### Probabilistic Forecast Reconciliation

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  - Daily series is aggregate of 24 hourly series.
- Potentially need forecasts of all time series.

Potential approaches

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- Outcome does respect aggregation structure (Coherent)
- Motivation is aggregation but can be generalised to any linear constraints.

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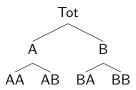
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- Getting there necessitates a rethink of the existing point forecasting literature.

## A simple hierarchy

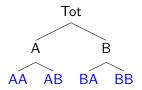
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## A simple hierarchy

### Consider a hierarchy given by



- Let n be the number of series,  $y_t$  be an n-vector of all series.
- Let m be the number of bottom level series and  $b_t$  be an m-vector of the bottom level series.



### The S matrix

Coherence holds when

$$y = Sb$$

The  $n \times m$  matrix **S** defines the aggregation constraints, e.g.

$$m{S} = egin{pmatrix} 1 & 1 & 1 & 1 \ 1 & 1 & 0 & 0 \ 0 & 0 & 1 & 1 \ & m{I}_{4 imes4} & & \end{pmatrix}$$

# As a regression model

• Cast the problem as a regression model with base forecasts  $\hat{y}_{T+h}$  as the "dependent variable" and S as the "design matrix".

$$\hat{m{y}}_{T+h} = m{S}m{eta}_{T+h} + m{e}_{T+h}$$

• Initial approach (Athanasopoulos et al, 2009; Hyndman et al, 2011) was to fit by OLS yielding reconciled forecasts:

$$ilde{oldsymbol{y}}_{T+h} = oldsymbol{S}(oldsymbol{S}'oldsymbol{S})^{-1}oldsymbol{S}'\hat{oldsymbol{y}}_{T+h}$$

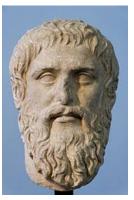


### Generalisation

Wherever we can use OLS we can use GLS

$$\tilde{\mathbf{y}}_{T+h} = \mathbf{S}(\mathbf{S}'\mathbf{W}^{-1}\mathbf{S})^{-1}\mathbf{S}'\mathbf{W}^{-1}\hat{\mathbf{y}}_{T+h}$$

- Diagonal W considered by Athanasopoulos et al (2017)
- MinT approach (Wickremasuriya et al, 2018) use a W that is an estimate of the in-sample forecast error covariance matrix.



 $\label{eq:approx} \mathsf{A}\mathsf{\Gamma}\mathsf{E}\Omega\mathsf{M}\mathsf{T}\mathsf{E}\mathsf{T}\mathsf{P}\mathsf{H}\mathsf{T}\mathsf{O}\Sigma\ \mathsf{M}\mathsf{H}\Delta\mathsf{E}\mathsf{I}\Sigma\ \mathsf{E}\mathsf{I}\Sigma\mathsf{I}\mathsf{T}\Omega$  Those without knowledge of geometry may not enter.

## Coherent Subspace

#### Definition

The **coherent subspace** is the *m*-dimensional linear subspace of  $\mathbb{R}^n$  spanned by the columns of S, i.e.  $\mathfrak{s} = \mathsf{sp}(S)$ 

Instead of using bottom-level series a different combination of m basis series could be used (e.g. top and m-1 bottom). Although  ${\boldsymbol S}$  would be different  ${\mathfrak s}$  would be the same.

## Coherent Point Forecast

#### Definition

A **coherent point forecast** is any forecast lying in the linear subspace  $\mathfrak s$ 

## Reconciled Point Forecast

Let  $\hat{\mathbf{y}} \in \mathbb{R}^n$  be an incoherent forecast and g(.) be a function  $g: \mathbb{R}^n \to \mathbb{R}^m$ .

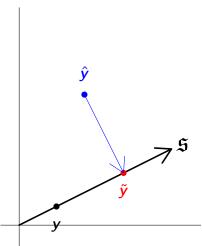
#### Definition

A **point forecast**  $\tilde{y}$  is reconciled with respect to g(.) iff

$$\tilde{\pmb{y}} = \pmb{S}g(\hat{\pmb{y}})$$

when g(.) is linear it is easier to write  $\tilde{y} = SG\hat{y}$ 

# Geometry



## Why reconciliation works

- The realised observation always lies on s.
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- The realised observation always lies on s.
- Orthogonal projections always get us 'closer' to all points in sincluding the actual realisation.
- Ergo reconciliation reduces the error and not just in expectation.
- What about the MinT approach?

• Consider the covariance matrix of  $y_{T+h} - \hat{y}_{T+h}$ .

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- This can be estimated using in-sample forecast errors.

$$\mathbf{W} = \sum_{t=1}^{T} (\mathbf{y}_t - \hat{\mathbf{y}}_t)(\mathbf{y}_t - \hat{\mathbf{y}}_t)'$$

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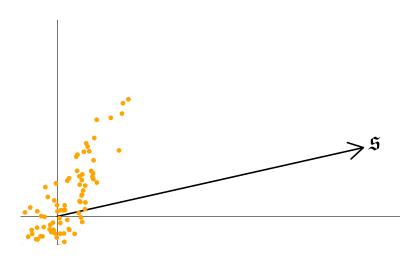
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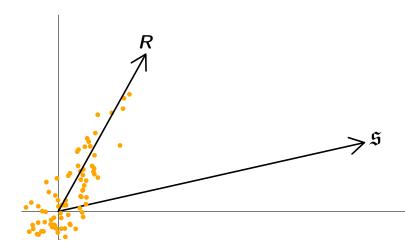
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- This provides information about the likely direction of an error.
- Projecting along this direction is more likely to result in a reconciled forecast that is closer to the target.

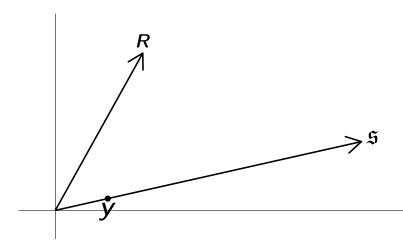
# In-Sample errors



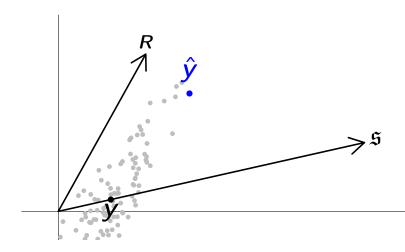
## Most likely direction



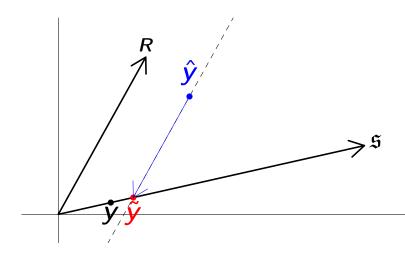
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- When we generalise to probabilistic forecasts the regression interpretation does not really fit.
- Geometric ideas can easily be generalised.

### Coherent Probabilistic Forecast

Let  $(\mathbb{R}^m, \mathcal{F}_{\mathbb{R}^m}, \nu)$  and  $(\mathfrak{s}, \mathcal{F}_{\mathfrak{s}}, \mu)$  be probability triples on m-dimensional space and the coherent subspace respectively.

#### Definition

The probability measure  $\mu$  is coherent if

$$u(\mathcal{B}) = \mu(s(\mathcal{B})) \quad \forall \mathcal{B} \in \mathcal{F}_{\mathbb{R}_m}$$

where  $s(\mathcal{B})$  is the image of  $\mathcal{B}$  under premultiplication by  $\boldsymbol{S}$ 

#### Reconciled Probabilistic Forecast

Let  $g: \mathbb{R}^n \to \mathbb{R}^m$  be a function. Then

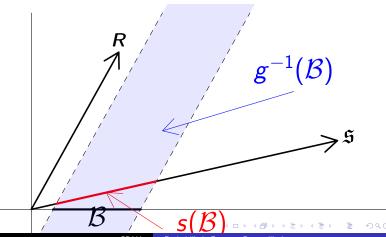
#### Definition

The probability triple  $(\mathfrak{s}, \mathcal{F}_{\mathfrak{s}}, \tilde{\nu})$  reconciles the probability triple  $(\mathbb{R}^n, \mathcal{F}_{\mathbb{R}^n}, \hat{\nu})$  with with respect to g iff

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where  $g^{-1}$  is the pre-image of g.

### Geometry



## **Analytically**

If we have an unreconciled density the reconciled density can be obtained by linear transformations and marginalisation.

$$\begin{aligned} \Pr(\tilde{\boldsymbol{b}} \in \mathcal{B}) &= \Pr(\hat{\boldsymbol{y}} \in g^{-1}(\mathcal{B})) \\ &= \int\limits_{g^{-1}(\mathcal{B})} f(\hat{\boldsymbol{y}}) d\hat{\boldsymbol{y}} \\ &= \int\limits_{\mathcal{B}} \int f(\boldsymbol{S}\tilde{\boldsymbol{b}} + \boldsymbol{R}\tilde{\boldsymbol{a}}) |\left(\boldsymbol{S} \ \boldsymbol{R}\right)| d\tilde{\boldsymbol{a}} d\tilde{\boldsymbol{b}} \end{aligned}$$

### Elliptical distributions

Consider case where the base and true predictive distributions are elliptical.

#### Theorem

There exists a matrix G such that the true predictive distribution can be recovered by linear reconciliation.

This follows from the closure property of elliptical distributions under affine transformations and marginalisation.

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- Suppose  $\hat{\mathbf{y}}_{T+h}^{[1]}, \dots, \hat{\mathbf{y}}_{T+h}^{[J]}$  is a sample from the unreconciled probabilistic forecast.

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- Often densities are unavailable but we can simulate a sample from the predictive distribution.
- Suppose  $\hat{\mathbf{y}}_{T+h}^{[1]}, \dots, \hat{\mathbf{y}}_{T+h}^{[J]}$  is a sample from the unreconciled probabilistic forecast.
- Then setting  $\tilde{\mathbf{y}}_{T+h}^{[j]} = \mathbf{SG}\hat{\mathbf{y}}_{T+h}^{[j]}$  produces a sample from the reconciled distribution with respect to g.

### Multivariate Scores

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  - Log Score
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- Scoring rules can be used to evaluate probabilistic forecasts
  - Log Score
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- We may want to compare
  - Coherent v Incoherent
  - Coherent v Coherent

#### Coherent v Incoherent

When using log score

#### Theorem

Let f(y) be the true predictive density (on  $\mathfrak{s}$ ) and LS be the (negatively-oriented) log score. Then there exists an unreconciled density  $\hat{f}(y)$  on  $\mathbb{R}^n$  such that

$$E_{\mathbf{y}}\left[LS(\hat{f},\mathbf{y})\right] < E_{\mathbf{y}}\left[LS(f,\mathbf{y})\right]$$

The log score is not proper in this context.

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  - Bottom up does not do well.
  - OLS (an orthogonal projection) does reasonably well.
  - MinT (an oblique projection) does best.

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- How should probabilistic reconciliation work for non-elliptical distributions.
- Are non-linear reconciliation methods worthwhile?
- Further development of multivariate scoring rules.