

# Operating Systems II : CS3523

## Spring 2019

Programming Assignment 1 : Implementing Rate-Monotonic Scheduling & Earliest Deadline First Scheduling through Discrete Event Simulation

Instructor : Dr. Sathya Peri

Author : Puneet Mangla (CS17BTECH11029)

---

### Design of Program :

We implemented **Rate – Monotonic & Earliest Deadline First** scheduling algorithms and compared / tested them using **Discrete Event Stimulation**.

#### **class Process**

A process in the program is defined by an object of class Process. The class contains the following parameters as process attributes to make the flow easy :

**int pid** - process ID

**int process\_time** – time take to complete execution

**int period** – period of arrival of process

**int deadline** – timestamp at which its deadline is completed

**int arrival\_time** – arrival time in the system

**int interrupted** – whether it was preempted or not

**int nowaiting\_time** – time it should finish execution when there is no waiting

**nowaiting\_time** and **deadline** are calculated as follows :

```
nowaiting_time = arrival_time + process_time  
deadline      = arrival_time + period
```

### time and next\_arrival

time is the current stimulated clock time whereas next\_arrival is the least time when a new process arrives in a system , this help us to hop directly to next\_arrival ensuring discrete time stimulation.

### priority\_queue<Process> processes

We maintained a priority queue that stores all the future coming processes **prioritized according to their arrival time.**

### map<Process> ready\_queue

A map is maintained for the processes currently in ready queue for fast indexing . Processes are scheduled from this ready queue only.

### Process schedule(map<int,Process>\* ready\_queue)

This functions takes out a process from the ready queue with the highest priority and returns it .

The highest priority process is the process with least **period** and least **deadline** in case of **RMS** and **EDF** respectively.

---

## Comparison metrics :

1. **Missed Deadlines** : Number of processes that missed their deadlines i.e before completing execution they expired.
  2. **Average waiting time** : Average time spent by a process in ready queue waiting to be dispatched.
-

## Algorithm :

1. Initially at `time = 0` , `ready_queue` is empty and algorithms starts .
2. At current clock time (initially 0) processes whose `arrival_time` is current time are popped from processes queue and placed in the `ready_queue`.
3. The `next_arrival` time is set to the arrival time of top process of processes queue . This will be the time when new process(es) arrive in the system.
4. A process is scheduled from `ready_queue` by calling `schedule` function and assigned as `running` process.
5. We keep on scheduling processes from `ready_queue` till the a **process A**' s finishing time exceeds `next_arrival` time. That **process A** is now assigned as `prev_running` process and current time is hopped to `next_arrival` time.
6. When time is hopped to `next_arrival` time , we check if any of the processes in `ready_queue` are expired . If yes we remove them from `ready_queue` .
7. New processes are filled from processes queue in `ready_queue` and `next_arrival` is assigned again as in **step 3**
8. A **process P** is scheduled from modified `ready_queue` and that process is compared with `prev_running` process. If the `prev_running` process still has high priority we make it as `running` process again and add **process P** to `ready_queue` . Else the `prev_running` process was preempted by **P** and we set **P** as `running` process and `prev_running.interrupted = true` .

9. Now we again have a running process . We check it was preempted or not by its `running_interrupted` flag. If yes we mark its execution as **resumes or starts** otherwise.
  10. **Step 5** is repeated again till the processes queue is empty . Once it is empty we assigned `next_arrival` as `INT_MAX` so that all process currently in ready queue are executed without any preemption.
- 

## Complications while programming:

1. Finding and verifying edge cases was a challenging task .
  2. Forgot to consider the deadlines for last processes ,so they were finishing execution even their deadline was expired.
  3. If two processes have same priority , scheduling different processes results in slightly different logs and statistics . This sometimes makes it difficult to check program correctness
- 

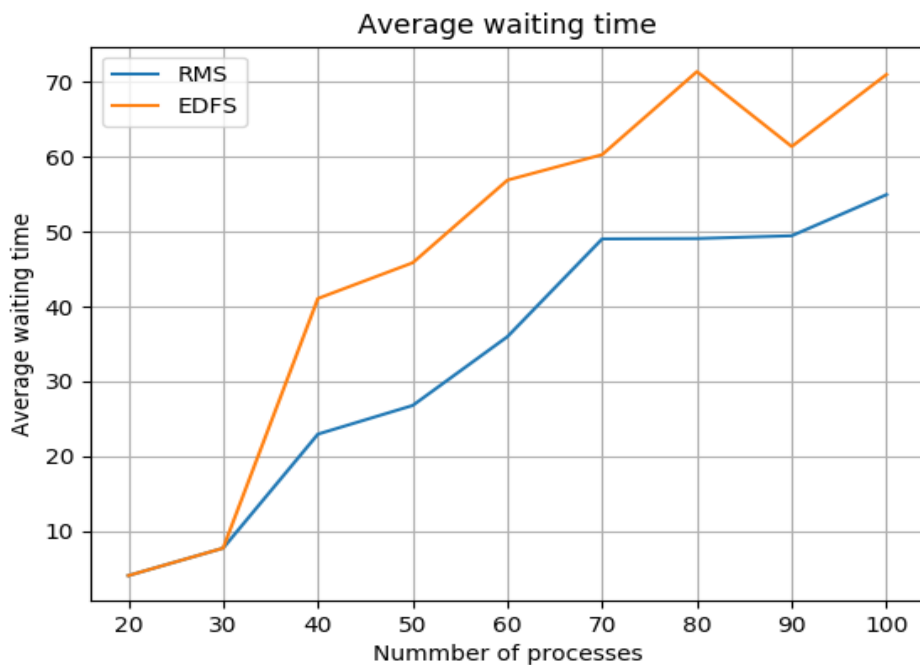
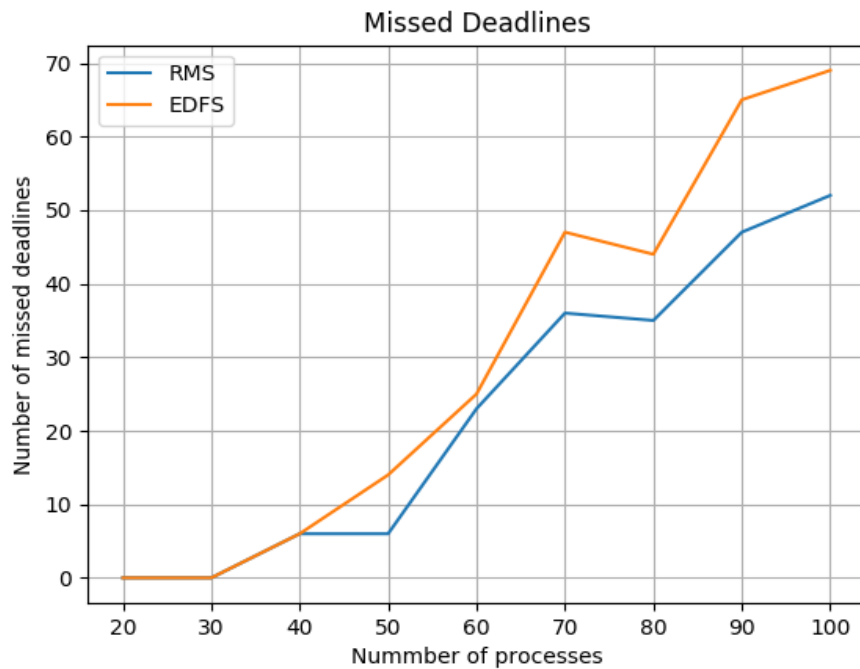
## Graphs :

C++ script is written to generate random input file with number of process ranging from 20 ( 2 processes each repeating 10 times ) to 100 ( 10 processes each repeating 10 times ) with a difference of 10 processes .

**For CPU utilization > 1 :**

Period and processing time of each process is randomly chosen in the following ranges respectively :

$$60 \leq \text{period} \leq 110$$
$$10 \leq \text{process\_time} \leq 30$$



As evident from the graphs **RM scheduling outperform EDF Scheduling** for large number of processes both in terms of average waiting time and number of deadlines missed. This outperforming of RMS over EDF is due to **dommino effect** .

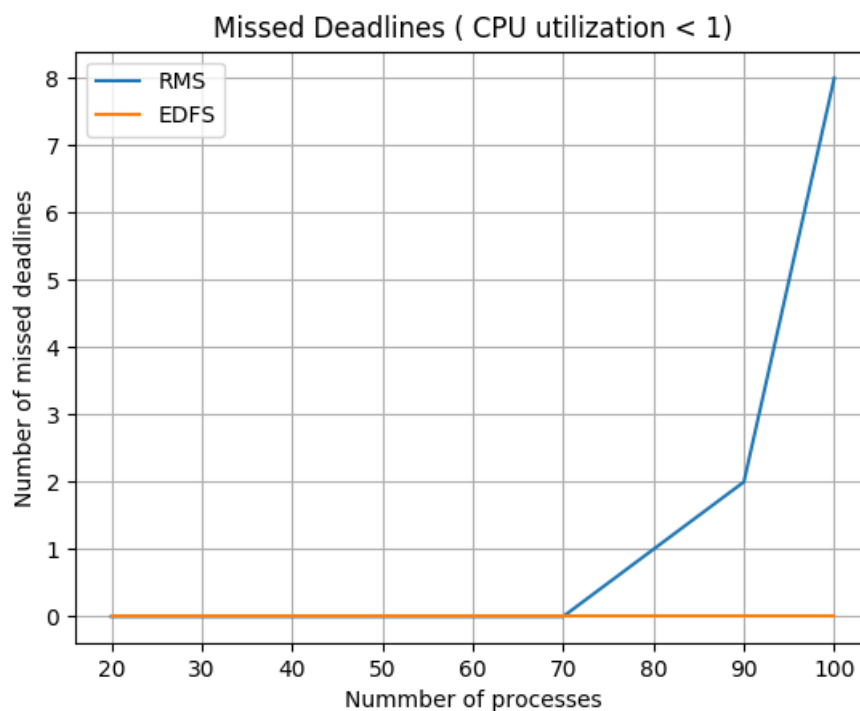
The increase in the average waiting time decreases gradually as number of processes increases whereas the number of deadlines missed rises almost monotonically with processes.

**For CPU utilization < 1 :**

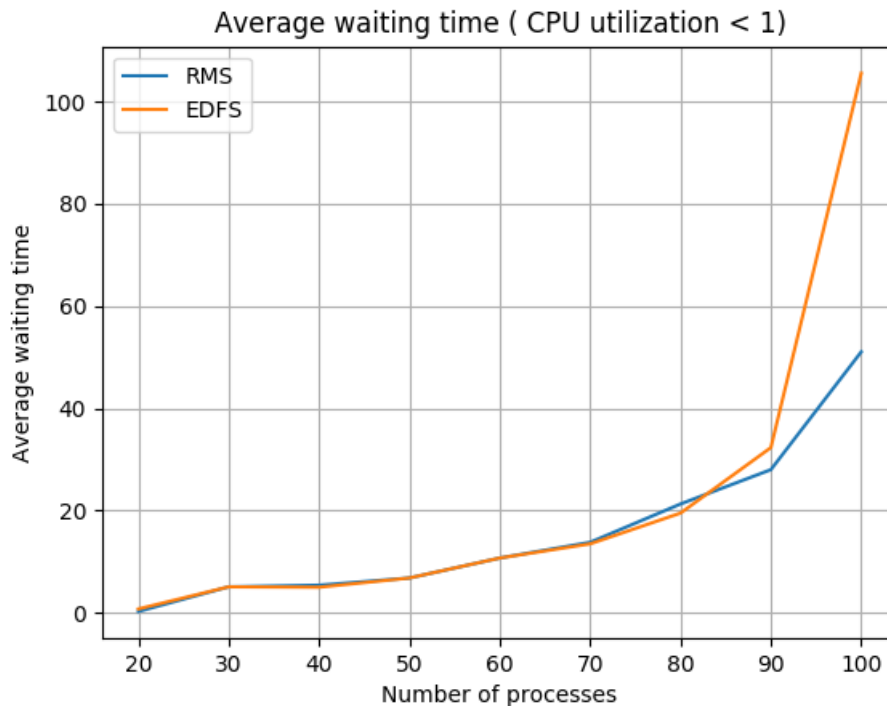
Period and processing time of each process is randomly chosen in the following ranges respectively :

$$150 \leq \text{period} \leq 250$$

$$10 \leq \text{process\_time} \leq 30$$



When CPU utilization doesn't exceed 1 we can see that **EDF** has proven to be a good scheduling algorithm than **RMS** in terms of number of missed deadlines . The deadlines misses in RMS is because the CPU utilization exceeds the upper bound given by



When the **RMS** process starts missing the deadlines , the processes are not completed and discarded from ready queue due to which that process doesn't have to wait anymore in the ready queue and leads to decrease in average waiting time . Whereas **EDF** is trying to schedule those processes and hence average waiting time increases.

---

## Conclusion :

From the graphs we can conclude that **CPU utilization is exceeding 1 then RMS** is the best scheduling algorithm in both terms ( Average waiting time and deadline miss )

If CPU utilization is less than 1 then **EDF** is better than **RMS** in terms of **number of missed deadlines** whereas **RMS** outperforms **EDF** in terms of **average waiting time**.

---