

# MA-110 Linear Algebra and Differential Equations

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# Matrix Associated to a Linear Map

**Example:** The matrix of  $S(a_0 + a_1x + a_2x^2) = a_1 + 4a_2x$ , w.r.t. the bases  $\mathcal{B} = \{1, x, x^2\}$  of  $\mathcal{P}_2$  and  $\mathcal{C} = \{1, x\}$  of  $\mathcal{P}_1$  is  $A =$

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} \text{ and } \boxed{A_{*1} = [S(1)]_{\mathcal{C}}, A_{*2} = [S(x)]_{\mathcal{C}}, A_{*3} = [S(x^2)]_{\mathcal{C}}}.$$

**General Case:** If  $T : V \rightarrow W$  is linear, then the matrix of  $T$  w.r.t. the ordered bases  $\mathcal{B} = \{v_1, \dots, v_n\}$  of  $V$ , and  $\mathcal{C} = \{w_1, \dots, w_m\}$  of  $W$ , denoted  $[T]_{\mathcal{C}}^{\mathcal{B}}$ , is

$$A = ([T(v_1)]_{\mathcal{C}} \cdots [T(v_n)]_{\mathcal{C}}) \in \mathcal{M}_{m \times n}.$$

**Example:** Projection onto the line  $x_1 = x_2$

$$P \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{x_1 + x_2}{2} \\ \frac{x_1 + x_2}{2} \end{pmatrix} \text{ has standard matrix } \begin{pmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{pmatrix}.$$

This is the matrix of  $P$  w.r.t. the standard basis.

**Question:** What is  $[P]_{\mathcal{B}}^{\mathcal{B}}$  where  $\mathcal{B} = \{(1, 1)^T, (-1, 1)^T\}$ ?

**Conclusion:** The matrix of a transformation depends on the chosen basis. Some are better than others!

- Solve the differential equation for  $u$ :  $du/dt = 3u$ .

The solution is  $u(t) = c e^{3t}$ ,  $c \in \mathbb{R}$ . With initial condition  $u(0) = 2$ , the solution is  $u(t) = 2e^{3t}$ .

- Consider the system of linear 1<sup>st</sup> order differential equations (ODE) with constant coefficients:

$$du_1/dt = 4u_1 - 5u_2,$$

$$du_2/dt = 2u_1 - 3u_2,$$

How does one find the solution?

- Write the system in matrix form

$$du/dt = Au,$$

where  $u(t) = \begin{pmatrix} u_1(t) \\ u_2(t) \end{pmatrix}$ ,  $A = \begin{pmatrix} 4 & -5 \\ 2 & -3 \end{pmatrix}$ .

- Assuming the solution is  $u(t) = e^{\lambda t} v$ , where  $v = \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2$ , we need to find  $\lambda$  and  $v$ .

# Eigenvalues and Eigenvectors: Definition

We have  $u'_1 = 4u_1 - 5u_2$ ,  $u'_2 = 2u_1 - 3u_2$ , where  $u_1(t) = e^{\lambda t} x$ ,  $u_2(t) = e^{\lambda t} y$

$$\lambda e^{\lambda t} x = 4e^{\lambda t} x - 5e^{\lambda t} y,$$

$$\lambda e^{\lambda t} y = 2e^{\lambda t} x - 3e^{\lambda t} y.$$

Cancelling  $e^{\lambda t}$ , we get

**Eigenvalue problem:** Find  $\lambda$  and  $v = (x, y)^T$  satisfying

$$4x - 5y = \lambda x,$$

$$2x - 3y = \lambda y.$$

In the matrix form, it is

$$Av = \lambda v$$

. This equation has two unknowns,  $\lambda$  and  $v$ .

If there exists a  $\lambda$  such that  $Av = \lambda v$  has a non-zero solution  $v$ , then  $\lambda$  is called an **eigenvalue** of  $A$  and all *nonzero*  $v$  satisfying  $Av = \lambda v$  are called **eigenvectors** of  $A$  associated to  $\lambda$ .

**Question:** How many eigenvalues can  $A$  have? How do we find them & the associated eigenvectors? Reduce the number of unknowns!

# Eigenvalues and Eigenvectors: Solving $Ax = \lambda x$

- Rewrite  $Av = \lambda v$  as  $(A - \lambda I)v = 0$ .
- $\lambda$  is an eigenvalue of  $A$ 
  - $\Leftrightarrow$  there is a nonzero  $v$  in the nullspace of  $A - \lambda I$
  - $\Leftrightarrow N(A - \lambda I) \neq 0$ , i.e.,  $\dim(N(A - \lambda I)) \geq 1$ ,
  - $\Leftrightarrow A - \lambda I$  is not invertible
  - $\Leftrightarrow \det(A - \lambda I) = 0$ .
- $\det(A - \lambda I)$  is a polynomial in the variable  $\lambda$  of degree  $n$ . Hence it has *at most*  $n$  roots  $\Rightarrow A$  has at most  $n$  eigenvalues.
- $\det(A - \lambda I)$  is called the **characteristic polynomial** of  $A$ .
- If  $\lambda$  is an eigenvalue of  $A$ , then the nullspace of  $A - \lambda I$  is called the **eigenspace** of  $A$  associated to eigenvalue  $\lambda$ .

**Question:** When is 0 an eigenvalue of  $A$ ? What are the corresponding eigenvectors?

**To summarise:** An eigenvalue of  $A$  is a root (in  $\mathbb{R}$ ) of its characteristic polynomial. Any non-zero vector in the corresponding eigenspace is an associated eigenvector.

**Recall:** The ODE system we want to solve is

$$u_1' = 4u_1 - 5u_2, \quad u_2' = 2u_1 - 3u_2,$$

The solutions are  $u_1(t) = e^{\lambda t} x$ ,  $u_2(t) = e^{\lambda t} y$ , where  $(x, y)^T$  is a solution of:

$$\begin{pmatrix} 4 & -5 \\ 2 & -3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \lambda \begin{pmatrix} x \\ y \end{pmatrix} \quad (Av = \lambda v)$$

The characteristic polynomial of  $A$  is  $\det(A - \lambda I)$

$$= \det \begin{pmatrix} 4-\lambda & -5 \\ 2 & -3-\lambda \end{pmatrix} = (4-\lambda)(-3-\lambda) + 10 = \lambda^2 - \lambda - 2 = (\lambda + 1)(\lambda - 2)$$

The eigenvalues of  $A$  are  $\lambda_1 = -1, \lambda_2 = 2.$

Eigenvectors  $v_1$  and  $v_2$  associated to  $\lambda_1 = -1$  and  $\lambda_2 = 2$  respectively are in:  $N(A - \lambda_1 I) = N(A + I)$ , and  $N(A - \lambda_2 I) = N(A - 2I)$ .

Solving  $(A + I)v = 0$ , i.e.,  $\begin{pmatrix} 5 & -5 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 0$ , we get  $N(A + I) =$

$\left\{ \begin{pmatrix} y \\ y \end{pmatrix} \mid y \in \mathbb{R} \right\}$  and hence  $v_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  is an eigenvector associated to  $\lambda_1 = -1$ .

Similarly, solving  $(A - 2I)v = 0$  gives  $N(A - 2I) = \left\{ \begin{pmatrix} \frac{5y}{2} \\ y \end{pmatrix} \mid y \in \mathbb{R} \right\}$ . In

particular,  $v_2 = \begin{pmatrix} 5 \\ 2 \end{pmatrix}$  is an eigenvector associated to  $\lambda_2 = 2$ .

Thus, the system  $du/dt = Au$  has two special solutions  $e^{-t}v_1$  and  $e^{2t}v_2$ .

**Note:** When two functions satisfy  $du/dt = Au$ , then so do their linear combinations.

**Complete solution:**  $u(t) = c_1 e^{-t} v_1 + c_2 e^{2t} v_2$ , i.e.,

$$\begin{pmatrix} u_1(t) \\ u_2(t) \end{pmatrix} = c_1 e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 5 \\ 2 \end{pmatrix}.$$

$$\text{i.e. } u_1(t) = c_1 e^{-t} + 5c_2 e^{2t}, \quad u_2(t) = c_1 e^{-t} + 2c_2 e^{2t}.$$

If we put initial conditions (IC)  $u_1(0) = 8$  and  $u_2(0) = 5$ , then

$$c_1 + 5c_2 = 8, \quad c_1 + 2c_2 = 5 \Rightarrow c_1 = 3, \quad c_2 = 1.$$

Hence the solution of the original ODE system with the given IC is

$$u_1(t) = 3e^{-t} + 5e^{2t}, \quad u_2(t) = 3e^{-t} + 2e^{2t}.$$



In some cases it is easy to find the eigenvalues.

**Example:**  $A = \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix}$  is diagonal. Characteristic polynomial  $(3-\lambda)(2-\lambda)$ .

Eigenvalues:  $\lambda_1 = 3, \lambda_2 = 2$ .

Eigenvectors:  $(A - 3I)v_1 = 0 \Rightarrow Av_1 = 3v_1$ .

Can take  $v_1 = e_1$

Similarly, an eigenvector associated to  $\lambda_2$  is  $v_2 = e_2$

Further,  $\mathbb{R}^2$  has a basis consisting of eigenvectors of  $A$ :  $\{e_1, e_2\}$ .

**Special case:** If  $A$  is a diagonal matrix with diagonal entries  $\lambda_1, \dots, \lambda_n$ , then

Eigenvalues:  $\lambda_1, \dots, \lambda_n$

Eigenvectors:  $e_1, \dots, e_n$ , which form a basis for  $\mathbb{R}^n$ .

## Finding Eigenvalues: Examples

**Example:** Projection onto the line  $x = y$ :  $P = \begin{pmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{pmatrix}$ .  $v_1 = \begin{pmatrix} 1 & 1 \end{pmatrix}^T$

projects onto itself  $\Rightarrow \lambda_1 = 1$  with eigenvector  $v_1$ .  $v_2 = \begin{pmatrix} 1 & -1 \end{pmatrix}^T \mapsto 0$   
 $\Rightarrow \lambda_2 = 0$  with eigenvector  $v_2$ . Further,  $\{v_1, v_2\}$  is a basis of  $\mathbb{R}^2$ .

**Question:** Do a collection of eigenvectors always form a basis of  $\mathbb{R}^n$ ?

**A:** No! **Example:** For  $c \in \mathbb{R}$ , let  $A = \begin{pmatrix} c & 1 \\ 0 & c \end{pmatrix}$ .

Characteristic Polynomial:  $\det(A - \lambda I) = (c - \lambda)^2$ .

Eigenvalues:  $\lambda = c$ .

Eigenvectors:  $(A - I)v = 0 \Rightarrow v = \begin{pmatrix} 1 & 0 \end{pmatrix}^T$

**Question:** Is it unique? Eigenspace of  $A$  is 1 dimensional  $\Rightarrow$   
 $\mathbb{R}^2$  has no basis of eigenvectors of  $A$ .

**Think:** What is the advantage of a basis of eigenvectors?

**Defn.** The  $n \times n$  matrices  $A$  and  $B$  are *similar*, if there exists an invertible matrix  $P$  such that  $P^{-1}AP = B$ .

**Observe:** If  $B = P^{-1}AP$ , then (i)  $\det(A) = \det(B)$ , and (ii)  $B^n = P^{-1}A^nP$  for each  $n$ .

**Theorem:** If  $A$  and  $B$  are similar, then they have the same characteristic polynomial. In particular, they have the same eigenvalues,  $\det(A) = \det(B)$  and  $\text{Trace}(A) = \text{Trace}(B)$ .

*Proof.* Given:  $B = P^{-1}AP$ . prove:  $\det(A - \lambda I) = \det(B - \lambda I)$ .

**Note:** It is enough to prove that  $A - \lambda I$  and  $B - \lambda I$  are similar!

Indeed,  $B - \lambda I = P^{-1}AP - \lambda P^{-1}P$   
$$= P^{-1}(A - \lambda I)P.$$

□

**Ques:** Why care?

Write  $\det(A - \lambda I) = (\lambda_1 - \lambda) \cdots (\lambda_n - \lambda)$ . Compare constant coeff.:

$\det(A) = \lambda_1 \cdots \lambda_n = \det(B)$ ; Compare coeff. of  $\lambda^{n-1}$ : Sum of diagonal entries

$= a_{11} + \cdots + a_{nn} = \text{Trace of } A = \lambda_1 + \cdots + \lambda_n = \text{Trace of } B$ .

**Ques:** How are eigenvalues of  $A$  and  $B$  related?