1.

```
def computeQValueFromValues(self, state, action):
    Compute the Q-value of action in state from the
     value function stored in self.values.
   "*** YOUR CODE HERE ***"
    "get the rewards from the given state"
   def getReward(s, a, s ):
        "this will return the reward + the y discount * the prev value"
       return self.mdp.getReward(s, a, s_) + self.discount*self.getValue(s_)
   "what other states can i get to and whats the probability of gettign to them"
   statesAndProbs = self.mdp.getTransitionStatesAndProbs((state, action))
   return sum(p * getReward(state, action, s) for s, p in statesAndProbs)
   "*** YOUR CODE HERE ***"
def computeActionFromValues(self, state):
     The policy is the best action in the given state
     according to the values currently stored in self.values.
     You may break ties any way you see fit. Note that if
     there are no legal actions, which is the case at the
     terminal state, you should return None.
   "*** YOUR CODE HERE ***"
   "get the q values possible."
   def theKey(a): return self.computeQValueFromValues(state, a)
   "then return the max given thos values"
   return max(self.mdp.getPossibleActions(state), key=theKey, default=None)
   "*** YOUR CODE HERE ***"
```

```
def question2():
    answerDiscount = 0.9
    answerNoise = 0.2
    return answerDiscount, answerNoise
```

```
def question3a():
    answerDiscount = .1
    answerNoise = 0
    answerLivingReward = 0 | answerNoise: int
    return answerDiscount, answerNoise, answerLivingReward
    # If not possible, return 'NOT POSSIBLE'
def question3b():
    answerDiscount = .5
    answerNoise = .2
    answerLivingReward = -2
    return answerDiscount, answerNoise, answerLivingReward
def question3c():
   answerDiscount = .9
    answerNoise = 0
    answerLivingReward = 0
    return answerDiscount, answerNoise, answerLivingReward
    # If not possible, return 'NOT POSSIBLE'
def question3d():
    answerDiscount = .9
    answerNoise = .2
    answerLivingReward = 0
    return answerDiscount, answerNoise, answerLivingReward
    # If not possible, return 'NOT POSSIBLE'
def question3e():
    answerDiscount = 0
    answerNoise = 0
    answerLivingReward = 10
    return answerDiscount, answerNoise, answerLivingReward
```

```
def update(self, state, action, nextState, reward):
    """
    The parent class calls this to observe a
    state = action => nextState and reward transition.
    You should do your Q-Value update here
    NOTE: You should never call this function,
    it will be called on your behalf
    """

    "*** YOUR CODE HERE ***"
    "make sure the state is in the qvalues list, otherwise set it to 0"
    if state not in self.qValues:
        "state wasnt in the list, so set it to 0 cant get to it."
        self.qValues[state] = {action: 0.0}

    "set the qvalue based off the a * qval"

    self.qValues[state][action] = (1 - self.alpha) * self.getQValue(
        state, action) + self.alpha * (reward + self.discount * self.getValue(nextState))
    "*** YOUR CODE HERE ***"
```

```
def computeValueFromQValues(self, state):
    """
    Returns max_action Q(state,action)
    where the max is over legal actions. Note that if
    there are no legal actions, which is the case at the
    terminal state, you should return a value of 0.0.
    """

    "*** YOUR CODE HERE ***"

def q(action): return self.getQValue(state, action)
# max(T(s,a,s')[R(s,a,s') + rVk(s')])
return max(map(q, self.getLegalActions(state)), default=0.0)
    "*** YOUR CODE HERE ***"
```

```
def getQValue(self, state, action):
    """
    Returns Q(state,action)
    Should return 0.0 if we have never seen a state
    or the Q node value otherwise
    """

    "*** YOUR CODE HERE ***"
    "check if the states are in qvals and action in qvals"
    " question 6"
    if state in self.qValues and action in self.qValues[state]:
        return self.qValues[state][action]
    return 0.0
    "*** YOUR CODE HERE ***"
```

```
def computeActionFromQValues(self, state):
    """
    Compute the best action to take in a state. Note that if there are no legal actions, which is the case at the terminal state, you should return None.
    """
    "*** YOUR CODE HERE ***"
    "get the qvalue given the state and action"
    def q(action): return self.getQValue(state, action)
    "return the max of the possible actions"
    return max(self.getLegalActions(state), key=q, default=None)
    "*** YOUR CODE HERE ***"
```

```
def getAction(self, state):
      Compute the action to take in the current state. With
      probability self.epsilon, we should take a random action and
     take the best policy action otherwise. Note that if there are
     no legal actions, which is the case at the terminal state, you
      should choose None as the action.
     HINT: You might want to use util.flipCoin(prob)
     HINT: To pick randomly from a list, use random.choice(list)
    "*** YOUR CODE HERE ***"
    "use the flipcoin prob, make sure its in range"
    if util.flipCoin(1 - self.epsilon):
        "return the qvalue"
        return self.computeActionFromQValues(state)
    "return the randomly selected path"
    return random.choice(self.getLegalActions(state))
    "*** YOUR CODE HERE ***"
```

```
def question8():
    answerEpsilon = 'NOT POSSIBLE'
    answerLearningRate = 'NOT POSSIBLE'
    # return answerEpsilon, answerLearningRate
    # If not possible, return 'NOT POSSIBLE'
    return 'NOT POSSIBLE'
```

```
def question8():
    answerEpsilon = None
    answerLearningRate = None
    # return answerEpsilon, answerLearningRate
    # If not possible, return 'NOT POSSIBLE'
    return 'NOT POSSIBLE'
```

```
def getQValue(self, state, action):
    """
    Returns Q(state,action)
    Should return 0.0 if we have never seen a state
    or the Q node value otherwise
    """

    "*** YOUR CODE HERE ***"
    "check if the states are in qvals and action in qvals"
    " question 6"
    if state in self.qValues and action in self.qValues[state]:
        return self.qValues[state][action]
    return 0.0

    "*** YOUR CODE HERE ***"
```