## Homework 4: Graph Spectra

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### 1 Introduction

This report briefly presents the results obtained using the algorithm presented on the paper "On spectral clustering: Analysis and an algorithm" by A. Ng, M. Jordan and Y. Weiss [1].

The paper discusses an algorithm to partition a graph into K communities using a spectral approach, ie, the study of the eigenvalues and eigenvectors from matrices derived from the graph's edges structure.

### 2 The algorithm

The paper presents a spectral clustering algorithm more stable that the "out-of-the-box" methods such as KMeans and other classical spectral clustering approaches.

Given a set of points  $S = \{s_1, \ldots, s_n\}$  in  $\mathbb{R}^l$  that we want to cluster into k subsets:

- 1. Form the affinity matrix  $A \in \mathbb{R}^{n \times n}$  defined by  $A_{ij} = \exp(-||s_i s_j||^2/2\sigma^2)$  if  $i \neq j$ , and  $A_{ii} = 0$ .
- 2. Define D to be the diagonal matrix whose (i, i)-element is the sum of A's i-th row, and construct the matrix  $L = D^{-1/2}AD^{-1/2}$ .
- 3. Find  $x_1, x_2, \ldots, x_k$ , the k largest eigenvectors of L (chosen to be orthogonal to each other in the case of repeated eigenvalues), and form the matrix  $X = [x_1x_2 \ldots x_k] \in \mathbb{R}^{n \times k}$  by stacking the eigenvectors in columns.
- 4. Form the matrix Y from X by renormalizing each of X's rows to have unit length (i.e.  $Y_{ij} = X_{ij}/(\sum_j X_{ij}^2)^{1/2}$ ).
- 5. Treating each row of Y as a point in  $\mathbb{R}^k$ , cluster them into k clusters via K-means or any other algorithm (that attempts to minimize distortion).
- 6. Finally, assign the original point  $s_i$  to cluster j if and only if row i of the matrix Y was assigned to cluster j.

Figure 1: The algorithm, as presented in the paper

The algorithm consists in 3 steps made of substeps: Pre-processing, Decomposition and Grouping.

Let  $\mathcal{G}(V, E)$  be a graph, V the set of its nodes/vertices and E the set of edges such that  $E = \{(i,j) \mid \text{an edge between node i and j exists }\}$ 

#### 2.1 Pré-processing

In this step, we build **A**, a matrix representation for  $\mathcal{G}$ .  $A \in \mathbb{R}^{nxn}$  is the Affinity matrix. It captures similarities between nodes on the graph. In this algorithm this similarity depends on the distance between the points (here represented as nodes).

Step 1 of figure 1 defines the affinity between nodes i and j as  $A_{ij} = e^{-\frac{||s_i - s_j||^2}{2\sigma^2}}$ . For unweighted graphs, it becomes clear that the affinity matrix is in fact the adjacency matrix where  $A_{ij} = 1$  if an edge exists between nodes i and j. If the graph is also undirected then  $A_{ij} = A_{ji}$ .

From A we can build the diagonal matrix  $D \in \mathbb{R}^{n \times n}$  of degrees where  $D_{ii} = \sum_{j|(i,j)\in E} A_{ij}$ .

### 2.2 Decomposition

In this step we compute the spectrum ,eigenvalues and eigenvectors, of G.

But instead of computing the spectrum of A, we compute that of the graph's Laplacian L. A common definition for the Laplacian is L = D - A but in this algorithm, it's defined (step 2) as  $L = D^{\frac{1}{2}}AD^{\frac{1}{2}}$ 

The reason we compute the spectrum of L is that its eigenvalues reveal global graph structures that are not evident from the edges structure. Namely, the eigenvalues give important information about the graph's connectivity, if the k first eigenvalues of L are 0, then the graph has K connected components. Conversely, if the 2nd smallest eigenvalue,  $\lambda_2$  is greater than 0, then  $\mathcal{G}$  is connected (K = 1 components).

#### 2.3 Grouping

By using the first K eigenvectors, after normalizing them, as points in  $\mathbb{R}^K$  we can the run any classical clustering algorithm on this space. We chose to use the default Scipy's implementation of KMeans, in Python. Finally we just replace the i-th eigenvector in  $Cluster_i$  by node i.

## 3 Results

In order to test the performance of the algorithm we used both graph datasets from Canvas. The results presented are for both datasets.

### 3.1 Graph Sparsity

Below we show the sparsity of A for both datasets.

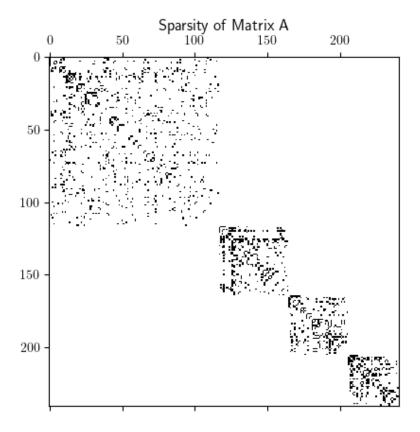


Figure 2: Matrix A's sparsity for dataset example1.dat



Figure 3: Matrix A's sparsity for dataset example2.dat

## 3.2 Graph Spectrum

Results see below.

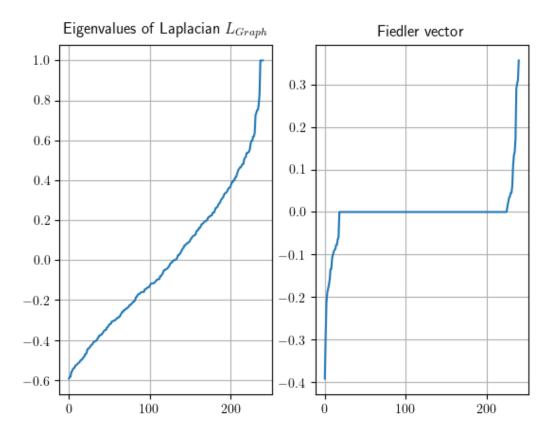


Figure 4: Graph Spectrum for example1.dat dataset

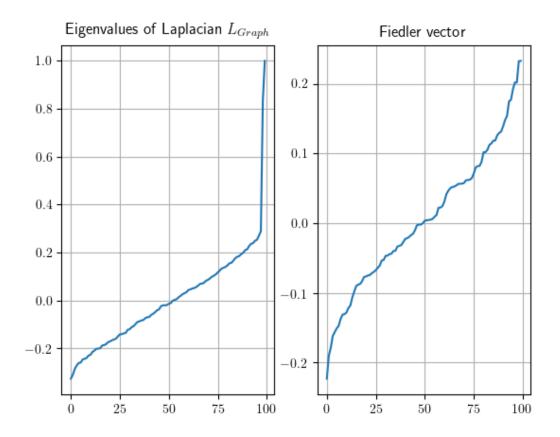


Figure 5: Graph Spectrum for example 2.dat dataset

# 3.3 Graph K-partitions

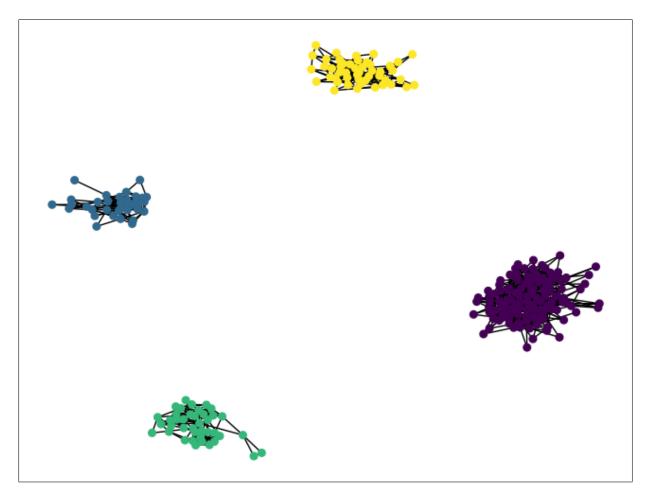


Figure 6: Graph's partitions for dataset example 1.dat using  $\mathcal{K}=4$  clusters

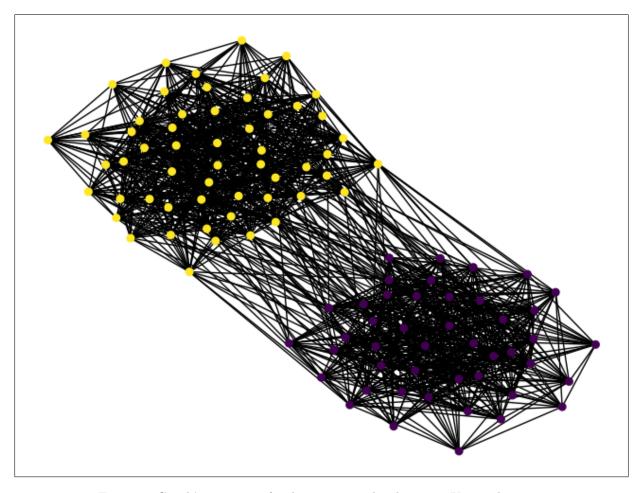


Figure 7: Graph's partitions for dataset example 1.dat using  $\mathcal{K}=2$  clusters

### 4 Build instructions

Syntax: python graph\_spectra.py [ARG\_FLAG1] [ARG\_VALUE1] For further help just run  $python\ graph\_spectra.py$  -h Run script  $graph\_spectra.py$  in the same directory where the data directory is stored.

#### Argument parser:

```
—dataset choices: 'example1.dat', 'example2.dat'
—partitions default: 4

All flags with double hyphens!
```

# References

[1] Andrew Y. Ng, Michael I. Jordan, and Yair Weiss. "On Spectral Clustering: Analysis and an algorithm". In: Advances in Neural Information Processing Systems 14 [Neural Information Processing Systems: Natural and Synthetic, NIPS 2001, December 3-8, 2001, Vancouver, British Columbia, Canada]. Ed. by Thomas G. Dietterich, Suzanna Becker, and Zoubin Ghahramani. MIT Press, 2001, pp. 849-856. URL: https://proceedings.neurips.cc/paper/2001/hash/801272ee79cfde7fa5960571fee36b9b-Abstract.html.