

Random Variable (RV) — The Big Picture

A **random variable** is like a bridge between a real-world random experiment and numbers we can work with mathematically.

- It **assigns a numerical value** to each possible outcome of a random process.
- Formally, it's a function from the *sample space* (all possible outcomes) to real numbers.
- If we roll a die, the random variable XXX could be defined as "the number showing on the die." Possible outcomes $\rightarrow \{1, 2, 3, 4, 5, 6\}$.

1. Discrete Random Variable (DRV)

- **Definition:** Can only take **finite** or **countably infinite** values.
- **Key property:** We can list all possible values, even if the list is very long.
- **Probability tool: Probability Mass Function (PMF)** $P(X=x)P(X=x)P(X=x) \rightarrow$ gives the probability of each possible value.
- The sum of all probabilities is **1**.

Example: Number of students in a class.

- Possible values: $\{0, 1, 2, 3, \dots\}$
- We can assign:

$$P(X = 30) = 0.25, \quad P(X = 31) = 0.15, \quad \dots$$

Common discrete distributions: Binomial, Poisson, Geometric.

2. Continuous Random Variable (CRV)

- **Definition:** Takes **uncountably infinite** values within an interval or multiple intervals.
- **Key property:** The probability of taking any *exact* single value is **zero**. We talk about **probability over intervals** instead.
- **Probability tool: Probability Density Function (PDF)** $f(x)f(x)f(x) \rightarrow$
 - The **area under the curve** of the PDF over an interval gives the probability.
 - The total area under the curve = 1.

Example: Height of a person.

- Possible values: 150.000... cm, 150.001 cm, 150.002 cm, ...
- To find the probability that height is between 150 cm and 160 cm:

$$P(150 \leq X \leq 160) = \int_{150}^{160} f(x) dx$$

Common continuous distributions: Normal, Uniform, Exponential.

Independence for Random Variables

Just like **two events** are independent if one happening doesn't affect the other, **two random variables** are independent if knowing the value of one gives you **no information** about the value of the other.

Mathematical Definition

The mathematical definition of independence depends on the type of random variable.

- **Discrete Case:** For discrete variables, X and Y are independent if for all possible values x and y: $P(X=x, Y=y) = P(X=x) \cdot P(Y=y)$

This means the probability of both events occurring together (the joint probability) is simply the product of their individual probabilities (their marginal probabilities).

If X and Y are independent, knowing X does not affect the distribution of Y.

Example (Discrete): Two independent coin tosses.

- $P(X = 1) = 0.5, P(Y = 1) = 0.5$
- $P(X = 1, Y = 1) = 0.25$
- Since $P(X = 1, Y = 1) = P(X = 1) \cdot P(Y = 1)$, the tosses are independent.

- **Continuous Case:** For continuous variables, independence is defined using their probability density functions (PDFs). X and Y are independent if their joint PDF, $f_{X,Y}(x,y)$, can be factored into the product of their individual (marginal) PDFs, $f_X(x)$ and $f_Y(y)$:

$$f_{X,Y}(x,y) = f_X(x) \cdot f_Y(y)$$

Example: Independent Uniform Random Variables

- Let X = outcome of a spinner that lands anywhere between 0 and 1 uniformly.
- Let Y = outcome of another independent spinner that also lands uniformly between 0 and 1.

Marginal PDFs:

$$f_X(x) = \begin{cases} 1 & 0 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

$$f_Y(y) = \begin{cases} 1 & 0 \leq y \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

Joint PDF (if independent):

$$f_{X,Y}(x,y) = f_X(x) \cdot f_Y(y)$$

So,

$$f_{X,Y}(x,y) = \begin{cases} 1 \cdot 1 = 1 & 0 \leq x \leq 1, 0 \leq y \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

Events vs. Random Variables

It's important to distinguish between these two concepts:

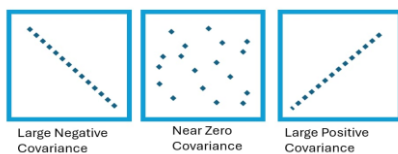
- **Event Independence** focuses on whether the **outcome** of one specific event (e.g., getting a 6 on a die) changes the probability of another specific event.
- **Random Variable Independence** is a more powerful concept that focuses on whether the **entire probability distribution** of one variable remains unchanged regardless of the value of the other.

Covariance: A Measure of Joint Variability

Covariance is a statistical tool that describes how two random variables change in relation to each other. It indicates the **direction** of the linear relationship between them.

Interpretation of Covariance

- **Positive Covariance (>0):** When one variable tends to increase, the other also tends to increase. Think of a positive trend.
 - **Example:** As daily temperatures rise (X), ice cream sales also tend to increase (Y).
- **Negative Covariance (<0):** When one variable increases, the other tends to decrease. This indicates an inverse relationship.
 - **Example:** The more hours a student spends playing video games (X), the lower their exam score tends to be (Y).
- **Zero Covariance ($=0$):** There's no consistent linear relationship between the two variables. Their movements are not predictably linked in a linear fashion.



Mathematical Definition

For two random variables, X and Y, the covariance is defined as the expected value of the product of their deviations from their respective means.

$$\text{Cov}(X, Y) = E[(X - \mu_X)(Y - \mu_Y)]$$

- $\mu_X = E[X]/n$ is the mean of X.
- $\mu_Y = E[Y]/n$ is the mean of Y.

Covariance vs. Independence

It's crucial to remember that **zero covariance does not necessarily imply independence**. While independent variables always have a covariance of zero, a covariance of zero only means there is no **linear** relationship. There could still be a non-linear relationship between the variables.

The Central Limit Theorem (CLT) is a statistical principle that states that the **distribution of sample means** will be approximately normal for a large enough sample size, regardless of the original population's distribution. This powerful theorem is the cornerstone of many statistical methods.

The primary implication of the CLT is that it allows us to use normal distribution-based techniques, such as **confidence intervals** and **hypothesis testing**, even when we don't know the original population's distribution.

Mathematical Formulation

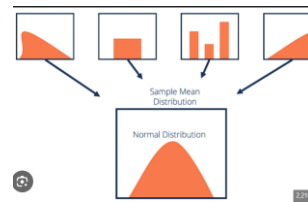
or in standardized form:

$$Z = \frac{\bar{X} - \mu}{\sigma / \sqrt{n}} \approx N(0, 1)$$

Key Conditions and Implications

The CLT holds true under a few key conditions:

- The samples must be **independent** and **identically distributed** (i.i.d.).
- The population must have a **finite variance**.
- The sample size (n) must be **large enough** (a common rule of thumb is $n \geq 30$).



Example Calculation

Consider a population with a mean of $\mu=50$ and a standard deviation of $\sigma=20$. If we take a sample of $n=100$, we can determine the properties of the sampling distribution of the sample mean.

The **standard error** is:

$$SE = \sigma / \sqrt{n} = 20 / \sqrt{100} = 2$$

According to the CLT, the distribution of our sample means (X) will be approximately normal with a mean of 50 and a standard deviation (standard error) of 2. We can write this as $X \sim N(50, 2)$. This means we can expect most sample means to fall within a predictable range around 50.

Advantages (Pros)

1. **Universality:** Works for any population shape if the sample size is large enough.
2. **Foundation for Statistics:** Justifies using normal-based methods for hypothesis testing, confidence intervals, etc.
3. **Simplifies Analysis:** Converts complex or unknown distributions into a predictable normal form.
4. **Practical Application:** Works well in real-world scenarios where exact population distribution is unknown.

Disadvantages (Cons)

1. **Sample Size Requirement:** Needs a sufficiently large nnn for accuracy, especially for skewed or heavy-tailed data.
2. **Not Always Exact:** For small samples from non-normal populations, the approximation can be poor.
3. **Finite Variance Requirement:** Does not hold for distributions with infinite variance (e.g., Cauchy).
4. **Independence Assumption:** Fails if data points are highly dependent or correlated.

Chebyshev's Inequality

Chebyshev's Inequality states that for any dataset or probability distribution (with finite mean μ and finite standard deviation σ), the proportion of observations lying within k

standard deviations of the mean is **at least** $1 - 1/k^2$, where $k > 1$.

Key Features:

1. **Distribution-free:** Works for *any* distribution shape (normal, skewed, uniform, etc.)
2. **Minimum guarantee:** Gives the smallest possible proportion of values within a range — the actual proportion could be higher.
3. **Finite variance condition:** Requires σ^2 to exist.

Mathematical Form:

$$P(|X - \mu| < k\sigma) \geq 1 - \frac{1}{k^2}$$

or equivalently,

$$P(|X - \mu| \geq k\sigma) \leq \frac{1}{k^2}$$

where:

- X = random variable
- μ = mean
- σ = standard deviation
- k = number of standard deviations from the mean

Typical Values:

- $k = 2$: At least $1 - \frac{1}{4} = 75\%$ of values within 2σ
- $k = 3$: At least $1 - \frac{1}{9} \approx 88.9\%$ within 3σ

Example:
A class has an average score $\mu = 70$ and standard deviation $\sigma = 8$. Find the minimum proportion of students scoring between 54 and 86.

Here:

$$k = \frac{86 - 70}{8} = 2$$

By Chebyshev's inequality:

$$P(|X - 70| < 2 \times 8) \geq 1 - \frac{1}{2^2} = 1 - \frac{1}{4} = 0.75$$

At least 75% of students have scores between 54 and 86.

Advantages:

- Works without knowing the exact distribution
- Useful for identifying outliers and spread in non-normal data

Limitations:

- Bound is conservative (actual proportion is often much higher)
- Requires finite variance — fails for infinite-variance distributions.

Diverse Continuous and Discrete Distributions

A) Discrete Distributions

1. Bernoulli Distribution The Bernoulli distribution models a single random trial with two possible outcomes: **success (1)** or **failure (0)**. The **Bernoulli distribution** is the simplest probability distribution.

It models a random experiment that has **only two possible outcomes**:

- **Success (1)** with probability p
- **Failure (0)** with probability $1 - p$

🌟 **Formula (Probability Mass Function):**

If X is a Bernoulli random variable:

$$P(X = x) = \begin{cases} p & \text{if } x = 1 \\ 1 - p & \text{if } x = 0 \end{cases}$$

where $x \in \{0, 1\}$.

🌟 **Properties:**

- Mean (expected value):
$$E[X] = p$$
- Variance:
$$\text{Var}(X) = p(1 - p)$$

✅ **Small Example: Tossing a coin** 🟡

- Let's say "Head" = success = 1.
- "Tail" = failure = 0.
- Probability of Head = $p = 0.5$.

Then:

- $P(X = 1) = 0.5$ (Head)
- $P(X = 0) = 0.5$ (Tail)

2. Binomial Distribution

- The **Binomial Distribution** models the number of **successes** in a fixed number of independent trials, where each trial has only **two outcomes**:
- Success (with probability p)
- Failure (with probability $q = 1 - p$)

Conditions for Binomial Distribution:

- Fixed number of trials (n)
- Each trial has two outcomes (success/failure)
- Probability of success (p) is the same for each trial
- Trials are independent

The Probability Mass Function (PMF) of the Binomial Distribution is:

$$P(X = k) = \binom{n}{k} p^k (1 - p)^{n - k}, \quad k = 0, 1, 2, \dots, n$$

where:

- n = number of trials
- k = number of successes
- p = probability of success in each trial
- $\binom{n}{k} = \frac{n!}{k!(n - k)!}$

✅ **Small Example: Tossing a coin**

Suppose we toss a fair coin $n = 3$ times ($p = 0.5$).

- $P(X = 0)$: 0 heads = $\binom{3}{0} (0.5)^0 (0.5)^3 = 0.125$
- $P(X = 1)$: 1 head = $\binom{3}{1} (0.5)^1 (0.5)^2 = 0.375$
- $P(X = 2)$: 2 heads = $\binom{3}{2} (0.5)^2 (0.5)^1 = 0.375$
- $P(X = 3)$: 3 heads = $\binom{3}{3} (0.5)^3 (0.5)^0 = 0.125$

So distribution = {0:0.125, 1:0.375, 2:0.375, 3:0.125}

3. Poisson Distribution

The Poisson distribution counts the number of times an event occurs within a specific interval of time or space, assuming the events happen at a constant average rate, λ . This is useful for modeling rare events over a continuous period, like the number of emails a person receives in an hour.

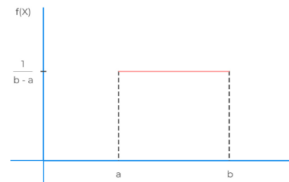
Formula (Probability Mass Function):

If X = number of events in interval, then:

$$P(X = k) = \frac{e^{-\lambda} \lambda^k}{k!}, \quad k = 0, 1, 2, \dots$$

where:

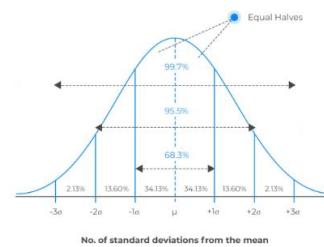
- λ = average number of events in the interval (mean rate)
- $e \approx 2.718$
- k = actual number of occurrences



2. Normal Distribution The Normal distribution, also known as the "bell curve," is a symmetric, unimodal distribution defined by its **mean (μ)** and **standard deviation (σ)**.

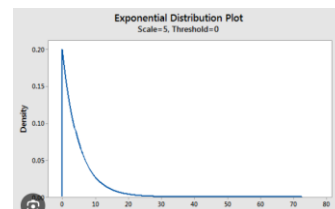
It is one of the most important distributions in statistics because it describes many natural phenomena, such as human heights, blood pressure, and test scores.

- PDF:** $f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$



3. Exponential Distribution The Exponential distribution models the **time between events** in a Poisson process. It's often used to describe the waiting time until the next event occurs, assuming the events happen at a constant rate. For example, it can model the time between consecutive bus arrivals at a bus stop.

- PDF:** $f(x) = \lambda e^{-\lambda x}$, for $x \geq 0$



1. Descriptive Statistics:

Descriptive statistics are the first step in data analysis, providing a concise summary of a dataset. They help us understand the data's central location and how its values are spread out.

Main Measures

- Central Tendency:**
 - Mean (\bar{x}):** The average value, calculated by summing all values and dividing by the count. It's sensitive to extreme values.
 - Median:** The middle value of an ordered dataset. It's a robust measure, unaffected by outliers.
 - Mode:** The value that appears most frequently in the dataset.
- Spread:**
 - Range:** The difference between the maximum and minimum values, indicating the total span of the data.

4. Geometric Distribution

Models the number of trials needed until you get the **first success** in a sequence of independent trials (like coin flips, dice rolls, or machine failures).

Probability Mass Function (PMF):

If X = number of trials until the first success, then

$$P(X = k) = (1 - p)^{k-1} \cdot p \quad \text{for } k = 1, 2, 3, \dots$$

- p = probability of success on each trial
- $(1 - p)^{k-1}$ = probability that the first $k - 1$ trials are failures
- Final p = probability that the k -th trial is success

Example: Rolling a die

Suppose we roll a die until we get a "6".

- Probability of success (getting a 6) = $p = \frac{1}{6}$.
- Probability of failure (not 6) = $1 - p = \frac{5}{6}$.

Let X = the trial number when we see the first 6.

Probabilities:

- First roll is a 6:**

$$P(X = 1) = p = \frac{1}{6} \approx 0.167$$

- Second roll is the first 6:**
(First roll not 6, second roll is 6)

$$P(X = 2) = (1 - p) \cdot p = \frac{5}{6} \cdot \frac{1}{6} \approx 0.139$$

- Third roll is the first 6:**

$$P(X = 3) = (1 - p)^2 \cdot p = \left(\frac{5}{6}\right)^2 \cdot \frac{1}{6} \approx 0.116$$

And so on... probabilities keep decreasing.

Interpretation:

- You have about a **16.7% chance** of getting a 6 on the first roll,
- A **13.9% chance** of waiting until the second roll,
- An **11.6% chance** of waiting until the third roll, etc.

On average, the first 6 will appear at:

$$E[X] = \frac{1}{p} = 6 \text{ rolls.}$$

B) Continuous Distributions

1. Uniform Distribution The Uniform distribution models situations where all values within a given interval $[a, b]$ are **equally likely**. This means the probability density is constant across the entire interval. An example is a random number generator that produces a value between 1 and 10, where every number has the same chance of being selected.

- Probability Density Function (PDF):** $f(x) = \frac{1}{(b-a)}$, for $a \leq x \leq b$

- **Variance (σ^2) & Standard Deviation (σ):** These measure the average squared deviation (variance) and root mean square deviation (standard deviation) from the mean.

Example: $X=\{4,7,7,10,12\}$

- **Mean:** $54+7+7+10+12=540=8$
- **Median:** The sorted data is $\{4,7,7,10,12\}$, so the median is 7.
- **Mode:** 7, because it appears twice.
- **Range:** $12-4=8$
- **Sample Variance (s^2):** Using deviations from the mean $(-4,-1,-1,2,4)$, the sum of squares is $16+1+1+4+16=38$. The sample variance is $s^2=5-138=9.5$.
- **Sample Standard Deviation (s):** $s=9.5 \approx 3.082$

2. Graphical Statistics:

Graphical statistics use visual tools to quickly reveal patterns, distributions, and relationships within data that may be difficult to discern from numbers alone.

Common Plots

- **Histogram:** Displays the frequency distribution of a numeric variable. It shows the data's shape, skewness, and modality.
- **Boxplot:** A concise summary of the data's quartiles. It shows the median (Q2), the first and third quartiles (Q1, Q3), the interquartile range (IQR), and potential outliers.
- **Scatter Plot:** Illustrates the relationship between two numeric variables, helping to identify correlation and trends.
- **Q-Q Plot:** Compares the quantiles of the data to the quantiles of a theoretical distribution (e.g., normal), providing a visual check for how well the data fits that distribution.

Example (using $X=\{4,7,7,10,12\}$):

- A **boxplot** of this data would show the median at 7. The first quartile (Q1) would be the median of the lower half $\{4, 7\}$, which is 5.5. The third quartile (Q3) would be the median of the upper half $\{10, 12\}$, which is 11. The IQR is $11-5.5=5.5$.

3. Method of Moments (MoM):

The **Method of Moments** is a statistical technique for estimating unknown parameters of a probability distribution by equating **sample moments** (calculated from data) with **theoretical moments** (derived from the distribution).

- **Moments** are numerical measures that describe the shape and characteristics of a distribution.
- The **first moment** is the mean, the **second central moment** is the variance, etc.

Steps in MoM

1. Write theoretical moments

- Express population moments (mean, variance, etc.) in terms of unknown parameters.
- Example: $E[X] = \mu$, $Var(X) = \sigma^2$.

2. Compute sample moments

- From data X_1, X_2, \dots, X_n :
- First moment (mean):

$$M_1 = \frac{1}{n} \sum_{i=1}^n X_i$$

- Second moment (variance):

$$M_2 = \frac{1}{n} \sum_{i=1}^n (X_i - M_1)^2$$

3. Equating moments

- Set sample moments equal to theoretical ones:

$$M_k = \mu_k(\text{parameters})$$

4. Solve for parameters

- Number of equations = number of unknowns.
- Solve to get parameter estimates.

- For Poisson, mean = $\mu = \lambda$.
- From data $X = \{4, 7, 7, 10, 12\}$, sample mean = $\bar{X} = 8$.
- By MoM: set $\bar{X} = \lambda$.
- So, estimate $\hat{\lambda}_{MoM} = 8$.

2. Maximum Likelihood Estimation (MLE)

Maximum Likelihood Estimation (MLE) is a statistical method for estimating the parameters of a probability distribution (like mean, variance, probability ppp, etc.). The core idea is to choose the parameter values that maximize the likelihood of observing the data you actually have.

Let data x_1, x_2, \dots, x_n come from $N(\mu, \sigma^2)$.

- If μ is known, MLE of variance is:

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2$$

- If both μ and σ^2 are unknown,

- MLE of μ = sample mean
- MLE of $\sigma^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$

Why MLE?

- **Consistent:** They converge to the true value as sample size grows.
- **Efficient:** They have minimum possible variance among all unbiased estimators.
- **Suited for a wide range of models.**

Steps

Write the likelihood function for your data in terms of the unknown parameter(s).

Take the likelihood function to get the log-likelihood.

Differentiate the likelihood with respect to the parameter(s).

Solve the resulting equations to find the parameter values that maximize the likelihood.

1. Subtypes and Supertypes

- **Supertype** → A **general entity** containing attributes common to multiple related entities.

- **Subtype** → A **specialized entity** that inherits all attributes of its supertype and may have extra attributes or behaviors.
- Similar to **inheritance** in object-oriented programming but used in database modeling.

Purpose

1. **Avoids redundancy** – Common attributes are stored only once in the supertype.
2. **Encourages specialization** – Unique features of subtypes can be stored separately.
3. **Improves clarity** – Clearly shows relationships and differences between entities.
4. **Supports flexibility** – New subtypes can be added without changing the supertype.
5. **Models real-world hierarchy** – Many systems naturally have “general-specific” structures.

Example

- **Supertype:** Vehicle
 - Attributes: VehicleID, Model, Manufacturer
- **Subtypes:**
 - **Car** → Additional attributes: NumberOfDoors, FuelType
 - **Bike** → Additional attribute: Type (e.g., mountain, road)

Real-World Use

- **Transportation System:**
 - Supertype: Vehicle
 - Subtypes: Car, Bus, Truck
- **Hospital Database:**
 - Supertype: Person
 - Subtypes: Patient, Doctor, Staff

Diagram Representation

Vehicle (Supertype)

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Car Bike Truck (Subtypes)

2. Hierarchical Data

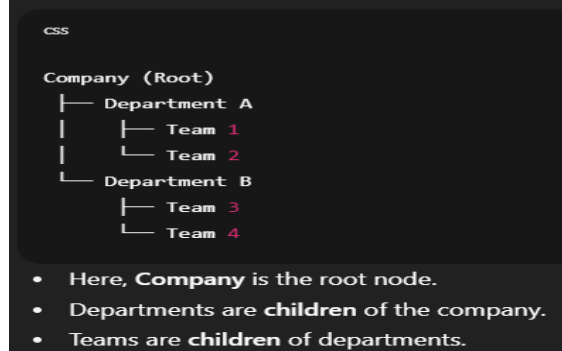
- **Hierarchical data** is organized in a **tree-like structure** where:
 - Each record/node has **exactly one parent** (except the root).
 - A record can have **zero or more children**.
- The **root** is the top-most node with no parent.
- Relationships are **one-to-many** (parent → multiple children).

Purpose

1. **Models natural hierarchies** like organizations, categories, or file systems.

2. **Efficient navigation** when moving top-down or bottom-up in the hierarchy.
3. **Clear structure** for representing nested relationships.
4. **Logical grouping** of related data under a common parent.

Example – Company Structure



Real-World Uses

- **Organizational charts** (e.g., CEO → Managers → Employees).
- **File systems** (e.g., Folder → Subfolder → Files).
- **Product categories** in e-commerce.
- **XML/JSON** data storage (tags/nodes form a hierarchy).

Advantages

- Intuitive structure for hierarchical relationships.
- Efficient for queries like “get all sub-items of X”.
- Matches many real-world use cases.

Limitations

- Can be harder to update (moving nodes may require multiple updates).
- More complex queries compared to flat relational tables.

3. Recursive Relationships

- A **recursive relationship** is a relationship where **an entity is related to itself**.
- The **same table/entity** is used for both sides of the relationship.
- This is also called a **self-referencing relationship**.

Purpose

1. **Model self-referential structures** where an object relates to other objects of the same type.
2. **Represent hierarchies** within a single entity (e.g., manager-employee, parent-child).
3. **Avoid duplicate tables** for the same type of data.

Example – Employee Management

Entity: Employee (EmployeeID, Name, ManagerID)

- ManagerID is a **foreign key** referencing EmployeeID in the **same table**.

Table Example:

EmployeeID	Name	ManagerID
1	Alice	NULL
2	Bob	1
3	Carol	1
4	David	2

Meaning:

- Alice has no manager (top-level).
- Bob and Carol report to Alice.
- David reports to Bob.

Real-World Uses

- **Organizational hierarchies** (CEO → Managers → Employees).
- **Folder structures** (Folder contains subfolders).
- **Bill of Materials (BOM)** (product contains sub-components).
- **Linked lists** stored in databases.

Types of Recursive Relationships

1. **One-to-One (1:1):** An entity relates to exactly one other of the same type.
 - Example: One employee mentors exactly one other employee.
2. **One-to-Many (1:M):** One record relates to many others of the same type (most common).
 - Example: One manager manages many employees.
3. **Many-to-Many (M:M):** Many records relate to many others of the same type.
 - Example: Authors collaborating on multiple books with each other.

Advantages

- Reduces redundancy (only one table for the entity).
- Easy to expand the hierarchy to multiple levels.
- Supports complex, multi-level relationships naturally.

Limitations

- Queries can become complex (especially retrieving multiple hierarchy levels).
- Performance can drop for deep hierarchies without proper indexing.

4. Historical Data

- **Historical data** refers to the storage of **past states of data** for reference, analysis, compliance, or tracking changes over time.
- Instead of overwriting old values, new records are created with **validity periods** (start and end dates).

- Often used in **time-based queries** to retrieve data "as it was" at a certain point in the past.

Purpose

1. **Track changes over time** – maintain a history of modifications.
2. **Enable time-travel queries** – see data as it existed on a specific date.
3. **Compliance & auditing** – fulfill legal or business record-keeping requirements.
4. **Trend analysis** – identify patterns by comparing past and current data.

Example – Employee Salary History

EmployeeID	Salary	StartDate	EndDate
101	40000	01-01-2020	31-12-2021
101	45000	01-01-2022	NULL

Meaning:

- Employee 101 earned ₹40,000 between Jan 2020 and Dec 2021.
- From Jan 2022 onward, salary increased to ₹45,000 (EndDate = NULL means current record).

Real-World Uses

- **Data warehouses** – store years of transactional history for analysis.
- **Financial records** – maintain past account balances and transactions.
- **Healthcare systems** – track patient medical history.
- **Retail sales** – monitor price changes over time.

Types of Historical Data Storage

1. **Slowly Changing Dimensions (SCD)** (in data warehousing):
 - **Type 1:** Overwrite old data (no history).
 - **Type 2:** Keep history with start and end dates.
 - **Type 3:** Store limited history in extra columns.
2. **Audit Tables:** Separate tables just for historical logs.
3. **Temporal Tables:** Database feature to auto-maintain history (available in modern DBMS).

Advantages

- Enables trend analysis and forecasting.
- Essential for compliance and audits.
- Improves business intelligence decision-making.

Limitations

- Increases storage requirements.
- Requires careful indexing for performance.
- Can make queries more complex.

Feature	Discrete Random Variable	Continuous Random Variable
Definition	Takes a countable number of possible values (finite or infinite countable).	Takes uncountably infinite values within an interval (cannot list all).
Examples	Number of students in a class (0, 1, 2, ...) Number of heads in coin tosses.	Height of a student (e.g., 165.4 cm, 165.43 cm, ...) Time taken to run a race.
Probability Representation	Probability Mass Function (PMF): $P(X = x)$.	Probability Density Function (PDF): $f(x)$, with probability as area under curve.
Probability of a single value	Can be non-zero, e.g., $P(X = 2) = 0.3$.	Always zero, because infinite values exist. Probability is defined over an interval.
Summation / Integration	Total probability: $\sum P(X = x) = 1$.	Total probability: $\int_{-\infty}^{\infty} f(x) dx = 1$.
Typical Distributions	Binomial, Poisson, Geometric.	Normal, Exponential, Uniform (continuous).

Examples

- Discrete RV Example (Poisson):
Number of emails received in an hour. Possible values: 0, 1, 2, ...
- Continuous RV Example (Normal):
Height of people in a city. Any real value within a range (say 140 cm to 200 cm).

Independent Variable – Definition

An independent variable is the variable that is manipulated or controlled in an experiment or study to observe its effect on another variable (dependent variable). It is the cause/input in cause–effect relationships.

Types of Independent Variables

- Manipulated Independent Variable
 - Actively changed by the researcher.
 - Example:* Giving different doses of a medicine to test its effect on blood pressure.
- Subject Independent Variable
 - Based on characteristics of subjects (cannot be controlled).
 - Example:* Gender, age, or IQ level when studying academic performance.
- Situational Independent Variable
 - Based on environment or context.
 - Example:* Testing memory in a quiet vs. noisy room.

Example:

In an experiment to test the effect of study hours on exam scores:

- Independent Variable = Study hours (cause).**
- Dependent Variable = Exam score (effect).**