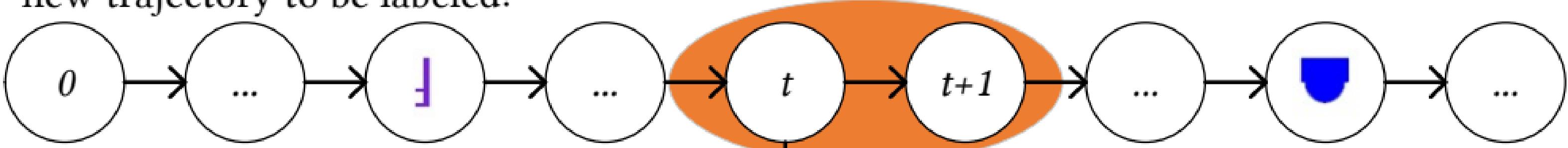


new trajectory to be labeled:



*a relabeled transition (source --• target pair)
that helps estimators understand that it's
impossible to go from <1, 0> to <0, 1>*

old trajectory sampled by “pertask”:

