# CS2040S Data Structures and Algorithms

Augmented Trees!

#### Last week...

**Dictionaries** 

Binary search trees

**Tries** 

Balanced search trees

- AVL trees
- Scapegoat trees
- B-trees

### Today: Dynamic Data Structures

1. Maintain a set of items

2. Modify the set of items

3. Answer queries.

### Today: Dynamic Data Structures

1. Maintain a set of items

2. Modify the set of items

3. Answer queries.

B-trees are at the heart of *every* database!

Big picture idea:

Trees are a good way to store, summarize, and search dynamic data.

### **Dynamic Data Structures**

- Operations that create a data structure
  - build (preprocess)
- Operations that modify the structure
  - insert
  - delete

- Query operations
  - search, select, etc.

"Why do we need to learn how an AVL tree works?"

Just use a Java TreeMap, amiright?

"Why do we need to learn how an AVL tree works?"

1. Learn how to think like a computer scientist.

"Why do we need to learn how an AVL tree works?"

- 1. Learn how to think like a computer scientist.
- 2. Learn to modify existing data structures to solve new problems.

### **Augmented Data Structures**

Many problems require storing additional data in a standard data structure.

Augment more frequently than invent

### **Augmented Data Structures**

Many problems require storing additional data in a standard data structure.

Augment more frequently than invent

Useful for summarizing and processing data

### Today

Three examples of augmenting balanced BSTs

1. Order Statistics

2. Interval Queries

3. Orthogonal Range Searching

#### Basic methodology:

1. Choose underlying data structure (tree, hash table, linked list, stack, etc.)

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(subject to insert/delete/etc.)

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(subject to insert/delete/etc.)

4. Develop new operations.

Input

A set of integers.

Output: select(k)

#### select(2) returns:

<b>52</b>	7	13	43	22	92	18	9	65	67	87	25
											4

- 1. 52
- **√**2. 9
  - 3. 13
  - 4. 43
  - 5. 25



Input

A set of integers.

Output: select(k)

Input

A set of integers.

Output: select(k)

Input

A set of integers.

Output:  $select(k) \longrightarrow Sort: O(n log n)$ 

Input

A set of integers.

Output: select(k) ———— QuickSelect: O(n)

Solution 1:

Sort: O(n log n)

Solution 2:

QuickSelect: O(n)

#### Solution 1:

```
Preprocess: sort --- O(n log n)
```

Select: O(1)

#### Solution 2:

Preprocess: nothing --- O(1)

QuickSelect: O(n)

#### Solution 1:

Preprocess: sort --- O(n log n)

Select: O(1)

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Preprocess: nothing --- O(1)

QuickSelect: O(n)

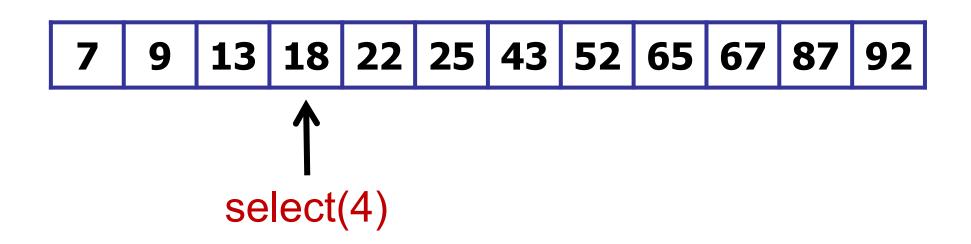
Trade-off: how many items to select?

#### Implement a data structure that supports:

- insert(int key)
- delete(int key)

#### and also:

select(int k)



#### Solution 1:

Basic structure: sorted array A.

insert(int item): add item to sorted array A.

select(int k): return A[k]

7 9 13 18 22 25 43 52 65 67 87 92

#### Solution 2:

Basic structure: unsorted array A.

insert(int item): add item to end of array A.

select(int k): run QuickSelect(k)

7 9 13 18 22 25 43 52 65 67 87 92

## When is it more efficient to maintain a sorted array (Solution 1)?

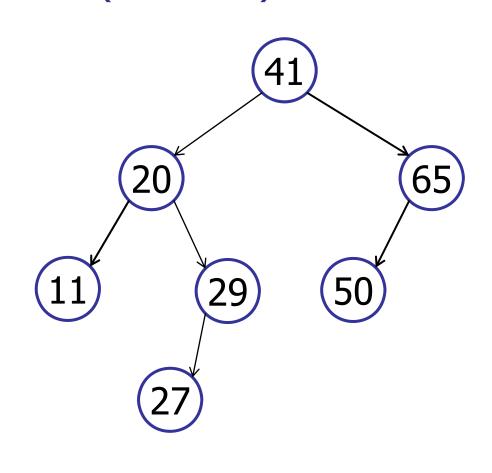
- A. Always
- B. When there are more inserts than selects.
- C. When there are more selects than inserts.
  - D. Never
  - E. I'm confused.



	Insert	Select
Solution 1: Sorted Array	O(n)	O(1)
Solution 2: Unsorted Array	O(1)	O(n)

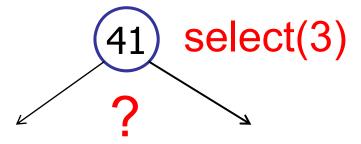


Today: use a (balanced) tree

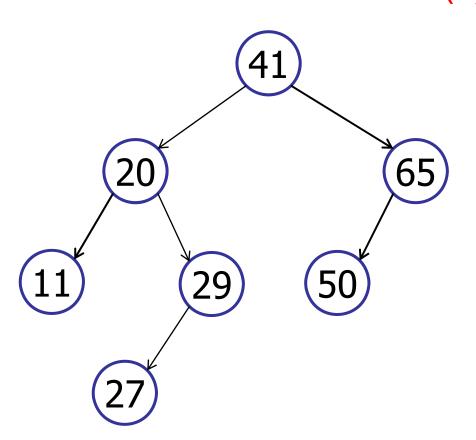


 11
 20
 27
 29
 41
 50
 65

How to find the right item?



Simple solution: traversal select(k): O(k)

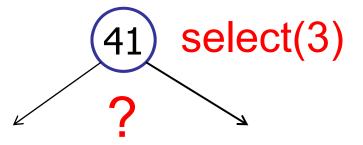


in-order traversal

11 20 27 29 41 50 65

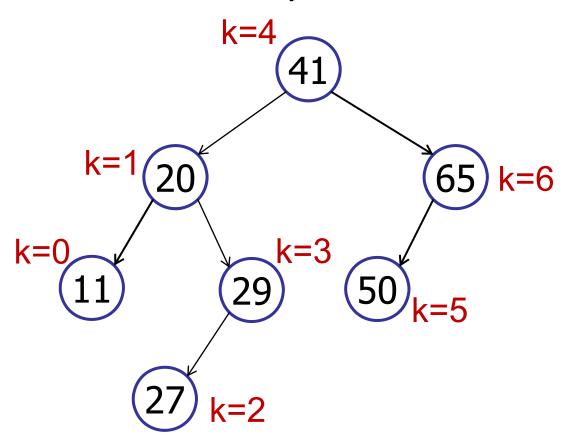
Augment!

What extra information would help?



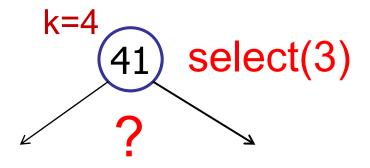


Idea: store rank in every node



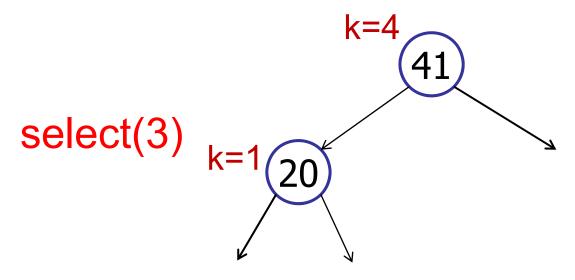
11 20 27 29 41 50 65

Idea: store rank in every node



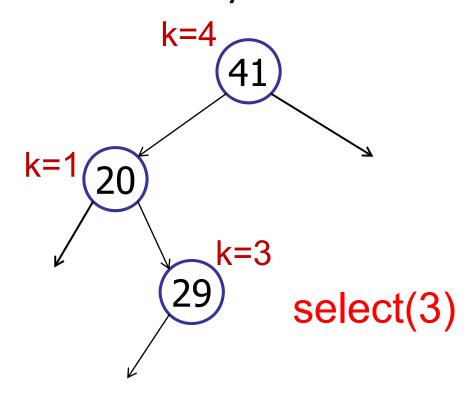
11 20 27 29 41 50 65

Idea: store rank in every node



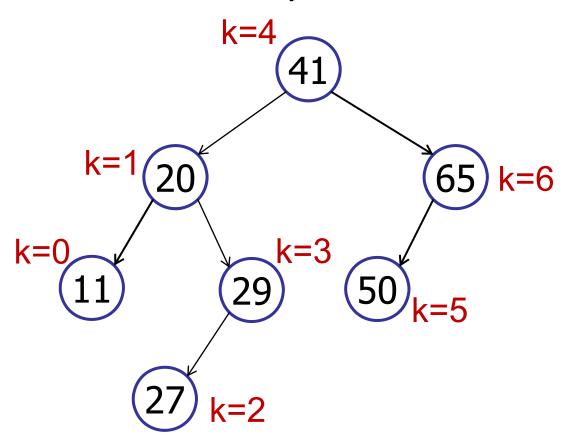


Idea: store rank in every node



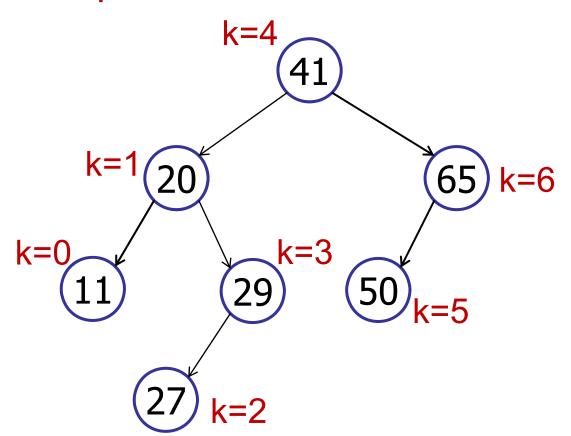
11 20 27 29 41 50 65

Idea: store rank in every node



11 20 27 29 41 50 65

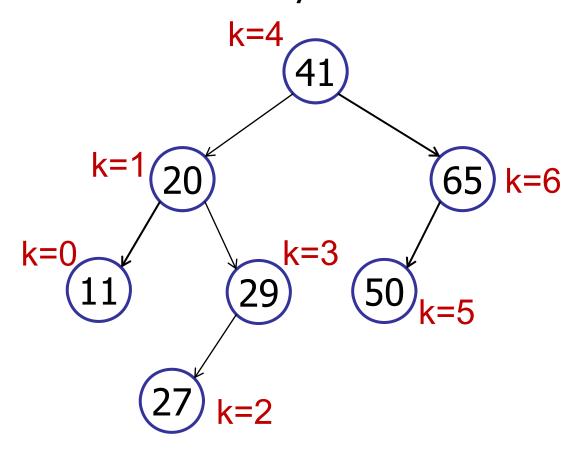
What is the problem if we store rank in every node?





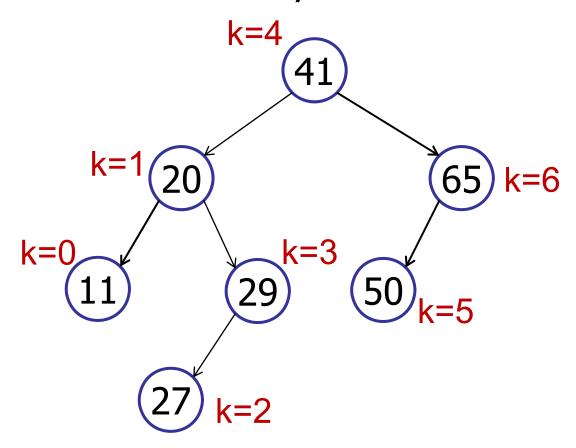
11	20	27	29	41	<b>50</b>	65
----	----	----	----	----	-----------	----

Idea: store rank in every node



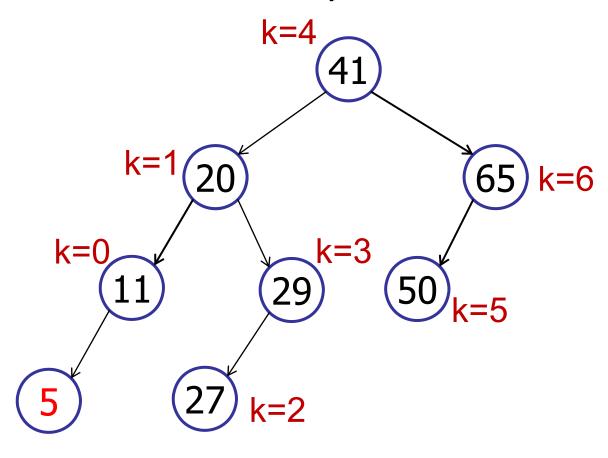
Problem: insert(5)

Idea: store rank in every node



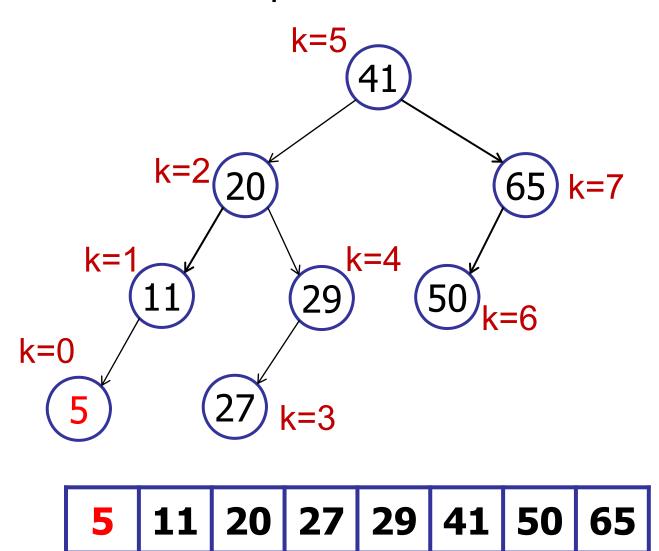
Problem: insert(5) requires updating all the ranks!

Idea: store rank in every node

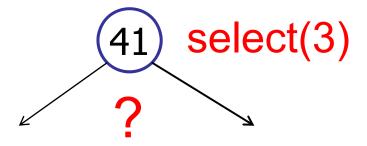


 5
 11
 20
 27
 29
 41
 50
 65

Conclusion: too expensive to store rank in every node!

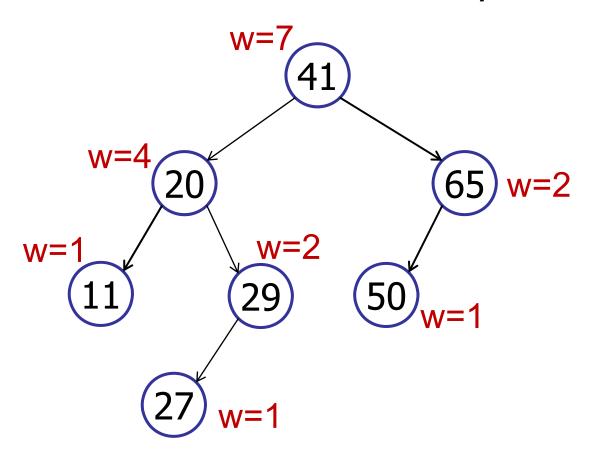


What should we store in each node?





Idea: store size of sub-tree in every node



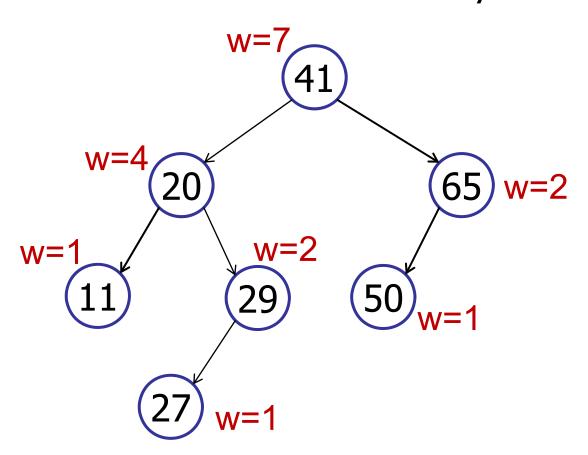
Idea: store size of sub-tree in every node

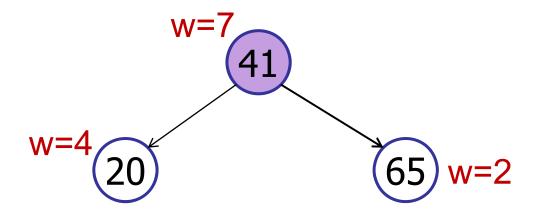
The <u>weight</u> of a node is the size of the tree rooted at that node.

#### Define weight:

```
w(leaf) = 1
 w(v) = w(v.left) + w(v.right) + 1
```

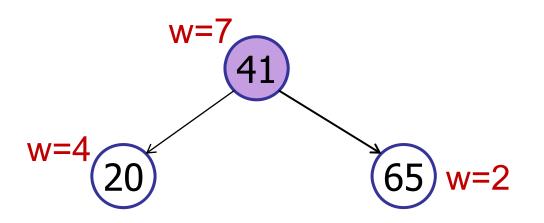
Idea: store size of sub-tree in every node





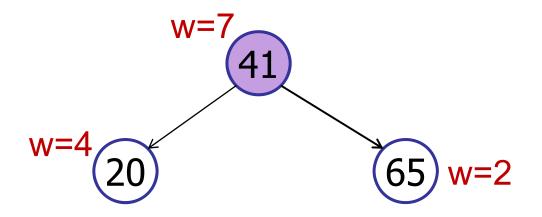
#### What is the rank of 41?

- 1. 1
- 2. 3
- **✓**3. 5
  - 4. 7
  - 5.9
  - 6. Can't tell.

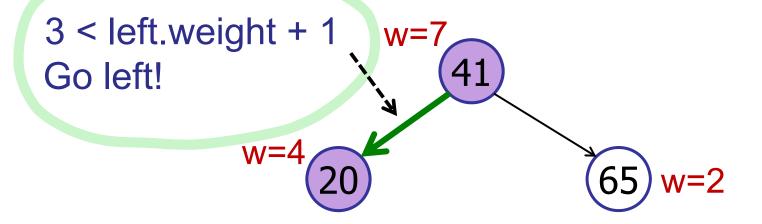


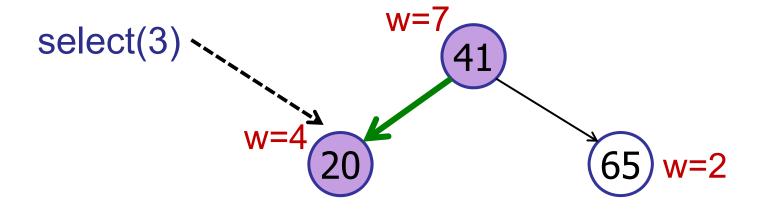


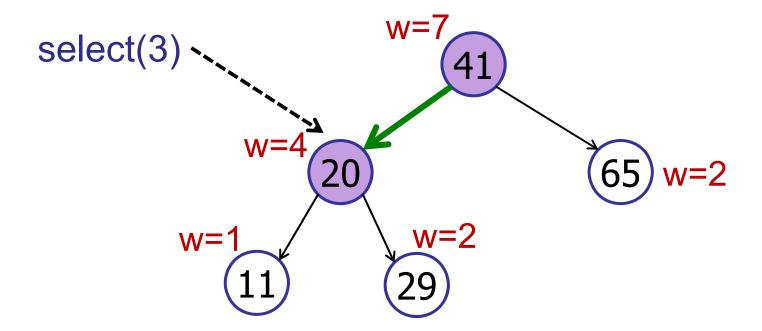
Example: select(3)

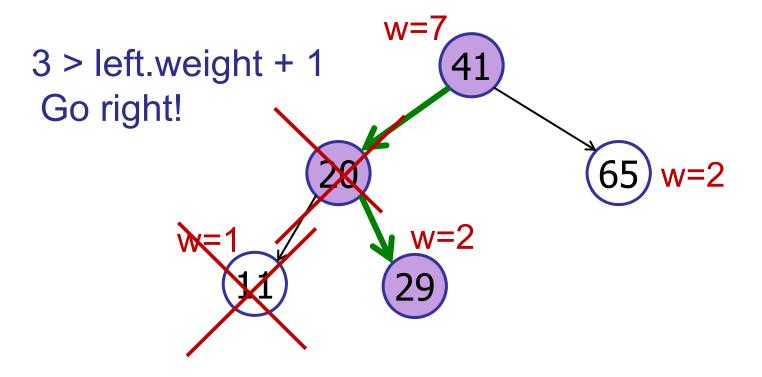


"rank in subtree" = left.weight + 1

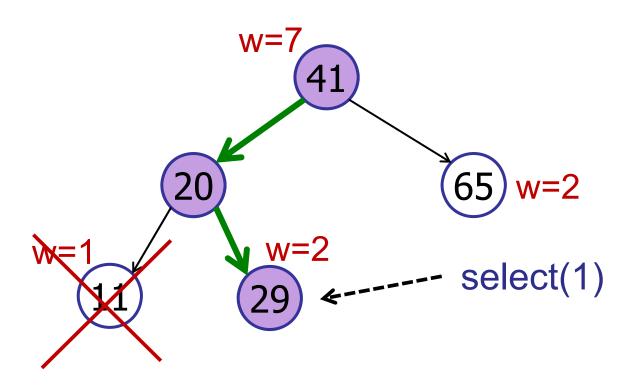








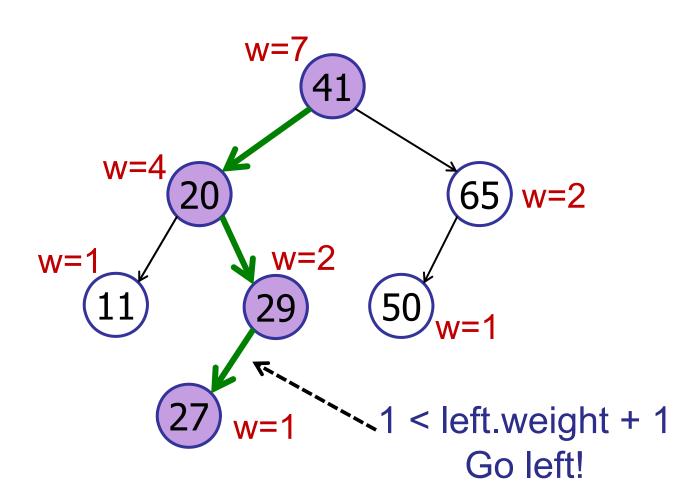
Example: select(3)

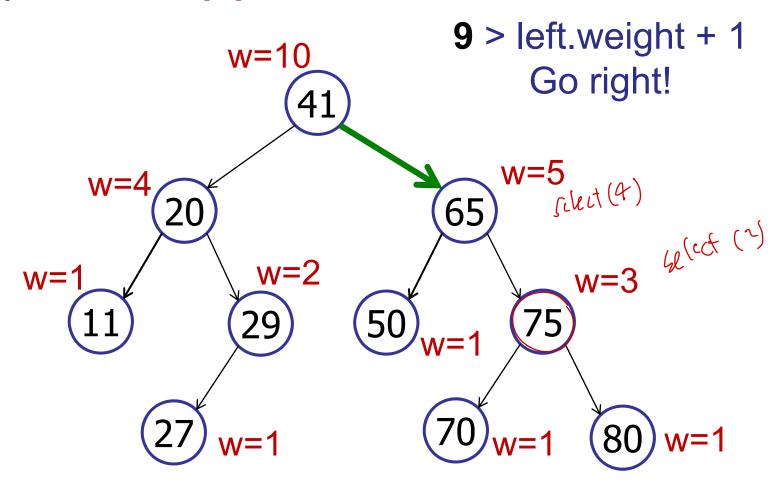


#### Item to select:

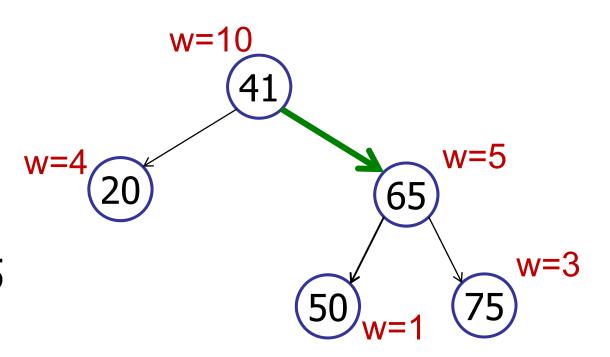
$$3 - (left.weight + 1) =$$

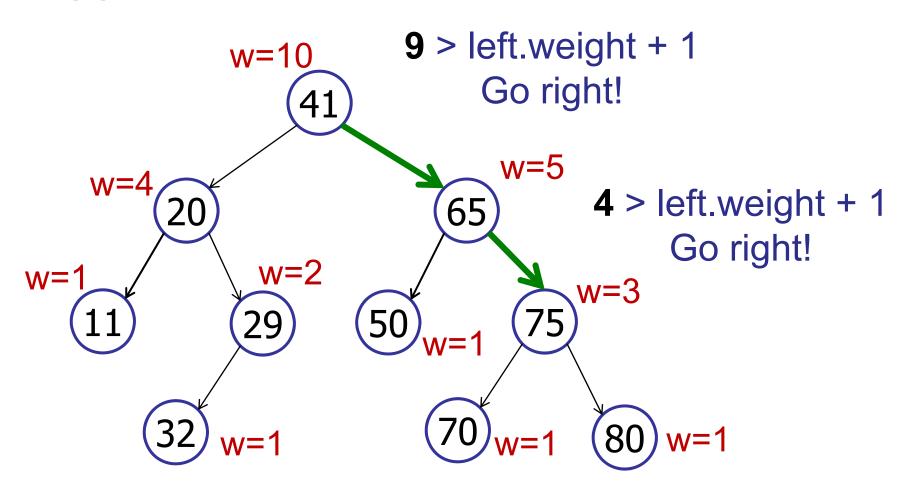
$$3 - (1 + 1) = 1$$



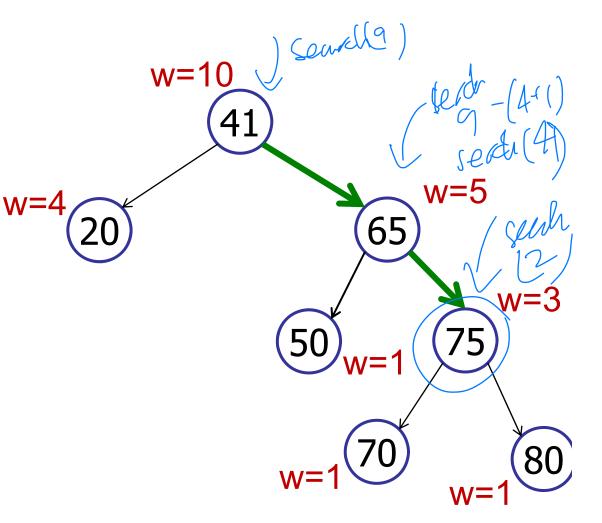


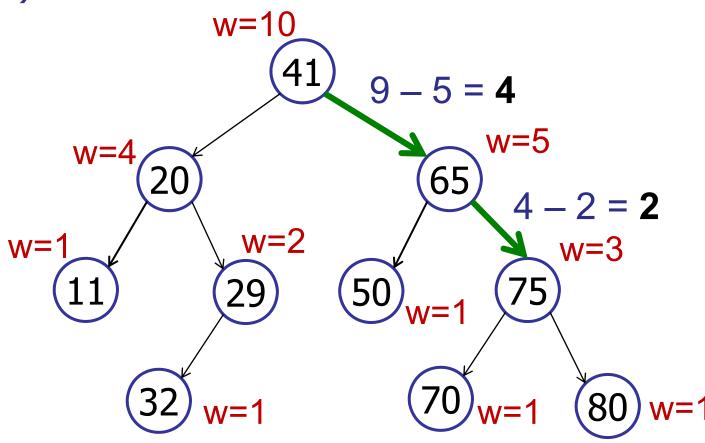
- 1. Go left at 65
- ✓2. Go right at 65
  - 3. Stop at 65
  - 4. I'm confused





- 1. Go left at 75
- 2. Go right at 75
- **✓**3. Stop at 75
  - 4. I'm confused





### select(k)

```
rank = left.weight + 1;
if (k == rank) then
    return v;
else if (k < rank) then
    return left.select(k);
else if (k > rank) then
    return right.select(k-rank);
```

select(k): finds the node with rank k

Example: find the 10th tallest student in the class.

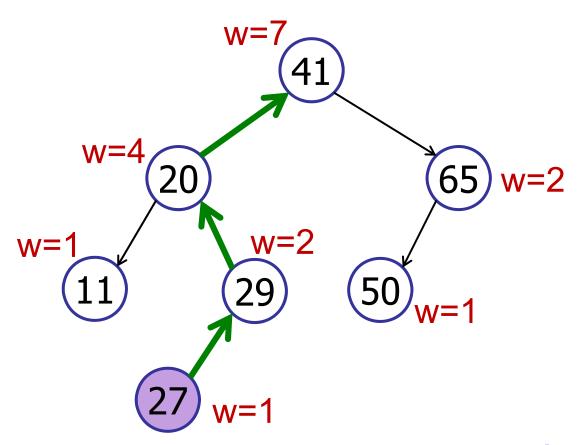
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Example: find the 10th tallest student in the class.

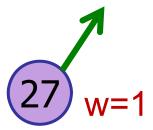
rank(v): computes the rank of a node v

Example: determine the percentile of Johnny's height. Is Johnny in the 10<sup>th</sup> percentile or the 90<sup>th</sup> percentile?

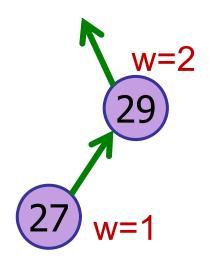
Example: rank(27)



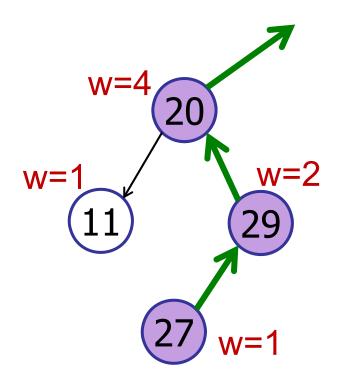
Example: rank(27)



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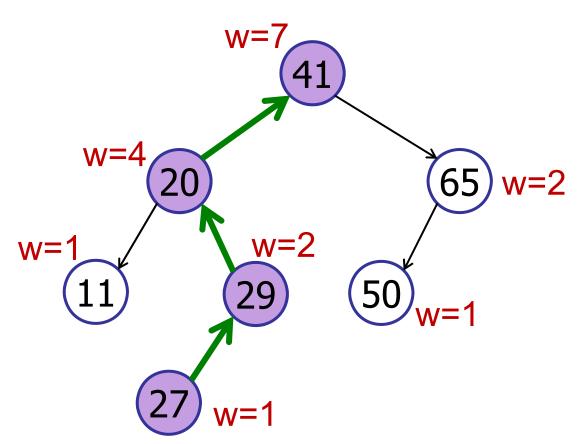


Example: rank(27)



rank = 1 + 2

Example: rank(27)

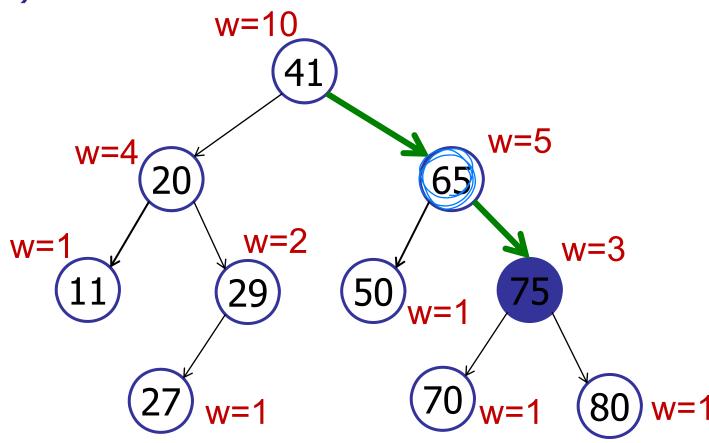


rank = 1 + 2 = 3

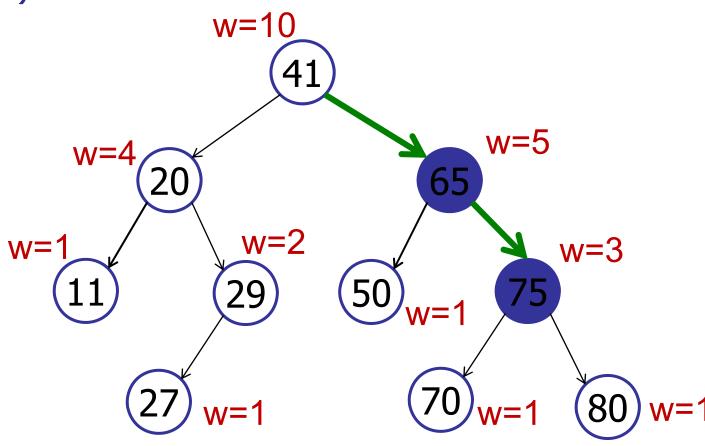
Rank(v): computes the rank of a node v

```
rank(node)
     rank = node.left.weight + 1;
     while (node != null) do
           if node is left child then
                  do nothing
           else if node is right child then
                  rank += node.parent.left.weight + 1;
           node = node.parent; _____ plate _____ node
     return rank;
```

rank(75)



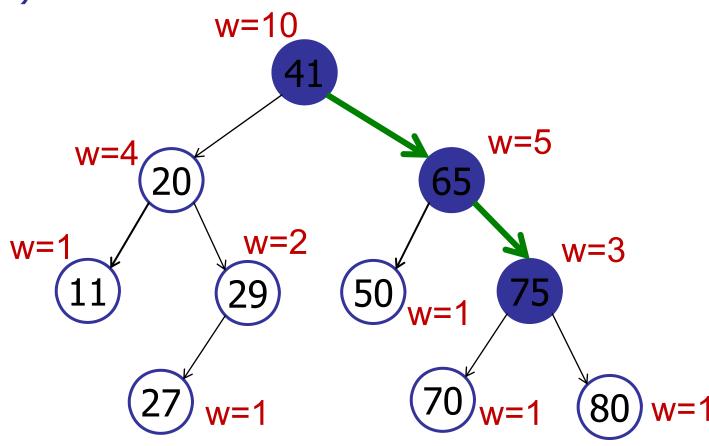
rank(75)



$$rank = 2 + 2$$

#### **Dynamic Order Statistics**

rank(75)



$$rank = 2 + 2 + 5 = 9$$

#### **Dynamic Order Statistics**

node = node.parent;

return rank;

Rank(v): computes the rank of a node v rank(node) rank = node.left.weight + 1; while (node != null) do if node is left child then do nothing else if node is right child then rank += node.parent.left.weight + 1;

#### Augmenting data structures

#### Basic methodology:

1. Choose underlying data structure:

**AVL** tree

- 2. Determine additional info needed: Weight of each node
- 3. Maintained info as data structure is modified.

  Update weights as needed
- 4. Develop new operations using the new info.

Select and Rank

#### Augmenting data structures

#### Basic methodology:

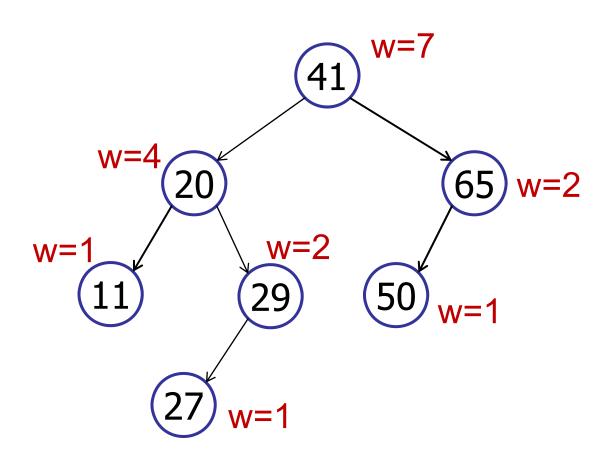
1. Choose underlying data structure:

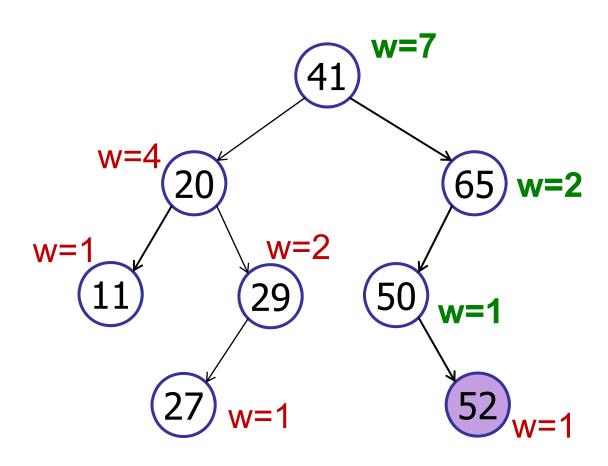
**AVL** tree

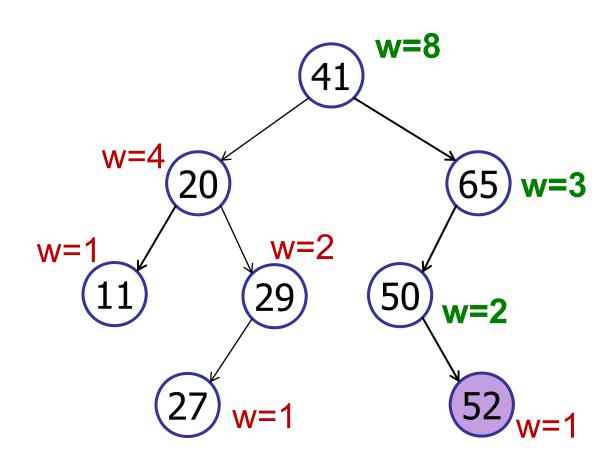
- 2. Determine additional info needed: Weight of each node
- 3. Maintained info as data structure is modified.

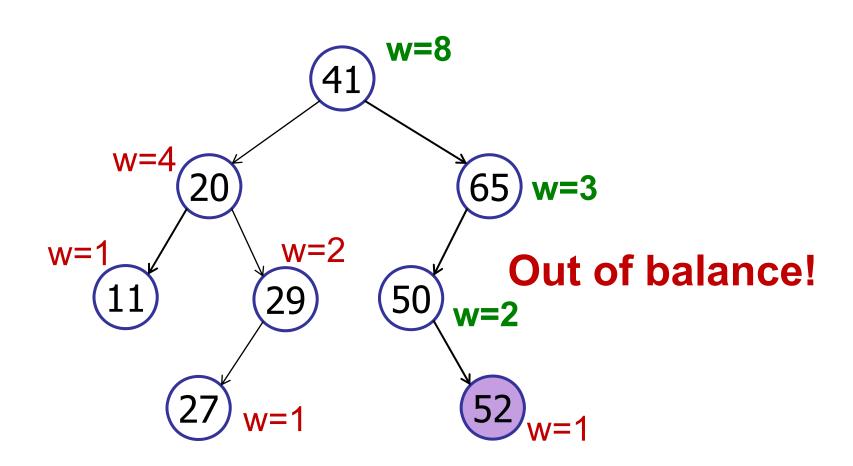
  Update weights as needed
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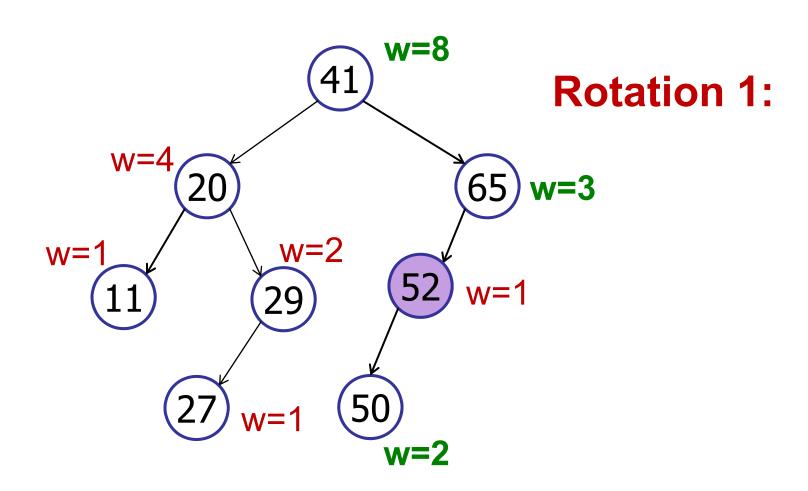
Select and Rank

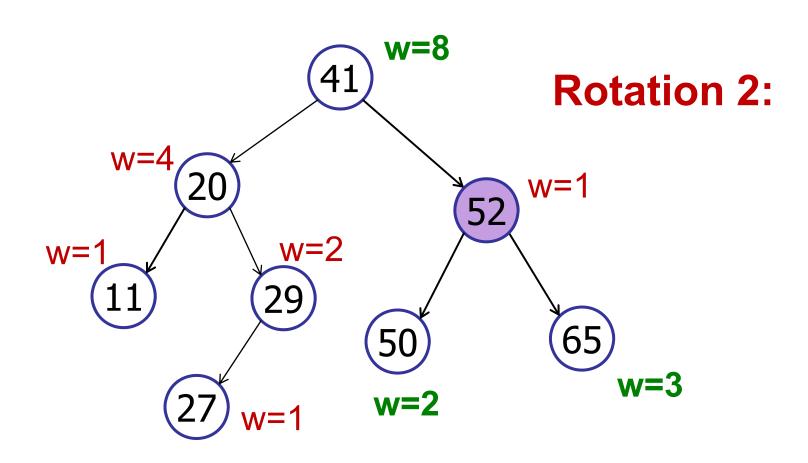




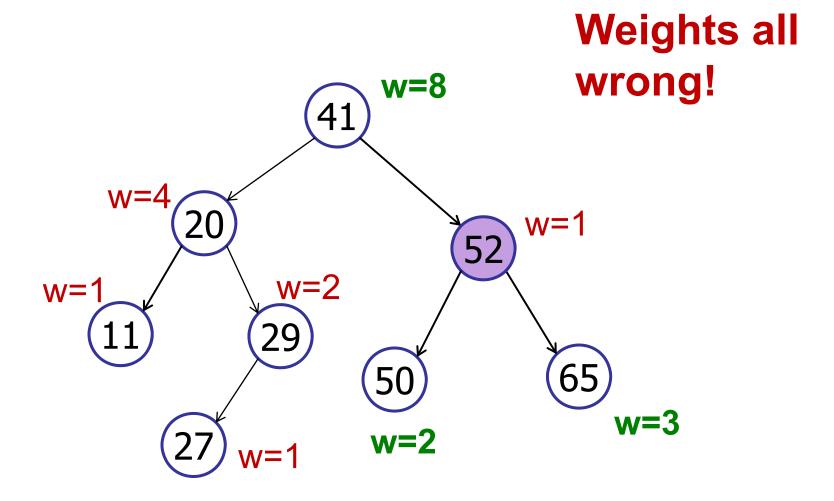


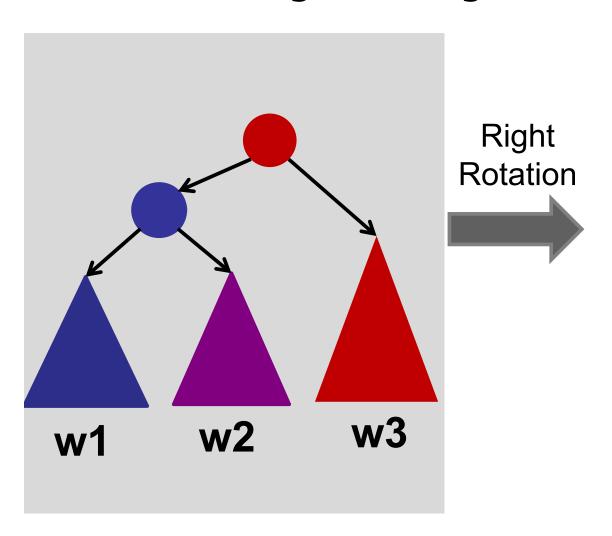


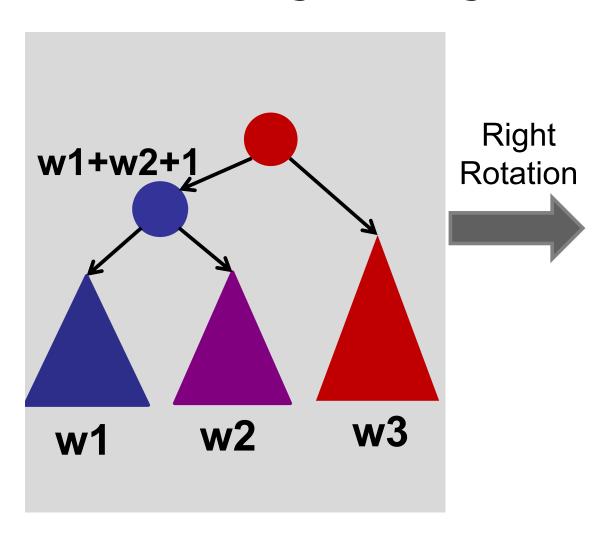


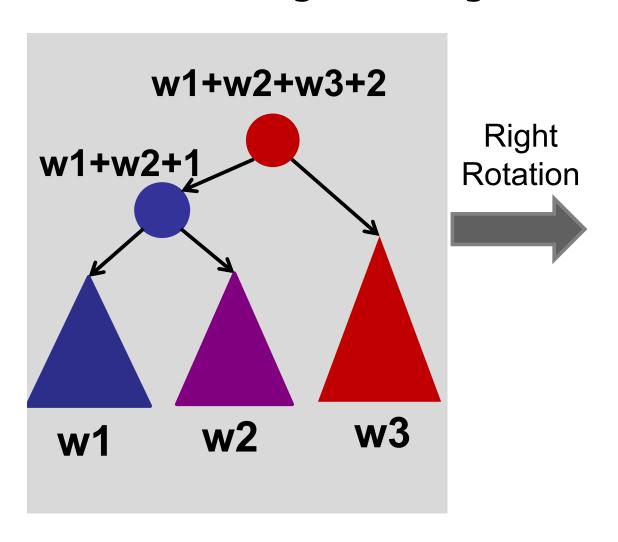


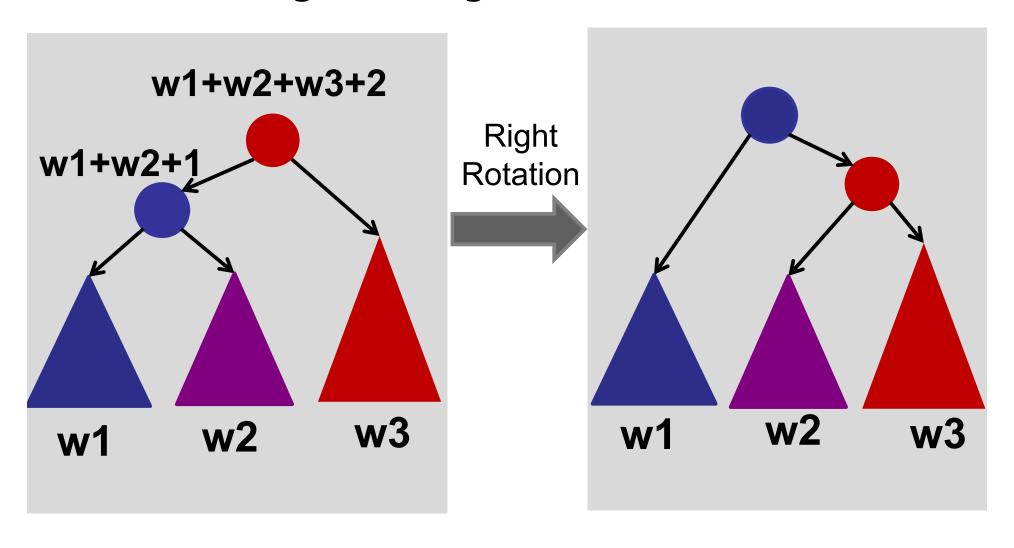
How to update weights on rotation?

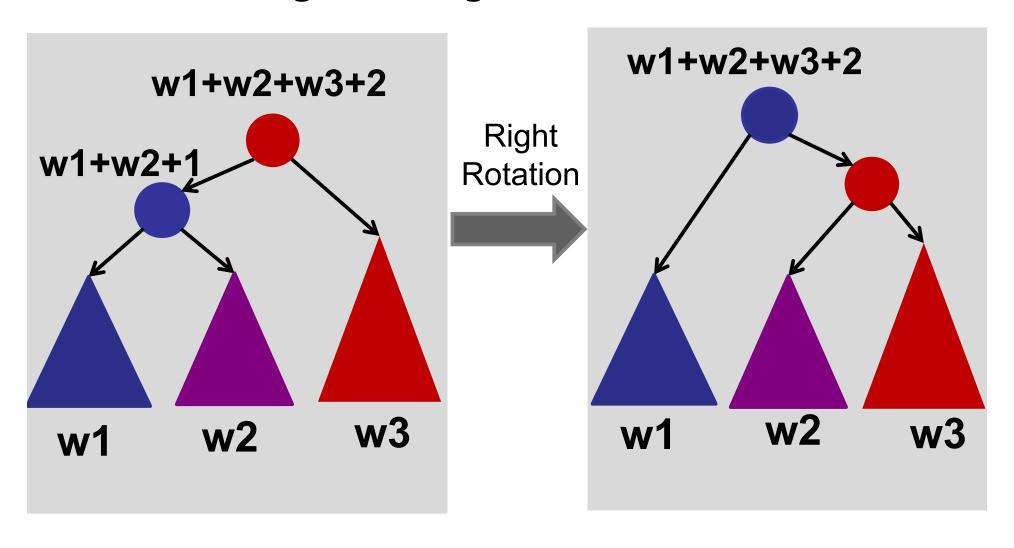


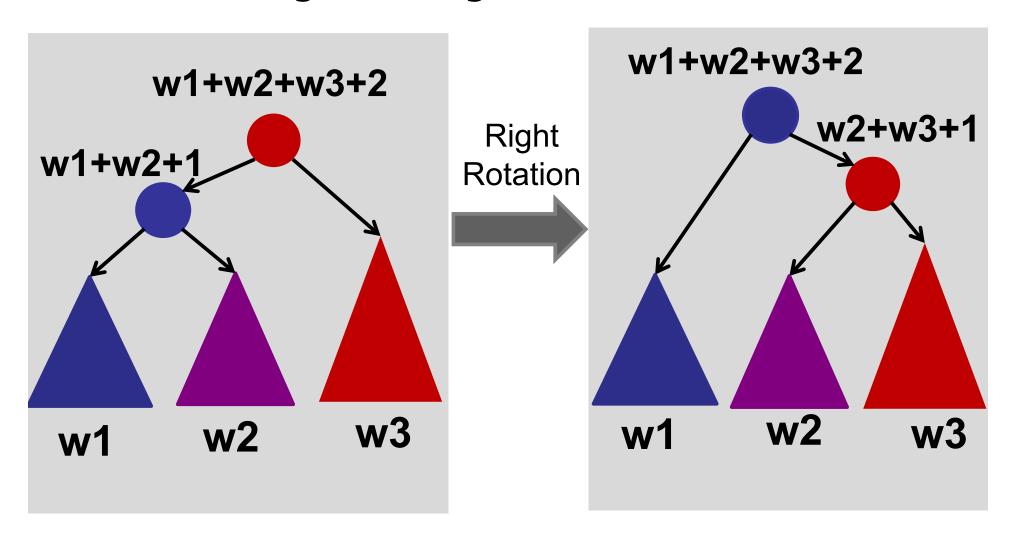










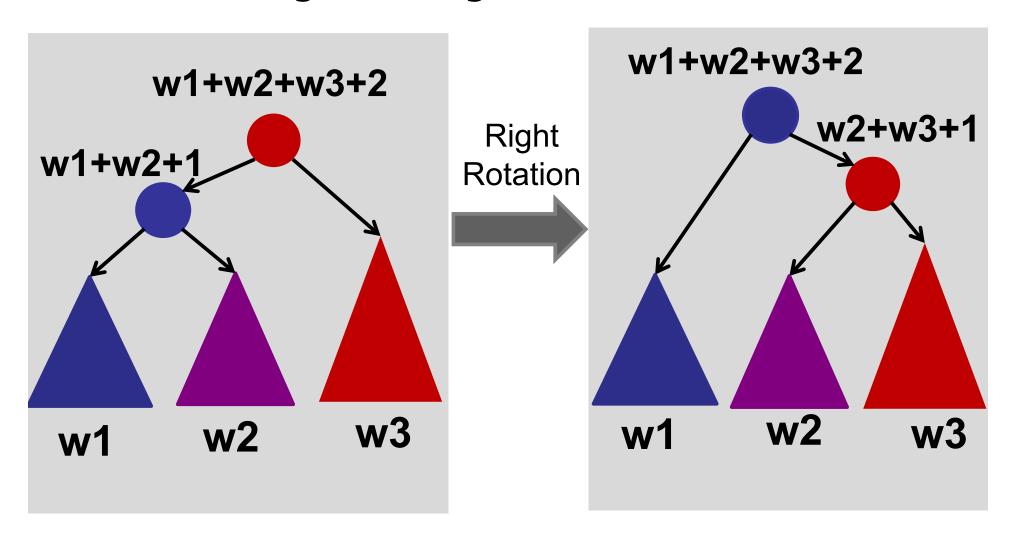


# How long does it take to update the weights during a rotation?

- 1.0(1)
- 2. O(log n)
- 3. O(n)
- 4.  $O(n^2)$
- 5. What is a rotation?

How long does it take to update the weights during a rotation?

- 1. O(1)
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- 5. What is a rotation?



## Augmenting data structures

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- 2. Determine additional info needed.
- 3. Verify that the additional info can be maintained as the data structure is modified.

(subject to insert/delete/etc.)

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## Today

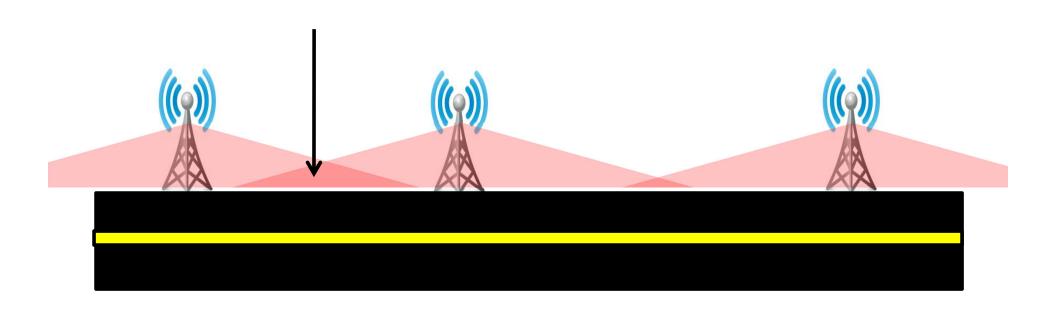
Three examples of augmenting balanced BSTs

1. Order Statistics

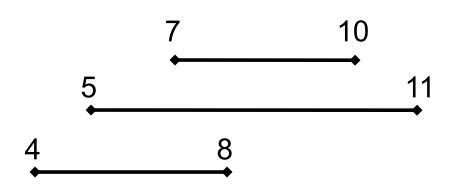
2. Intervals

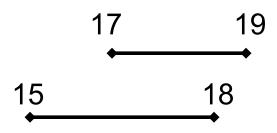
3. Orthogonal Range Searching

Find a tower that covers my location.

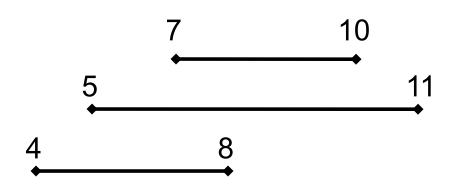


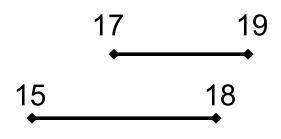
Find a tower that covers my location.





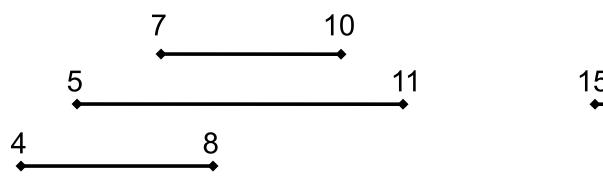
Find a tower that covers my location.





insert(begin, end) delete(begin, end)

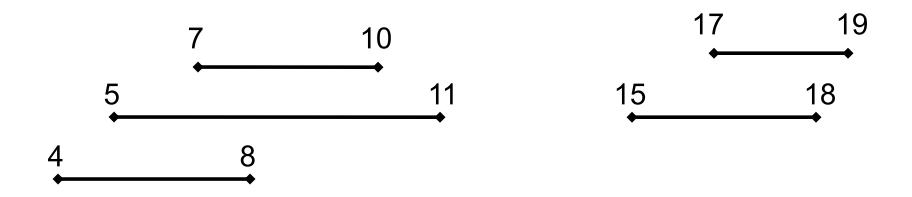
Find a tower that covers my location.



insert(begin, end) delete(begin, end)

query(x): find an interval that overlaps x.

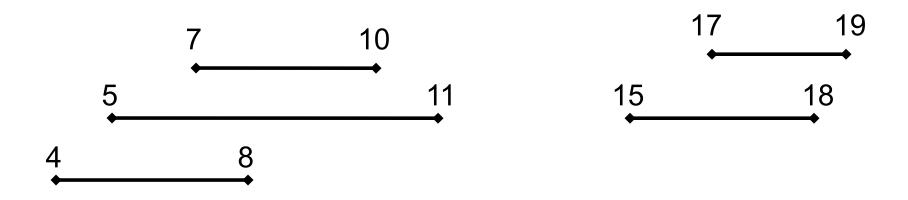
Find a tower that covers my location.



Idea 1: Keep intervals in a list.

Query: scan entire list.

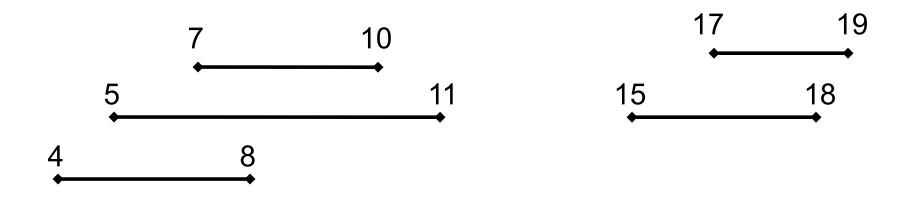
Find a tower that covers my location.



Idea 1: Keep intervals in a list.

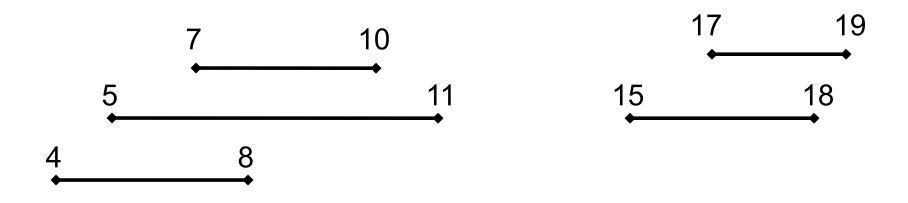
Query: scan entire list.

Find a tower that covers my location.



Idea 2: O(1) queries??

Find a tower that covers my location.

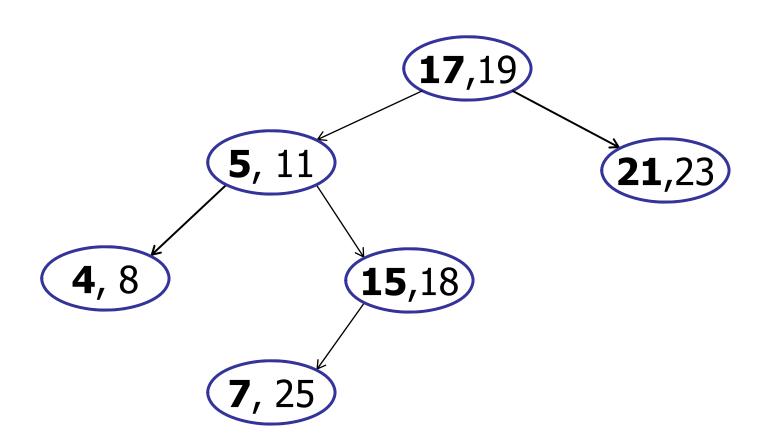


Idea 2: O(1) queries

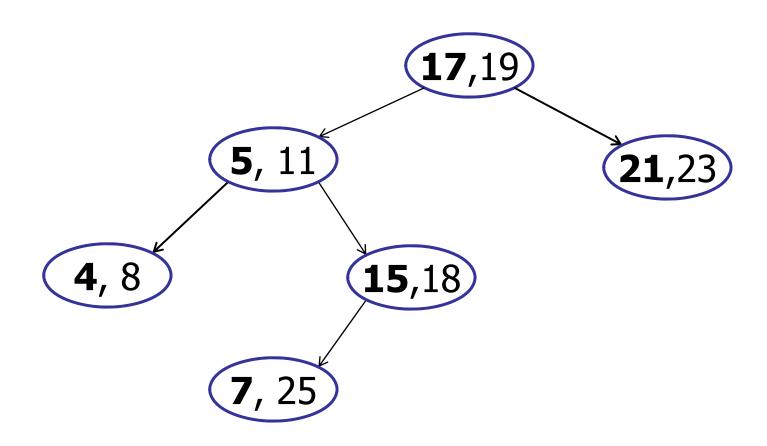
			A	A	A	A	A	В	В	C				D	D	D	D	Ε	
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20

#### Idea 3: Interval Trees

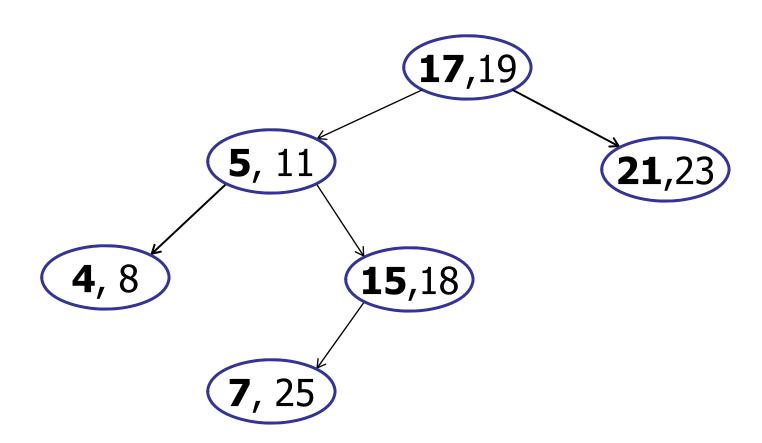
Each node is an interval



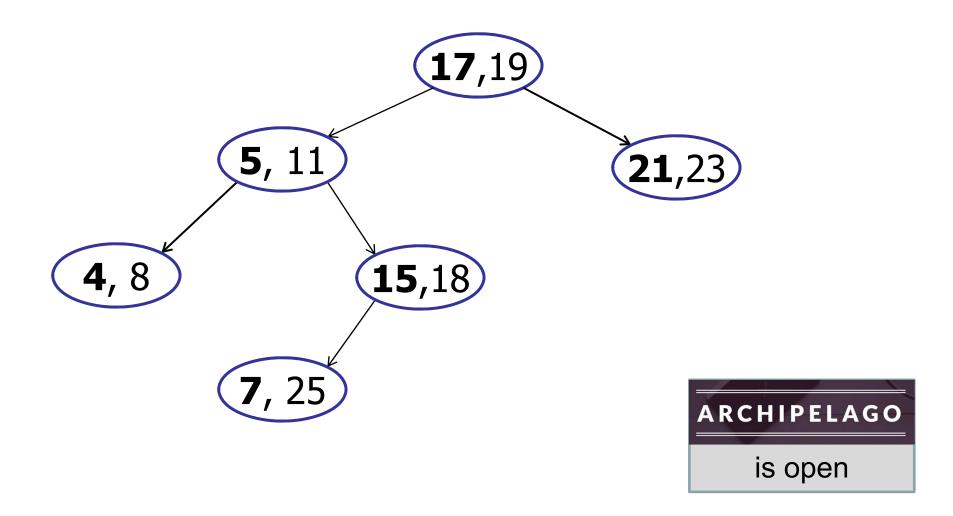
Sorted by left endpoint



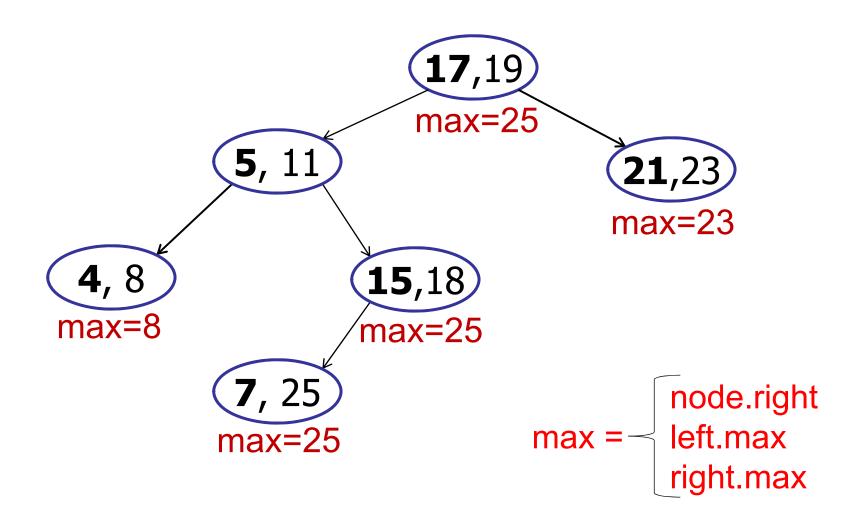
search-interval(25) = ?

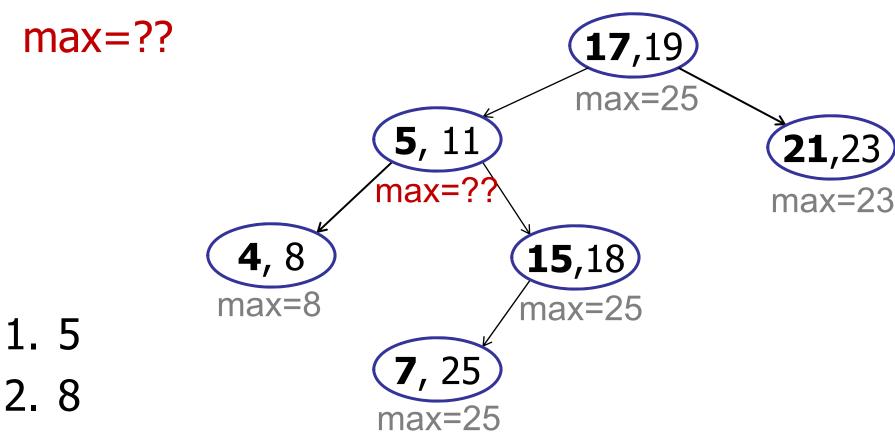


Augment: ??



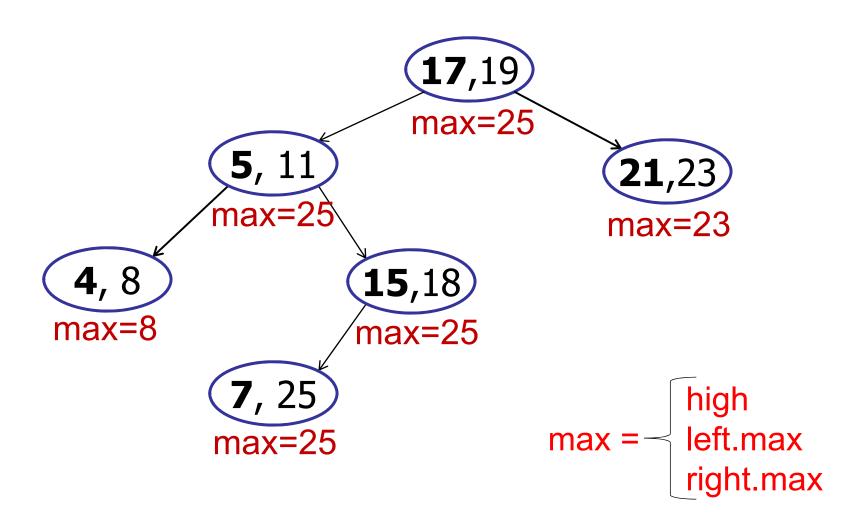
Augment: maximum endpoint in subtree



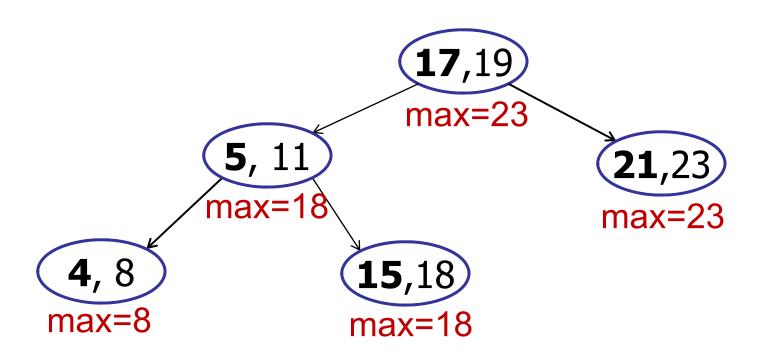


- 2.8
- 3. 11
- 4. 18
- **✓**5. 25
  - 6. 19

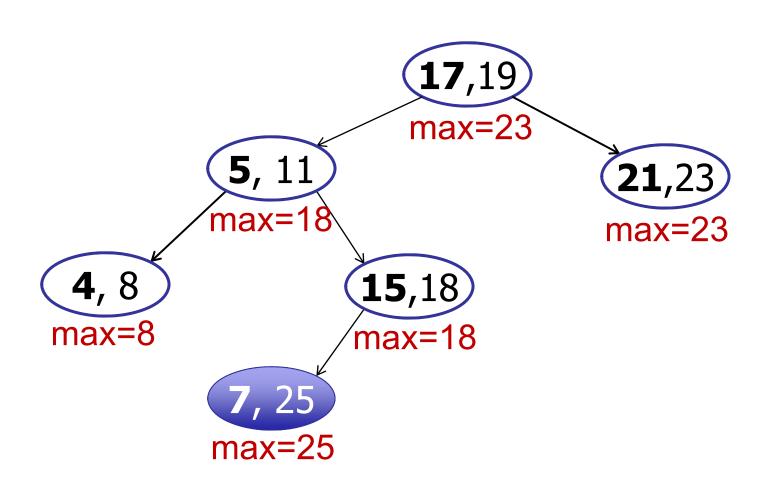
Augment: maximum endpoint in subtree



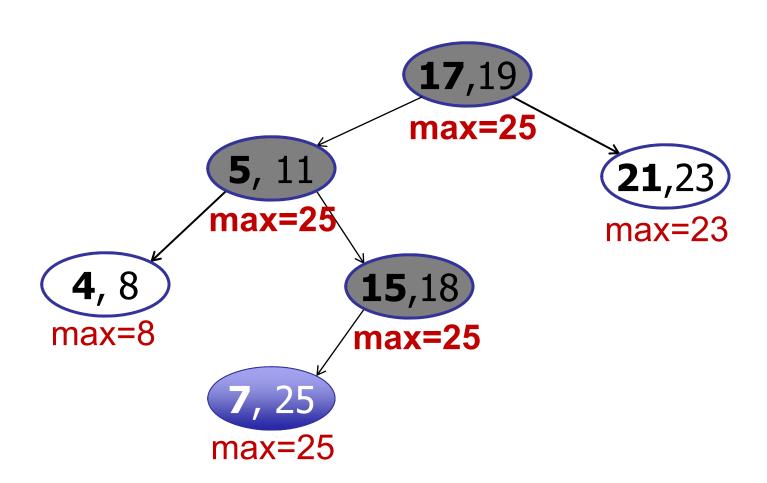
Insertion: example - insert(7, 25)



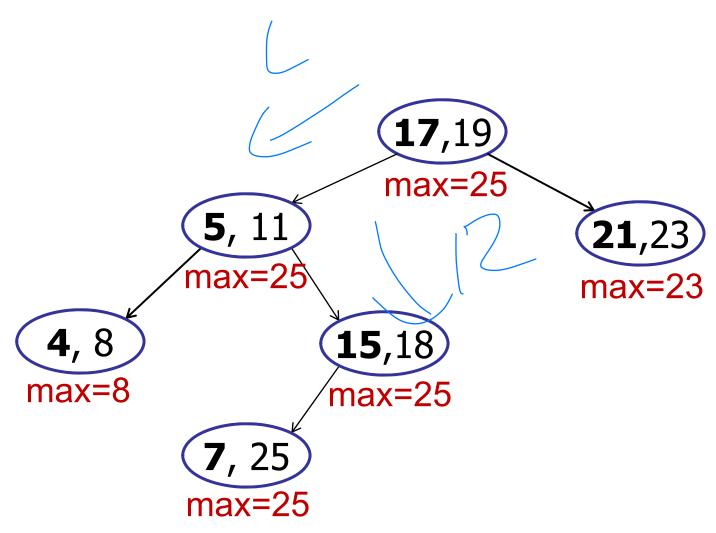
Insertion: example - insert(7, 25)



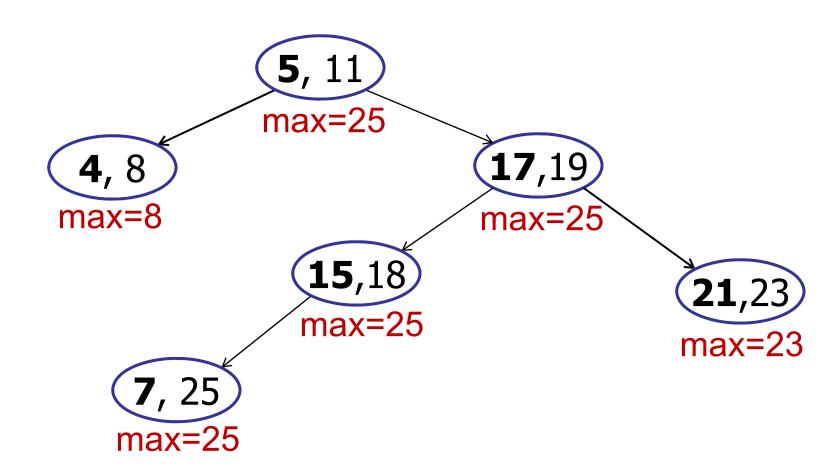
Insertion: example - insert(7, 25)



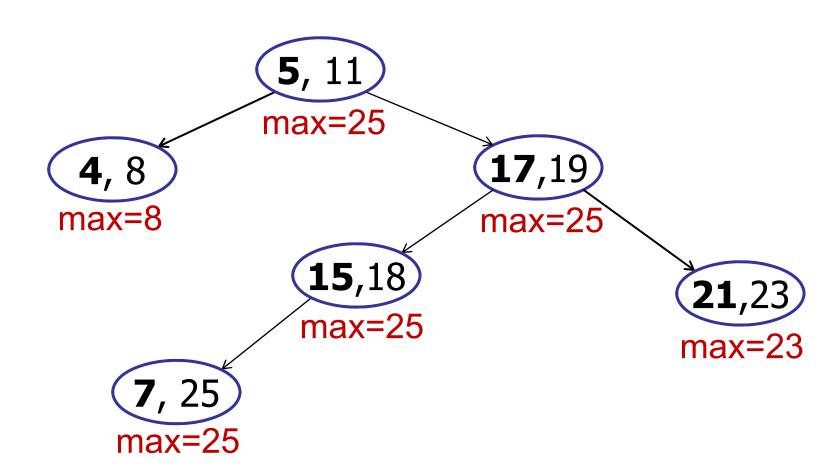
Insertion: *out-of-balance* 



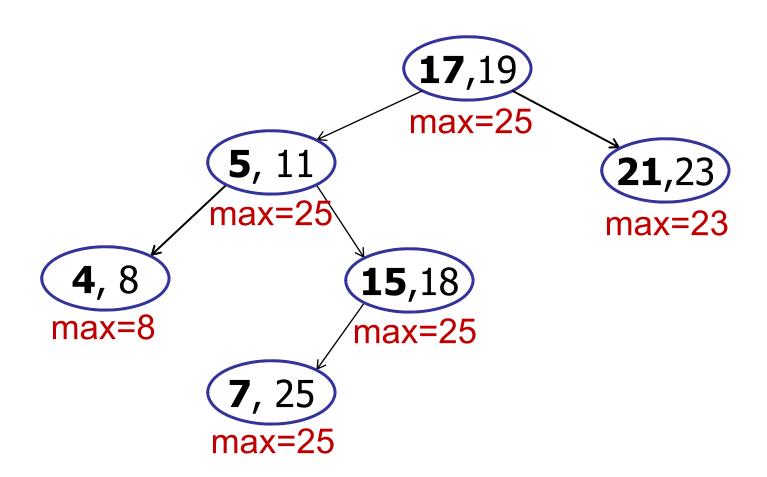
Insertion: right-rotate (17, 19)



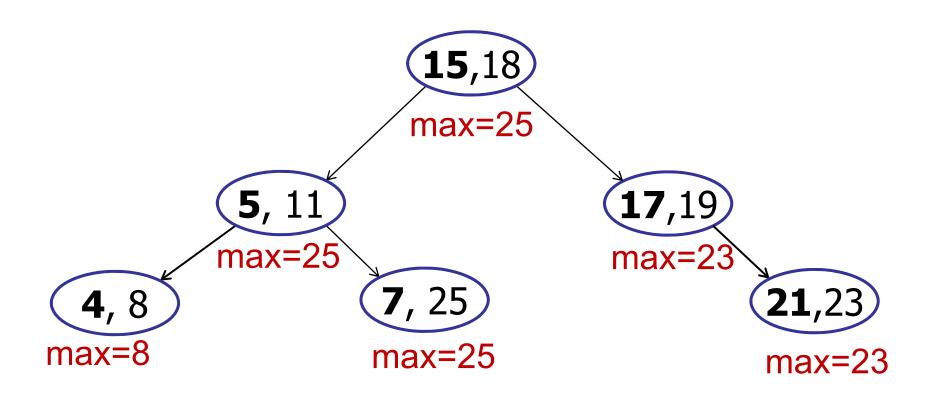
Insertion: right-rotate (17, 19), OOPS!



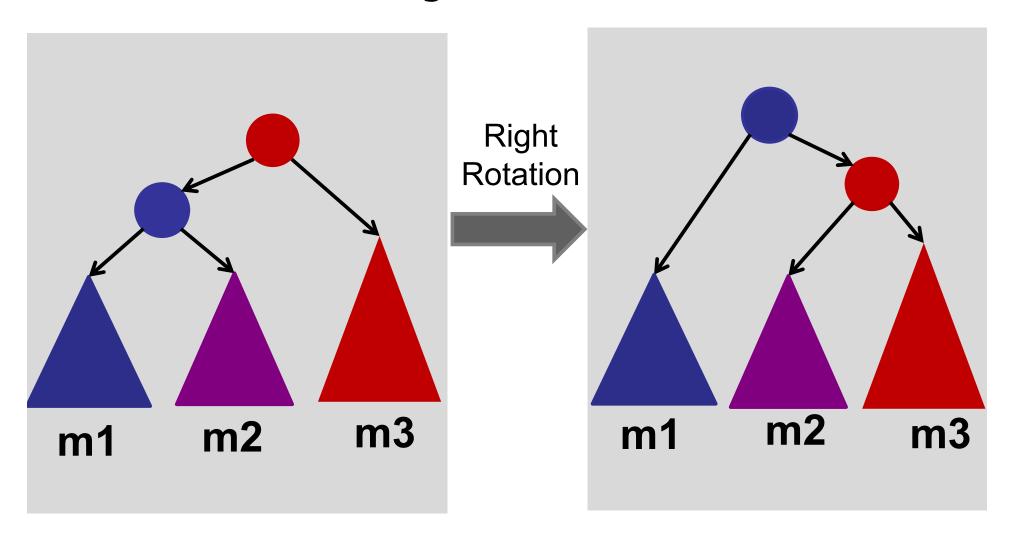
Insertion: out-of-balance



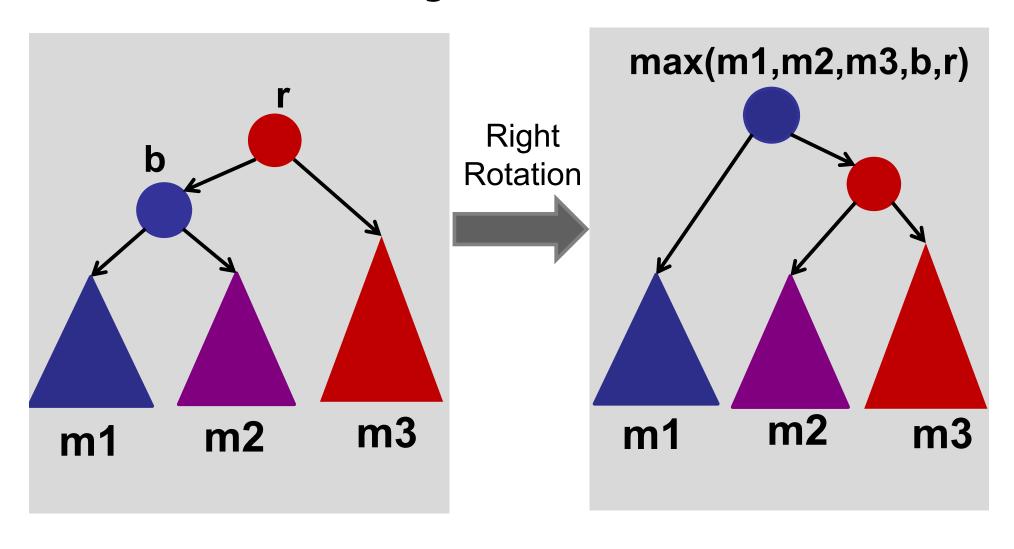
Insertion: left-rotate, right-rotate



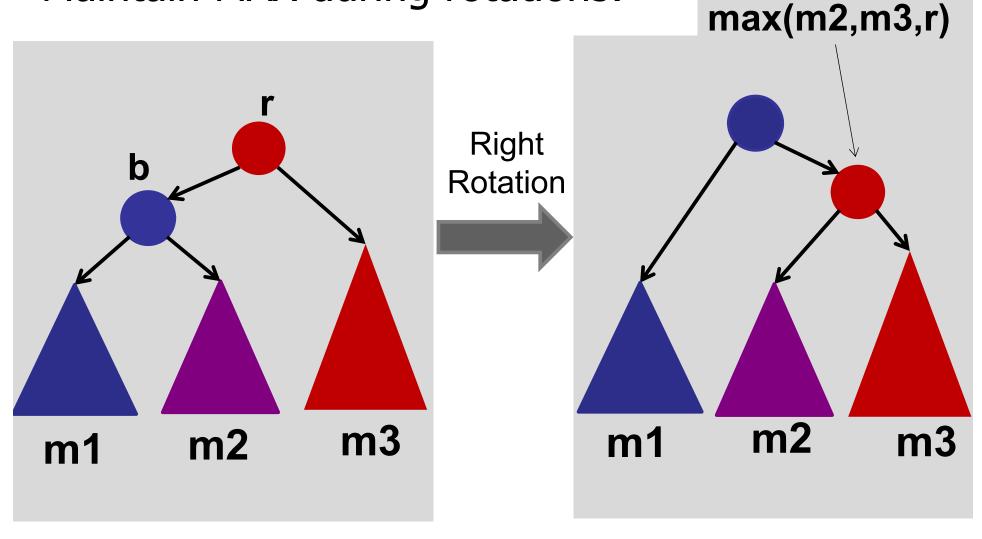
#### Maintain MAX during rotations:

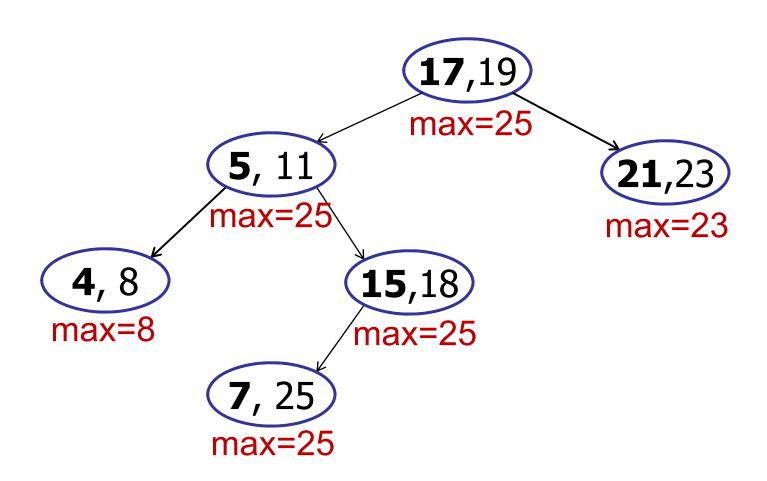


#### Maintain MAX during rotations:

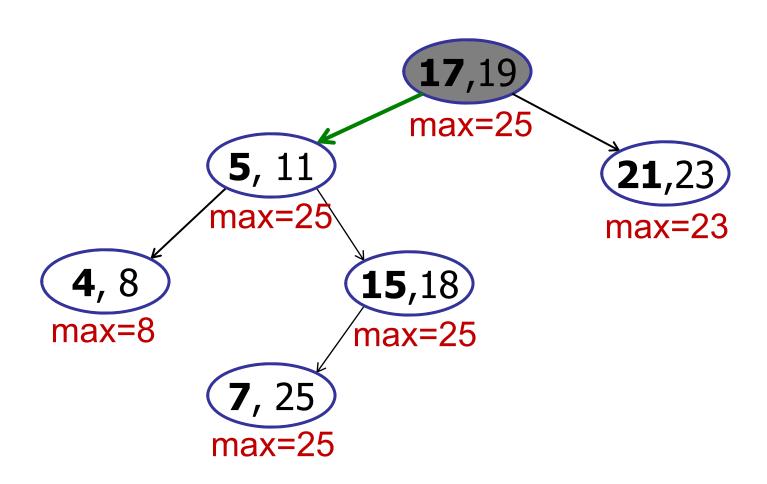


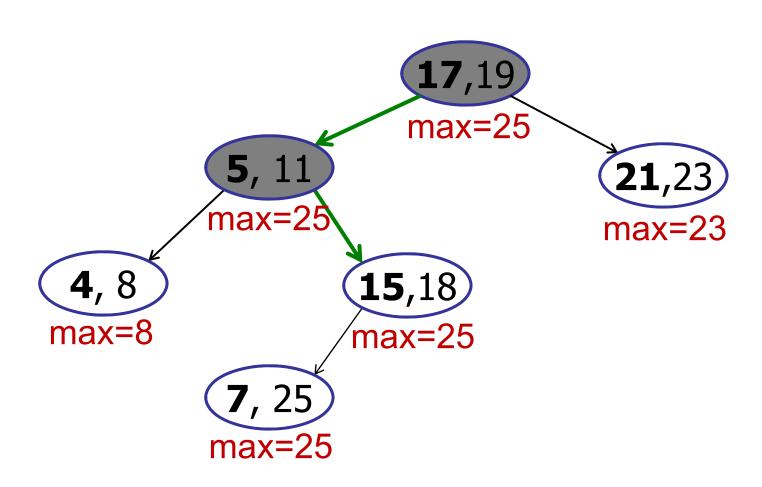
Maintain MAX during rotations:

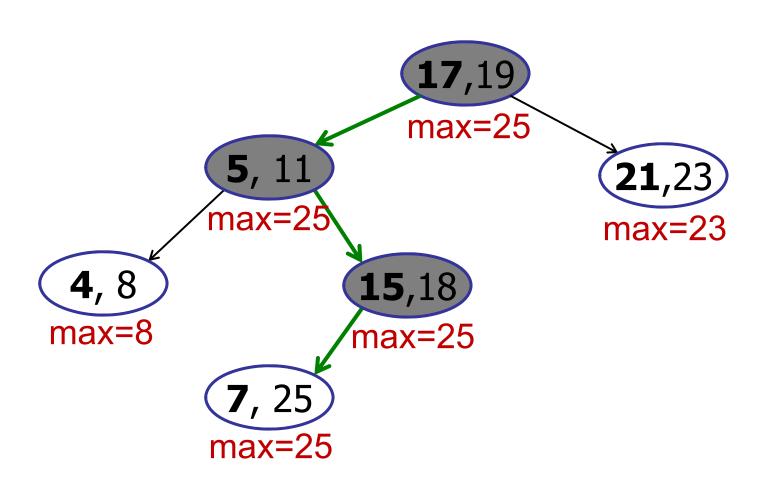


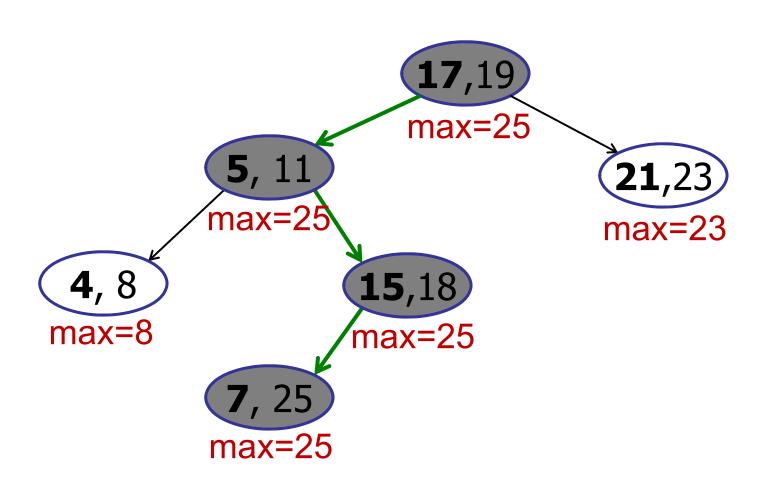


```
interval-search(x): find interval containing x
interval-search(x)
    c = root;
    while (c != null and x is not in c.interval) do
          if (c.left == null) then
                 c = c.right;
          else if (x > c.left.max) then
                c = c.right;
          else c = c.left;
    return c.interval;
```



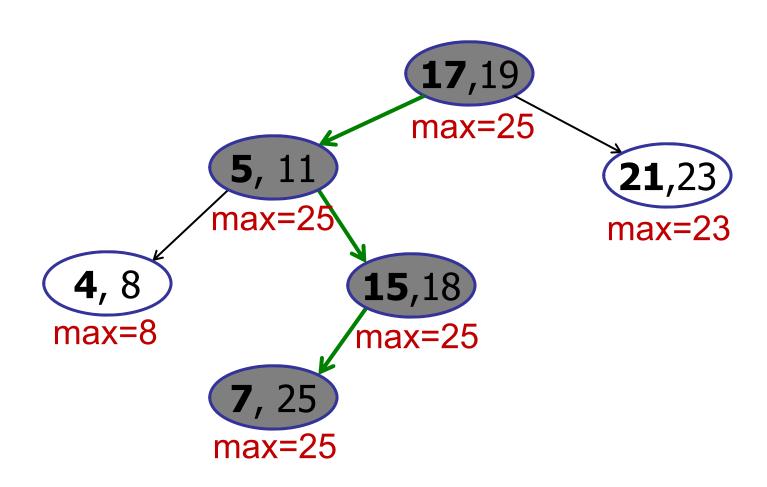




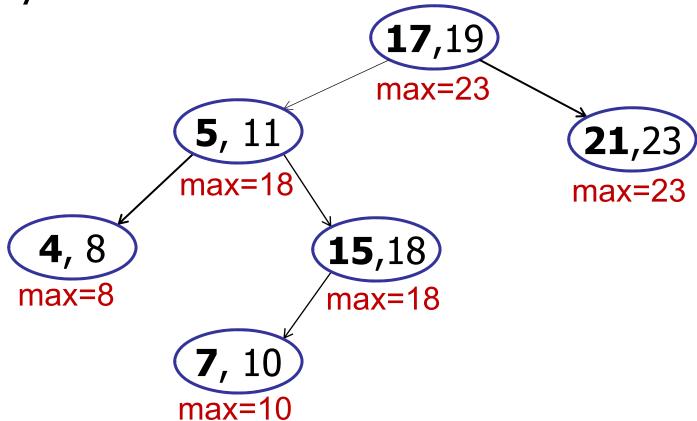


```
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                 c = c.right;
          else if (x > c.left.max) then
                c = c.right;
          else c = c.left;
    return c.interval;
```

Will any search find (21, 23)?

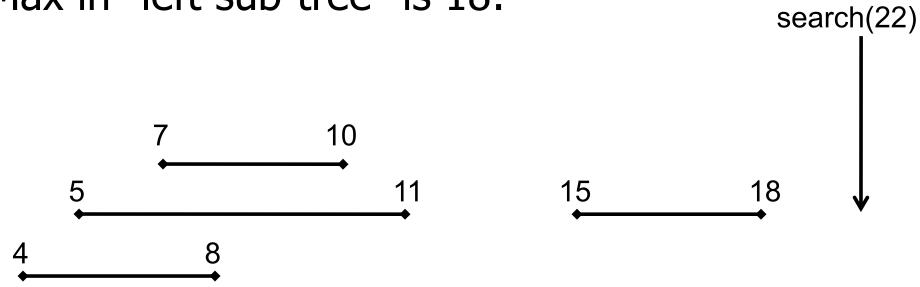


Why does it work?

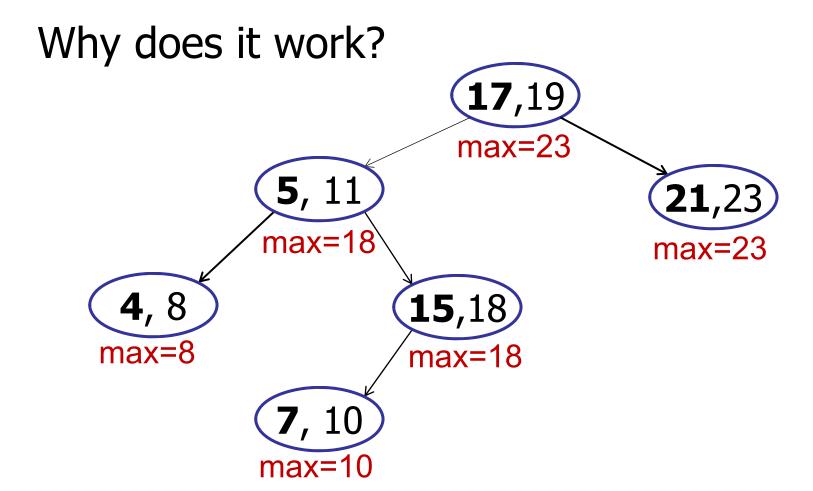


Claim: If search goes right, then no overlap in left subtree.

Max in "left sub-tree" is 18:



Safe to go right: 22 is not in the left sub-tree.

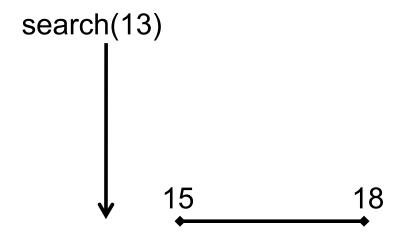


Claim: If search goes left and there is no overlap in the left subtree...

Why does it work? **17**,19 max=23**5**, 11 max=18 max=23 **15**,18 4, 8 max=8 max=18 **7**, 10 max=10

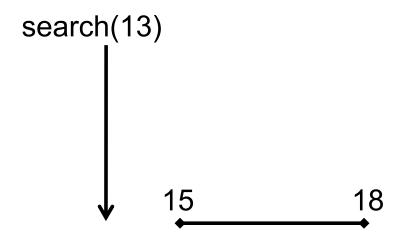
Claim: If search goes left, then safe to go left.

Max in "left sub-tree" is 18:



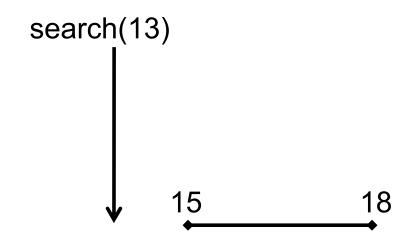
Go left: search(13) < 18

Max in "left sub-tree" is 18:



Go left: search(13) < 15 < 18

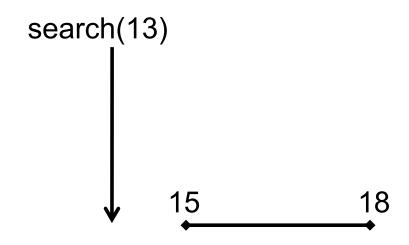
Max in "left sub-tree" is 18:



Go left: search(13) < 15 < 18

Tree sorted by left endpoint.

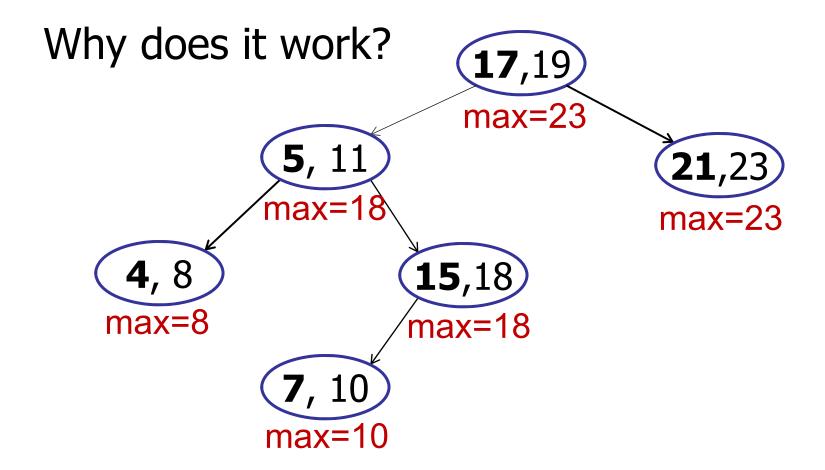
Max in "left sub-tree" is 18:



Go left: search(13) < 15 < 18

Tree sorted by left endpoint.

13 < every interval in right subtree



Claim: If search goes left and no overlap, then key < every interval in right sub-tree.

If search goes right: then no overlap in left subtree.

→ Either search finds key in right subtree or it is not in the tree.

If search goes left: if there is no overlap in left subtree, then there is no overlap in right subtree either.

→ Either search finds key in left subtree or it is not in the tree.

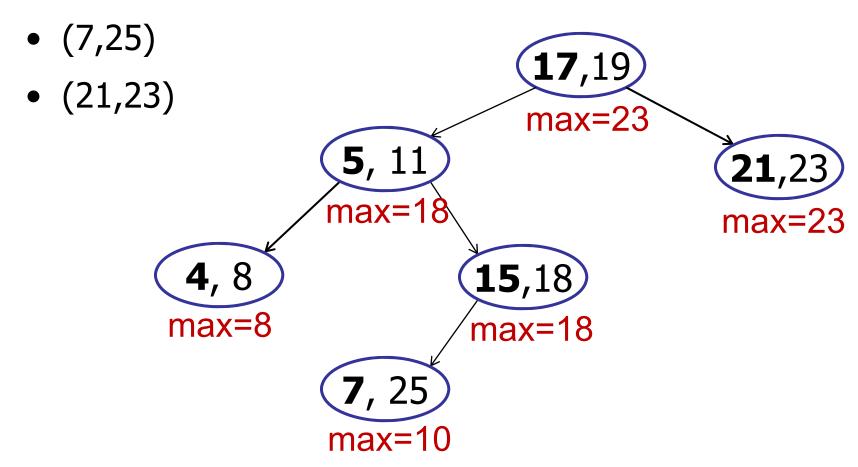
Conclusion: search finds an overlapping interval, if it exists.

#### The running time of interval-search is:

- 1. O(1)
- 2. O(log n)
- 3. O(n)
- 4. O(n log n)
- 5.  $O(n^2)$
- 6. Can't say.

Extension: List all intervals that overlap with point?

E.g.: search(22) returns:



Extension: List all intervals that overlap with point?

All-Overlaps Algorithm:

**Repeat** until no more intervals:

- -Search for interval.
- -Add to list.
- Delete interval.

**Repeat** for all intervals on list:

Add interval back to tree.

# The running time of All-Overlaps, if there are k overlapping intervals?

- 1. O(1)
- 2. O(k)
- 3. O(k log n)
- 4. O(k + log n)
- 5. O(kn)
- 6. O(kn log n)

Extension: List all intervals that overlap with point?

All-Overlaps Algorithm: O(k log n)

**Repeat** until no more intervals:

- -Search for interval.
- -Add to list.
- Delete interval.

**Repeat** for all intervals on list:

Add interval back to tree.

Best known solution: O(k + log n)

### Today

Three examples of augmenting BSTs

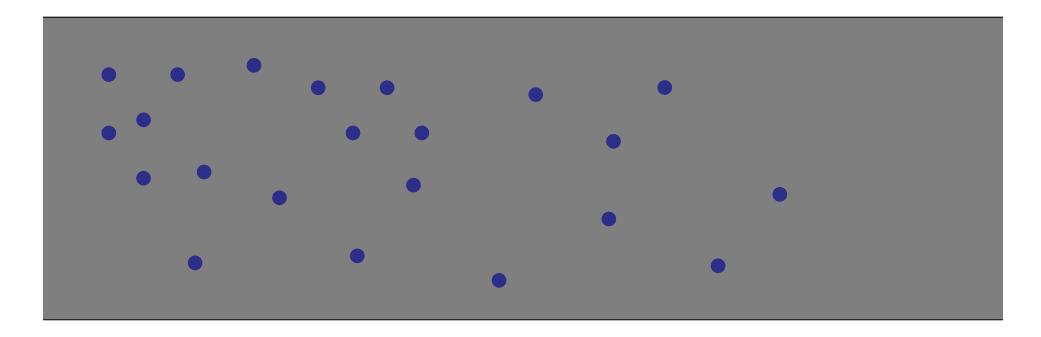
1. Order Statistics

2. Intervals

3. Orthogonal Range Searching

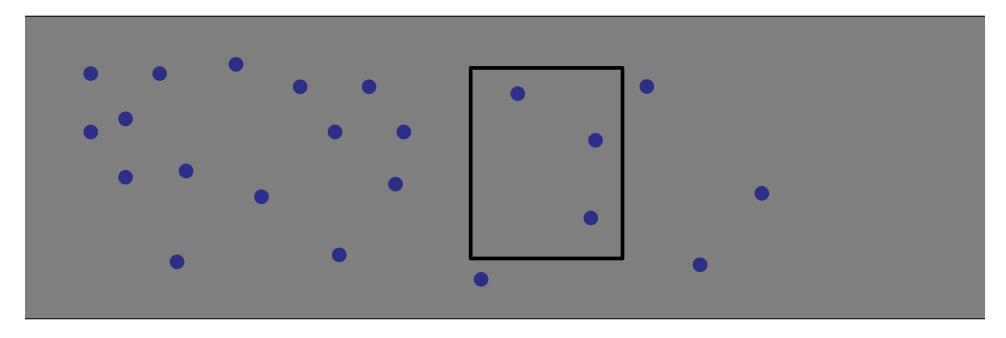
## Orthogonal Range Searching

Input: *n* points in a 2d plane



## Orthogonal Range Searching

Input: *n* points in a 2d plane

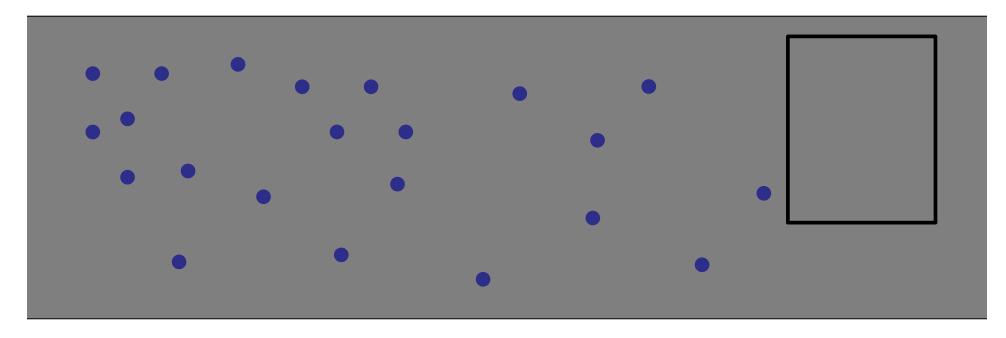


Query: Box

- Contains at least one point?
- How many?

## Orthogonal Range Searching

Input: *n* points in a 2d plane

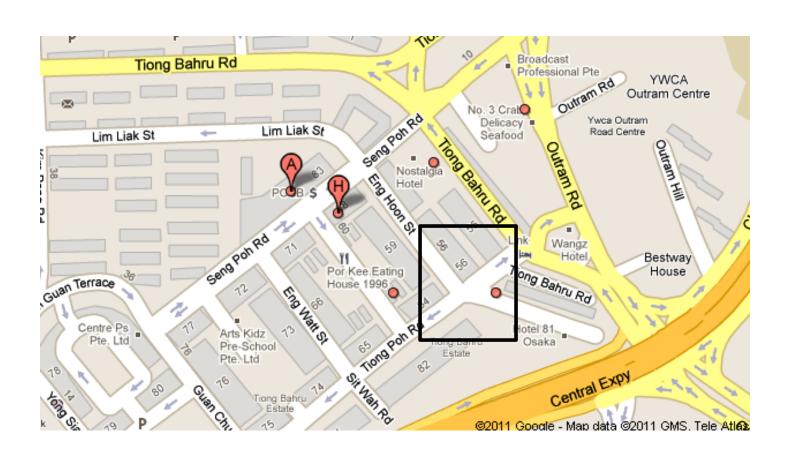


Query: Box

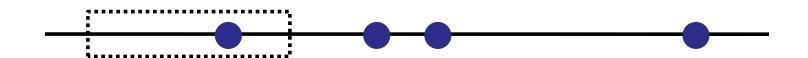
- Contains at least one point?
- How many?

## Practical Example

Are there any good restaurants within one block of me?



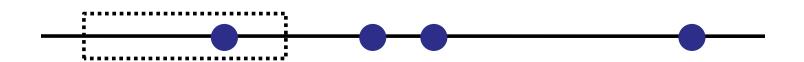
#### One Dimension



#### One Dimension

#### Range Queries

- Important in databases
- "Find me everyone between ages 22 and 27."

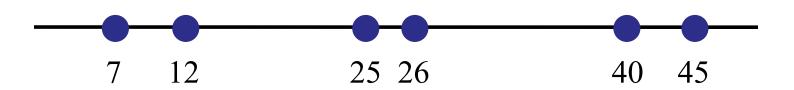


#### One Dimension

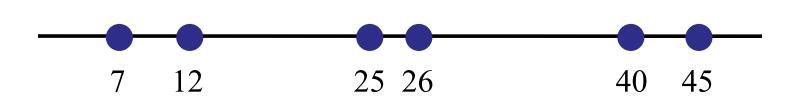
#### Strategy:

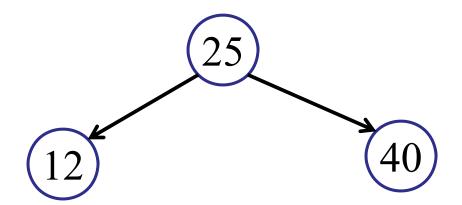
1. Use a binary search tree.

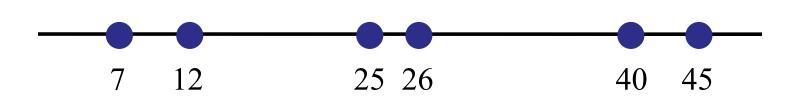
- 2. Store all points in the <u>leaves</u> of the tree. (Internal nodes store only copies.)
- 3. Each internal node  $\nu$  stores the MAX of any leaf in the <u>left</u> sub-tree.

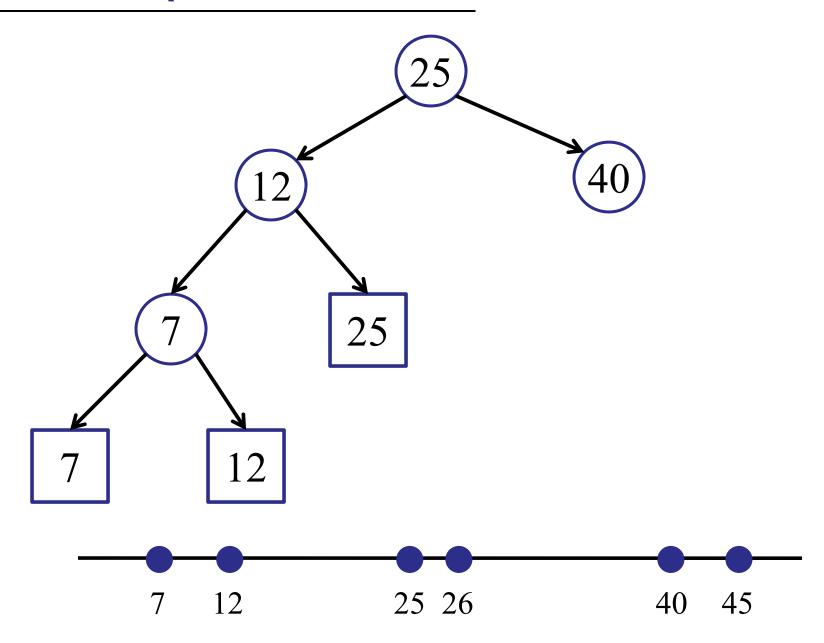


**(25)** 

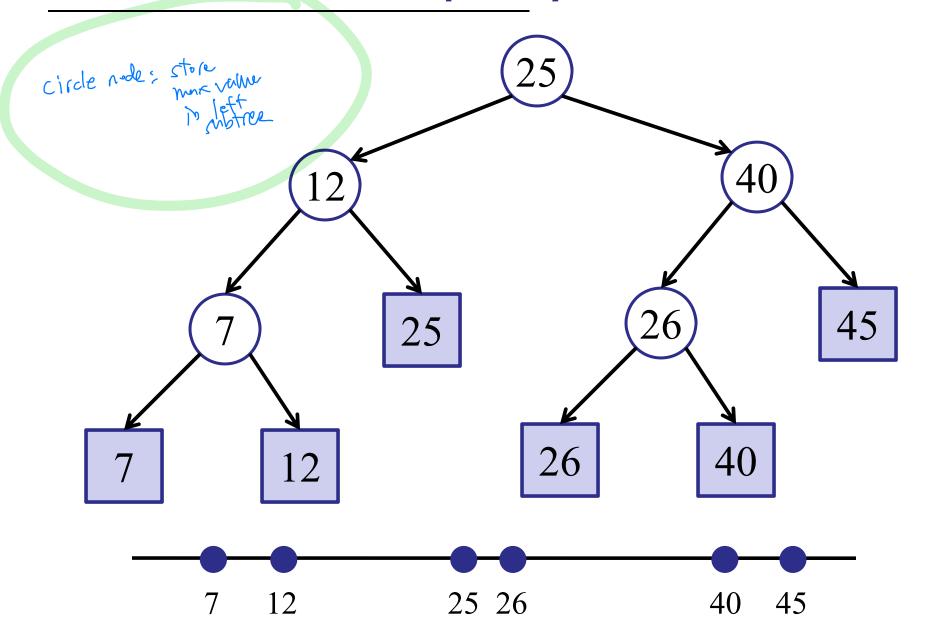




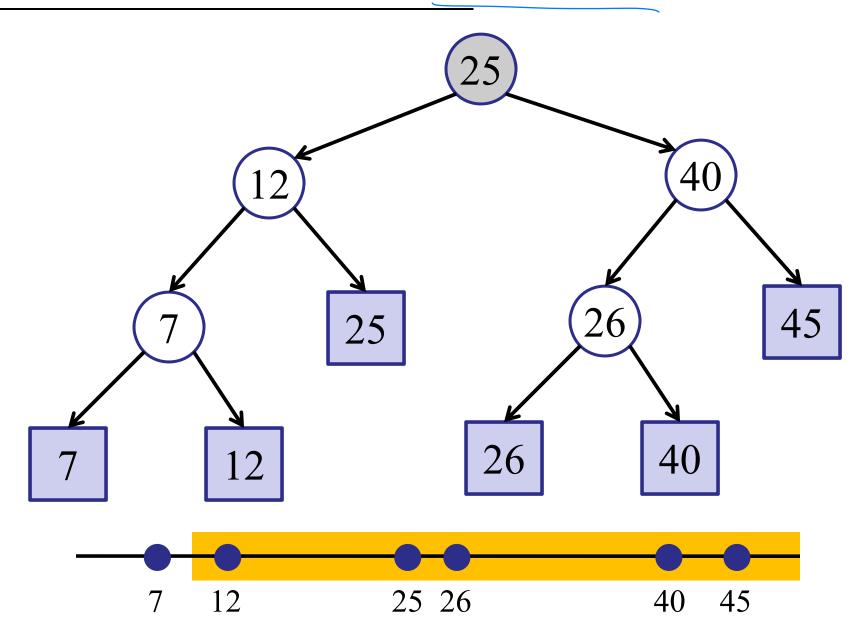




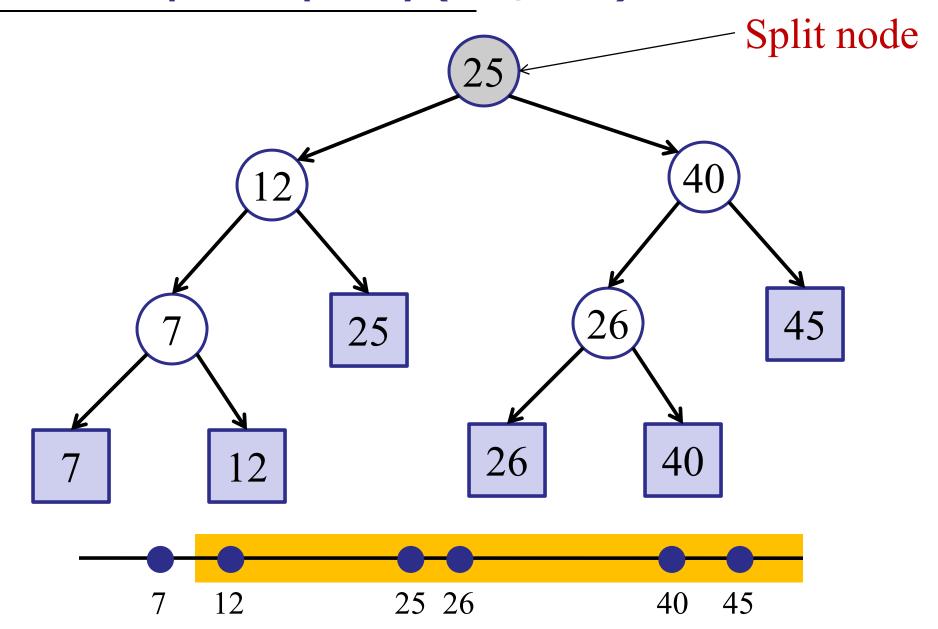
### Note: BST Property



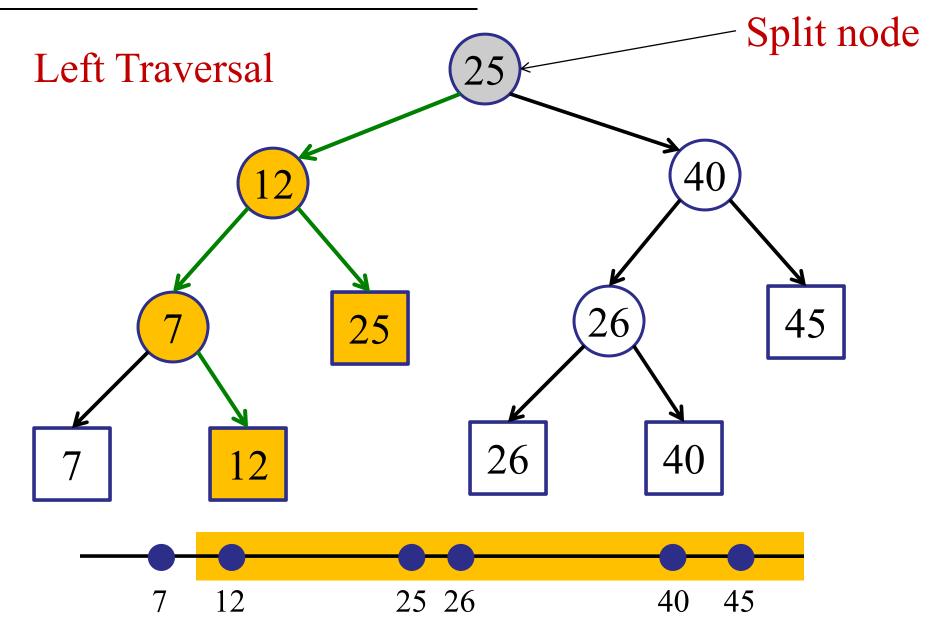
## Example: query(10, 50)

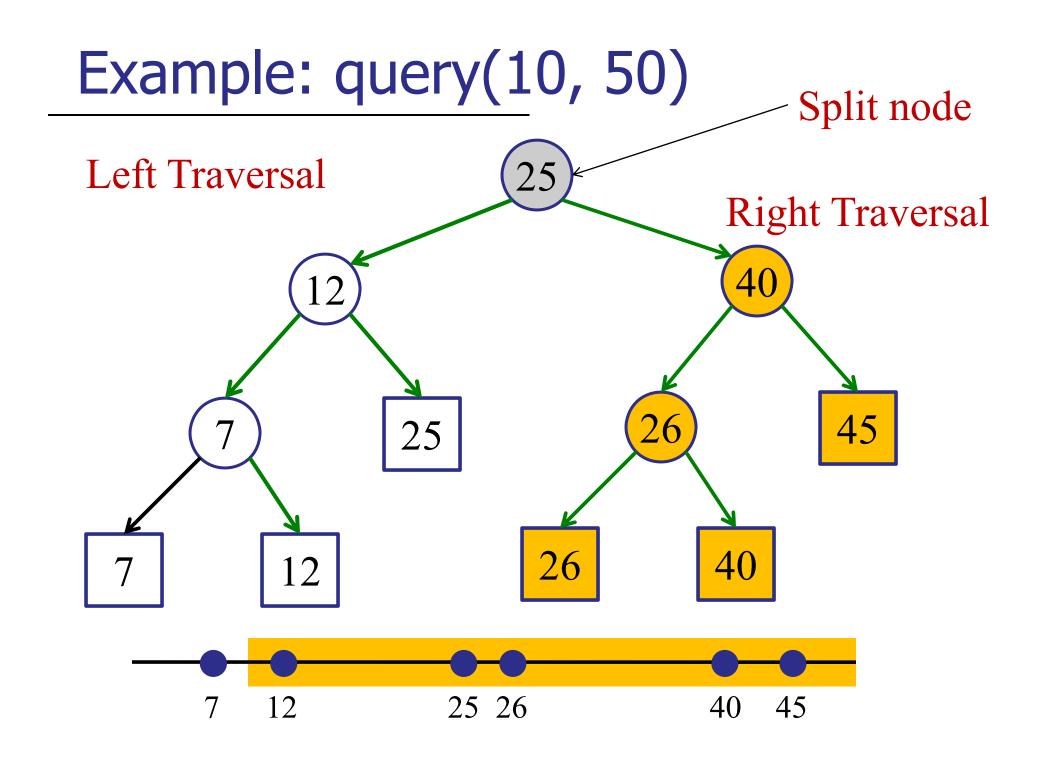


## Example: query(10, 50)

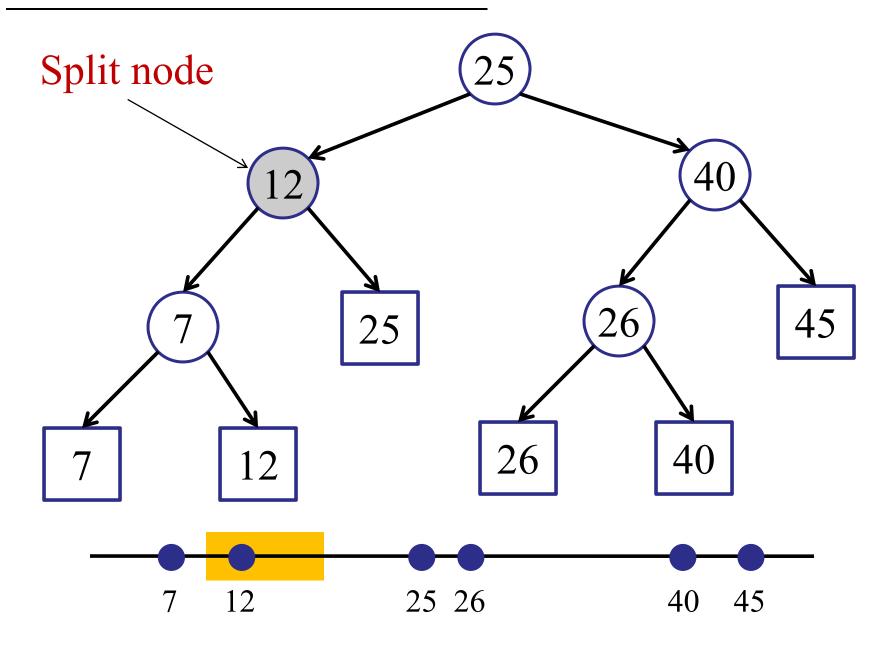


## Example: query(10, 50)

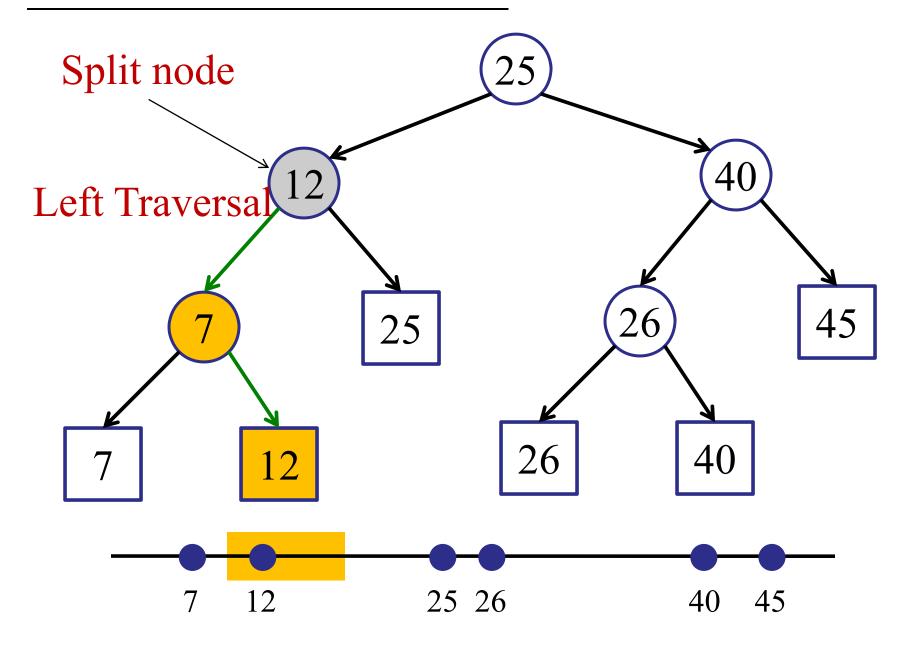




## Example: query(8, 20)



## Example: query(8, 20)

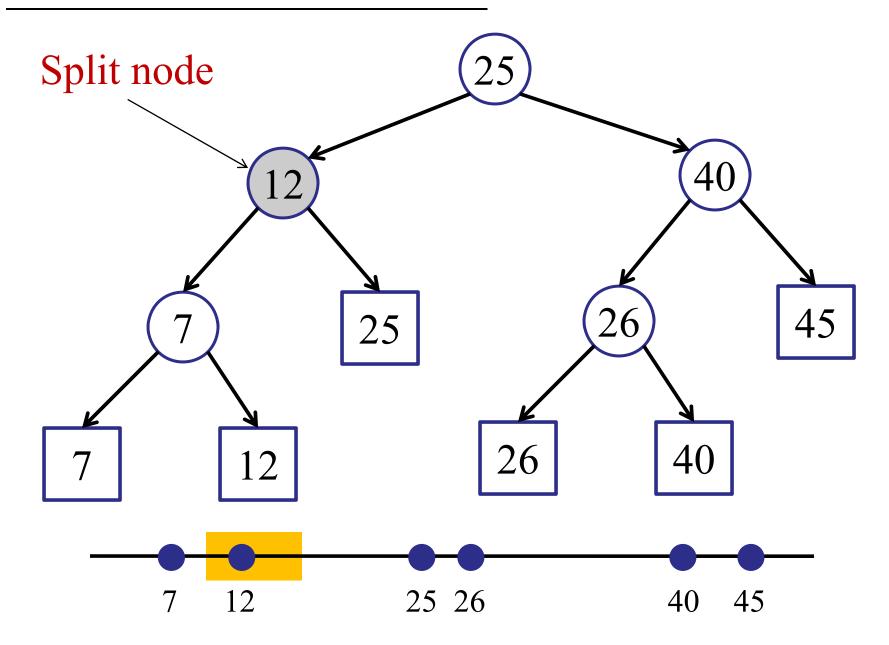


#### Algorithm:

- Find "split" node.
- Do left traversal.
- Do right traversal.

```
FindSplit(low, high)
     v = root;
     done = false;
     while !done {
            if (high <= v.key) then v=v.left;
            else if (low > v.key) then v=v.right;
            else (done = true);
     return v;
```

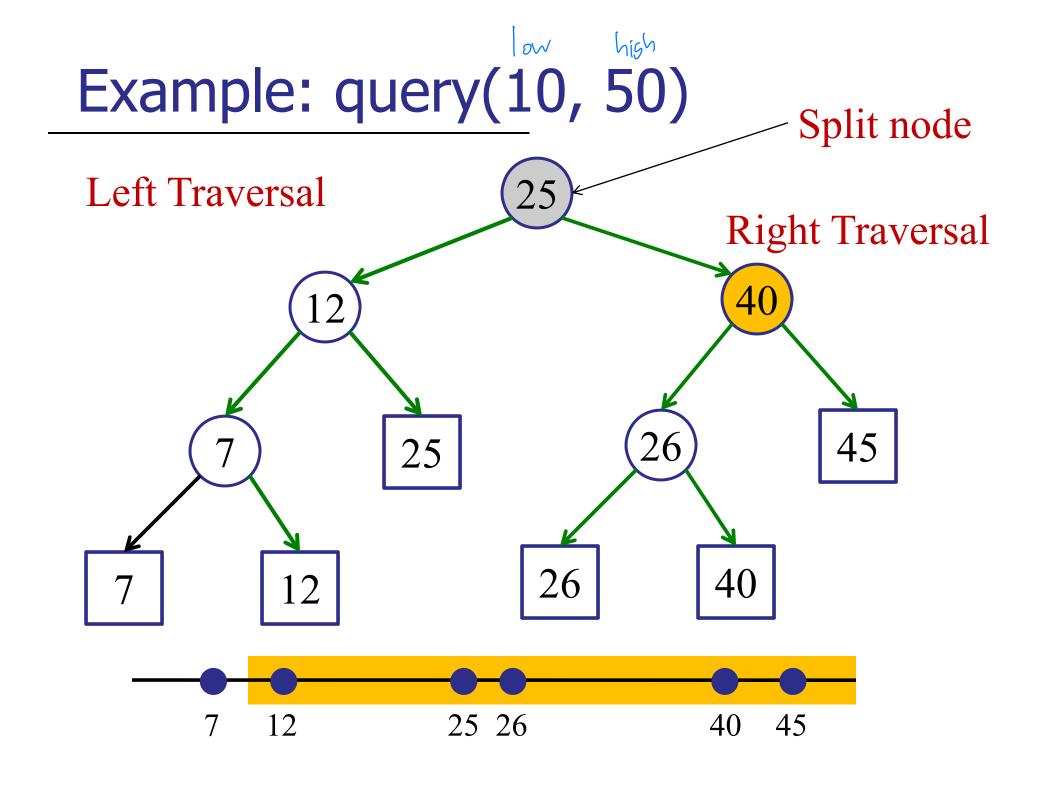
## Example: query(8, 20)

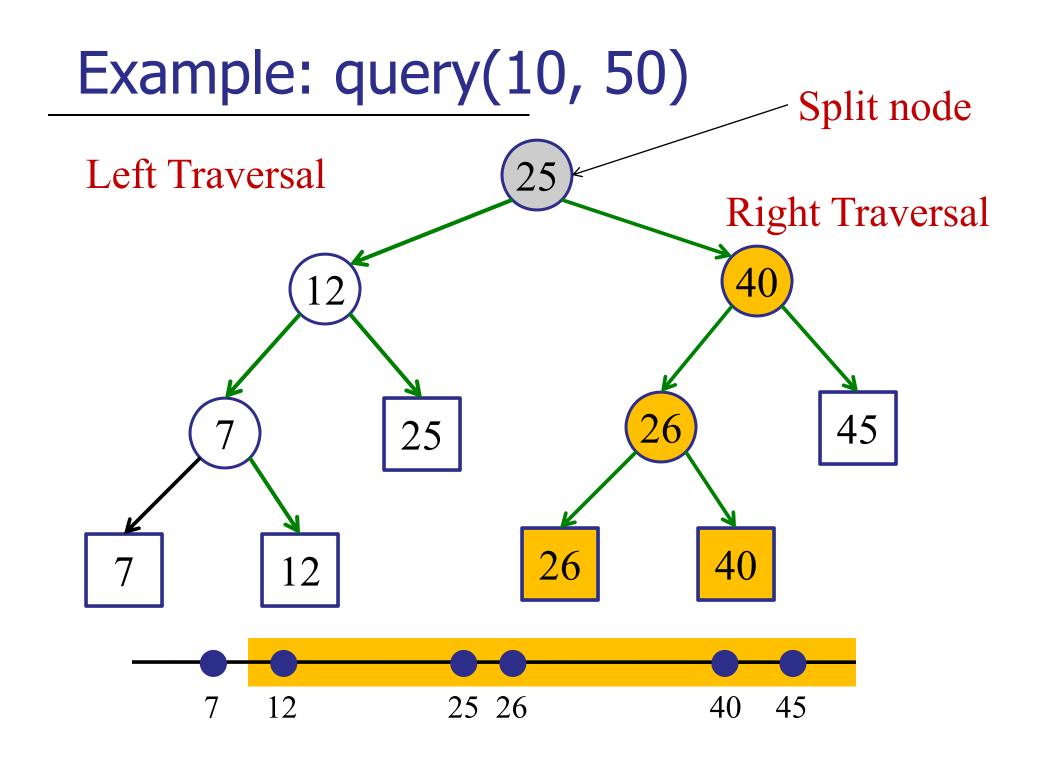


#### Algorithm:

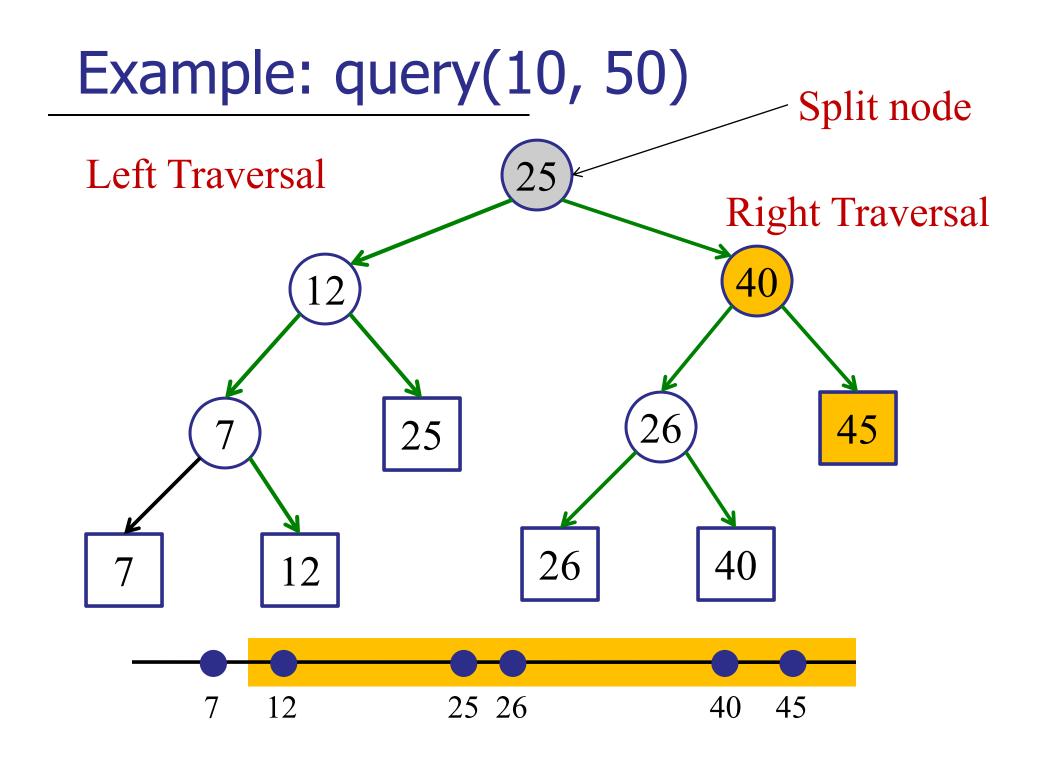
- v = FindSplit(low, high);
- LeftTraversal(v, low, high);
- RightTraversal(v, low, high);

```
RightTraversal(v, low, high)
     if (v.key <= high) {</pre>
            all-leaf-traversal(v.left);
            RightTraversal(v.right, low, high);
     else {
            RightTraversal(v.left, low, high);
```

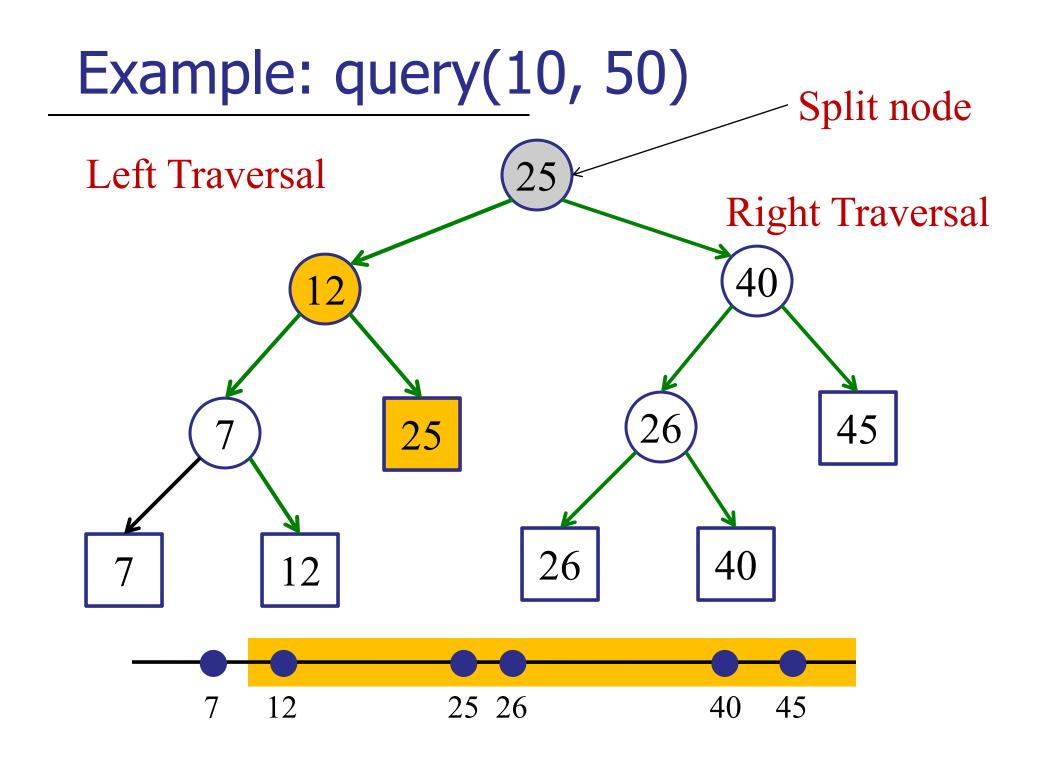


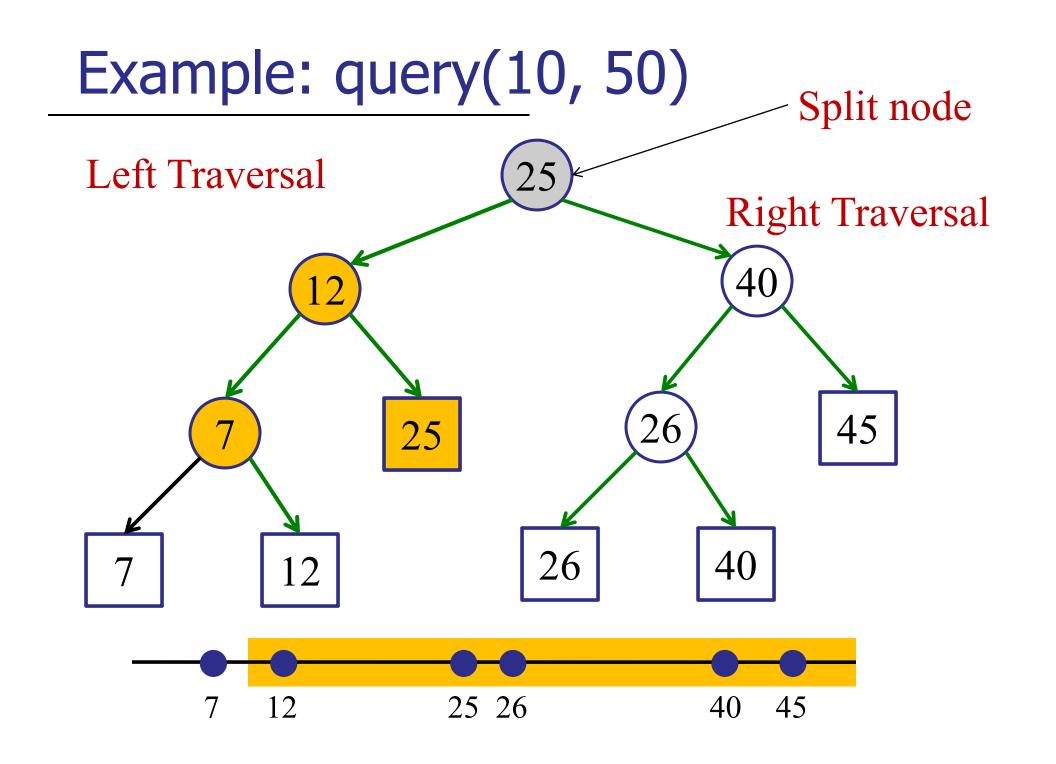


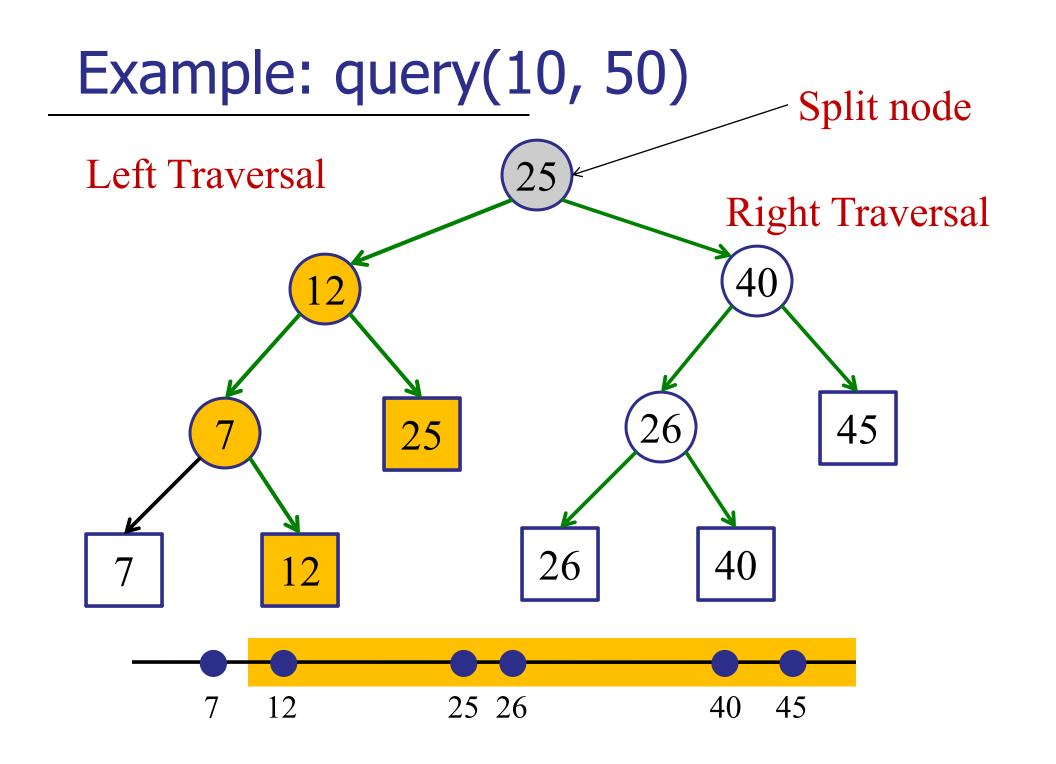
```
RightTraversal(v, low, high)
     if (v.key <= high) {
           all-leaf-traversal(v.left);
           RightTraversal(v.right, low, high);
     else {
           RightTraversal(v.left, low, high);
```



```
LeftTraversal(v, low, high)
     if (low <= v.key) {
           all-leaf-traversal(v.right);
           LeftTraversal(v.left, low, high);
     else {
           LeftTraversal(v.right, low, high);
```







```
LeftTraversal(v, low, high)
     if (low <= v.key) {
           all-leaf-traversal(v.right);
           LeftTraversal(v.left, low, high);
     else {
           LeftTraversal(v.right, low, high);
```

#### Algorithm:

- v = FindSplit(low, high);
- LeftTraversal(v, low, high);
- RightTraversal(v, low, high);

### **Analysis**

#### Query time:

- Finding split node: O(log n)
- Left Traversal:

At every step, we either:

- 1. Output all right sub-tree and recurse left.
- 2. Recurse right.
- Right Traversal:

At every step, we either:

- 1. Output all left sub-tree and recurse right.
- 2. Recurse left.

### **Analysis**

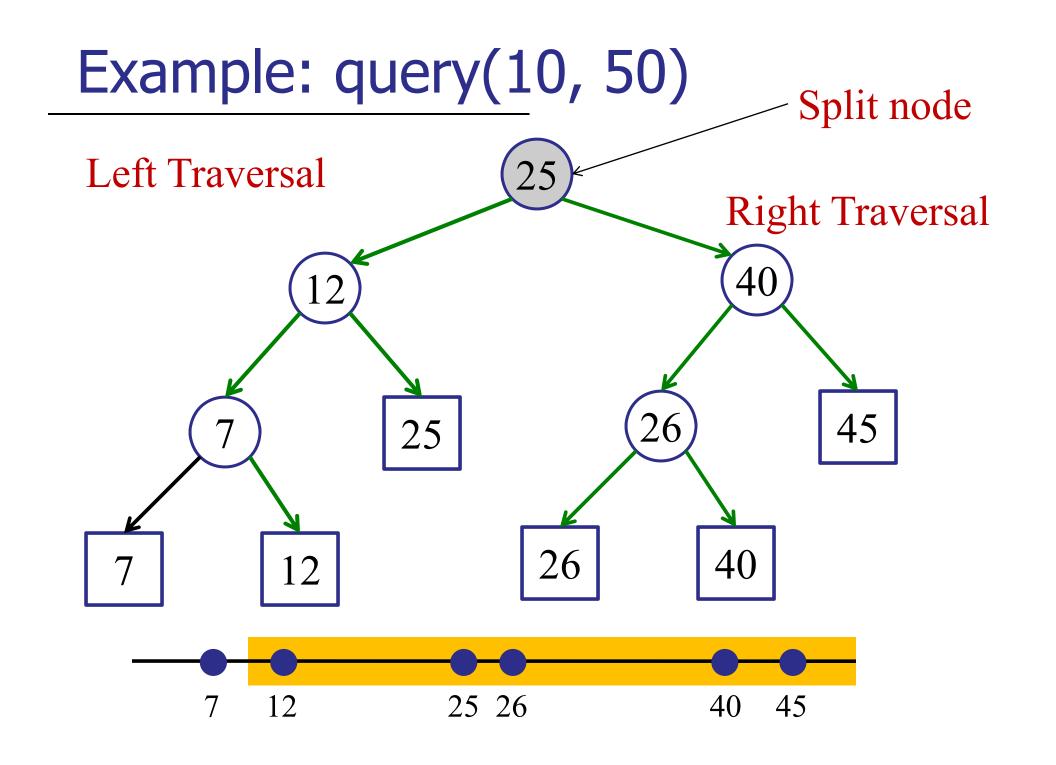
#### Left Traversal:

At every step, we either:

- 1. Output all right sub-tree and recurse left.
- 2. Recurse right.

#### Counting:

- 1. Recurse at most O(log n) times (i.e., option 2).
- 2. How expensive is "output all sub-tree" (i.e., option 1)?



#### Left Traversal:

At every step, we either:

- 1. Output all right sub-tree and recurse left.
- 2. Recurse right.

#### Counting:

- 1. Recurse at most O(log n) times (i.e., option 2).
- 2. How expensive is "output all sub-tree" (i.e., option 1)?
  - $\rightarrow$  O(k), where k is number of items found.

Query time complexity:

O(k + log n)

where k is the number of points found.

Preprocessing (buildtree) time complexity:

O(n log n)

Total space complexity:

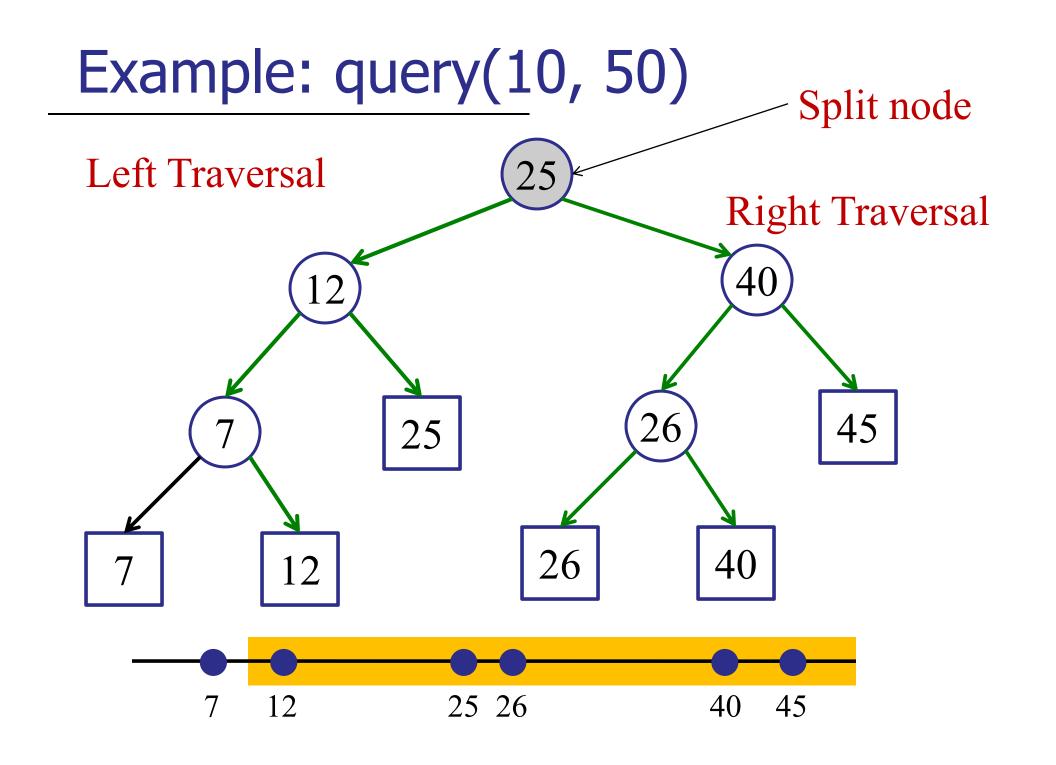
O(n)

What if you just want to know *how many* points are in the range?

What if you just want to know *how many* points are in the range?

- Augment the tree!
- Keep a count of the number of nodes in each sub-tree.
- Instead of walking entire sub-tree, just remember the count.

```
LeftTraversal(v, low, high)
     if (low <= v.key) {
           all-leaf-traversal(v.right);
           total += v.right.count;
           LeftTraversal(v.left, low, high);
     else {
           LeftTraversal(v.right, low, high);
```

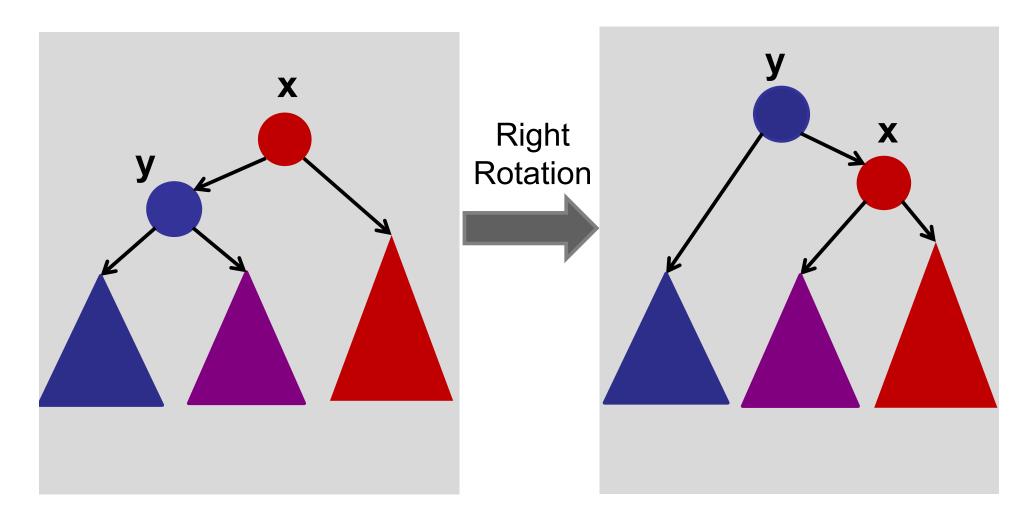


## 1D Range Tree

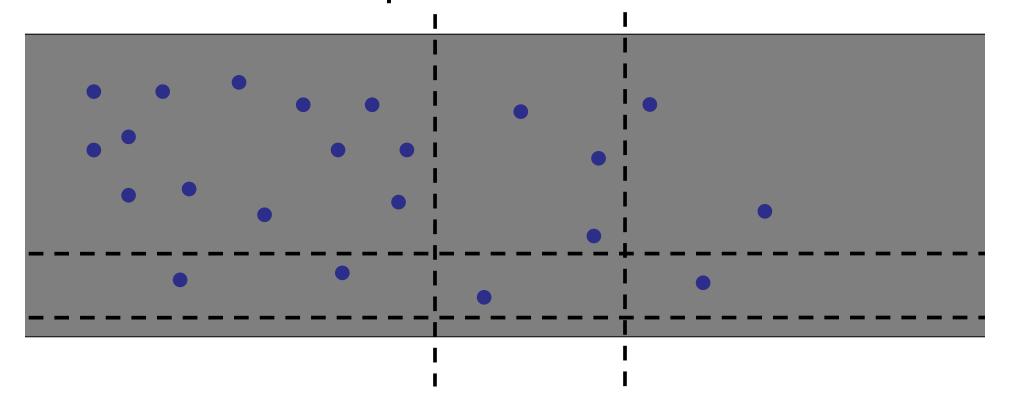
Done??

What about dynamic updates?

– Need to verify rotations!

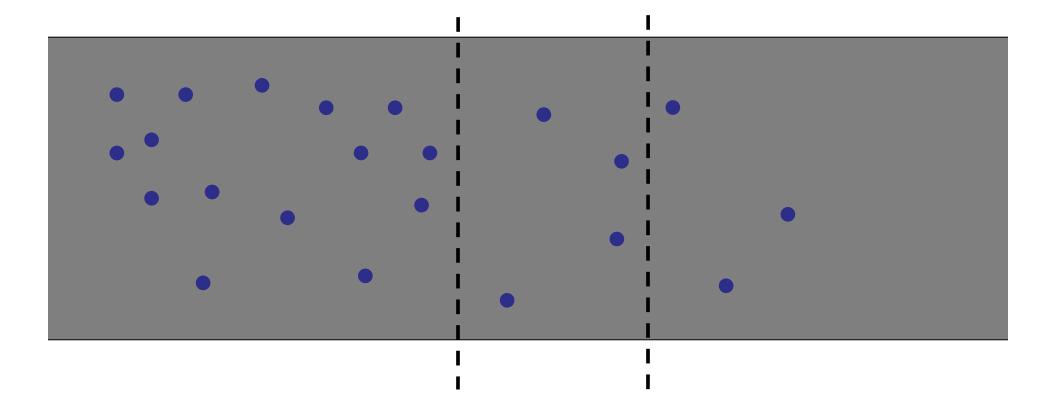


Ex: search for all points between dashed lines.

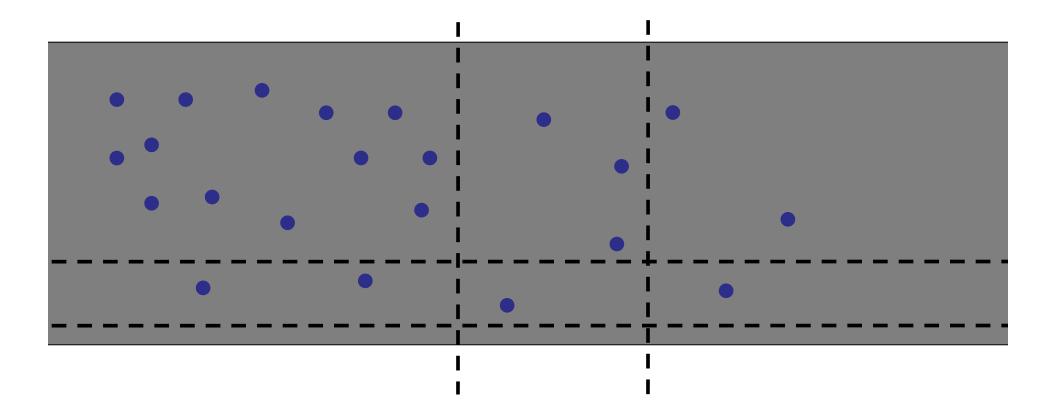


#### Step 1:

Create a 1d-range-tree on the x-coords.



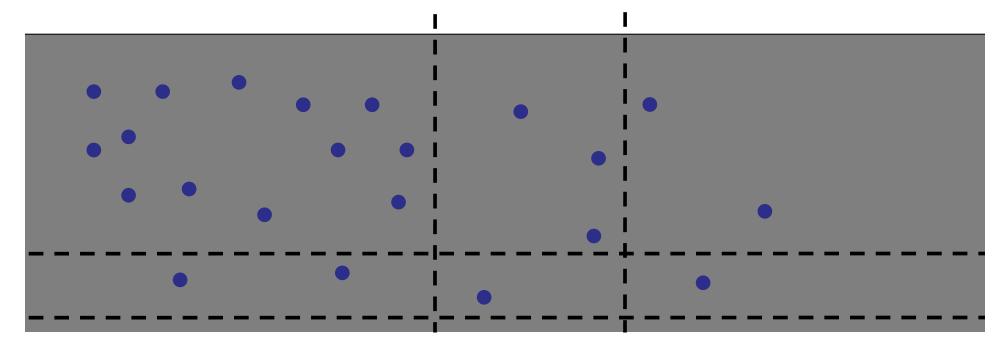
**Problem**: can't enumerate entire sub-trees, since there may be too many nodes that don't satisfy the y-restriction.



```
LeftTraversal(v, low, high)
  if (v.key >= low) {
        all-leaf-traversal(v.right);
        LeftTraversal(v.left, low, high);
  else {
        LeftTraversal(v.right, low, high);
```

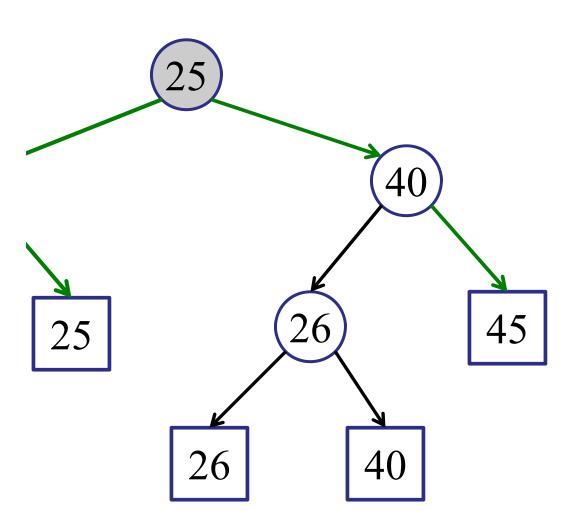
#### **Solution**: Augment!

- Each node in the x-tree has a set of points in its sub-tree.
- Store a y-tree at each x-node containing all the points in the sub-tree.

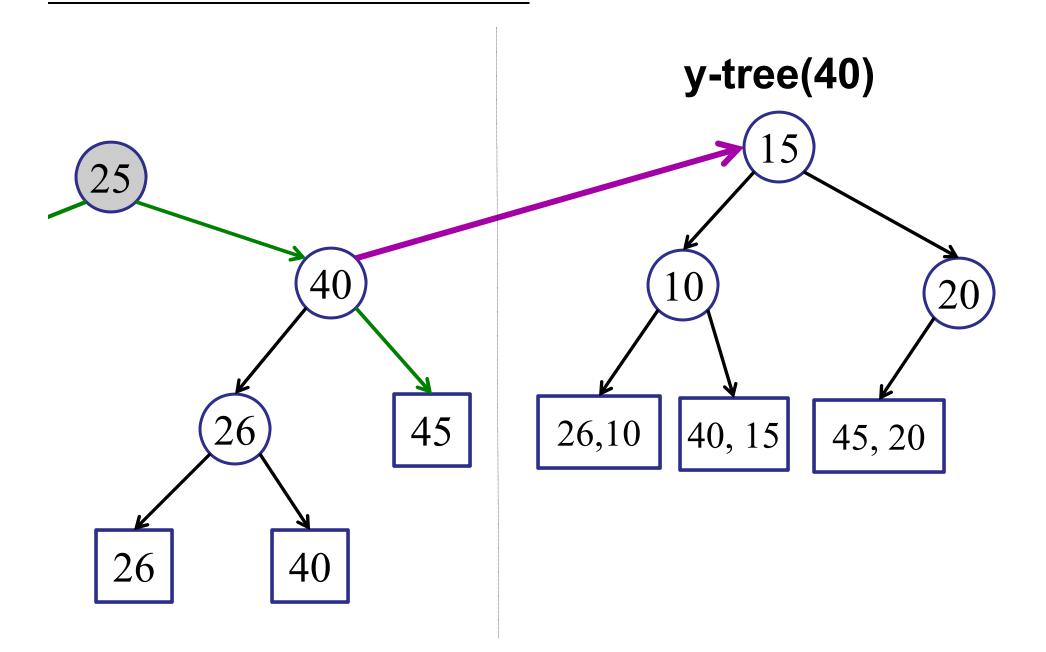


```
LeftTraversal(v, low, high)
  if (v.key.x >= low.x) {
        ytree.search(low.y, high.y);
        LeftTraversal(v.left, low, high);
  else {
        LeftTraversal(v.right, low, high);
```

# Example:

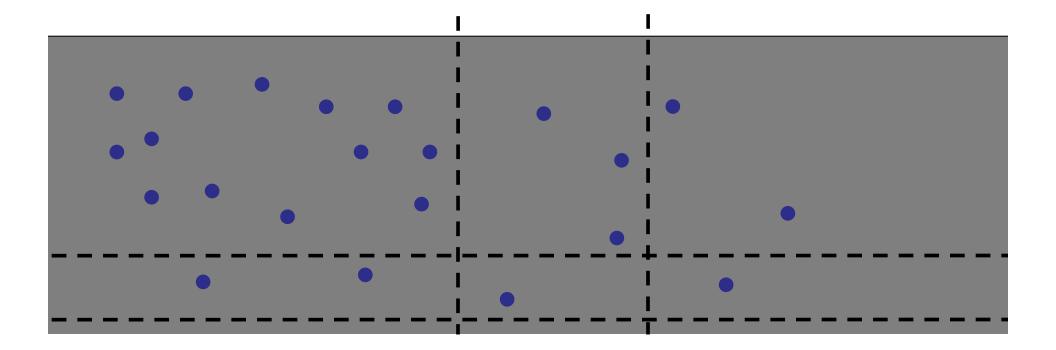


# Example:



#### Idea:

- Build an x-tree using only x-coordinates.
- For every node in the x-tree, build a y-tree out of nodes in subtree using only y-coordinates.



Query time:  $O(log^2n + k)$ 

- O(log n) to find split node.
- O(log n) recursing steps
- O(log n) y-tree-searches of cost O(log n)
- O(k) enumerating output

#### Space complexity: O(n log n)

- Each point appears in at most one y-tree per level.
- There are O(log n) levels.
- → Each node appears in at most O(log n) y-trees.

The rest of the x-tree takes O(n) space.

Building the tree: O(n log n)

- Tricky...
- − Left as a puzzle... ☺

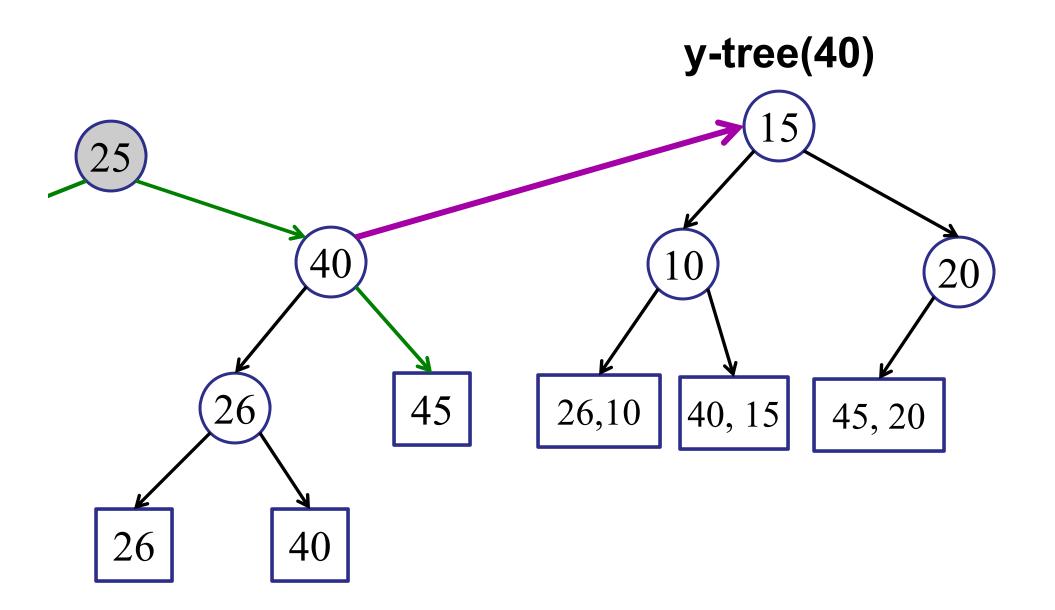
Challenge of the Day...

#### **Dynamic Trees**

#### What about inserting/deleting nodes?

- Hard!
- How do you do rotations?
- Every rotation you may have to entirely rebuild the y-trees for the rotated nodes.
- Cost of rotate: O(n) !!!!

# Example:



#### d-dimensional

# What if you want high-dimensional range queries?

- Query cost: O(logdn + k)
- buildTree cost: O(n log<sup>d-1</sup>n)
- Space: O(n log<sup>d-1</sup>n)

#### Idea:

- Store d–1 dimensional range-tree in each node of a 1D range-tree.
- Construct the d–1-dimensionsal range-tree recursively.

#### **Curse of Dimensionality**

# What if you want high-dimensional range queries?

- Query cost: O(logdn + k)
- buildTree cost: O(n log<sup>d-1</sup>n)
- Space: O(n log<sup>d-1</sup>n)

#### Idea:

- Store d–1 dimensional range-tree in each node of a 1D range-tree.
- Construct the d–1-dimensionsal range-tree recursively.

### Real World (aside)

#### kd-Trees

- Alternate levels in the tree:
  - vertical
  - horizontal
  - vertical
  - horizontal
- Each level divides the points in the plane in half.

### Real World (aside)

#### kd-Trees

- Alternate levels in the tree
- Each level divides the points in the plane in half.
- Query cost:  $O(\sqrt{n})$  worst-case
  - Sometimes works better in practice for many queries.
  - Easier to update dynamically.
  - Good for other types of queries: e.g., nearestneighbor

### Today

Three examples of augmenting BSTs

1. Order Statistics

2. Intervals

3. Orthogonal Range Searching