Managing Memory

6.037 - Structure and Interpretation of Computer Programs

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Massachusetts Institute of Technology

Lecture 8B

So far, we've examined just a bit of the overall Scheme story.

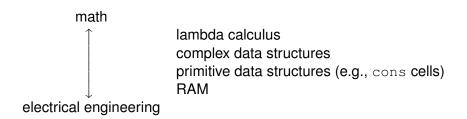
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complex data structures primitive data structures (e.g., cons cells)

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Implementing cons-cell memory

• We've been using the cons-cell abstraction this whole class.



• Computer memory doesn't really work like that.

Computer Memory

 Conventional memory is an array of locations, each of which has an integer address, and stores a single value.



 Addresses are sequential, so we often move around memory by adding and subtracting values from addresses.

Vectors

- We will model memory using vectors.
- Also a generally-useful data structure (similar to arrays in other languages).
- Vectors support constant-time access of an arbitrary element.

- (make-vector $\langle size \rangle$) $\rightarrow \langle v \rangle$
 - Returns a vector of the given size.

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 - Sets the element at index n of v.

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- (vector-set! $\langle v \rangle \langle n \rangle \langle val \rangle$) \rightarrow undefined
 - Sets the element at index n of v.
- (vector-length $\langle v \rangle$) $\rightarrow \langle size \rangle$

Vectors and Lists

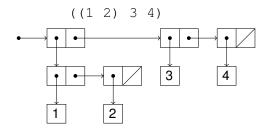
| Lists | Vectors |
|---------------------------------------|-------------------------------|
| Constant-time append at the | No append at all |
| beginning | |
| Constant-time insert at any | No insert at all |
| point (with mutation) | |
| Accessing the n th element | Accessing the nth element |
| takes $O(n)$ | takes constant time |
| Structure can be shared be- | Every vector is entirely dis- |
| tween different lists | joint |
| Rich set of built-in proce- | Few built-ins (but you can |
| dures (map, etc.) | build more) |

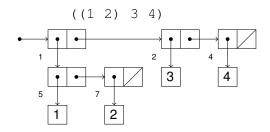
 We will represent cons cells using two vectors, the-cars and the-cdrs.

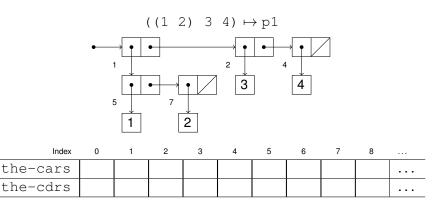
- We will represent cons cells using two vectors, the-cars and the-cdrs.
- A cons cell is an index i into the arrays
 - Its car is (vector-ref the-cars i)
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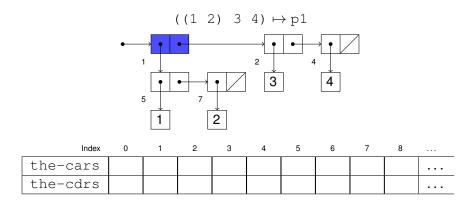
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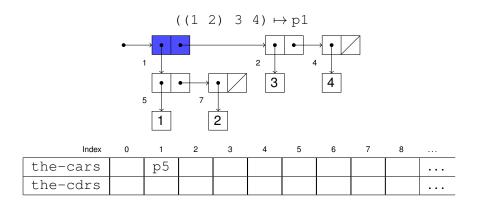
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- A cons cell is an index i into the arrays
 - Its car is (vector-ref the-cars i)
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- To represent other data, we'll use tagging.
 - ni is a number with value i
 - pi is a pointer to a pair at index i
 - e0 is the special empty list

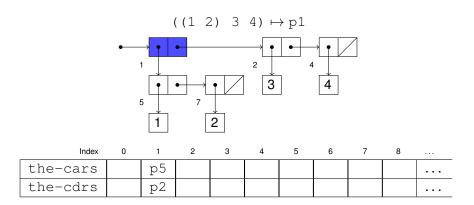


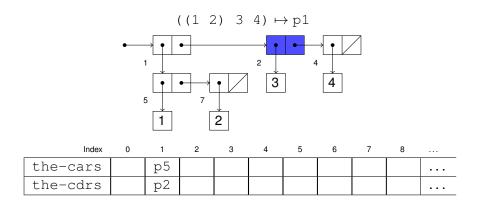


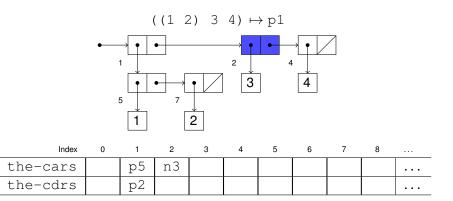


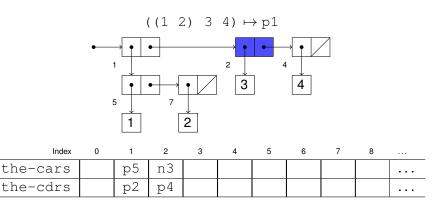


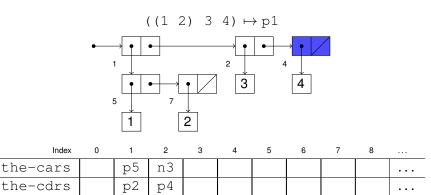


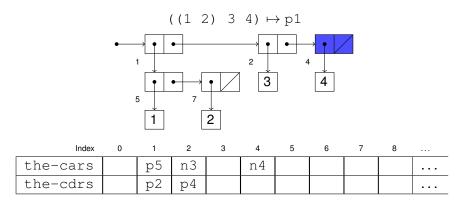


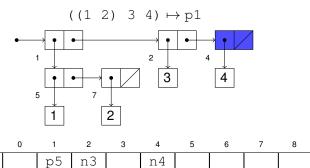






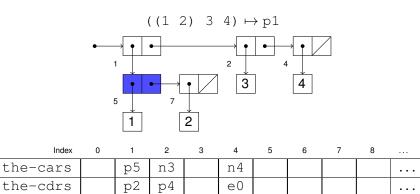


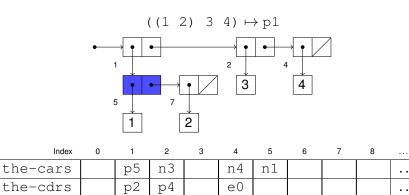




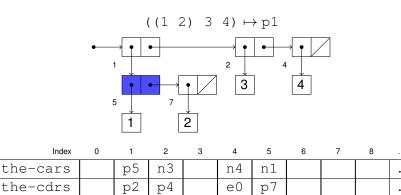
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| the-cars | | р5 | n3 | | n4 | | | | | |
| the-cdrs | | p2 | р4 | | e0 | | | | | |

Index

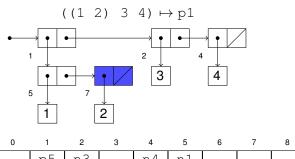




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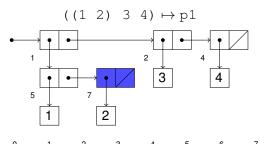


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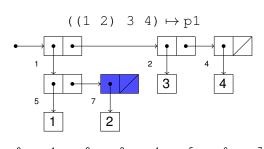


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|----------|---|----|----|---|----|----|---|---|---|--|
| the-cars | | р5 | n3 | | n4 | n1 | | | | |
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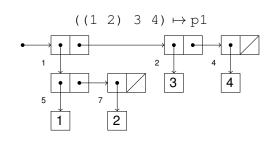
Indev



| Index | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | |
|----------|---|----|----|---|----|----|---|----|---|--|
| the-cars | | р5 | n3 | | n4 | n1 | | n2 | | |
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car and cdr

```
(define (gc-car pair)
  (vector-ref the-cars (pointer-value pair)))
(define (gc-cdr pair)
  (vector-ref the-cdrs (pointer-value pair)))
(define (qc-set-car! pair new-car)
  (vector-set! the-cars
               (pointer-value pair) new-car))
(define (qc-set-cdr! pair new-cdr)
  (vector-set! the-cdrs
               (pointer-value pair) new-cdr))
```

```
(define (gc-cons car cdr)
  (let ((pair (gc-new-pair)))
      (gc-set-car! pair car)
      (gc-set-cdr! pair car)
    pair))
```

gc-new-pair

```
(define *free* 0)
(define (gc-new-pair)
  (let ((new-pair *free*))
        (set! *free* (+ *free* 1))
        (tag-pointer 'pair new-pair)))
```

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```

What's wrong?

Too many cons cells!

```
(define (find-primes n)
  (define (helper ns)
   (cons (car ns) (find-primes
        (filter (lambda (i) (not (divides? i n))) (cdr ns))
  (helper (cdr (integers-less-than n))))
```

- (2 3 4 5 6 7 8 9 10 11 12 ...)
- (3 5 7 9 11 13 15 17 19 21 ...)
- (5 7 11 13 17 19 23 25 27 ...)

Goal: Re-use storage

- Every filter step generates intermediate lists
- But those lists can never be accessed again!
- We can re-use that storage space

The Big Idea

- We can simulate a machine with infinite memory by detecting and re-using memory that can never be used again.
- How do we do that?

Reachability

- There is a set of objects (the "root set") the program can directly access (e.g. the global environment)
- Objects can point to other objects (e.g. cons cells, the environment pointer of a lambda)
- Any object that is transitively reachable by following pointers from the root set is live and must be preserved.
- Anything else is garbage and can be reused.

First try: Reference Counting

- We could keep track of how many pointers there are to each object.
- Every time we generate a new reference to an object, we increase the reference count.
 - define
 - set!
 - apply a compound procedure
 - ...
- Whenever we remove a reference to an object, decrease the count.
 - set! (The old value)
 - After applying a compound procedure.
 - ...

Reference Counting: Problems

Naïve refcounting leaks circular objects!

```
(define x (list 'a))
(set-cdr! x x)
(set! x 0)
```

- Performance impact in many cases.
 - Every time you leave a frame, you need to walk its variables

Garbage Collection

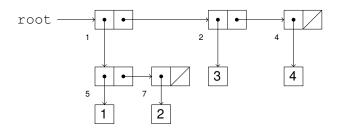
- Describe the "root set" explicitly.
 - On real hardware, this is the "registers"
 - In m-eval this is (roughly) the global environment plus the current environment.
- Only objects reachable from this set by some sequence of car and cdr can ever matter.
- Any memory that is not accessible in this way is garbage, and can be reused.

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 - sweep all of memory, collecting every unmarked object into the free list.

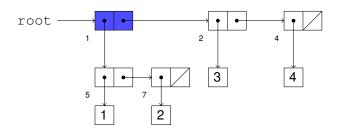
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 - Starting from the root set, recursively <u>mark</u> every reachable object.
 - sweep all of memory, collecting every unmarked object into the free list.
- Allocation then takes place by removing new pairs from the free list.



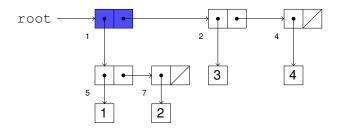
Index the-cars the-cdrs the-marks

| X | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | |
|---|---|----|----|---|----|----|---|----|---|--|
| S | | р5 | n3 | | n4 | n1 | | n2 | | |
| S | | p2 | р4 | | e0 | р7 | | e0 | | |

 \uparrow



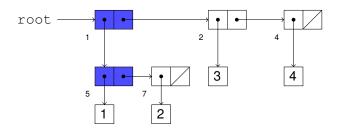
3 6 Index 0 2 4 5 8 p5 the-cars n3 n4 n1 n2 . . . p7 the-cdrs $p\overline{2}$ $p\bar{4}$ e0 e0 . . . the-marks #t



Index the-cars the-cdrs the-marks

| X | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | |
|---|---|----|----|---|----|----|---|----|---|--|
| 3 | | р5 | n3 | | n4 | n1 | | n2 | | |
| 3 | | p2 | р4 | | e0 | р7 | | e0 | | |
| 3 | | #t | | | | | | | | |

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3 Index 0 2 4 5 p5 the-cars n3 n4 n1 p7 the-cdrs $p\overline{2}$ $p\overline{4}$ e0 the-marks #t #t

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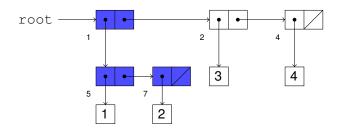
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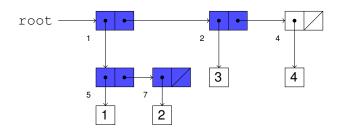
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n2

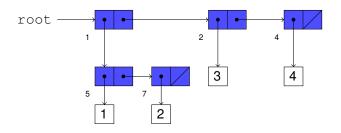
e0



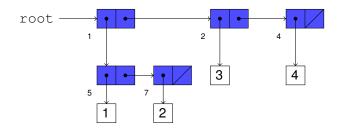
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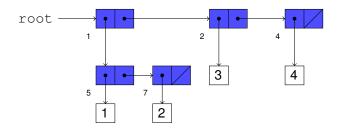


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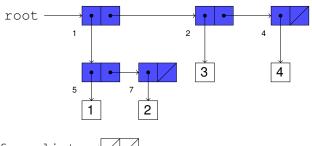
free-list →

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| the-cars | | р5 | n3 | | n4 | n1 | | n2 | | |
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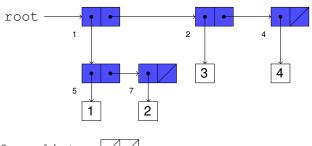


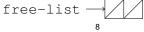
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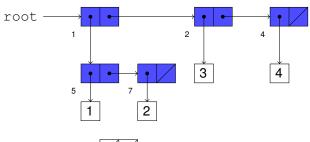


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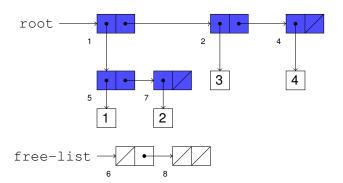




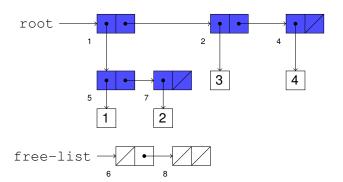
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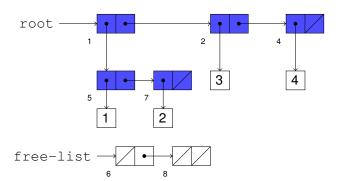
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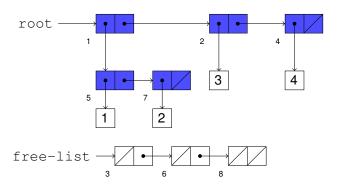
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| the-cars | | p5 | n3 | | n4 | n1 | e0 | n2 | e0 | |
| the-cdrs | | p2 | р4 | | e0 | р7 | р8 | e0 | e0 | |
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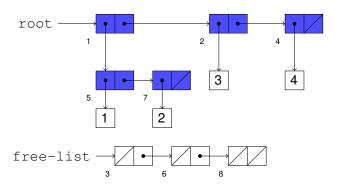
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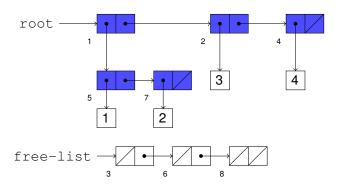
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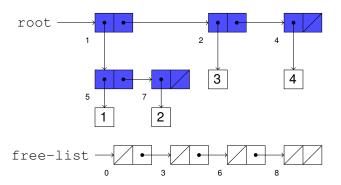
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| the-cdrs | | p2 | р4 | р6 | e0 | р7 | р8 | e0 | e0 | |
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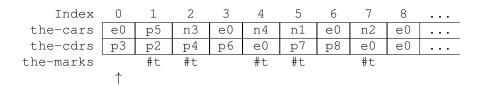


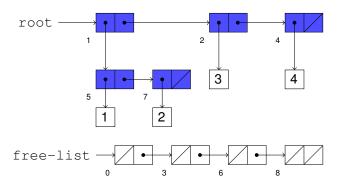
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| the-marks | | #t | #t | | #t | #t | | #t | | |
| | | \uparrow | | | | | | | | |







Index 2 4 5 6 8 . . . p5 the-cars e0 n3 e0n4 n1 e0 n2 e0. . . the-cdrs p3 рŹ p4 e0p7 p8 e0 e0р6 . . . #t #t the-marks #t #t #t

```
(define (mark p)
  (if (and (qc-pair? p)
           (not (vector-ref
                 the-marks
                  (pointer-value p))))
      (begin
        (vector-set! the-marks
                      (pointer-value p)
                      #t)
        (mark (qc-car p))
        (mark (gc-cdr p)))))
```

mark-and-sweep

```
(define (mark-and-sweep root)
  (clear-all-marks)
  (mark root)
  (set! *free-list* *gc-nil*)
  (sweep (- *memory-size* 1)))
```

gc-new-pair with a free list

mark-and-sweep: problems

• How do we keep track of state during mark?

mark-and-sweep: problems

- How do we keep track of state during mark?
- sweep needs to examine all of memory.

mark-and-sweep: problems

- How do we keep track of state during mark?
- sweep needs to examine all of memory.
- Heap fragmentation becomes a big problem.

An alternate plan: Stop-and-copy

 To solve these problems, many real systems use some form of a copying garbage collector.

An alternate plan: Stop-and-copy

- To solve these problems, many real systems use some form of a copying garbage collector.
- Our <u>stop-and-copy</u> collector maintains two regions of memory, the working memory and the free memory.

An alternate plan: Stop-and-copy

- To solve these problems, many real systems use some form of a copying garbage collector.
- Our <u>stop-and-copy</u> collector maintains two regions of memory, the working memory and the <u>free</u> memory.
- When we run out of memory, we <u>copy</u> live objects into the free memory, and switch the roles of the halves.

Stop-and-Copy

• We allocate pairs as we did initially with a *free* pointer.

Stop-and-Copy

- We allocate pairs as we did initially with a *free* pointer.
- When we run out of memory, we switch the free and working memories, and we relocate root into the new working memory.

Stop-and-Copy

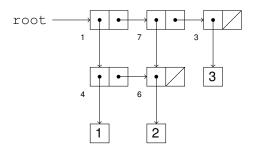
- We allocate pairs as we did initially with a *free* pointer.
- When we run out of memory, we switch the free and working memories, and we relocate root into the new working memory.
- We use a new pointer, scan, initially pointing at the start of the new working memory.
- As long as scan < *free*, we relocate the car and cdr of scan, and increment scan.

Relocation

- To relocate a pointer:
 - If the value it points to has already been copied, update it to point at the new location.
 - Otherwise, allocate a new pair, copy the pair it points to there, and update it.

Relocation

- To relocate a pointer:
 - If the value it points to has already been copied, update it to point at the new location.
 - Otherwise, allocate a new pair, copy the pair it points to there, and update it.
 - Replace the car of the old pair with a tag known as a broken heart()
 - Replace the cdr of the old pair with the pair's new address.



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| the-cdrs | | р7 | | e0 | р6 | | e0 | рЗ | | |

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root: р0

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root: р0

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5 3 4 6 Index 2 7 p3 $p\overline{1}$ n1 n2 n3 new-cars р3 new-cdrs p2 p4 e0e0

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stop-and-copy

```
(define (stop-and-copy)
  (define (loop scan)
    (if (< scan *free*)
        (begin
          (vector-set! new-cars scan
                        (relocate
                         (vector-ref new-cars scan)))
          (vector-set! new-cdrs scan
                        (relocate
                         (vector-ref new-cdrs scan)))
          (loop (+ scan 1)))))
  (set! *free* 0)
  (set! *root* (relocate *root*))
  (loop 0)
  (swap-spaces))
```

relocate

```
(define (relocate ptr)
  (if (qc-pair? ptr)
      (if (broken-heart? (gc-car pair))
          (qc-cdr pair)
          (let ((new-pair *free*))
            (set! *free* (+ 1 *free*))
            (vector-set! new-cars new-pair
                          (qc-car ptr))
            (vector-set! new-cdrs new-pair
                          (qc-cdr ptr))
            (qc-set-car! ptr *broken-heart*)
            (qc-set-cdr! ptr
                          (tag-pointer 'pair new-pair))
            (tag-pointer 'pair new-pair)))
     ptr))
```

Properties of stop-and-copy

- Since it moves things around, the garbage collector must know about every pointer into the heap.
- Compacts used memory into a single chunk
 - This means allocation is extremely efficient.
- You only get to use half of your memory.
 - But with mark-and-sweep you potentially needed that for the stack.
- Most modern GCs use something that looks more like stop-and-copy than mark-and-sweep.

Generational GC

- Think about the kinds of garbage a program creates.
- find-primes generated a lot of garbage, but it was very short-lived.
- In the adventure game, players, brains and items are created and destroyed, but tend to last a while first.
- This turns out to be true in general: A large amount of garbage is destroyed very quickly, whereas garbage that sticks around for a while is likely to stick around more.

Generational GC

- Big Idea: Have two (or more!) memory pools.
- Allocate everything into a small one, and scan it every time you do a GC.
- If an object survives a few garbage collections, move it into a larger pool, which is only fully scanned rarely.
- Nearly every real modern GC works roughly this way.