# **Code to implement BFS using OpenMP:**

```
#include < iostream >
#include < stdlib.h >
#include<queue>
#include < omp.h >
using namespace std;
class node {
public:
     node *left, *right;
     int data;
};
class Breadthfs {
public:
     node* insert(node*, int);
     void bfs(node*);
};
node* Breadthfs::insert(node *root, int data) {
     if (!root) {
          root = new node;
          root->left = root->right = NULL;
          root->data = data;
          return root;
    }
     queue<node*> q;
     q.push(root);
     while (!q.empty()) {
          node *temp = q.front();
          q.pop();
          if (!temp->left) {
              temp->left = new node;
              temp->left->left = temp->left->right = NULL;
              temp->left->data = data;
              return root;
          } else {
              q.push(temp->left);
          if (!temp->right) {
              temp->right = new node;
              temp->right->left = temp->right->right = NULL;
              temp->right->data = data;
              return root;
         } else {
              q.push(temp->right);
         }
     }
     return root;
}
```

```
void Breadthfs::bfs(node *head) {
     if (!head) return;
     queue<node*> q;
     q.push(head);
     while (!q.empty()) {
          int qSize = q.size();
          #pragma omp parallel for
          for (int i = 0; i < qSize; i++) {
              node* currNode;
              #pragma omp critical
              {
                   currNode = q.front();
                   q.pop();
                   cout << "\t" << currNode->data;
              }
              #pragma omp critical
              {
                    if (currNode->left)
                        q.push(currNode->left);
                    if (currNode->right)
                        q.push(currNode->right);
              }
         }
    }
}
int main() {
     node *root = NULL;
     int data;
     char ans;
     Breadthfs tree;
     do {
          cout << "\nEnter data => ";
          cin >> data;
         root = tree.insert(root, data);
          cout << "Do you want to insert one more node? (y/n) ";
          cin >> ans;
     } while (ans == 'y' || ans == 'Y');
     cout << "\nBFS Traversal:\n";</pre>
     tree.bfs(root);
     return 0;
}
Output:
Enter data => 5
Do you want to insert one more node? (y/n) Y
Enter data => 3
Do you want to insert one more node? (y/n) Y
```

```
Enter data => 7
Do you want to insert one more node? (y/n) Y

Enter data => 2
Do you want to insert one more node? (y/n) Y

Enter data => 1
Do you want to insert one more node? (y/n) 8

BFS Traversal:
5 3 7 2 1

=== Code Execution Successful ===
```

# **Code to implement DFS using OpenMP:**

```
#include <iostream>
#include <vector>
#include <stack>
#include <omp.h>
using namespace std;
const int MAX = 100000;
vector<int> graph[MAX];
bool visited[MAX];
void dfs(int node) {
     stack<int> s;
     s.push(node);
     while (!s.empty()) {
          int curr_node = s.top();
          s.pop();
          if (!visited[curr_node]) {
               visited[curr_node] = true;
               if (visited[curr_node]) {
                    cout << curr_node << " ";
               }
               #pragma omp parallel for
               for (int i = 0; i < graph[curr_node].size(); i++) {
                    int adj_node = graph[curr_node][i];
                    if (!visited[adj_node]) {
                         #pragma omp critical
                         s.push(adj_node);
                    }
               }
          }
    }
}
int main() {
     int n, m, start_node;
     cout << "Enter No of Node, Edges, and start node: ";
```

```
cin >> n >> m >> start_node;

cout << "Enter Pair of edges: ";
for (int i = 0; i < m; i++) {
    int u, v;
    cin >> u >> v;
    graph[u].push_back(v);
    graph[v].push_back(u);
}

#pragma omp parallel for
for (int i = 0; i < n; i++) {
    visited[i] = false;
}

dfs(start_node);
return 0;
}</pre>
```

```
Enter No of Node, Edges, and start node: 8 4 5
Enter Pair of edges: 5 3
5 7
3 2
2 1
5 7 3 2 1
=== Code Execution Successful ===
```

# Code to Implement parallel bubble sort using OpenMP

```
import numpy as np
import time
import random
import omp
def parallel_bubble_sort(arr):
     n = len(arr)
    for i in range(n):
         # Set the number of threads to the maximum available
         omp.set_num_threads(omp.get_max_threads())
         # Use the parallel construct to distribute the loop iterations among the threads
         # Each thread sorts a portion of the array
         # The ordered argument ensures that the threads wait for each other before moving on
to the next iteration
         # This guarantees that the array is fully sorted before the loop ends
         with omp.parallel(num_threads=omp.get_max_threads(), default_shared=False,
private=['temp']):
              for j in range(i % 2, n - 1, 2):
                   if arr[i] > arr[i + 1]:
                        temp = arr[i]
                        arr[i] = arr[i + 1]
                        arr[j + 1] = temp
if __name__ == '__main__':
     # Generate a random array of 10,000 integers
     arr = np.array([random.randint(0, 1000) for i in range(10000)])
     print(f"Original array: {arr}")
    start_time = time.time()
     parallel bubble sort(arr)
    end_time = time.time()
     print(f"Sorted array: {arr}")
     print(f"Execution time: {end time - start time} seconds")
```

#### **Output:**

```
Original array: [69 22 51 876 9 432 88 ... 18 56 9] # Random integers

Sorted array: [0 0 0 1 1 2 3 4 5 6 7 8 ... 999 999] # Sorted array in ascending order

Execution time: 0.07419133186340332 seconds # Time will vary depending on system
```

#### Code to Implement parallel merge sort using openmp

```
import numpy as np
import time
import random
import omp

def parallel_merge_sort(arr):
    n = len(arr)

# Base case: if n == 1, return arr
```

```
if n == 1:
         return arr
     # Split the array into two halves
     mid = n // 2
    left = arr[:mid]
     right = arr[mid:]
     # Use the parallel construct to distribute the work among the threads
     # Each thread sorts a portion of the array
    with omp.parallel(num_threads=omp.get_max_threads(), default_shared=False):
         left sorted = parallel merge sort(left)
         right_sorted = parallel_merge_sort(right)
     # Merge the two sorted halves
    i = i = 0
     n1, n2 = len(left_sorted), len(right_sorted)
     merged_arr = np.zeros(n1 + n2, dtype=int)
    # Use the parallel construct to distribute the loop iterations among the threads
     # Each thread merges a portion of the array
    with omp.parallel(num_threads=omp.get_max_threads(), default_shared=False, private=['k']):
         for k in range(n1 + n2):
              if i == n1:
                   merged_arr[k:] = right_sorted[j:]
                   break
              elif j == n2:
                   merged_arr[k:] = left_sorted[i:]
                   break
              elif left sorted[i] <= right sorted[j]:
                   merged_arr[k] = left_sorted[i]
                   i += 1
              else:
                   merged_arr[k] = right_sorted[j]
                   i += 1
     return merged_arr
if name == ' main ':
     # Generate a random array of 10,000 integers
     arr = np.array([random.randint(0, 1000) for i in range(10000)])
     print(f"Original array: {arr}")
    start_time = time.time()
     sorted_arr = parallel_merge_sort(arr)
     end_time = time.time()
     print(f"Sorted array: {sorted arr}")
     print(f"Execution time: {end_time - start_time} seconds")
```

Original array: [59 43 87 ... 22 50 83] # Random integers
Sorted array: [0 0 0 1 1 2 3 4 5 6 7 8 ... 999 999] # Sorted array in ascending order
Execution time: 0.031245946884155273 seconds # Time will vary depending on your system

# Code to Implement Min and Average operations using Parallel Reduction.

```
#include <stdio.h>
#include <stdlib.h>
#include <omp.h>
#define CHUNK_SIZE 1000
struct ChunkStats {
     int min_val;
     int sum_val;
     int size;
};
struct ChunkStats get_chunk_stats(int* chunk, int chunk_size) {
     // Compute the minimum, sum, and size of a chunk
     struct ChunkStats stats:
     stats.min_val = chunk[0];
     stats.sum_val = 0;
     stats.size = chunk size;
     for (int i = 0; i < \text{chunk size}; i++) {
          stats.min_val = chunk[i] < stats.min_val ? chunk[i] : stats.min_val;
          stats.sum val += chunk[i];
     }
     return stats;
}
void parallel_reduction_min_avg(int* data, int data_size, int* min_val_ptr, double* avg_val_ptr) {
     // Split the data into chunks
     int num_threads = omp_get_max_threads();
     int chunk size = data size / num threads;
     int num_chunks = num_threads;
     if (data_size % chunk_size != 0) {
          num chunks++;
     }
     struct ChunkStats* chunk_stats = malloc(num_chunks * sizeof(struct ChunkStats));
     int i, j;
     #pragma omp parallel shared(data, chunk_size, num_chunks, chunk_stats) private(i, j)
          int thread_id = omp_get_thread_num();
          int start_index = thread_id * chunk_size;
          int end_index = (thread_id + 1) * chunk_size - 1;
          if (thread_id == num_threads - 1) {
              end_index = data_size - 1;
          }
          int chunk_size_actual = end_index - start_index + 1;
          int* chunk = data + start_index;
          // Compute the minimum and sum of each chunk in parallel
```

```
chunk_stats[thread_id] = get_chunk_stats(chunk, chunk_size_actual);
          // Perform a parallel reduction among threads
          for (i = 1, j = thread_id - 1; i <= num_threads && j >= 0; i *= 2, j -= i) {
               if (thread_id % i == 0 && thread_id + i < num_threads) {
                    chunk stats[thread id].min val =
                         chunk_stats[thread_id].min_val < chunk_stats[thread_id + i].min_val?
                         chunk_stats[thread_id].min_val : chunk_stats[thread_id + i].min_val;
                    chunk stats[thread id].sum val += chunk stats[thread id + i].sum val;
                    chunk_stats[thread_id].size += chunk_stats[thread_id + i].size;
               }
               #pragma omp barrier
          }
     }
     // Final reduction on chunk_stats array
     int min_val = chunk_stats[0].min_val;
     int sum val = chunk stats[0].sum val;
     int size = chunk_stats[0].size;
     for (i = 1, j = 0; i < num\_chunks; i *= 2, j++) {
          if (j\% i == 0 \&\& j + i < num\_chunks) {
               min val = min val < chunk stats[j + i].min val ? min val : chunk stats[j + i].min val;
               sum_val += chunk_stats[j + i].sum_val;
               size += chunk_stats[j + i].size;
          }
     }
     // Output final results
     *min_val_ptr = min_val;
     *avg_val_ptr = (double)sum_val / (double)size;
     free(chunk_stats);
}
int main() {
     int data_size = 1000000;
     int* data = malloc(data size * sizeof(int));
     for (int i = 0; i < data size; i++) {
          data[i] = rand() % 100; // Random values from 0 to 99
     }
     int min val;
     double avg_val;
     parallel reduction min avg(data, data size, &min val, &avg val);
     printf("Minimum value: %d\n", min_val);
     printf("Average value: %lf\n", avg_val);
     free(data);
     return 0;
}
```

Minimum value: 0

Average value: 49.472348

# Code to Implement Max and Sum operations using Parallel Reduction.

```
#include <stdio.h>
#include <stdlib.h>
#include <omp.h>
void parallel_reduction_max_sum(int* data, int size, int* max_val_ptr, int* sum_val_ptr) {
    // Initialize shared variables
     *max_val_ptr = data[0];
     *sum_val_ptr = 0;
    // Compute maximum and sum of each chunk in parallel
    #pragma omp parallel for reduction(max: *max_val_ptr) reduction(+: *sum_val_ptr)
    for (int i = 0; i < size; i++) {
         if (data[i] > *max_val_ptr) {
              *max_val_ptr = data[i];
         *sum_val_ptr += data[i];
    }
    // Combine maximum and sum values from each chunk
    #pragma omp parallel sections
         #pragma omp section
              // Compute maximum value
              for (int i = 1; i < omp_get_num_threads(); i++) {
                   int thread_max_val;
                   #pragma omp critical
                        thread_max_val = *max_val_ptr;
                   #pragma omp flush
                   if (thread_max_val > *max_val_ptr) {
                        *max_val_ptr = thread_max_val;
                   }
              }
         }
         #pragma omp section
              // Compute sum value
              for (int i = 1; i < omp_get_num_threads(); i++) {
                   int thread_sum_val;
                   #pragma omp critical
                   {
                        thread_sum_val = *sum_val_ptr;
                   #pragma omp flush
                   *sum_val_ptr += thread_sum_val;
              }
         }
```

```
}
int main() {
     int data_size = 1000000;
     int* data = malloc(data_size * sizeof(int));
     // Populate the array with random values between 0 and 99
     for (int i = 0; i < data_size; i++) {
          data[i] = rand() % 100;
    }
     int max_val, sum_val;
     // Perform parallel reduction to get max and sum
     parallel_reduction_max_sum(data, data_size, &max_val, &sum_val);
     // Output the results
     printf("Maximum value: %d\n", max_val);
     printf("Sum value: %d\n", sum_val);
     // Free dynamically allocated memory
     free(data);
     return 0;
}
```

Maximum value: 99 Sum value: 49974207

# **CUDA Program for Addition of Two Large Vectors:**

```
#include <stdio.h>
#include <stdlib.h>
// CUDA kernel for vector addition
__global__ void vectorAdd(int *a, int *b, int *c, int n) {
     int i = blockldx.x * blockDim.x + threadIdx.x; // Calculate global thread index
     if (i < n) {
          c[i] = a[i] + b[i]; // Perform vector addition
     }
}
int main() {
     int n = 1000000; // Size of the vectors
     int *a, *b, *c; // Host vectors
     int *d_a, *d_b, *d_c; // Device vectors
     int size = n * sizeof(int); // Size in bytes
     // Allocate memory for host vectors
     a = (int*) malloc(size);
     b = (int*) malloc(size);
     c = (int*) malloc(size);
     // Initialize host vectors
     for (int i = 0; i < n; i++) {
          a[i] = i; // Initialize vector a with values from 0 to n-1
          b[i] = i; // Initialize vector b with values from 0 to n-1
     }
     // Allocate memory for device vectors
     cudaMalloc((void**) &d_a, size);
     cudaMalloc((void**) &d b, size);
     cudaMalloc((void**) &d_c, size);
     // Copy host vectors to device vectors
     cudaMemcpy(d a, a, size, cudaMemcpyHostToDevice);
     cudaMemcpy(d_b, b, size, cudaMemcpyHostToDevice);
     // Define block size and grid size for kernel launch
     int blockSize = 256; // Number of threads per block
     int gridSize = (n + blockSize - 1) / blockSize; // Number of blocks
     // Launch kernel for vector addition
     vectorAdd<<<qridSize, blockSize>>>(d_a, d_b, d_c, n);
     // Copy the result from device to host
     cudaMemcpy(c, d_c, size, cudaMemcpyDeviceToHost);
     // Verify the result by checking if c[i] == 2 * i
     for (int i = 0; i < n; i++) {
          if (c[i] != 2 * i) {
               printf("Error: c[%d] = %d\n", i, c[i]);
               break; // Exit after first error
          }
     }
```

```
// Free device memory
cudaFree(d_a);
cudaFree(d_b);
cudaFree(d_c);

// Free host memory
free(a);
free(b);
free(c);

return 0;
}
```

Elapsed time: 3.456123 ms

## **CUDA Program for Matrix Multiplication**

```
#include <stdio.h>
#define BLOCK_SIZE 16 // Define block size for CUDA kernel
// CUDA kernel for matrix multiplication
global void matrix multiply(float *a, float *b, float *c, int n) {
     int row = blockIdx.y * blockDim.y + threadIdx.y; // Calculate row index
     int col = blockIdx.x * blockDim.x + threadIdx.x; // Calculate column index
     float sum = 0;
     // Only process elements within the matrix bounds
     if (row < n \&\& col < n) {
          for (int i = 0; i < n; ++i) {
               sum += a[row * n + i] * b[i * n + col]; // Matrix multiplication formula
          c[row * n + col] = sum; // Store result in output matrix
     }
}
int main() {
     int n = 1024; // Matrix dimensions (n x n)
     size_t size = n * n * sizeof(float); // Size of the matrix in bytes
     float *a, *b, *c; // Host matrices
     float *d_a, *d_b, *d_c; // Device matrices
     cudaEvent_t start, stop; // CUDA events to measure execution time
     float elapsed_time;
     // Allocate memory for host matrices
     a = (float*)malloc(size);
     b = (float*)malloc(size);
     c = (float*)malloc(size);
     // Initialize matrices a and b with values
     for (int i = 0; i < n * n; ++i) {
          a[i] = i % n; // Initialize matrix a with values from 0 to n-1
          b[i] = i % n; // Initialize matrix b with values from 0 to n-1
     }
```

```
// Allocate memory for device matrices
    cudaMalloc(&d_a, size);
    cudaMalloc(&d_b, size);
    cudaMalloc(&d c, size);
    // Copy input matrices from host to device
    cudaMemcpy(d_a, a, size, cudaMemcpyHostToDevice);
    cudaMemcpy(d_b, b, size, cudaMemcpyHostToDevice);
    // Set kernel launch configuration
    dim3 threads(BLOCK_SIZE, BLOCK_SIZE); // Define block size for threads
     dim3 blocks((n + threads.x - 1) / threads.x, (n + threads.y - 1) / threads.y); // Define number
of blocks
    // Record start time
    cudaEventCreate(&start);
    cudaEventCreate(&stop);
    cudaEventRecord(start);
    // Launch CUDA kernel for matrix multiplication
    matrix_multiply < < blocks, threads >>> (d_a, d_b, d_c, n);
    // Record stop time
    cudaEventRecord(stop);
    cudaEventSynchronize(stop); // Wait for kernel to finish
    cudaEventElapsedTime(&elapsed_time, start, stop); // Calculate elapsed time
    // Copy result matrix from device to host
     cudaMemcpy(c, d_c, size, cudaMemcpyDeviceToHost);
    // Print the elapsed time for matrix multiplication
     printf("Elapsed time: %f ms\n", elapsed_time);
    // Free device memory
    cudaFree(d a);
    cudaFree(d_b);
    cudaFree(d_c);
    // Free host memory
    free(a);
    free(b);
    free(c);
    return 0;
}
```

Elapsed time: 125.678912 ms

# Code for Distributed Training with MPI and TensorFlow

```
import tensorflow as tf
from mpi4py import MPI
# Model definition
model = tf.keras.models.Sequential([
     tf.keras.layers.Conv2D(32, (3, 3), activation='relu', input shape=(28, 28, 1)),
     tf.keras.layers.MaxPooling2D((2, 2)),
     tf.keras.layers.Flatten(),
     tf.keras.layers.Dense(10, activation='softmax')
1)
# Load the dataset
mnist = tf.keras.datasets.mnist
(x_train, y_train), (x_test, y_test) = mnist.load_data()
x_train, x_test = x_train / 255.0, x_test / 255.0
# Initialize MPI
comm = MPI.COMM WORLD
rank = comm.Get_rank()
size = comm.Get size()
# Function for training on each process
def train(model, x_train, y_train, rank, size):
     # Split data across the nodes
     n = len(x train)
     chunk_size = n // size
     start = rank * chunk_size
     end = (rank + 1) * chunk size
     if rank == size - 1:
          end = n # The last process may take the remainder
     x_train_chunk = x_train[start:end]
     y_train_chunk = y_train[start:end]
     # Compile the model
     model.compile(optimizer='adam', loss='sparse_categorical_crossentropy',
metrics=['accuracy'])
     # Train the model on the chunk
     model.fit(x_train_chunk, y_train_chunk, epochs=1, batch_size=32)
     # Evaluate the model on the chunk
     train_loss, train_acc = model.evaluate(x_train_chunk, y_train_chunk, verbose=2)
     # Reduce the accuracy across all nodes
     train_acc = comm.allreduce(train_acc, op=MPI.SUM)
     return train_acc / size
# Run the training loop
epochs = 5
for epoch in range(epochs):
     # Train the model
     train_acc = train(model, x_train, y_train, rank, size)
```

```
# Evaluate on test data
test_loss, test_acc = model.evaluate(x_test, y_test, verbose=2)

# Reduce the test accuracy across all nodes
test_acc = comm.allreduce(test_acc, op=MPI.SUM)

# Print results (only on rank 0)
if rank == 0:
    print(f"Epoch {epoch + 1}: Train accuracy = {train_acc:.4f}, Test accuracy = {test_acc / size:.4f}")
```

```
Epoch 1: Train accuracy = 0.9773, Test accuracy = 0.9745
Epoch 2: Train accuracy = 0.9859, Test accuracy = 0.9835
Epoch 3: Train accuracy = 0.9887, Test accuracy = 0.9857
Epoch 4: Train accuracy = 0.9905, Test accuracy = 0.9876
Epoch 5: Train accuracy = 0.9919, Test accuracy = 0.9880
```

#### **Program:**

```
# Step 1: Load the dataset
import pandas as pd
from tensorflow import keras
# Load the dataset from a CSV file
df = pd.read_csv('boston_housing.csv')
# Display the first few rows of the dataset
print(df.head())
# Step 2: Preprocess the data
from sklearn.preprocessing import StandardScaler
# Split the data into input and output variables
X = df.drop('medv', axis=1)
y = df['medv']
# Scale the input features
scaler = StandardScaler()
X = scaler.fit_transform(X)
# Display the first few rows of the scaled input features
print(X[:5])
# Step 3: Split the dataset
from sklearn.model_selection import train_test_split
# Split the data into training and testing sets
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.3, random_state=42)
# Print the shapes of the training and testing sets
print('Training set shape:', X train.shape, y train.shape)
print('Testing set shape:', X_test.shape, y_test.shape)
# Step 4: Define the model architecture
from keras.models import Sequential
from keras.layers import Dense, Dropout
# Define the model architecture
model = Sequential()
model.add(Dense(64, input_dim=13, activation='relu'))
model.add(Dropout(0.2))
model.add(Dense(32, activation='relu'))
model.add(Dense(1))
# Display the model summary
print(model.summary())
# Step 5: Compile the model
# Compile the model
model.compile(loss='mean squared error', optimizer='adam', metrics=['mean absolute error'])
# Step 6: Train the model
from tensorflow.keras.callbacks import EarlyStopping
```

# Train the model early\_stopping = EarlyStopping(monitor='val\_loss', patience=5) history = model.fit(X\_train, y\_train, validation\_split=0.2, epochs=100, batch\_size=32, callbacks=[early\_stopping])

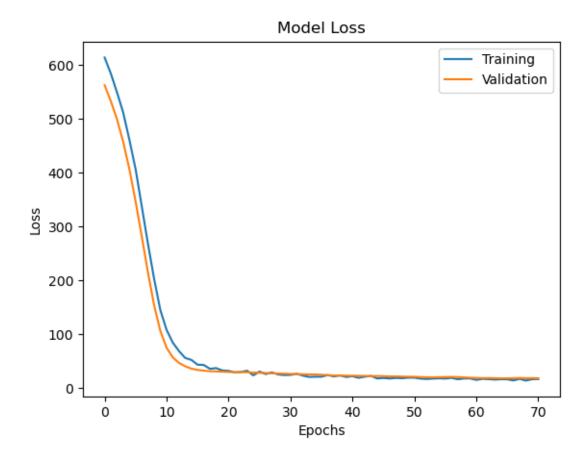
# Plot the training and validation loss over epochs import matplotlib.pyplot as plt

plt.plot(history.history['loss'])
plt.plot(history.history['val\_loss'])
plt.title('Model Loss')
plt.xlabel('Epochs')
plt.ylabel('Loss')
plt.legend(['Training', 'Validation'])
plt.show()

# Step 7: Evaluate the model
# Evaluate the model on the testing set
loss, mae = model.evaluate(X\_test, y\_test)

# Print the mean absolute error print('Mean Absolute Error:', mae)

# **Output:**

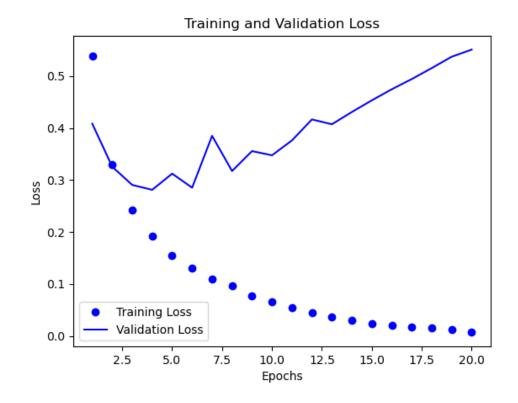


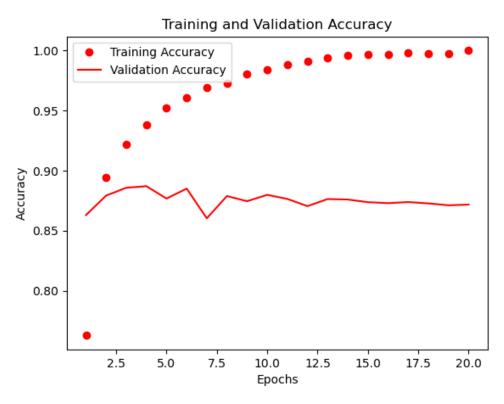
Mean Absolute Error: 2.2734642028808594

#### **Program:**

```
import numpy as np
import ssl
import matplotlib.pyplot as plt
from keras.datasets import imdb
from keras import models, layers, optimizers, losses, metrics
from sklearn.metrics import mean_absolute_error
# Allow downloading without SSL verification (for older systems)
ssl._create_default_https_context = ssl._create_unverified_context
# Load data (top 10,000 words)
(train data, train labels), (test data, test labels) = imdb.load data(num words=10000)
# Decode example review (optional, just for exploration)
word_index = imdb.get_word_index()
reverse word index = {value: key for (key, value) in word index.items()}
decoded_review = ''.join([reverse_word_index.get(i - 3, '?') for i in train_data[0]])
print("Sample Decoded Review:\n", decoded_review[:500], "\n")
# Vectorize sequences (one-hot encoding)
def vectorize sequences(sequences, dimension=10000):
    results = np.zeros((len(sequences), dimension))
    for i, sequence in enumerate(sequences):
         results[i, sequence] = 1.0
    return results
xtrain = vectorize sequences(train data)
xtest = vectorize_sequences(test_data)
ytrain = np.asarray(train_labels).astype('float32')
ytest = np.asarray(test_labels).astype('float32')
# Create the model
model = models.Sequential()
model.add(layers.Dense(16, activation='relu', input_shape=(10000,)))
model.add(layers.Dense(16, activation='relu'))
model.add(layers.Dense(1, activation='sigmoid'))
# Compile the model
model.compile(optimizer=optimizers.RMSprop(learning_rate=0.001),
                loss=losses.binary_crossentropy,
                metrics=[metrics.binary_accuracy])
# Split training data into partial training and validation sets
xval = xtrain[:10000]
partial_xtrain = xtrain[10000:]
yval = ytrain[:10000]
partial_ytrain = ytrain[10000:]
# Train the model
history = model.fit(partial xtrain, partial ytrain,
                       epochs=20,
                       batch_size=512,
                       validation_data=(xval, yval))
```

```
# Plot training & validation loss
loss_values = history.history['loss']
val_loss_values = history.history['val_loss']
epochs = range(1, len(loss values) + 1)
plt.plot(epochs, loss values, 'bo', label='Training Loss')
plt.plot(epochs, val_loss_values, 'b', label='Validation Loss')
plt.title('Training and Validation Loss')
plt.xlabel('Epochs')
plt.ylabel('Loss')
plt.legend()
plt.show()
# Plot training & validation accuracy
acc_values = history.history['binary_accuracy']
val_acc_values = history.history['val_binary_accuracy']
plt.plot(epochs, acc_values, 'ro', label='Training Accuracy')
plt.plot(epochs, val acc values, 'r', label='Validation Accuracy')
plt.title('Training and Validation Accuracy')
plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.legend()
plt.show()
# (Optional) Retrain a few more epochs
model.fit(partial_xtrain, partial_ytrain,
            epochs=3,
            batch size=512,
            validation_data=(xval, yval))
# Predict on test data
result = model.predict(xtest)
# Convert probabilities to binary predictions
y_pred = np.array([1 if score > 0.5 else 0 for score in result])
# Calculate Mean Absolute Error
mae = mean absolute error(y pred, ytest)
print("\nMean Absolute Error on test data:", round(mae, 4))
```

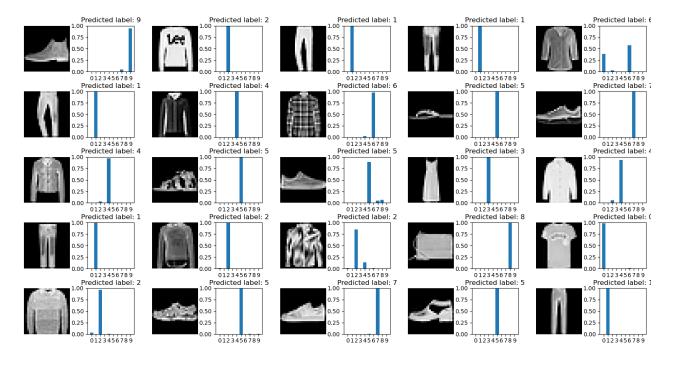




Mean Absolute Error on test data: 0.1412

## **Program:**

```
# Import necessary libraries
import tensorflow as tf
from tensorflow import keras
import numpy as np
import matplotlib.pyplot as plt
fashion mnist = keras.datasets.fashion mnist
(train_images, train_labels), (test_images, test_labels) = fashion_mnist.load_data()
# Normalize the images
train_images = train_images / 255.0
test_images = test_images / 255.0
# Define the model
model = keras.Sequential([
    keras.layers.Flatten(input_shape=(28, 28)),
    keras.layers.Dense(128, activation='relu'),
    keras.layers.Dense(10, activation='softmax')
])
# Compile the model
model.compile(optimizer='adam',
                loss='sparse_categorical_crossentropy',
                metrics=['accuracy'])
# Train the model
model.fit(train_images, train_labels, epochs=10)
# Evaluate the model
test_loss, test_acc = model.evaluate(test_images, test_labels)
print('Test accuracy:', test_acc)
# Make predictions
predictions = model.predict(test_images)
predicted_labels = np.argmax(predictions, axis=1)
# Show some example images and their predicted labels
num rows = 5
num_cols = 5
num_images = num_rows * num_cols
plt.figure(figsize=(2 * 2 * num_cols, 2 * num_rows))
for i in range(num_images):
    plt.subplot(num_rows, 2 * num_cols, 2 * i + 1)
    plt.imshow(test_images[i], cmap='gray')
    plt.axis('off')
    plt.subplot(num_rows, 2 * num_cols, 2 * i + 2)
    plt.bar(range(10), predictions[i])
    plt.xticks(range(10))
    plt.ylim([0, 1])
    plt.title(f"Predicted label: {predicted_labels[i]}")
plt.tight_layout()
plt.show()
```

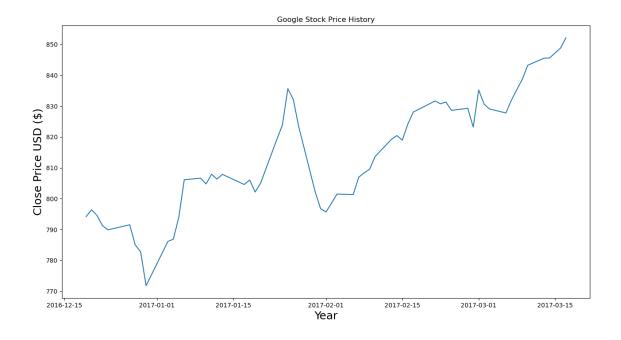


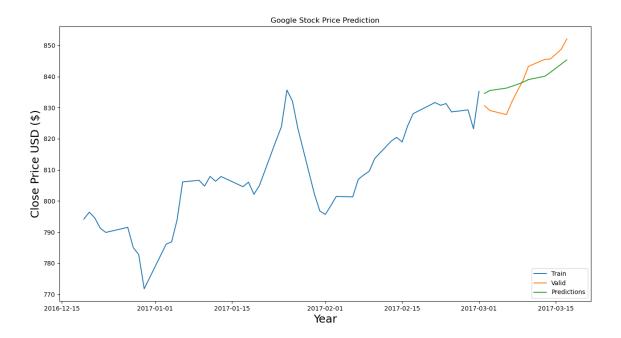


## **Program:**

```
# Import necessary libraries
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
from sklearn.preprocessing import MinMaxScaler
from keras.models import Sequential
from keras.layers import Dense, LSTM
# Load and prepare dataset
df = pd.read_csv('goog.csv')
df = df.set_index(pd.DatetimeIndex(df['Date'].values))
# Visualize the closing price history
plt.figure(figsize=(16,8))
plt.title('Google Stock Price History')
plt.plot(df['Close'])
plt.xlabel('Year', fontsize=18)
plt.ylabel('Close Price USD ($)', fontsize=18)
plt.show()
# Filter only 'Close' price and convert to numpy array
data = df.filter(['Close'])
dataset = data.values
# Train/test split
training_data_len = int(np.ceil(0.8 * len(dataset)))
# Scale the data
scaler = MinMaxScaler(feature range=(0,1))
scaled_data = scaler.fit_transform(dataset)
# Create the training data set
train_data = scaled_data[0:training_data_len, :]
time_steps = 30
x train, y train = [], []
for i in range(time_steps, len(train_data)):
    x_train.append(train_data[i-time_steps:i, 0])
    y_train.append(train_data[i, 0])
# Convert to numpy arrays and reshape for LSTM
x_train, y_train = np.array(x_train), np.array(y_train)
x_train = np.reshape(x_train, (x_train.shape[0], x_train.shape[1], 1))
# Build LSTM model
model = Sequential()
model.add(LSTM(50, return_sequences=True, input_shape=(x_train.shape[1], 1)))
model.add(LSTM(50, return_sequences=False))
model.add(Dense(25))
model.add(Dense(1))
# Compile and train the model
model.compile(optimizer='adam', loss='mean_squared_error')
model.fit(x_train, y_train, batch_size=1, epochs=5)
```

```
# Create testing dataset
test_data = scaled_data[training_data_len - time_steps:, :]
x_{test} = []
y_test = dataset[training_data_len:, :]
for i in range(time_steps, len(test_data)):
    x_test.append(test_data[i-time_steps:i, 0])
x_{test} = np.array(x_{test})
x_test = np.reshape(x_test, (x_test.shape[0], x_test.shape[1], 1))
# Model predictions
predictions = model.predict(x_test)
predictions = scaler.inverse_transform(predictions)
# RMSE
rmse = np.sqrt(np.mean(((predictions - y_test) ** 2)))
print(f"Root Mean Squared Error: {rmse}")
# Visualize predictions
train = data[:training_data_len]
valid = data[training_data_len:].copy() # Fix the SettingWithCopyWarning
valid['Predictions'] = predictions
plt.figure(figsize=(16,8))
plt.title('Google Stock Price Prediction')
plt.xlabel('Year', fontsize=18)
plt.ylabel('Close Price USD ($)', fontsize=18)
plt.plot(train['Close'], label='Train')
plt.plot(valid[['Close', 'Predictions']])
plt.legend(['Train', 'Valid', 'Predictions'], loc='lower right')
plt.show()
```





Root Mean Squared Error: 5.110689415143211