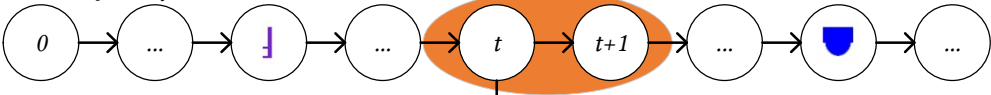


new trajectory to be labeled:



*a relabeled transition (source \dashrightarrow target pair)
that helps estimators understand that it's
impossible to go from $\langle 1, 0 \rangle$ to $\langle 0, 1 \rangle$*

old trajectory sampled by “**pertask**”:

