

### 3.5, Q1:

Monotonicity of Sample Complexity: Let  $\mathcal{H}$  be a hypothesis class for a binary classification task. Suppose that  $\mathcal{H}$  is PAC learnable and its sample complexity is given by  $m_{\mathcal{H}}(\cdot, \cdot)$ . Show that  $m_{\mathcal{H}}$  is monotonically increasing in both parameters. That is, show that:

1. for  $\delta \in (0, 1)$  for  $0 \leq \epsilon_1 \leq \epsilon_2 \leq 1$ , show that  $m_{\mathcal{H}}(\epsilon_1, \delta) \geq m_{\mathcal{H}}(\epsilon_2, \delta)$ .
2. for  $\epsilon \in (0, 1)$  for  $0 \leq \delta_1 \leq \delta_2 \leq 1$ , show that  $m_{\mathcal{H}}(\epsilon, \delta_1) \geq m_{\mathcal{H}}(\epsilon, \delta_2)$ .

#### Solution, fixed $\delta$

First recall what it means to be PAC-learnable:

For every  $\epsilon, \delta \in (0, 1)$ , for every distribution  $\mathcal{D}$  over  $\mathcal{X}$ , for every labelling function  $f : \mathcal{X} \rightarrow \{0, 1\}$ , if the realisability assumption holds with respect to  $(\mathcal{H}, \mathcal{D}, f)$ , then for all constants  $m \geq m_{\mathcal{H}}(\epsilon, \delta)$ , on running the learning algorithm on a random i.i.d sample  $S \in X^m \sim \mathcal{D}^m$ , the algorithm produces a hypothesis  $h_S$ , such that with probability  $(1 - \delta)$ , the learning error  $L_{(\mathcal{D}, f)}(h) \leq \epsilon$ .

$\epsilon_1$  and  $\epsilon_2$  are the error rates that we wish to achieve. Intuitively, the smaller the error we want, the more samples we need. Hence  $\epsilon_1 \leq \epsilon_2 \implies m_{\mathcal{H}}(\epsilon_1, \delta) \geq m_{\mathcal{H}}(\epsilon_2, \delta)$ .

Formally, we shall provide a **proof by contradiction**. Let us assume that:

$$\epsilon_1 \leq \epsilon_2 \implies m_{\mathcal{H}}(\epsilon_1, \delta) \leq m_{\mathcal{H}}(\epsilon_2, \delta) \quad (\text{assumption for contradiction})$$

Unwrapping the definition, this means that:

- 1 Giving the learning algorithm  $m_1 = m_{\mathcal{H}}(\epsilon_1, \delta)$  samples, the best error rate we are able to achieve is  $\epsilon_1$ ,  $(1 - \delta)$  of the time.
- 2 Similarly, on giving the learning algorithm learning algorithm  $m_2 = m_{\mathcal{H}}(\epsilon_2, \delta)$  samples, the best error rate we are able to achieve is  $\epsilon_2$ ,  $(1 - \delta)$  of the time.

Since the fraction  $(1 - \delta)$  is the same in both cases, we can focus purely on the error rate.

Recall that  $\epsilon_1 < \epsilon_2$  and  $(m_2 > m_1)$  from our assumption of contradiction.

Hence, in the  $m_2$  case, we can simply **discard samples** and provide the learning algorithm with  $m_1$  samples, thereby reducing our error rate to  $\epsilon_1$ . However, we had assumed that for  $m_2$ ,  $\epsilon_2$  was **the best error rate we could have achieved**.

this contradiction arose from our contradictory assumption. Hence, it must be the case that as  $\epsilon$  decreases, the quantity  $m_{\mathcal{H}}(\epsilon, \cdot)$  increases.  $\square$ .

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#### Solution, fixed $\epsilon$

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### 3.5, Q2:

Let  $\mathcal{X}$  be a discrete domain, and let  $\mathcal{H}_{\text{singleton}} \equiv \{[z] : z \in \mathcal{X}\} \cup \{h\}$ , where

$$[z] : \mathcal{X} \rightarrow \{0, 1\}; \quad [z](x) \equiv \begin{cases} 1 & x = z \\ 0 & \text{otherwise} \end{cases}$$
$$h : \mathcal{X} \rightarrow \{0, 1\}; \quad h^-(x) \equiv 0$$

The realizability assumption here implies that the true hypothesis  $f$  labels negatively all examples in the domain, perhaps except one.

1. Describe an algorithm that implements the ERM rule for learning  $\mathcal{H}_{\text{singleton}}$  in the realizable setup.
2. Show that  $\mathcal{H}_{\text{singleton}}$  is PAC learnable. Prove an upper bound on the sample complexity.

#### Solution, part (a)

Let  $\mathcal{X}$  be the domain, let  $f : \mathcal{X} \rightarrow \{0, 1\}$  be the underlying target function  $f$  that we are trying to approximate using  $\mathcal{H}$ .

We define the sample loss  $L_S(h)$  as the number of elements in  $S$  that are mis-classified by  $h$ . More formally,  $L_S(h) \equiv |\{(x, y) \in S : h(x) \neq y\}|$ .

The ERM algorithm must, given a particular sample set  $S \in \mathcal{X}^n \sim \mathcal{D}^n$ , provides a function  $h_0 \in \mathcal{H} = \text{ERM}(S)$  which has minimum sample loss  $L_S(h_0)$  across all functions in  $\mathcal{H}$ .

We can check over the classification of all the samples  $s \in S$ .

- If all samples  $s \in S$  are classified as 0: we return  $h^-$  — this will always return 0.
- If some sample  $s_1 \in S$  is classified as 1: notice that our hypothesis space  $\mathcal{H}$  can only allow us to set *at most one sample to 1*. So, we can pick *any* sample  $s_1$  to create our hypothesis function  $h = [s_1]$ , since that is the best we can do.

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def hminus(_): return 0 # h-: sends all samples to 0
def indicator(z): return lambda x: 1 if x == z else 0 #indicator of z
def erm_sample(S):
    # all samples which have label 1
    one_samples = [y for (x, y) in S if y == 1]
    if len(one_samples) == 0: return hminus # send all samples to 0!
    else: # we will have at least one element in one_samples
        return indicator(one_samples[0])
```

#### Solution, part (b)

The definition of a hypothesis class  $\mathcal{H}$  to be PAC-learnable is that there exists a function  $m_{\mathcal{H}} : (0, 1)^2 \rightarrow \mathbb{N}$  and a learning algorithm such that:

For every  $\epsilon, \delta \in (0, 1)$ , for every distribution  $\mathcal{D}$  over  $\mathcal{X}$ , for every labelling function  $f : \mathcal{X} \rightarrow \{0, 1\}$ , if the realisability assumption holds with respect to  $(\mathcal{H}, \mathcal{D}, f)$ , then for all constants  $m \geq m_{\mathcal{H}}(\epsilon, \delta)$ , on running the learning algorithm on a random i.i.d sample  $S \in X^m \sim \mathcal{D}^m$ , the algorithm produces a hypothesis  $h_S$ , such that with probability  $(1 - \delta)$ , the learning error  $L_{(\mathcal{D}, f)}(h) \leq \epsilon$ .

**TODO**

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#### 4.5, Q1:

Prove that the following two statements are equivalent for any learning algorithm  $A$ , any probability distribution  $\mathcal{D}$ , and any loss function whose loss is in the range  $[0, 1]$ :

$$\begin{aligned} \forall \epsilon, \delta > 0, \exists M \equiv m(\epsilon, \delta), \forall m \geq M : \mathbb{P}_{S \sim \mathcal{D}^m} [L_{\mathcal{D}}(A(S)) > \epsilon] < \delta. \\ \Updownarrow \\ \lim_{m \rightarrow \infty} \mathbb{E}_{S \sim \mathcal{D}^m} [L_{\mathcal{D}}(A(S)) > \epsilon] = 0. \end{aligned}$$

**Solution**

**TODO**

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#### 6.8, Q1:

For two hypothesis classes  $\mathcal{H}, \mathcal{H}'$ , if  $\mathcal{H}' \subseteq \mathcal{H}$  then  $\text{VCdim}(\mathcal{H}') \leq \text{VCdim}(\mathcal{H})$ .

**Solution**

Recall that the VC dimension of a given set family  $\mathcal{H}$  is the size of the largest set  $C$  such that  $\mathcal{H}$  shatters  $C$ . That is, the intersection of  $C$  with every element in  $\mathcal{H}$  is equal to the powerset of  $C$ :

$$\text{VCdim}(\mathcal{H}) \equiv \max_C \{h \cap C : h \in \mathcal{H}\} = 2^C \quad \text{We denote powerset of } C \text{ by } 2^C$$

Now, if a set family  $\mathcal{H}'$  is a subset of another set family  $\mathcal{H}$ , and if  $\mathcal{H}'$  shatters  $C$ , then:

$$\begin{aligned} \mathcal{H}' \text{ shatters } C &\equiv \{h \cap C : h \in \mathcal{H}'\} = 2^C && \text{Given, (1)} \\ \{h \cap C : h \in \mathcal{H}'\} &\subseteq \{h \cap C : h \in \mathcal{H}\} && \text{Since } \mathcal{H}' \subseteq \mathcal{H} \\ 2^C &\subseteq \{h \cap C : h \in \mathcal{H}\} && \text{From (1)} \end{aligned}$$

Hence, any set that can be shattered by  $H'$  can be shattered by  $H$  if  $H' \subseteq H \implies \text{VCdim}(H') \leq \text{VCdim}(H)$ .

On the other hand, clearly if  $H$  is larger than  $H'$ , then  $H$  can shatter more. For example, let  $H' = \phi \subsetneq H$ . Then  $H'$  can only shatter the empty set, while  $H$  can in general shatter sets larger than the empty set. Hence, we have strict inequality:  $\text{VCdim}(\emptyset) < \text{VCdim}(H)$  for example.