

Department of Electrical Engineering  
IIT Hyderabad



## **EE 6340/3801** **Wireless Communications**

**Channel**

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### Lecture 5 Outline

- **Announcements**
  - TA: **ANNU SURAJPU**, [ee21resch01010@iith.ac.in](mailto:ee21resch01010@iith.ac.in)
- Review of Last Lecture
  - **Doppler**
  - **Introduction to Wideband Channel**
- Today's lecture
  - **Wideband Channel**
  - **Scattering Function**
  - **Multipath Intensity Profile**
  - **Doppler Power Spectrum**

## Narrowband Model

$$r(t) = \Re\{v(t)e^{j(2f_c t + \phi_0)}\} \\ = \Re\left\{\left[\frac{\lambda\sqrt{G}e^{-j2\pi d/\lambda}}{4\pi d}u(t) + n(t)\right]e^{j(2f_c t + \phi_0)}\right\}$$

- Assume **delay spread**  $\max_{m,n} |\tau_n(t) - \tau_m(t)| \ll 1/B$
- Then  $u(t-\tau) \approx u(t)$ .
- Received signal given by

$$r(t) = \Re\left\{u(t)e^{j(2f_c t + \phi_0)} \left[\sum_{n=0}^{N(t)} \alpha_n(t)e^{-j\phi_n(t)}\right] + n(t)e^{j(2f_c t + \phi_0)}\right\}$$

- No signal distortion (spreading in time)
- Multipath affects complex scale factor in brackets.
- Characterize scale factor by setting  $u(t) = e^{j\phi_0}$ : or 1

$$s(t) = \Re\{e^{j2\pi f_c t}\} = \cos 2\pi f_c t,$$

## NarrowBand Channel Model

- The received signal

$$r(t) = \Re\left\{\left[\sum_{n=0}^{N(t)} \alpha_n(t)e^{-j\phi_n(t)}\right] e^{j2\pi f_c t}\right\}$$

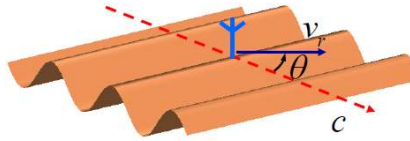
$$= r_I(t) \cos 2\pi f_c t + r_Q(t) \sin 2\pi f_c t,$$

$$r_I(t) = \sum_{n=1}^{N(t)} \alpha_n(t) \cos \phi_n(t),$$

$$r_Q(t) = \sum_{n=1}^{N(t)} \alpha_n(t) \sin \phi_n(t).$$

For large  $N(t)$ ,  $r_I(t)$  and  $r_Q(t)$  **jointly Gaussian** by CLT

# Doppler



Receiving antenna moves with speed  $v_r$  at an angle  $\theta$  relative to the propagation direction of the incoming wave, which has frequency  $f_c$ .

Frequency of received signal:

$$f = f_c + v$$

where the Doppler shift is

$$v = -f_c \frac{v_r}{c} \cos(\theta)$$

The maximal Doppler shift is

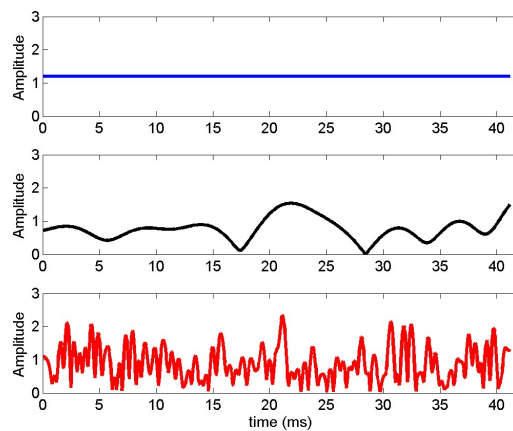
$$v_{\max} = f_c \frac{v}{c}$$

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## FADING: DOPPLER

- At given frequency

–  $v \uparrow \rightarrow f_D \uparrow \rightarrow$  channel changes more rapidly

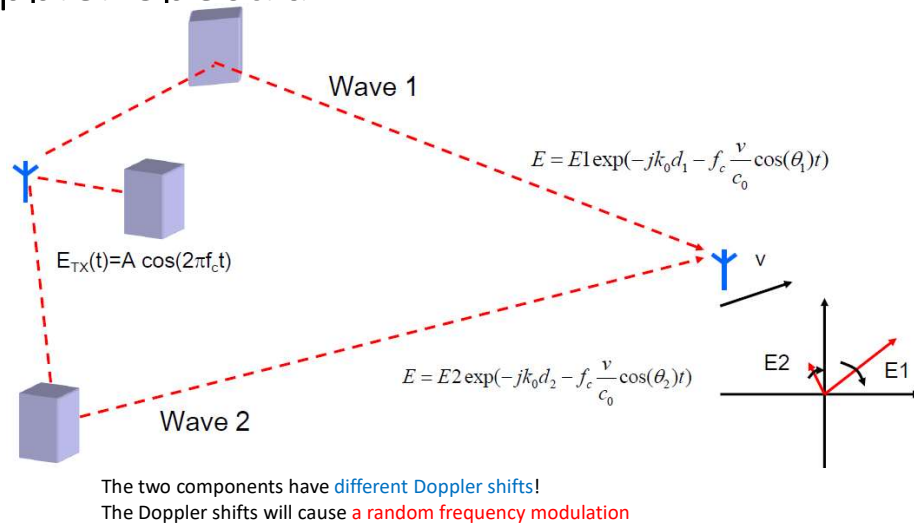


$f_D = 0 \text{ Hz}$

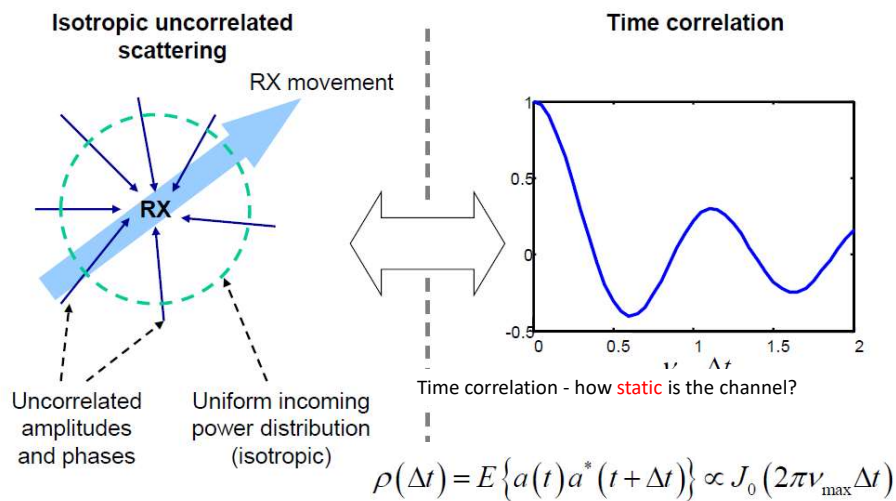
$f_D = 100 \text{ Hz}$

$f_D = 1000 \text{ Hz}$

## Doppler Spectra



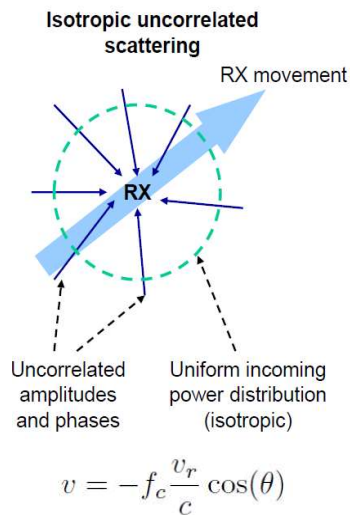
## Doppler Spectrum



## Doppler Spectrum

*Jakes* Model

A MPC arriving in the **direction**  $\theta$  has to be multiplied by the **pattern**  $G(\theta)$



$$S(\theta) = \overline{\Omega} [pdf_{\theta}(\theta)G(\theta) + pdf_{\theta}(-\theta)G(-\theta)]$$

Change of variable from  $\theta$  to  $v$

$$\left| \frac{d\theta}{dv} \right| = \left| \frac{1}{\frac{dv}{d\theta}} \right| = \frac{1}{|v_{max} \sin \theta|} = \frac{1}{\sqrt{v_{max}^2 - v^2}}$$

Using  $pdf(\theta) = 1/2\pi$  and  $G(\theta)=1.5$

$$S_D(v) \propto \frac{1}{\pi \sqrt{v_{max}^2 - v^2}}$$

## Coherence Time

- Coherence time is the time domain **dual** of **Doppler spread**
- Used to characterize the **time varying nature** of the frequency **dispersiveness** of the channel in the time domain.
- The Maximum Doppler spread and coherence time are inversely proportional to one another

$$T_c \approx \frac{0.4}{v_{max}}$$

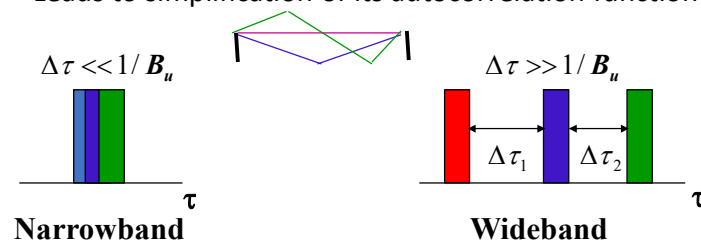
- **Slow fading** arises when the  $T_c \gg$  the delay requirement of the application. The channel can be considered roughly constant over the period of use.
- **Fast fading** occurs when the  $T_c \ll$  relative to the delay requirement of the application.

# Wideband Channels

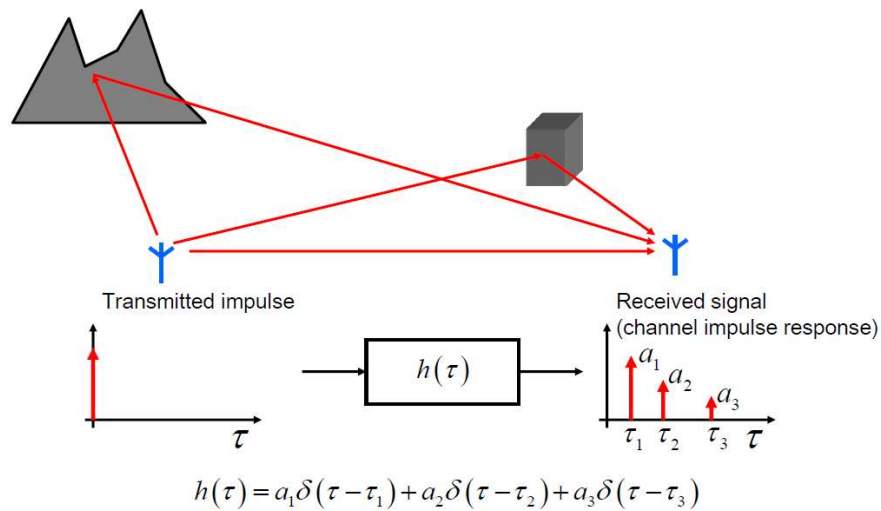
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## Wideband Channels

- Individual multipath components resolvable
- True when time difference between components exceeds signal bandwidth
- Requires statistical characterization of  $h(\tau, t)$ 
  - Assume CLT, stationarity and uncorrelated scattering
  - Leads to simplification of its autocorrelation function



## Delay dispersion: A simple case



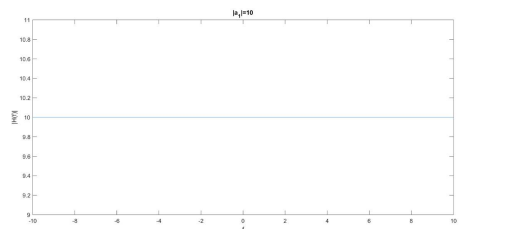
## Effect of No Delay Dispersion: Frequency Flat Fading

- Single Path:

$$h(\tau) = a_1\delta(\tau - \tau_1)$$

Taking Fourier Transform, we have

$$H(f) = \int_{-\infty}^{\infty} h(\tau)e^{-j2\pi f\tau} d\tau$$



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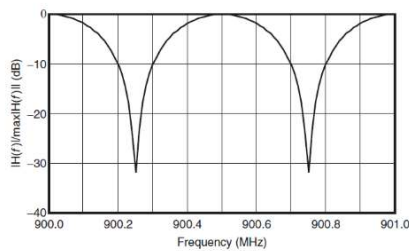
## Effect of Delay Dispersion: Frequency Selective Fading

- Two Path:

$$h(\tau) = a_1 \delta(\tau - \tau_1) + a_2 \delta(\tau - \tau_2)$$

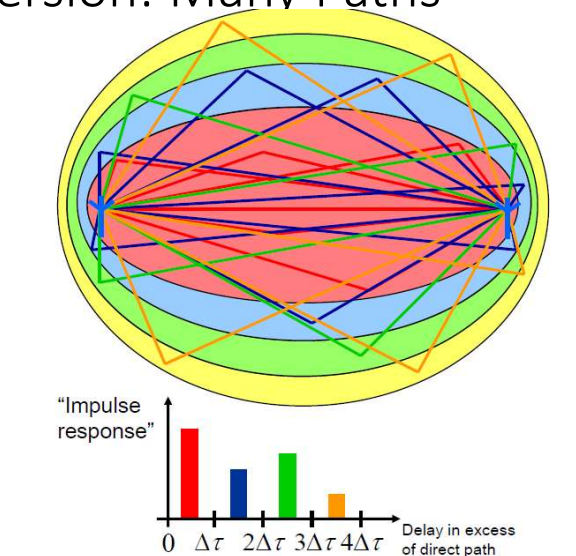
Taking Fourier Transform, we have  $H(f) = \int_{-\infty}^{\infty} h(\tau) e^{-j2\pi f \tau} d\tau$   
 $= a_1 e^{-j2\pi f \tau_1} + a_2 e^{-j2\pi f \tau_2}$

$$|H(f)| = \sqrt{|a_1|^2 + |a_2|^2 + 2|a_1||a_2|\cos\{2\pi f \Delta\tau - \Delta\phi\}}$$



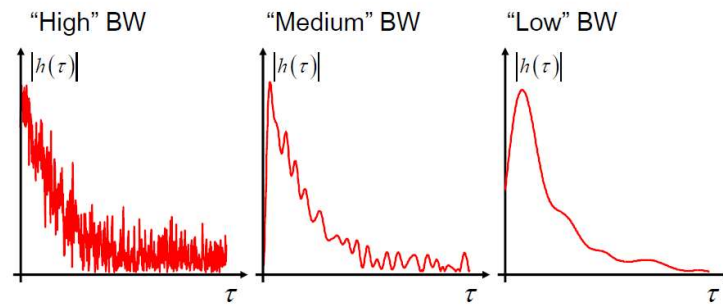
$|a_1| = 1.0$ ,  $|a_2| = 0.95$ ,  $\Delta\phi = 0$ ,  
 $\tau_1 = 4\mu\text{s}$ ,  $\tau_2 = 6\mu\text{s}$  at the 900-MHz carrier frequency

## Delay Dispersion: Many Paths

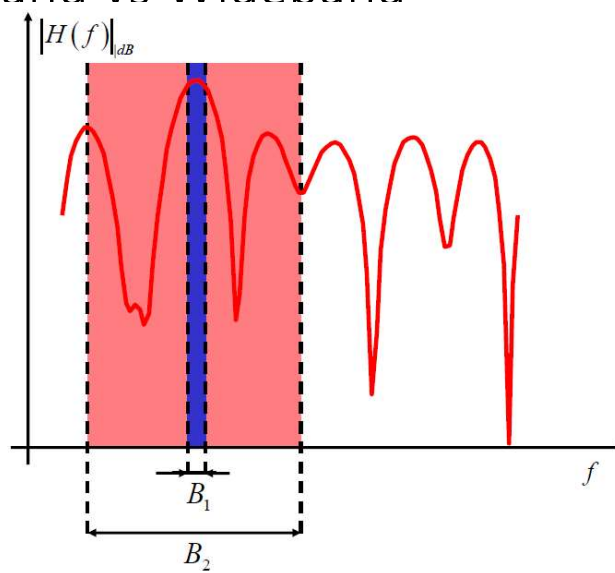




## Narrowband vs Wideband



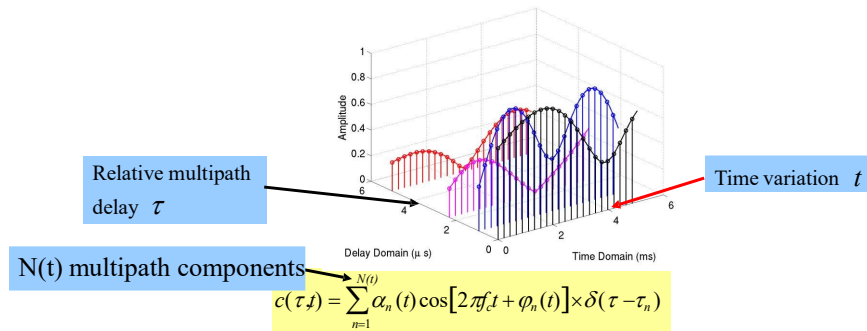
## Narrowband vs Wideband



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## FADING: IMPULSE RESPONSE

- The impulse response of fading is time-varying!



- $f_c$ : system operating frequency (e.g. 900MHz, 1.8GHz)
- $t$ : the time variation (both amplitude and phase changes with respect to time)
- $\tau$ : relative delay between multipath components
- $\varphi_n(t)$ : depends on path distance and Doppler shift ( $2\pi f_D t$ )

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## FADING: IMPULSE RESPONSE

- Complex baseband representation

$$\begin{aligned} c(t, \tau) &= \sum_{n=1}^N \alpha_n(t) \operatorname{Re} \left[ e^{j2\pi f_c t + \varphi_n(t)} \right] \times \delta(\tau - \tau_n) \\ &= \operatorname{Re} \left\{ e^{j2\pi f_c t} \left[ \sum_{n=1}^N \alpha_n(t) e^{j\varphi_n(t)} \times \delta(\tau - \tau_n) \right] \right\} \\ h(\tau, t) &= \sum_{n=1}^N \alpha_n(t) e^{j\varphi_n(t)} \times \delta(\tau - \tau_n) \end{aligned}$$

- Maximum delay spread

- The time interval between the first multipath and the last multipath

$$\tau_{\max} = \tau_N - \tau_1$$

## Time Varying Impulse Response

- Response of channel at  $t$  to impulse at  $t-\tau$ :

$$h(\tau, t) = \left( \sum_{n=0}^{N(t)} \alpha_n(t) e^{-j\phi_n(t)} \delta(\tau - \tau_n(t)) \right)$$

$$\phi_n(t) = 2\pi f_c \tau_n(t) - \phi_{D_n} - \phi_0$$

- $t$  is time when impulse response is observed
- $t-\tau$  is time **when impulse put into the channel**
- $\tau$  is **how long ago impulse** was put into the channel for **the current observation**
  - path delay for MP component currently observed

## In-Phase and Quadrature under CLT Approximation

- In phase and quadrature signal components:

$$r_I(t) = \sum_{n=0}^{N(t)} \alpha_n(t) e^{-j\phi_n(t)} \cos(2\pi f_c t),$$

$$r_Q(t) = \sum_{n=0}^{N(t)} \alpha_n(t) e^{-j\phi_n(t)} \sin(2\pi f_c t)$$

- For  $N(t)$  large,  $r_I(t)$  and  $r_Q(t)$  jointly Gaussian by CLT (sum of large # of random vars).
- Received signal characterized by its mean, autocorrelation, and cross correlation.
- If  $\phi_n(t)$  uniform, the in-phase/quad components are mean zero, independent, and stationary.

## Auto and Cross Correlation

- Assume  $\phi_n \sim U[0, 2\pi]$
- Recall that  $\theta_n$  is the **multipath arrival angle**
- Autocorrelation of inphase/quad signal is

$$A_{r_I}(\tau) = A_{r_Q}(\tau) = PE_{\theta_n}[\cos 2\pi f_{D_n}\tau], \quad f_{D_n} = v \cos \theta_n / \lambda$$

- Cross Correlation of inphase/quad signal is

$$A_{r_I, r_Q}(\tau) = PE_{\theta_n}[\sin 2\pi f_{D_n}\tau] = -A_{r_I, r_Q}(\tau)$$

- Autocorrelation of received signal is

$$A_r(\tau) = A_{r_I}(\tau) \cos(2\pi f_c \tau) - A_{r_I, r_Q}(\tau) \sin(2\pi f_c \tau)$$

## Cross Correlation

- Cross Correlation of inphase/quad signal is

$$r_I(t) = \sum_{n=0}^{N(t)} \alpha_n(t) e^{-j\phi_n(t)} \cos(2\pi f_c t), \quad r_Q(t) = \sum_{n=0}^{N(t)} \alpha_n(t) e^{-j\phi_n(t)} \sin(2\pi f_c t), \quad \phi_n \sim U[0, 2\pi]$$

- Thus,  $A_{r_I, r_Q}(0) = 0$  so  $r_I(t)$  and  $r_Q(t)$  independent

- Autocorrelation of received signal is

$$A_{r_I, r_Q}(\tau) = E[r_I(t)r_Q(t+\tau)] = P_r E_{\theta_n}[\sin 2\pi f_{D_n}\tau] = -A_{r_I, r_Q}(\tau)$$

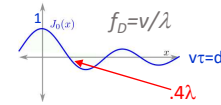
- Thus,  $r(t)$  is stationary (WSS)

$$A_r(\tau) = A_{r_I}(\tau) \cos(2\pi f_c \tau) - A_{r_I, r_Q}(\tau) \sin(2\pi f_c \tau)$$

## Uniform AOAs

- Under uniform scattering, in phase and quad comps have no cross correlation and autocorrelation is

$$A_{r_I}(\tau) = A_{r_Q}(\tau) = P_r J_0(2\pi f_D \tau)$$



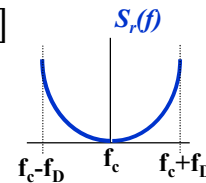
*Decorrelates over roughly half a wavelength*

- The PSD of received signal is

$$S_r(f) = .25[S_{r_I}(f - f_c) + S_{r_I}(f + f_c)]$$

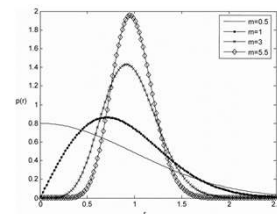
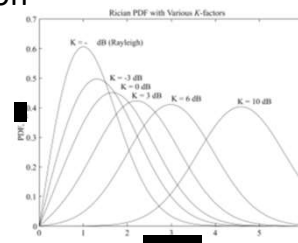
$$S_{r_I}(f) = \mathcal{F}[P_r J_0(2\pi f_D \tau)]$$

*Used to generate simulation values*



## Signal Envelope Distribution

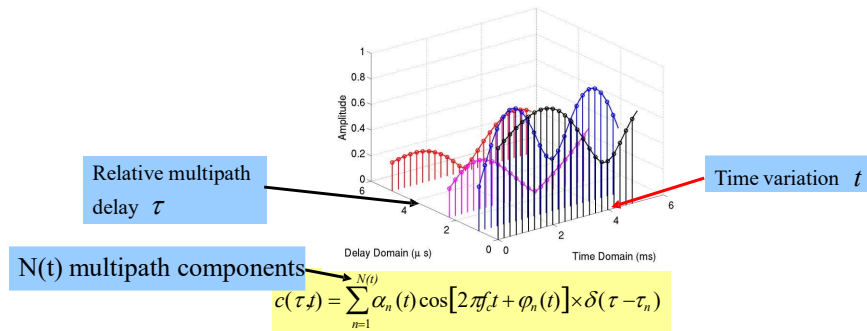
- CLT approx. leads to Rayleigh distribution (power is exponential)
- When LOS component present, Rician distribution is used
- Measurements support Nakagami distribution in some environments
  - Similar to Rician, but models "worse than Rayleigh"
  - Lends itself better to closed form BER expressions



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## FADING: IMPULSE RESPONSE

- The impulse response of fading is time-varying!

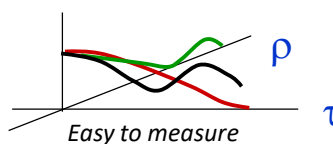


- $f_c$ : system operating frequency (e.g. 900MHz, 1.8GHz)
- $t$ : the time variation (both amplitude and phase changes with respect to time)
- $\tau$ : relative delay between multipath components
- $\varphi_n(t)$ : depends on path distance and Doppler shift ( $2\pi f_D t$ )

## Scattering Function

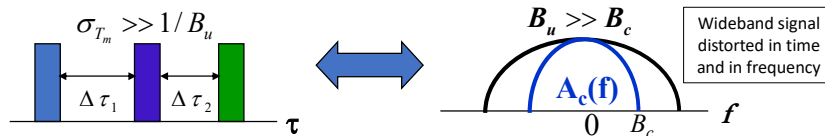
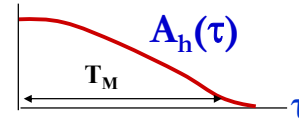
- Typically characterize  $h(\tau, t)$  by its statistics, since it is a random process
- Underlying process WSS and Gaussian, so only characterize mean (0) and correlation
- Autocorrelation is  $A_c(\tau_1, \tau_2, \Delta t) = A_c(\tau, \Delta t)$ 
  - Correlation for single mp delay/time difference
- Statistical scattering function:
  - Average power for given mp delay and doppler

$$s(\tau, \rho) = F_{\Delta t}[A_c(\tau, \Delta t)]$$



## Multipath Intensity Profile

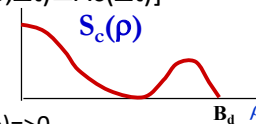
- Defined as  $A_h(\tau, \Delta t=0) = A_h(\tau)$ 
  - Determines **average** ( $\mu_{T_m}$ ) and **rms** ( $\sigma_{T_m}$ ) **delay spread**
  - Approximates maximum delay of significant multipath
- Coherence bandwidth  $B_c = 1/\sigma_{T_m}$ 
  - Maximum frequency over which  $A_c(\Delta f) = F[A_c(\tau)] > 0$
  - $A_c(\Delta f) = 0$  implies signals separated in freq. by  $\Delta f$  will be **uncorrelated** after going through channel: freq. distortion



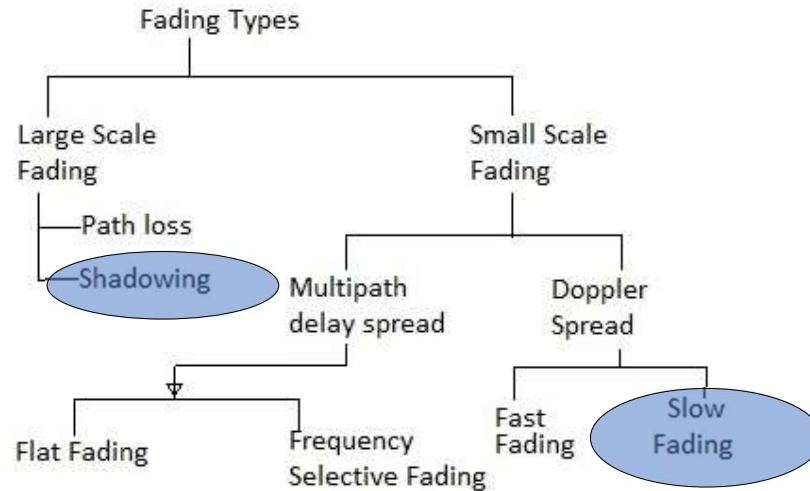
## Doppler Power Spectrum

Scattering Function:  $s(\tau, \rho) = \mathcal{F}_{\Delta t}[A_c(\tau, \Delta t)]$

- Doppler Power Spectrum:  $S_c(\rho) = \mathcal{F}_{\Delta t}[A_c(\Delta f=0, \Delta t) \triangleq A_c(\Delta t)]$   
 $A_c(\Delta f, \Delta t) = \mathcal{F}_{\tau}[A_c(\tau, \Delta t)]$ 
  - Power of multipath at given Doppler
  - Doppler spread**  $B_d$ : Max. doppler for which  $S_c(\rho) > 0$ .
  - Coherence time  $T_c = 1/B_d$ : Max time over which  $A_c(\Delta t) > 0$ 
    - $A_c(\Delta t) = 0 \Rightarrow$  signals separated in time by  $\Delta t$  uncorrelated after passing through channel
- Why do we look at Doppler w.r.t.  $A_c(\Delta f=0, \Delta t)$ ?
  - Captures Doppler associated with a narrowband signal
  - Autocorrelation over a narrow range of frequencies
  - Fully captures time-variations, multipath angles of arrival



## Fading Summary



## Main Points

- **Narrowband model** has in-phase and quad. comps that are zero-mean stationary Gaussian processes
  - Auto and cross correlation depends on AOA of multipath
- **Uniform scattering** makes autocorrelation of inphase and quad comps of RX signal follow Bessel function
  - Signal components decorrelate over half wavelength
  - The PSD has a bowl shape centered at carrier frequency
- Fading distribution depends on environment
  - Rayleigh, Rician, and Nakagami all common
- **Wideband channels** have resolvable multipath
  - Will statistically characterize  $c(\tau, t)$  for WSSUS model



## Main Points

- Wideband channels have resolvable multipath
  - Statistically characterize  $h(\tau, t)$  for WSSUS model
  - Scattering function characterizes rms delay and Doppler spread. Key parameters for system design.
- Delay spread defines maximum delay of significant multipath components. Inverse is coherence BW
  - Signal distortion in time/freq. when delay spread exceeds inverse signal BW (signal BW exceeds coherence BW)
- Doppler spread defines maximum nonzero doppler, its inverse is coherence time
  - Channel decorrelates over channel coherence time