

oomph::DistributableLinearAlgebraObject

```
graph BT; A[oomph::PseudoElasticPreconditionerSubsidiaryPreconditionerOld] --> B[oomph::BlockPreconditioner< CRDoubleMatrix >]; B --> C[oomph::Preconditioner]; C --> D[oomph::DistributableLinearAlgebraObject];
```

oomph::Preconditioner

oomph::BlockPreconditioner< CRDoubleMatrix >

oomph::PseudoElasticPreconditionerSubsidiaryPreconditionerOld