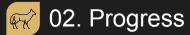


Midterm Presentation

Team Coyote1















Introduction

1.1 Background



United States Department of Agriculture

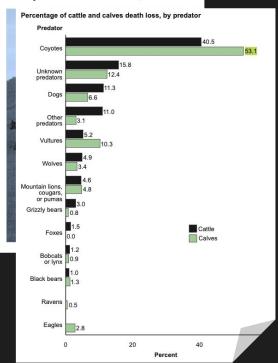
Animal and Plant Health Inspection Service

Veterinary Services

National Animal Health Monitorina System

December 2017

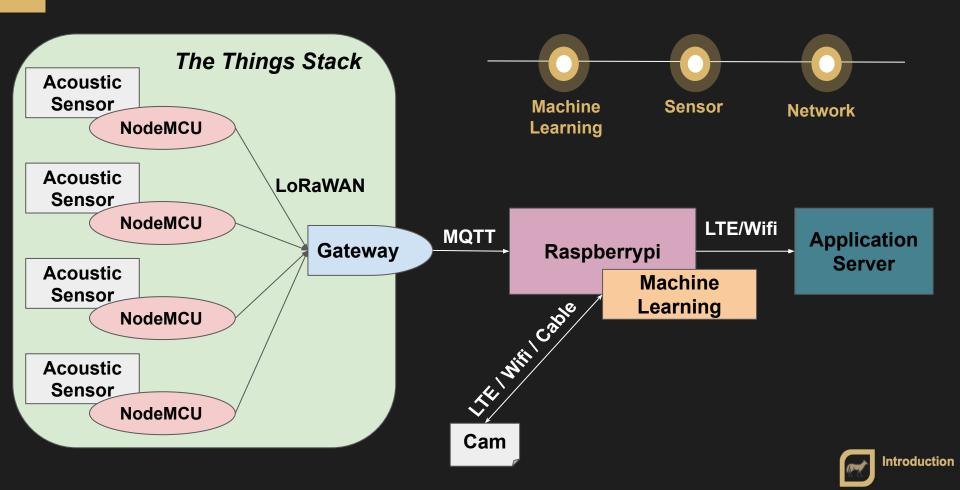
Death Loss in U.S. Cattle and **Calves Due to Predator and** Nonpredator Causes, 2015





Introduction

1.2 Project Architecture





02

Progress

2.1 LoRaWAN



- ✓ Network server stack
- Open-source components for networks
- ✓ Physical layer process of radio modulation



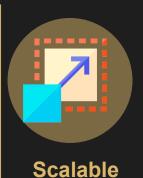
2.1 LoRaWAN

















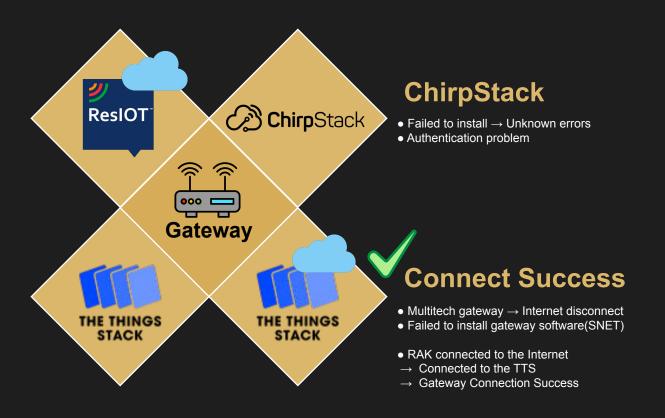
2.2 Gateway

ResloT

- Failed to install (Insufficient storage Error)
- ResloT does not support the Rak gateway.

The Things Stack

- Can't access the console window
- Authentication problem
- 401, 404 errors occurred
- Multitech gateway → Already registered





2.3 Esp32 – Gateway

[Esp32]





Wifi & Bluetooth

Wide Range of applications can be targeted

No need to connect bluetooth - wifi module



Low-cost & Low-power

Low-cost & Low-power system on a chip microcontrollers



Temperature range

Wide operating temperature $(-104\% \sim 221\%)$

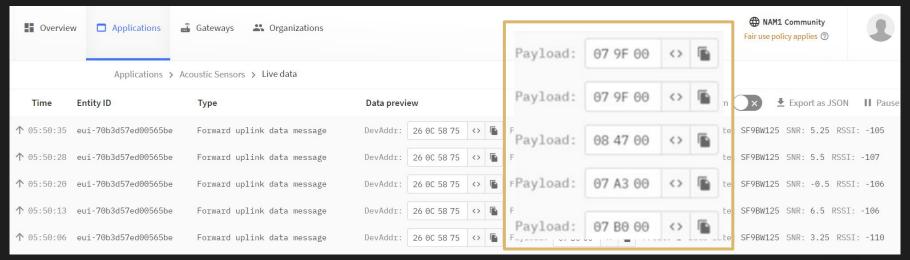


2.3 Esp32 – Gateway

[Esp32]









2.4 Gateway – Raspberry pi

[MQTT]

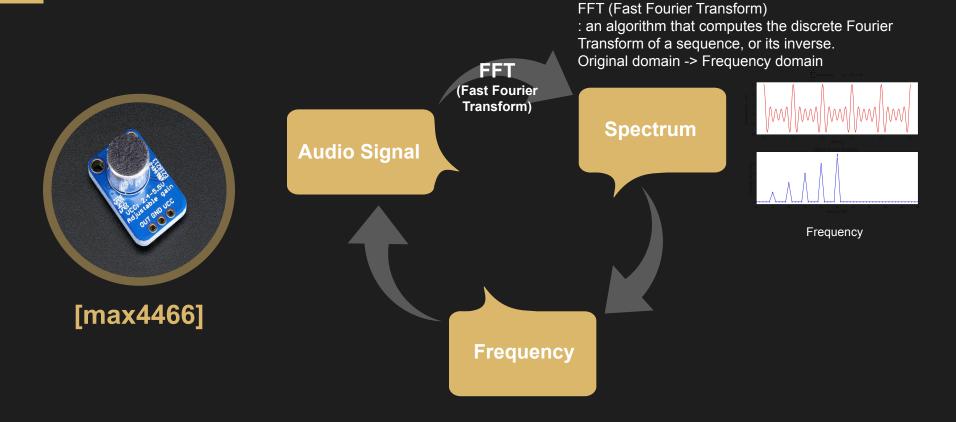
- ✓ MQ Telemetry Transport
- ✓ Light weight
- ✓ Machine Machine Network protocol
- Minimum power & packet







2.5 Acoustic Sensor





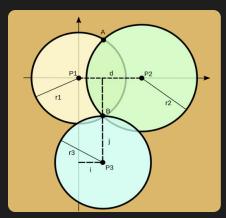
2.1 ~ 2.5 Demo Video

Esp32 — the things stack cloud server — MQTT Broker



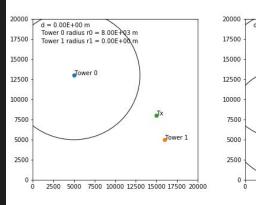
2.6 Localization Directionality

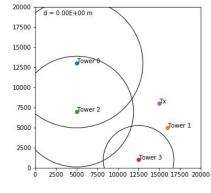
Trilateration

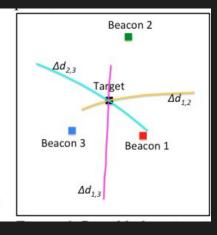


- The length of r2 and r3 could be calculated using the difference in the time when the sound came in
- ullet The N value, the first time the sound came in o could not be obtained
- The length of r1 was not obtained

TDOA (Time Difference Of Arrival)







- Using the parallax with a sound between the two sensors
- Much easier to find the distance by tying two sensors together
- Overlapping parts of the three sides
 - → 3 pairs of methods were obtained to draw a line 90 degrees through the center of the sides that connected the 2 sensors
 - ⇒ Source of sound !!!
- Sound localization → Triangulation and Hyperbola
- Possible to manage the end node in TTS application at once





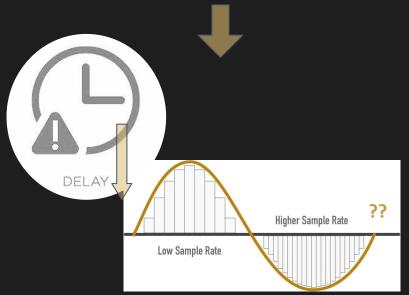
03

Problem

3. Problem



- Low Power
- Wide Area
- Low Bit Rate Networking Protocols









Weekly Plan

4. Weekly Plan

	Sep 4th	Oct 1st	Oct 2nd	Oct 3rd	Oct 4th	Nov 1st	Nov 2nd	Nov 3rd	Nov 4th	Dec 1st	Dec 2nd	Dec 3rd
LoRaWAN Setting												
NodeMCU - Acoustic Sensor Code												
AcousticSensor - GW Connect 🧹												
Sound Filtering & Data Compress												
MQTT Connection √												
Raspberrypi-MachineLearning												
Camera Sensor Code												
GW - CameraSensor Connect												
Test												
Paper												
PR												





