



## CT10M Series

### • High Quality

✧ The hardware design and components selection are more optimized and reasonable;

### • High Power Density

✧ The structure design layout is more compact;

### • High Performance

✧ The software upgrade is more compatible with the end user, industrial control is more flexible, accurate, and the performance is stronger, and it is more suitable for precision control occasions with higher requirements for torque, control accuracy, and response speed;

### • Optimize Products User Experience

✧ Easy operation, maintainability, environmental protection, scalability and convenience of Internet of Things access.



CT10M:Power Rate

1 phase & 3 phase Input  
3 phase output

220V (+-20%) 0.4KW~4.0KW

380V (+-20%) 0.4KW~400KW

## Best Solution For General Purpose Series

Start Torque @0.5Hz  
**100%**

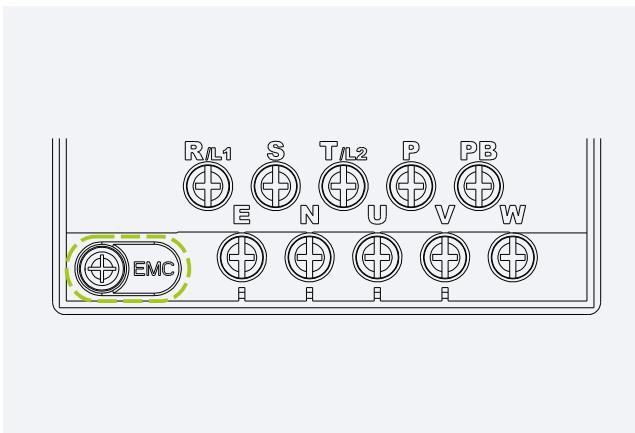
Overload Capability  
**200%**

Ambient Temp °C  
**40**

Speed Regulation  
**1:100**



## REASONABLE STRUCTURAL DESIGN



### EMC grounding design

✧ Independent grounding system selection switch (through the screw access or not to choose), easy to solve the problem of EMC interference and leakage current.



### Advanced drive technology

✧ Capable of driving different types of motor. CT10M series runs not only induction motors, but also synchronous motors like IPM\*1 and SPM\*2 motors with high performance open and closed loop vector control.

✧ Minimize equipment needed for your business by using the same drive to run induction and synchronous motors.

① Interior Permanent Magnet Motor (Motors with permanent magnets inserted into the rotor)

② Surface Mounted Permanent Magnet Motor (Motors with permanent magnets mounted on the surface of the rotor)



## ADVANCED DESIGN



◆ EMC Filter  
C3 Level Filter Build-In Standardly  
Better EMC Performance



◆ IGBT Selection  
Selection Of Large Margin  
Current>2 Times of VFD Current



◆ Overload Capacity  
120% long time running without trip.  
150% for 60 seconds  
180% for 10 seconds



◆ Voltage Range  
Compatible with ±15% input voltage fluctuation, output voltage table.



◆ S Curve  
S Curve Acceleration/Deceleration  
Better Start /Stop Performance



◆ Flying Start Function  
Restart The Running Motor Smoothly  
No Current Surge  
High Accuracy



◆ Protection  
Overcurrent, Overvoltage, PID feedback failure, Overheat, Undervoltage, The main contactor is abnormal, Motor overload, Fast protection, Unbalanced output, Frequency conversion overload, System abnormal, Motor detection abnormalOutput phase loss, Input phase loss, Short circuit protection of control board power supply.



## ❖ SPECIFICATION

### Input & Output

	1AC 220~240V(± 15%)
Input voltage	3AC 220~240V(± 15%)
	3AC 380~460V(± 15%)
Input frequency	50Hz/60Hz ±5%
Output voltage	0~input voltage, deviation <±3%
Output frequency	0~600Hz

### Control Characteristics

Control mode	v/f control Sensor-less vector control Torque control
Speed accuracy	±0,5% (V/f) ±0,2% (SVC)
Speed fluctuation	±0,3% (SVC)
Torque response	< 10ms (SVC)
Starting torque	0,5Hz: 150% (V/f) 0,25Hz: 180% (SVC)
Overload capability	150% Rated current -60s 180% Rated current -10s 200% Rated current -1s
Simple PLC Multi-step speed	16 speed External digital signal control Internal clock
PID function	Standard build-in
Communication	Modbus

### Featured functions

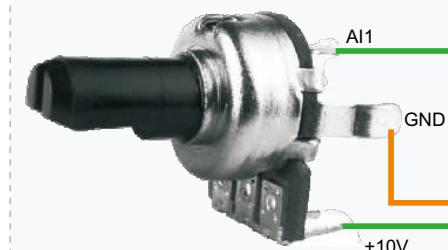
Featured functions	Input & Output delay Flexible parameters display AVR (Automatic Voltage Regulation) Timing control, fixed length control, etc. Simple PLC, 16-steps speed control Torque control build-in S curve acceleration/deceleration Multi-functional programmable keypad V/f separated control
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### Environment Limitation

Installation location	Without direct sunlight, free from dust, corrosive gases, oil mist, flammable gases, water vapor, water drop and salt, etc.
Altitude	0~2000m Derated 1% for every 1000m when the altitude is above 1000meters
Ambient temperature	-10°C~50°C (Output derated while the temperature is higher than 40°C)
Storage temperature	-20°C~+70°C
Relative Humidity	5-95% no condensation

## ❖ EASILY CONNECT WAY

### External potentiometers

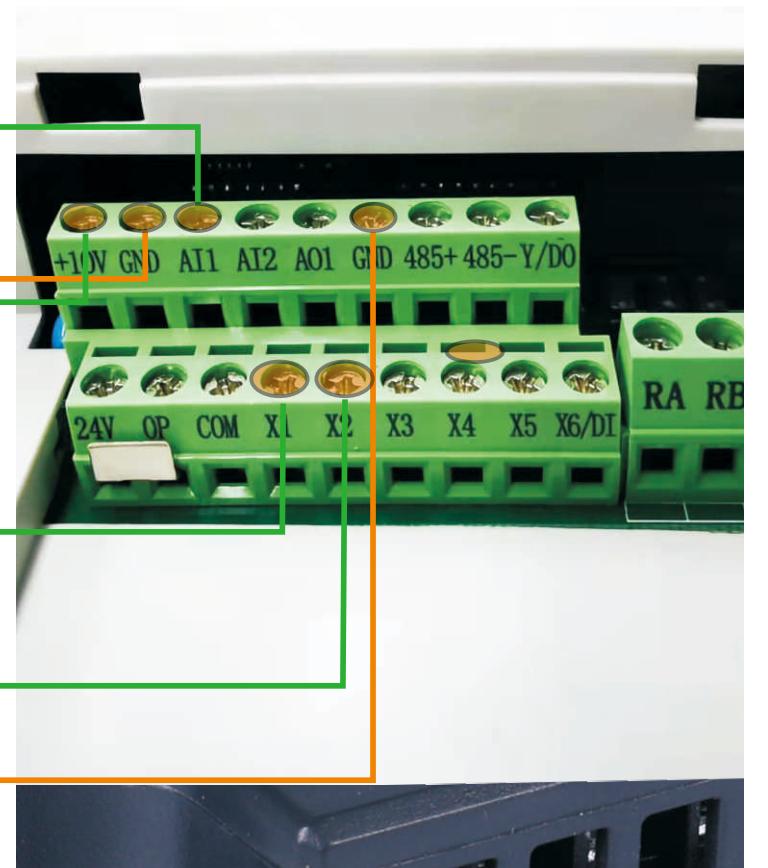


"Setting Way,P0-03=2 To Use External potentiometers"

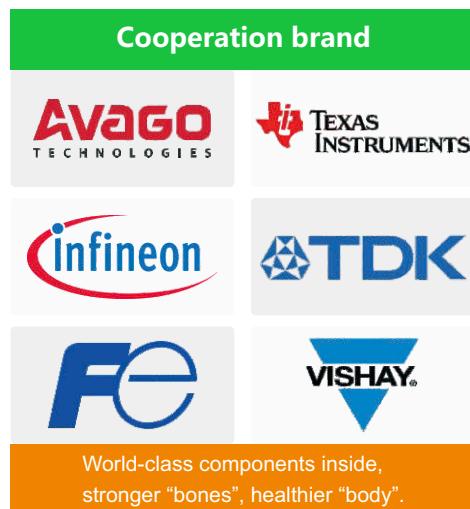
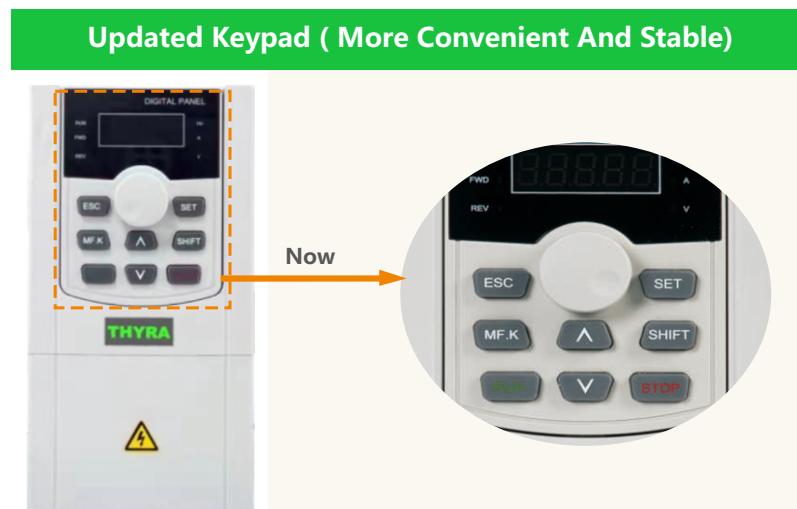
### External Switch



External Start Button, P0-02=1,P4-00=1  
External Stop Button,P4-02=3,P4-11=2

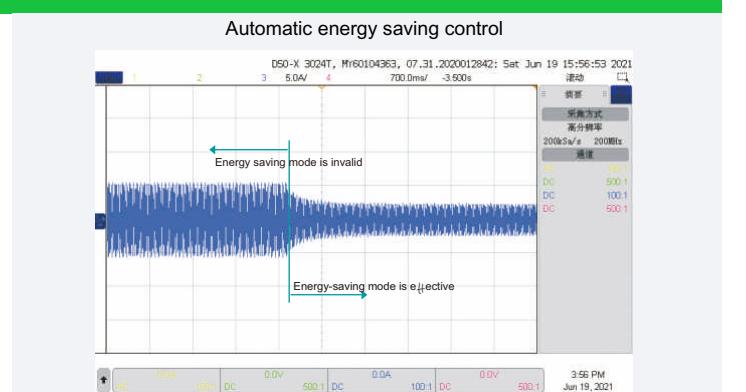


## ❖ DRIVE DESIGN & FEATURES



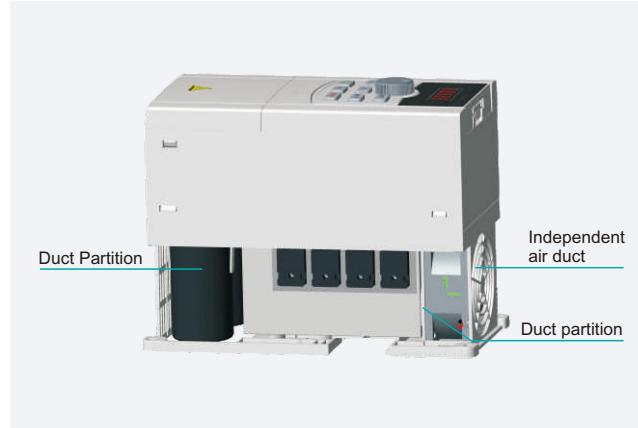
### Energy-saving operation of fans and pumps

With excellent automatic energy-saving function, you only need to set the maximum energy-saving target, as long as the operation meets the energy-saving conditions, you can enter the automatic energy-saving state. By setting the VF function, one-to-multiple and long-distance control applications can be realized to meet the application of transformation occasions.



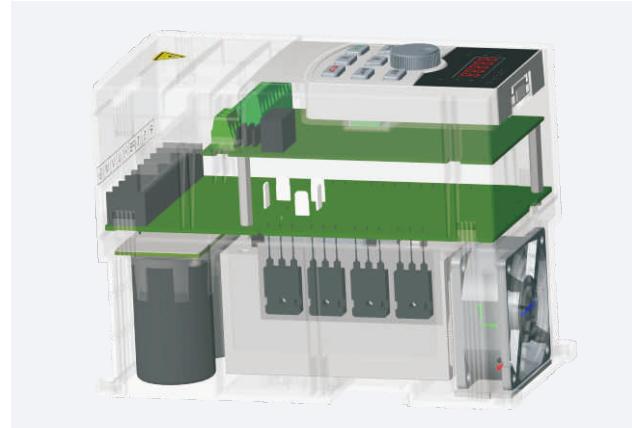


## HIGH PERFORMANCE



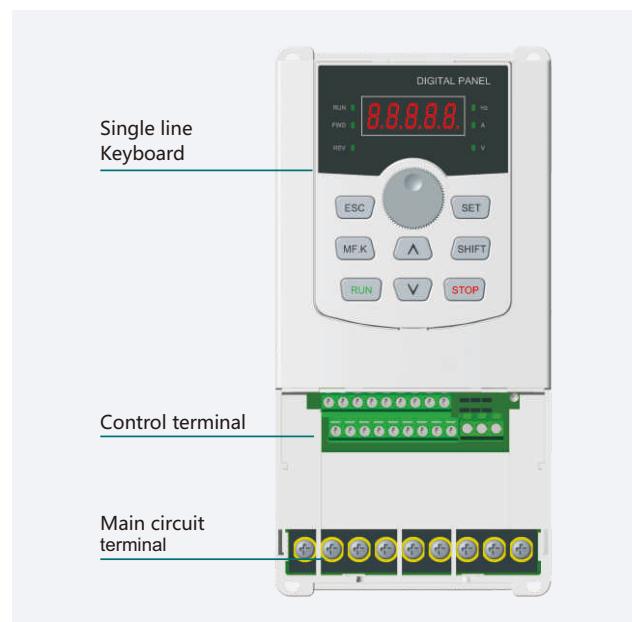
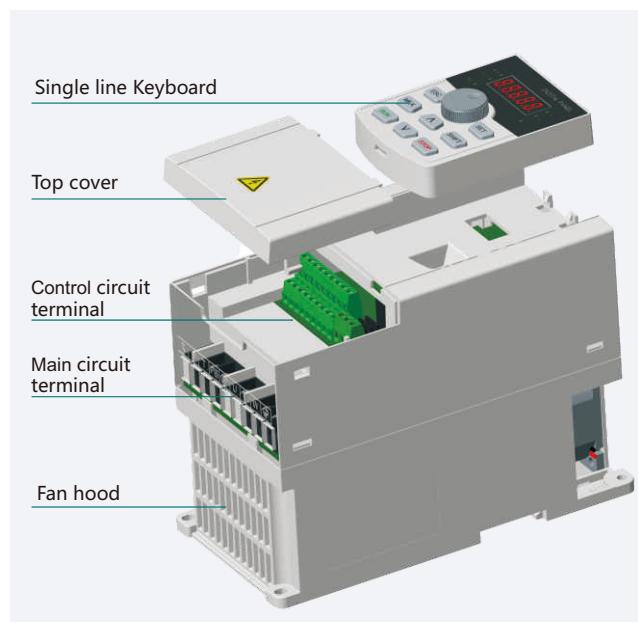
### Independent air duct design

- High protection: completely independent air duct, scientific layout inside the machine, taking into account the heat dissipation of high-power devices.
- The machine has the characteristics of high temperature resistance: scientific air duct design, rapid heat dissipation, low temperature rise of the machine, and no need to reduce the capacity under the ambient temperature of 50 °C.

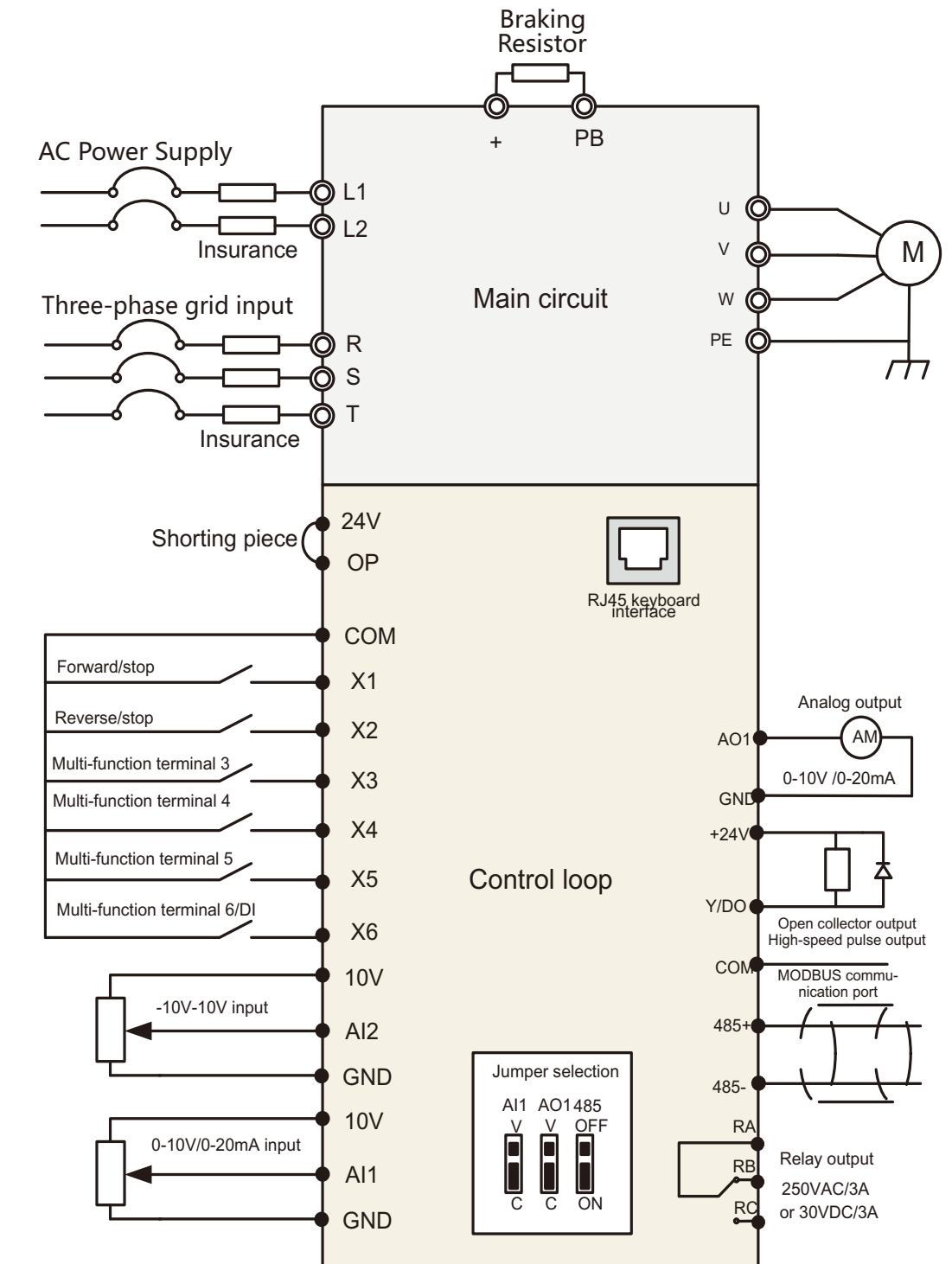


### Layered structure design

- The electrical part is separated from the cooling air duct layer by layer, and each part is independent, which can effectively deal with the dust problem of circuit boards and sensitive devices.



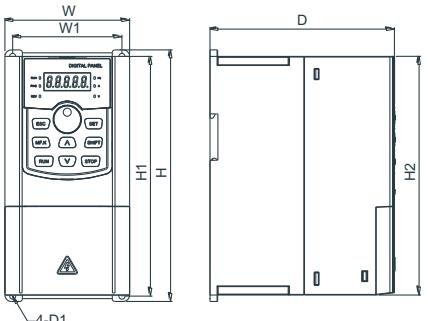
## BASIC WIRING DIAGRAM





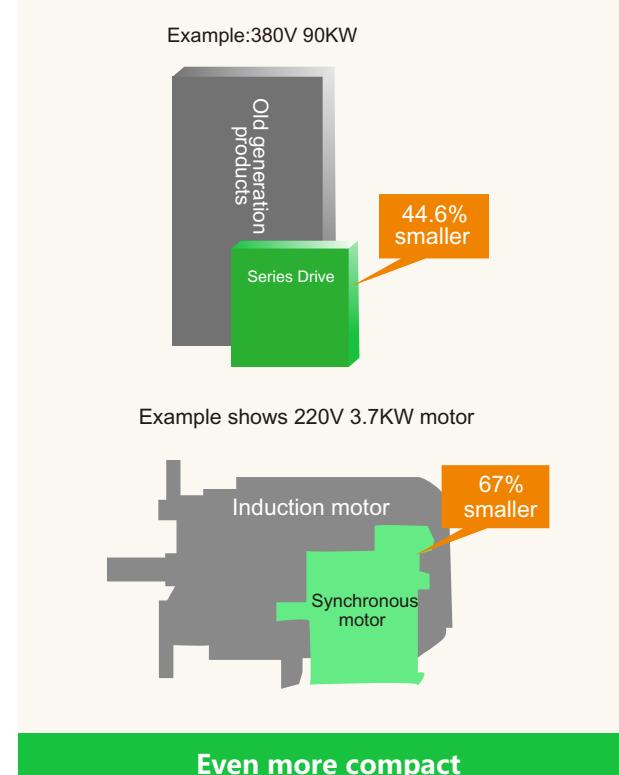
## TECHNICAL SPECIFICATION

Model	External and installation dimensions (mm)						Pore size	Weight (kg)
	W1	H1	H	H2	W	D		
CT10M-2S-0.7G	67.5	160	170	----	84.5	129	Φ 4.5	1.0
CT10M-2S-1.5G								
CT10M-4T-1.5G								
CT10M-4T-2.2G								
CT10M-2S-2.2G	85	185	194	----	97	143.5	Φ 5.5	1.4
CT10M-2S-4.0G								
CT10M-4T-4.0G								
CT10M-4T-5.5G								
CT10M-2T-5.5G	106	233	245	----	124	171.2	Φ 5.5	2.5
CT10M-4T-7.5G								
CT10M-4T-11G								
CT10M-2T-7.5G								
CT10M-2T-11G								
CT10M-4T-15G	120	317	335	----	200	178.2	Φ 8	8.4
CT10M-4T-18.5G								
CT10M-4T-22G								
CT10M-2T-15G								
CT10M-2T-18.5G								
CT10M-4T-30G	150	387.5	405	----	255	195	Φ 8	12.8
CT10M-4T-37G								
CT10M-2T-22G								
CT10M-2T-30G								
CT10M-4T-45G	180	437	455	----	300	225	Φ 10	17.8
CT10M-4T-55G								
CT10M-4T-75G								
CT10M-4T-90G	260	750	785	----	395	291	Φ 12	50
CT10M-4T-110G								
CT10M-4T-132G								
CT10M-4T-160G	360	950	990	----	500	368	Φ 14	88
CT10M-4T-185G								
CT10M-4T-200G								
CT10M-4T-220G								
CT10M-4T-250G	400	1000	1040	----	650	406	Φ 14	123
CT10M-4T-280G								
CT10M-4T-315G								
CT10M-4T-355G								
CT10M-4T-400G	600	1250	1300	----	815	428	Φ 14	165



- With inside EMC filter and building-block design for IO extension card and different kinds of PG card;
- Top performance in our industry which represent in torque in less than 1Hz 0.5Hz 0.25Hz 0.1Hz and 0Hz that it can compare with any domestic chinese brand for output torque;
- Smooth running and stability;
- Low noise on motor and fast response for 0.1S acceleration and deceleration without dead zone;
- Reverse and forward free switching;
- Sleeping function and energy saving function as well as in built PLC programming;
- Accurate and constant torque mode control;
- Support two group motor parameters which can realize two motor switching control;
- 220V single phase /three phase input and three phase output.

## DRIVE DESIGN & FEATURES

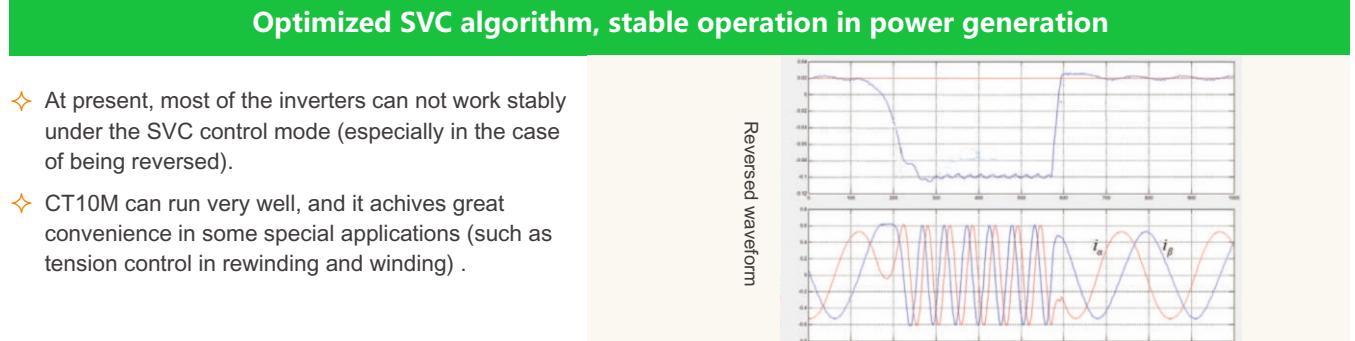
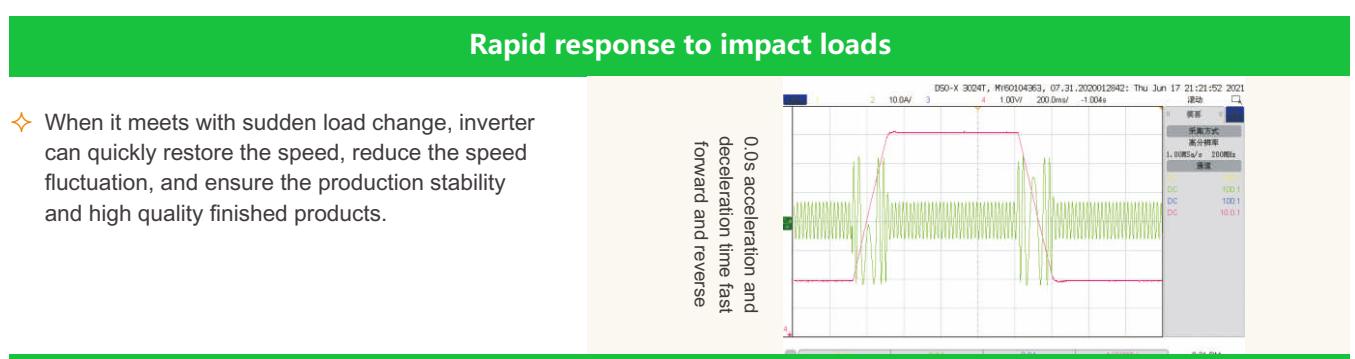
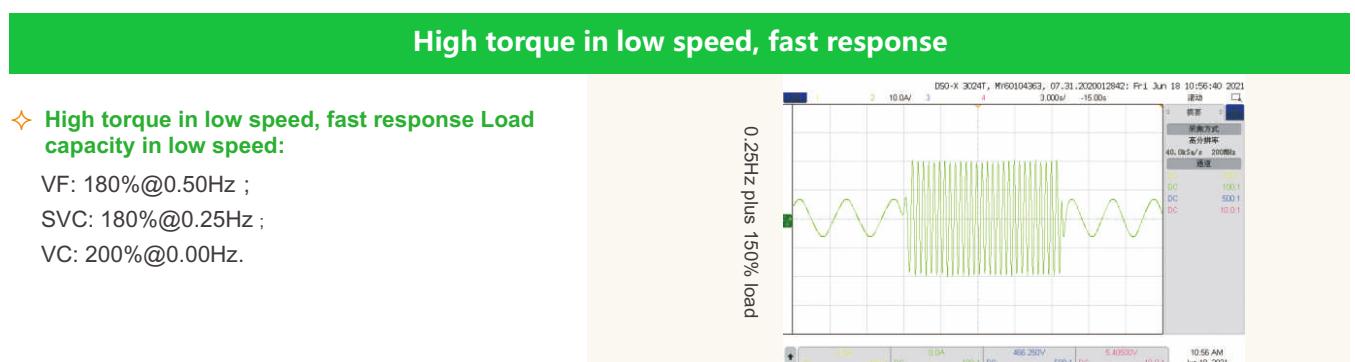
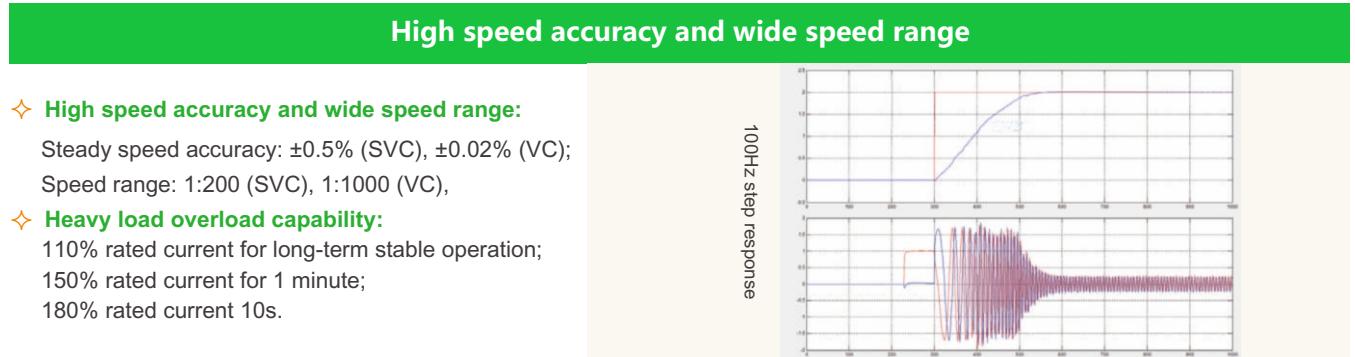


- Continues to make applications even smaller by combining the compact designed drive with the light, efficient design of a synchronous motor.
- Use Side-by-Side installation for an even more compact setup.
- Finless models available.

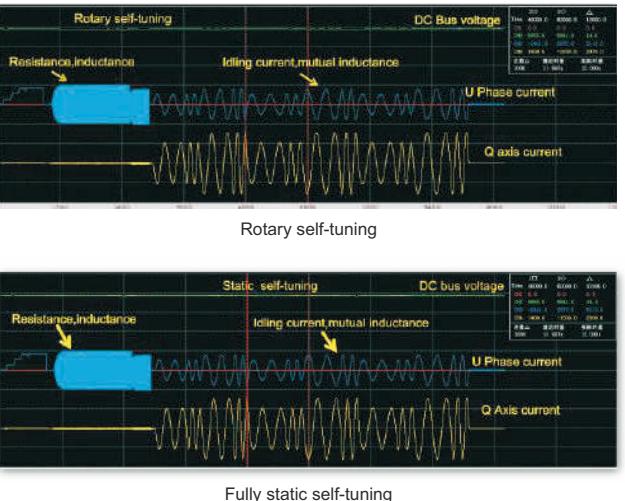




## ◆ DRIVE DESIGN & FEATURES

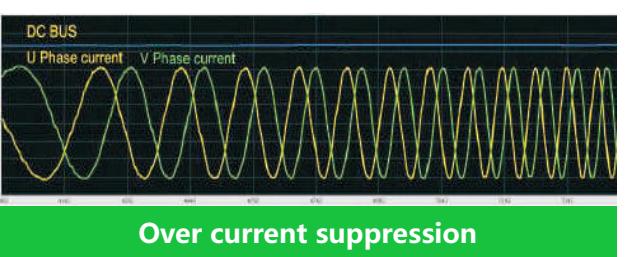


## ◆ PERFORMANCE FEATURES



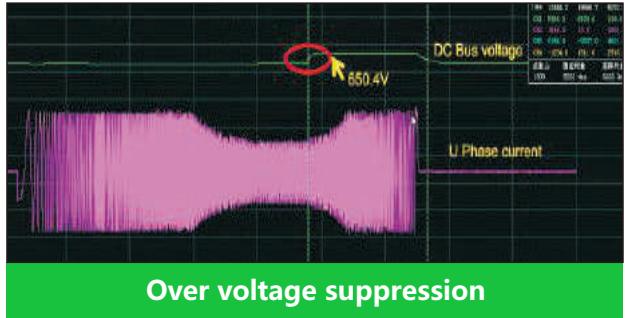
### Self-tuning of motor parameters

- ◇ It could accurately acquire the motor parameters both in rotary and static self-tuning, so as to provide higher control accuracy and response speed, which is convenient and simple.
- ◇ **Rotary self-tuning:** Must unload the motor. Suit for applications with higher requirement of control accuracy.
- ◇ **Fully static self-tuning:** Leading motor tuning algorithm, can acquire the motor parameters in static status, which is comparable to the rotary self-tuning.

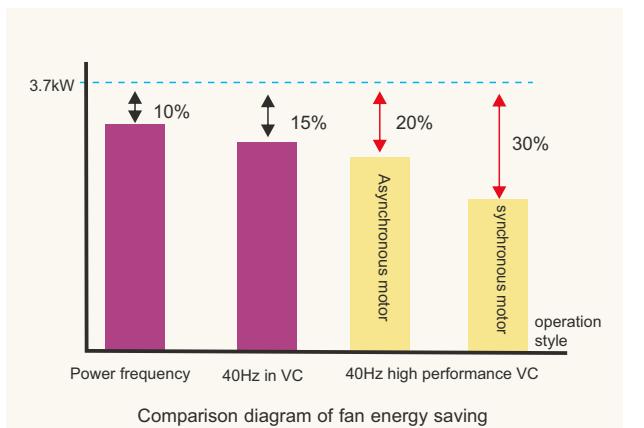


### Over current suppression

The current suppression function could avoid the frequent OC fault of inverter. While the current is over the current protection point, it could continuously limit the current below the protection point, so as to protect devices, prevent the overcurrent fault caused by sudden load or interference and reduce the loss caused by stop without reason.



The overvoltage suppression function could prevent inverter from overvoltage fault in ACC/DEC process. During ACC/DEC, if the bus voltage of inverter reaches or exceeds the overvoltage protection point, the overvoltage suppression function could suppress the rising of bus voltage by automatically adjust the operation frequency, so as to protect the devices and avoid the overvoltage fault caused by the rising of bus voltage.



### Excellent energy-saving functions

Adopt the new generation of energy-saving control technology to realize the high-efficiency operation of induction motor; reduce the excitation current according to the load current, and automatically adjust according to the loading condition; improve the motor efficiency at most; reduce the motor consumption and energy consumption. 30% of AM&PMSM adopt the VC mode to drive PMSM and the energy utilization could increase by more than 10%.



## APPLICATIONS



Printing Dyeing



Wire Drawing Mchine



Water Supply



Packing Machiine



Industrial Washing Machine



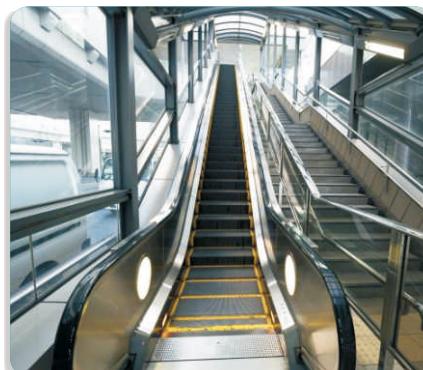
Construction Hoist



Ball Mill



Air Compressor



Escalator



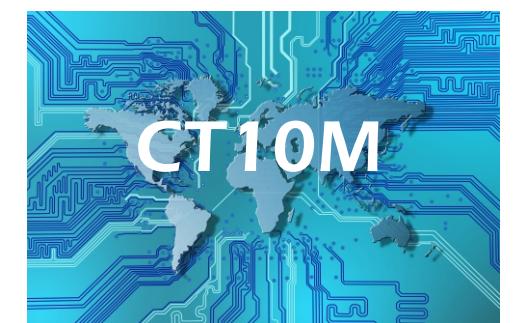
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