Assignment 3: CS 215

Due: 14th September before 11:55 pm

Remember the honor code while submitting this (and every other) assignment. All members of the group should work on all parts of the assignment. We will adopt a zero-tolerance policy against any violation.

Submission instructions:

- 1. You should type out all the answers to the written problems in Word (with the equation editor) or using Latex, or write it neatly on paper and scan it. In either case, prepare a pdf file.
- 2. Put the pdf file and the code for the programming parts all in one zip file. The pdf should contain the names and ID numbers of all students in the group within the header. The pdf file should also contain instructions for running your code. Name the zip file as follows: A3-IdNumberOfFirstStudent-IdNumberOfSecondStudent.zip. (If you are doing the assignment alone, the name of the zip file is A3-IdNumber.zip).
- 3. Upload the file on moodle BEFORE 11:55 pm on the due date (i.e. 15th september). We will nevertheless allow and not penalize any submission until 10:00 am on the following day (i.e. 15th September). No assignments will be accepted thereafter.
- 4. Note that only one student per group should upload their work on moodle.
- 5. Please preserve a copy of all your work until the end of the semester.

Questions:

- 1. Consider a shelf containing n books, each one with a distinct color. Let us suppose that you pick a book uniformly at random with replacement (i.e. you put the book back on the shelf after picking it) and independently of what was picked earlier. Let $X^{(n)}$ be the number of times you would need to pick a book in this fashion, such that you have chosen a book of each color at least once. We can write that $X^{(n)} = X_1 + X_2 + ... + X_n$ where X_i denotes the additional number of times you have to pick a book such that you move from having picked books of i-1 distinct colors to i distinct colors. We wish to determine E(X) and Var(X). To this end, do as follows:
 - (a) What is X_1 ? When books with i-1 distinct types of colors have been collected, what is the probability of picking a book with a different color (i.e. different from the previous i-1 colors)? [3 points] Solution: Clearly $X_1 = 1$. The other probability is (n i + 1)/n.
 - (b) Due to independence, X_i is a geometric random variable. What is its parameter? Let Z be a random variable for the trial number for the first head obtained in a sequence of independent Bernoulli trials with head probability p. Then $P(Z = k) = (1 p)^{k-1}p$ where k = 1, 2, 3, ..., and Z is said to be a geometric random variable with parameter p. [3 points]
 - **Solution:** By definition of X_i , it is a geometric random variable with parameter (n-i+1)/n.
 - (c) Show that the expected value of a geometric random variable with parameter p is 1/p. Derive the variance of a geometric random variable. [4+4=8 points]
 Solution: See https://proofwiki.org/wiki/Expectation_of_Shifted_Geometric_Distribution and https://proofwiki.org/wiki/Variance_of_Shifted_Geometric_Distribution. Note that what we

call a geometric random variable is termed 'shifted random variable' here.

- (d) Hence derive $E(X^{(n)})$ for this problem. [3 points] Solution: $E(X^{(n)}) = 1/p_1 + 1/p_2 + ... + 1/p_n = \frac{n}{n} + \frac{n-1}{n} + ... + \frac{n}{1} = n(1/1 + 1/2 + ... + 1/n) = nH_n$ where $H_n = 1 + 1/2 + 1/3 + ... + 1/n$.
- (e) Hence derive an upper bound on $Var(X^{(n)})$ for this problem. You will need the inequality that the sum of reciprocals of squares of positive integers is upper bounded by $\pi^2/6$. [3 points] Solution: We have $Var(X^{(n)}) = \sum_{i=1}^n Var(X_i)$ due to independence. This gives $Var(X^{(n)}) = \sum_{i=1}^n (1-p_i)/p_i^2 < \sum_{i=1}^n 1/p_i^2 = \frac{n^2}{n^2} + \frac{n^2}{(n-1)^2} + ... + \frac{n^2}{1} = n^2(\frac{1}{1^2} + \frac{1}{2^2} + ... + \frac{1}{n^2}) = n^2\pi^2/6$.
- (f) Plot a graph of $E(X^{(n)})$ versus n for different n. If $E(X^{(n)}) = \Theta(f(n))$, what is f(n)? [3+2=5 points] **Solution:** It turns out that H_n is $\Theta(\log n)$ as can be seen from the accompanying code plot-Hn.m. Hence $E(X^{(n)}) = \Theta(n \log n)$.
- 2. (a) A student is trying to design a procedure to generate a sample from a distribution function F, where F is invertible. For this, (s)he generates a sample u_i from a [0,1] uniform distribution using the 'rand' function of MATLAB, and computes $v_i = F^{-1}(u_i)$. This is repeated n times for i = 1...n. Prove that the values $\{v_i\}_{i=1}^n$ follow the distribution F. [6 points]

Solution: We have $v = F^{-1}(u)$. Hence $P(V \le y) = F_V(y) = P(u \le F(y)) = F(y)$ since $U \sim Uniform(0,1)$ due to which $P(U \le u) = u$. This proves that the values $\{v_i\}_{i=1}^n$ follow the distribution F.

- 3. (a) In this exercise, we will perform maximum likelihood based plane fitting. Let the equation of the plane be z = ax + by + c. Let us suppose we have access to accurate X and Y coordinates of some N points lying on the plane. We also have access to the Z coordinates of these points, but those have been corrupted independently by noise from $\mathcal{N}(0, \sigma^2)$. Write down the log-likelihood function \mathcal{L} to be maximized in order to determine a, b, c. Write down three linear equations corresponding to setting partial derivatives of \mathcal{L} w.r.t. a, b, c (respectively) to 0. Express these equations in matrix and vector form. [3+4=7 points]
 - (b) Repeat the previous part if z had the form $z = a_1x^2 + a_2y^2 + a_3xy + a_4x + a_5y + a_6$. Again, let us suppose we have access to accurate X and Y coordinates of some N points lying on the plane. We also have access to the Z coordinates of these points, but those have been corrupted independently by noise from $\mathcal{N}(0, \sigma^2)$. Write down the log-likelihood function \mathcal{L} to be maximized in order to determine $a_1, a_2, ..., a_6$. Write down linear equations corresponding to setting partial derivatives of \mathcal{L} w.r.t. $a_1, a_2, ..., a_6$ (respectively) to 0. Express these equations in matrix and vector form. [4+4=8 points]
 - (c) Now write MATLAB code to solve this linear system for data consisting of XYZ coordinates of N=2000 points, stored in the file 'XYZ.txt' in the homework folder. Read the data using the MATLAB function

'dlmwrite'. The data consist of N rows, each containing the X,Y,Z coordinates of a point (in that order). What is the predicted equation of the plane? What is the predicted noise variance? State these in your report, and print them out via your code. [10 points]

Solution: See the code in the homework folder for planefitting. The log-likelihood function for part (a) is $L(a,b,c) = -\sum_{i=1}^{N} (z_i - ax_i - by_i - c)^2/\sigma^2 + \text{constants using } \pi, \sigma$. The three linear equations are: $\sum_{i=1}^{N} (z_i x_i - ax_i^2 - bx_i y_i - cx_i) = 0$; $\sum_{i=1}^{N} (z_i x_i - ax_i y_i - by_i^2 - cy_i) = 0$; $\sum_{i=1}^{N} (z_i - ax_i - by_i - c) = 0$. The equations in matrix vector form are expressed as follows:

$$\begin{pmatrix} \sum_{i=1}^{N} x_i^2 & \sum_{i=1}^{N} x_i y_i & \sum_{i=1}^{N} x_i \\ \sum_{i=1}^{N} x_i y_i & \sum_{i=1}^{N} y_i^2 & \sum_{i=1}^{N} y_i \\ \sum_{i=1}^{N} x_i & \sum_{i=1}^{N} y_i & N \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^{N} z_i x_i \\ \sum_{i=1}^{N} z_i y_i \\ \sum_{i=1}^{N} z_i \end{pmatrix}$$
(1)

For part (b), the log-likelihood function is $\sum_{i=1}^{N} (z_i - a_i x_i^2 - a_2 y_i^2 - a_3 x_i y_i - a_4 x_i - a_5 y_i - a_6)/\sigma^2 + \text{constants}$ with π, σ . The derivative equations in matrix-vector form are:

$$\begin{pmatrix} \sum_{i=1}^{N} x_{i}^{4} & \sum_{i=1}^{N} x_{i}^{2} y_{i}^{2} & \sum_{i=1}^{N} x_{i}^{3} y_{i} & \sum_{i=1}^{N} x_{i}^{3} & \sum_{i=1}^{N} x_{i}^{2} y_{i} & \sum_{i=1}^{N} x_{i}^{2} \\ \sum_{i=1}^{N} x_{i}^{2} y_{i}^{2} & \sum_{i=1}^{N} y_{i}^{4} & \sum_{i=1}^{N} x_{i} y_{i}^{3} & \sum_{i=1}^{N} x_{i} y_{i}^{2} & \sum_{i=1}^{N} y_{i}^{2} \\ \sum_{i=1}^{N} x_{i}^{3} y_{i} & \sum_{i=1}^{N} x_{i} y_{i}^{3} & \sum_{i=1}^{N} x_{i} y_{i}^{2} & \sum_{i=1}^{N} x_{i}^{2} y_{i} & \sum_{i=1}^{N} x_{i} y_{i}^{2} \\ \sum_{i=1}^{N} x_{i}^{3} y_{i} & \sum_{i=1}^{N} x_{i} y_{i}^{2} & \sum_{i=1}^{N} x_{i}^{2} y_{i} & \sum_{i=1}^{N} x_{i}^{2} y_{i} & \sum_{i=1}^{N} x_{i} y_{i}^{2} & \sum_{i=1}^{N} x_{i} y_{i}^{2} \\ \sum_{i=1}^{N} x_{i}^{2} y_{i} & \sum_{i=1}^{N} y_{i}^{3} & \sum_{i=1}^{N} x_{i} y_{i}^{2} & \sum_{i=1}^{N} x_{i} y_{i} & \sum_{i=1}^{N} y_{i}^{2} & \sum_{i=1}^{N} y_{i}^{2} \\ \sum_{i=1}^{N} x_{i}^{2} y_{i} & \sum_{i=1}^{N} y_{i}^{2} & \sum_{i=1}^{N} x_{i} y_{i} & \sum_{i=1}^{N} x_{i} y_{i} & \sum_{i=1}^{N} y_{i}^{2} & \sum_{i=1}^{N} y_{i} \\ \sum_{i=1}^{N} z_{i} y_{i} & \sum_{i=1}^{N} z_{i} y_{i} & \sum_{i=1}^{N} z_{i} y_{i} & \sum_{i=1}^{N} z_{i} y_{i} & \sum_{i=1}^{N} z_{i} y_{i} \\ \sum_{i=1}^{N} z_{i} z_{i} & \sum_{i=1}^{N} z_{i} &$$

- 4. We have extensively seen parametric PDF estimation in class via maximum likelihood. In many situations, the family of the PDF is however unknown. Estimation under such a scenario is called nonparametric density estimation. We have studied one such technique in class, namely histogramming, and we also analyzed its rate of convergence. There is another popular technique for nonparametric density estimation. It is called KDE or Kernel density estimation, the formula for which is given as $\hat{p}_n(x;\sigma) = \frac{\sum_{i=1}^n \exp\left(-(x-x_i)^2/(2\sigma^2)\right)}{n\sigma\sqrt{2\pi}}$. Here $\hat{p}_n(x)$ is an estimate of the underlying probability density at value x, $\{x_i\}_{i=1}^n$ are the n samples values, from which the unknown PDF is being estimated, and σ is a bandwidth parameter (similar to a histogram bin-width parameter). The choice of the appropriate σ is not very straightforward. We will implement one possible procedure to choose σ called cross-validation. For this, do as follows:
 - (a) Use MATLAB to draw n = 1000 independent samples from $\mathcal{N}(0, 16)$. We will use a random subset of 750 samples (set T) for building the PDF, and the remaining 250 as the validation set V. Note that T and V must be disjoint sets.
 - (b) In your report, write down an expression for the joint likelihood of the samples in V, based on the estimate of the PDF built from T with bandwidth parameter σ . [3 points]
 - (c) For different values of σ from the set $\{0.001, 0.1, 0.2, 0.9, 1, 2, 3, 5, 10, 20, 100\}$, write MATLAB code to evaluate the log of the joint likelihood LL of the samples in V, based on the estimate of the PDF built from T. Plot of a graph of LL versus $\log \sigma$ and include it in your report. In the report, state which value of σ yielded the best LL value, and print it via your code as well. This procedure is called cross-validation. [7 points]
 - (d) In this experiment, we know the ground truth pdf which we shall denote as p(x). So we can peek into it, in order to choose the best σ . This is impractical in actual experiments, but for now it will serve as a method of comparison. For each σ , write MATLAB code to evaluate $D = \sum_{x_i \in V} (p(x_i) \hat{p_n}(x;\sigma))^2$. Plot of a graph of D versus $\log \sigma$ and include it in the report. In the report, state which value of σ yielded the best D value, and also what was the D value for the σ parameter which yielded the best LL. [7 points]
 - (e) Now, suppose the set T and V were equal to each other. What happens to the cross-validation procedure, and why? Explain in the report. [4+4=8 points]

Solution: The likelihood for a sample $\tilde{x}_j \in V$ based on the estimate $\hat{p}_n(x)$ derived from samples in T is given as:

$$p(\tilde{x}_j) = \frac{\sum_{i=1}^{|T|} \exp(-(\tilde{x}_j - x_i)^2 / (2\sigma^2))}{\sigma |T| \sqrt{2\pi}}.$$
 (3)

So the log of the joint likelihood, assuming independence, is:

$$\log p(\tilde{x}_1, \tilde{x}_2, ..., \tilde{x}_{|V|}) = \sum_{j=1}^{|V|} \log \left(\frac{\sum_{i=1}^{|T|} \exp(-(\tilde{x}_j - x_i)^2 / (2\sigma^2))}{\sigma |T| \sqrt{2\pi}} \right). \tag{4}$$

See code kde.m. As you can see, the max LL estimate of σ and the best difference estimate of σ are quite close to each other. The latter is the ideal one, but it is not computable in practice. If the sets T and V were equal to each other, the smallest σ value gets chosen by the cross-validation method based on maximizing LL. In such a case, the density estimator is just a sum of delta functions, one at each x_i . A Dirac-delta function $\delta(x)$ is defined as a function which evaluates to infinity at x=0 and 0 elsewhere in such a way that $\int_{-\infty}^{\infty} \delta(x) dx = 1$. This will yield the highest likelihood. Why? Consider the function $f(z) = e^{-z^2/(2\sigma^2)}/(\sigma\sqrt{2\pi})$. Now f(0) attains its highest value as $\sigma \to 0$. Another way of interpreting this is that the height of a Gaussian at the mean increases as σ decreases. When T and V are equal, the density is being evaluated at the same points as which it was estimated from.

- 5. Let X be a real-valued random variable whose values lie from a to b always, where a < b. Then consider an intermediate result (called IR) that $E[e^{s(X-E[X])}] \le e^{s^2(b-a)^2/8}$ where s > 0. Now, let $X_1, X_2, ..., X_n$ be independent random variables such for every i, we have X_i always lies in $[a_i, b_i]$ where $a_i < b_i$. Let $S_n = \sum_{i=1}^n X_i$. Derive an upper bound on $P(S_n E[S_n] > t)$ in terms of a_i, b_i, t using Markov's inequality and IR, and upon suitable elimination of s. Notice that IR is an upper bound on the moment generating function of random variable X with bounded values. We will now proceed to prove IR as follows:
 - (a) Without loss of generality, we consider E(X) = 0, because X can be replaced by X E(X) anyways. Hence, we consider $a \le 0 \le b$. The function e^{sx} is a convex function of x, and hence a line segment joining two distinct points of the graph always lies above the graph of the function between the two points. Hence $e^{sx} \le \frac{(b-x)e^{sa}}{b-a} + \frac{(x-a)e^{sb}}{b-a}$.
 - (b) Taking, expectation on both sides, prove that $E(e^{sx}) \le e^{L(s(b-a))}$ where $L(h) = \frac{ha}{b-a} + \log(1 + (a-ae^h)/(b-a))$.
 - (c) Using Taylor's expansion and the result that $(x+y)/2 \ge \sqrt{xy}$ for real-valued x, y, prove that $L''(h) \le 1/4$ for all real-valued h.
 - (d) Hence, conclude the proof (write the final, now somewhat obvious step).

[5 + (1+3+1) = 10 points] Solution: The intermediate result is called Hoeffding's lemma. Assuming it to be true, we prove the stated inequality which is called Hoeffding's inequality as follows. We have $P(S_n - E[S_n] \ge t) = P(\exp(s[S_n - E[S_n]) \ge \exp(st)) \le \exp(-st)E[\exp(s(S_n - E(S_n))])$. The last inequality is due to Markov's inequality since $\exp(s(Sn_n - E[S_n]))$ is always non-negative. The RHS simplifies to the following due to independence and use of Hoeffding's lemma: $\exp(-st)\prod_{i=1}^n E[s(X_i - E[X_i])] \le \exp(-st)\prod_{i=1}^n \exp[s^2(b_i - a_i)^2/8] = \exp[-st + \sum_{i=1}^n s^2(b_i - a_i)^2/8]$. We want to minimize the upper bound on the RHS by taking the derivative w.r.t. s and setting it to 0. This yields $s = \frac{4t}{\sum_{i=1}^n (b_i - a_i)^2}$. Substituting this back into the RHS containing the exponent, we have $P(S_n - E[S_n] \ge t) \le \exp[-2t^2/\sum_{i=1}^n (b_i - a_i)^2]$ which is the desired inequality, called Hoeffding's inequality.

- (a) The first step is clear and does not require re-iteration.
- (b) Taking expectation on both sides, we have $E(e^{\lambda x}) \leq \frac{b E[X]}{b a} e^{\lambda a} + \frac{E[X] a}{b a} e^{\lambda b} = \frac{be^{\lambda a}}{b a} + \frac{-ae^{\lambda b}}{b a} = e^{L(\lambda(b a))}$. Here we define $L(h) = ha/(b a) + \log\left(1 + [a(1 e^h)/(b a)]\right)$. Plugging $h = \lambda(b a)$ into this definition of L(h) yields $e^{L(h)} = e^{ha/(b a)}\left(1 + a(1 e^h)/(b a)\right) = e^{\lambda a}\left[1 + \frac{a(1 e^{\lambda(b a)})}{b a}\right] = \frac{be^{\lambda a} ae^{\lambda b}}{b a}$.
- (c) It is easy to see that L(0) = 0, L'(0) = 0, $L''(h) = -\frac{abe^h}{(b ae^h)^2}$. We see that the double derivative has the form $L''(h) = -\frac{xy}{(x+y)^2}$ for suitable x, y. By the AM-GM inequality we have $(x+y)^2 \ge 4xy$, and hence $L''(h) \le -\frac{xy}{4xy} \le 1/4$. This is true for all real-valued h.

(d) Finally, we use Taylor's theorem to express $L(h) = L(0) + hL'(0) + h^2L''(\tilde{h})/2$ for some real-valued \tilde{h} . Using our previous results, we see that $L(h) \leq h^2/8$. Hence $E[e^{\lambda x}] \leq e^{L(\lambda(b-a))} \leq e^{\lambda(b-a)^2/8}$. This is the proof of Hoeffding's lemma.