

Human Brain Distinctiveness Based on EEG Spectral Coherence Connectivity

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I. INTRODUCTION

Abstract—The use of EEG biometrics, for the purpose of automatic people recognition, has received increasing attention in the recent years. **Most of the current analyses rely on the extraction of features characterizing the activity of single brain regions, like power spectrum estimation, thus neglecting possible temporal dependencies between the generated EEG signals.** However, important physiological information can be extracted from the way different brain regions are functionally coupled. In this study, we propose a novel approach that fuses spectral coherence-based connectivity between different brain regions as a possibly viable biometric feature. The proposed approach is tested on a large dataset of subjects ($N = 108$) during **eyes-closed (EC)** and **eyes-open (EO)** resting state conditions. The obtained recognition performance shows that using brain connectivity leads to higher distinctiveness with respect to power-spectrum measurements, in both the experimental conditions. Notably, a 100% recognition accuracy is obtained in EC and EO when integrating functional connectivity between regions in the frontal lobe, while a lower 97.5% is obtained in EC (96.26% in EO) when fusing power **spectrum information from parieto-occipital (centro-parietal in EO) regions.** Taken together, these results suggest that the functional connectivity patterns represent effective features for improving EEG-based biometric systems.

Index Terms—Biometrics, electroencephalography (EEG), match score fusion, resting state, spectral coherence.

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ELECTROENCEPHALOGRAPHY (EEG) signals provide relevant information about individual differences related to brain anatomical and functional traits as already pointed out in early neurophysiologic studies [1] and [2]. Although some isolated attempts to discriminate people from their electrical brain activity have been performed in the past [3], only recently, the scientific community has started a more systematic investigation on the use of EEG signals as human distinctive traits which can be potentially used in a biometric system [4]. A variety of EEG elicitation protocols for the purpose of automatic user recognition has been implemented, ranging from resting state with eyes open (EO) and eyes closed (EC) to self-paced mental imagery [5].

In particular, **resting state** is an advantageous condition for biometric applications since it does not require active involvement of the subject during the EEG recording, thus reducing inconvenience, fatigue, and artifact occurrences. **From a neurophysiological perspective, ongoing EEG activity during resting state elicits patterns of synchronous oscillations in specific frequency ranges (from 1 to 40 Hz) that share and support basic cognitive functions [6]. Furthermore, it has been suggested that EEG activity during resting wakefulness carries genetic information [7] and personality correlates [8].** The number of studies investigating EEG activity during resting states as a potential biometric marker has increased, though the obtained results suggest that more efforts should be done to improve its efficacy in terms of **correct recognition performance (CRR)** and/or sample size, i.e., the number of subjects to recognize. A comprehensive survey of the different methods, protocols, and achieved results can be found in [9].

As evidenced by this survey, the large part of the studies exploring EEG for biometric purposes has **focused on the extraction of features from the activity of single sensors (or channels)** corresponding to different brain regions. However, complementary information can be obtained from the temporal dependence between activities of different brain areas [10]. From a neuroscience perspective, two brain regions that exhibit coherent or correlated activities are supposed to exchange information [11], [12] and this kind of communication represents, nowadays, a key element to understand the brain organization [13]. Many analytical tools are available to measure statistical interdependence between brain signals that are based on different mathematical principles (e.g., correlation, information theory, phase coherence, and Granger causality), implemented in time- or frequency domain, capturing linear or nonlinear changes [14], [15]. These tools allow the estimation of the so-called **functional brain connectivity** [16].

resting
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Interestingly enough, we know that the way different brain regions are functionally connected is not homogeneous, and that specific connectivity patterns emerge during wakeful resting state conditions [17]. Our hypothesis is that the functional connectivity between EEG sensors could be a more robust feature for biometric recognition purpose, compared to EEG activity of channels considered separately. A previous study has tested, among others, time-domain connectivity measures between two frontal sensors (Fp1 and Fp2) for the identification of 51 subjects [18]. The recognition accuracy, obtained separately with different classifiers, reached a maximum of $CRR = 31\%$ for cross-correlation and $CRR = 24\%$ for mutual information. In this regard, the large part of the studies using EEG for biometric purposes showed that the extraction of features describing the spectral content of the signals could give better recognition performance [9]. Hence, frequency-domain connectivity measures could be more appropriate for detecting those putative distinctive features. 由于昼夜节律, 不同时间的脑电可能变化

Changes of EEG amplitudes in the same subject and during the same condition can occur due to the physiologic circadian rhythms [19], substance assumption [20], or different recording technical solutions [21]. In contrast to univariate measures, such as power spectrum estimation, spectral coherence is a simple bivariate connectivity method that is not sensitive to the amplitude changes of the EEG oscillations. In fact, two signals may have different amplitudes and/or phases, but high coherence occurs when this phase difference tends to remain constant [22]. Therefore, this property could play a critical role in increasing the overall classification performance in presence of large intrasubject EEG variability due to scale factors.

Another common issue in EEG-based biometric systems is the general tendency to perform classification from single elements, e.g., power spectrum of one EEG signal or functional connectivity between two EEG signals [18], [23]–[25]. Less often the feature space has been enriched by including information from a limited number of *a priori* selected elements [26], [27]. These parsimonious procedures appear certainly justified by possible implications on industrial research for smart EEG systems with few sensors. However, such technical solution restricts the feature space and consequently can affect the overall classification performance. Alternative methodological solutions integrating information from multiple elements can be beneficial with the aim of catching more robust and distinctive brain patterns, thus maximizing the recognition rates.

In this study, we propose a fusion approach [28] to integrate at the match-score level, the information obtained from the estimation of spectral coherence. The combined use of EEG spectral coherence and classification algorithms has been previously exploited in neuroscience to distinguish between healthy and diseased populations [29] or to determine the changes between baseline and motor/cognitive tasks [30]. To the best of our knowledge, this is the first time that such a combined approach is also used for biometric purposes.

II. METHODS

A. Dataset and Preprocessing

Scalp EEG signals were gathered from the freely online database PhysioNet BCI [31]. The database consists of $N = 108$

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healthy subjects recorded in two different baseline conditions, i.e., 1-min EO resting state and 1-min EC resting state. In each condition, subjects were comfortably seated on a reclining chair in a dimly lit room. During EO, they were asked to avoid ocular blinks in order to reduce signal contamination. The EEG data were recorded with a 64-channel system (BCI2000 system [32]) with an original sampling rate of 160 Hz. All the EEG signals are here referenced to the mean signal gathered from electrodes on the ear lobes. Data are subsequently downsampled to 100 Hz after applying a proper antialiasing low-pass filter to restrict the available frequency range up to 50 Hz. The electrode positions on the scalp follow the standard 10–10 montage. Five electrodes are excluded and only $N_{ch} = 56$ electrodes (see Fig. 3) are retained for the subsequent analysis. These electrodes were selected because they constitute a montage common to different available datasets that we can use in future analysis.

For each subject and condition (EO, EC) the obtained EEG signals are segmented into $N_T = 6$ consecutive nonoverlapping epochs of 10 s. These epochs are considered as different observations of the same mental state and they are used to extract specific spectral features for the assessment of person recognition. In particular, we consider the two following methods, power spectral density (PSD) and spectral coherence (COH) connectivity detailed in Sections II-B and II-C, respectively.

B. Power Spectral Density

Although parametric linear or nonlinear EEG signal processing has been recently investigated for biometric purposes [33], [34], a nonparametric Fourier Transform-based spectral analysis is chosen in this study due to its obvious physical interpretation in terms of EEG rhythms. Specifically, the PSD of the EEG signals was extracted from each segmented epoch (10 s) by computing the Welch's averaged modified periodogram. A sliding Hanning window of 1 s, with an overlap of 0.5 s, is applied to improve the estimation quality. The number of FFT points is set to 100 in order to have a PSD estimate with a frequency resolution of 1 Hz (the frequency sampling is 100 Hz). The resulting PSD for the electrode i , with $i = 1, \dots, N_{ch}$, is a feature vector of $N_{FT} = 41$ elements characterizing the power of the EEG oscillations from 0 up to 40 Hz. In the present study, we consider a restricted range of frequency, namely 1–40 Hz. This choice covers the standard spectrum of physiologic EEG oscillations from low (Delta 13 Hz, Theta 4–7 Hz) to intermediate (Alpha 8–14 Hz) and high frequency bands (Beta 15–29 Hz, Gamma 30–40 Hz). Each segmented epoch is finally characterized by $N_E^{(PSD)} = N_{ch}$ feature vectors $\hat{\zeta}^{(PSD)}$ of $N_F = 40$ elements, where $N_{ch} = 56$ is the total number of electrodes.

C. Spectral Coherence Connectivity

In this study, functional connectivity is estimated by calculating COH [35]. This method is frequently used due to its practical and intuitive interpretation. COH quantifies the level of synchrony between two stationary signals at a specific frequency f . Given two EEG signals recorded from channels i and j , the spectral coherence $COH_{i,j}(f)$ for a particular frequency

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数据切分

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f is computed as follows:

$$\text{COH}_{i,j}(f) = \frac{|S_{i,j}(f)|^2}{S_{i,i}(f) \cdot S_{j,j}(f)} \quad (1)$$

where $S_{i,j}(f)$ is the cross spectrum of the signals acquired from channels i and j , while $S_{i,i}(f)$ and $S_{j,j}(f)$ are the respective autospectra. By definition $\text{COH}_{i,j}(f)$ ranges between 0, which corresponds to no synchrony at the frequency f , and 1, which corresponds to maximum synchrony at the frequency f . Here, $S_{i,j}(f)$, $S_{i,i}(f)$, and $S_{j,j}(f)$ are computed by means of the Welch's averaged modified periodogram, with same parameters used for the computation of the PSD (see Section II-B.). In particular, the use of 1-s Hanning windows is aimed to improve the stationarity of the segmented EEG signals [36]. For each electrode pair, we consider a feature vector $\hat{\zeta}^{(\text{COH})}$ consisting of $N_F = 40$ COH values ranging from $f = 1$ to $f = 40$ Hz. The total number of electrodes N_{ch} being equal to 56, we have that $i = 1, \dots, N_{\text{ch}} - 1$ and $j = i + 1, \dots, N_{\text{ch}}$ and each segmented epoch (10 s) is finally characterized by $N_E^{(\text{COH})} = \frac{N_{\text{ch}} \cdot (N_{\text{ch}} - 1)}{2} = 1540$ features vectors of N_F elements.

D. Classifier

We use a classification approach to predict the class, namely the subject identity, to which the observed feature vector $\hat{\zeta}$ belongs. The model we use for the discriminant analysis assumes that the feature vectors $\hat{\zeta}$ form a Gaussian mixture distribution. For this reason, before the classification, we apply a Fisher's Z transformation to the COH values in order to normalize their distributions [37]. A logarithmic transformation is instead applied to the PSD values [38].

A Mahalanobis distance-based classifier is then used to perform identification. This method requires the computation of the covariance matrix of the feature vectors of each class. Given the few observations for each subject (six epochs) the covariance matrices cannot be robustly computed. Therefore, we use a common procedure consisting in the approximation to equal covariance matrices [39]. Specifically, a pooled covariance matrix is obtained by merging the class-specific distributions of the feature vectors after removing their mean value. Notably, the normalizing transformations, previously introduced, support such approximation. A partition of the $N_T \times N$ normalized feature vectors extracted from the dataset is used to enroll the subjects and generate templates representing the class distributions.

A cross-validation framework is here considered to assess the recognition performance. In each cross-validation run, for each subject m , five epochs are used to generate the class distributions (i.e., enrollment phase), while the remaining epoch is employed to perform the identification (i.e., test phase). A number $N_r = 6$ of runs are provided, considering all possible partitions (leave-one-out framework). The Mahalanobis distances are computed between each observation m in the test dataset, and the class distributions n obtained in the enrolling, according to the formula:

$$d_{m,n} = (\hat{\zeta}_m - \mu_n) \Sigma^{-1} (\hat{\zeta}_m - \mu_n)^T \quad (2)$$

with $m, n = 1, \dots, N$, N being the number of classes (subjects), $\hat{\zeta}_m$ the observed feature vector from subject m , μ_n the mean vector for the class distribution n , and Σ the pooled covariance matrix.

We use the misclassification (or confusion) matrix \mathbf{M} to evaluate the recognition performance. Each column of this matrix $N \times N$ represents the instances in a predicted subject identity (i.e., class), while each row represents the instances in an actual class. For a given subject m , the predicted subject identity \hat{n} is obtained according to

$$\hat{n} = \arg \min_n d_{m,n}. \quad (3)$$

Eventually, for each run the correct recognition rate (CRR) is defined as the average over the diagonal of the resulting misclassification matrix \mathbf{M}

$$\text{CRR} = \left(\frac{1}{N} \sum_{n=1}^N M[n, n] \right) \times 100. \quad (4)$$

E. Match Score Fusion

Performance in terms of correct recognition percentage is computed as described in the previous section for both the PSD and COH feature vectors estimated from each channel and channel pair, respectively. Furthermore we hypothesize that different spectral features could be distinctive for different subjects. Therefore, we try to obtain complementary information considering multiple spectral features from different EEG channels or channel pairs, in order to improve overall performance. Through the fusion of single-element information we obtain patterns of brain activity, supposed to be a more robust characterization representative of brain organization of specific subjects. In this regard, we perform a fusion at the match score level, considering the sum of scores related to different elements

$$S_{m,n} = \sum_{e \in E} \frac{1}{d_{m,n}^e} \quad (5)$$

where E is a selection of elements from the set of 56 channels for $\hat{\zeta}^{(\text{PSD})}$, or from 1540 channel pairs when considering $\hat{\zeta}^{(\text{COH})}$. We then compute the misclassification matrix \mathbf{M} to evaluate recognition accuracy as described in Section II-D by maximizing $S_{m,n}$ with respect to n . We select the elements to consider in the match score fusion according to a forward-backward approach. Specifically, only elements which improve accuracy are retained in the fusion. First, all the elements are sorted in a descending order of accuracy according to the single-element classification results. Starting from the first one, each single element is then added stepwise in the subset E to compute (5). If the inclusion of the i -th element improves the resulting accuracy then it is retained for the final fusion, otherwise it is removed (see Fig. 3). More details about the pseudocode implementation of the match score fusion can be found in the Supplementary File 1.

Each step of the fusion algorithm is computed within a leave-one-out cross-validation framework, as discussed in Section II-D. Specifically, for each tested subset of elements E , related to a specific step of the fusion algorithm, $S_{m,n}$ is computed for each of the six partitions of the dataset. Then, the

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CRRs related to the different partitions are averaged together to obtain the performance related to the particular step. If that performance represents an improvement compared to the previous step, the related element is retained in E for the final fusion. This analysis is carried out separately for three brain macro-areas (or zones), namely frontal (F), central (C), and parieto-occipital (P), in order to compare performance and distinctive activity patterns among them.

III. RESULTS AND DISCUSSION

In this section, the results of the analysis performed for subject recognition based on EEG signals are reported and discussed. Resting-state conditions EO and EC are investigated separately and the related outcome is here compared for all the performed tests. Two different characterizations of the brain activity are considered as distinctive features to test within the provided biometric framework. In particular, after the preprocessing described in Section II-A, PSD and COH estimates are obtained as reported in Sections II-B and C. As previously pointed out, PSD measures the activity of single brain regions while COH rather measures their functional connectivity. Then, two different sets of feature vectors, $\hat{\zeta}^{(PSD)}$ and $\hat{\zeta}^{(COH)}$, are extracted according to the previously described methods. A classification based on Mahalanobis distance, detailed in Section II-D, is then carried out to evaluate the distinctiveness of the two considered feature vectors in all tested conditions, in terms of CRR.

A. Single-Element Classification

A preliminary test on distinctiveness related to each feature is reported in Fig. 1. The CRR values obtained within a cross-validation framework, as described in Section II-D, are shown in false colors. In particular, the scalp maps shown in Fig. 1(a) represent the spatial distribution of the CRR values obtained through single channel PSD features, in the EO and EC conditions. The adjacency matrices shown in Fig. 1(b) report the CRR values of the COH features for each channel pair. Given the $N_{ch} \times N_{ch}$ adjacency matrix \mathbf{Adj} , each element $Adj_{i,j}$ represents the CRR obtained considering the COH between channels i, j as feature vector. According to this representation, the position of the EEG channels over the head is coded by the x and y axes of the adjacency matrix.

The CRR scalp maps for the PSD features show that the most distinctive regions appear in the central part of the brain (C) during EO (max CRR = 86.91%), while the P zone is more distinctive in the EC condition (max CRR = 90.49%). The better distinctiveness of the posterior areas during EC condition was already reported in previous EEG studies [25], [26], [33] and it is probably related to well-known physiological increase of the parieto-occipital Alpha power in such condition [40]. A possible explication for this evidence is that EC resting states interrupt the visual processing while enhancing endogenous and autonomic related brain activity [41], which reflects the influence of genetic factors [42]. For the CRR adjacency matrices in the EC condition the best discriminant channel pairs are mainly located in the parieto-occipital zone P (max CRR = 78.5%). In the EO condition, the CRR values are generally lower compared to EC (max CRR = 75.86%). In both conditions, short-range func-

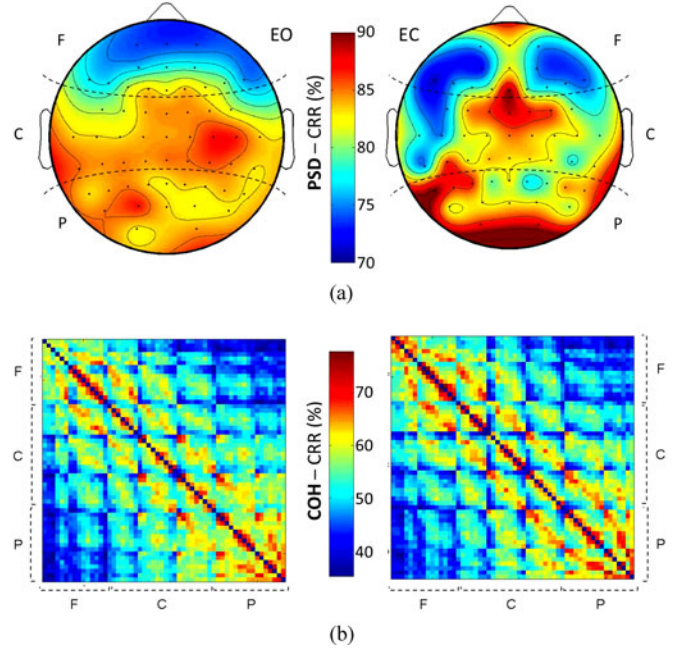


Fig. 1. Spatial distribution of CRR values obtained considering (a) PSD features from single EEG channel and (b) COH features from single channel pairs. In (b), the elements of the adjacency matrices code all the possible EEG channel pairs. They are organized in order to highlight the connectivity within and between three zones: frontal (F), central (C), and parieto-occipital (P). The two analyzed conditions EO (on the left) and EC (on the right) are reported for each of the two investigated spectral features.

tional connectivity carries more distinctive information as can be observed by the tendency of the highest CRR values to stand close to the main diagonal of the \mathbf{Adj} matrices.

Taken together, these findings show that COH features are less distinctive than PSD features in a single-element approach. This outcome is in line with our hypothesis that a functional brain network consisting of more elements “linked” together could better characterize different people, describing some aspects of brain organization assumed to be specific of each subject.

B. Match-Score Fusion

To improve performance, a fusion of the elements at the match score level is obtained for each brain zone (F, C, and P), within the same cross-validation framework described in Section II-E. The related CRR improvements with respect to the single element approach are shown in Fig. 2. Here, the two conditions EO and EC, and the two considered features PSD and COH, are compared. In general, the match-score fusion approach improves the performance with respect to the single element approach for each zone, condition, and feature. **Notably, a perfect recognition rate (CRR = 100%) is obtained when fusing the scores of the COH features**, for the EC condition (in all the zones) and for the EO condition (in the frontal zone). The different behavior in performance improvement between PSD and COH features can be in part explained by the lower variability of the PSD features vector across different brain regions (Supplementary File 4). In this case, most of distinctive information is supposed to be contained in the single elements. Instead,

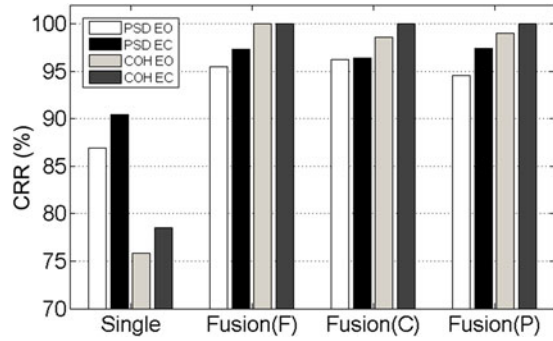


Fig. 2. Performances in terms of CRR (y-axis) obtained considering single-element classification versus match-score fusion in each brain zone (x-axis). The color of the bars codes the spectral feature and the condition according to the legend.

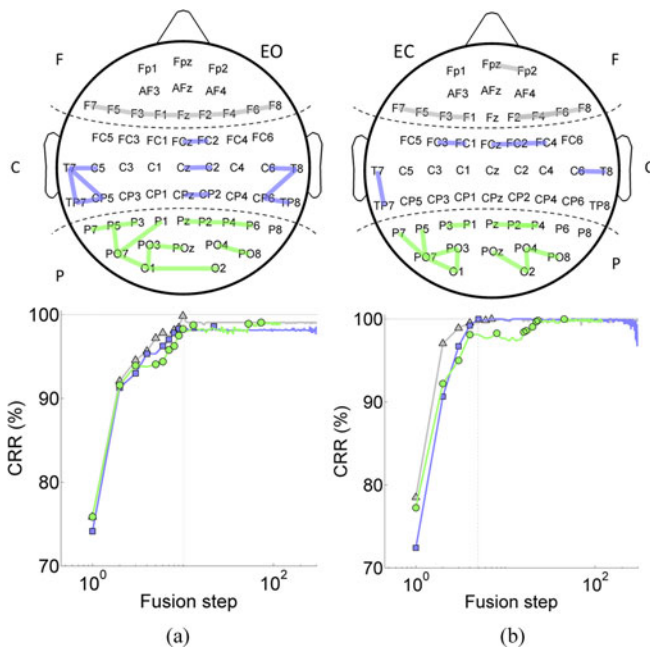


Fig. 3. Distinctive functional connectivity patterns in each brain zone (on the top) and related steps for the match score fusion selection (on the bottom). Results for the EO and EC to conditions are reported in (a) and (b), respectively. The color of each line in the bottom panels codes the CRR values obtained for different brain zones, according to the top panels. Symbol markers highlight the fusion steps that increased the overall CRR accuracy. Different symbols are used for different cerebral zones (F-triangles, C-circles, P-squares). X-axes are put into logarithmic scales for the sake of representation.

COH features vector tends to be more variable across brain regions and the inclusion of more COH elements can eventually improve the CRR, while single elements represent very partial information.

Fig. 3 shows the optimal combination of channel pairs in every zone for COH features (see Section II-E). Results are shown for the two conditions EO (a) and EC (b). The plots shown on the bottom part of the figure represent the steps of the match score fusion. Here, each highlighted symbol represents a subsequent improvement of the overall CRR, which leads to include the related channel pair in the final distinctive connectivity

pattern represented in the upper part of the figure. It can be noticed that the maximum value of CRR is achieved more rapidly for the EC condition, as shown by the vertical lines in the plots on the bottom part of the figure. The resulting distinctive connectivity patterns consist mainly of short-range COH elements, a result which is in line with the previous outcome reported in the single-element classification analysis. The topology of the more discriminant COH elements reveals a hemispheric symmetry with respect to the longitudinal line. In particular, the predominance of the frontal EEG sensors (line F7-F8) can be observed in both the EO and EC conditions. Neurophysiological evidence shows that specific genetic factors can influence EEG frontal activity [43]. Thus the highly discriminant spectral COH observed in this zone could in part reflect a subjective distinctiveness of brain functioning. We also report the involvement of temporo-parietal and dorsal centro-parietal sensors of the brain zone C. Brain regions near the temporo-parietal junction play a specific role in self-other distinction processes and in representing thoughts, beliefs, desires, and emotions [44], influenced by a combination of biological and environmental factors. A comprehensive analysis reporting the fusion steps for the COH features in all the conditions and zones is detailed in Table I, along with a description of the obtained identification accuracy and topology. A predominance of short-range connectivity characterizes the distinctive patterns for all the considered brain zones.

Notably, the inclusion of the long-range (i.e., interzone) connectivity in the fusion algorithm does not improve the recognition performance (Supplementary File 2). The superiority of short-range over long-range connectivity could be partially imputed to volume conduction effects, which are known to affect COH measurements [45]. Although removing those effects is important, in general, to estimate true interactions between the cortical generators, this would not represent an issue in our study. In fact, volume conduction effects depend on the morphology and electrical conductivity of the subject's head structures. In this regard, any possible volume conduction contributions on the EEG signals could instead represent a relevant personal trait to be exploited for the biometric recognition. As a partial confirmation of our claim, we report that the recognition performance of the imaginary coherence (robust to volume conduction effects [45]) is significantly lower than standard COH (Supplementary File 3).

To sum up, the results of the herein proposed analysis show that a perfect identification of 108 subjects (CRR = 100%) can be obtained considering spectral COH features within specific regions of the head, and fusing the respective information at the match score level. This result outperforms the state-of-the-art recognition performance obtained with EEG during resting states, notably a CRR = 98.73% for a dataset of 45 subjects [33] and a CRR = 97.5% for a dataset of 40 subjects [24].

C. Limitations and Possible Solution

The proposed approach presents methodological and technical limitations that should be taken into account in scenarios different from the presented experimental protocol. First, the

TABLE I
CRRs FOR COH FEATURES, OBTAINED THROUGH THE FUSION OF THE CHANNEL PAIRS REPORTED IN EACH ROW

Eyes-Open												
F	72,74	91,43	94,55	97,2	97,82	99,06	99,84	100				
	F2-F4	F1-F3	F4-F6	F3-F5	F6-F8	F1-Fz	F5-F7	F2-Fz				
C	74.14	91.28	92.99	95.33	96.26	97.04	97.82	98.29	98.44	98.6		
	TP7-T7	CP5-TP7	C5-T7	T8-C6	FC2-FCz	C2-Cz	CP2-CPz	CP5-T7	TP8-CP6	CP6-T8		
P	75.86	91.59	93.92	94.08	94.39	95.79	96.26	97.51	98.29	98.75	98.91	99.07
	P7-P5	PO4-PO8	O1-PO3	O1-PO7	P2-P4	PO7-P5	O1-O2	P2-Pz	P3-P5	P4-P6	POz-PO3	PO7-P1
Eyes-Closed												
F	77.26	97.04	97.82	98.6	98.75	99.06	99.69	100				
	F2-F4	F3-F5	F1-F3	F5-F7	F6-F8	F4-F6	Fp2-Fpz	F2-F6				
C	72.43	90.65	96.73	99.22	100							
	TP7-T7	FC2-FCz	FC2-FC4	C6-T8	FC1-FC3							
P	78.5	92.21	95.01	98.13	98.29	98.44	98.6	99.06	99.69	99.84	100	
	PO3-O1	PO4-PO8	PO7-O1	PO3-PO7	P2-P4	PO7-P7	PO7-P5	P1-P3	O2-PO4	O2-POz	P4-Pz	

Each column represents a step of the fusion, and the related accuracy achieved is reported together with the channel pair considered in that step (see Section E.). Results for EO, EC, and the three investigated brain zones are shown.

COH requires EEG signals to be (quasi)stationary. Appropriate short time windows should be selected by testing the stationarity of the signals [46]. Alternatively, different connectivity methods that do not require stationarity (e.g., wavelet-based) can be used [47]. Second, the Mahalanobis distance-based classifier assumes that features are Gaussian distributed. Possible deviation from Gaussianity should be then compensated by applying appropriate data transformations [37] or using reduced polynomial regression-based classifiers [48]. Third, the fusion approach implies many EEG sensors to be placed on the scalp. This affects the design of the biometric system and the time needed to establish a good skin-sensor electrical contact. Possible solutions can come from the technology development related to dry and miniaturized sensors, or contactless biosensors [49]. Finally, most of the computational time is spent during the offline enrollment and definition of the fusion steps (around 20 min on a current standard personal computer). Though it is not the aim of this study, we envisage that possible optimizations can be obtained by parallelizing the single-element ranking and the cross-validation runs described in Section II.

IV. CONCLUSION

In the past few years, there has been a growing interest in EEG-based biometric systems. Compared to other traits that are usually considered in biometrics (e.g., fingerprint, iris, voice, signature), EEG activity presents two main advantages, among others: *i*) it is harder to steal and *ii*) it is a dynamic measure, thus allowing for constant recognition and mental state monitoring [4].

Despite such interest, **classification performance decreases from maximum accuracy when the number of people to recognize becomes high, i.e., $N > 100$ [50], [51]. Possible causes rely on the methods that are commonly used to extract characteristic features from the EEG signals.** Indeed, the majority of these methods only consider the activity of a single brain region without taking into account its dynamic relationship with other regions. However, the human brain works as an interconnected system where different specialized areas continuously

exchange information through stable synchronous connectivity patterns [10].

In the present study, we propose to exploit such synchronous “communication” between different EEG sensors, under the hypothesis that this information could exhibit stronger intraclass invariant properties. Specifically, spectral coherence estimates within specific zones (i.e., frontal, central, parieto-occipital) are integrated according to a fusion at match score level [28] based on the sum rule. We test the proposed approach on a large number of subjects ($N=108$) having been recorded with a high-density EEG system with 56 sensors.

Taken together, the obtained results indicate that:

- 1) the combined use of spectral coherence and fusion algorithms significantly improves the overall recognition performance compared to existing techniques based on single element approaches and/or power spectrum estimates; and
- 2) a perfect recognition can be achieved in both eyes-closed and eyes-open resting states by considering eleven EEG sensors in the frontal region of the brain. This represents a technical advantage for future implementation of smart EEG-based biometric helmets.

Although connectivity-based approaches have not received much attention in this field, we suggest that they will probably turn out to be effective invariant features to further develop robust EEG-based user-recognition systems.

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