Topics in Physics - C. Mukku

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Tensor algebra preliminaries

1.1 Raising and lowering of two indeces simeltaneously

Note that

$$a_i b^i = (a^j g_{ij}) b^i = (a^j g_{ij}) (b_k g^{ki})$$

In minkowski space, we know that $g^{ij}=0$ if $i\neq j$, and $(g^{ii}g_{ii})^2=1$, so we can rewrite the above expression as:

$$(a^{j}g_{ij})(b_{k}g^{ki}) =$$
$$(a^{i}g_{ii})(b_{i}g^{ii}) =$$
$$a^{i}b_{i}$$

Lagrangian, Hamiltonian mechanics

Mechanics in terms of generalized coords.

2.1 Lagrangian

Define a functional. L over the config. space of partibles q^i , $qdot^i$. $L = L(q^i, qdot^i)$. We have an explicit dependence on t.

$$L = KE - PE$$

Assuming a 1-particle system of unit mass,

$$L = \frac{1}{2}\dot{q}^2 - V(q)$$

Assuming an n-particle system of unit mass,

$$L = \sum_{i} \frac{1}{2} q dot^{i^2} - V(q^i)$$

2.2 Variational principle

Take a minimum path from A to B. Now notice that the path that is slightly different from this path will have some delta from the minimum.

Action

$$S(t0, t1) = \int L dt = \int_{t0}^{t1} L(q^i, qdot^i) dt$$

. Least action: $\delta S = 0$

In physics, we try to minimise the action L = T - V where T is the Kinetic energy (Travail), and V (Voltage) is the Potential energy.

So, the question is, why does minimising the lagrangian work, and how do we get the euler-lagrange equations from this?

Functional calculus

this chapter develops a completely handway physics version of functional analysis.

Definition 1 A functional F is a function: $F:(\mathbb{R}\to\mathbb{R})\to\mathbb{R}$

Notation 1 Evaluation of a functional F with respect to f is denoted by F[f].

3.1 Functional Derivative - take 1

Consider a functional $F: (\mathbb{R} \to \mathbb{R}) \to \mathbb{R}$, a function $f: \mathbb{R} \to \mathbb{R}$, and a "test function" $\phi: \mathbb{R} \to \mathbb{R}$. Consider a functional F. We only define the derivative of a functional F with respect to a function f by what happens under an integral sign as follows:

$$\int \frac{\delta F}{\delta f}(x)\phi(x)dx = \lim_{\epsilon \to 0} \frac{F[f + \epsilon \phi] - F[f]}{\epsilon}$$

Now, we can define a small variation in F as:

$$\delta F : (\mathbb{R} \to \mathbb{R}) \times (\mathbb{R} \to \mathbb{R}) \to \mathbb{R}$$
$$\delta F(f, \phi) \equiv \int \frac{\delta F}{\delta f}(x) \phi(x) dx$$

Intuitively, δF tells us the variation of the function f along a test function ϕ . So, it encapsulates some kind of "directional derivative".

So, we can look at $\frac{\delta F}{\delta f}$ as a functional as follows:

$$\frac{\delta F}{\delta f} : (\mathbb{R} \to \mathbb{R}) \to \mathbb{R}$$
$$\frac{\delta F}{\delta f}(\phi) = \delta F(f, \phi)$$

Wehre $\frac{\delta F}{\delta f}$ allows us to "test" the change of F with respect to f along a given "direction" ϕ .

3.2 Functional Derivative as taught in class

Substitute $\phi = \delta(x - p)$. Now, the quantity:

$$\frac{\delta F}{\delta f}\phi(x) = \delta F(f, \delta(x-p))$$

Rewriting δF by sticking it under an integral:

$$\int \frac{\delta F}{\delta f}(x)\delta(x-p)\mathrm{d}x = \lim_{\epsilon \to 0} \frac{F[f + \epsilon\delta(x-p)] - F[f]}{\epsilon}$$
$$\frac{\delta F}{\delta f}\Big|_{p} = \lim_{\epsilon \to 0} \frac{F[f + \epsilon\delta(x-p)] - F[f]}{\epsilon}$$

That is, we can start talking about "derivative of the functional F with respect to a function f at a point p" as long as we only test the functional F against δ -functions.

So, we can alternatively define this quantity as:

$$\left. \frac{\delta F}{\delta f} \right|_{p} \equiv \lim_{\epsilon \to 0} \frac{F[f + \epsilon \delta(x - p)] - F[f]}{\epsilon}$$

While this does not "look like a functional", it actually is, if we mentally replace:

$$p \to \int - \delta(x-p) \mathrm{d}x$$

This is how mukku got that expression.

3.3 Common functional derivatives

3.3.1
$$F[f] = \int_0^\infty f dx$$

$$\frac{\delta F[f]}{\delta f(x_0)} = \lim_{\epsilon \to 0} \frac{\int_0^\infty (f + \epsilon \delta(x - x_0)) dx - \int_0^\infty f dx}{\epsilon}$$
$$= \int_0^\infty \delta(x - x_0) dx = 1$$

3.3.2
$$F[f] = \int_0^\infty g[f] dx$$

This does not actually type-check for me. $g:(\mathbb{R}\to\mathbb{R})\to reals$, so I don't fully understand what we are "varying" where when we integrate with respect to dx.

So, there's something bizarre here that I don't understand — the integral doesn't really make sense.

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3.3.3 Derivative of $F[\phi] \equiv \int (\frac{\partial \phi}{\partial y})^2$

$$\left. \frac{\delta F}{\delta f} \right|_{p} = \int \left(\frac{\partial \phi}{\partial y} \right)^{2}$$

3.4 Deriving E-L from functional magic

3.5 Weird things in Functional Analysis as taught in class

Consider the functional

$$J[f] = \int g[f']dy$$
:

since g is a functional, it has a type $g:(\mathbb{R}\to\mathbb{R})\to\mathbb{R}$. So, our integrand must be some function df, and not some space component dy. I don't understand what the definition of J means.

Maxwell's equations in Minkowski space

Let us first review Maxwell's equations:

$$\nabla \cdot E = \frac{\rho}{\epsilon_0}$$
 (Electric charges produce fields)

 $\nabla \cdot B = 0$ (Only magnetic dipoles exist)

$$\nabla \times E = -\frac{\partial B}{\partial t}$$
 (Lenz Law / Faraday's law - time varying magnetic field induces current that opposes it)

$$\nabla \times B = \mu_0 \left(J + \epsilon_0 \frac{\partial E}{\partial t} \right)$$
 (Ampere's law + fudge factor)

4.1 Constructing F, or Tensorifying Maxwell's equations

Begin with the equation that $\nabla \cdot B = 0$. This tells that B can be written as the curl of some other field:

$$B \equiv \nabla \times A \tag{4.1}$$

Expanding this equation of B in tensorial form:

$$B^{i} = \mathcal{E}^{ijk} \partial_{j} A^{k}$$

$$\tag{4.2}$$

Next, take $\nabla \times E = -\frac{\partial B}{\partial t}$.

$$\nabla \times E = -\frac{\partial B}{\partial t} = \frac{\partial (\nabla \times A)}{\partial t} = \nabla \times \frac{\partial A}{\partial t}$$

$$\nabla \times \left(E + \frac{\partial A}{\partial t} \right) = 0$$

writing this as the gradient of some field ϕ scaled by $\alpha : \mathbb{R}$

$$E + \frac{\partial A}{\partial t} = \alpha (\nabla \phi)$$
$$E = \alpha \nabla \phi - \frac{\partial A}{\partial t}$$

Since electrostatics is time-independent, we choose to think of $\alpha = -1$, so we can interpret ϕ as the potential.

$$E^{i} = -\frac{\partial \phi}{\partial x^{k}} g^{ik} - \frac{\partial A^{i}}{\partial t}$$

$$\tag{4.3}$$

A slight reformulation (since we know that in Minkowski space, $\partial_t = \partial_0$) we get the equation:

$$E^{i} = -g^{ik}\partial_{k}\phi - \partial_{0}A^{i}$$

$$\tag{4.4}$$

We get the metric $g^i k$ involved to raise the covariant $\frac{\partial \phi}{\partial x^k}$ into the contravariant E^i .

(Sid question: how does one justify switching $\nabla \times$ and ∂ ? It feels like some algebra)

Here be magic! We define A new rank-2 tensor in Minkowski space-time, called F (for Faraday),

$$F_{\mu\nu} \equiv \partial_{\mu} A_{\nu} - \partial_{\nu} A_{\mu} \tag{4.5}$$

(Sid question: why is this object $F_{\mu\nu}$ covariant? What does this mean?)

Lemma 1 $F_{\mu\nu}$ is antisymmetric.

Lemma 2 $F_{\mu\nu}$ has 6 degrees of freedom

Proof. Number of degrees of freedom of F:

$$\frac{4^2 \text{ (total)} - 4 \text{ (diagonal)}}{2 \text{ (anti-symmetry)}} = 6$$

Notice that F is a 1-form!

4.2 Expressing B, E in terms of F

We now wish to re-expresss B^{ij} and E^{ij} in terms of F, so that this F captures all of maxwell's equations.

$$B^{i} = \mathcal{E}^{ijk} \partial_{j} A^{k} = \mathcal{E}^{ikj} \partial_{k} A^{j}$$
 by k, j being free variables
$$B^{i} = \frac{1}{2} \left(\mathcal{E}^{ijk} \partial_{j} A^{k} + \mathcal{E}^{ikj} \partial_{k} A^{j} \right)$$
 Substituting $\partial_{j} A_{k} - \partial_{k} A_{j} = F_{jk}$,
$$B^{i} = \frac{1}{2} \mathcal{E}^{ijk} F_{jk}$$

So, B in terms of F is:

$$B^{i} = \frac{1}{2} \mathcal{E}^{ijk} F_{jk}$$

$$\tag{4.6}$$

Similarly, we wish to write E in terms of F. The algebra is as follows:

$$E^{i} = -g^{ik}\partial_{k}\phi - \partial_{0}A^{i}$$

$$E^{i} = -g^{ik}\partial_{k}\phi - \partial_{0}g^{ik}A_{k}$$
 Is this allowed? Am I always allowed to insert the g_{ik} ?
$$E^{i} = -g^{ik}(\partial_{k}\phi + \partial_{0}A_{k})$$

Since $k = \{1, 2, 3\}$ (k is spacelike coordinates), and we would like to relate ϕ with A (to unify E), we set:

$$A_0 \equiv -\phi \tag{4.7}$$

Continuing the derivation,

$$E^{i} = -g^{ik}(\partial_{k}(-A_{0}) + \partial_{0}A_{k})$$

$$E^{i} = -g^{ik}(\partial_{0}A_{k} - \partial_{k}A_{0})$$

$$E^{i} = -g^{ik}F_{0k}$$

So, finally, the relation is:

$$E^i = -g^{ik} F_{0k} \tag{4.8}$$

Let us reconsider what we believed E to be. We had:

$$E = -\nabla \phi - \frac{\partial A}{\partial t}$$

However, comparing dimensions, space derivative of $\phi =$ time derivative of A. This means that $\frac{\delta\phi}{\delta x} = \frac{\delta A}{\delta y}$, and so $\frac{\delta\phi}{\frac{\delta x}{\delta t}} = \delta A$. We arbitrarily pick c as our measuring stick for $\frac{\delta x}{\delta t}$. Also, in minkowski space, our measuring stick is actually (ct, x, y, z), so $\partial_0 = \partial_{ct}$ So, when we write the equation for E, we should actually write

$$E = c \left(-\frac{\nabla \phi}{c} - \frac{\partial A}{\partial ct} \right)$$

$$E^{i} = cF^{i0}$$
(4.9)

which becomes:

4.3 Rewriting Maxwell's equations in terms of F

Now that we have constructed the Faraday tensor F, we wish to re-expresss Maxwell's equations in terms of this object. This will give us a compact form of the laws which are invariant under coordinate transforms.

4.3.1 Combining (1)
$$\nabla E = \frac{\rho}{\epsilon_0}$$
, (4) $\nabla \times B = \mu_0 J + \frac{\partial E}{\partial t}$

1. Using (4)
$$\nabla \times B = \mu_0 J + \frac{\partial E}{\partial t}$$

We consider the 4th Maxwell equation:

$$\nabla \times B = \mu_0 J + \epsilon_0 \mu_0 \frac{\partial E}{\partial t}$$

$$\nabla \times B = \mu_0 J + \frac{1}{c^2} \frac{\partial E}{\partial t}$$
Converting to indices,
$$(\nabla \times B)^i = \mu_0 J^i + \frac{1}{c} \frac{\partial E^i}{\partial ct}$$

$$= \mu_0 J^i + \frac{1}{c} \frac{\partial E^i}{\partial X^0}$$

$$= \mu_0 J^i + \frac{\partial F^{i0}}{\partial X^0}$$

$$= \mu_0 J^i + \partial_0 F^{i0}$$
(From $E^i = cF^{i0}$)
$$= \mu_0 J^i + \partial_0 F^{i0}$$

Now, we start to simplify the LHS, $\nabla \times B$:

$$(\nabla \times B)^{i} = \mathcal{E}^{ijk} \partial_{j} B_{k}$$
Since $B^{k} = \frac{1}{2} \mathcal{E}^{kmn} F_{mn}$,
$$B_{k} = \frac{1}{2} \mathcal{E}_{kmn} F^{mn}$$
,
$$(\mathbf{TODO: this is scam})$$

$$(\nabla \times B)^{i} = \mathcal{E}^{ijk} \partial_{j} \left(\frac{1}{2} \mathcal{E}_{kmn} F^{mn} \right) = \frac{1}{2} \mathcal{E}^{ijk} \mathcal{E}_{kmn} \partial_{j} F^{mn}$$

Aside: We need to know how to evaluate $\mathcal{E}^{ijk}\mathcal{E}_{kmn}$:

$$\mathcal{E}_{i_1,i_2,\dots,i_n}\mathcal{E}_{j_1,j_2,\dots j_n} = \det \left\{ \begin{vmatrix} \delta_{i_1j_1} & \delta_{i_1j_2} & \dots & \delta_{i_1j_n} \\ \delta_{i_2j_1} & \delta_{i_2j_2} & \dots & \delta_{i_2j_n} \\ \vdots & \vdots & \ddots & \vdots \\ \delta_{i_nj_1} & \delta_{i_nj_2} & \dots & \delta_{i_nj_n} \end{vmatrix} \right\}$$

$$\mathcal{E}^{ijk}\mathcal{E}^{imn} = -1(\delta^m_j \delta^n_k - \delta^n_j \delta^m_k)$$

He argued that we get a -1 factor here due to the presence of the metric. I'm not fully convinced, but I can handwave this using the magic words "tensor density".

Plugging both equations together,

$$\begin{split} &\frac{1}{2}\mathcal{E}^{ijk}\mathcal{E}_{kmn}\partial_{j}F^{mn} = \mu_{0}J^{i} + \partial_{0}F^{i0} \\ &(\text{Since }kij \text{ is an even permutation of }ijk): \\ &\frac{1}{2}\mathcal{E}^{kij}\mathcal{E}_{kmn}\partial_{j}F^{mn} = \mu_{0}J^{i} + \partial_{0}F^{i0} \\ &(\text{Using }\mathcal{E}^{kij}\mathcal{E}_{kmn}) = -1(\delta^{m}_{i}\delta^{n}_{j} - \delta^{n}_{i}\delta^{m}_{j}): \\ &\frac{1}{2}\big[-\left(\delta^{i}_{m}\delta^{j}_{n} - \delta^{i}_{n}\delta^{j}_{m}\right)\big]\partial_{j}F^{mn} = \mu_{0}J^{i} + \partial_{0}F^{i0} \\ &-\frac{1}{2}\big[\partial_{n}F^{in} - \partial_{m}F^{mi}\big] = \mu_{0}J^{i} + \partial_{0}F^{i0} \\ &(F \text{ is anti-symmetric, so rewriting }\partial_{m}F^{mi} = -\partial_{m}F^{im}): \\ &-\frac{1}{2}\big[\partial_{n}F^{in} + \partial_{m}F^{im}\big] = \mu_{0}J^{i} + \partial_{0}F^{i0} \\ &(\text{Replacing }\partial_{m}F^{im} \equiv \partial_{n}F^{in} \text{ since }m \text{ is free}): \\ &-\left[\partial_{m}F^{im}\right] = \mu_{0}J^{i} + \partial_{0}F^{i0} \\ &\mu_{0}J^{i} + \partial_{0}F^{i0} + \partial_{m}F^{im} = 0 \\ &\mu_{0}J^{i} + \partial_{u}F^{i\mu} = 0 \end{split} \qquad (\mu = \{0, 1, 2, 3\})$$

This gives us a continuity-style equation, linking the current density J to the rate of change of F.

$$\mu_0 J^i + \partial_\mu F^{i\mu} = 0$$
 $(\mu = \{0, 1, 2, 3\})$

Second part, using 1st equation

$$\nabla E = \frac{\rho}{\epsilon_0}$$

$$\partial_i E^i = \frac{\rho}{\epsilon_0}$$
(Substituting $E^i = cF^{i0}$, $c^2 = \frac{1}{\mu_0 \epsilon_0}$):
$$c\partial_i F^{i0} = \frac{\rho}{\epsilon_0} = \frac{\rho \mu_0}{\mu_0 \epsilon_0} = \rho \mu_0 c^2$$

$$\partial_i F^{i0} = \mu_0 c \rho$$
(Since F is anti-symmetric, $F^{00} = 0$, Hence):
$$\partial_0 F^{00} + \partial_i F^{i0} = \mu_0 c \rho$$

$$\partial_\mu F^{\mu 0} = \mu_0 c \rho$$

$$\partial_{\mu}F^{\mu 0} = \mu_0 c \rho \tag{4.10}$$

Combining part 1 and part 2:

$$\mu_0 J^i + \partial_\mu F^{i\mu} = 0$$
 (From B)

$$\partial_\mu F^{i\mu} = -\mu_0 J^i \partial_\mu F^{\mu 0} = \mu_0 c \rho$$

$$\partial_\mu F^{0\mu} = -\mu_0 c \rho$$

To combine these equations, we set:

$$\boxed{J^0 \equiv c\rho} \tag{4.11}$$

We arrive at the unified equation:

$$\partial_{\mu}F^{\nu\mu} = -\mu_0 J^{\nu}$$

Choose units such that $c = \frac{h}{2\pi} = G_n = 1$, which gives us:

$$\partial_{\mu}F^{\nu\mu}=-J^{\nu}$$
 F is antisymmetric, so flipping indices $\partial_{\mu}F^{\mu\nu}=J^{\nu}$

$$\partial_{\mu}F^{\mu\nu} = J^{\nu} \tag{4.12}$$

Note that this is Ampere's law!

4.3.2 Combining (2) $\nabla \times E = -\frac{\partial B}{\partial t}$, (3) $\nabla B = 0$

$$\nabla \times E = -\frac{\partial B}{\partial t}$$

$$(\nabla \times E)^{i} = \mathcal{E}^{ijk} \partial_{j} E_{k} = -\partial_{0} B$$

$$\mathcal{E}^{ijk} \partial_{j} E_{k} = -\partial_{0} (\frac{1}{2} \mathcal{E}^{ijk} F_{jk})$$

$$\mathcal{E}^{ijk} \partial_{j} E_{k} + \partial_{0} (\frac{1}{2} \mathcal{E}^{ijk} F_{jk}) = 0$$

$$2\mathcal{E}^{ijk} \partial_{j} E_{k} + \partial_{0} (\mathcal{E}^{ijk} F_{jk}) = 0$$

Now we begin from the other direction, and start the derivation. We know that the equation we want is:

$$\overline{\mathcal{E}^{\alpha\beta\mu\nu}}\partial_{\beta}F_{\mu\nu} = 0 \tag{4.13}$$

 $\alpha = 0$ case:

First, set $\alpha = 0$. So now, the other β, μ, ν are forced to be become space components — (i, j, k). Therefore, the equation now becomes:

$$\mathcal{E}^{0ijk}\partial_i F_{ik} = 0$$

However, note that $\mathcal{E}0ijk = \mathcal{E}ijk$, because if (ijk) is an even permutation, so will (0ijk), and vice versa for odd (since 0 < i, j, k).

Using this, the equation becomes

$$\mathcal{E}^{ijk}\partial_i F_{jk} = 0$$

$$\partial_i (\mathcal{E}^{ijk} F_{jk}) = 0$$
Since $B^i = \frac{1}{2} \mathcal{E}^{ijk} F_{jk}$:
$$\partial_i \left(\frac{B^i}{2} \right) = 0$$

$$\nabla B = 0$$

Hence, the above equation does encode $\nabla B = 0$.

 $\alpha=m$ case:

Let α be a spatial dimension $m = \{1, 2, 3\}$.

$$\mathcal{E}^{\alpha\beta\mu\nu}\partial_{\beta}F_{\mu\nu} = 0$$
$$\mathcal{E}^{m\beta\mu\nu}\partial_{\beta}F_{\mu\nu} = 0$$

Once again, we get two cases, one where $\beta=0$, and one where $\beta=n$ where n is a spatial dimension. If $\beta=0$, then the other dimensions are forced to be spatial dimensions, which we shall denote as $\mu\equiv x,\ \nu\equiv y$

$$\mathcal{E}^{m\beta\mu\nu}\partial_{\beta}F_{\mu\nu} = 0$$
$$\mathcal{E}^{m0xy}\partial_{0}F_{xy} + \mathcal{E}^{mn\mu\nu}\partial_{n}F_{\mu\nu} = 0$$

Now note that $\mathcal{E}^{m0\mu\nu} = -\mathcal{E}0m\mu\nu = -\mathcal{E}m\mu\nu$. Using this, we can rewrite the above equation as:

$$\mathcal{E}^{m0xy}\partial_0 F_{xy} + \mathcal{E}^{mn\mu\nu}\partial_n F_{\mu\nu} = 0$$
$$-\mathcal{E}^{mxy}\partial_0 F_{xy} + \mathcal{E}^{mn\mu\nu}\partial_n F_{\mu\nu} = 0$$

We now consider cases for μ in the second term, where either $\mu = 0$ or $\mu = o \in \{1, 2, 3\}$

If $\mu = 0$, then the other dimension ν must be a spatial dimension p. If $\mu = q$, then the other dimension ν must be a time dimension 0 (This is because we are not allowed to have 4 spatial dimensions, since the \mathcal{E} evaluates to 0 on repeated dimensions).

$$-\mathcal{E}^{mxy}\partial_{0}F_{xy} + \mathcal{E}^{mn\mu\nu}\partial_{n}F_{\mu\nu} = 0$$

$$-\mathcal{E}^{mxy}\partial_{0}F_{xy} +$$

$$\mathcal{E}^{mn0p}\partial_{n}F_{0p} \qquad (\mu = 0, \nu = p)$$

$$\mathcal{E}^{mnq0}\partial_{n}F_{q0} \qquad (\mu = q, \nu = 0)$$

$$= 0$$

Rearranging, and using the fact that $F_{0p} = -Fp0$, $\mathcal{E}mn0p = \mathcal{E}0mnp = \mathcal{E}mnp$, $\mathcal{E}mnq0 = -\mathcal{E}0mnq = -\mathcal{E}mnq$,

$$-\mathcal{E}^{mxy}\partial_0 F_{xy} + \mathcal{E}^{mnp}(-\partial_n F_{p0}) + (-\mathcal{E}^{mnq})\partial_n F_{q0} = 0$$

Multiplying throughout by -1, and noticing that since p, q are dummy indeces, we can set p = q. This allows us to get:

$$\mathcal{E}^{mxy}\partial_0 F_{xy} + 2\mathcal{E}^{mnp}\partial_n F_{p0} = 0$$

First, remember that $E_p = F_{p0}$. So, we can replace the term F_{p0} (upto fudging of constant factors that we have always done), with E_p .

Now, compare

$$\mathcal{E}^{mxy}\partial_0 F_{xy} + 2\mathcal{E}^{mnp}\partial_n E_p = 0$$
 (Our equation)

$$2\mathcal{E}^{ijk}\partial_j E_k + \partial_0(\mathcal{E}^{ijk}F_{jk}) = 0$$
 (Previous equation)

Note that the two equations are identical upto variable naming, and are hence considered equal. So, we have encoded both of Maxwell's laws into this particular equation:

$$\mathcal{E}^{\alpha\beta\mu\nu}\partial_{\beta}F_{\mu\nu} = 0 \tag{4.14}$$

Gauge theories

We construct a 1-dimensional guage theory and study its symmetries.

5.1 Euler-Lagrange equations for a field

Consider a Lagrangian:

$$\mathcal{L}(\phi, \phi', \dot{\phi}) = \dot{\phi}^2 - \phi'^2$$

When written in terms of M^4 (minkowski space), we know that

$$\partial_{\mu} \equiv (\partial_t, -\nabla)$$

Hence, in minkowski space, the lagrangian becomes a function of only:

$$\mathcal{L}(\phi, \partial_{\mu}\phi) \equiv \dots$$

So we managed to unify the space derivative and the time derivative (yay). Now, we can consider the action of this Lagrangian:

$$S[\phi] = \int L(\phi, \partial_{\mu}\phi) d^4x$$

Minimising the functional S,

$$\begin{split} \delta S[\phi] &= 0 \\ \delta \int L(\phi, \partial_{\mu} \phi) \, \mathrm{d}^4 x &= 0 \\ \int \left[\frac{\delta L}{\delta \phi} \delta \phi + \frac{\delta L}{\delta \partial_{\mu} \phi} \, \delta(\partial_{\mu} \phi) \, \right] \mathrm{d}^4 x \end{split}$$

Using linearity of integration, and commuting of δ, ∂_{μ}

$$\int \frac{\delta L}{\delta \phi} (\delta \phi) d^4 x + \int \frac{\delta L}{\delta \partial_{\mu} \phi} (\partial_{\mu} \delta \phi) d^4 x$$
Using
$$\int U dV = UV - \int V dU, V = \delta \phi, U = \frac{\delta L}{\delta \partial_{\mu} \phi}$$

$$\int \frac{\delta L}{\delta \phi} (\delta \phi) d^4 x + \left. \frac{\delta L}{\delta \partial_{\mu} \phi} (\delta \phi) \right|_{endpoints} - \int \delta \phi \left(\partial_{\mu} \frac{\delta L}{\delta \partial_{\mu} \phi} \right) d^4 x$$

Since fields decay at endpoints, forget the integral

$$\int \frac{\delta L}{\delta \phi} (\delta \phi) \mathrm{d}^4 x - \int \delta \phi \bigg(\partial_\mu \frac{\delta L}{\delta \partial_\mu \phi} \bigg) \mathrm{d}^4 x$$

Refactoring to pull the common $\delta \phi$,

$$\int \left(\frac{\delta L}{\delta \phi} - \partial_{\mu} \frac{\delta L}{\delta \partial_{\mu} \phi}\right) (\delta \phi) d^{4} x = 0$$

Since this is true for all perturbations $\delta \phi$ implies that:

$$\frac{\delta L}{\delta \phi} - \partial_{\mu} \frac{\delta L}{\delta \partial_{\mu} \phi} = 0$$

Hence, we have the Euler-Lagrange equation for scalar fields:

$$\left[\frac{\delta L}{\delta \phi} - \partial_{\mu} \frac{\delta L}{\delta \partial_{\mu} \phi} = 0 \right] \tag{5.1}$$

- 5.2 Klein-gordon equations
- 5.3 Lagrangian for a massive scalar field
- 5.4 Symmetries of a scalar field Lagrangian
- 5.5 Derving the force of the EM-field from the Lanrangian

Recall that $B = \nabla \times A$, $E = \nabla \phi - \frac{\partial A}{\partial t}$, and the force on a particle is $\vec{\mathbf{F}} = q(\vec{\mathbf{E}} + \vec{\mathbf{v}} \times \vec{\mathbf{B}})$.

$$ma = e(\nabla \phi - \frac{\partial A}{\partial t}) + e(v \times (\nabla \times A))$$

$$ma = e(\nabla \phi - \frac{\partial A}{\partial t}) + e(\nabla \cdot (v \cdot A) - (v \cdot \nabla)A)$$

Note that $(v \cdot \nabla)A$ is:

$$v \cdot \nabla = \frac{\mathrm{d}x}{\mathrm{d}t} \frac{\partial}{\partial x} + \frac{\mathrm{d}y}{\mathrm{d}t} \frac{\partial}{\partial y} + \frac{\mathrm{d}z}{\mathrm{d}t} \frac{\partial}{\partial z}$$
$$(v \cdot \nabla)A = \frac{\mathrm{d}x}{\mathrm{d}t} \frac{\partial A}{\partial x} + \frac{\mathrm{d}y}{\mathrm{d}t} \frac{\partial A}{\partial y} + \frac{\mathrm{d}z}{\mathrm{d}t} \frac{\partial A}{\partial z}$$

However, now let us compare $\frac{\mathrm{d}A}{\mathrm{d}t}$ and $(v\cdot \nabla)A$:

$$\frac{\mathrm{d}A}{\mathrm{d}t} = \frac{\partial A}{\partial t} + \frac{\mathrm{d}x}{\mathrm{d}t} \frac{\partial A}{\partial x} + \frac{\mathrm{d}y}{\mathrm{d}t} \frac{\partial A}{\partial y} \frac{\mathrm{d}z}{\mathrm{d}t} \frac{\partial A}{\partial z}$$
$$\frac{\mathrm{d}A}{\mathrm{d}t} = \frac{\partial A}{\partial t} + (v \cdot \nabla)A$$

Now, rewriting ma,

$$ma = e(\nabla \phi - \frac{\partial A}{\partial t}) + e(\nabla \cdot (v \cdot A) - (v \cdot \nabla)A)$$
$$ma = e(\nabla \phi - \frac{\partial A}{\partial t}) + e(\nabla \cdot (v \cdot A) - (v \cdot \nabla)A)$$

5.6 Local and global symmetries

Charged particle interaction in fields, or, how maxwell's equations have U(1) symmetry

(written in red ink pen)

Consider a scalar field ϕ , and the lagrangian:

$$\mathcal{L}(\phi, \partial_{\mu}\phi) = \frac{1}{2}(\partial_{\mu}\phi)(\partial_{\mu}\phi) - \frac{1}{2}m^{2}\phi^{2}$$

Next, we want to consider charged particle interactions, which comes from $H = \frac{(p-eA)^2}{2m}$, which creates the lorentz force $e\vec{\mathbf{v}} \times \vec{\mathbf{B}} = e\vec{\mathbf{v}} \cdot \vec{\mathbf{A}}$.

We know that \mathcal{L} is invariant under global rotation $e^{i\theta}$. Now we study local gauge invariance by making θ a function of space. That is, $\theta \to \theta(x)$.

We use the complex form of the lagrangian:

$$\mathcal{L} = (\partial_{\mu}\phi)(\partial^{\mu}\phi)^* - m^2|\phi|^2$$

We now consider the transform:

$$phi \rightarrow e^{ie\theta(x)}\phi$$

This implies the transforms:

$$\partial_{\mu}\phi = \partial_{\mu}(e^{ie\theta(x)}\phi) = e^{ie\theta(x)}\partial_{\mu}\phi + iee^{ie\theta(x)}\phi\partial_{\mu}\theta = e^{ie\theta(x)}(\partial_{\mu}\phi + ie\phi\partial_{\mu}\theta)$$

Hence, for invariance, we get:

$$(\partial_{\mu}\phi)(\partial^{\mu}\phi)^{*}$$

$$= (e^{ie\theta(x)}(\partial_{\mu}\phi + ie\phi\partial_{\mu}\theta))(e^{ie\theta(x)}(\partial^{\mu}\phi + ie\phi\partial^{\mu}\theta))^{*}$$

$$= (\partial_{\mu}\phi + ie\phi\partial_{\mu}\theta)(\partial^{\mu}\phi^{*} - ie\phi^{*}\partial^{\mu}\theta)$$

We introduce:

$$D_{\mu}\phi \equiv (\partial_{\mu} - iA_{\mu})\phi(\partial^{\mu} + iA^{\mu})\phi^*$$

We shall check that this transforms in a lorentzian way. In the new coordinate system:

$$\begin{split} \bar{D}_{\mu}\bar{\phi} &\equiv ([\partial_{\mu} - i\bar{A}_{\mu})\bar{\phi}][(\partial^{\mu} + i\bar{A}^{\mu})\bar{\phi}^{*}] \\ &= [(\partial_{\mu} - i\bar{A}_{\mu})(e^{ie\theta(x)})\phi][(\partial^{\mu} + i\bar{A}^{\mu})(e^{ie\theta(x)}\phi)^{*}] \\ &= [\partial_{\mu}(e^{ie\theta(x)}\phi) - i\bar{A}_{\mu}e^{ie\theta(x)}\phi][\partial_{\mu}(e^{-ie\theta(x)}\phi^{*}) + i\bar{A}_{\mu}e^{-ie\theta(x)}\phi^{*}] \\ &= \text{evaluate } \partial_{\mu}(UV) \\ &= [e^{ie\theta(x)}(\partial_{\mu}\phi) + iee^{ie\theta(x)}(\partial_{\mu}\theta)\phi - i\bar{A}_{\mu}e^{ie\theta(x)}\phi][e^{-ie\theta(x)}(\partial_{\mu}\phi^{*}) - iee^{-ie\theta(x)}(\partial_{\mu}\theta)\phi^{*} + i\bar{A}_{\mu}e^{-ie\theta(x)}\phi^{*}] \\ &= [e^{ie\theta(x)}(\partial_{\mu}\phi + ie(\partial_{\mu}\theta)\phi - i\bar{A}_{\mu}\phi)][e^{-ie\theta(x)}(\partial_{\mu}\phi^{*} - ie(\partial_{\mu}\theta)\phi^{*} + i\bar{A}_{\mu}\phi^{*})] \\ &= [\partial_{\mu}\phi + ie(\partial_{\mu}\theta)\phi - i\bar{A}_{\mu}\phi][\partial_{\mu}\phi^{*} - ie(\partial_{\mu}\theta)\phi^{*} + i\bar{A}_{\mu}\phi^{*}] \\ &= [\partial_{\mu} + ie(\partial_{\mu}\theta) - i\bar{A}_{\mu}]\phi[\partial_{\mu} - ie(\partial_{\mu}\theta) + i\bar{A}_{\mu}]\phi^{*} \end{split}$$

Comparing:

$$D_{\mu}\phi \equiv (\partial_{\mu} - iA_{\mu})\phi(\partial^{\mu} + iA^{\mu})\phi^{*}$$

$$\bar{D}_{\mu}\bar{\phi} \equiv [\partial_{\mu} + ie(\partial_{\mu}\theta) - i\bar{A}_{\mu}]\phi[\partial_{\mu} - ie(\partial_{\mu}\theta) + i\bar{A}_{\mu}]\phi^{*}$$

$$-iA_{\mu} = +ie(\partial_{\mu}\theta) - i\bar{A}_{\mu}$$

$$-A_{\mu} = e(\partial_{\mu}\theta) - \bar{A}_{\mu}$$

$$\bar{A}_{\mu} = e(\partial_{\mu}\theta) + A_{\mu}$$

TODO: This is not what mukku got! mukku got $\bar{A}_{\mu} = A_{\mu} - e(\partial_{\mu}\theta)$. HOW?

So now, we know how A_{μ} transforms:

$$\bar{A}_{\mu} = A_{\mu} - e(\partial_{\mu}\theta) \tag{6.1}$$

So, now, our modified lagrangian is:

$$\mathcal{L}(\phi, \phi^*, \partial_{\mu}\phi, \partial_{\mu}\phi^*, A_{\mu}) = [(\partial_{\mu} - iA_{\mu})\phi][(\partial^{\mu} - iA^{\mu})\phi]^* - \frac{1}{2}m|\phi|^2$$

We want to understand if we can add interaction terms for A_{μ} . If not, what the obstacles are. We would like the interaction terms to be a Lorentz tensor, and we would like it to respect local symmetrics.

$$\mu^2 A_{\mu} A^{\mu} \to \mu^2 \bar{A}_{\mu} \bar{A}^{\mu} = \mu^2 (A_{\mu} + e \partial_{\mu} \theta) (A^{\mu} + e \partial^{\mu} \theta)$$

So clearly, we cannot have mass terms of the form $\mu^2 A_\mu A^\mu$. We must try other things and check if they are interesting.

We now try to inspect some invariants of A_{μ} . For example, we can construct:

$$F_{\mu\nu} = \partial_{\mu}A_{\nu} - \partial_{\nu}A_{\mu}$$

We already know that F is a Lorentz tensor. Let's check if it's gauge invariant.

$$\begin{split} \bar{F}_{\mu\nu} &= \ \partial_{\nu} \bar{A}_{\mu} - \partial_{\mu} A_{\nu} \\ &= \ \partial_{\nu} (A_{\mu} - e(\partial_{\mu}\theta)) - \partial_{\mu} (A_{\nu} - e\partial_{\nu}\theta)) \\ &\text{Since partial derivatives commute:} \\ &= \ \partial_{\nu} A_{\mu} - \underline{e} \partial_{\nu} \partial_{\mu} \theta - \partial_{\mu} A_{\nu} - \underline{e} \partial_{\mu} \partial_{\nu} \theta)) \\ &= \ \partial_{\nu} A_{\mu} - \partial_{\mu} A_{\nu} = F_{\mu\nu} \end{split}$$

Hence, $F_{\mu\nu}$ is also gauge invariant.

Here, there is some sentence of how "there are only two invariants possible for $F_{\mu\nu}$:

- $F^{\mu\nu}F_{\mu\nu}$
- $e^{\mu\nu\alpha\beta}F_{\mu\nu}F_{\alpha\beta}$ (what is e in this context?) Supposedly, we can ignore this since it relates to divergence (??) **TODO:** figure this out

So, extending the lagrangian with the $F_{\mu\nu}$ term gives us:

$$\mathcal{L}(\phi, \phi^*, \partial_{\mu}\phi, \partial_{\mu}\phi^*, A_{\mu}) = \frac{1}{4}F^{\mu\nu}F_{\mu\nu} + [D_{\mu}\phi][D^{\mu}\phi]^* - \frac{1}{2}m|\phi|^2$$
 where:

$$D_{\mu} \equiv (\partial^{\mu} - iA^{\mu})$$

$$F_{\mu\nu} \equiv \partial_{\mu}A_{\nu} - partial_{\nu}A_{\mu}$$

Now, performing variational calculus on this lagrangian, we should theoretically regain maxwell's equations:

TODO: follow the last part of the stuff written in red ink pen to understand what in the actual fuck happened

28CHAPTER 6. CHARGED PARTICLE INTERACTION IN FIELDS, OR, HOW MAXWELL'S EQUATION.

Non abelian gauge theories

Let $\phi_i = (\phi_1, \phi_2, \phi_3)$ be a vector of scalar fields.

Consider the "usual" lagrangian:

$$\mathcal{L} = (\partial_{\mu}\phi)^{\dagger}(\partial^{\mu}\phi) - \frac{1}{2}m\phi^{\dagger}\phi$$

This clearly has a global symmetry $\phi \to U(\theta)\phi$ where $U \in SU(n)$

We enlarge the global symmetry to a local symmetry $\phi \to U(\theta(x))\phi$. Note that $\phi^{\dagger}\phi$ is still invariant, but we need to check the first term of the Lagrangian.

Working out the changes:

$$\begin{split} \partial_{\mu}\bar{\phi} &= \partial_{\mu}(U\phi) = (\partial_{\mu}U)\phi + (U\partial_{\mu}\phi) \\ \partial_{\mu}\bar{\phi}^{\dagger} &= \partial_{\mu}(U\phi)^{\dagger} = \partial_{\mu}(\phi^{\dagger}U^{\dagger}) = (\partial_{\mu}\phi^{\dagger})U^{\dagger} + \phi^{\dagger}(\partial_{\mu}U^{\dagger}) \\ \text{So, the term to be invariant is:} \\ (\partial_{\mu}\bar{\phi})^{\dagger}(\partial^{\mu}\bar{\phi}) &= \\ [(\partial_{\mu}\phi^{\dagger})U^{\dagger} + \phi^{\dagger}(\partial_{\mu}U^{\dagger})][(\partial^{\mu}U)\phi + (U\partial^{\mu}\phi)] &= \\ (\partial_{\mu}\phi^{\dagger})U^{\dagger}(\partial^{\mu}U)\phi + (\partial_{\mu}\phi^{\dagger})U^{\dagger}(U\partial^{\mu}\phi) + \\ \phi^{\dagger}(\partial_{\mu}U^{\dagger})(\partial^{\mu}U)\phi + \phi^{\dagger}(\partial_{\mu}U^{\dagger})(U\partial^{\mu}\phi) \end{split}$$

This mess of equations clearly does not look like $(\partial_{\mu}\phi)(\partial^{\mu}\phi)$, even after using the simplification $UU^{\dagger} = U^{\dagger}U = I$, so this is not invariant.

So let's define a new covariant derivative (I wish I knew what those words mean):

$$(D_{\mu})_{\alpha,\beta} = \partial_{\mu}\delta_{\alpha\beta} - ig(A_{\mu})_{\alpha,\beta}$$

Where g is some kind of coupling coefficient (more on this later), and A_{μ} is some arbitrary quantity on which we will use the symmetries we expect to give some structure.

We need $D_{\mu}\phi$ to transform reasonably, hence, we stipulate that:

$$(D_{\mu}\bar{\phi}) \to UD_{\mu}\phi$$

Assuming that transformation law holds, we show that $D_{\mu}\phi$ is invariant:

$$(D_{\mu}\bar{\phi})^{\dagger}(D^{\mu}\bar{\phi}) = (U(D_{\mu}\phi))^{\dagger}(U(D_{\mu}\phi)) = ((D_{\mu}\phi^{\dagger})U^{\dagger})(U(D_{\mu}\phi)) =$$

$$(D_{\mu}\phi)^{\dagger}(D^{\mu}\phi) \text{ since } UU^{\dagger} = I$$
Hence, we showed that:
$$(D_{\mu}\bar{\phi})^{\dagger}(D^{\mu}\bar{\phi}) \to (D_{\mu}\phi)^{\dagger}(D^{\mu}\phi)$$

Now, we need to ensure that the law we took actually works. For this law to hold, we will derive conditions that govern A:

$$\begin{split} &(D_{\mu}\bar{\phi}) = UD_{\mu}\phi \\ &\partial_{\mu}\bar{\phi} - ig\bar{A}_{\mu}\bar{\phi} = U(\partial_{\mu}\phi - igA_{\mu}\phi) \\ &\partial_{\mu}(U\phi) - ig\bar{A}_{\mu}\bar{\phi} = U(\partial_{\mu}\phi - igA_{\mu}\phi) \\ &(\partial_{\mu}U)\phi + \underline{U}(\partial_{\mu}\phi) - ig\bar{A}_{\mu}\bar{\phi} = \underline{U}\partial_{\mu}\phi - igUA_{\mu}\phi \\ &(\partial_{\mu}U)\phi - ig\bar{A}_{\mu}\bar{\phi} = -igUA_{\mu}\phi \\ &- ig\bar{A}_{\mu}(U\phi) = -igUA_{\mu}\phi - (\partial_{\mu}U)\phi \\ &(ig\bar{A}_{\mu}U)\phi = (igUA_{\mu} + (\partial_{\mu}U))\phi \\ &ig\bar{A}_{\mu}U = igUA_{\mu} + (\partial_{\mu}U) \\ &A_{\mu} = UA_{\mu}U^{-1} + \frac{(\partial_{\mu}U)U^{-1}}{ig} \end{split}$$

So, we now know what the correction term is for the D_{μ} for the non-abelian gauge theory. Notice that $(\partial_{\mu}U)U^{-1}$ is a function of θ , the parameter.

$$A_{\mu} = UA_{\mu}U^{-1} + \frac{(\partial_{\mu}U)U^{-1}}{ig}$$
 (7.1)

Supposedly, A_{μ} is a connection, and the field strength tensor F is the curvature of the connection:

$$\begin{split} [D_{\mu},D_{\nu}] &= [\partial_{\mu}-ieA_{\mu},\partial_{\nu}-ieA_{\nu}] \\ &= (\partial_{\mu}-ieA_{\mu})(\partial_{\nu}-ieA_{\nu}) - (\partial_{\nu}-ieA_{\nu})(\partial_{\mu}-ieA_{\mu}) \\ &= (\partial_{\mu}\partial_{\nu}-\partial_{\mu}(ieA_{\nu}) + (-ieA_{\mu})(\partial_{\nu}) + i^{2}e^{2}A_{\mu}A_{\nu}) - \\ &\quad (\partial_{\nu}\partial_{\mu}-\partial_{\nu}(ieA_{\mu}) + (-ieA_{\nu})(\partial_{\mu}) + i^{2}e^{2}A_{\mu}A_{\nu}) \\ &= (\partial_{\mu}\partial_{\nu}-\partial_{\mu}(ieA_{\nu}) + (-ieA_{\mu})(\partial_{\nu}) + i^{2}e^{2}A_{\mu}A_{\nu}) - \\ &\quad (\partial_{\nu}\partial_{\mu}-\partial_{\nu}(ieA_{\mu}) + (-ieA_{\nu})(\partial_{\mu}) + i^{2}e^{2}A_{\mu}A_{\nu}) \\ &\quad \textbf{TODO: understand how } (-ieA_{\mu})(\partial_{\nu}) \text{ terms get cancelled} \\ &= -ie(\partial_{\mu}A_{\nu}-\partial_{\nu}A_{\mu}) \end{split}$$

which is indeed F.

The group that governs the symmetries of ϕ is SU(2), since SU(2) has a dimension (as a manifold) of 3 (SU(n) has n^2-1 degrees of freedom).