#### Lecture 29: Locking in xv6

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# Why locking in xv6?

- PI P2 Kernel C data
- No threads in xv6, so no two user programs can access same userspace memory image
  - No need for userspace locks like pthreads mutex
- However, scope for concurrency in xv6 kernel
  - Two processes in kernel mode in different CPU cores can access same kernel data structures  $P \mapsto \text{Kurel} \rightarrow \text{INT}$
  - When a process is running in kernel mode, another trap occurs, and the trap handler can access data that was being accessed by previous kernel code
- Solution: spinlocks used to protect critical sections
  - Limit concurrent access to kernel data structures that can result in race conditions
- xv6 also has a sleeping lock (built on spinlock, not discussed)

### Spinlocks in xv6

- Acquiring lock: uses xchg x86 atomic instruction (test and set)
  - Atomically set lock variable to 1 and returns previous value
  - If previous value is 0, it means free lock has been acquired, success!
  - If previous value is 1, it means lock is held by someone, continue to spin in a busy while loop till success
- Releasing lock: set lock variable to 0
- Must disable interrupts on CPU core before spinning for lock
  - Interrupts disabled only on this CPU core to prevent another trap handler running and requesting same lock, leading to deadlock
  - OK for process on another core to spin for same lock, as the process on this core will release it
  - Disable interrupts before starting to spin (otherwise, vulnerable window after lock acquired and before interrupts disabled)

```
1500 // Mutual exclusion lock.
1501 struct spinlock {
       uint locked:
                           // Is the lock held?
1503
1504
       // For debugging:
1505
       char *name;
                           // Name of lock.
1506
       struct cpu *cpu;
                           // The cpu holding the lock.
       uint pcs[10];
1507
                           // The call stack (an array of program counters)
1508
                           // that locked the lock.
1509 };
1573 void
1574 acquire(struct spinlock *lk)
       pushcli(); // disable interrupts to avoid deadlock.
1576
1577
       if(holding(Tk))
                                                   Success
1578
         panic("acquire");
1579
1580
       // The xchg is atomic.
1581
       while(xchg(&lk->locked, 1)
1582
1583
1584
       // Tell the C compiler and the processor to not move loads or stores
       // past this point, to ensure that the critical section's memory
1586
       // references happen after the lock is acquired.
1587
       __sync_synchronize();
1588
       // Record info about lock acquisition for debugging.
1590
       1k \rightarrow cpu = mycpu():
1591
       getcallerpcs(&lk, lk->pcs);
1592 }
```

### Disabling interrupts

- Must disable interrupts on CPU core before beginning to spin for spinlock
- Interrupts stay disabled until lock is released
- What if multiple spinlocks are acquired?
  - Interrupts must stay disabled until all locks are released
- Disabling/enabling interrupts:
  - pushcli disables interrupts on first lock acquire, increments count for future locks
  - popcli decrements count, reenables interrupts only when all locks released and count is zero

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```
1662 // Pushcli/popcli are like cli/sti except that they are matched:
1663 // it takes two popcli to undo two pushcli. Also, if interrupts
1664 // are off, then pushcli, popcli leaves them off.
1665
1666 void
1667 pushcli(void)
1668 {
1669
      int eflags;
1670
1671
      eflags = readeflags();
1672
      cli():
       if(mycpu()->ncli == 0)
1674
         mycpu()->intena = eflags & FL_IF;
1675
     mycpu()->ncli += 1;
1676
1677
1678 void
1679 popcli(void)
1680 {
      if(readeflags()&FL_IF)
1681
1682
         panic("popcli - interruptible");
1683
      if(--mycpu()->ncli < 0)
1684
         panic("popcli");
1685
       if(mycpu()->ncli == 0 && mycpu()->intena)
1686
         sti();
1687 }
```

#### ptable.lock (1)

```
2409 struct {
2410    struct spinlock lock;
2411    struct proc proc[NPROC];
2412 } ptable;
```

- The process table protected by a lock, any access to ptable must be done with ptable.lock held
- Normally, a process in kernel mode acquires ptable.lock, changes ptable, releases lock
  - Example: when allocproc allocates new struct proc
- But during context switch from process P1 to P2, ptable structure is being changed all through context switch, so when to release lock?
  - P1 acquires lock, switches to scheduler, switches to
     P2, P2 releases lock

If the process is context switched out from P1 to P2, and lock held, then the destination process releases the lock held by the initial process.

## ptable.lock (2)

- Every function that calls sched() to give up CPU will do so with ptable.lock held. Which functions invoke sched()?
  - Yield, when a process gives up CPU due to timer interrupt
  - Sleep, when process wishes to block
  - Exit, when process terminates
- Every function that <u>swtch</u> switches to will release ptable.lock. What functions does swtch return to?
  - Yield, when switching in a process that is resuming after yielding is done
  - Sleep, when switching in a process that is waking up after sleep
  - Forkret for newly created processes
- Purpose of forkret: to release ptable.lock after context switch, before returning from trap to userspace

That's why we don't directly return from the trapret but instead we take the path of forkret to release the lock and then return.

```
2826 // Give up the CPU for one scheduling round.
2827 void
2828 yield(void)
2829 {
2830    acquire(&ptable.lock);
2831    myproc()->state = RUNNABLE;
2832    sched();
2833    release(&ptable.lock);
2834 }
```

```
2852 void
2853 forkret(void)
2854 {
2855
      static int first = 1:
      // Still holding ptable.lock from scheduler.
2857
      release(&ptable.lock);
2858
2859
      if (first) {
2860
        // Some initialization functions must be run in the context
2861
        // of a regular process (e.g., they call sleep), and thus cannot
2862
        // be run from main().
2863
        first = 0:
2864
        iinit(ROOTDEV):
2865
        initlog(ROOTDEV);
2866
      trapret
```

# ptable.lock (3)

- Scheduler goes into loop with lock held
- Switch to P1, P1 switches back to scheduler with lock held, scheduler switches to P2, P2 releases lock
- Periodically, end of looping over all processes, releases lock temporarily
  - What if no runnable process found due to interrupts being disabled?
     Release lock, enable interrupts, allow processes to become runnable.

```
2757 void
2758 scheduler(void)
2759
       struct proc *p;
       struct cpu *c = mycpu();
       c \rightarrow proc = 0:
2763
2764
       for(;;){
         // Enable interrupts on this processor.
2765
2766
2767
2768
         // Loop over process table looking for process to run.
2769
         acquire(&ptable.lock):
2770
         for(p = ptable.proc; p < &ptable.proc[NPROC]; p++){</pre>
2771
           if(p->state != RUNNABLE)
2772
             continue:
2773
2774
           // Switch to chosen process. It is the process's job
           // to release ptable.lock and then reacquire it
           // before jumping back to us.
           c \rightarrow proc = p;
           switchuvm(p);
           p->state = RUNNING;
           swtch(&(c->scheduler), p->context);
           switchkvm():
2784
           // Process is done running for now.
2785
           // It should have changed its p->state before coming back.
2786
           c \rightarrow proc = 0:
2787
2788
         release(&ptable.lock);
2789
2790
2791 }
```

#### Summary

- Spinlocks in xv6 based on xchg atomic instruction
- Processes in kernel mode hold spinlock when accessing shared data structures, disabling interrupts on that core while lock is held
- Special ptable.lock held across context switch