# Power-On-The-Airway: A Useful Concept for Pandemic Ventilators

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#### Abstract

Mechanical ventilation must do work on the airway in order to inflate the lungs. Considering the power done on the airway may have several uses:

- Computing the maximum required power on the airway in a clinical situation provides engineers a minimum power output requirment by an air drive mechanism.
- Power-on-the-airway is independent of the means of air production, whether by fan, blower, pump, piston, bag-squeezer, or bellows. It therefore may serve as a unifying means of controlling air production to meet a clinical goal independent of the means of production.

By specifying an *air drive* as a modular component in a ventilator system that produces air by doing work on the airway according to a standardized specification and protocol, it may be possible to separate the concern of air prodution from other concerns of building ventilators to address the COVID-19 pandemic. This approach provides supply chain resillience by allowing air drives to be an interachable part with no need for extensive redesign, testing, and certification.

### 1 Introduction

Let us define the term *air drive* to mean the mechanism that produces air and air/oxygen/medical gas mixtures in a mechanical ventilation system. Because of the COVID-19 pandemic, many humanitarian engineering teams have experimented with squeezing inexpensive Bag Mask Valves (BMVs), or *bag squeezers*. Other mechanisms include pistons, bellows, positive displacement pumps, which

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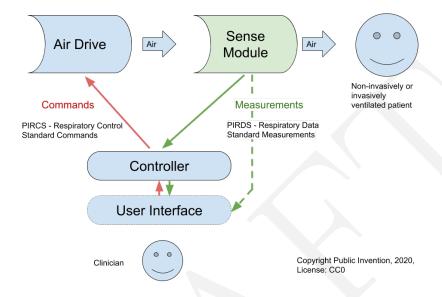


Figure 1: A Basic Modular Structure of a Ventilator

tend to produce a fixed volume against a variable pressure. Still other mechanisms such as velocity pumps, fans and blowers tend to produce a fixed pressure against a variable back-pressure leading to the injection of a variable volume. One goal in this paper is to unify these two very different mechanisms.

A second goal is to champion a modular approach to ventilator design and construction to better address the COVID-19 panedemic. As of June, 2020, many teams are independently building new ventilator designs. Cooperation and division of labor might increase the number of lives saved. This paper proposes a means of separating the technical problem of precisly producing medical air on demand from other concerns of building a ventilator. By providing a standard interface to the "Air Drive" module of Figure 1, work on that module can proceed independent of other modules. Finally, creating air drives as a module provides supply-chain resillience.

MIT has presented a useful computation of the work that must be done on the airway for maximum patient need, from which they conclude a minimum power requirement for an air drive for mechanical ventilation[1]. Expanding on this work is a second goal of this paper.

### 2 Physical Preliminaries

Roughly speaking, volume times pressure is work. To inject an infinitessimal amount of air in to any air vessel or across any air threshold, the work is the product of the pressure in at the threshold and the volume injected. A threshold into a vessel of fixed size is easy to analyze. A vessel such as a balloon whose volume is dependent on internal pressure is slightly more complicated. A rubber balloon has a *compliance* which is defined to be the change in volume with a change in pressure.

A human lung system is even more complicated, because it has has both static and dynamic compliance https://en.wikipedia.org/wiki/Lung\_compliance.

Nonetheless, if we use a simplified model, work done over time on an airway is the integral over time of injected volume multiplied by pressure, where both injected volume and pressure are a function of time.

If pressure in the airway is a constant p pascals, a machine which produces a flow of f cubic meters per second, the machine is perforning  $p \cdot f$  watts on the airway.

### 3 Ventilation Modes

Mechanical ventilators offer a number of control modes, the two simplest for invasive ventilation being pressure-control mode and volume-control mode. They patient may fight against the action of the ventilator, called dys-syncrhony. However, if we disregard this clinically important problem, the modes are simple.

Pressure control mode create inspiration by providing air at an approximately fixed pressure for a fixed period of time. Volume control mode pushes air at a potentially variable but limited to some maximum pressure into the airway until a volume is acheived.

Volume control mode is easy to acheive with a piston which is powerful enough: use the piston to push the desired volume of air out of a cylinder and into the airway. (A weak piston might not be able to do this.) In so doing we may control the speed of this push which will somewhat control the pressure. A positive-displacement pump with a small chamber may be pumped many times to achieve the desired volume; in this say a piston and positive-displacement pump are similar.

## 4 Human Breating Requirements

The ranges of pressures, flows, and volumes and the precisions with which they must be controlled to ventilate a sick human being may surprise mechanical engineers, and help us contextualize the problem. The medical profession universally uses cm  $H_2O$  as measure of physiological pressures. We summarize only the most relevant maximu values here:

- Maximum ventilaton volume in one minute is 80 liters.
- Maximum pressure needed to for ventilation is 80 cm H2O = 7845.32 Pa.
- Maximum instantaneous 250 liters per minute.
- A high-oxygen environment should be assumed. Engineers need to plan for anything in contact with medical air to have either 50% or 100% FiO2.

"In a normal person, at rest the work of breathing is about 0.35 J/L, and the power of breathing is about 2.4 J/min." https://derangedphysiology.com/main/cicm-primary-exam/required-reading/respiratory-system/Chapter% 20041/work-breathing-and-its-components#:~:text=Definitions%20of%20work% 20and%20power%20of%20breathing&text=Tada.,is%20about%202.4%20J%2Fmin. "Normal minute ventilation is between 5 and 8 L per minute (Lpm). Tidal volumes of 500 to 600 mL at 1214 breaths per minute yield minute ventilations between 6.0 and 8.4 L, for example. Minute ventilation can double with light exercise, and it can exceed 40 Lpm with heavy exercise." https://www.acepnow.com/article/avoid-airway-catastrophes-extremes-minute-ventilation/#:~:text=Normal%20minute%20ventilation%20is%20between,40%20Lpm%20with% 20heavy%20exercise.

Maximum presumed momentary flow rate: 250 lpm (this is flow rate measured by the Sensirion SFM3200)

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Maximum presumed momentary flow rate: 250 lpm (this is flow rate measured by the Sensirion SFM3200). Momentary flow rate is obviously much higher than minute ventilation due to time spent in expiration. (250 ; 40.)

Assume a large adult male is in respiratory distress. They may require a minute volume of 40 Lpm. A disease condition might make this less efficient, so let us assume 80 Lpm.

Maximum airway pressure may be assumed to be 40 to 50 cm H2O.

A very important reference: http://www.ubccriticalcaremedicine.ca/rotating/material/Lecture\_1%20for%20Residents.pdf states: "Lung compliance will change with age, body position, and various pathological entities. Normal adult lung compliance ranges from 0.1 to 0.4 L/cm H20. Compliance is

measured under static conditions; that is, under conditions of no flow, in order to eliminate the factors of resistance from the equation."

"In a spontaneously breathing adult, normal airway resistance is estimated at 2 to 3 cm  $\rm H2O/L/sec.$ "

The inspiring MIT E-Vent Power calculation: https://e-vent.mit.edu/mechanical/power-calculation/performs a pressure-based evaluation, becasue the Ambubag is guaranteed to have a volume greater than tidal volume (800ml) they apply.

## 5 Why use Power-on-the-Airway instead of Flowat-Pressure?

Power-on-the-airway (P) is the product of flow-into-the-airway (F) times current airway pressure (A):

$$P = F \cdot A \tag{1}$$

It is difficult to precisely and safely control ventilation without knowing the pressure in the airway (A) due to the extreme danger of barotrauma. Therefore one can ask, "Why not discuss flow-at-pressure instead of power-on-they-airway?" Since they are mathematically interchangeable, it is largely a matter of style. Power-on-the-airway has the advantage of being more relevant to mechanical engineers when operating on direct power devices. Flow-at-pressure makes more sense when considering pressure-release devices. In order to create a usable standard, we somewhat arbitrarily choose power-on-the-airway as the most useful to ventilator builders. It is important to note that clinicians should never need to know about this standard. We hope to insulate the doctor and patient from this decision, just as at some level they do not know or care what voltage is used internally by a device.

## 6 Practical Air Drive Components

Air flow may be produced by three basic mechanisms practical for addressing the pandemic.

- Pressure producing devices:
  - Fans and blowers
  - Centrifugal pumps
- Volume producing devices:
  - Positive displacement pumps
  - BMV squeezers
  - Pistons
  - Bellows
- Pressure releasing devices:
  - Electronically controlled valves,
  - Fulidically controlled devices.

### 6.1 Pressure Producing Devices

Pressure producing devices include fans, blowers, and centrifugal pumps, which all use a rotary motor to spin blades. The differ in blade configuration and housing.

In practice, the datasheets of fans show the flow of air they proceed agianst a given pressure. At some pressure, this flow drops to zero. In general, fans are provide high flow but develop low pressure. They are generally unsuitable for respiration, which requires lower flow and higher pressure.

Note the following language from the RespiraWorks team addresses the problem directly: https://docs.google.com/document/d/1CE33EcGAdlNdnJA9XW9oGD9veOWSuuBIR2MPmKtkjYQ/edit#

"Our design centers around a low inertia centrifugal blower, currently sourced from CPAP machines. These brushless fans with lifetime lubricated bearings can spin to high speeds very quickly, allowing a fine degree of time-resolved pressure control. At the same time, they can develop pressures well above 40 cmH2O; even accounting for flow losses, our test model exceeds 100 cmH2O."

"One of our main assumptions is that access to CPAP blowers will be uninterrupted. We believe both that they are sourced in large quantities (the vendors weve contacted in China have more than 5,000 in stock), and that they do not present manufacturing difficulties (fundamentally, it is only three injection molded parts and a brushless DC motor)."

One firm, AirFan, http://www.airfan.fr/mfa0300.html, makes fans for ventilators using a low-inertial centrifugal pump.

### 6.2 Volume Producing Devices

The world is full of positive-displacement pumps and compressors. Diaghram pumps are particularly suited because the airway is contained. Typical compressors fill tanks or tires to at least 35 psi = 2460.74 cm H2O, about 50 times

more than the higest medical breathing pressures of 50 cm H2O. A typical compressor to produce a 250 lpm flow (10 cubic feet per minute) costs more than \$200 and requires more than 1 horesepower (746 watts).

This typical pressure-too-high and flow-too-low situation may be why many teams have turned to using BMV squeezers, pumps and bellows, which can be considered positive-displacement pumps with an exceptionally large displacement that is pumped only once per breath. These devices have the apparent advantages of visible simplicity and supply-chain resillience.

A piston presents the problem of producing a reasonably tight seal without adding harmful lubricants into the high-oxygen airway. However, since breathing pressures are low, this may be a surmountable problem. A bellows with a flexible chamber, usually constrained to remain within a fixed volume, is another alternative. Both approaches tend to have simple geometries in which the change in volume can be easily calculated as a function of the change in the piston of fixed part of the bellows, making it straightforward to compute flow and therefore power-on-the-airway as a function of the position of the motive element.

On the other hand, a bag-squeezer produces relatively complicated geometry changes which may be highly dependent on potentially changing elasticity and deformability of the bag material. It may not be possible to compute change in volume easily. The MIT paper suggest that power applied to the bag produces power on the airway in rough proportion, but the constant of proportionality may change during the squeezing action. However, it is easy enough to simply measure the volume as a function of the position of the squeezing apparatus, and thus to use an MCU to produce accurate power-on-the-airway when demanded. It is difficult to see how a bag-squeezer could provide precise control of any kind without either careful calibration or adaptive control based on rapid pressure measurements [Giseburt].

### 6.3 Pressure Releasing Devices

- Pressure releasing devices:
  - Electronically controlled valves,
  - Fulidically controlled devices.

A relatively common approach to ventilation is to assume a source of highpressure air and control the release of this air into the airway with a control valve. This has even been done with pure fluidic control which has no moving parts by directing a flowing airstream into or away from the patient.

In such cases the power-on-the-airway is unrelated to power consumed by operation of the valve, and depends on the pressure and flow from the pressurized source. However, this is irrelevant to the control system.

### 6.4 Summary

To be supply-chain resilient, we would prefer to use commonly available parts. In general, fans produce too much flow and not enough pressure, and pumps produce too much pressure and not enough flow. This may be one of the reason for preponderance of "bag squeezer" designs in pandemic ventilator projects. Some blowers designed specifically for CPAP machiens have performance better matched to the breathing task. These may present supply-chain resillience problems.

### 7 Building an Air Drive

If a blower or centrifugal pump is used as the mechanism of an air drive and the speed of the blower or pump can be controlled by voltage, and air drive could consist of the blower, a means of digitally controlling voltage or pulse-width-modulation (PWM), an MCU to receive and interpret commands, and a map of the voltage or PWM required to produce a given flow/power at all allowable pressures. Such an air drive does not need a sensor. It simply a command in terms of watts, calls a subroutine to look up the voltage in a table or compute it via interpolation or some formula, and outputs the voltage control.

A positive displacement pump would be different. Generally any such pump produces a stable, known volume displacement with each stroke or rotation. The air drive would take its command in watts, divide the pressure sent by the controller to obtain the desired flow and then operate itself at a rate necessary to produce the desired flow.

A pressure gating valve would require that the pressure in the tank be known and the behavior of a valve be completely understand, but in principle it would also compute a desired flow and operate the valve to acheive that flow. It might, instead, have its own flow sensor and quickly adjust flow rate to the desired value by its own devices.

The whole point of the air drive is that the effect of all these machines will be unimportant or even unobservable to doctor and patient. It will not matter to them how the work is done.

## 8 Specification of a Power-on-the-airway Air Drive

Conceptually an air drive is an air-producing device which can be be controlled by specifying two values:

- Watts of work to be done on the airway, and
- The pressure of the airway.

In practice, these two values must be transmitted electronically to the air drive. Typically this would be done with an MCU controller that supports I2C, SPI, or a serial interface. The information could be encoded at the byte-level or

in a human-readable format like JSON. Likewise, a physical standard, such as the ISO 22mm airway connector, would make it easier in practice for air drives to be truly interchangable, but the defintion of such protocols to embody this approach is beyond the scope of this paper.

We assume that when an air drive receives a command, it is required to do whatever is necessary to produce the specified watts on the airway if the airway is at the specified pressure. It is to continue doing this until it receives the next command.

An air drive may or may not have its own ability to sense the pressure in the airway for its own purposes. It is acceptable for an air drive to be a rather unintelligent machine that was simply calibrated at manufacture time to produce the required flow against the specified pressure to produce the required watts.

### 9 How to Test a Power-on-the-airway Air Drive

The performance of an air drive can be measured with the following values:

- power producible against maximum pressure,
- duty cycle,
- power accuracy is a percentage,
- command repsonse time: maximum time to accept a new command in ms,
- power response time: maximum change in watts/ms per ms,
- mean time to failures in thousands of hours,

For example, a good air drive for mechanical ventilation would be able to produces 21 watts on the airway at any pressure up to 50 cm H2O within  $\pm 2.1 watts$ , operate at a 50% duty cycle, and have a response time 1 Watt/ms, reconfigurable every 10ms. Such a response time would allow the air drive, operating against a suitable mechanical system such as a test lung, to generate 50 cm H2O pressure at 250 lpm in 21 ms, and to release that pressure to zero when so ordered in 21 ms. It could reliably perform this work for thousands of hours at a duty cycle of 50%.

The resonse time is clinically important in order to allow efficient ventilation at high respiration rates. We do not yet have a mathematical model to understand the impact of low response time, but clearly if the air drive takes a long time to start doing work on the airway and a long time to release it, gas exchange and possibly even maximum tidal volume will be impaired. [See Schulz and Read, Anesthesia.]

To test an air drive, attach the air drive to a pneumatic cylinder. Install a flow and pressure sensor between the two. Weight or activate the pneumatic cylinder to produce a range of pressures from 0 to the specified maximum. Command the air drive to produce a range of powers up to the maximum specified

power. Perform this from a "standing start" or zero power and returning to zero power. The response time can be computed from the pressure and flow curve. At any point in time, power-on-the-airway is pressure times flows. Measure that the power-on-the-airway is within the specified accuracy.

If you don't have a pneumatic cylinder, a test lung can accomplish approximately the same test because it's small volume will quickly be pressurized. This will require a bit more study of power-on-the-airway to produce pressure, which will be a function of the restriction on the test lung, compliance, and total volume. Nonetheless it should be possible by ramping up power to measure all parameters at all pressures.

### 9.1 The Importance of Zero Power

It is important that zero power is a specifiable value which must be met by any air drive claiming to meet a spec. This situation may be illustrated by a plastic bag of 1-liter capcity stuffed inside a 500ml glass bottle. Such a model of a lung would be extreme, but must not be discounted. Such a lung model begins an in inspiration with extraordinarily high compliance, which means that a tiny positive pressure makes the first 500ml flow quickly into the lung model. The compliance then drops to almost zero: not amount of additional pressure will increase the air in the lung (treating air as imcompressible and assuming the bottle does not burst.)

However, we take as a principle that within the specifications a doctor should be able to prescribe any breathing that they see fit for the patient. So, upon reaching 500 ml, not more positive flow is possible, and therefore no positive work is possible. However, the air drive must not allow work to be done on it. That is, it must prevent the back flow of air into the air drive itself, which would be negative power on the airway. If a doctor says 500ml are to be held statically in the lungs for 1s, the air drive must be able to accomplish that be so verified, even if it is against zero flow. This has implications for some mechanical devices which must be considered.

## 10 Example Calculations

## 11 Implementing Ventilation Modes With Poweron-the-airway

In order to accomplish interchangability of air drives within a ventilator without changing the observable behavior of the ventilator, we imagine a controller which is sending commands to commands to the air drive. This controller implements one or more ventilation modes. The controller represent an algorithm for implementing a ventilation mode in terms of power-on-the-airway. In almost all cases, the algorithm will use pressure and possibly flow sensors on the airway

that the controller can read. The air drive may not be able to sense these things itself.

There are a number of ways such an algorithm could be implemented, but one of the most familiar would be as a PID controller. In the terminology of such systems, the power-on-the-airway in watts is the *control variable*, but the *error value* depends on the ventilation mode.

### 11.1 Pressure Control Mode

Pressure Controlled Ventilation (PCV) is perhaps the most basic. In this mode the error value of the PID controller would be the difference between the desired PIP and the airway pressure during the inspiration phase, which is a fixed time, and the difference between the desired PEEP and the airway pressure during the fixed expiration period. A controller with a single airway pressure sensor can implement this mode.

#### 11.2 Volume Control Mode

Volume Controlled Ventilation (VCV) may assign a fixed flow rate to performed on the airway until a tidal volume is acheived. (Generally there remains a maximum pressure, either implemented mechanically with a pop-off valve, or electronically.) Since flow rate and tidal volume are fixed, the time of inspiration is calculate by tidal volume divided by flow rate. Such a mode can be implemented in two ways. If the controller has a flow sensor, the flow in the airway subtracted from the prescribed flow can be the error value. However, interestingly, if we have an airdrive, the controller could implement volume control mode with a single pressue sensor, by multiplying the desired flow rate times the current pressure to produce the watts to command the air drive to produce. If the air drive does its job, the flow will be accurate to with the specified accuracy.

Note that in either case the simple and well-established PID controller approach can be used.

#### 11.3 Power-on-the-airway as a clinical measure

The integration of power over time is work. Although a patient's lung restriction and compliance may change over time, any inspiration provided by a power-on-the-airway drive automatically provides the power of breathing if you simply sum up the watts commanded and divided by time in each time interval between commands. A controller using a power-on-the-airway drive thus almost automatically computes the inspiratory work of breathing.

We speculate that it might be clinically valuable to define a ventilation mode which controls the power-on-the-airway done in a given insipriation.

# 12 Future Work

## References

 $[1]\,$  MIT Emergency Ventilator: Power Calculation, 2020. [Online; accessed 05–June-2020].