

## Lab 01 - Setup Development Environment and Toolchain

### Objectives

The aim of this tutorial is to guide you to setup development environment and necessary toolchains for cross-development of ARM-based embedded applications, which is a bare metal OS with peripheral interfacing in our course.

Note: although the guide below will be described in Windows, most of the tools are also available in Linux and Mac OS.

### 1. Visual Studio Code

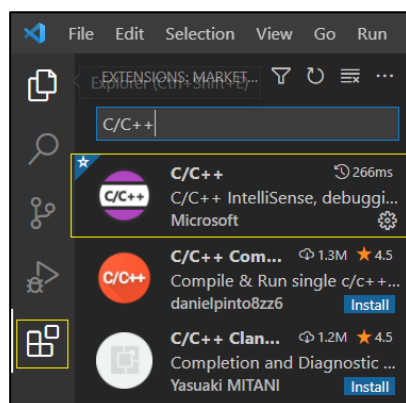
The first tool that we need is a source-code editor. You can use any tool you like, such as Eclipse CDT or Sublime Text. In our course, it is recommended to use **Visual Studio Code** - a powerful and lightweight editor.

#### a. Install VS Code

- Download the [VS Code installer](#) for Windows
- Double-click on the downloaded file to run the installer

#### b. Install the C/C++ extension for VS Code

- Open VS Code
- Click at the Extensions icon in the Activity Bar on the left side of VS Code
- Type "C/C++" in the Search box to search for the C/C++ extension
- Click the **Install** button of the extension



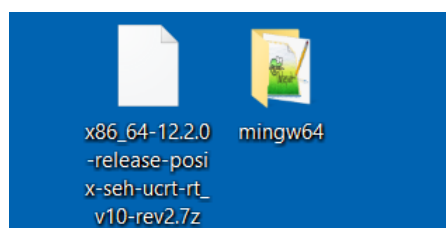
## 2. Install standard GCC toolchain

Sometimes you may like to check your code with standard console input and output. In that case, you need the standard GCC to compile the program targeting your computer (like in traditional programming activities).

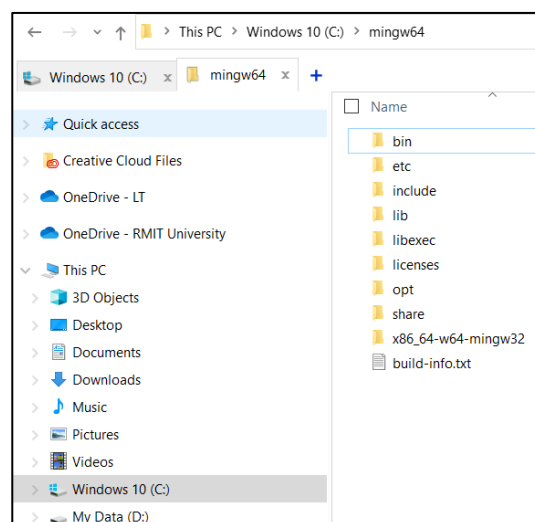
- a) Go to this link: [MinGW-W64-builds](https://sourceforge.net/projects/mingw-w64/files/Release%20binaries/mingw-w64-releases/). Download **x86\_64 release-posix-seh-ucrt-rt** with latest version.

▼ Assets 10		
<a href="#">i686-12.2.0-release-posix-dwarf-msvcrt-rt_v10-rev2.7z</a>	74.5 MB	Dec 11, 2022
<a href="#">i686-12.2.0-release-posix-dwarf-ucrt-rt_v10-rev2.7z</a>	74.4 MB	Dec 11, 2022
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<a href="#">i686-12.2.0-release-win32-dwarf-ucrt-rt_v10-rev2.7z</a>	74.4 MB	Dec 11, 2022
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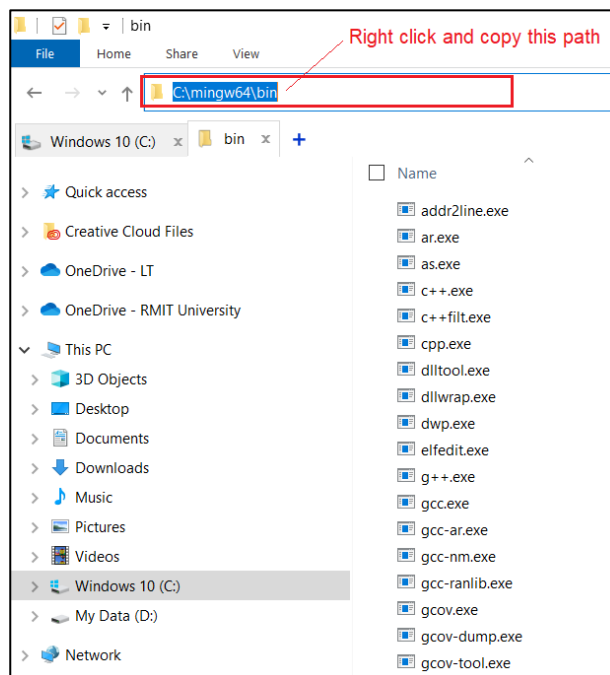
- b) After you download the file, right click on it and select “**Extract Here**” with WinRAR or 7-Zip tool to extract it. You will get the extracted folder **mingw64** as below:



- c) Now, copy that folder to your **C drive** as below.

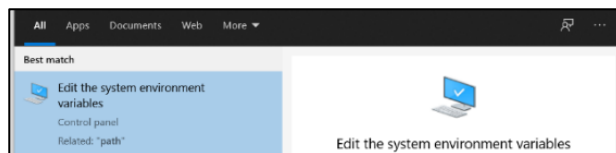


- d) Go into the **bin** folder and copy its path. For example, with the instructions above, the path will be “C:\mingw64\bin” (it is fine if you copy it in another place with a different path but must have no space characters in the path).

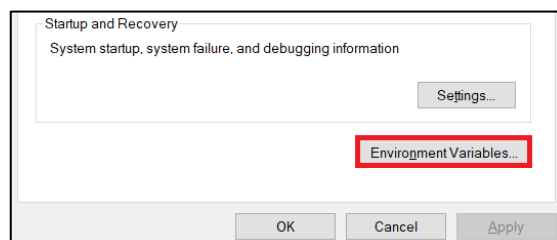


- e) Add the above path to the Windows **PATH environment variable** so that **gcc** tool can run without the full path in Windows Terminal (PowerShell and Command Prompt):

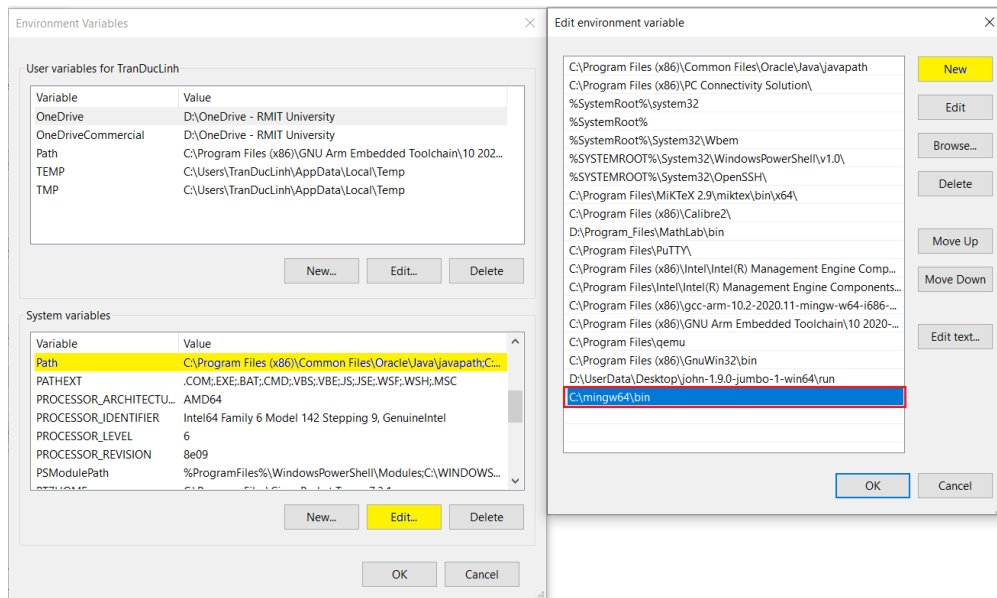
- In the search bar, search for “**variables**” and select “**Edit the system environment variables**”.



- Select “**Environment Variables**”



- Under **System variables** area, select **Path** > **Edit**. In the **Edit environment variable** window, press **New** and input path to the bin directory of our installed GCC tool. After that, press **OK** in all windows to complete PATH setting.



f) Test the **gcc** tool to make sure that it is installed properly:

- Type **powershell** in Search bar to open PowerShell.  
Note: close and reopen powershell if you are opening it while or before doing PATH setting step above (so that it can be updated with the PATH setting).
- Type “**gcc --version**”. If it is installed correctly, you should see the result as below:

```

Windows PowerShell
PS C:\Users\TranDucLinh> gcc --version
gcc.exe (x86_64-posix-seh-rev0, Built by MinGW-W64 project) 8.1.0
Copyright (C) 2018 Free Software Foundation, Inc.
This is free software; see the source for copying conditions. There is NO
warranty; not even for MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE.

```

### 3. GNU Embedded Toolchain for ARM (gcc-arm)

To be able to compile your code, you will need a compiler. Since our target is to develop applications for a Raspberry Pi board (in which its processor is an ARM microcontroller), we will install GNU Embedded Toolchain for ARM.

- a. Download link for **32-bit gcc-arm**:

<https://developer.arm.com/tools-and-software/open-source-software/developer-tools/gnu-toolchain/gnu-rm/downloads>

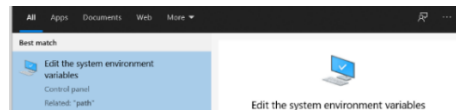
For Windows, select latest version of **gcc-arm-none-eabi-...-win32.exe** to download and install.

- b. After installation, go to this installed location and **browse to bin folder then copy its path**. For example, in my computer, the path is below (note: *you may get newer version with different number*):

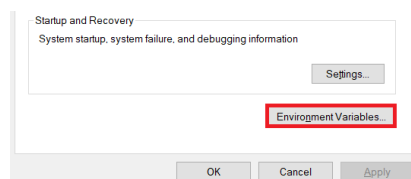
C:\Program Files (x86)\GNU Arm Embedded Toolchain\10 2020-q4-major\bin

- c. Now, we need to change the PATH environment variable of the Windows to be able to run it later.

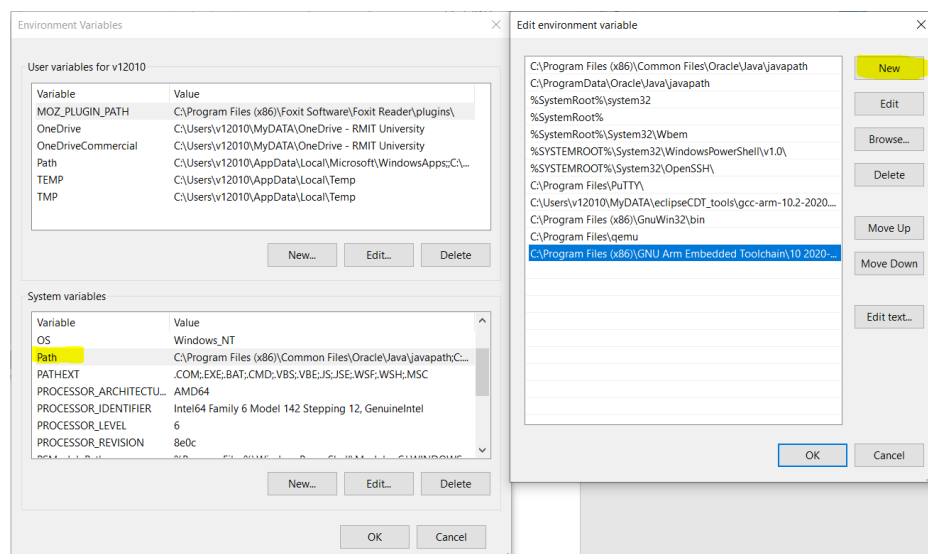
- o In the search bar, search for “**path**” and select “**Edit the system environment variables**”.



- o Select “**Environment Variables**”



- o Under **System variables** area, select **Path** > **Edit**. In the **Edit environment variable** window, press **New** and input path to the bin directory of our installed gcc-arm tool (by default is C:\Program Files (x86)\GNU Arm Embedded Toolchain\10 2020-q4-major\bin).



After that, press OK in all windows to complete PATH setting.

d. Test the gcc-arm tool to make sure that it is installed properly:

- o Type **cmd** in Search bar to open **Command Prompt** (in latest version of Windows, there could be some problems with cmd. If so, you can use **PowerShell** instead).

Note: Close and Reopen Command Prompt if it is running before.

- o Type “**arm-none-eabi-gcc --version**”. If it is installed correctly, you should see the result as below:

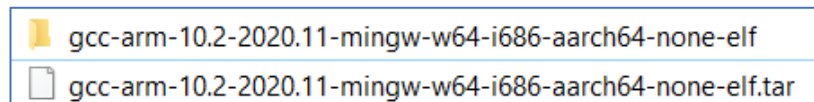
```
C:\Users\v12010>arm-none-eabi-gcc --version
arm-none-eabi-gcc (GNU Arm Embedded Toolchain 10-2020-q4-major) 10.2.1 20201103 (release)
Copyright (C) 2020 Free Software Foundation, Inc.
This is free software; see the source for copying conditions. There is NO
warranty; not even for MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE.
```

e. Similarly, install **64-bit gcc-arm tool**:

- o Go to the link: <https://developer.arm.com/downloads/-/gnu-a>

For Windows, refer to section **Windows hosted cross compilers**.

- o Under category **AArch64 bare-metal target**, select and download file [gcc-arm-10.3-2021.07-mingw-w64-i686-aarch64-none-elf.tar.xz](#)
- o After downloading, extract it. You may need [7-zip](#) to do so.



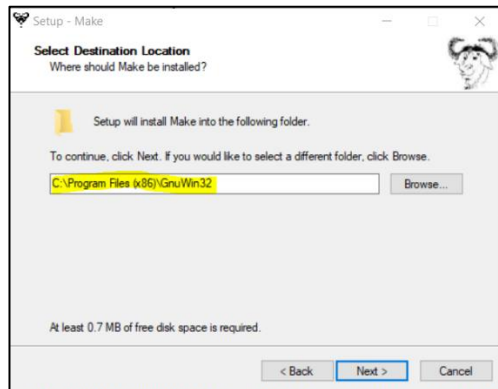
- o Cut and paste the extracted folder into the directory that you installed other tools above (by default is **C:\Program Files (x86)**).
- o Add the path of **bin** directory of the tool (for example, **C:\Program Files (x86)\gcc-arm-10.2-2020.11-mingw-w64-i686-aarch64-none-elf\bin**) to the path environment variable like we did above.
- o Check with command prompt: **aarch64-none-elf-gcc --version**. If successful, you should see the output as below:

```
C:\Users\v12010>aarch64-none-elf-gcc --version
aarch64-none-elf-gcc (GNU Toolchain for the A-profile Architecture 10.2-2020.11 (arm-10.16)) 10.2.1 20201103
Copyright (C) 2020 Free Software Foundation, Inc.
This is free software; see the source for copying conditions. There is NO
warranty; not even for MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE.
```

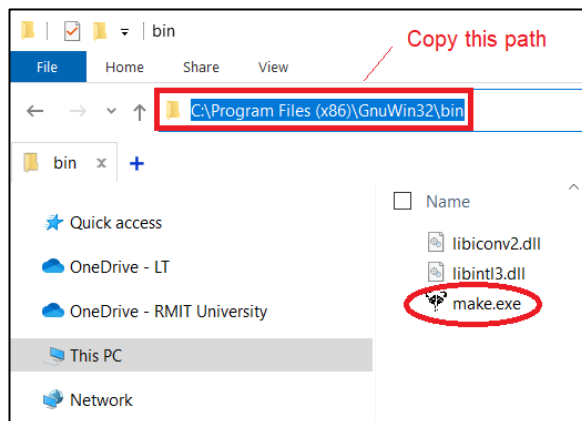
## 4. Install Make tool for Windows

- a. Go to the link <http://gnuwin32.sourceforge.net/packages/make.htm>

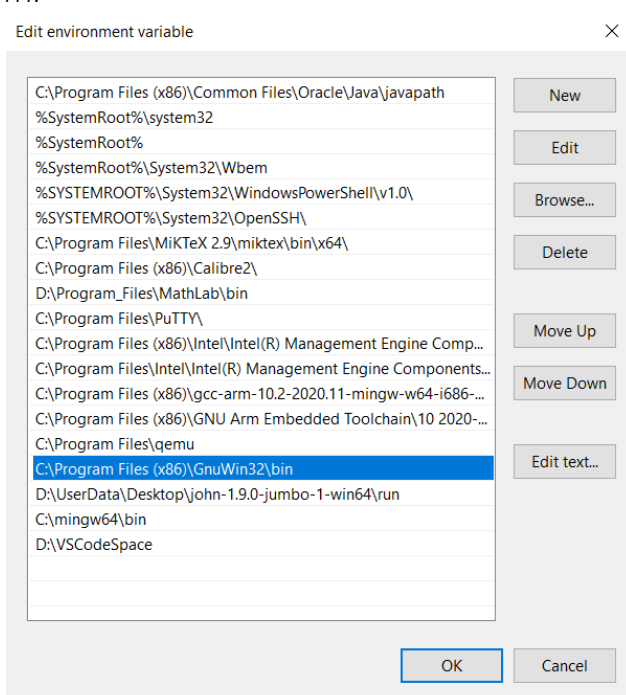
Select “Complete package, except sources” [Setup](#) to download and install it.  
*Leave the path by default when installing it as below:*



- b. Then go there, go inside its **bin** folder (you should see make.exe file there), and copy the path.



- c. Similarly, add path to its bin directory (by default is `C:\Program Files (x86)\GnuWin32\bin`) to system PATH:



- d. Next, close and re-open PowerShell to be updated if you are opening it. Finally, you should be successful with "**make --version**" command.

```
C:\Users\v12010>make --version
GNU Make 3.81
Copyright (C) 2006 Free Software Foundation, Inc.
This is free software; see the source for copying conditions.
There is NO warranty; not even for MERCHANTABILITY or FITNESS FOR A
PARTICULAR PURPOSE.

This program built for i386-pc-mingw32
```

## 5. Raspberry Pi Imager

We will need this tool to write OS image to the SD card later

Download link: <https://www.raspberrypi.com/software/>

**Install Raspberry Pi OS using Raspberry Pi Imager**

Raspberry Pi Imager is the quick and easy way to install Raspberry Pi OS and other operating systems to a microSD card, ready to use with your Raspberry Pi. [Watch our 45-second video](#) to learn how to install an operating system using Raspberry Pi Imager.

Download and install Raspberry Pi Imager to a computer with an SD card reader. Put the SD card you'll use with your Raspberry Pi into the reader and run Raspberry Pi Imager.

[Download for Windows](#)

[Download for macOS](#)

[Download for Ubuntu for x86](#)

## 6. Test the development environment

- a. **Close and re-open VS Code** if it is opening. Click on **File > Add Folder to Workspace**. Browse to/ create a folder where you want to save all of your programs (e.g. D:\EEET2490), and select it.
- b. Create a folder for your project, e.g. named **Test**. Create a source file named **main.c** with a simple main function inside like below:

```
EEET2490 > Test > C main.c > main()
1  int main(){
2      return 0;
3  }
```

- c. Now, let's create a simple **Makefile** (its name is Makefile) in the same folder. Write into the file:

```
all:

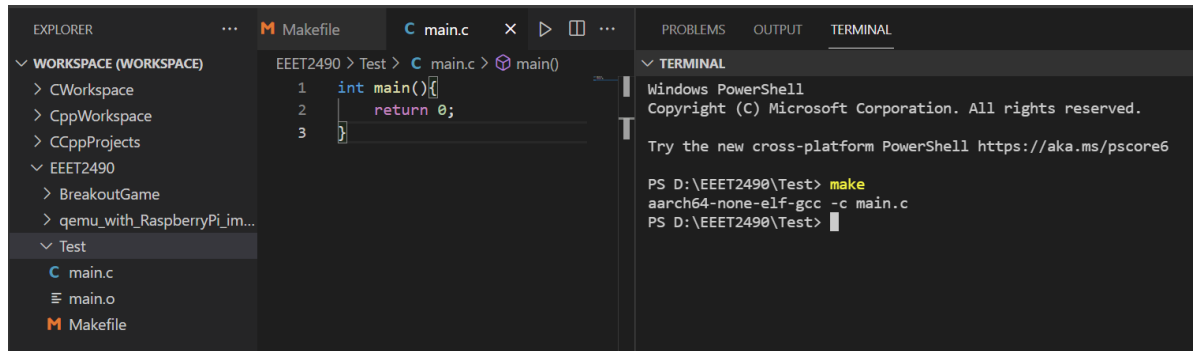
    aarch64-none-elf-gcc -c main.c
```

**Note:** The second line in the Makefile's content above is indented with **TAB** key.

- d. Right click on the **Test** folder, select "Open in Integrated Terminal" to have the command prompt terminal opened to that folder.



- e. Type “make” in the terminal. If all the required tools are installed correctly above, you will see the source file is compiled and generated **main.o** file as below.



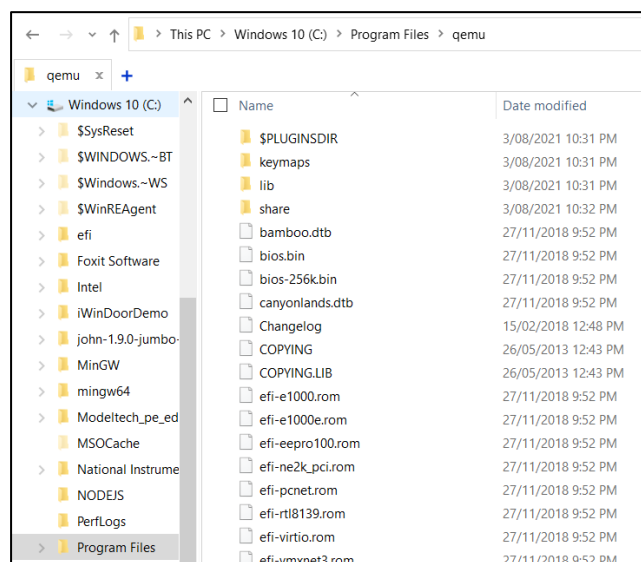
```
1 int main() {
2     return 0;
3 }
```

```
PS D:\EEET2490\Test> make
aarch64-none-elf-gcc -c main.c
PS D:\EEET2490\Test>
```

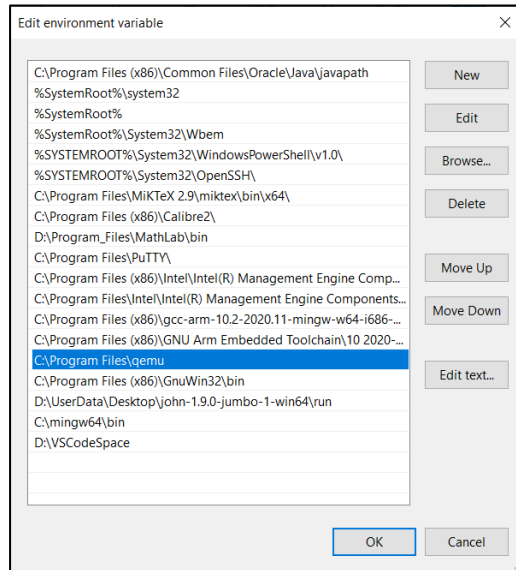
## 7. Raspberry Pi Emulation with QEMU

We have completed setting up our development above. Now, we will setup the QEMU tool to emulate a Raspberry Pi machine and test our development projects later.

- Download the QEMU version 20181127 via following link: [qemu20181127.zip](#)
- Create a folder namely **qemu** in the “Program Files” folder of C drive (its path will be C:\Program Files\qemu).
- Copy the **qemu20181127.zip** file there, right click on it and select “Extract Here” with Winrar or 7-Zip tool to extract it. You will see it as below



- d. Similarly, add path (C:\Program Files\qemu) to system PATH environment variable



- e. Check again with Command Prompt: **qemu-system-aarch64 --version**

```
C:\> Command Prompt

Microsoft Windows [Version 10.0.18363.1556]
(c) 2019 Microsoft Corporation. All rights reserved.

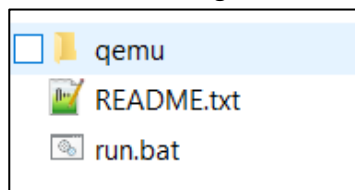
C:\Users\TranDucLinh>qemu-system-aarch64 --version
QEMU emulator version 3.0.92 (v3.1.0-rc2-11731-ge7dfdcb196-dirty)
Copyright (c) 2003-2018 Fabrice Bellard and the QEMU Project developers
```

```
C:\Users\v12010\MyDATA\eclipse_workspace\Test>qemu-system-aarch64 --version
QEMU emulator version 6.0.0 (v6.0.0-11869-g800a25ea45-dirty)
Copyright (c) 2003-2021 Fabrice Bellard and the QEMU Project developers
```

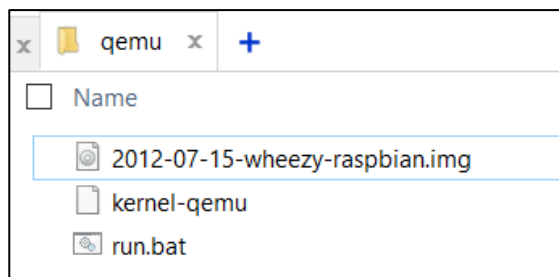
So, we have successfully installed the QEMU tool. Since it works as a virtualization tool (similar to VirtualBox and Vmware), we will need an OS image of the machine that is going to be emulated.

For testing our QEMU tool, we will have to download Raspberry pi images here: [LINK](#).

- After downloading and extracting, you should see those files



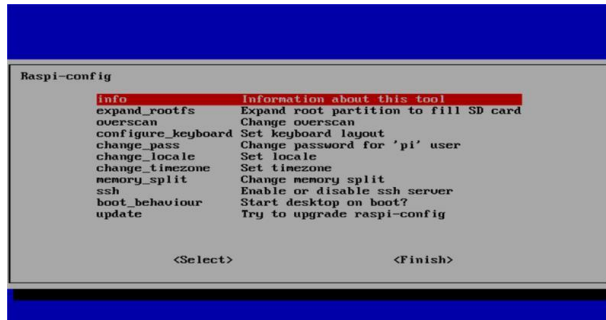
Inside the qemu folder above, it contains run.bat (.bat file contains command for qemu to run emulation), kernel-qemu (Raspberry Pi kernel) and 2012-07-15-wheezy-raspbian.img (Raspberry Pi SD card image).



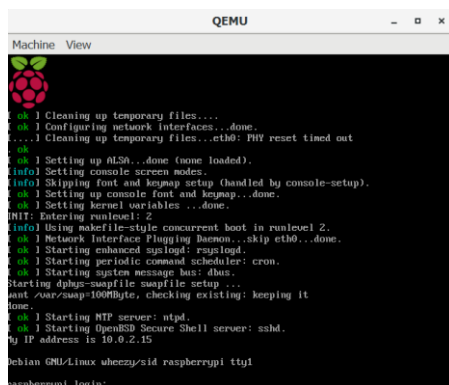
- Now, you can double click on the **run.bat** file to start the emulation. You can right click on this file, and select edit to view its content. Indeed, it will execute the command below (try copy and paste it in Command Prompt to run it manually):

```
qemu-system-arm.exe -M versatilepb -cpu arm1176 -hda 2012-07-15-wheezy-raspbian.img -kernel kernel-qemu -m 192 -append "root=/dev/sda2"
```

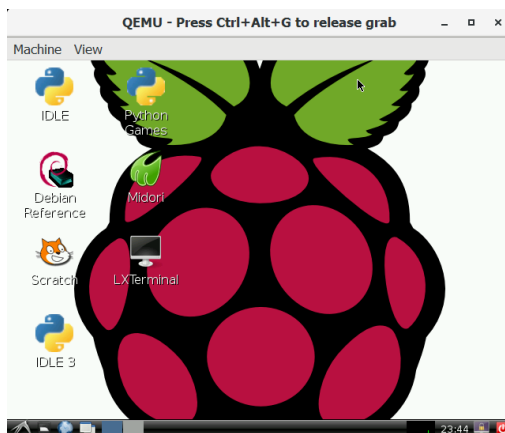
- Our emulated Raspberry will start booting up. You may see the config window below. If yes, use **TAB** button to select “Finish”.



- Then, it will continue booting up to the command prompt. The username and password of the default account in that OS image is:
  - Username: pi
  - Password: raspberry



- After logging in, type “startx” to start the GUI. You will see the following screen of Raspbian OS.



Up to here, we have successfully installed and tested our necessary tools for development and verification. In following tutorials, we will explore the architecture of the ARM based Raspberry Pi SoC and start the development.