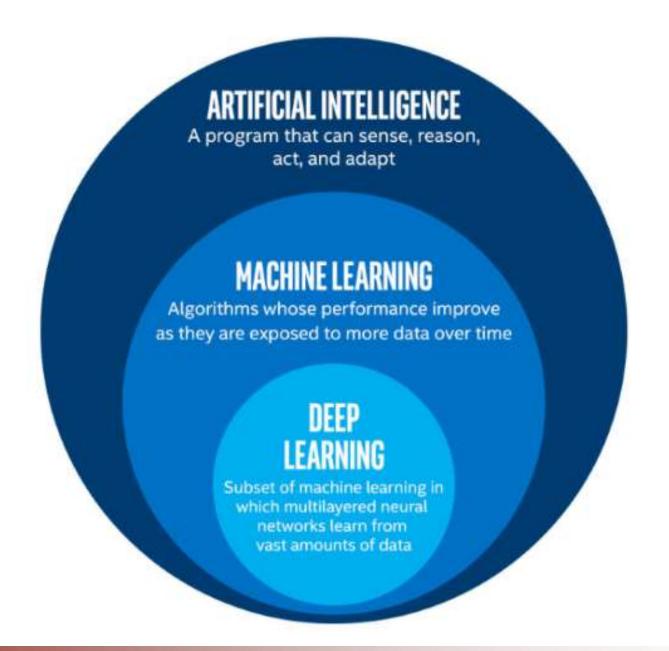
# Machine Learning

 Machine learning is a field of artificial intelligence that gives computer systems the ability to "learn" (e.g., progressively improve performance on a specific task) from data/results of their actions, without being explicitly programmed



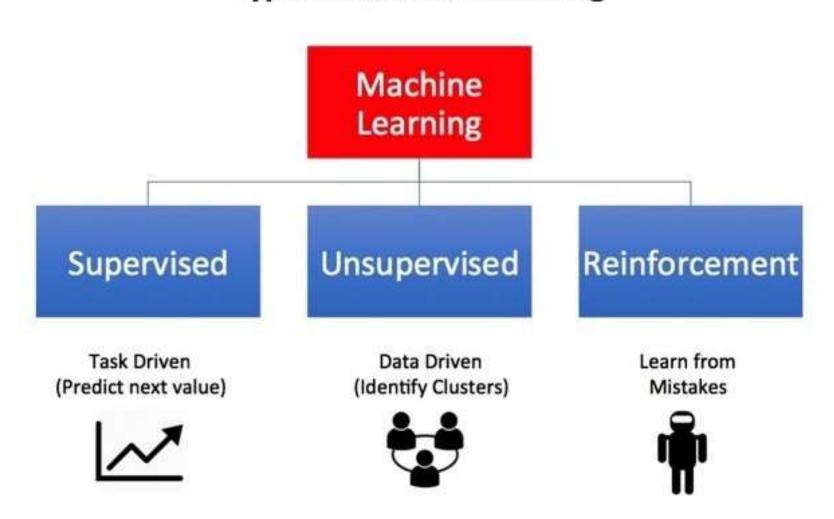


### Machine Learning vs. Artificial Intelligence

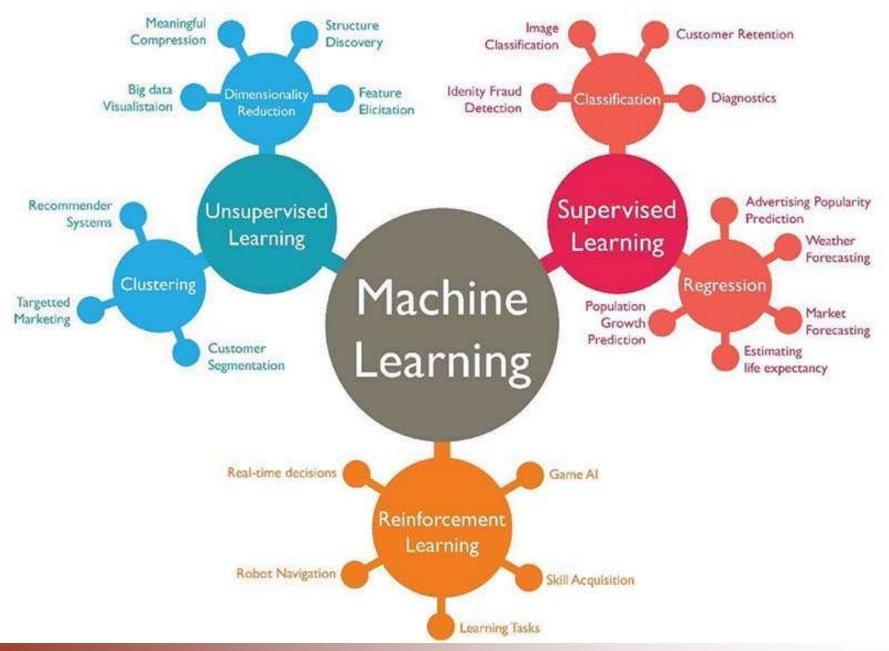


### Machine Learning - Types

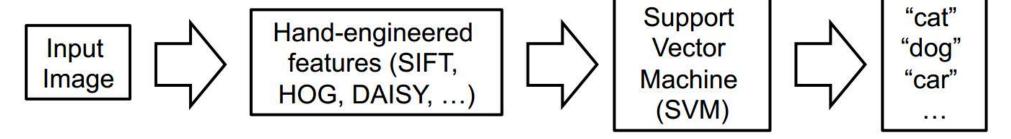
#### Types of Machine Learning



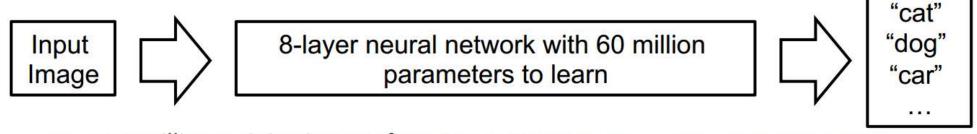
# Machine Learning



State-of-the-art object detection until 2012:

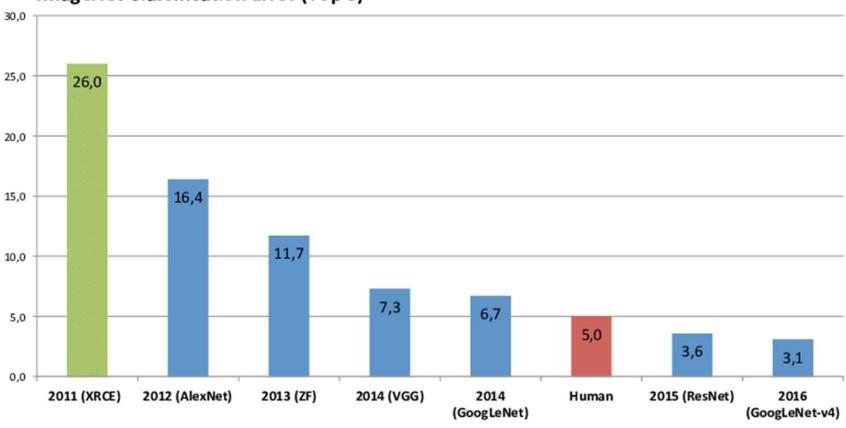


Deep Supervised Learning (Krizhevsky, Sutskever, Hinton 2012; also LeCun, Bengio, Ng, Darrell, ...):



~1.2 million training images from ImageNet [Deng, Dong, Socher, Li, Li, Fei-Fei, 2009]

#### ImageNet Classification Error (Top 5)



One of the main foci of Data Science and Data Mining

Goal: to learn from imitation













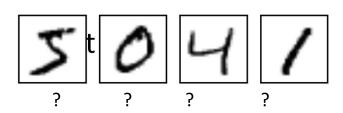






























Minimize the prediction error (a.k.a, the Loss)

- Example:
- Prediction:  $f(x) = \sqrt{1 x^2}$
- Loss function: L(x) = |y'-y|
- First iteration:
  - L(5) = |5 -10| = 5
  - L(0) = | 0 2 | = 2
  - L(4) = |4 (-1)| = 5
  - L(1) = | 1 7 | = 6

Total loss: 18



• Example:



- Prediction:  $f(x) = \sqrt{1}$

- Loss function:
  - L(x) = |y'-y|

5	0	Ч	/
5	0	4	1
5	0	4	1

Second iteration:

- L(5) = |5-9| = 4
- L(0) = |0-1| = 1
- L(4) = |4-0| = 4
- L(1) = |1-6| = 5
- Total loss: 14

• Example:



- Prediction: f(x)=√
   Loss function:
  - 9 1 0 6 8 0 1 5

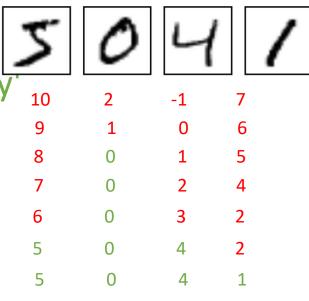
5 0 4 1 5 0 4 1

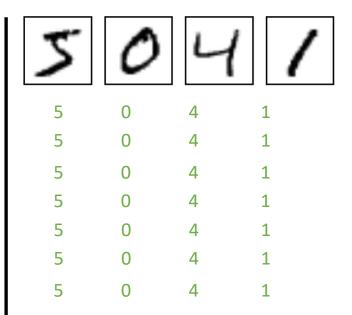
• Third iteration:

L(x) = |y'-y|

- L(5) = |5-8| = 3
- L(0) = |0-0| = 0
- L(4) = |4-1| = 3
- L(1) = |1-5| = 4
- Total loss: 10

- Example:
- Prediction: f(x)=√
- Loss function: L(x) = |y'-y|
- n<sup>th</sup> iteration:
  - L(5) = |5-5| = 0
  - L(0) = |0-0| = 0
  - L(4) = |4-5| = 0
  - L(1) = |1-1| = 0





Total loss: 0

- Requires knowing many answers to your question
  - Sometimes not possible
- Data can be shaped (new features), normalized (scaling), cleaned (outliers), improved (redundancy)
- Bias / Variance
- Amount of training data
- Dimensionality
- Noise
- Complexity

### Chihuahua or Muffin?

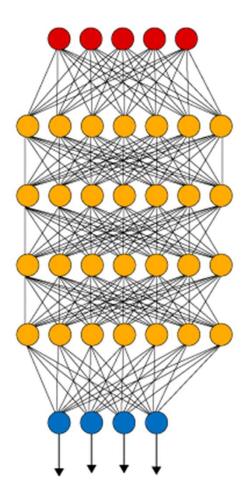


# Croissant or Dog?

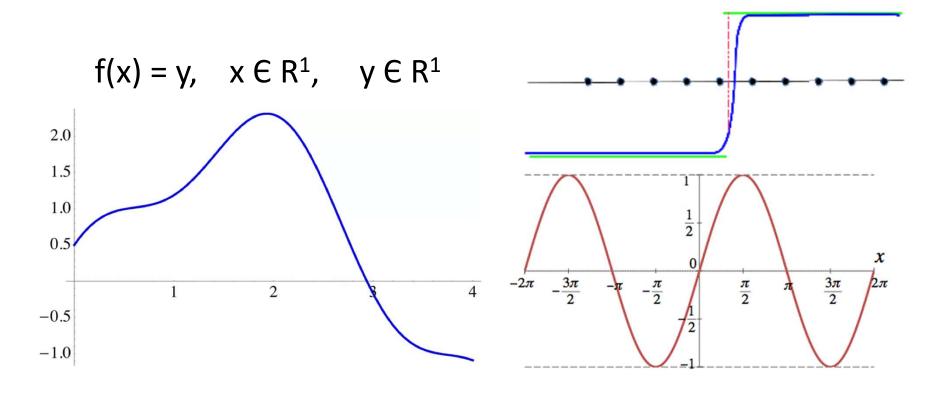


### Neural Networks

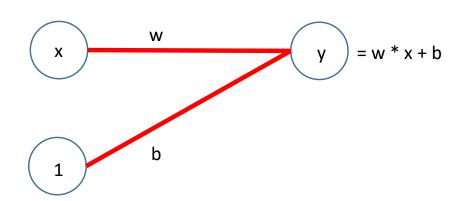
- Neural Networks
  - Buzz-word
  - Solves everything apparently
  - Deep Learning
- Resources:
  - Deep Learning Course, by Google (Coursera)
  - Deep Learning Specialization Course, by Udacity
  - Deep Learning, by Goodfellow, Bengio & Courtville
  - Lectures on Deep Learning, by Palazzi
- Algorithm that can approximate any function
  - But what does this even mean?



 A deep NN with arbitrarily high complexity can approximate any function with arbitrarily high precision



• But how?  $x \in R^1$ ,  $y \in R^1$ , no hidden layers



The simplest network.

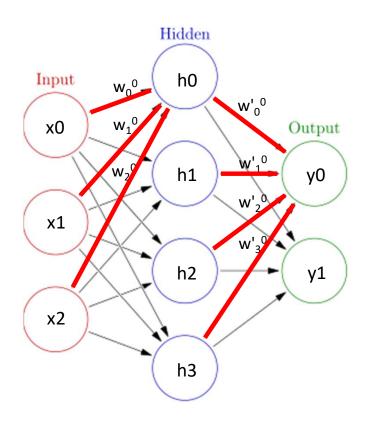
Just an input x, an output y.

There is usually a bias term, like a weight that is multiplied by 1 and added.

What should be the values of w and b to make this network work like:

$$y = x$$
  
 $y = (1-x)$   
 $y = 2x-1$ 

• But how?  $x \in \mathbb{R}^3$ ,  $y \in \mathbb{R}^2$ , a 4-wide hidden layer



A network is basically many matrices of weights which are multiplied by vectors of nodes.

Layers have activation functions, g(a), we'll come back to those. An input is given, and the hidden nodes are calculated.

$$h^{j} = g[\sum_{i}(w_{i}^{j} x_{i}) + b^{j}]$$
  
$$h^{0} = g[(w_{0}^{0} x_{0}) + (w_{1}^{0} x_{1}) + (w_{2}^{0} x_{2}) + b^{0}]$$

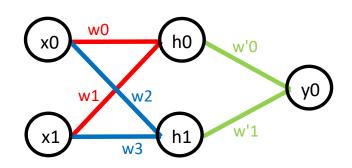
After the hidden nodes have values, we calculate the output nodes. The output layer might not have an activation function.

$$y^{j} = \sum (w'_{i}^{j} h_{i} + b'^{j})$$

$$y^{0} = (w'_{0}^{0} h_{0}) + (w'_{1}^{0} h_{1}) + (w'_{2}^{0} h_{2}) + (w'_{3}^{0} h_{3}) + b'^{0}$$

Simple practical example:

 $x \in \mathbb{R}^2$ ,  $y \in \mathbb{R}^1$ , a 2-wide hidden layer



Given inputs: (x0, x1) = (1, 2)

And weights:

When the layer uses a quadratic activation function:

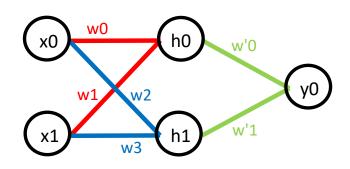
$$g(a) = a^2$$

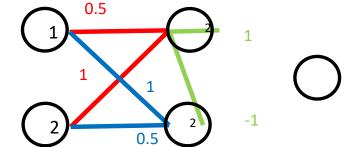
#### What is the output y0?

$$h = g[\sum(w^*x) + b]$$
$$y = \sum(w'^*h + b')$$

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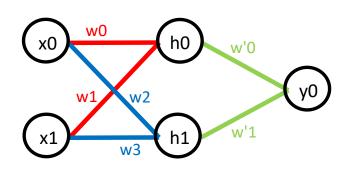
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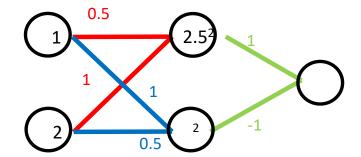
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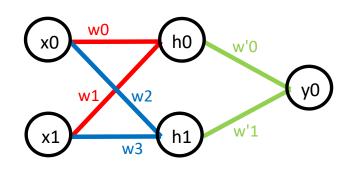
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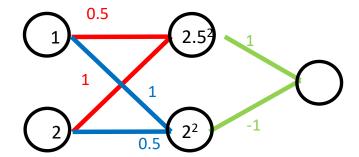
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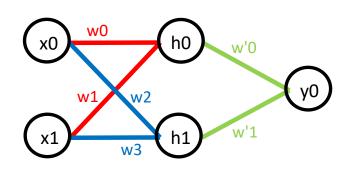
$$g(a) = a^2$$

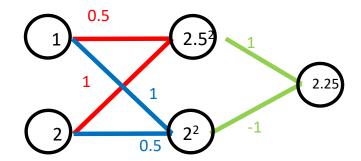
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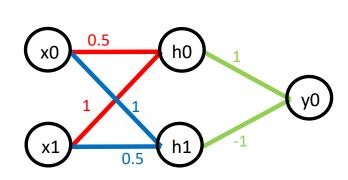
$$g(a) = a^2$$

#### What is the output y0?

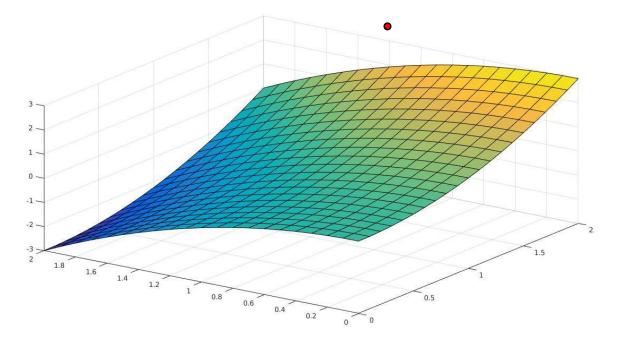
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$$y = \sum(w'^*h + b')$$

Simple practical example:

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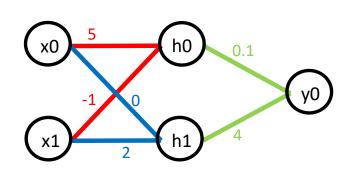


With these weights, this is the function that this NN outputs. By changing the weights, different functions are found.

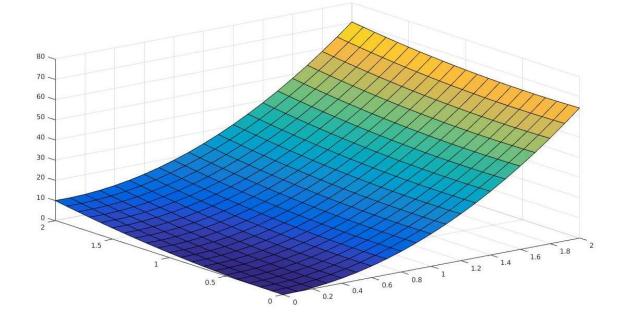


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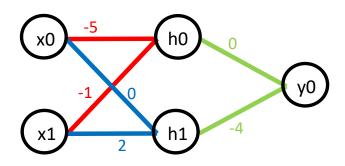


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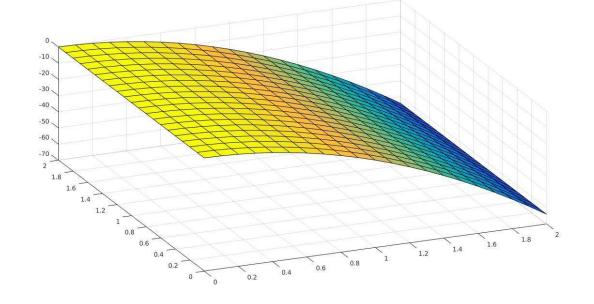


Simple practical example:

 $x \in \mathbb{R}^2$ ,  $y \in \mathbb{R}^1$ , a 2-wide hidden layer



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So the question now becomes:

 Given some network and a target function, how do we determine these weights to approximate this function?

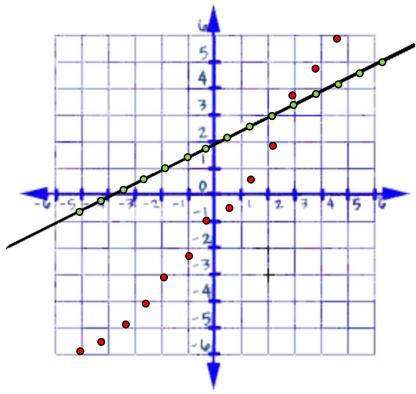
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**BACKPROPAGATION** 

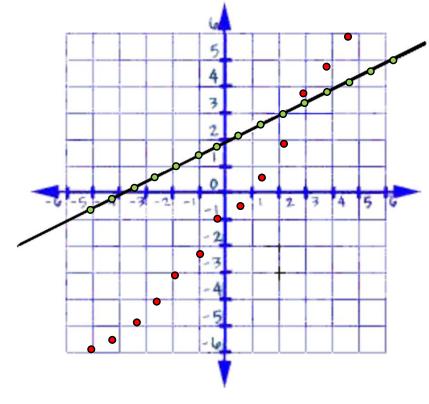
- Backpropagation Minimizes a loss function L
- Consider a line equation. We have a dataset of points on that line (green)
- Our network starts with random weights, and outputs random points (red)
- We want the NN to approximate the line function
- Our loss function measures the error of our network
  - What are possible loss functions we could use?



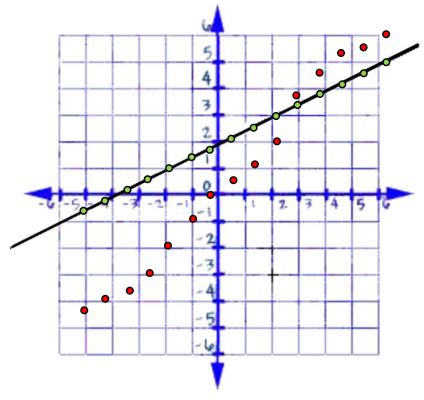
- Backpropagation Minimizes a loss function L
- The absolute or squared difference between our known outputs (the ones on the training set) and the network outputs

$$L(y,y') = \sum (|y' - y|)$$
  
 
$$L(y,y') = \sum ((y' - y)^2)$$

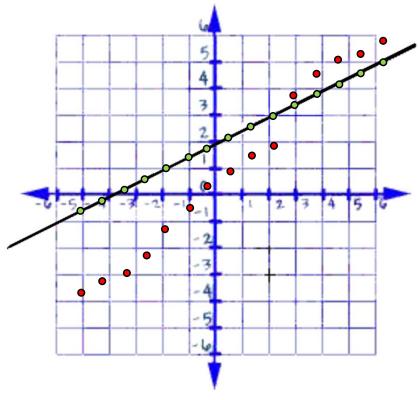
- Globally continuous
- Differentiable



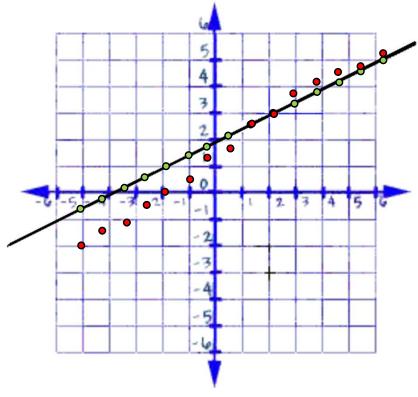
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- As we minimize the loss function, we get better and better results...



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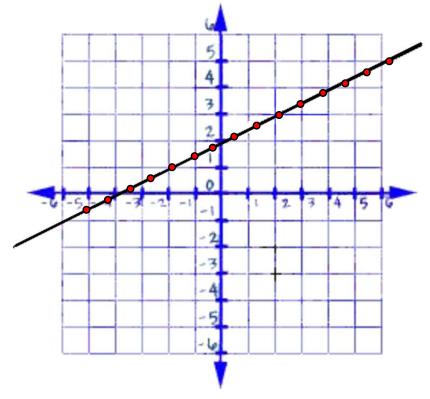


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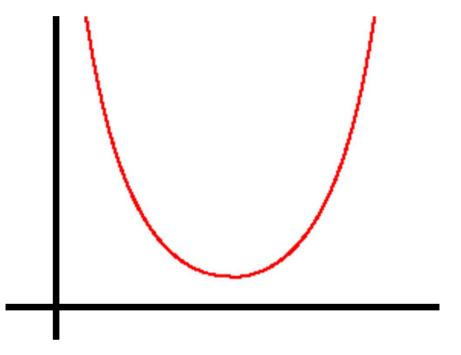


- Backpropagation Minimizes a loss function L
- As we minimize the loss function, we get better and better results...

...until our loss function is 0 (or close)

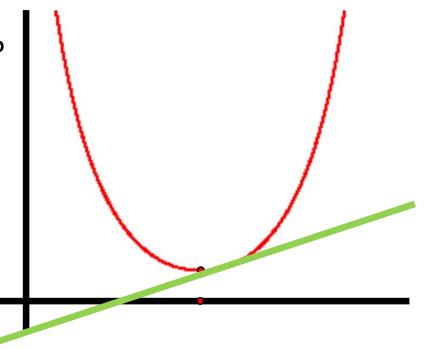


- Backpropagation Minimizes a loss function L
- As we minimize the loss function, we get better and better results...
- ...until our loss function is 0 (or close)
- Some loss functions don't approximate 0
- Noise also makes minimizing harder

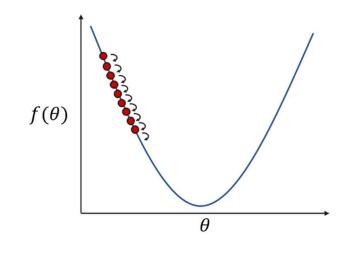


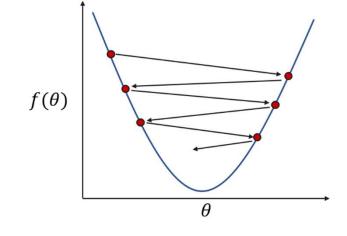
- Backpropagation Minimizes a loss function L using partial derivatives
- How does minimization actually work?
  - (Partial) Derivatives!

By finding the point where L'(y,y')=0, we find the minimum of L(y,y'). The partial derivates of each weight tell us how much that weight contributed to the error.



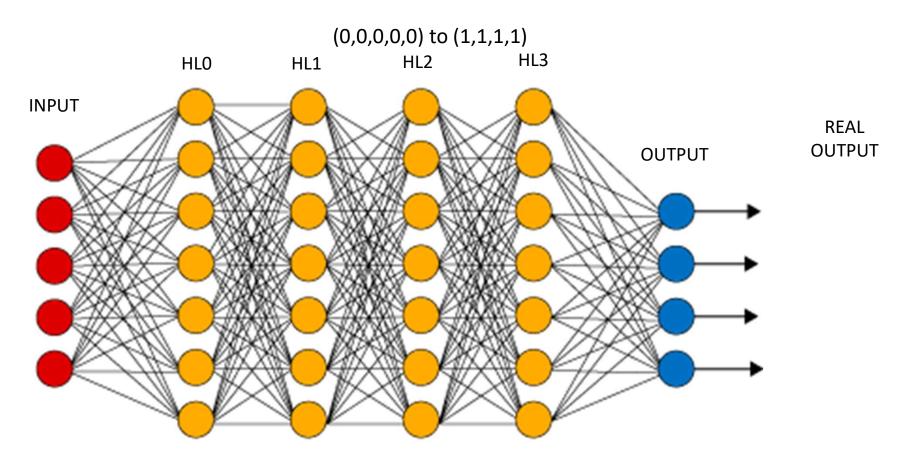
- Backpropagation Minimizes a loss function L using partial derivatives
- We shift each weight a small amount based on its partial derivative
- Amount depends on the Learning Rate (a hyper parameter)

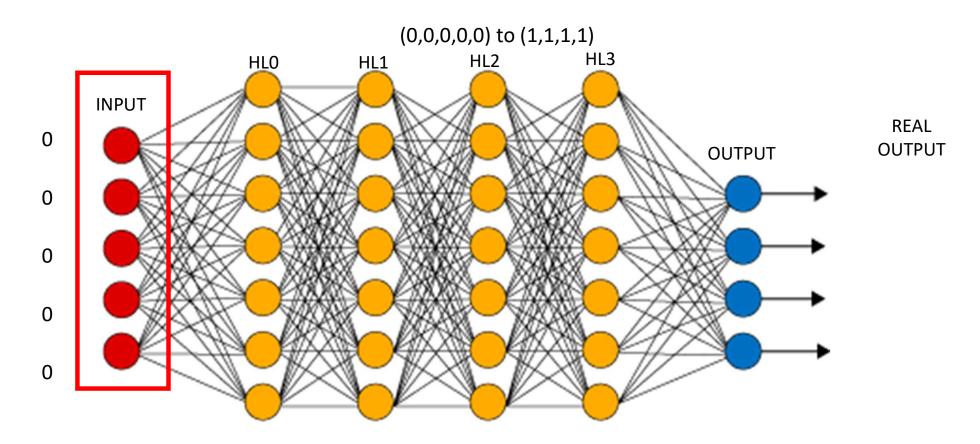


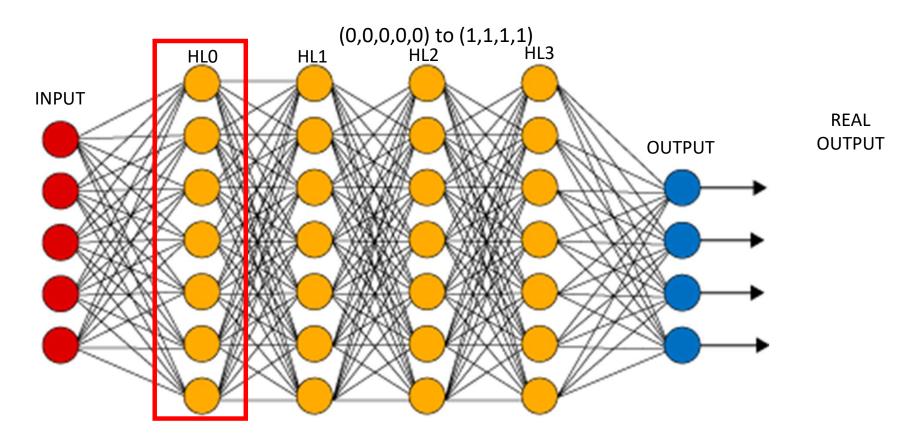


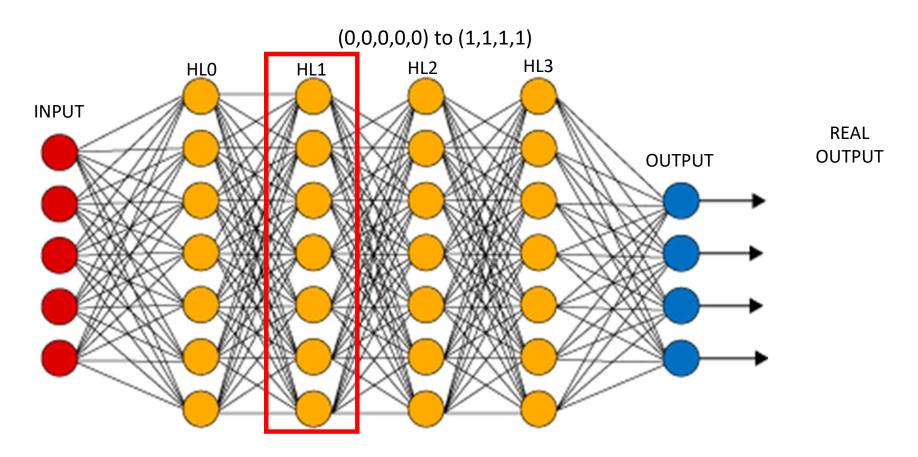
Learning Rate too small

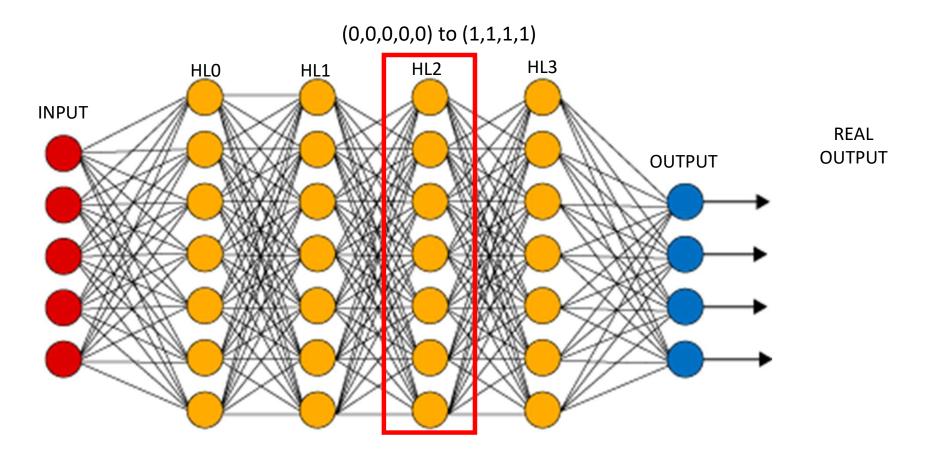
Learning Rate too big

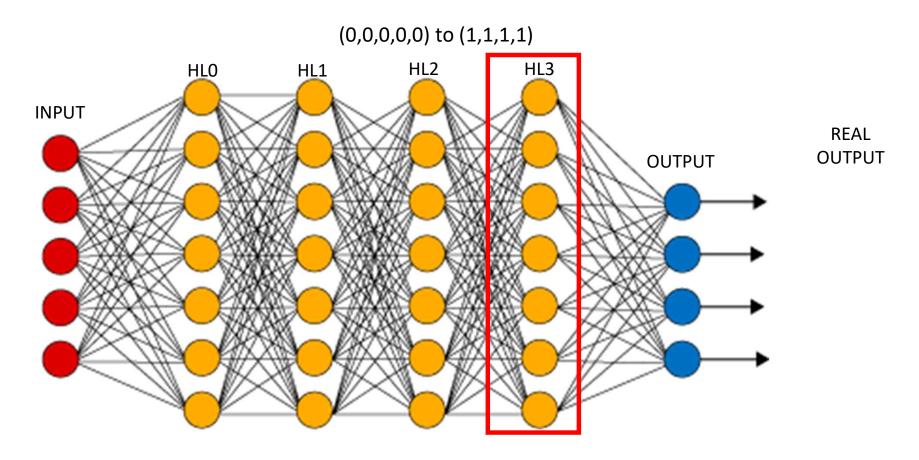


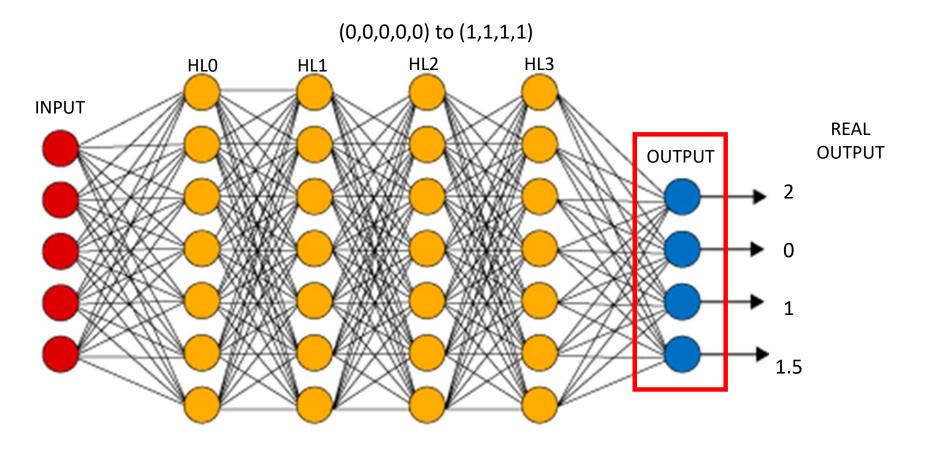


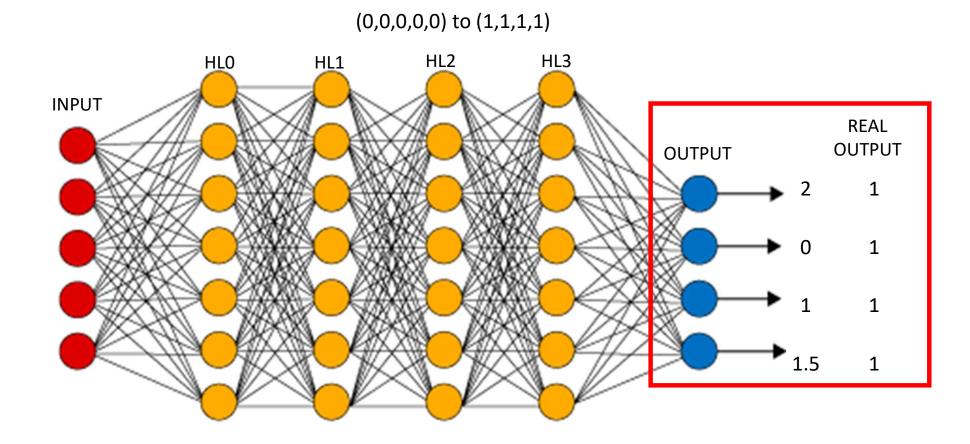


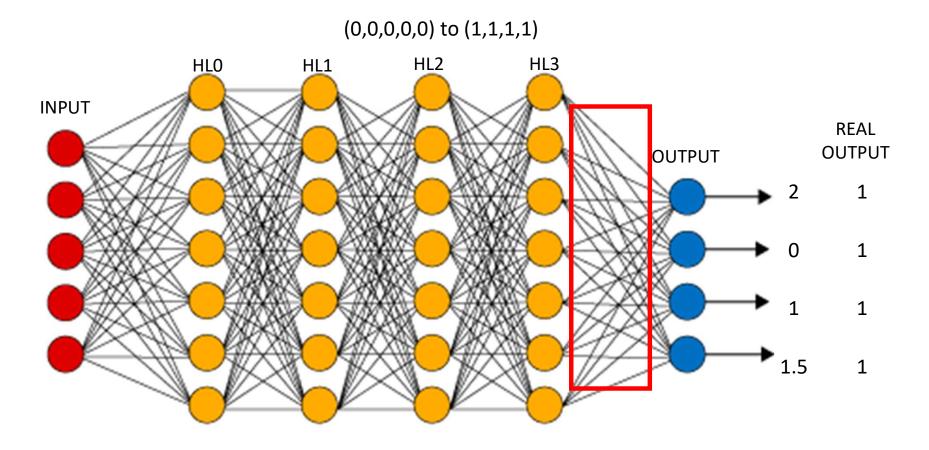


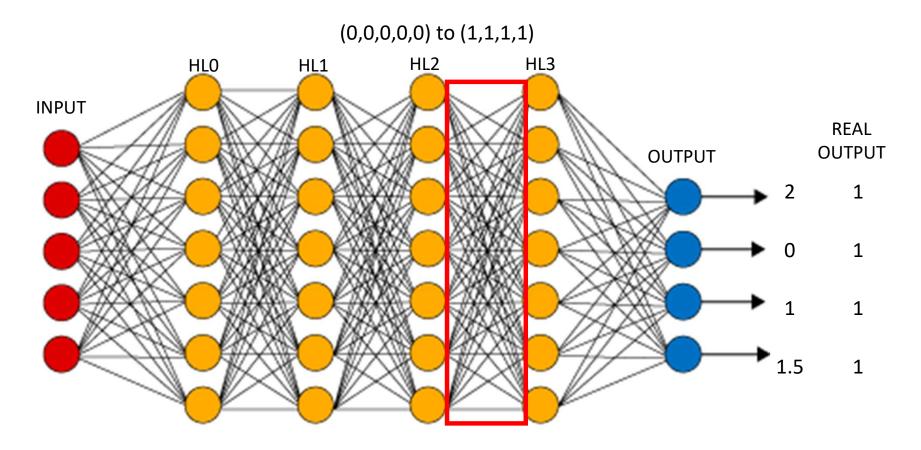


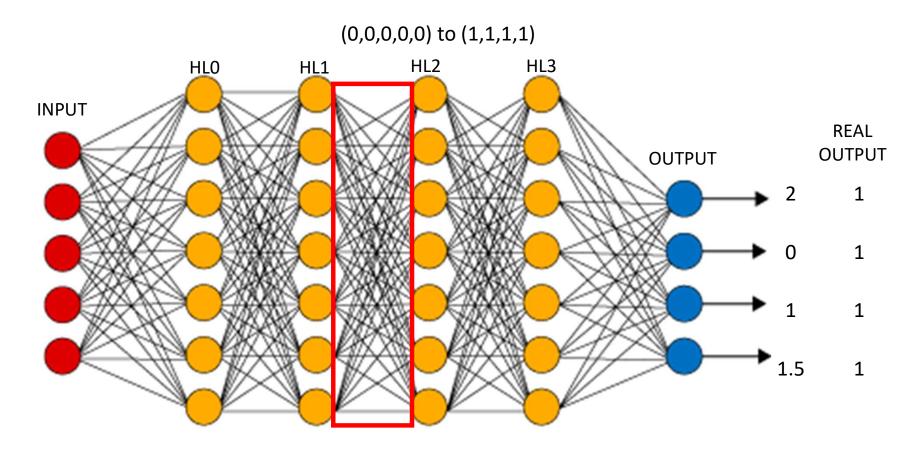


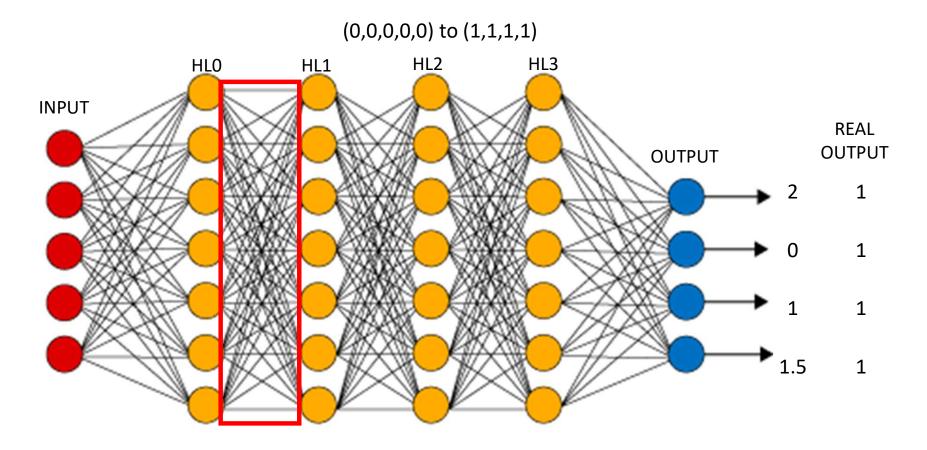


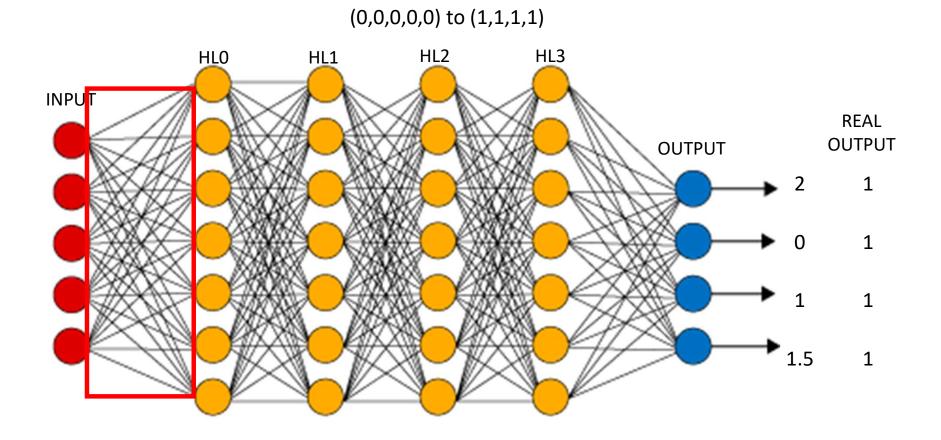


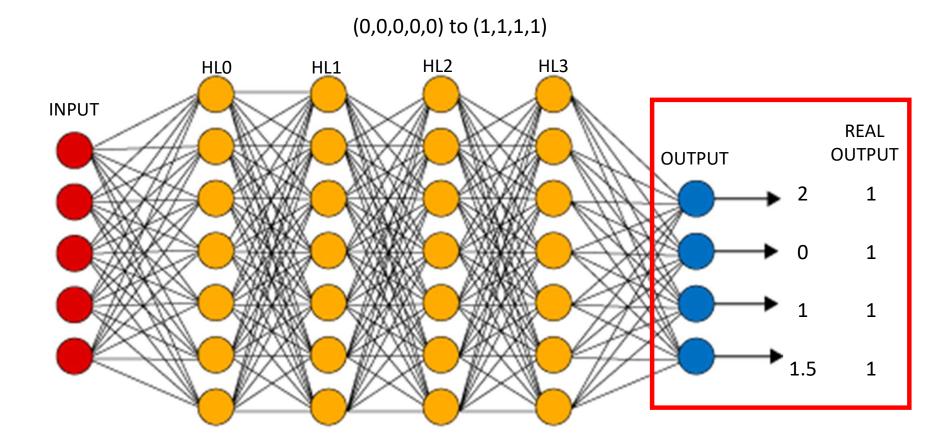


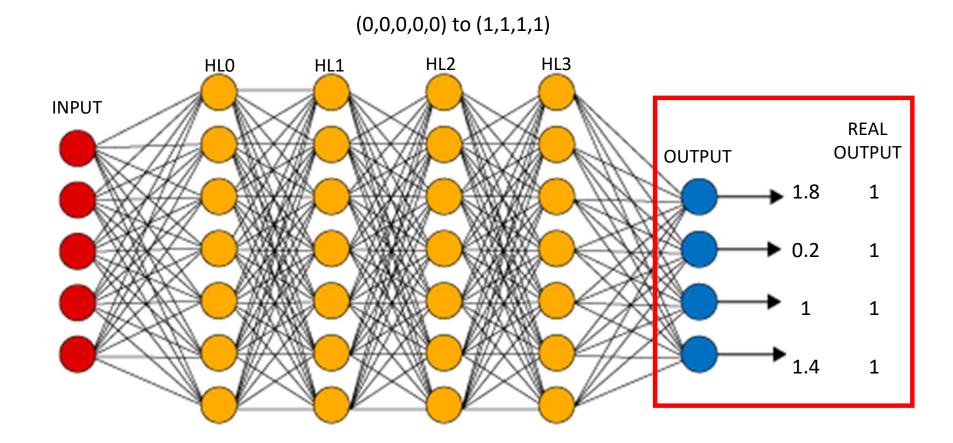


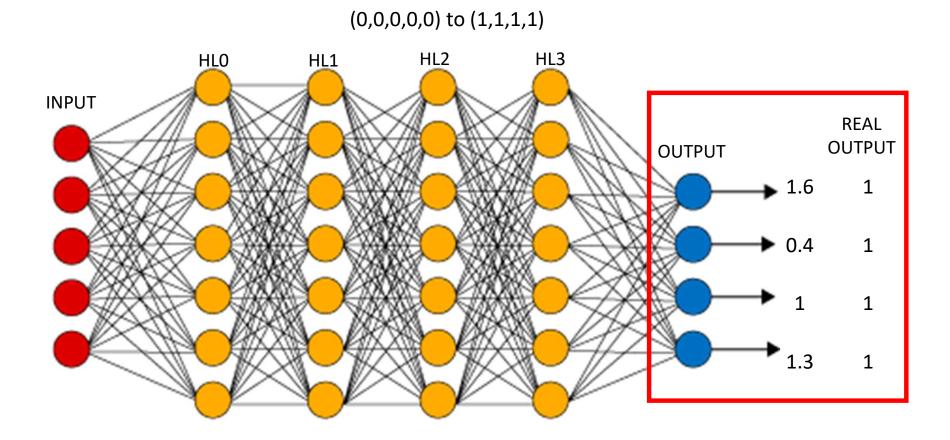


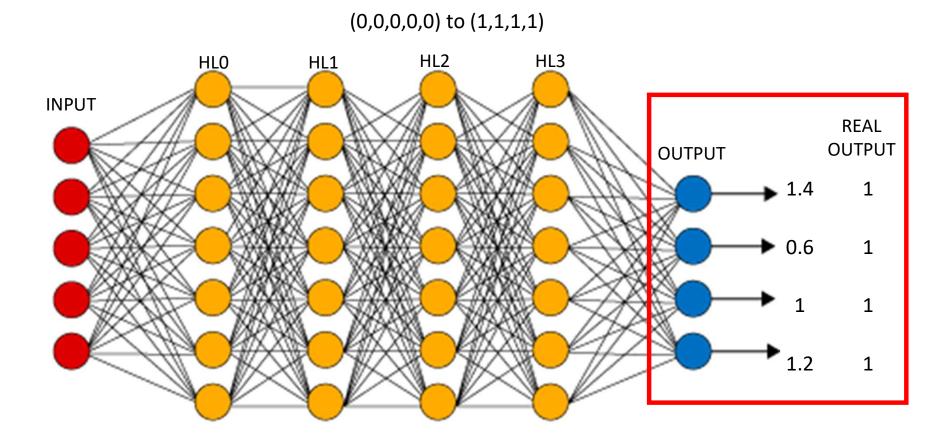


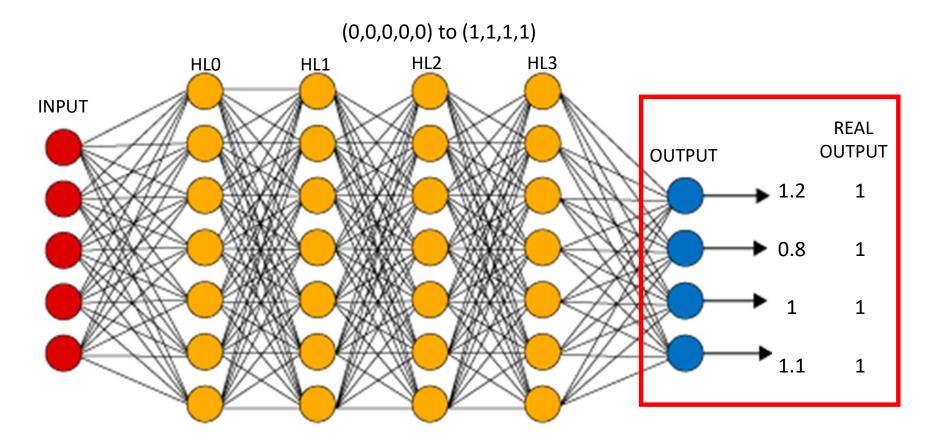


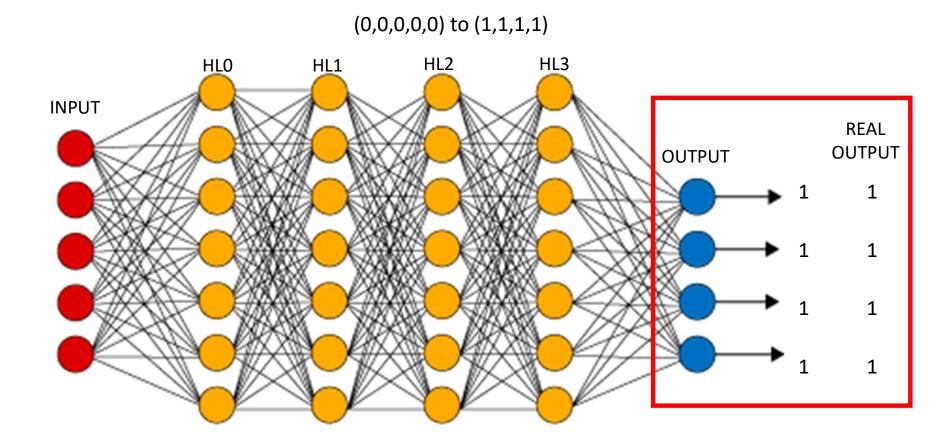








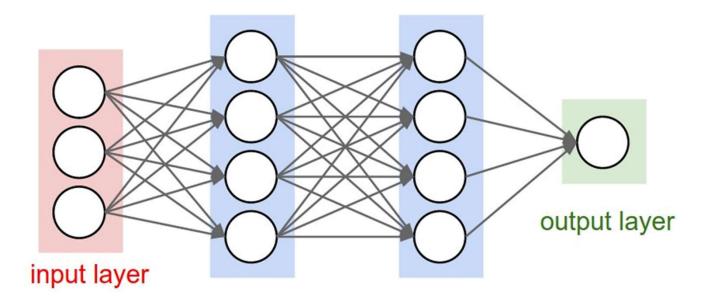




- Pipeline: forwards and backwards, batch by batch
  - To take advantage of GPUs and matrix calculations
- Given any sort of numerical dataset, we can say it represents a function f(INPUTS) = OUTPUTS
  - Classification outputs are probabilities of classes
  - Regression outputs are numerical values
  - Image processing inputs are pixel values
  - Natural Language processing inputs are letters
  - ...
- And a neural network can approximate this function

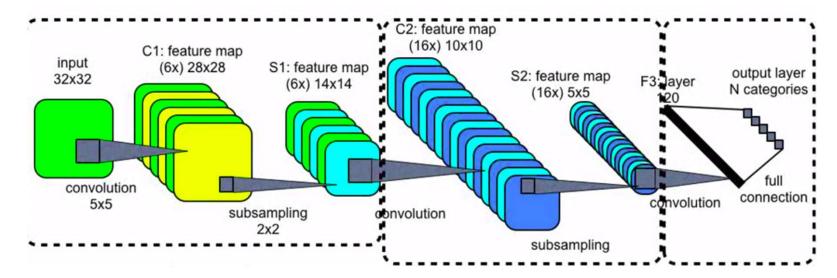
- Many different types of networks
  - No ideal architecture, just recommendations
- Layers
  - Type
  - Depth
  - Width
- Activation functions
- Loss functions
- Optimizer

Fully Connected Layers



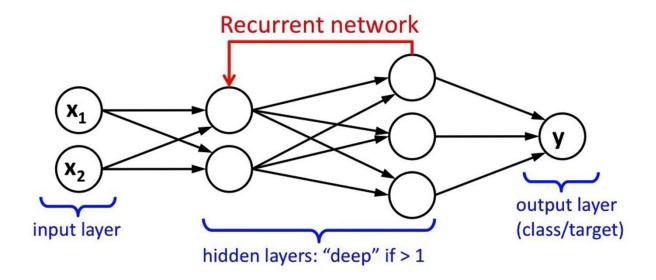
- Used everywhere
- Just connect all nodes from previous layer to all nodes from next layer

Convolutional Layers



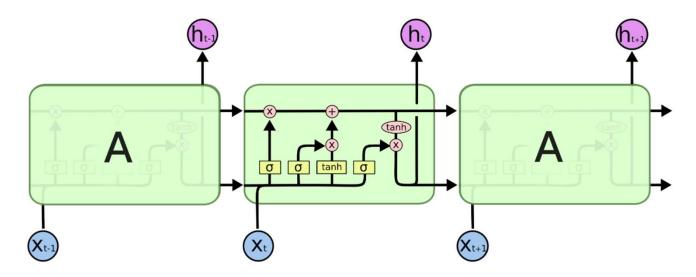
- Used with images
- Have a set of weights that processes many small parts of the previous layer

Recurrent Layers



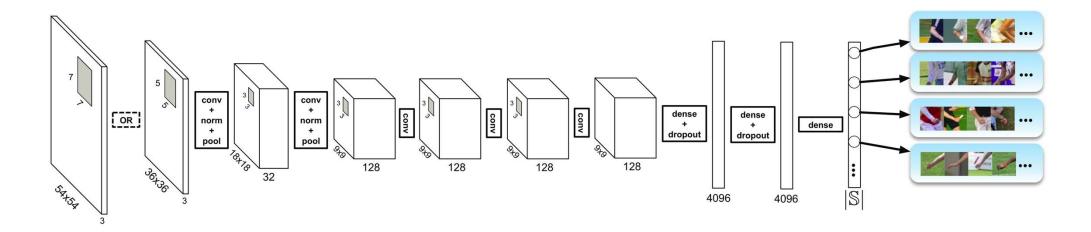
- Used when input has temporal dependencies
- The layer feeds previous output to other layers

Long Short-Term Memory (LSTM) Layers



- Used when input has temporal dependencies
- The layer saves information from forward passes to give to future forward passes

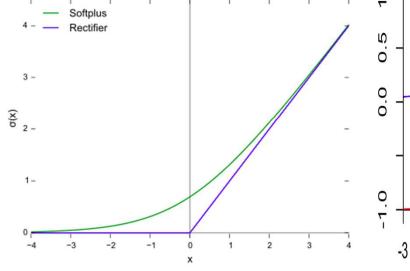
Depth and Width

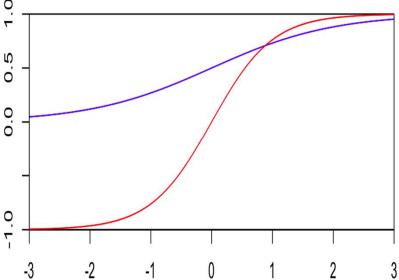


- Depends on the problem. No fixed formulae, but usually larger means capable of more complex functions
- Some proposals have networks finding their own ideal architectures

- Activation Functions
  - Allow for non-linearity
  - Without these, we could only approximate linear equations
- RELU
- ELU
- Softplus
- Sigmoid
- Tanh
- Identity

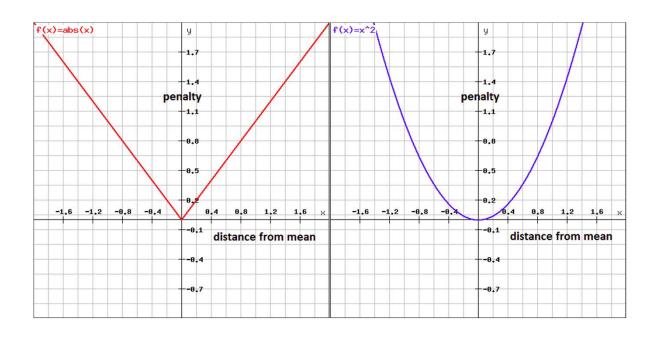
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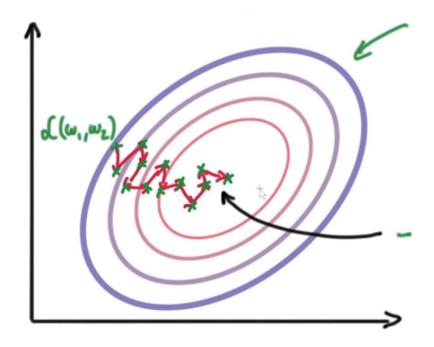
- Loss Functions
  - Affect learning process/speed
- Absolute difference
- Mean Squared
- Log difference
- Cross-entropy

• ...



- Optimizers
  - Affect learning process/speed
  - Some solve problems with vanishing/exploding gradients on very deep networks
- Stochastic Gradient Descent
- ADADelta
- ADAGrad
- ADAM
- RMSProp

• ...



## Neural Networks - Hyper-Parameters

- Input / output size (problem-dependent)
- Learning Rate
- Batch size
- Learning stop condition
  - Time
  - Performance
- Depth / width (layers)
- Kernel configurations (convolutional layers)

• ...

#### Neural Networks - Other issues

- Vanishing gradients
- Exploding gradients
  - On very deep networks, solved with some optimizers
- Overfitting
  - Drop-outs turn on and off random nodes to create random noise
- If things don't work, no one really knows why
  - Black-box
  - We have no idea what the weights mean...



# Artificial Intelligence Machine Learning – Neural Networks/Deep learning Luís Paulo Reis

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