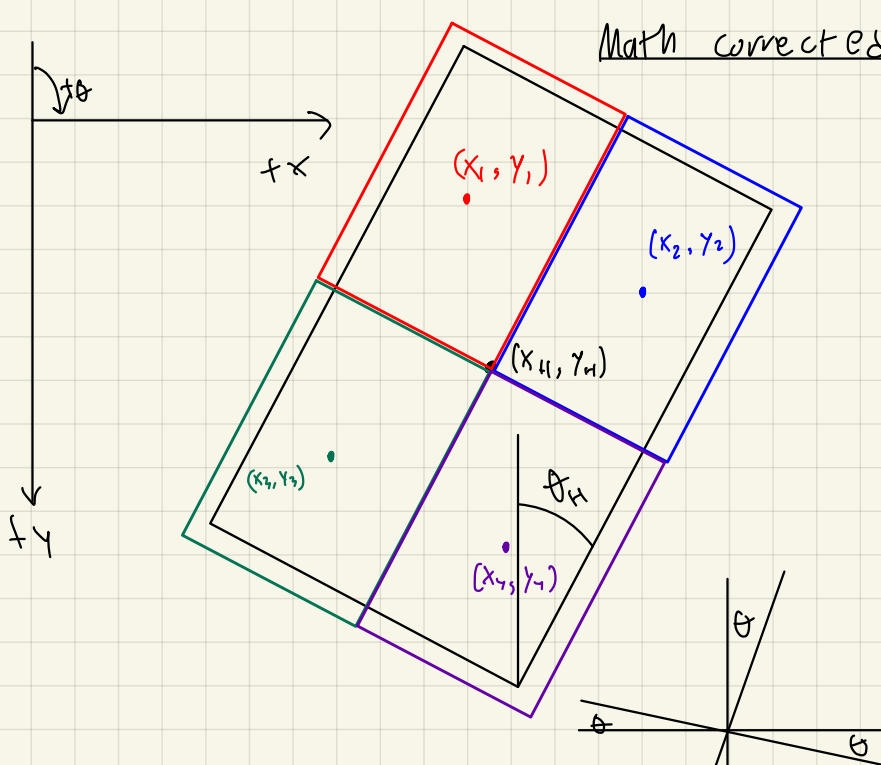
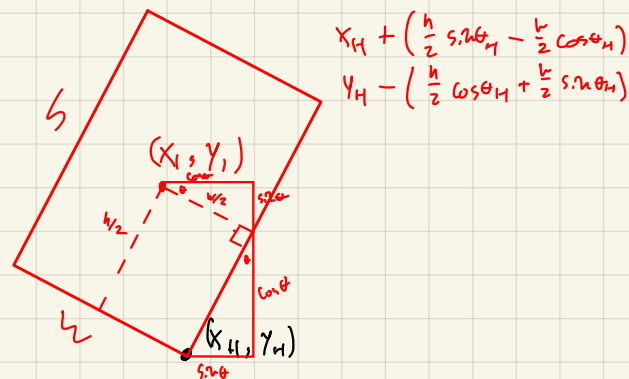


Math corrected 10/14/2021



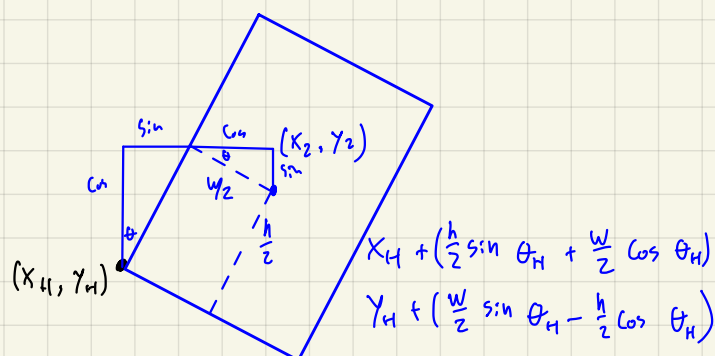
$$X_1 = X_H + \frac{h}{2} \sin \theta_H - \frac{w}{2} \cos \theta_H$$

$$Y_1 = Y_H - \frac{h}{2} \cos \theta_H - \frac{w}{2} \sin \theta_H$$



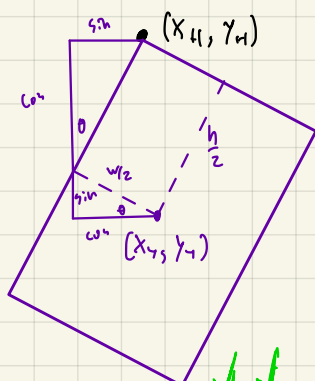
$$X_2 = X_H + \frac{h}{2} \sin \theta_H + \frac{w}{2} \cos \theta_H$$

$$Y_2 = Y_H - \frac{h}{2} \cos \theta_H + \frac{w}{2} \sin \theta_H$$



$$X_H = X_H - \frac{h}{2} \sin \theta_H + \frac{w}{2} \cos \theta_H$$

$$Y_H = Y_H + \frac{h}{2} \cos \theta_H + \frac{w}{2} \sin \theta_H$$

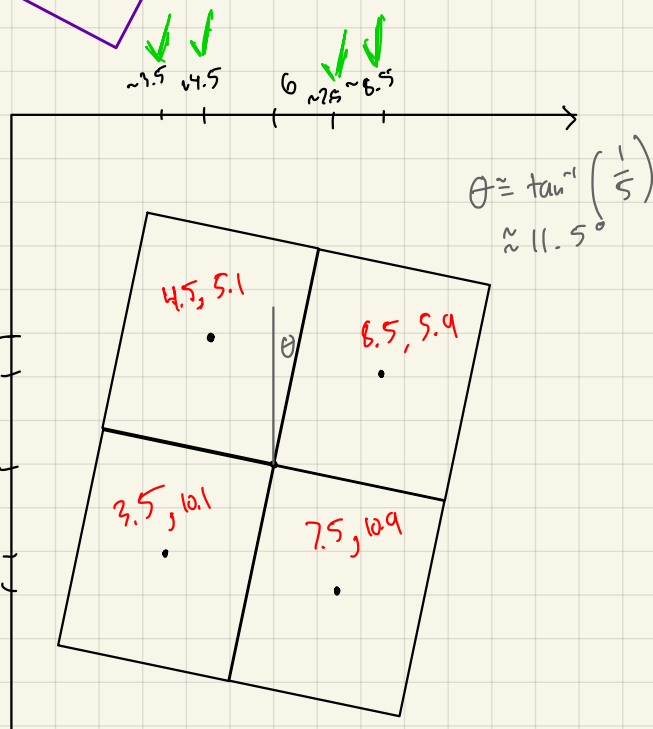
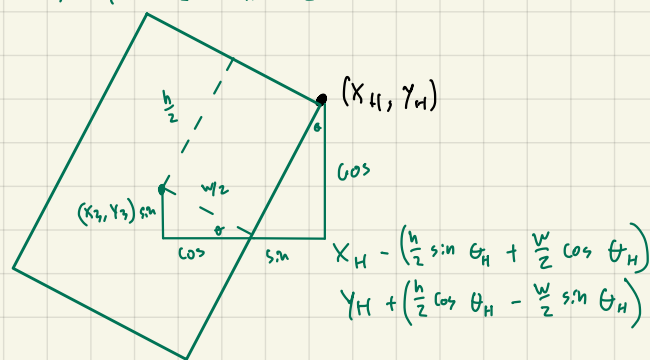


$$X_H + \left( \frac{w}{2} \cos \theta - \frac{h}{2} \sin \theta \right)$$

$$Y_H + \left( \frac{h}{2} \cos \theta + \frac{w}{2} \sin \theta \right)$$

$$X_3 = X_H - \frac{h}{2} \sin \theta_H - \frac{w}{2} \cos \theta_H$$

$$Y_3 = Y_H + \frac{h}{2} \cos \theta_H - \frac{w}{2} \sin \theta_H$$

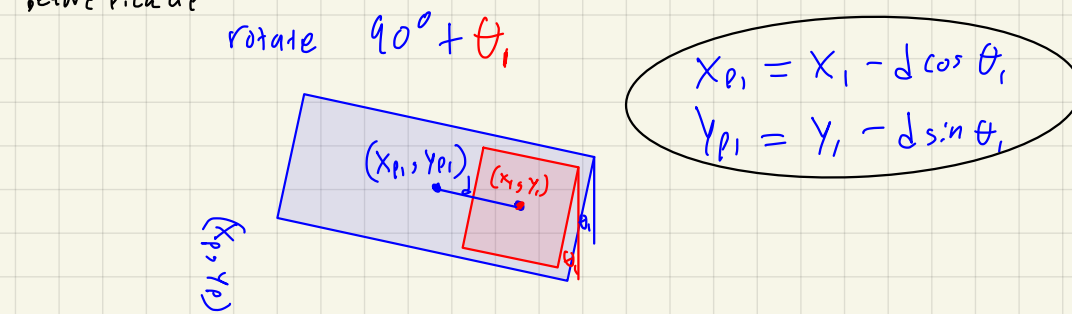
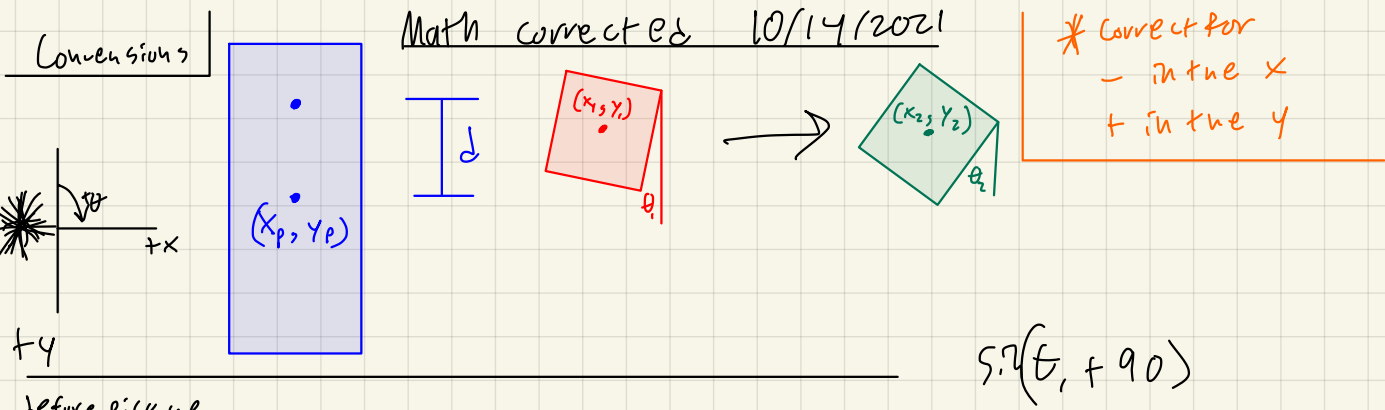


$$X_H = 6$$

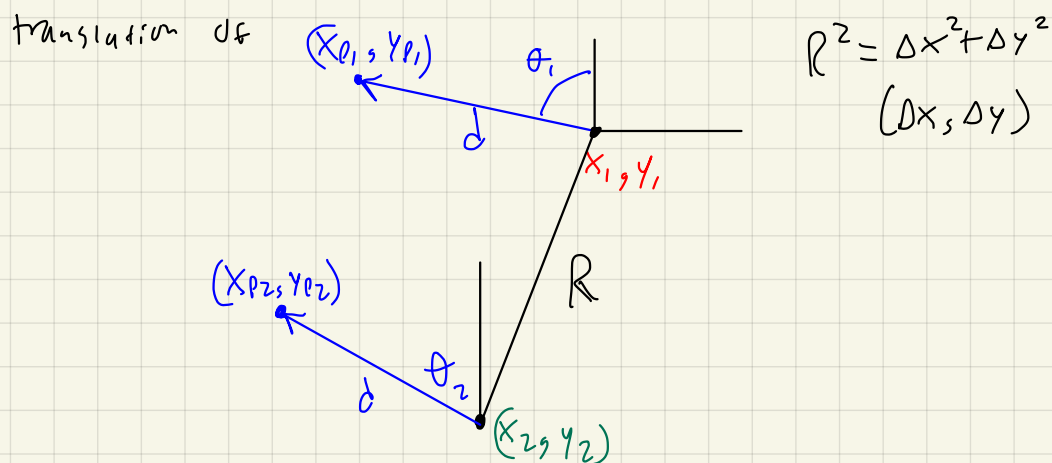
$$Y_H = 8$$

$$h = 5$$

$$w = 4$$



UNRELATED!!! Translation Vector



10/19/2021

Surveying the sensors

TR - tr: 654.321, 194.020, 88.666  
br: 654.103, 214.072, 88.604  
bl: 642.237, 213.460, 88.591  
tl: 642.463, 193.888, 88.648

BR - tr: 654.040, 219.453, 88.591  
br: 653.761, 239.488, 88.591  
bl: 641.930, 279.314, 88.591  
tl: 642.148, 219.308, 88.591

BL - tr: 633.387, 219.094, 88.542  
br: 633.174, 239.113, 88.533  
bl: 621.340, 238.982, 88.549  
tl: 621.555, 218.965, 88.565

TL - tr: 633.667, 193.768, 88.598  
br: 633.387, 213.825, 88.598  
bl: 621.512, 213.656, 88.598  
tl: 621.788, 193.609, 88.675

6/21/21

Glasz z: 93.467

HDI z: 93.332