

## **UNIT-1**

### **❖ Training and Learning in Pattern Recognition Systems-**

#### **Training and Learning Overview:**

Training and learning in pattern recognition systems involve teaching a model to identify patterns and make decisions based on input data. This process uses either prior knowledge (a priori knowledge) or data gathered through experience. The goal is to improve the model's accuracy and reliability in recognizing patterns.

Training and learning in pattern recognition systems involve teaching a model to identify patterns and make decisions based on input data. This process uses either prior knowledge (a priori knowledge) or data gathered through experience. The goal is to improve the model's accuracy and reliability in recognizing patterns.

#### **Example: Handwriting Recognition System**

Imagine you are developing a handwriting recognition system that can identify handwritten digits (0-9) from images. Here's how training and learning would work for this system:

#### **Steps:**

##### **1. A Priori Knowledge:**

- Before training begins, you might have some pre-existing knowledge about the shapes and structures of digits. For instance, you know that the digit '0' is generally circular, '1' is a straight line, and '8' consists of two circles stacked vertically.

##### **2. Experience (Training with Data):**

- To teach the system, you gather a large dataset of handwritten digit images, each labeled with the correct digit (0-9). This dataset could be something like the MNIST dataset, which contains thousands of handwritten digit samples.
- Training Process:

- **Feature Extraction:** The system extracts features from each image, such as edges, lines, and curves that make up the digits.
- **Learning from Data:** Using a supervised learning approach, the model is trained with these labeled images. During training, the model learns to associate specific patterns in the images (feature vectors) with the correct digit labels.
- **Feedback and Adjustment:** As the model processes each image, it makes a prediction. If the prediction is incorrect, the model adjusts its internal parameters to improve accuracy. This process is repeated many times with different images until the model's performance stabilizes.

### 3. Improving Accuracy:

- **Learning Curve:** Throughout training, you monitor the model's performance using a learning curve, which plots accuracy against the number of training iterations. Initially, the model might make many errors, but as it sees more examples, its accuracy improves.
- **Validation:** To ensure the model generalizes well to new data, you validate its performance using a separate set of images that it hasn't seen during training. This helps fine-tune the model and prevent overfitting.

### 4. Outcome:

- After sufficient training, the model becomes proficient at recognizing handwritten digits. When presented with a new, unseen image of a digit, it can accurately predict the correct digit based on the patterns it learned during training.

\*\*\*\*\*

## ❖ A Priori Knowledge or Experience

### Definition:

A priori knowledge refers to information and rules that are known before training begins. It is the pre-existing understanding or assumptions about the data and the problem.

Experience refers to knowledge gained through the exposure of the model to actual data during training.

### Example:

**A Priori Knowledge:** When building a system to recognize handwritten digits, knowing that digits are made of lines and curves is a priori knowledge.

**Experience:** By feeding the system thousands of images of handwritten digits and their correct labels, the system learns from experience to recognize different digits.

\*\*\*\*\*

## ❖ Learning Curves

### Definition:

A learning curve is a graphical representation that shows how the performance of a model improves over time as it learns from more data. It typically plots the error rate or accuracy on the y-axis against the number of training iterations or data samples on the x-axis.

### Example:

If you are training a model to recognize handwritten digits, you might start with 100 images. As you add more images (200, 500, 1000, etc.), you plot the model's accuracy at each step. The learning curve shows whether the model is improving as it processes more data.

### Understanding Learning Curves:

Steep Learning Curve: Rapid improvement in performance with more data.

Plateau: Performance stops improving significantly, indicating that the model has learned most of what it can from the available data.

\*\*\*\*\*

## ❖ Training Approaches

### 1. Supervised Learning:

#### Definition:

Supervised learning involves training a model using labeled data. Each training example includes input data and the corresponding correct output (label).

#### Example:

Dataset: Images of handwritten digits labeled with the correct digit (0-9).

Process: The model learns to associate patterns in the images with the correct digit labels. If the input is an image of a '3', the model should output '3'.

## **2. Unsupervised Learning:**

Definition:

Unsupervised learning involves training a model using data that has no labels. The model tries to find patterns and relationships in the data on its own.

Example:

Dataset: A collection of images of handwritten digits with no labels.

Process: The model might group similar images together (clustering), even though it doesn't know what the digits are. It might group all images of '3's together because they look similar.

## **3. Semi-Supervised Learning:**

Definition:

Semi-supervised learning combines both labeled and unlabeled data for training. This approach leverages a small amount of labeled data to improve the learning from a larger set of unlabeled data.

Example:

Dataset: 100 labeled images of digits and 900 unlabeled images.

Process: The model first learns from the labeled data, then refines its understanding using the patterns found in the unlabeled data.

## **4. Reinforcement Learning:**

Definition:

Reinforcement learning involves training a model to make a sequence of decisions by rewarding it for correct decisions and penalizing it for incorrect ones.

Example:

Task: A robot navigating a maze.

Process: The robot receives rewards for moving closer to the exit and penalties for hitting walls. Over time, it learns the best path to take to reach the exit efficiently.

\*\*\*\*\*