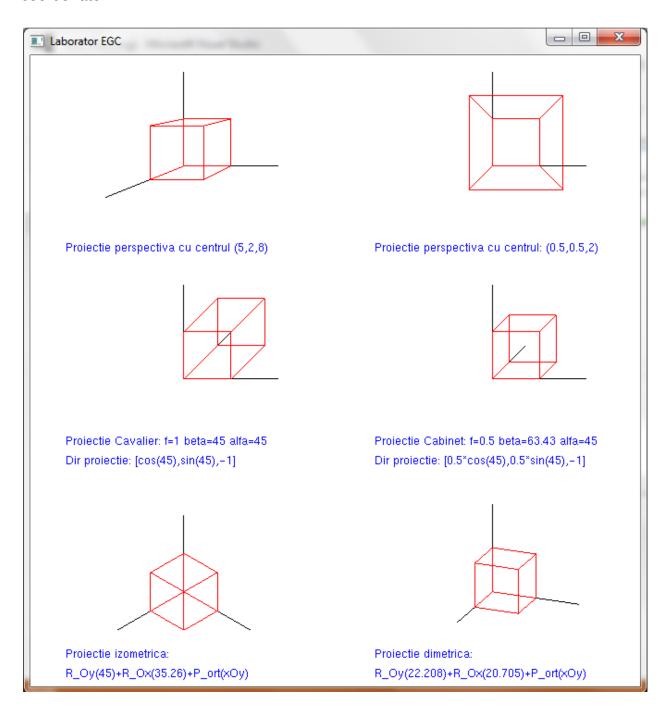
Program care afişează în fereastra aplicației 6 proiecții ale unui cub

In spațiul 3D cubul are laturile egale cu 1, fețele paralele cu planele principale ale sistemului de cordonate si colțul de (xmin, ymin, zmin) in originea sistemului de coordonate.



```
// Cele 6 proiectii se creaza in 6 contexte vizuale
Visual2D v2d1,v2d2,v2d3,v2d4,v2d5,v2d6;
Object3D cube;
PolyLine3D axa_ox, axa_oy, axa_oz;
Text text1, text2, text3, text4, text5, text6, text32, text42, text52, text62;
float n=1; // latura cubului
//functia care permite adaugarea de obiecte
void DrawingWindow::init()
{
  //adaugare contexte vizuale
  v2d1.init(-2.5,-2,2.5,2.5,0,0,DrawingWindow::width/2,DrawingWindow::height/3);
  v2d2.init(-2.5,-
2,2.5,2.5,DrawingWindow::width/2,0,DrawingWindow::width,DrawingWindow::height/3);
v2d3.init(-2.5,-2,2.5,2.5,0,DrawingWindow::height/3,DrawingWindow::width/2, 2 *
                                                          DrawingWindow::height/3);
  v2d4.init(-2.5,-
2,2.5,2.5,DrawingWindow::width/2,DrawingWindow::height/3,DrawingWindow::width, 2*
                                                           DrawingWindow::height/3);
  v2d5.init(-2.5,-2,2.5,2.5,0,2 *
DrawingWindow::height/3, DrawingWindow::width/2, DrawingWindow::height);
  v2d6.init(-2.5,-2,2.5,2.5,DrawingWindow::width/2,2 *
DrawingWindow::height/3, DrawingWindow::width, DrawingWindow::height);
  v2d1.tipTran(true);
  v2d2.tipTran(true);
  v2d3.tipTran(true);
  v2d4.tipTran(true);
  v2d5.tipTran(true);
  v2d6.tipTran(true);
//creare cub
  vector <Point3D> vertices;
  vector <Face> faces;
 //varfurile de jos
  vertices.push back( Point3D(0,0,0));
  vertices.push back(Point3D(n,0,0));
```

```
vertices.push back( Point3D(n,0,n));
 vertices.push_back( Point3D(0,0,n));
//varfurile de sus
 vertices.push back( Point3D(0,n,0));
 vertices.push_back( Point3D(n,n,0));
 vertices.push_back( Point3D(n,n,n));
 vertices.push back( Point3D(0,n,n));
//cele 6 fete
 vector <int> contour;
 //fata jos
      contour.clear();
      contour.push back(0);
      contour.push back(1);
      contour.push back(2);
      contour.push back(3);
      faces.push_back( Face(contour));
//fata sus
      contour.clear();
      contour.push back(4);
      contour.push back(5);
      contour.push back(6);
      contour.push_back(7);
      faces.push_back( Face(contour));
//fata fata
      contour.clear();
      contour.push back(0);
      contour.push back(1);
      contour.push back(5);
      contour.push back(4);
      faces.push_back( Face(contour));
//fata dreapta
      contour.clear();
      contour.push back(1);
      contour.push back(2);
      contour.push back(6);
      contour.push back(5);
      faces.push back( Face(contour));
//fata spate
      contour.clear();
```

```
contour.push back(2);
      contour.push back(3);
      contour.push back(7);
      contour.push back(6);
      faces.push_back( Face(contour));
//fata stanga
      contour.clear();
      contour.push back(3);
      contour.push back(0);
      contour.push back(4);
      contour.push back(7);
      faces.push back(Face(contour));
cube.init(vertices,faces,Color(1,0,0),false);
// adauga cubul in cele 6 contexte vizuale
      addObject3D to Visual2D(cube,v2d1);
      addObject3D to Visual2D(cube,v2d2);
      addObject3D to Visual2D(cube,v2d3);
      addObject3D to Visual2D(cube,v2d4);
      addObject3D to Visual2D(cube,v2d5);
      addObject3D to Visual2D(cube,v2d6);
//Creaza axele sistemului de coordonate 3D
      vector <Point3D> vertices Ox;
      vector <Point3D> vertices Oy;
      vector <Point3D> vertices Oz;
      vertices Ox.push back( Point3D(0,0,0));
      vertices Ox.push back(Point3D(2,0,0));
      vertices Oy.push_back( Point3D(0,0,0));
      vertices Oy.push back( Point3D(0,2,0));
      vertices Oz.push back( Point3D(0,0,0));
      vertices Oz.push back(Point3D(0,0,2));
      axa ox.init(vertices Ox,Color(0,0,0));
      axa oy.init(vertices Oy,Color(0,0,0));
      axa oz.init(vertices Oz,Color(0,0,0));
```

```
// adauga axele in cele 6 contexte vizuale
      addObject3D to Visual2D(axa ox,v2d1);
      addObject3D to Visual2D(axa oy,v2d1);
      addObject3D_to_Visual2D(axa_oz,v2d1);
      addObject3D to Visual2D(axa ox,v2d2);
      addObject3D to Visual2D(axa oy,v2d2);
      addObject3D to Visual2D(axa oz,v2d2);
      addObject3D to Visual2D(axa ox,v2d3);
      addObject3D to Visual2D(axa oy,v2d3);
      addObject3D to Visual2D(axa oz,v2d3);
      addObject3D to Visual2D(axa ox,v2d4);
      addObject3D to Visual2D(axa oy,v2d4);
      addObject3D to Visual2D(axa oz,v2d4);
      addObject3D to Visual2D(axa ox,v2d5);
      addObject3D to Visual2D(axa oy,v2d5);
      addObject3D to Visual2D(axa oz,v2d5);
      addObject3D to Visual2D(axa ox,v2d6);
      addObject3D to Visual2D(axa oy,v2d6);
      addObject3D_to_Visual2D(axa_oz,v2d6);
//text
      text1.init("Proiectie perspectiva cu centrul (5,2,8)",Point2D(-2.5,-
1.8),Color(0.0,1),BITMAP HELVETICA 12);
      text2.init("Proiectie perspectiva standard: (0,0,-d)",Point2D(-2.5,-
1.8),Color(0,0,1),BITMAP_HELVETICA 12);
      text3.init("Proiectie Cavalier: f=1 beta=45 alfa=45",Point2D(-2.5,-
1.4),Color(0,0,1),BITMAP HELVETICA 12);
      text32.init("Dir proiectie: [-cos(45),-sin(45),-1]",Point2D(-2.5,-
1.8),Color(0,0,1),BITMAP HELVETICA 12);
      text4.init("Proiectie Cabinet: f=0.5 beta=63.43 alfa=45",Point2D(-2.5,-
1.4),Color(0,0,1),BITMAP HELVETICA 12);
      text42.init("Dir proiectie: [-0.5*cos(45),-0.5*sin(45),-1]",Point2D(-2.5,-
1.8),Color(0,0,1),BITMAP HELVETICA 12);
```

```
text5.init("Proiectie izometrica:",Point2D(-2.5,-
1.4),Color(0,0,1),BITMAP HELVETICA 12);
      text52.init("R Oy(45)+R Ox(35.26)+P ort(xOy)",Point2D(-2.5,-
1.8),Color(0,0,1),BITMAP HELVETICA_12);
      text6.init("Proiectie dimetrica:",Point2D(-2.5,-
1.4),Color(0,0,1),BITMAP_HELVETICA_12);
      text62.init("R Oy(22.208)+R Ox(20.705)+P ort(xOy)",Point2D(-2.5,-
1.8),Color(0,0,1),BITMAP HELVETICA 12);
      addText to Visual2D(text1,v2d1);
      addText to Visual2D(text2,v2d2);
      addText to Visual2D(text3,v2d3);
      addText to Visual2D(text32,v2d3);
      addText to Visual2D(text4,v2d4);
      addText to Visual2D(text42,v2d4);
      addText to Visual2D(text5,v2d5);
      addText to Visual2D(text52,v2d5);
      addText to Visual2D(text6,v2d6);
      addText to Visual2D(text62,v2d6);
      int i;
      Transform3D::loadIdentityModelMatrix();
//primul cub - proiectie perspectiva cu centru oarecare de proiectie
      Transform3D::perspectiveProjectionMatrix(5,2,8);
      for (i = 0; i < v2d1.visual2D objects3D.size(); i++)
      {
             Transform3D::applyTransform(v2d1.visual2D objects3D[i]);
      }
//al doilea cub - proiectie perspectiva cu centru oarecare de proiectie
      Transform3D::perspectiveProjectionMatrix(0.5,0.5,2);
      for (i = 0; i < v2d2.visual2D objects3D.size(); i++)
      {
             Transform3D::applyTransform(v2d2.visual2D objects3D[i]);
      }
//al treilea cub - proiectie Cavalier: f = 1, alfa = 45 grade => a = cos(PI/4),
// b = \sin(PI/4), c = -1
```

```
Transform3D::parallelProjectionMatrix(cos(PI/4), sin(PI/4), -1);
      // sau Transform3D::obliqueProjectionMatrix (1, 45);
      for (i = 0; i < v2d3.visual2D objects3D.size(); i++)
      {
             Transform3D::applyTransform(v2d3.visual2D objects3D[i]);
      }
// al patrulea cub - proiectie Cabinet: f = 0.5, alfa = 45 grade => a = 0.5 * cos(PI/4),
// b = 0.5 * sin(PI/4), c = -1
      Transform3D::parallelProjectionMatrix(0.5 * cos(PI/4), 0.5 * sin(PI/4),-1);
      // sau Transform3D::obliqueProjectionMatrix (0.5, 45);
      for (i = 0; i < v2d4.visual2D objects3D.size(); i++)
             Transform3D::applyTransform(v2d4.visual2D objects3D[i]);
//al cincilea cub - proiectie izometrica
      //rotatie fata de Oy (cu unghiul 45 grade),
      // urmata de rotatie fata de Ox (cu unghiul 35.26 grade)
      // urmata de proiectie ortografica in planul xOy
      Transform3D::loadIdentityModelMatrix();
      Transform3D::rotateMatrixOy(45.0f * PI/180.0f);
      Transform3D::rotateMatrixOx(35.26f * PI/180.0f);
      Transform3D::parallelProjectionMatrix(0,0,1);
      // sau Transform3D::axonometricProjectionMatrix(35.26, 45);
      for (i = 0; i < v2d5.visual2D objects3D.size(); i++)
             Transform3D::applyTransform(v2d5.visual2D objects3D[i]);
      }
//al saselea cub - proiectie dimetrica
      //rotatie fata de Oy (cu unghiul 22.208 grade),
      // urmata de rotatie fata de Ox (cu unghiul 20.705 grade)
      // urmata de proiectie ortografica in planul xOy
      Transform3D::loadIdentityModelMatrix();
      Transform3D::rotateMatrixOy(22.208f * PI/180.0f);
      Transform3D::rotateMatrixOx(20.705f * PI/180.0f);
       Transform3D::parallelProjectionMatrix(0,0,1);
      // sau Transform3D::axonometricProjectionMatrix(20.705, 22.208);
      for (i = 0; i < v2d6.visual2D objects3D.size(); i++)
```

```
{
             Transform3D::applyTransform(v2d6.visual2D objects3D[i]);
// adauga cele 6 contexte vizuale in fereastra curenta
      addVisual2D(v2d1);
      addVisual2D(v2d2);
      addVisual2D(v2d3);
      addVisual2D(v2d4);
      addVisual2D(v2d5);
      addVisual2D(v2d6);
}
//functia care se apeleaza la redimensionarea ferestrei
void DrawingWindow::onReshape(int width,int height)
{
      v2d1.poarta(0,0,width/2,height/3);
      v2d2.poarta(width/2,0,width,height/3);
      v2d3.poarta(0,height/3,width/2,2 * height/3);
      v2d4.poarta(width/2,height/3,width,2 * height/3);
      v2d5.poarta(0,2 * height/3,width/2,height);
      v2d6.poarta(width/2,2 * height/3,width,height);
}
int main(int argc, char** argv)
 //creare fereastra
       DrawingWindow dw(argc, argv, 600, 600, 200, 50, "Laborator EGC");
      //se apeleaza functia init() - in care s-au adaugat obiecte
      dw.init();
 //se intra in bucla principala de desenare
      dw.run();
      return 0;
}
```