



pumas^{Al}

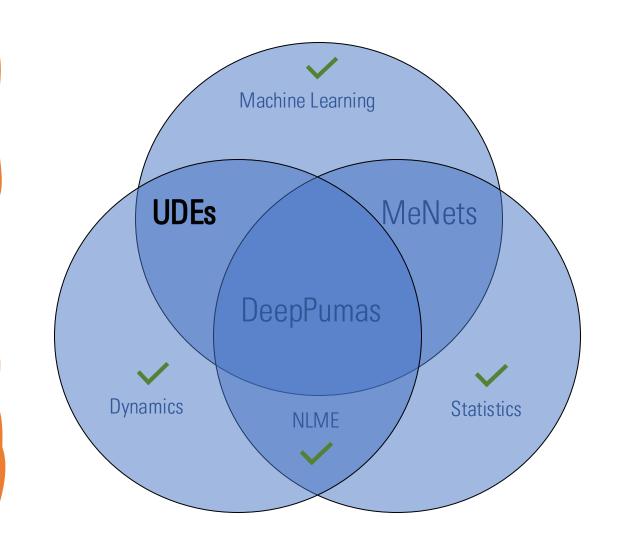
NeuralODEs and UDEs

Niklas Korsbo





What to make of embedded ML?







NLME WITH DEEPPUMAS

1.0emontono 0.5-

Time

Typical values

$$\theta \in \mathbb{R}^3_+$$
$$\Omega \in \mathbb{R}^3_+$$

Patient data



$\eta \sim \text{MvNormal}(\Omega)$

Individual parameters

Universal differential equations (UDEs)

$$Ka_{i} = \theta_{1} \cdot e^{\eta_{i,1}} + c_{1} \cdot Age_{i} + CL_{i} = \theta_{2} \cdot e^{\eta_{i,2}}$$

$$V_{i} = \theta_{3} \cdot e^{\eta_{i,3}} + c_{2} \cdot Weight_{1}^{c_{3}} + CL_{i} = \theta_{3} \cdot e^{\eta_{i,3}} + CL_{i} \cdot Weight_{1}^{c_{3}} + CL_{i} = \theta_{3} \cdot e^{\eta_{i,3}} + CL_{i} \cdot Weight_{1}^{c_{3}} + CL_{i} = \theta_{3} \cdot e^{\eta_{i,3}} + CL_{i} \cdot Weight_{1}^{c_{3}} + CL_{i} \cdot Wei$$

Dynamics

$$\frac{d[\text{Depot}]}{dt} = -Ka[\text{Depot}],$$

$$\frac{d[\text{Central}]}{dt} = Ka[\text{Depot}] -$$

Error model

 $Outcome \sim Normal \left(Central, \sqrt{Central} \cdot \sigma \right)$



Universal Differential Equations and friends



2018 - "Neural Ordinary Differential Equations", Chen et al.

2020 - "Universal Differential Equations for Scientific Machine Learning", Rackauckas et al.

Neural ODE

$$\frac{d\mathbf{X}}{dt} = NN(\mathbf{X}(t), t)$$

Use a differential equation solvers as a scaffold for continuous time, continuous depth neural networks.

Similar to recurrent neural networks and ResNets

Universal differential equation (UDE)

$$\frac{dx}{dt} = x \cdot y - NN(x)$$

$$\frac{dy}{dt} = p - x \cdot y$$

Insert universal approximators (like NNs) to capture terms in dynamical systems.

Scientific Machine Learning (SciML)

An abstract concept of mixing scientific modeling with machine learning.



Different encoded knowledge



$$\begin{split} \frac{dDepot}{dt} = & \text{NN (Depot, Central, R) [1]} \\ \frac{dCentral}{dt} = & \text{NN (Depot, Central, R) [2]} \\ \frac{dR}{dt} = & \text{NN (Depot, Central, R) [3]} \end{split}$$

Number of states.

$$egin{aligned} rac{dDepot}{dt} &= -\operatorname{NN}_1\left(Depot
ight) \ rac{dCentral}{dt} &= &\operatorname{NN}_1\left(Depot
ight) - \operatorname{NN}_2\left(Central
ight) \ rac{dR}{dt} &= &\operatorname{NN}_3\left(Central,R
ight) \end{aligned}$$

- Number of states.
- Relationships
- Dependence/independence of terms
- Conservation between Depot and Central

$$egin{aligned} rac{dDepot}{dt} &= -K_a \cdot Depot \ rac{dCentral}{dt} &= \!\! K_a \cdot Depot - rac{CL}{V_c} \cdot Central \ rac{dR}{dt} &= \!\! ext{NN} \left(rac{Central}{V_c}, R
ight) \end{aligned}$$

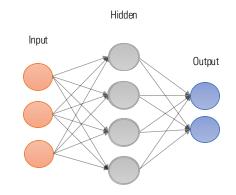
- Explicit knowledge of some terms
- Relationships (R independent of Depot!)

$$egin{aligned} rac{dDepot}{dt} &= -K_a \cdot Depot \ rac{dCentral}{dt} &= \!\! K_a \cdot Depot - rac{CL}{V_c} \cdot Central \ rac{dR}{dt} &= \!\! k_{in} \cdot \left(1 + ext{NN}\left(rac{Central}{V_c}
ight)
ight) - k_{out} \cdot R \end{aligned}$$

- Precise position of the unknown function.
- Precise input to the unknown function.
- Lots of knowledge!



UDEs – pretty simple, really



Mathematically: Just a function!

NNs are useable anywhere where you'd use a function!

- Decide where in the dynamics you have an unknown function.
- Decide what inputs this function may have.
- Fit <u>everything</u> in concert

The only hard part is building software for fitting but, with DeepPumas, that's not your problem!

