

# Probabilistic Forecast Reconciliation

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  - Daily series is aggregate of 24 hourly series.
- Potentially need forecasts of all time series.

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- Potential approaches
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- Forecasts do not respect aggregation structure (**Incoherent**)
- Outcome *does* respect aggregation structure (**Coherent**)
- Motivation is aggregation but can be generalised to any linear constraints.



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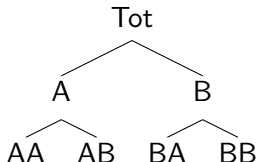
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- There are good solutions for point forecasting that:
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- Generalisation to probabilistic forecasts is our contribution.
- Getting there necessitates a rethink of the existing point forecasting literature.

## A simple hierarchy

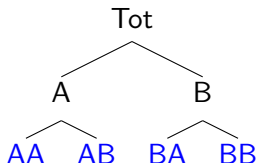
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- Let  $n$  be the number of series,  $\mathbf{y}_t$  be an  $n$ -vector of all series.
- Let  $m$  be the number of bottom level series and  $\mathbf{b}_t$  be an  $m$ -vector of the bottom level series.

# The $\mathbf{S}$ matrix

Coherence holds when

$$\mathbf{y}_t = \mathbf{S}\mathbf{b}_t$$

The  $n \times m$  matrix  $\mathbf{S}$  defines the aggregation constraints, e.g.

$$\mathbf{S} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ \mathbf{I}_{4 \times 4} \end{pmatrix}$$



# As a regression model

- Cast the problem as a regression model with base forecasts  $\hat{\mathbf{y}}_{T+h}$  as the “dependent variable” and  $\mathbf{S}$  as the “design matrix”.

$$\hat{\mathbf{y}}_{T+h} = \mathbf{S}\boldsymbol{\beta}_{T+h} + \mathbf{e}_{T+h}$$

- Initial approach (Athanasopoulos et al, 2009; Hyndman et al, 2011) was to fit by OLS yielding reconciled forecasts:

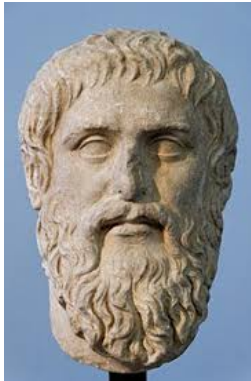
$$\tilde{\mathbf{y}}_{T+h} = \mathbf{S}(\mathbf{S}'\mathbf{S})^{-1}\mathbf{S}'\hat{\mathbf{y}}_{T+h}$$

# Generalisation

- Wherever we can use OLS we can use GLS

$$\tilde{\mathbf{y}}_{T+h} = \mathbf{S}(\mathbf{S}'\mathbf{W}^{-1}\mathbf{S})^{-1}\mathbf{S}'\mathbf{W}^{-1}\hat{\mathbf{y}}_{T+h}$$

- Diagonal  $\mathbf{W}$  considered by Athanasopoulos et al (2017)
- MinT approach (Wickremasuriya et al, 2018) use a  $\mathbf{W}$  that is an estimate of the *in-sample* forecast error covariance matrix.



ΑΓΕΩΜΤΕΤΡΗΤΟΣ ΜΗΔΕΙΣ ΕΙΣΙΤΩ

Those without knowledge of geometry may not enter.

# Coherent Subspace

## Definition

The **coherent subspace** is the  $m$ -dimensional linear subspace of  $\mathbb{R}^n$  spanned by the columns of  $\mathbf{S}$ , i.e.  $\mathfrak{s} = \text{sp}(\mathbf{S})$

Instead of using bottom-level series a different combination of  $m$  **basis series** could be used (e.g. top and  $m - 1$  bottom).  
Although  $\mathbf{S}$  would be different  $\mathfrak{s}$  would be the same.

# Coherent Point Forecast

## Definition

A **coherent point forecast** is any forecast lying in the linear subspace  $\mathcal{S}$

# Reconciled Point Forecast

Let  $\hat{\mathbf{y}} \in \mathbb{R}^n$  be an incoherent forecast and  $g(\cdot)$  be a function  $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$ .

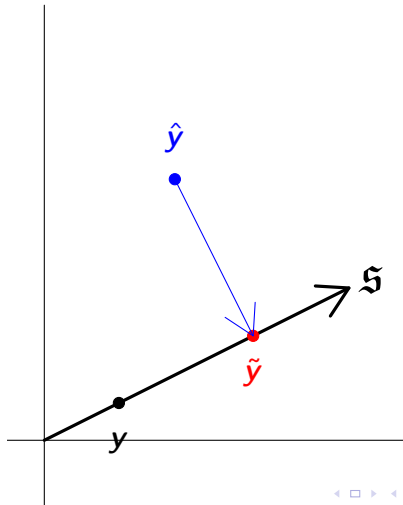
## Definition

A **point forecast**  $\tilde{\mathbf{y}}$  is reconciled with respect to  $g(\cdot)$  iff

$$\tilde{\mathbf{y}} = \mathbf{S}g(\hat{\mathbf{y}})$$

when  $g(\cdot)$  is linear it is easier to write  $\tilde{\mathbf{y}} = \mathbf{S}\mathbf{G}\hat{\mathbf{y}}$

# Geometry



# Why reconciliation works

- The realised observation always lies on  $\mathfrak{s}$ .
- Orthogonal projections always get us 'closer' to all points in  $\mathfrak{s}$  including the actual realisation.
- Ergo reconciliation reduces the error and not just in expectation.



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- The realised observation always lies on  $\mathfrak{s}$ .
- Orthogonal projections always get us 'closer' to all points in  $\mathfrak{s}$  including the actual realisation.
- Ergo reconciliation reduces the error and not just in expectation.
- What about the MinT approach?

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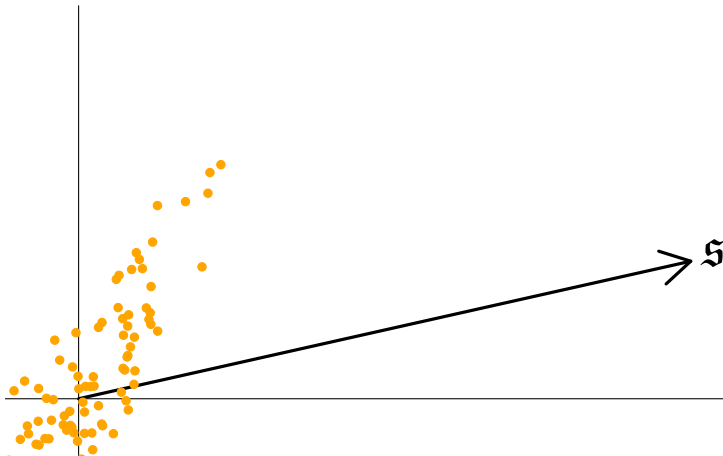
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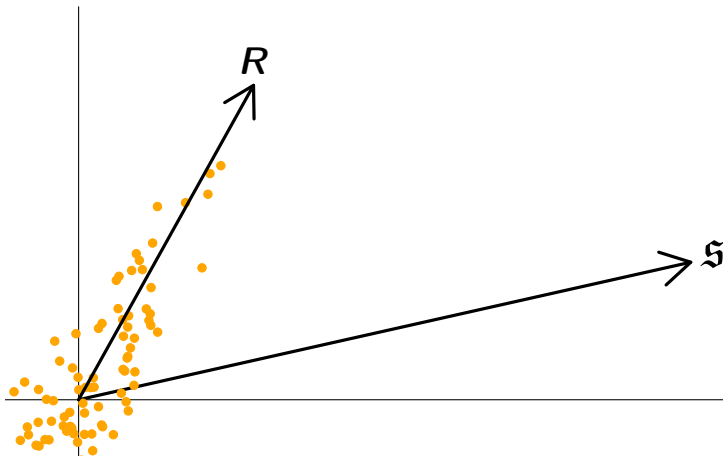
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- This provides information about the likely direction of an error.
- Projecting along this direction is more likely to result in a reconciled forecast that is closer to the target.

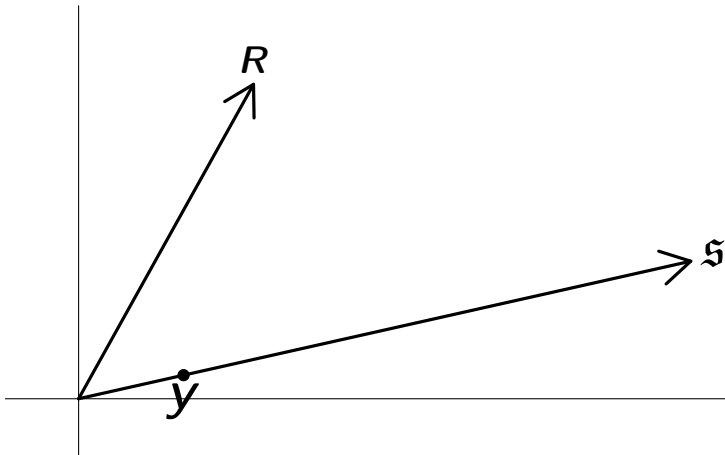
# In-Sample errors



## Most likely direction

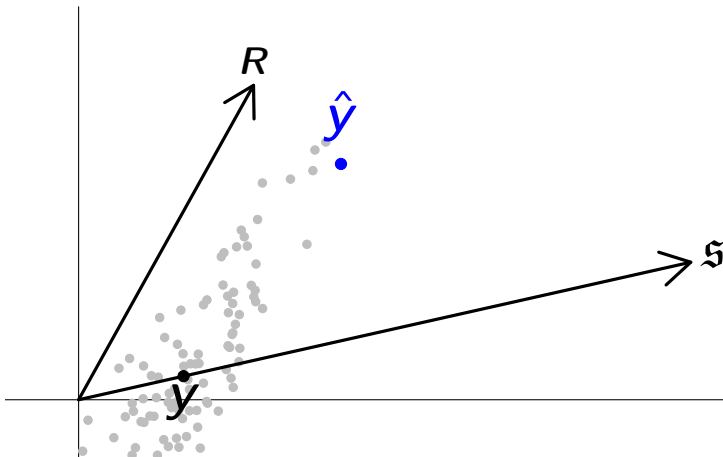


# Geometry: Oblique Projection

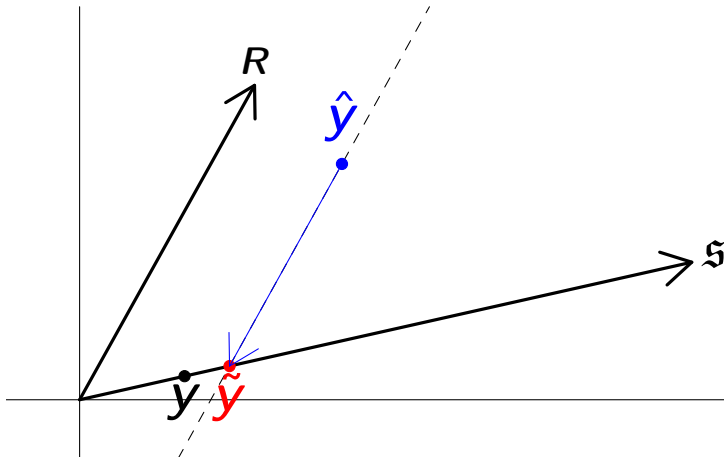




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- When we generalise to probabilistic forecasts the regression interpretation does not really fit.
- Geometric ideas can easily be generalised.

# Coherent Probabilistic Forecast

Let  $(\mathbb{R}^m, \mathcal{F}_{\mathbb{R}^m}, \nu)$  and  $(\mathfrak{s}, \mathcal{F}_{\mathfrak{s}}, \mu)$  be probability triples on  $m$ -dimensional space and the coherent subspace respectively.

## Definition

The probability measure  $\mu$  is coherent if

$$\nu(\mathcal{B}) = \mu(s(\mathcal{B})) \quad \forall \mathcal{B} \in \mathcal{F}_{\mathbb{R}^m}$$

where  $s(\mathcal{B})$  is the image of  $\mathcal{B}$  under premultiplication by  $\mathbf{S}$

# Reconciled Probabilistic Forecast

Let  $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a function. Then

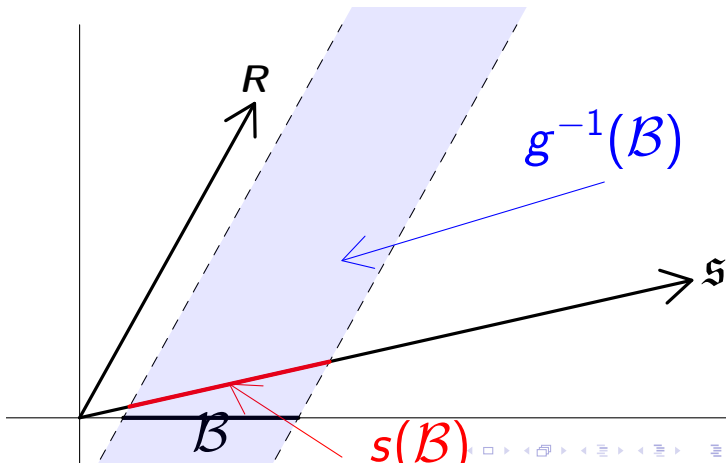
## Definition

The probability triple  $(\mathfrak{s}, \mathcal{F}_{\mathfrak{s}}, \tilde{\nu})$  reconciles the probability triple  $(\mathbb{R}^n, \mathcal{F}_{\mathbb{R}^n}, \hat{\nu})$  with with respect to  $g$  iff

$$\tilde{\nu}(s(\mathcal{B})) = \nu(\mathcal{B}) = \hat{\nu}(g^{-1}(\mathcal{B})) \quad \forall \mathcal{B} \in \mathcal{F}_{\mathbb{R}^m}$$

where  $g^{-1}$  is the pre-image of  $g$ .

# Geometry





# Analytically

If we have an unreconciled density the reconciled density can be obtained by linear transformations and marginalisation.

$$\begin{aligned}
 \Pr(\tilde{\mathbf{b}} \in \mathcal{B}) &= \Pr(\hat{\mathbf{y}} \in g^{-1}(\mathcal{B})) \\
 &= \int_{g^{-1}(\mathcal{B})} f(\hat{\mathbf{y}}) d\hat{\mathbf{y}} \\
 &= \int_{\mathcal{B}} \int f(\mathbf{S}\tilde{\mathbf{b}} + \mathbf{R}\tilde{\mathbf{a}}) |(\mathbf{S} \ \mathbf{R})| d\tilde{\mathbf{a}} d\tilde{\mathbf{b}}
 \end{aligned}$$

# Elliptical distributions

Consider case where the base and true predictive distributions are elliptical.

## Theorem

*There exists a matrix  $\mathbf{G}$  such that the true predictive distribution can be recovered by linear reconciliation.*

This follows from the closure property of elliptical distributions under affine transformations and marginalisation.

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  - Log Score
  - Energy Score
  - Variogram score
- We may want to compare
  - Coherent v Incoherent
  - Coherent v Coherent

# Coherent v Incoherent

When using log score

## Theorem

*Let  $f(\mathbf{y})$  be the true predictive density (on  $\mathfrak{s}$ ) and  $LS$  be the (negatively-oriented) log score. Then there exists an unreconciled density  $\hat{f}(\mathbf{y})$  on  $\mathbb{R}^n$  such that*

$$E_{\mathbf{y}} [LS(\hat{f}, \mathbf{y})] < E_{\mathbf{y}} [LS(f, \mathbf{y})]$$

The log score is not proper **in this context**.

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  - OLS (an orthogonal projection) does reasonably well.
  - MinT (an oblique projection) does best.



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  - It is likely to depend on the specific score used.
- How should probabilistic reconciliation work for non-elliptical distributions.
- Are non-linear reconciliation methods worthwhile?

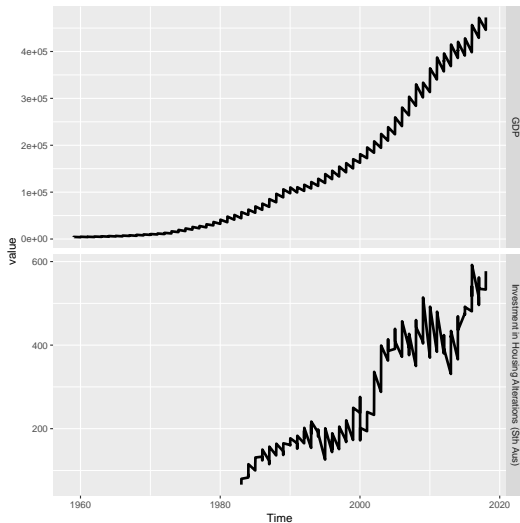


# Thank You!

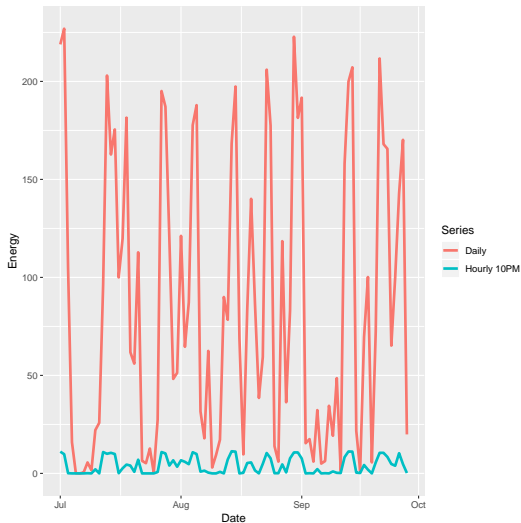
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## Questions?

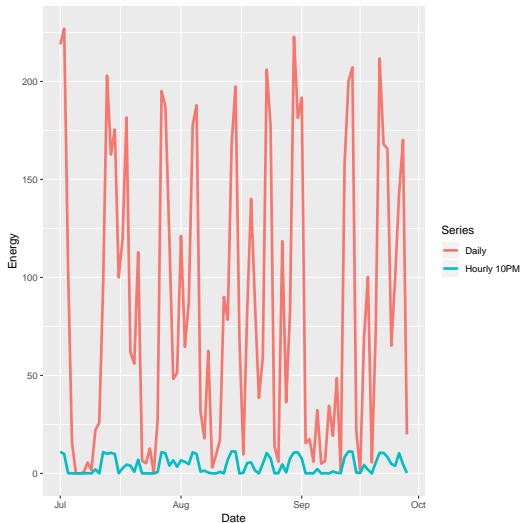
# GDP



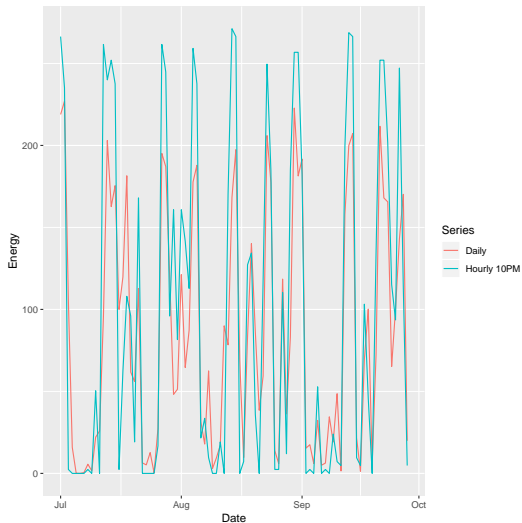
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# What we do NOT do

- Use disaggregate series as predictors (although we can).
- All information is contained in the most disaggregate series.
- In principle using the correct multivariate model for the most disaggregate series and aggregating them should work.
- Disaggregate series are:
  - Very noisy
  - High-dimensional
  - Prone to model misspecification

# Macro Example

Improvement in RMSE of GDP forecasts over seasonal random walk using ARIMA models both without and with reconciliation.

Method	h=1	h=2
Base	56.1496	33.8093
BU	54.1873	36.1718
OLS	56.6164	34.6302
WLS	56.6819	36.0987
MinT Sam.	56.2204	31.6136
MinT Shr.	57.7249	36.8764





# Simulation Results

Hierarchy from earlier bottom series are ARIMA models. Training sample of 500, one-step ahead forecasts, 1000 replications.

Forecasting	Energy score	Variogram score	Log score
MinT(Sample)	<b>10.01</b>	<b>8.41</b>	<b>11.29</b>
OLS	10.53	8.86	11.54
Bottom-up	12.35	9.22	12.05
Incoherent	11.12	9.53	

