MIMO Skript - Wintersemester 2013 Kapitel 2

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2 Point - to - Point MIMO Systems

2.1 MIMO Channel Capacity

Inhalt: s. Skript in VL ausgeteilt

2.2 SIMO Systems

Remarks

- In SIMO Systems only <u>coding</u> and <u>diversity</u> <u>gains</u> can be exploited (no multiplexing gains)
- To realize these gains diversity combining has to be performed

- Diversity combining schemes vary in complexity and performance
- There are many diversity combining schemes. Here we consider:
 - Maximal ratio combining (MRC)
 - Equal gain combining (EGC)
 - Selection combining (SC)
- Diversity combining problem

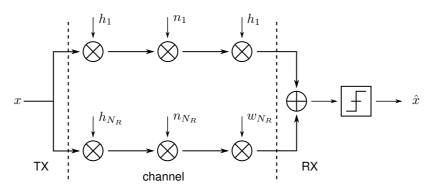


Abbildung 1: Block Diagramm for SIMO

- how to choose combining weights w_n ?
- what performance (e.g. error rate, outage probability) is achieved?
- what diversity and coding/combining gain is achieved?

2.2.1 Preliminaries

Consider an equivalent system:

$$y = hx + n;$$

$$\mathcal{E}\{|x^2|\} = \mathcal{E}_s; \qquad \qquad \mathcal{E}\{|n^2|\} = \sigma_n^2; \qquad \qquad \mathcal{E}\{|h|^2\} = 1$$

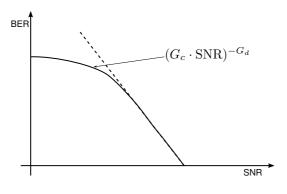


Abbildung 2: Exemplary BER for SIMO

G_c: Coding gain
G_d: Diversity gain

• Instantaneous SNR: $\gamma_t = \frac{\mathcal{E}_s}{\sigma_z^2} \cdot |h|^2$

• Average SNR: $\bar{\gamma}_t = \mathcal{E}\{\gamma_t\} = \frac{\mathcal{E}_s}{\sigma_s^2}$

Bit and Symbol Error Rate

• The Bit and Symbol Error Rate of many modulation schemes can be expressed for given γ_t as:

$$P_e(\gamma_t) = aQ(\sqrt{b\gamma_t})$$

where:

• $Q(x) = \frac{1}{\sqrt{2\pi}} \cdot \int_{x}^{\infty} e^{-\frac{t^2}{2}} dt$

• $P_e(\gamma_t)$ may be exact result or approximation

• BPSK: exact with a = 1, b = 2

• M-ary QAM: tight approximation with $a = 4\left(1 - \frac{1}{\sqrt{M}}\right), b = \frac{3}{M-1}$

 $\left(Einschub:Gray-Code:BER=\frac{1}{\log_2 M}\cdot SER\right)$

• Alternative representation of Q - function:

$$Q(x) = \frac{1}{\pi} \int_0^{\frac{\pi}{2}} e^{-\frac{x^2}{2\sin^2\theta}} \ d\theta$$

 \rightarrow Integral limits are fixed and do not depend on integration variables!

• Average error probability

$$P_e = \mathcal{E}\{P_e(\gamma_t)\} = \int_0^\infty aQ(\sqrt{bx})p_{\gamma_t}(x) dx$$

- Integral may be difficult to solve analytically

- Integral has infinite support \rightarrow numerical evaluation difficult

• Using alternative representation of Q-function we get:

$$P_{e} = \int_{0}^{\infty} \frac{a}{\pi} \int_{0}^{\frac{\pi}{2}} e^{-\frac{bx}{2\sin^{2}\theta}} p_{\gamma_{t}}(x) d\theta dx$$

$$= \frac{a}{\pi} \int_{0}^{\frac{\pi}{2}} \int_{0}^{\infty} p_{\gamma_{t}}(x) e^{-\frac{b}{2\sin^{2}\theta}x} dx d\theta \qquad = \frac{a}{\pi} \int_{0}^{\frac{\pi}{2}} M_{\gamma_{t}}(\frac{b}{2\sin^{2}\theta}) d\theta$$

where:

– $M_{\gamma_t}(s) = \int_0^\infty p_{\gamma_t}(x) e^{-sx} \ dx$ is the Laplace transform of $p_{\gamma_t}(s)$

– $M_{\gamma_t}(-s)$ is the so called Moment Generation Function (MGF) of p_{γ_t}

- Here, we will also refer to $M_{\gamma_t}(s)$ as MGF

- $M_{\gamma_t}(s)$ is sometimes easier to obtain than p_{γ_t}

 The above integral can be easily evaluated numerically because of the finite integral limits

Outage probability

• The outage probability is the probability that the channel cannot support a certain rate, R, i.e. (where γ_T is the threshold SNR):

$$C = \log_2(1 + \gamma_t) < R \quad \leftrightarrow \quad \gamma_t < 2^R - 1 \hat{=} \gamma_T$$

Thus, the outage probability is given by:

$$P_{out} = P_0\{\gamma_t < \gamma_T\} = \int_0^{\gamma_T} p_{\gamma_t}(x) \ dx$$

• Using the inverse Laplace Transform

$$p_{\gamma_t}(x) = \frac{1}{2\pi j} \int_{c-j\omega}^{c+j\omega} M_{\gamma_t}(s) e^{sx} dx$$

where c > 0 is a small constant that lies in the region of convergence of the integral, we obtain:



- 1.

$$P_{out} = \frac{1}{2\pi j} \int_{c-j\omega}^{c+j\omega} M_{\gamma_t}(s) \int_0^{\gamma_T} e^{sx} dx ds = \frac{1}{2\pi j} \int_{c-j\omega}^{c+j\omega} M_{\gamma_t}(s) e^{\gamma_T s} \frac{ds}{s}$$

(lower integral limit is 0 since $p_{\gamma_t}(0) = 0$)

- and 2.:

$$\begin{split} p_{\gamma_t}(x) &= \int_0^x p_{\gamma_t}(t) \ dt = 0 \\ \text{for } x &= 0 \text{ note: } p_{\gamma_t}(x) \xleftarrow{Laplace}_{transform} \frac{1}{s} M_{\gamma_t}(s) \end{split}$$

General combining scheme

$$y = \left(\sum_{n=1}^{N_R} h_n w_n\right) x + \sum_{n=1}^{N_R} w_n n_n$$
$$\gamma_t = \frac{\mathcal{E}_s \left| \sum_{n=1}^{N_R} h_n w_n \right|^2}{\sigma_n^2 \sum_{n=1}^{N_R} |w_n|^2}$$

where w_n depends on the particular combining scheme.

2.2.2 MRC (Maximum Ratio Combining)

• what weight w_n maximize γ_t ?

- Cauchy-Schwarz inequality

$$\left| \sum_{n=1}^{N_R} h_n w_n \right|^2 \le \sum_{n=1}^{N_R} |h_n|^2 \cdot \sum_{n=1}^{N_R} |w_n|^2$$

where equality holds if and only if $w_n = c \cdot h_n^*$ for some non-zero constant c.

- for $w_n = h_n^*$, we obtain

$$\gamma_t = \frac{\mathcal{E}_s}{\sigma_n^2} \cdot \frac{\left(\sum_{n=1}^{N_R} |h_n|^2\right)^2}{\sum_{n=1}^{N_R} |h_n|^2} = \frac{\mathcal{E}_s}{\sigma_n^2} \sum_{n=1}^{N_R} |h_n|^2$$

- $w_n = h_n^* \, \forall \, n$ are the MRC combining weights.
- For performance analysis we assume independent identically distributed (IID) Rayleigh fading

• Error rate

$$\gamma_t = \sum_{n=1}^{N_R} \gamma_n$$

 \rightarrow sum of IID random variables (r.v.s.)

$$M_{\gamma_t}(s) = \left(M_{\gamma}(s)\right)^{N_R} = \frac{1}{(1+s\bar{\gamma})^{N_R}} = \frac{1}{\bar{\gamma}^{N_R}} \cdot \frac{1}{(s+\frac{1}{\bar{\kappa}})^{N_R}}$$

inverse Laplace-transform (from tables)

$$p_{\gamma_t}(x) = \frac{1}{\bar{\gamma}^{N_R}} \cdot \frac{x^{N_R - 1}}{(N_R - 1)!} e^{-\frac{x}{\bar{\gamma}}}; \quad x \ge 0$$

• Direct approach

$$P_e = \int_0^\infty a \cdot Q(\sqrt{ax}) p_{\gamma_t}(x) \ dx = a \left(\frac{1-\mu}{2}\right)^{N_R} \cdot \sum_{n=0}^{N_R-1} \binom{N_R-1+n}{n} \left(\frac{1+\mu}{2}\right)^n$$
 where $\mu = \sqrt{\frac{b\bar{\gamma}}{2+b\bar{\gamma}}}$

• MGF approach

$$P_e = \frac{a}{\pi} \int_0^{\frac{\pi}{2}} M_{\gamma_t} \left(\frac{b}{2 \sin^2 \theta} \right) d\theta$$

$$= \frac{a}{\pi} \int_0^{\frac{\pi}{2}} \frac{1}{\bar{\gamma}^{N_R} \left(\frac{b}{2 \sin^2 \theta} + \frac{1}{\bar{\gamma}} \right)^{N_R}} d\theta \quad \text{(numerisch berechnen!)}$$

• with high SNR: $\bar{\gamma} \to \infty \iff \frac{1}{\bar{\gamma}} \to 0$ and with MGF approach this leads to Average Error Probability P_e :

$$\begin{split} P_e &= \frac{a}{\pi} \cdot \frac{1}{\bar{\gamma}^{N_R}} \cdot \left(\frac{2}{b}\right)^{N_R} \int_0^{\frac{\pi}{2}} \sin^{2N_R} \theta \ d\theta \\ &= \frac{a}{2^{N_R+1} \cdot b^{N_R}} \left(\frac{2N_R}{N_R}\right) \frac{1}{\bar{\gamma}^{N_R}} \quad \text{as } \bar{\gamma} \to \infty \\ &\stackrel{!}{=} \left(\frac{1}{G_c \bar{\gamma}}\right) \end{split}$$

where:

$$-\int_0^{\frac{\pi}{2}} \sin^{2N_R} \theta \ d\theta = \frac{\pi}{2^{N_R+1}} \cdot \binom{2N_R}{N_R}$$

– Diversity gain: $G_d = N_R$

- Combining/Coding gain:
$$G_c = 2b \left(\frac{a}{2} {2N_R \choose N_R}\right)^{-\frac{1}{N_R}}$$

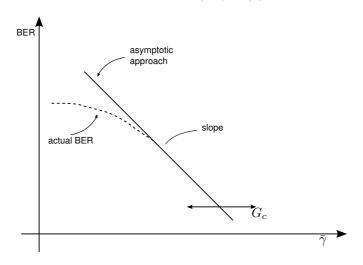


Abbildung 3: BER for average SNR $\bar{\gamma}_t$

- MRC exploits the maximal possible diversity
- Diversity gain is not affected by correlation as the branches are not fully correlated
- Diversity gain depends on fading distribution

Outage probability

$$P_{out} = \int_0^{\gamma_T} p_{\gamma_t}(x) \ dx = \frac{1}{\bar{\gamma}^{N_R}} \int_0^{\gamma_T} \frac{x^{N_R - 1}}{(N_R - 1)!} e^{-\frac{x}{\bar{\gamma}}} \ dx$$
$$= 1 - e^{-\frac{\gamma_T}{\bar{\gamma}}} \cdot \sum_{n=1}^{N_R} \frac{\left(\frac{\gamma_T}{\bar{\gamma}}\right)^n}{(n-1)!}$$

• Approximation (Taylor series): $\bar{\gamma} \to \infty$: $-e^{-\frac{x}{\bar{\gamma}}} = 1 - \frac{x}{\bar{\gamma}} + O(\frac{1}{\bar{\gamma}})$ where a function f(x) is O(x) if $\lim_{x \to \infty} \frac{f(x)}{x} = 0$.

$$\Rightarrow P_{out} = \frac{1}{\gamma^{N_R}} \int\limits_{0}^{\gamma_T} \frac{x^{N_R - 1}}{(N_R - 1)!} \left(1 - \frac{x}{\bar{\gamma}} + O\left(\frac{1}{\bar{\gamma}}\right) \right)$$

• Diversity and coding gain can also be defined for P_{out}

2.2.3 EGC (Equal Gain Combining)

Combining Weights

- For MRC, both, the amplitudes and phases of the channel gains $h_n = |h_n|e^{j\varphi_n}$ have to be known (or estimated in practice)
- In EGC it is assumed that only the phases are known and weights $w_n = e^{-j\varphi_n}$ are used.

$$\Rightarrow \gamma_t = \frac{\mathcal{E}_s}{\sigma_n^2} \frac{\left| \sum_{n=1}^{N_R} |h_n| e^{j\varphi_n} e^{-j\varphi_n} \right|^2}{\sum_{n=1}^{N_R} |e^{-j\varphi_n}|^2} = \frac{\mathcal{E}_s}{\sigma_n^2} \frac{1}{N_R} \left(\sum_{n=1}^{N_R} |h_n| \right)^2$$
$$= \frac{1}{N_R} \left(\sum_{n=1}^{N_R} \sqrt{\gamma_n} \right)^2; \text{ with } \gamma_n = \frac{\mathcal{E}_s}{\sigma_n^2} |h_n|^2$$

Performance Analysis

- IID case
 - $\Rightarrow \sqrt{\gamma_n}$ is Rayleigh distributed
 - \Rightarrow Exact analysis is much more difficult than for MRC \Rightarrow see book by Simon & Alouini p.341
- Approximate result

$$P_{e} = \frac{a}{2} \left[1 - \sqrt{\frac{2b\bar{\gamma}}{5 + 2b\bar{\gamma}}} \sum_{n=0}^{N_{R}-1} \frac{\binom{2n}{n}}{4^{n} (1 + \frac{2}{5}b\bar{\gamma})^{n}} \right]$$

- high SNR
 - \Rightarrow use high SNR analysis of Wang & Giannakis, 2003
 - \Rightarrow at high SNR, only pdf of γ_n around 0 is relevant for performance

$$\Rightarrow \begin{array}{l} \text{Rayleigh} \\ p_{\gamma}(x) = \frac{1}{\bar{\gamma}} e^{-\frac{x}{\bar{\gamma}}} \stackrel{\text{Taylor Serie}}{=} \frac{1}{\bar{\gamma}} + O\left(\frac{1}{\bar{\gamma}}\right) \text{ as } x \to 0 \end{array}$$

• need pdf γ_t : (γ_n bekannt, \rightarrow ges.: Wurzel, etc.) (cumulative distribution function of $\sqrt{\gamma}$ (cdf))

$$P_{\sqrt{\gamma}}(x) = \Pr\{\sqrt{\gamma} \le x\} = \Pr\{\gamma \le x^2\} = P_{\gamma}(x^2) = \text{cdf of } \gamma$$
$$\to p_{\sqrt{\gamma}}(x) = \frac{d}{dx} P_{\sqrt{\gamma}}(x) = 2x \cdot p_{\gamma}(x^2) = \frac{2x}{\bar{\gamma}} + O\left(\frac{1}{\bar{\gamma}}\right)$$

• Laplace Transformation to MGF

• inverse Laplace Transform

$$\begin{split} p_{\sqrt{\gamma_{t}}}(x) &= \mathcal{L}^{-1}\Big\{M_{\sqrt{\gamma_{t}}}(s)\Big\} = \left(\frac{2N_{R}}{\bar{\gamma}}\right)^{N_{R}} \cdot \frac{x^{2N_{R}-1}}{(2N_{R}-1)!} + O\left(\frac{1}{\bar{\gamma}^{N_{R}}}\right) \\ P_{\gamma_{t}}(x) &= \Pr\{\gamma_{t} \leq x\} = \Pr\{\sqrt{\gamma_{t}} \leq \sqrt{x}\} = P_{\sqrt{\gamma_{t}}}(\sqrt{x}) \to \operatorname{cdf of } \sqrt{\gamma_{t}} \\ p_{\gamma_{t}}(x) &= \frac{d}{dx}P_{\gamma_{t}}(x) = \frac{1}{2\sqrt{x}} \cdot p_{\gamma_{t}}(\sqrt{x}) = \frac{1}{2}\left(\frac{2N_{R}}{\bar{\gamma}}\right)^{N_{R}} \cdot \frac{x^{N_{R}-1}}{(2N_{R}-1)!} + O\left(\bar{\gamma}^{-N_{R}}\right) \\ \to M_{\gamma_{t}}(s) &= \mathcal{L}\{p_{\gamma_{t}}(x)\} = \frac{1}{2}\left(\frac{2N_{R}}{\bar{\gamma}}\right)^{N_{R}} \cdot \frac{(N_{R}-1)!}{(2N_{R}-1)!} \cdot b^{N_{R}} + O\left(\bar{\gamma}^{-N_{R}}\right) \end{split}$$

• Error Probability:

$$P_{e} = \frac{a}{\pi} \int_{0}^{\frac{\pi}{2}} M_{\gamma_{t}} \left(\frac{b}{2 \sin^{2}(\theta)} \right) d\theta$$

$$= \frac{a}{\pi} \frac{1}{2} \left(\frac{2N_{R}}{\bar{\gamma}} \right)^{N_{R}} \frac{(N_{R} - 1)!}{(2N_{R} - 1)!} \frac{2^{N_{R}}}{b^{N_{R}}} \int_{0}^{\frac{\pi}{2}} \sin^{2N_{R}}(\theta) d\theta + O\left(\frac{1}{\bar{\gamma}^{N_{R}}} \right)$$

$$= \frac{aN_{R}^{N_{R}}}{2b^{N_{R}}N_{R}!} \frac{1}{\bar{\gamma}^{N_{R}}} + O\left(\frac{1}{\bar{\gamma}^{N_{R}}} \right) \stackrel{!}{=} \left(\frac{1}{G_{c} \cdot \bar{\gamma}} \right)^{G_{d}}$$

$$\Rightarrow \text{Diversity gains } G = N$$

 \implies Diversity gain: $G_d = N_R$

$$\implies$$
 Combining gain: $G_c = \frac{b}{N_R} \left(\frac{2N_R!}{a}\right)^{\frac{1}{N_R}}$

vergleiche auch Blatt mit Kurven III und IV

A similar asymptotic analysis can be conducted for the outage probability.

2.2.4 SC (Selection Combining)

Combining weights

- only the strongest branch is chosen
- strongest branch: $\hat{n} = \underset{n}{\operatorname{argmax}} \gamma_n \longrightarrow \gamma_t = \gamma_{\hat{n}}$
- ullet only on RF receiver chain required o saves hardware complexity

Performance analysis

• cdf of: γ_t

$$P_{\gamma_t}(x) = \Pr\{\gamma_{\hat{n}} \le x\} = \Pr\{\gamma_1 \le x \cap \gamma_2 \le x \cap \dots \gamma_{N_R} \le x\}$$

$$\stackrel{(IID)}{=} \left(\Pr\{\gamma_n \le x\}\right)^{N_R} = \left(P_{\gamma}(x)\right)^{N_R}$$

• pdf:

$$p_{\gamma_t}(x) = \frac{d}{dx} P_{\gamma_t}(x) = N_R \left(P_{\gamma}(x) \right)^{N_R - 1} \cdot p_{\gamma}(x)$$
 where:
$$p_{\gamma}(x) = \frac{1}{\bar{\gamma}} e^{-\frac{x}{\bar{\gamma}}}; \quad x \ge 0$$

$$P_{\gamma}(x) = \int_0^x p_{\gamma}(x) \ dx = 1 - e^{-\frac{x}{\bar{\gamma}}}; \quad x \ge 0$$

$$\to p_{\gamma_t}(x) = \frac{N_R}{\bar{\gamma}} \left(1 - e^{-\frac{x}{\bar{\gamma}}} \right)^{N_R - 1} e^{-\frac{x}{\bar{\gamma}}}; \quad x \ge 0$$

Error probability

• direct approach \rightarrow closed-form solution possible

• MGF approach (with Binomial expansion):

$$p_{\gamma_t}(x) = \frac{N_R}{\bar{\gamma}} e^{-\frac{x}{\bar{\gamma}}} \sum_{n=0}^{N_R - 1} {N_R - 1 \choose n} 1^{N_R - 1 - n} \left(-e^{-\frac{x}{\bar{\gamma}}} \right)^n$$
$$= \frac{N_R}{\bar{\gamma}} \sum_{n=0}^{N_R - 1} {N_R - 1 \choose n} \cdot (-1)^n e^{-\frac{x(n+1)}{\bar{\gamma}}}; \quad x \ge 0$$

$$M_{\gamma_t}(s) = \frac{N_R}{\bar{\gamma}} \sum_{n=0}^{N_R - 1} \binom{N_R - 1}{n} (-1)^n \frac{1}{s + \frac{n+1}{\bar{\gamma}}}$$

$$P_e = \frac{a}{\pi} \int_0^{\frac{\pi}{2}} M_{\gamma_t} \left(\frac{b}{2 \sin^2 \theta} \right) d\theta = \frac{a N_R}{\pi \bar{\gamma}} \sum_{n=0}^{N_R - 1} \binom{N_R - 1}{n} (-1)^n \int_0^{\frac{\pi}{2}} \frac{d\theta}{\frac{b}{2 \sin^2 \theta} + \frac{n+1}{\bar{\gamma}}}$$

 \rightarrow can be evaluated numerically

• high SNR approach $\Rightarrow \bar{\gamma} \to \infty$

$$\begin{split} p_{\gamma_t} &= \frac{N_R}{\bar{\gamma}} \left[1 - \exp\left(-\frac{x}{\bar{\gamma}}\right) \right]^{N_R - 1} \exp\left(-\frac{x}{\bar{\gamma}}\right) \\ &\stackrel{\bar{\gamma} \to \infty}{=} \frac{N_R}{\bar{\gamma}} \left[1 - \left(1 - \frac{x}{\bar{\gamma}} + O\left(\bar{\gamma}^{-1}\right)\right) \right]^{N_R - 1} \left(1 - \frac{x}{\bar{\gamma}} + O\left(\bar{\gamma}^{-1}\right)\right) \\ &= \frac{N_R}{\bar{\gamma}^{N_R}} x^{N_R - 1} + o\left(\bar{\gamma}^{-N_R}\right) \end{split}$$

$$M_{\gamma_t}(s) = \frac{N_R}{\bar{\gamma}^{N_R}} \frac{(N_R - 1)!}{s^{N_R}} + O\left(\bar{\gamma}^{-N_R}\right)$$
$$\left[\to P_e = \frac{a}{\pi} \int_0^{\frac{\pi}{2}} M_{\gamma_t} \left(\frac{b}{2\sin^2(\theta)}\right) d\theta \right]$$
$$= \frac{a(2N_R)!}{b^{N_R} 2^{N_R + 1} N_R!} \frac{1}{\bar{\gamma}^{N_R}} + O(\bar{\gamma}^{-N_R})$$

 \Longrightarrow Diversity gain: $G_d = N_R$

 \implies Combining gain: $G_c = 2b \left(\frac{2N_R!}{a(2N_R)!}\right)^{\frac{1}{N_R}}$

Outage Probability

$$\begin{split} P_{out} &= \Pr\{\gamma_{\hat{n}} \leq \gamma_T\} = P_{\gamma_{\hat{n}}}(\gamma_T) = \left[1 - \exp\left(-\frac{\gamma_T}{\bar{\gamma}}\right)\right]^{N_R} \\ \text{high SNR: } P_{out} &= \left(\frac{\gamma_T}{\bar{\gamma}}\right)^{N_R} + O\left(\bar{\gamma}^{-N_R}\right) \end{split}$$

2.2.5 Comparison

- Diversity Gain: MRC, EGC and SC all achieve the maximum possible diversity gain of $G_d = N_R$
- Combining Gain: The combining gains of MRC, EGC and SC are different
 - MRC/EGC:

$$\frac{G_C^{EGC}}{G_C^{MRC}} = \frac{\frac{1}{2b} \left(\frac{a}{2} {2N_R \choose N_R}\right)^{\frac{1}{N_R}}}{\frac{N_R}{b} \left(\frac{a}{2} \frac{1}{N_R!}\right)^{\frac{1}{N_R}}} = \frac{\left[(2N_R)!\right]^{\frac{1}{N_R}}}{2N_R (N_R)^{\frac{1}{N_R}}} \le 1$$

(independent of a or b which are modulation parameters, only depends on number of antennas)

$$N_R \gg 1$$
: $N_R! \approx \sqrt{2\pi}e^{-N_R}N_R^{N_R+\frac{1}{2}}$ (Stirling)

$$\frac{G_c^{EGC}}{G_c^{MRC}}\bigg|_{N_R\gg 1} = \frac{\left(\sqrt{2\pi}e^{-2N_R}(2N_R)^{2N_R+\frac{1}{2}}\right)^{\frac{1}{N_R}}}{2N_R\left(\sqrt{2\pi}e^{-N_R}N_R^{N_R+\frac{1}{2}}\right)^{\frac{1}{N_R}}} = \frac{2\cdot 2^{\frac{1}{2N_R}}}{2} \stackrel{N_R\to\infty}{\to} \frac{2}{e} \equiv -1.3\text{dB}$$

- MRC/SC:

$$\begin{split} \frac{G_c^{SC}}{G_c^{MRC}} &= \frac{2b \left(\frac{a}{2} \binom{2N_R}{N_R}\right)^{\frac{1}{N_R}}}{2b \left(\frac{a}{2} \frac{(2N_R)!}{N_R!}\right)^{\frac{1}{N_R}}} = \frac{1}{\left(N_R!\right)^{\frac{1}{N_R}}} \leq 1 \\ \frac{G_c^{SC}}{G_c^{MRC}} \bigg|_{N_R \gg 1} &= \frac{1}{\sqrt{2\pi^{\frac{1}{N_R}}}e^{-1}N_R^{1+\frac{1}{2N_R}}} N_R \overset{\rightarrow}{\to} \infty \frac{e}{N_R} \end{split}$$

 \rightarrow loss increases with N_R

- Ergebnis:
 - unterschiedliche Kurven in Diagramm "Combiner Performance Comparison, BPSK" ergeben sich durch G_c
 - alle Kurven haben die gleiche Steigung $\Rightarrow G_d$ ist überall gleich
 - nur Abstände sind unterschiedlich $\Rightarrow G_c$ wird in MRC besser "genutzt" als in EGC und SC

2.3 MISO Systems

Remarks

- Similar to SIMO systems, in MISO systems only coding and diversity gains can be obtained.
- To realize these gains, a careful transmitter design is necessary
- ullet System design depends on whether or not channel state information (CSI) is available at transmitter

2.3.1 Naive Approach

• Assume we simply send the same signal over all N_T transmit antennas

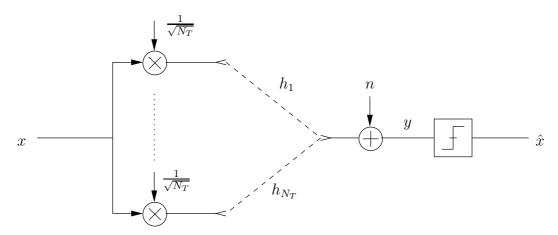


Abbildung 4: Block Diagramm of naive MISO

- Transmit power: $\mathcal{E}\left\{\left|\frac{1}{\sqrt{N_T}}x\right|^2 + \dots, \left|\frac{1}{\sqrt{N_T}}x\right|^2\right\} = \mathcal{E}\left\{N_T \frac{1}{N_T}|x|^2\right\} = \mathcal{E}_s$
- Received signal: $y = \frac{1}{\sqrt{N_T}} \sum_{n=1}^{N_T} h_n \cdot x + n$
- Rayleigh fading: h_n are zero mean complex gaussian random variables $\to h$ is also zero mean complex gaussian
- i.i.d.:

$$- \mathcal{E}\{|h_n|^2\} = 1 \ \forall n$$

$$- \mathcal{E}\{|h|^2\} = \frac{1}{N_T} \mathcal{E}\left\{ \left| \sum_{n=1}^{N_T} h_n \right|^2 \right\} = \frac{1}{N_T} \mathcal{E}\left\{ \sum_{n=1}^{N_T} |h_n|^2 \right\} = 1$$

- statistical properties of h are independent of N_T
- the multiple transmit antennas have no benefit at all
- more sophisticated transmitter designs necessary

2.3.2 Full CSI Available at the Transmitter

- $h_n, n \in \{1, \dots, N_T\}$ is known at the transmitter
- Perform "precoding" (beamforming) with coefficients w_n

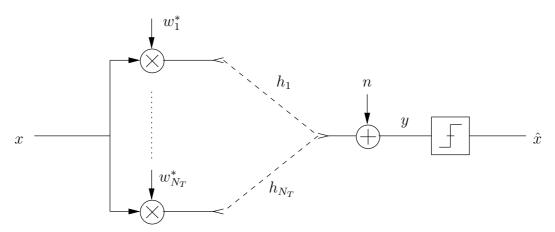


Abbildung 5: Block Diagramm of MISO with CSI

- Transmit Power: Two constraints maybe considered
 - Average transmit power constraint

$$P_{av} = \mathcal{E}\left\{\sum_{n=1}^{N_T} |w_n^* x|^2\right\} = \sum_{n=1}^{N_T} |w_n|^2 \underbrace{\mathcal{E}\{|x|^2\}}_{\mathcal{E}} = \mathcal{E}_s \Rightarrow \sum_{n=1}^{N_T} |w_n|^2 = 1$$

- Power constraint for each transmit antenna

$$\rightarrow |w_n| = \frac{1}{\sqrt{N_T}} \longrightarrow P_{av} = \mathcal{E}_s$$

• Recveived signal: $y = \sum_{n=1}^{N_T} w_n^* h_n x + n$ (equivalent SISO channel)

Maximum Ratio Transmission (MRT)

- \bullet we have only the average power constraint: $\sum_{n=1}^{N_T} |w_n|^2 = 1$
- SNR: $\gamma_t = \frac{\mathcal{E}_s |h|^2}{\sigma_n^2} = \frac{\mathcal{E}_s \left|\sum_{n=1}^{N_T} w_n^* \cdot h_n\right|^2}{\sigma_n^2}$
- Maximize SNR under constraint $\sum_{n=1}^{N_T} |w_n|^2 = 1$
- \bullet constraint optimization problem \to Lagrange method

$$L = \frac{\mathcal{E}_s}{\sigma_n^2} \left| \sum_{n=1}^{N_T} w_n^* \cdot h_n \right|^2 + \lambda \left(\sum_{n=1}^{N_T} |w_n|^2 - 1 \right); \quad \text{where: } \lambda = \text{Lagrange Multiplier}$$

 \Rightarrow Wirtinger Kalkül: treat z and z^* as independent variables for differentiation:

$$\begin{split} \frac{\partial z^*}{\partial z} &= 0; \quad \frac{\partial |z|^2}{\partial z} = \frac{\partial z \cdot z^*}{\partial z} = z^* \\ \frac{\partial x^2}{\partial x} &= 2x; \quad \frac{\partial (z^*)^2}{\partial z^*} = 2 \cdot z^*; \frac{\partial |z|^2}{\partial z} = z^* \end{split}$$

$$\frac{\partial L}{\partial w_m^*} = \frac{\mathcal{E}_s}{\sigma_n^2} \left(\sum_{n=1}^{N_T} w_n^* \cdot h_n \right)^* h_m + \lambda w_m$$

$$ightarrow w_m = rac{\mathcal{E}_s}{\sigma_n^2 \cdot \lambda} \Big(\sum_{n=1}^{N_T} w_n^* h_n \Big)^* h_m$$
 const., independent of $m := c$

$$\rightarrow w_m = c \cdot h_m$$

$$\rightarrow \sum_{n=1}^{N_T} |w_n|^2 = 1 \rightarrow c^2 = \frac{1}{\sum_{n=1}^{N_T} |h_n|^2}$$

$$\rightarrow w_n = \frac{h_n}{\sqrt{\sum_{n=1}^{N_T} |h_n|^2}} \equiv MRT \text{ gains}$$

$$\to \text{SNR} = \frac{\mathcal{E}_s}{\sigma_n^2} \left| \sum_{n=1}^{N_T} \frac{|h_n|^2}{\sqrt{\sum_{n=1}^{N_T} |h_n|^2}} \right|^2 = \frac{\mathcal{E}_s}{\sigma_n^2} \sum_{n=1}^{N_T} |h_n|^2$$

- ⇒ same SNR as for maximum ration combining (MRC)
- \Rightarrow MRT with N_T transmit antennas achieves the same performance as MRC with N_T receive antennas
- \Rightarrow MRT/MRC can be extended to $N_T \times N_R$ MIMO systems
 - \rightarrow has the same performance as MRC with $N_T \cdot N_R$ receive antennas and one transmit antenna

Equal Gain Transmission (EGT)

- we employ gains: $w_n = \frac{1}{\sqrt{N_T}} \cdot \frac{h_n}{|h_n|} \to |w_n| = \frac{1}{\sqrt{N_T}}$
- SNR:

$$\gamma_t = \frac{\mathcal{E}_s}{\sigma_n^2} \left| \sum_{n=1}^{N_T} w_n^* h_n \right|^2$$

$$= \frac{\mathcal{E}_s}{\sigma_n^2} \left| \sum_{n=1}^{N_T} \frac{1}{\sqrt{N_T}} \cdot \frac{|h_n|^2}{|h_n|} \right|^2 = \frac{1}{N_T} \cdot \frac{\mathcal{E}_s}{\sigma_n^2} \left| \sum_{n=1}^{N_T} |h_n| \right|^2$$

$$\gamma_n = \frac{\mathcal{E}_s}{\sigma_n^2} |h_n|^2$$

same SNR as for EGC
$$\rightarrow \gamma_t = \frac{1}{N_T} \left| \sum_{n=1} N_T \sqrt{\gamma_n} \right|^2$$

 \rightarrow EGC with N_T transmit antennas achieves the same performance as EGC with N_T receive antennas

Transmit Antennas Selection

• select antenna with maximum channel gain for transmission:

$$w_n = \begin{cases} \frac{h_n}{|h_n|}, & \text{if } n = \hat{n} \\ 0, & \text{otherwise} \end{cases} \text{ where } \hat{n} = \underset{n}{\operatorname{argmax}} |h_n|$$

• antenna selection with N_T transmit antennas achieves the same performance as Selection Combining with N_T receive antennas

2.3.3 No CSI at Transmitter - Space - Time - Coding

- $h_n, n \in \{1, \ldots, N_T\}$, is only known at the receiver
- "Space-time-coding" has to be employed to realize diversity gain
- $T \times N_T$ matrics **X** are transmitted in T symbol intervals over N_T antennas
- X is drawn from a matrix alphabet \mathcal{X}
- Example:

$$\mathbf{X} = \begin{pmatrix} x_{1,1} & x_{1,2} & \cdots & x_{1,N_T} \\ x_{2,1} & x_{2,2} & \cdots & x_{2,N_T} \\ \vdots & \vdots & \ddots & \vdots \\ x_{T,1} & x_{T,2} & \cdots & x_{T,N_T} \end{pmatrix}$$

- We distinguish:
 - Space-time-block-codes (STBCs)
 - $\to \mathbf{X}$ is obtained by mapping K scalar symbols s_k , k = 1, ..., K from a scalar alphabet \mathcal{A} to matrix \mathbf{X}
 - Space-time-trellis-codes (STTCs)
 - \rightarrow **X** is obtained from scalar symbols s_k through a trellis encoding process. [see: Tarokh, Seshadri, Calderbank: Space-time-codes for high datarate wireless communication: Performance criterions and coder construction; IEEE Trans. Inf. Theory 1998]
 - here: We concentrate on space-time-block-codes (STBCs), but many results can be easily extended to space-time-trellis-codes
- STBCs:
 - K M-ary scalar symbols (e.g. M-PSK symbols) are mapped to STBC matrices \mathbf{X} $\mathbf{S} = [s_1, \dots, s_K] \to \mathbf{X}$ $s_k \in \mathcal{A} \to x \in \mathcal{X}$ with $|\mathcal{X}| = M^K$
 - Example: "Alamouti"-Code

$$\mathbf{X} = \frac{1}{\sqrt{2}} \begin{pmatrix} s_1 & s_2 \\ -s_2^* & s_1^* \end{pmatrix}$$

[Alamouti: A simple transmit diversity technique for wireless communication, IEEE JSAC 1998]

Optimal Detection

• Signal model:

$$\begin{pmatrix} y_1 \\ \vdots \\ y_T \end{pmatrix} = \mathbf{X} \begin{pmatrix} h_1 \\ \vdots \\ h_{N_T} \end{pmatrix} + \begin{pmatrix} n_1 \\ \vdots \\ n_T \end{pmatrix}$$
$$\mathbf{y} = \mathbf{X} \cdot \mathbf{h} + \mathbf{n}$$

- Optimal detection ML-detection
 - h is known at receiver
 - **n** is AWGN with $\mathcal{E}\{\mathbf{n} \cdot \mathbf{n^H}\} = \sigma_{\mathbf{n}}^2 \cdots \mathbf{I}_{T \times T}$

$$p(\mathbf{y}|\mathbf{X}) = \frac{1}{\pi^T |\sigma_n^2 \mathbf{I}_{T \times T}|} \exp\left(-(\mathbf{y} - \mathbf{X}\mathbf{h})^H (\sigma_n^2 \mathbf{I}_{T \times T})^{-1} (\mathbf{y} - \mathbf{X}\mathbf{h})\right)$$
$$= \frac{1}{\pi^T \sigma_n^{2T}} \exp\left(-\frac{1}{\sigma_n^2} (\mathbf{y} - \mathbf{X}\mathbf{h})^H (\mathbf{y} - \mathbf{X}\mathbf{h})\right) = \frac{1}{\pi^T \sigma_n^{2T}} \exp\left(||\mathbf{y} - \mathbf{X}\mathbf{h}||^2\right)$$

 \rightarrow the optimal estimate $\hat{\mathbf{X}}$ or equivalently the optimal estimate $\hat{\mathbf{s}}$ can be obtained as

$$\hat{\mathbf{s}} = \underset{\mathbf{s} \in \mathcal{A}^K}{\operatorname{argmax}} \ p(\mathbf{y}|\mathbf{X}) = \underset{\mathbf{s} \in \mathcal{A}^K}{\operatorname{argmin}} ||\mathbf{y} - \mathbf{X}\mathbf{h}||^2$$

– Disadvantage: In general, metric $||\mathbf{y} - \mathbf{X}\mathbf{h}||^2$ has to be calculated M^K times \rightarrow complexity increases exponentially with K

Types of STBCs

- Orthogonal STBCs (OSTBCs)
 - OSTBCs are a special class of STBCs which allow independent detection of each $s_k \to \text{only } K \cdot M$ metrics have to be evaluated
 - Rate STBCs: $R_{STBC} = \frac{K}{T}$
 - Examples:
 - * Alamouti Code $(K=2,T=2) \rightarrow R_{STBC}=1$

$$\mathbf{X} = \frac{1}{\sqrt{2}} \begin{pmatrix} s_1 & s_2 \\ -s_2^* & s_1^* \end{pmatrix} \updownarrow T$$

$$\longleftrightarrow N_T$$

 \rightarrow only "full rate" OSTBC for complex s_k

*
$$N_T = 3, K = 3, T = 4$$

$$\mathbf{X} = \frac{1}{\sqrt{3}} \begin{pmatrix} s_1 & s_2 & s_3 \\ -s_2^* & s_1^* & 0 \\ s_3^* & 0 & -s_3^* \\ 0 & -s_3^* & s_2^* \end{pmatrix} \to R_{STBC} = \frac{K}{T} = \frac{3}{4}$$

- Orthogonality: $\mathbf{X}^H \mathbf{X} = const \cdot \mathbf{I}_{N_T \times N_T}$
- Independent detection of $s_1 \ \& \ s_2$ for Alamouti Code

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} s_1 & s_2 \\ -s_2^* & s_1^* \end{pmatrix} \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} + \begin{pmatrix} n_1 \\ n_2 \end{pmatrix}$$

$$\rightarrow \underbrace{\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}}_{\tilde{p}} = \frac{1}{\sqrt{2}} \underbrace{\begin{pmatrix} h_1 & h_2 \\ h_2^* & -h_1^* \end{pmatrix}}_{\tilde{p}} \underbrace{\begin{pmatrix} s_1 \\ s_2 \end{pmatrix}}_{\tilde{p}} + \underbrace{\begin{pmatrix} n_1 \\ n_2^* \end{pmatrix}}_{\tilde{p}}$$

(Anmerkung:
 $\underline{\text{nur}}_{-}\binom{s_1}{s_2}$ gewünscht, nicht: $s_1^*, s_2^*)$

$$\mathbf{F}^{H}\mathbf{F} = \frac{1}{2} \begin{pmatrix} h_{1}^{*} & h_{2} \\ h_{2}^{*} & -h_{1} \end{pmatrix} \begin{pmatrix} h_{1} & h_{2} \\ h_{2}^{*} & -h_{1}^{*} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} |h_{1}|^{2} + |h_{2}|^{2} & 0 \\ 0 & |h_{1}|^{2} + |h_{2}|^{2} \end{pmatrix}$$

- $\rightarrow \frac{\sqrt{2}}{\sqrt{|h_1|^2+|h_2|^2}} \cdot \mathbf{F}$ is unitary matrix
- $\rightarrow \text{ ML decision: } \hat{\mathbf{s}} = \underset{\mathbf{s}}{\operatorname{argmin}} \left| \left| \frac{2}{|h_1|^2 + |h_2|^2} \cdot \mathbf{F}^H \cdot \tilde{\mathbf{y}} \mathbf{s} \right| \right|^2$
- \rightarrow independent ML decoding

$$\hat{s}_1 = \underset{s_1}{\operatorname{argmin}} \left| s_1 - \frac{h_1^* y_1 + h_2 y_2^*}{\frac{1}{\sqrt{2}} (|h_1|^2 + |h_2|^2)} \right|$$

$$\hat{s}_2 = \underset{s_2}{\operatorname{argmin}} \left| s_2 - \frac{h_1^* y_1 - h_2 y_2^*}{\frac{1}{\sqrt{2}} (|h_1|^2 + |h_2|^2)} \right|$$

- independent decoding property can be proved for all OSTBCs
- low complexity is at the expense of a rate-loss compared to other STBCs for $N_T > 2$
 - \rightarrow Frequenzhopping
 - \rightarrow keine Kanalinformation aus vorher empfangenen Symbolen möglich \Rightarrow Kanal ändert sich ständig: nur Entscheidung, ob Rauschen oder Signal + Rauschen
- Performance Analysis of Alamouti Code
 - Decision-variables after combining

$$r_1 = \sqrt{2} \frac{h_1^* y_1 + h_2 y_2^*}{|h_1|^2 + |h_2|^2}$$

$$r_2 = \sqrt{2} \frac{h_1^* y_1 - h_2 y_2^*}{|h_1|^2 + |h_2|^2}$$

because of symmetry it suffices to consider r_1

$$r_{1} = \sqrt{2} \frac{h_{1}^{*} \left(\frac{1}{\sqrt{2}} s_{1} h_{1} + \frac{1}{\sqrt{2}} h_{2} s_{2} + n_{1}\right) + h_{2} \left(-\frac{1}{\sqrt{2}} h_{2} s_{1}^{*} + \frac{1}{\sqrt{2}} h_{1} s_{2}^{*} + n_{2}\right)^{*}}{|h_{1}|^{2} + |h_{2}|^{2}}$$

$$= \sqrt{2} \frac{\frac{1}{\sqrt{2}} \left(|h_{1}|^{2} + |h_{2}|^{2}\right) s_{1} + h_{1}^{*} n_{1} + h_{2} n_{2}^{*}}{|h_{1}|^{2} + |h_{2}|^{2}}$$

$$= 1 \cdot s_{1} + n_{eq}$$

where

$$n_{eq} = \sqrt{2} \frac{h_1^* n_1 + h_2 n_2^*}{|h_1|^2 + |h_2|^2}$$

$$SNR \to \gamma_t = \frac{\mathcal{E}_s \cdot 1^2}{\sigma_{eq}^2} \quad \text{with} \quad \mathcal{E}\{|s_1|^2\} = \mathcal{E}_s$$

$$\sigma_{eq}^2 = 2 \frac{|h_1|^2 \sigma_n^2 + |h_2|^2 \sigma_n^2}{\left(|h_1|^2 + |h_2|^2\right)^2} = \frac{2\sigma_n^2}{|h_1|^2 + |h_2|^2}$$

$$\rightarrow \gamma_t = \frac{1}{2} \frac{\mathcal{E}_s}{\sigma^2} (|h_1|^2 + |h_2|^2)$$

- $\rightarrow SNR_{Alamouti} = \frac{1}{2}SNR_{MRC} = \frac{1}{2}SNR_{MRT}$
- \rightarrow Alamouti code has diversity gain $G_d = 2$
- \to Transmission with Alamouti STBC requires 3dB higher SNR to achieve same performance as MRT \to 3dB loss in coding gain G_c
- → Lack of CSI knowledge at transmitter "costs" 3dB in power efficiency
- \rightarrow General
 - · OSTBCs achieve a diversity gain of $G_d = N_T$ if only one receive antenna is available
 - · if N_R receive antennas are available, MRC can be used at the receiver to yield a diversity gain of $G_d=N_TN_R$

• Other STBCs:

- Quasi orthogonal STBCs
 - * higher rate than OSTBCs
 - * only subset of symbols have to be decoded jointly
 - * Example: $K = N_T = T = 4$

$$\mathbf{X} = \frac{1}{2} \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ -s_2^* & s_1^* & -s_4^* & s_3^* \\ -s_3^* & -s_4^* & s_1^* & s_2^* \\ s_4 & -s_3 & -s_2 & s_1 \end{pmatrix}$$

- * Anmerkung 1: X ist ähnlich zu Alamouti Code
- * Anmerkung 2: $\mathbf{X}^H \mathbf{X}$: viele Nicht-diagonal Elemente sind Null; die, die ungleich Null sind, zeigen, welche Symbole gemeinsam entschlüsselt werden müssen

- Golden Code for $N_T=N_R=2$: achieves a rate of $R_{STBC}=2$ and full diversity of $G_d=N_T,N_R=4$
- Differential STBCs: $\mathbf{X}_k = \mathbf{X}_{k-1} \cdot \mathbf{D}_k$. \mathbf{X}_k is transmitted, \mathbf{D}_k is transmitted
- Linear dispersion codes: designed to achieve high mutual information
- noncoherent STBCs (On-Off-Keying)

Space Time Code Design Given:

- Code $\mathscr{X} = \{\mathbf{X}_1, \dots, \mathbf{X}_{|\mathscr{X}|}\}$
- Channel: IID Rayleigh-fading:
 - $-h_n \sim \mathcal{CN}(0,1); \quad n \in \{1, 2, \dots, N_T\}$
 - AWGN $n \sim \mathcal{CN}(0, \sigma_n^2)$

Problem: How should we design codebook \mathcal{X} ?

- Need to derive error rate for general codebooks $\mathcal{X}!$
 - Codeword error rate

$$P_e = \frac{1}{|\mathcal{X}|} \sum_{i=1}^{|\mathcal{X}|} \Pr{\{\mathbf{x}_i \neq \hat{\mathbf{x}}_i\}}$$

where $\hat{\mathbf{x}}_i$ is the detected codeword and we assume that all codewords are equally likely

Problem: $\Pr{\mathbf{x}_i \neq \hat{\mathbf{x}}_i}$ is not tractable in general

• Use union bound to upper bound $\Pr\{\mathbf{x}_i \neq \hat{\mathbf{x}}_i\}$ as upper sum over <u>pairwise error probabilities</u>(PEP) $\Pr\{\mathbf{x}_i \to \mathbf{x}_j\}$ where it is assumed that \mathbf{x}_i was transmitted and $\overline{\mathbf{x}}_i$ and $\overline{\mathbf{x}}_j$ are the only codewords in the codebook

$$P_e \leq \frac{1}{|\mathcal{X}|} \sum_{i=1}^{|\mathcal{X}|} \sum_{j=1}^{|\mathcal{X}|} \Pr{\{\mathbf{x}_i \to \mathbf{x}_j\} \text{ where } j \neq i}$$

Calculation of PEPs

Recall: $\hat{\mathbf{x}} = \underset{\mathbf{x} \in \mathcal{X}}{\operatorname{argmin}} ||\mathbf{y} - \mathbf{x}\mathbf{h}||^2$

Now, \mathbf{x}_i and \mathbf{x}_j are the only alternatives and an error is made if $||\mathbf{y} - \mathbf{x}_i \mathbf{h}||^2 > ||\mathbf{y} - \mathbf{x}_j \mathbf{h}||^2$ since \mathbf{x}_i was sent but \mathbf{x}_j was detected

$$\begin{aligned} & \rightarrow ||\mathbf{x}_{i}\mathbf{h} + \mathbf{n} - \mathbf{x}_{i}\mathbf{h}||^{2} > ||\mathbf{x}_{i}\mathbf{h} + \mathbf{n} - \mathbf{x}_{j}\mathbf{h}||^{2} \\ & \quad ||\mathbf{n}||^{2} > ||(\mathbf{x}_{i} - \mathbf{x}_{j})\mathbf{h} + \mathbf{n}||^{2} \\ & \rightarrow ||\mathbf{n}||^{2} > \underbrace{\mathbf{h}^{H}(\mathbf{x}_{i} - \mathbf{x}_{j})^{H}(\mathbf{x}_{i} - \mathbf{x}_{j})\mathbf{h}}_{\Delta} + \mathbf{h}^{H}(\mathbf{x}_{i} - \mathbf{x}_{j})\mathbf{n} + \mathbf{n}^{H}(\mathbf{x}_{i} - \mathbf{x}_{j})\mathbf{h} + ||\mathbf{n}||^{2} \end{aligned}$$

$$\rightarrow \underbrace{-\mathbf{h}^{H}(\mathbf{x}_{i} - \mathbf{x}_{j})^{H}\mathbf{n} - \mathbf{n}^{H}(\mathbf{x}_{i} - \mathbf{x}_{j})\mathbf{h}}_{z} > \Delta$$

for given \mathbf{h} , z is a gaussian random variable

$$\sigma_z^2 = \mathcal{E}\{|z|^2\} = \mathcal{E}\{2\mathbf{h}^H(\mathbf{x}_i - \mathbf{x}_j) \mathbf{n} \mathbf{n}^H(\mathbf{x}_i - \mathbf{x}_j) \mathbf{h} + 2\mathbf{h}^H(\mathbf{x}_i - \mathbf{x}_j)^H \mathbf{n} \mathbf{n}^T(\mathbf{x}_i - \mathbf{x}_j)^* \mathbf{h}^*\}$$

$$= 2\sigma_n^2 \Delta + 0$$

$$\Pr\{\mathbf{x}_i \to \mathbf{x}_j\} = \int_{\Delta}^{\infty} \frac{1}{\sqrt{2\pi}\sigma_z} \exp\left(-\frac{z^2}{2\sigma_z^2}\right) dz, \ t = \frac{z}{\sigma_z}$$
$$= \frac{1}{\sqrt{2\pi}} \int_{\frac{\Delta}{\sigma_z}}^{\infty} e^{-\frac{t^2}{2}} dt = Q\left(\frac{\Delta}{\sigma_z}\right) = Q\left(\frac{\Delta}{\sqrt{2\sigma_n^2 \Delta}}\right)$$
$$= Q\left(\sqrt{\frac{\Delta}{2\sigma_n^2}}\right)$$

- $\Pr{\mathbf{x}_i \to \mathbf{x}_j} = \mathcal{E}\left{Q\left(\sqrt{\frac{\Delta}{2\sigma_n^2}}\right)\right}$
 - to avoid cumbersome Q-function we use Chernoff bound:

$$Q(x) \le \frac{1}{2}e^{-\frac{x^2}{2}}$$

$$\Pr{\mathbf{x}_i \to \mathbf{x}_j} \le \frac{1}{2} \mathcal{E}_h \left\{ \exp\left(-\frac{\mathbf{h}^H \mathbf{Q} \mathbf{h}}{4\sigma_n^2}\right) \right\}$$
where $\mathbf{Q} = (\mathbf{x}_i - \mathbf{x}_j)^H (\mathbf{x}_i - \mathbf{x}_j)$

- Eigendecomposition: $\mathbf{Q} = \mathbf{U}^H \mathbf{\Lambda} \mathbf{U}$ with $\mathbf{\Lambda} = \text{diag}\{\lambda_1, \dots, \lambda_r, 0, \dots, 0\}$ $r = \text{rank}\{\mathbf{Q}\}$
- \bullet Elements **h** are i.i.d. Gaussian
 - $-\underline{\beta} = \mathbf{U}\mathbf{h}$ has also i.i.d. Gaussian random variables as elements since \mathbf{U} is unitary matrix

$$- \mathbf{h}^H \mathbf{Q} \mathbf{h} = \underbrace{\mathbf{h}^H \mathbf{U}^H}_{\beta^*} \mathbf{\Lambda} \underbrace{\mathbf{U} \mathbf{h}}_{\beta} = \sum_{i=1}^r \lambda_i |\beta_i|^2 \text{ with } \underline{\beta} = [\beta_1, \dots, \beta_{N_T}]$$

$$\Pr\{\mathbf{x}_{i} \to \mathbf{x}_{j}\} = \frac{1}{2} \mathcal{E}_{\underline{\beta}} \left\{ \exp\left(-\frac{\sum_{i=1}^{r} \lambda_{i} |\beta_{i}|^{2}}{4\sigma_{n}^{2}}\right) \right\}$$

$$= \frac{1}{2} \mathcal{E}_{\underline{\beta}} \left\{ \prod_{i=1}^{r} e^{-\frac{\lambda_{i}}{4\sigma_{n}^{2}} |\beta_{i}|^{2}} \right\}$$

$$= \frac{1}{2} \prod_{i=1}^{r} \mathcal{E}_{\beta_{i}} \left\{ e^{-\frac{\lambda_{i}}{4\sigma_{n}^{2}} |\beta_{i}|^{2}} \right\}$$

$$= \frac{1}{2} \prod_{i=1}^{r} \mathcal{E}_{|\beta_{i}|^{2}} \left\{ e^{-\frac{\lambda_{i}}{4\sigma_{n}^{2}} |\beta_{i}|^{2}} \right\} \stackrel{\triangle}{=} \text{MGF of exponentially distributed variable } \alpha_{i} = |\beta_{i}|^{2}$$

$$\begin{split} & \to P_{\alpha_i}(x) = e^{-x}, \ x \ge 0 \\ & \to \Pr\{\mathbf{x}_i \to \mathbf{x}_j\} \le \frac{1}{2} \prod_{i=1}^r \frac{1}{1 + \frac{\lambda_i}{4\sigma_n^2}} \\ & \le \prod_{i=1}^r \frac{1}{\frac{\lambda_i}{4\sigma_n^2}} = 2^{2r-1} \frac{1}{\prod_{i=1}^r \lambda_i} \left(\underbrace{\frac{1}{\sigma_n^2}}_{\infty_n} \right)^{-r} \end{split}$$

• upper bound on P_e :

$$\lambda_n(i,j) = n \text{th eigenvalue of } (\mathbf{x}_i - \mathbf{x}_j)^H (\mathbf{x}_i - \mathbf{x}_j)$$
$$r(i,j) = \text{ rank of } (\mathbf{x}_i - \mathbf{x}_j)^H (\mathbf{x}_i - \mathbf{x}_j)$$

$$\rightarrow P_e \leq \frac{1}{|\mathcal{X}|} \sum_{i=1}^{|\mathcal{X}|} \sum_{j=1}^{|\mathcal{X}|} 2^{2r(i,j)-1} \frac{1}{\prod\limits_{n=1}^{r(i,j)} \lambda_n(i,j)} \left(\frac{1}{\sigma_n^2}\right)^{-r(i,j)}$$

• generally loose bound but offers significant insight for code design

Two criteria:

Rank criterion: The diversity gain of a ST code is given by

$$G_d = \min_{i,j}(r(i,j)) = \min_{i,j} \operatorname{rank}\left((\mathbf{x}_i - \mathbf{x}_j)^H(\mathbf{x}_i - \mathbf{x}_j)\right)$$

 \rightarrow Design code such that minimum rank of all possible matrices $(\mathbf{x}_i - \mathbf{x}_j)^H (\mathbf{x}_i - \mathbf{x}_j)$ is maximized

$$T \updownarrow \overset{\stackrel{N_T}{\longleftrightarrow}}{\mathbf{X}_i} \Rightarrow r(i,j) = N_T \qquad \forall i \neq j$$

<u>Determinant criterion:</u> To maximize the coding gain among all codes with $r(i, j) = N_T$, we need to maximize $\max \min_{i,j} \prod_{n=1}^{N_T} \lambda_n(i,j) = \max \min_{i,j} \left| (\mathbf{x}_i - \mathbf{x}_j)^H (\mathbf{x}_i - \mathbf{x}_j) \right| \quad \forall i \neq j$

- Rank and determinant criterion can be used for the search for good space-time block codes and space-time trellis codes. These two criteria were first derived by Tarokh, et. al. 1998.
- ullet diversity increases to $N_T N_R$ if N_K receive antennas are available
- Example: see Bäro, Bauch, Hansmann: Improved codes for space-time trellis coded modulation. IEEE Comm. Letters, 2000.

2.3.4 Partial or Imperfect CSI at the Transmitter

- In practice, the CSI cannot be perfect. Channel estimation, quantization and noisy feedback channels introduce errors.
- If the system is optimized for perfect CSI (e.g. using MRT or EGT), the performance for imperfect CSI may be worse than for a system designed for no CSI(e.g. space-time coding)
- In this case, it is advantageous to use a hybrid approach and combine beamforming and space-time coding.

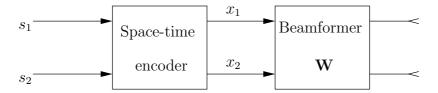


Abbildung 6: Block Diagramm of MISO with Beamforming

- W is the beamforming matrix which depends on the reliability of the CSI
- \bullet CSI is modeled as

$$\hat{h}_i = \rho h_i + \sqrt{1 - \rho^2} e_i$$

where:

- $-\hat{h}_i$ is the CSI estimate
- $-\rho$ is the correlation between \hat{h}_i and h_i
- $-e_i$ is the CSI error modeled as AWGN

extreme cases:

- $-\rho = 0: \hat{h}_i \text{ independent of } h_i \to \text{no CSI } (\mathbf{W} = \mathbf{I})$
- $-\rho = 1: \hat{h}_i = h_i \rightarrow \text{perfect CSI } (\mathbf{W} \text{ performs MRT})$
- W can be optimized under the assumptions for given ρ and \hat{h}_i \rightarrow see for details: Jöngren, Skorglund and Ottersten: "Combining Beamforming and Orthogonal Space-time Block Coding", IEEE on IT, 2002.

2.4 MIMO Systems without CSI at the transmitter

- We consider $N_T \times N_R$ MIMO system and assume that the channel matrix **H** is not known at the transmitter
 - \rightarrow no CSI at the transmitter (CSIT)
- signal model:

$$N_R \updownarrow \mathbf{y} = N_R \updownarrow \overset{N_T}{\longleftrightarrow} \mathbf{x} \updownarrow N_T + \mathbf{n} \updownarrow N_R$$

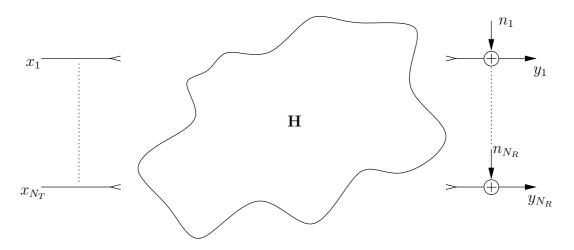


Abbildung 7: Block Diagramm of MISO without CSI

- x_n are M-ary i.i.d. scalar symbols taken e.g from an M-PSK or M-QAM symbol alphabet $\mathscr A$
- This scheme is often called "spatial multiplexing"
- We transmit N_T symbols per symbol interval \rightarrow rate $R = \log_2(M) \cdot N_T$ for uncoded transmission
- ullet Problem: How to detect ${f x}$ at the receiver considering
 - performance and
 - complexity?

2.4.1 Optimum Detection

- Elements of **n** are gaussian random variables with variance σ_n^2
- ullet H is known at the receiver

$$p(\mathbf{y}|\mathbf{x}) = \frac{1}{\pi^{N_R} \sigma_n^2 \mathbf{I}_{N_R \times N_R}} \exp\left(-(\mathbf{y} - \mathbf{H}\mathbf{x})^H (\sigma_n^2 \mathbf{I}_{N_R \times N_R})^{-1} (\mathbf{y} - \mathbf{H}\mathbf{x})\right)$$
$$= \frac{1}{\pi^{N_R} \sigma_n^{2N_R}} \exp\left(-\frac{1}{\sigma_n^2} ||\mathbf{y} - \mathbf{x}\mathbf{H}||^2\right)$$

• ML-Detection

$$\hat{x} = \underset{\mathbf{x} \in \mathscr{A}^{N_T}}{\operatorname{argmin}} ||\mathbf{y} - \mathbf{x}\mathbf{H}||^2 = \underset{\mathbf{x} \in \mathscr{A}^{N_T}}{\operatorname{argmax}} p(\mathbf{y}|\mathbf{x})$$

- $\rightarrow M^{N_T}$ metric calculations \rightarrow complexity is exponential in $N_T!!$
- \rightarrow in general too complex in practice

• Performance

- consider worst case pairwise error probability (PEP) to evaluate diversity gain
- PEP $\rightarrow x_i$ is transmitted but $x_j \neq x_i$ is detected this happens if $||\mathbf{y} - \mathbf{H}\mathbf{x}_i||^2 > ||\mathbf{y} - \mathbf{H}\mathbf{x}_j||^2$ $\rightarrow ||\mathbf{n}||^2 > ||\mathbf{H}(\mathbf{x}_i - \mathbf{x}_j) + \mathbf{n}||^2$
- the "worst case" is if $\mathbf{x}_i \& \mathbf{x}_j$ differ only in one element *i.e.*,

$$\mathbf{x}_{i} - \mathbf{x}_{j} = (x_{ni} - x_{nj}) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \\ 0 \end{bmatrix} \leftarrow \text{``1'' in position } n$$

where $\mathbf{x}_i = [x_{1i}, x_{2i}, \dots, x_{N_T i}]$

$$- ||\mathbf{n}||^2 > || \underbrace{\mathbf{h}_n}_{\text{nth column of } \mathbf{H}} \underbrace{(x_{ni} - x_{nj})}_{\Delta x_n(i,j)} + \mathbf{n}||^2$$

$$- ||\mathbf{n}||^2 > \mathbf{h}_n^H \mathbf{n} \Delta x_n^*(i,j) + \mathbf{n}^H \mathbf{h}_n \Delta x_n(i,j) + ||\mathbf{n}||^2 + ||\mathbf{h}_n||^2 - |\Delta x_n(i,j)|^2$$

$$||\mathbf{h}_n||^2 |\Delta x_n(i,j)|^2 < \underbrace{-\mathbf{h}_n^H \mathbf{n} \Delta x_n(i,j) - \mathbf{n}^H \mathbf{h}_n \Delta x_n(i,j)}_{\text{Gaussian random variable with variance } \sigma_{eq}^2 = 2\sigma_n^2 |\Delta x_n(i,j)|^2 ||\mathbf{h}_n||^2}$$

$$-\Pr\{\mathbf{x}_i \to \mathbf{x}_j || \mathbf{H}\} = Q\left(\sqrt{\frac{||\mathbf{h}_n||^2 |\Delta x_n(i,j)|^2}{2\sigma_n^2}}\right)$$

$$-\Pr\{\mathbf{x}_i \to \mathbf{x}_j\} = \mathcal{E}\left\{Q\left(\sqrt{\frac{||\mathbf{h}_n||^2|\Delta x_n(i,j)|^2}{2\sigma_n^2}}\right)\right\}$$

→ use same approach as for space-time code design to get diversity order

$$\gamma_t = \frac{||\mathbf{h}_n||^2 |\Delta x_n(i,j)|^2}{2\sigma_n^2} = \frac{|\Delta x_n(i,j)|^2}{2\sigma_n^2} (|h_{1n}|^2 + |h_{2n}^2 + \dots + |h_{N_R n}|^2)$$

- same form as SNR of MRC with N_R receive antennas
- diversity gain of spatial multiplexing wit ML-decoding is

$$G_d = N_R$$

- diversity of N_T transmit antennas is not exploited with spatial multiplexing
- to exploit this additional gain, coding across space is required (at the expense of rate)

(Hier gehören die detection performance kurven für BPSK hin)

2.4.2 Linear Receivers

- How can we avoid the complexity associated wit the joint detection of the elements of x?
- \bullet Idea: Employ linear filter (matrix) to separate the elements of ${\bf x}$
- Requires: $N_T \leq N_R$
- We form

$$\mathbf{r} = N_T \updownarrow \overset{\stackrel{N_R}{\longleftrightarrow}}{\mathbf{F}} \mathbf{y} = [r_1, \dots, r_{N_T}]^T$$

where \mathbf{F} is the filter matrix and \mathbf{y} is the received vector

such that x_n can be obtained from

$$\hat{x}_n = \underset{x_n \in \mathscr{A}}{\operatorname{argmin}} |r_i - x_n|^2$$
 where $\mathbf{F} \in \mathbb{C}^{N_T \times N_R}$

- ullet Two popular design criteria for ${f F}$
 - Zero-forcing (ZF) criterion
 - minimum mean squared error (MMSE) crtiterion

ZF Detection

$$r = Fy = F(Hx + n) = FHx + Fn$$

 $ZF \leftrightarrow we require \mathbf{FH} = \mathbf{I}_{N_T \times N_T}$

• noise covariance matrix

$$\Phi_{ee} = \mathcal{E}\{\mathbf{F}\mathbf{n}(\mathbf{F}\mathbf{n})^H\} = \sigma_n^2 \mathbf{F} \mathbf{F}^H$$

- $N_T = N_R \to \mathbf{F}\mathbf{H} = \mathbf{I}_{N_T \times N_T} \to \mathbf{F} = \mathbf{H}^{-1}$ assuming \mathbf{H} is invertible
- $\rightarrow N_T \leq N_R \rightarrow$ which one of the many **F** that yield **FH** = $\mathbf{I}_{N_T \times N_T}$?
- ullet choose ${f F}$ that leads to the smallest noise enhancement
- \bullet optimal ${\bf F}$ is the solution to the following problem:

$$\min_{\mathbf{F}} \operatorname{tr} \{ \sigma_n^2 \mathbf{F} \mathbf{F}^H \}$$

s.t
$$\mathbf{FH} = \mathbf{I}_{N_T \times N_T}$$

the constraint is equivalent to $\operatorname{tr}\{(\mathbf{FH} - \mathbf{I})(\mathbf{FH} - \mathbf{I})^H\} = 0$

Lagrangian:

$$L(\mathbf{F}) = \operatorname{tr}\{\sigma_n^2 \mathbf{F} \mathbf{F}^H\} + \lambda \operatorname{tr}\{\mathbf{F} \mathbf{H} \mathbf{H}^H \mathbf{F} - \mathbf{F} \mathbf{H} - \mathbf{H}^H \mathbf{F}^H + \mathbf{I}\}$$
$$= \sigma_n^2 \operatorname{tr}\{\mathbf{F} \mathbf{F}^H\} + \lambda \operatorname{tr}\{\mathbf{F} \mathbf{H} \mathbf{H}^H \mathbf{F}^H\} - \lambda \operatorname{tr}\{\mathbf{F} \mathbf{H}\} - \lambda \operatorname{tr}\{\mathbf{H}^H \mathbf{F}^H\} + \lambda N_T$$

• use rules for complex matrix differentiation in Table IV in paper by Hjörunges & Gesbert

$$\begin{split} \frac{\delta L(\mathbf{F})}{\delta \mathbf{F}^*} &= \sigma_n^2 \mathbf{F} + \lambda \mathbf{F} \mathbf{H} \mathbf{H}^H - \lambda \mathbf{H}^H = 0 \\ &\rightarrow \mathbf{F} (\sigma_n^2 \mathbf{I} + \lambda \mathbf{H} \mathbf{H}^H) = \lambda \mathbf{H}^H \\ &\rightarrow \mathbf{F} = \lambda \mathbf{H}^H (\sigma_n^2 \mathbf{I} + \lambda \mathbf{H} \mathbf{H}^H)^{-1} \end{split}$$

use matrix inversion lemma

$$(A + UBV)^{-1} = A^{-1} - A^{-1}U(B^{-1} + VA^{-1}U)^{-1}VA^{-1}$$

$$\begin{split} & \rightarrow \mathbf{F} = \lambda \mathbf{H}^H \left[\frac{1}{\sigma_n^2} \mathbf{I} - \frac{1}{\sigma_n^2} \mathbf{H} \left[\frac{1}{\lambda} \mathbf{I} + \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H} \right]^{-1} \mathbf{H}^H \frac{1}{\sigma_n^2} \right] \\ & = \frac{\lambda}{\sigma_n^2} \left[\underbrace{\mathbf{I}}_{\left(\frac{1}{\lambda} \mathbf{I} + \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H}\right) \left(\frac{1}{\lambda} \mathbf{I} + \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H}\right)^{-1} - \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H} \left[\frac{1}{\lambda} \mathbf{I} + \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H} \right] \right] \mathbf{H}^H \\ & = \frac{\lambda}{\sigma_n^2} \left[\frac{1}{\lambda} \mathbf{I} + \frac{1}{\lambda} \mathbf{H}^H \mathbf{H} - \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H} \right] \left(\frac{1}{\lambda} \mathbf{I} + \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H} \right)^{-1} \mathbf{H}^H \\ & = \frac{1}{\sigma_n^2} \left(\frac{1}{\lambda} \mathbf{I} + \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H} \right) \mathbf{H}^H \end{split}$$

• How to choose λ

$$\mathbf{F}\mathbf{H} = \frac{1}{\sigma_n^2} \left(\frac{1}{\lambda} \mathbf{I} + \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H} \right)^{-1} \mathbf{H}^H \mathbf{H} = \mathbf{I}$$
$$\frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H} = \frac{1}{\lambda} \mathbf{I} + \frac{1}{\sigma_n^2} \mathbf{H}^H \mathbf{H}$$
$$\Rightarrow \lambda \to \infty$$

$$\Rightarrow$$
 $\mathbf{F} = (\mathbf{H}^H \mathbf{H})^{-1}$ $\hat{=}$ Moore-Penrose pseudoinverse

noise covariance:

$$\Phi_{ee} = \sigma_n^2 \mathbf{F} \mathbf{F}^H = \sigma_n^2 (\mathbf{H}^H \mathbf{H})^{-1} \underbrace{\mathbf{H}^H \mathbf{H} (\mathbf{H} \mathbf{H})^{-1}}_{\mathbf{T}} = \sigma_n^2 (\mathbf{H}^H \mathbf{H})^{-1}$$

 Φ_{ee} is not in general a diagonal matrix

- effective noise ${f Fn}$ is spatially correlated

- "equalization of channel leads to coloring of noise
- Interpretation:

we have

$$\mathbf{FHx} = egin{bmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \\ \vdots \\ \mathbf{f}_{N_T} \end{bmatrix} egin{bmatrix} \mathbf{h}_1 & \mathbf{h}_2 & \dots & \mathbf{h}_{N_T} \end{bmatrix} \mathbf{x} = \mathbf{x}$$

- $-\mathbf{f}_i\mathbf{h}_i = 1 \quad \mathbf{f}_i\mathbf{h}_j = 0 \quad \forall i \neq j$
- \mathbf{f}_i^T is orthogonal to $\begin{bmatrix} \mathbf{h}_1 & \dots \mathbf{h}_{i-1} & \mathbf{h}_{i+1} & \dots & \mathbf{h}_{N_T} \end{bmatrix} \updownarrow N_R$
- \mathbf{f}_i^T is confined to an $N_R (N_T 1)$ dimensional subspace of the N_R dimensional space spanned by \mathbf{H}
- Diversity gain
 - e.g. SISO model: $r_i = \mathbf{f}_i \cdot \mathbf{h}_i \mathbf{x}_i + \mathbf{f}_i \cdot \mathbf{n}_i$

$$\rightarrow \text{SNR}_{eq} = \frac{\mathcal{E}_s |\mathbf{f}_i \mathbf{h}_i|^2}{\sigma_n^2 \|\mathbf{f}_i\|^2} = \frac{\mathcal{E}_s}{\sigma_n^2} \left| \tilde{\mathbf{f}}_i \cdot \mathbf{h}_i \right|, \text{ where } \mathbf{f}_i = \alpha \mathbf{f}_i \text{ with } \|\tilde{\mathbf{f}}_i\|^2 = 1$$

we can represent \mathbf{f}_i as: $\tilde{\mathbf{f}}_i^T = \alpha \mathbf{M} \boldsymbol{\beta}$,

where: $\mathbf{M} \in \mathbb{C}^{N_R \times (N_R - N_T + 1)}$ and $\boldsymbol{\beta} \in \mathbb{C}^{(N_R - N_T + 1) \times 1}$ $\widehat{=}$ basis of subspace

$$\rightarrow \tilde{\mathbf{f}}_i \mathbf{M}_i = \boldsymbol{\beta}^T \mathbf{M}_i^T \mathbf{M}_i,$$

where: $\mathbf{M}^H \mathbf{M} = \tilde{\mathbf{M}}_i = \mathbf{I}$ and $\tilde{\mathbf{M}}_i \to \mathcal{CN}(0, \sigma_n^2 \mathbf{I}_{(N_R - N_T + 1)})$

(since rows of \mathbf{M}^T are orthogonal)

$$SNR_{eq} = \frac{\mathcal{E}_s}{\sigma_n^2} \alpha^2 \left| \sum_{j=1}^{N_R - N_T + 1} \boldsymbol{\beta}_{ji} \tilde{\mathbf{h}}_{ji} \right|^2; \tilde{\mathbf{h}}_i = \begin{pmatrix} \tilde{h}_{1i}, & \tilde{h}_{2i}, & \dots, & \tilde{h}_{N_R - N_T + 1} \end{pmatrix}^T$$
$$\boldsymbol{\beta}_i = \begin{pmatrix} \beta_{1i}, & \dots, & \beta_{N_R - N_T + 1, i} \end{pmatrix}^T$$

- \rightarrow SNR_{eq} includes only $N_R N_T + 1$ independent Gaussian RV
- \rightarrow diversity gain is limited to: $G_d = N_R N_T + 1$

Example:

$$\begin{split} N_T &= N_R = 3 \\ G_d^{ZF} &= 1 \text{ but } G_d^{ML} = N_R = 3 \end{split}$$

 \rightarrow huge performance loss because of linear ZF

MMSE detection

- ZF criterion may be too strict and leads to noise enhancement
 - \rightarrow may be it is better to allow some interferences between signals but reduce noise enhancement

- \rightarrow What is the optimal trade-off between interference and noise?
- \rightarrow MMSE criterion
- MMSE criterion
 - error signal: $\mathbf{e} = \mathbf{F}\mathbf{y} \mathbf{x}$
 - $\text{ total error variance: } \sigma_e^2 = \mathcal{E}\big\{\|\mathbf{e}\|^2\big\} = \mathcal{E}\big\{\mathrm{tr}\{\mathbf{e}\mathbf{e}^H\}\big\} = \mathrm{tr}\big\{\mathcal{E}\{\mathbf{e}\mathbf{e}^H\}\big\} = \mathrm{tr}\big\{\Phi_{ee}\big\}$
 - Φ_{ee} : error covariance matrix
 - optimal filter: $\mathbf{F}_{\mathrm{opt}} = \underset{\mathbf{F}}{\operatorname{argmin}} \operatorname{tr} \{ \Phi_{ee} \}$
- Deviation of $\mathbf{F}_{\mathrm{opt}}$

$$-\Phi_{ee} = \mathcal{E}\{\mathbf{e}\mathbf{e}^H\} = \mathcal{E}\{(\mathbf{F}\mathbf{y} - \mathbf{x})(\mathbf{F}\mathbf{y} - \mathbf{x})^H\} = \mathbf{F} \cdot \mathbf{\Phi}_{yy} \cdot \mathbf{F}^H - \mathbf{F} \cdot \mathbf{\Phi}_{yx} - \mathbf{\Phi}_{xy} \cdot \mathbf{F}^H + \mathbf{\Phi}_{xx}$$
 with:

$$\begin{split} & \boldsymbol{\Phi}_{yy} = \mathcal{E}\{\mathbf{y}\mathbf{y}^H\} = \mathcal{E}\{(\mathbf{H}\mathbf{x} + \mathbf{n})(\mathbf{H}\mathbf{x} + \mathbf{n})^H\} = \mathcal{E}_s \cdot \mathbf{H}\mathbf{H}^H + \sigma_n^2 \cdot \mathbf{I}_{N_R \times N_T} \\ & \boldsymbol{\Phi}_{yx} = \mathcal{E}\{\mathbf{y}\mathbf{x}^H\} = \mathcal{E}\{(\mathbf{H}\mathbf{x} + \mathbf{n}) \cdot \mathbf{x}^H\} = \mathcal{E}_s \cdot \mathbf{H}^H = \boldsymbol{\Phi}_{xy}^H \\ & \boldsymbol{\Phi}_{xx} = \mathcal{E}_s \cdot \mathbf{I}_{N_T \times N_R} \end{split}$$

$$-\mathbf{F}_{\text{opt}} \rightarrow \frac{d}{d\mathbf{F}^*} \left(\text{tr} \{ \mathbf{F} \mathbf{\Phi}_{yy} \mathbf{F}^H \} - \text{tr} \{ \mathbf{F} \mathbf{\Phi}_{yx} \} - \text{tr} \{ \mathbf{\Phi}_{xy} \mathbf{F}^H \} + \text{tr} \{ \mathbf{\Phi}_{xx} \} \right) \stackrel{!}{=} 0$$

with Table IV in paper by Hjoranges & Gesbert:

$$\Rightarrow \mathbf{F} \cdot \mathbf{\Phi}_{yy} - \mathbf{\Phi}_{xy} = 0$$

$$\Rightarrow \mathbf{F}_{opt} = \mathbf{\Phi}_{xy} \cdot \mathbf{\Phi}_{yy}^{-1} = \mathcal{E}_s \mathbf{H}^H (\mathcal{E}_s \mathbf{H} \mathbf{H}^H + \sigma_n^2 \mathbf{I})^{-1}$$

$$= (\text{Matrix inversion Lemma}) =$$

$$= (\mathbf{H}^H \mathbf{H} + \frac{\sigma_n^2}{\varepsilon} \mathbf{I})^{-1} \cdot \mathbf{H}^H$$

- Comparison:

$$\begin{split} \mathbf{F}_{\mathrm{MMSE}} &= \left(\mathbf{H}^H \mathbf{H} + \frac{\sigma_n^2}{\mathcal{E}_s} \mathbf{I}\right)^{-1} \cdot \mathbf{H}^H \xrightarrow[\frac{\sigma_n^2}{\mathcal{E}_s} \to 0]{} \left(\mathbf{H}^H \cdot \mathbf{H}\right)^{-1} \mathbf{H}^H = \mathbf{F}_{ZF} \\ &\xrightarrow[\frac{\sigma_n^2}{\mathcal{E}_s} \to \infty]{} \frac{\mathcal{E}_s}{\sigma_n^2} \cdot \mathbf{H}^H = \mathbf{F}_{MF} \quad \widehat{=} \text{matched filter} \end{split}$$

- \Rightarrow For high SNR, $\frac{\mathcal{E}_s}{\sigma_n^2}$, the MMSE filter approaches the ZF-Filter, for low SNR, it approaches the matched filter.
 - \rightarrow MMSE receiver yields the same diversity gain as the ZF receiver

$$G_d^{MMSE} = G_d^{ZF} = N_R - N_T + 1 \le G_d^{ML} = N_R$$

- End-to-End Channel: $\mathbf{K} = \mathbf{F}\mathbf{H} = \left(\mathbf{H}^H\mathbf{H} + \frac{\sigma_n^2}{\mathcal{E}_s} \cdot \mathbf{I}\right)^{-1} \cdot \mathbf{H}^H \cdot \mathbf{H} \neq \text{diagonal matrix}$
 - \Rightarrow crosstalk/interference between elements \mathbf{x} in received signal after filtering \mathbf{r} . elements of $\mathbf{K}: K_{l,n}$

- Covariance for $\mathbf{F}_{\mathrm{opt}}$

$$\begin{split} & \boldsymbol{\Phi}_{ee} = \boldsymbol{\Phi}_{xy} \cdot \overbrace{\boldsymbol{\Phi}_{yy}^{-1} \cdot \boldsymbol{\Phi}_{yy} \cdot \boldsymbol{\Phi}_{yy}^{-1}}^{\boldsymbol{\Phi}_{yy}^{-1}} \cdot \boldsymbol{\Phi}_{xy}^{H} - \boldsymbol{\Phi}_{xy} \cdot \boldsymbol{\Phi}_{yy}^{-1} \cdot \boldsymbol{\Phi}_{yx} - \boldsymbol{\Phi}_{xy} \cdot \boldsymbol{\Phi}_{yy}^{-1} \cdot \boldsymbol{\Phi}_{xy}^{H} + \boldsymbol{\Phi}_{xx} \\ & = \boldsymbol{\Phi}_{xx} - \overbrace{\boldsymbol{\Phi}_{xy} \cdot \boldsymbol{\Phi}_{yy}^{-1}}^{\mathbf{F}_{opt}} \cdot \boldsymbol{\Phi}_{yx} \\ & = \mathcal{E}_{s} \mathbf{I} - \mathcal{E}_{s} \left(\mathbf{H}^{H} \mathbf{H} + \frac{\sigma_{n}^{2}}{\mathcal{E}_{s}} \cdot \mathbf{I} \right)^{-1} \cdot \mathbf{H}^{H} \mathbf{H} = (\text{Matrix inversion Lemma}) \\ & = \sigma_{n}^{2} \left(\mathbf{H}^{H} \mathbf{H} + \frac{\sigma_{n}^{2}}{\mathcal{E}_{s}} \cdot \mathbf{I} \right)^{-1} \\ & \boldsymbol{\Phi}_{ee} = \mathcal{E}_{s} (\mathbf{I} - \mathbf{K}) \end{split}$$

 $\rightarrow 0 \le K_{m,m} \le 1$ since main diagonal elements of Φ_{ee} are $0 \le [\Phi_{ee}]_{m,m} \le \mathcal{E}_s$ siehe auch Abbildung ??

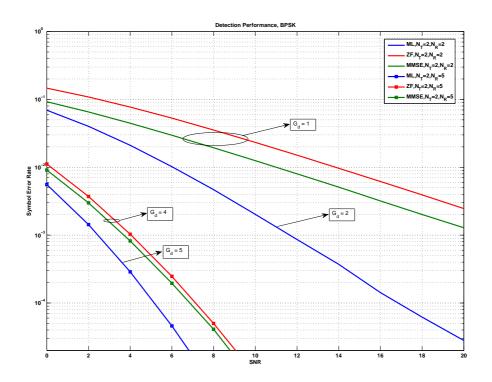


Abbildung 8: MMSE

SNR (biased vs. unbiased)

a) biased SNR

$$SNR_{bias,m} = \frac{\mathcal{E}_s}{[\boldsymbol{\Phi}_{ee}]_{mm}} = \frac{\mathcal{E}_s}{\mathcal{E}_s(1 - K_{mm})} = \frac{1}{1 - K_{mm}}, \quad 1 \le m \le 4$$

Anmerkung: $\mathbf{K} = \mathbf{F}_{\mathrm{opt}} \cdot \mathbf{H} \to \mathrm{SNR} = 1 \; \text{falls} \; \; \mathbf{K} = \mathrm{zeros}() \Rightarrow \text{woher SNR} = 1 \; \text{bei keiner}$ $Uebertragung? \Rightarrow nicht vorteilhaft: siehe: b) unbiased SNR$ but:

 \bullet SNR_{bias,m} does not represent the actual SNR since the main diagonal elements of **K** are smaller than 1

$$\bullet \ \mathbf{r} = \mathbf{F}\mathbf{H}\mathbf{x} + \mathbf{F}\mathbf{n} = \mathbf{K}\mathbf{x} + \underbrace{\mathbf{F}\mathbf{n}}_{\tilde{\mathbf{n}} = [\tilde{n}_1, \dots, \tilde{n}_{N_T}]^T}$$

•
$$r_m = \underbrace{K_{mm}}_{<1} x_m + \sum_{\substack{n=1\\n \neq m}}^{N_T} K_{mn} x_n + \tilde{n}_m$$

b) unbiased SNR

• remove bias:
$$r'_m = \frac{r_m}{K_{mm}} = x_m + \underbrace{\frac{\tilde{e}_m}{K_{mm}}}_{e'_m}$$

- scaling matrix: $\mathbf{C} = \operatorname{diag}\left\{\frac{1}{K_{11}}, \frac{1}{K_{22}}, \dots, \frac{1}{K_{N_m N_m}}\right\}$

•
$$\mathbf{r}' = \mathbf{Cr} \rightarrow \mathbf{e}' = [e'_1, \dots, e'_{N_T}]^T = \mathbf{r}' - \mathbf{x} = \mathbf{Cr} - \mathbf{x} = \mathbf{CFy} - \mathbf{x}$$

$$\bullet \ \ \boldsymbol{\Phi}_{e'e'} = \mathcal{E}\Big\{ \big(\mathbf{CFy} - \mathbf{x}\big) \big(\mathbf{CFy} - \mathbf{x}\big)^H \Big\} = \mathbf{CF}\boldsymbol{\Phi}_{yy}\mathbf{F}^H\mathbf{C}^H - \mathbf{CF}\boldsymbol{\Phi}_{yx} - \boldsymbol{\Phi}_{xy}\mathbf{F}^H\mathbf{C}^H + \boldsymbol{\Phi}_{xx}\mathbf{F}^H\mathbf{C}^H + \mathbf{CF}\mathbf{C}^H\mathbf{C}^H + \mathbf{CF}\mathbf{C}^H\mathbf{C}^H\mathbf{C}^H + \mathbf{CF}\mathbf{C}^H\mathbf{C}^$$

$$ullet$$
 $\mathbf{F} = \mathbf{F}_{\mathrm{opt}}
ightarrow \mathbf{F}_{\mathrm{opt}} \mathbf{\Phi}_{uu} = \mathbf{\Phi}_{xu} = \mathcal{E}_s \cdot \mathbf{H}^H$

$$\begin{split} \bullet & \ \mathbf{F} = \mathbf{F}_{\mathrm{opt}} \to \mathbf{F}_{\mathrm{opt}} \mathbf{\Phi}_{yy} = \mathbf{\Phi}_{xy} = \mathcal{E}_s \cdot \mathbf{H}^H \\ \to & \ \mathbf{\Phi}_{e'e'} = \mathcal{E}_s \mathbf{C} \underbrace{\mathbf{H}^H \mathbf{F}^H}_{\mathbf{K}^H} \mathbf{C}^H - \mathcal{E}_s \mathbf{C} \underbrace{\mathbf{F} \mathbf{H}}_{\mathbf{K}} - \mathcal{E}_s \underbrace{\mathbf{H}^H \mathbf{F}^H}_{\mathbf{K}^H} \mathbf{C}^H + \mathcal{E}_s \mathbf{I} \\ & = \mathcal{E}_s \big[\mathbf{I} + (\mathbf{C} - \mathbf{I}) \mathbf{K}^H \mathbf{C}^H - \mathbf{C} \mathbf{K} \big] \end{split}$$

Anmerkung: nur Hauptdiagonalelemente interessieren, da diese die Varianz darstellen

$$\rightarrow$$
 maindiagonal elements of $\Phi_{e'e'}$ = variances of $e'_m = \mathcal{E}_s \left(1 + \left(\frac{1}{K_{mm}} - 1\right)K_{mm}\frac{1}{K_{mm}} - \frac{1}{K_{mm}}K_{mm}\right) = \frac{1 - K_{mm}}{K_{mm}}$

 \rightarrow vgl. Abbildung ??

$$\rightarrow SNR_{unbiased} = \frac{\mathcal{E}_s}{[\Phi_{e'e'}]_{mm}} = \frac{\mathcal{E}_s}{\mathcal{E}_s \frac{1 - K_{mm}}{K_{mm}}} = \frac{K_{mm}}{1 - K_{mm}} = \frac{1}{1 - K_{mm}} - 1 = SNR_{biased} - 1, \quad 1 \le m \le N_T$$

 \rightarrow the SNR after bias removal is by "1" smaller than the biased SNR \rightarrow general result valid for any type of MMSE estimation

2.4.3 Decision - Feadback Equalization (Detection)

- Also known as:
 - BLAST (Bell Laboratories space-time system)
 - successive interference cancellation
- \bullet Problem of linear receiver: Noise enhancement because of linear filtering \to nonlinear filtering processing necessary

Basic Idea

- Recall (linear filter): $\mathbf{FH} = \mathbf{I}$ for linear ZF receiver $\to i$ th row of \mathbf{F}, \mathbf{f}_i , is orthogonal to the jth column of \mathbf{H}, \mathbf{h}_j , if $i \neq j$ (if i = j: inner product = 1)
- we can detect x_i , based on $r_i = \mathbf{f}_i \mathbf{y}$
- Once we have detected x_i , we can substract its contribution from \mathbf{y} : $\mathbf{y}_1 = \mathbf{y} \mathbf{h}_i \hat{x}_i$ (\hat{x}_i is detected symbol, we assume for now, $\hat{x}_i = x_i$)
- \mathbf{y}_1 can be expressed as $\mathbf{y}_1 = \mathbf{H}_i \mathbf{x}_i + \mathbf{n}$ where

$$\mathbf{H}_i = \begin{bmatrix} \mathbf{h}_1, \dots, \mathbf{h}_{i-1}, \mathbf{h}_{i+1}, \dots, \mathbf{h}_{N_T} \end{bmatrix}$$

$$\mathbf{x}_i = \begin{bmatrix} x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_{N_T} \end{bmatrix}$$

- \rightarrow we have reduced the number of signal streams to $N_T 1$ (N_R bleibt gleich)
- apply now linear ZF filter for symbol to detected next, e.g. x_j , where $j \in \{1, ..., i 1, i + 1, ..., N_T\}$
- \rightarrow $\mathbf{r}_j = \mathbf{f}_j \mathbf{y}_1$ where \mathbf{f}_j is the ZF filter for \mathbf{H}_1
- substract contribution of x_j from \mathbf{y}_1 : $\mathbf{y}_2 = \mathbf{y}_1 \mathbf{h}_j x_j$
- substract until last symbol is detected
- Blockdiagram see figure??
- Observations:
 - The order in which the x_1 are detected can be freely chosen and effects the performance $\to N_T!$ possible orders \to cannot explore all of them
 - Practical approach: Select in each step that x_i for which the noise variance enhancement is minimum, i.e. which has the smallest $\mathcal{E}\{|\mathbf{f}_i\mathbf{n}|^2\} = \sigma_n^2 ||\mathbf{f}_i||^2$
- Diversity order:

- stage 1:
$$G_d^1 = N_R - N_T + 1$$

- stage 2:
$$G_d^2 = G_d^1 + 1 = N_R - N_T + 2$$

:

- stage
$$N_T$$
: $G_d^{N_T} = N_R$

- overall:
$$G_d = N_R - N_T + 1$$

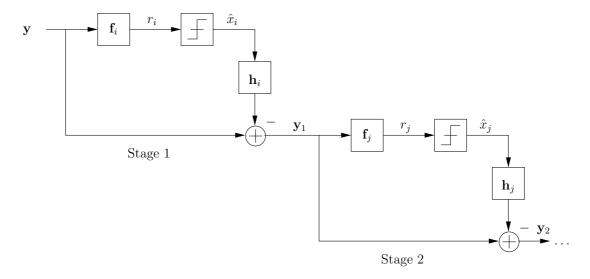


Abbildung 9: DFE Blockdiagram

- (Anmerkung: der schlechteste Fall dominiert (Stage 1), weitere koennen nur schwer beeinflussen)

ZF - DFE - Matrix Model

- Signal model: $\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{n} = \underbrace{\mathbf{H}\mathbf{P}}_{\tilde{\mathbf{H}}} \cdot \underbrace{\mathbf{P}^{-1}\mathbf{x}}_{\tilde{\mathbf{x}}} + \mathbf{n}$ with permutation matrix \mathbf{P}
- \bullet **P** has one "1" per column and row, all other elements are "0"
- \rightarrow can change the detection order to maximize performance
- note: $\mathbf{P}^T = \mathbf{P}^{-1}$
- Example:

$$\mathbf{P} = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} [r] \to \mathbf{P}^{-1} = \mathbf{P}^{T} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$
$$\tilde{\mathbf{x}} = \mathbf{P}^{T} \cdot \mathbf{x} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix} = \begin{pmatrix} x_{2} \\ x_{3} \\ x_{1} \end{pmatrix}$$

- Blockdiagram see figure ??
- DFE Filters:
 - \mathbf{F} feedworward filter
 - **B** feedback filter
- Filter calculation

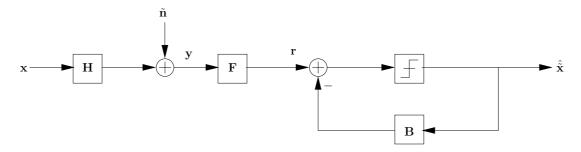


Abbildung 10: ZF-DFE Matrix Model

– Cholesky factorization: $\tilde{\mathbf{H}}^H \tilde{\mathbf{H}} = \mathbf{L}^H \mathbf{D} \mathbf{L}$ with diagonal matrix \mathbf{D} and lower triangular matrix \mathbf{L} (maindiagonal elements of \mathbf{L} are "1")

$$\mathbf{L} = \begin{bmatrix} 1 & 0 & \cdots & \cdots & 0 \\ l_{21} & 1 & \ddots & \ddots & \vdots \\ l_{31} & l_{32} & 1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \cdots & \cdots & \cdots & 1 \end{bmatrix}$$

 $-\mathbf{F} = \mathbf{D}^{-1}\mathbf{L}^{-H}\tilde{\mathbf{H}}^{H}$

$$\rightarrow \mathbf{r} = \mathbf{F} \mathbf{y} = \underbrace{\mathbf{D}^{-1} \mathbf{L}^{-H} \underbrace{\tilde{\mathbf{H}}^{H} \tilde{\mathbf{H}}}_{\mathbf{L}^{H} \mathbf{D} \mathbf{L}} \tilde{\mathbf{x}} + \underbrace{\mathbf{D}^{-1} \mathbf{L}^{-H} \tilde{\mathbf{H}}^{H} \mathbf{n}}_{\tilde{\mathbf{n}}}}_{\mathbf{n}}$$

– $\mathbf{B} = \mathbf{L} - \mathbf{I} = \text{lower triangular matrix with main$ diagonal elements "0"

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & \cdots & \cdots & 0 \\ l_{21} & 0 & \ddots & \ddots & \vdots \\ l_{31} & l_{32} & 0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \cdots & \cdots & \cdots & 0 \end{bmatrix}$$

- Interpretation:
 - after feedforward filter

$$\mathbf{r} = \begin{bmatrix} 1 & 0 & \cdots & \cdots & 0 \\ l_{21} & 1 & \ddots & \ddots & \vdots \\ l_{31} & l_{32} & 1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \cdots & \cdots & \cdots & 1 \end{bmatrix} \begin{bmatrix} \tilde{x}_1 \\ \tilde{x}_2 \\ \vdots \\ \tilde{x}_{N_T} \end{bmatrix} + \tilde{\mathbf{n}}$$

• from feedback filter

$$\tilde{\mathbf{r}} = \begin{bmatrix} 0 & 0 & \cdots & \cdots & 0 \\ l_{21} & 0 & \ddots & \ddots & \vdots \\ l_{31} & l_{32} & 0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \cdots & \cdots & \cdots & 0 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \\ \vdots \\ \hat{x}_{N_T} \end{bmatrix} \hat{x}_n : \text{decision on } \tilde{x}_n$$

$$\rightarrow \mathbf{r} - \tilde{\mathbf{r}} = \begin{bmatrix} \tilde{x}_1 + 0 \\ l_{21}(\tilde{x}_1 - \hat{x}_1) + \tilde{x}_2 + 0 \\ l_{31}(\tilde{x}_1 - \hat{x}_2) + l_{32}(\tilde{x}_2 - \hat{x}_2) + \tilde{x}_3 + 0 \end{bmatrix} + \tilde{\mathbf{n}}$$

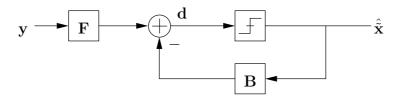


Abbildung 11: MMSE-DFE Blockdiagram

MMSE-DFE

• $\mathbf{B} = \mathbf{L} - \mathbf{I}$ has to be lower triangular matrx with all-zero main diagonal elements because of causality.

$$\bullet \ \mathbf{d} = \mathbf{F}\mathbf{y} - \mathbf{B}\hat{\tilde{\mathbf{x}}} \quad \to \mathbf{e} = \mathbf{d} - \tilde{\mathbf{x}} = \mathbf{F}\mathbf{y} - \underbrace{\left(\mathbf{B} + \mathbf{I}\right)}_{\mathbf{I}} \tilde{\mathbf{x}}$$

where we assume $\hat{\tilde{\mathbf{x}}} = \tilde{\mathbf{x}}$ for filter optimization

• Optimal F for given L

$$\sigma_e^2 = \operatorname{tr}\left\{\underbrace{\mathcal{E}\{\mathbf{e}\mathbf{e}^H\}}_{\Phi_{ee}}\right\} = \operatorname{tr}\left\{\mathbf{F}\Phi_{yy}\mathbf{F}^H\right\} - \operatorname{tr}\left\{\mathbf{F}\Phi_{y\tilde{x}}\mathbf{L}^H\right\} - \operatorname{tr}\left\{\mathbf{L}\Phi_{\tilde{x}y}\mathbf{F}^H\right\} + \operatorname{tr}\left\{\mathbf{L}\Phi_{\tilde{x}\tilde{x}}\mathbf{L}^H\right\}$$

$$\frac{\delta}{\delta \mathbf{F}^*} \sigma_e^2 = \mathbf{F} \mathbf{\Phi}_{yy} - \mathbf{L} \mathbf{\Phi}_{\tilde{x}y} = 0 \quad \rightarrow \mathbf{F} = \mathbf{L} \mathbf{\Phi}_{\tilde{x}y} \mathbf{\Phi}_{yy}^{-1}$$

where

$$egin{aligned} & \Phi_{yy} = \mathcal{E}_s ilde{\mathbf{H}} ilde{\mathbf{H}}^H + \sigma_n^2 \mathbf{I} \ & \\ & \Phi_{ ilde{x}y} = \mathcal{E}_s ilde{\mathbf{H}}^H \end{aligned}$$

$$\rightarrow \mathbf{F} = \mathbf{L}\tilde{\mathbf{H}}^{H}(\tilde{\mathbf{H}}\tilde{\mathbf{H}}^{H} + \frac{\sigma_{n}^{2}}{\mathcal{E}_{s}}\mathbf{I})^{-1} = \mathbf{L}(\tilde{\mathbf{H}}^{H}\tilde{\mathbf{H}} + \frac{\sigma_{n}^{2}}{\mathcal{E}_{s}}\mathbf{I})^{-1}\tilde{\mathbf{H}}^{H}$$

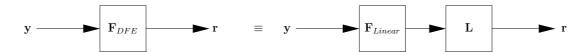


Abbildung 12: MMSE-DFE Equivalence

• Optimal L:

$$\begin{split} \boldsymbol{\Phi}_{ee} &= \mathbf{L}\boldsymbol{\Phi}_{\tilde{x}y}\boldsymbol{\Phi}_{yy}^{-1}\boldsymbol{\Phi}_{yy}\boldsymbol{\Phi}_{yy}^{-1}\boldsymbol{\Phi}_{\tilde{x}y}^{H}\mathbf{L}^{H} - \mathbf{L}\boldsymbol{\Phi}_{\tilde{x}y}\boldsymbol{\Phi}_{yy}^{-1}\boldsymbol{\Phi}_{y\tilde{x}}\mathbf{L}^{H} - \mathbf{L}\boldsymbol{\Phi}_{\tilde{x}y}\boldsymbol{\Phi}_{yy}^{-1}\boldsymbol{\Phi}_{\tilde{x}y}^{H}\mathbf{H}^{H} + \mathbf{L}\boldsymbol{\Phi}_{\tilde{x}\tilde{x}}\mathbf{L}^{H} \\ &= \mathbf{L}(\boldsymbol{\Phi}_{\tilde{x}\tilde{x}} - \boldsymbol{\Phi}_{\tilde{x}y}\boldsymbol{\Phi}_{yy}^{-1}\boldsymbol{\Phi}_{\tilde{x}y}^{H})\mathbf{L}^{H} \end{split}$$

= MMSE covariance matrix for a linear MMSE filter

$$ightarrow \Phi_{ee} = \sigma_n^2 \mathbf{L} (\tilde{\mathbf{H}}^H \tilde{\mathbf{H}} + \frac{\sigma_n^2}{\mathcal{E}_o} \mathbf{I})^{-1} \mathbf{L}^H$$

- \rightarrow need lower triangular matrix **L** which minimizes $\operatorname{tr}\{\Phi_{ee}\}$
- \rightarrow the optimum **L** whitenes $\Phi_{ee} \rightarrow \Phi_{ee}$ becomes diagonal matrix, i.e. **L** exploits the correlation after linear MMSE filtering to reduce noise variance!
- ightarrow L is obtained via Cholesky factorization

$$ilde{\mathbf{H}}^H ilde{\mathbf{H}} + rac{\sigma_n^2}{\mathcal{E}_s} \mathbf{I} = \mathbf{L} \mathbf{D} \mathbf{L}^H$$

$$\rightarrow \Phi_{ee} = \sigma_n^2 \mathbf{L} (\mathbf{L} \mathbf{D} \mathbf{L}^H)^{-1} \mathbf{L} = \sigma_n^2 \mathbf{L} \mathbf{L}^{-1} \mathbf{D}^{-1} \mathbf{L}^{-H} \mathbf{L}^H = \sigma_n^2 \mathbf{D}^{-1} \stackrel{\frown}{=} \text{diagonal matrix}$$

• Summary of MMSE calculation

$$-\mathbf{B} = \mathbf{L} - \mathbf{I} \text{ where } \tilde{\mathbf{H}}^H \tilde{\mathbf{H}} + \frac{\sigma_n^2}{\mathcal{E}_s} \mathbf{I} = \mathbf{L} \mathbf{D} \mathbf{L}^H$$

$$-\mathbf{F} = \mathbf{L} \underbrace{(\tilde{\mathbf{H}}^H \tilde{\mathbf{H}} + \frac{\sigma_n^2}{\mathcal{E}_s} \mathbf{I})^{-1} \tilde{\mathbf{H}}^H}_{\mathbf{F}_{Linear}}$$

- L is a prediction error filter, which whitenes the error signal e
- SNR:

$$\mathbf{D} = \operatorname{diag}\{\xi_1, \dots, \xi_{N_T}\}$$

$$\mathbf{\Phi}_{ee} = \operatorname{diag}\{\frac{\sigma_n^2}{\xi_1}, \dots, \frac{\sigma_n^2}{\xi_{N_T}}\}$$

- end-to-end channel

$$\begin{split} \mathbf{K} &= \mathbf{F}\tilde{\mathbf{H}} \\ &= \underbrace{\mathbf{L}(\tilde{\mathbf{H}}^H\tilde{\mathbf{H}} + \frac{\sigma_n^2}{\mathcal{E}_s}\mathbf{I})^{-1}\mathbf{L}^H}_{\mathbf{J}^H\tilde{\mathbf{H}}^H\tilde{\mathbf{H}}^H} \mathbf{L}^{-H}\tilde{\mathbf{H}}^H\tilde{\mathbf{H}} \\ &= \underbrace{\frac{1}{\sigma_n^2}\mathbf{\Phi}_{ee}}_{\mathbf{L}^{-H}}(\tilde{\mathbf{H}}^H\tilde{\mathbf{H}} + \frac{\sigma_n^2}{\mathcal{E}_s}\mathbf{I} - \frac{\sigma_n^2}{\mathcal{E}_s}\mathbf{I})\mathbf{L}^{-1}\mathbf{L} \\ &= \underbrace{\frac{1}{\sigma_n^2}\mathbf{\Phi}_{ee}}_{\mathbf{L}^{-H}}(\tilde{\mathbf{H}}^H\tilde{\mathbf{H}} + \frac{\sigma_n^2}{\mathcal{E}_s}\mathbf{I})\mathbf{L}^{-1}\mathbf{L} - \frac{\sigma_n^2}{\mathcal{E}_s}\mathbf{L}^{-H}] \\ &= \mathbf{L} - \frac{1}{\mathcal{E}_s}\mathbf{\Phi}_{ee}\mathbf{L}^{-H} \end{split}$$

 \rightarrow main diagonal of **K**:

$$K_{mm} = 1 - \frac{\sigma_n^2}{\mathcal{E}_s \xi_m} < 1$$

- biased SNR

$$SNR_{m,bias} = \frac{\mathcal{E}_S}{[\mathbf{\Phi}_{ee}]_{mm}} = \frac{\mathcal{E}_s}{\sigma_n^2} \xi_m = \frac{1}{1 - K_{mm}}, \quad 1 \le m \le N_T$$

- unbiased SNR

$$SNR_{m,unbiased} = SNR_{m,bias} - 1 = \frac{1}{1 - K_{mm}} - 1 = \frac{K_{mm}}{1 - K_{mm}}, \quad 1 \le m \le N_T$$

2.4.4 Sphere Decoding

- Linear and DFE receivers cannot approach performance of ML-detector
- ML detector: $\hat{\mathbf{x}} = \underset{\mathbf{x} \in A^{N_T}}{\operatorname{argmin}} ||\mathbf{y} \mathbf{H}\mathbf{x}||^2$
- \rightarrow high complexity for brute force search

Main Idea

- can we search ML metric in a "smarter" way, akin to the smart search of the viterbi algorithm for problems with a trellis structure
- we need to find a way to prune/dismiss non-ML sequences/vectores early on
- $\rightarrow\,$ this is accomplished by sphere decoding

Step 1 Bring metric into a suitable form:

- real representation: $||\mathbf{y} \mathbf{H}\mathbf{x}||^2 = ||\tilde{\mathbf{y}} \tilde{\mathbf{H}}\tilde{\mathbf{x}}||^2$
- where:

$$\begin{split} \tilde{\mathbf{y}} &= \begin{bmatrix} \operatorname{Re}\{\mathbf{y}^T\} & \operatorname{Im}\{\mathbf{y}^T\} \end{bmatrix}^T \\ \tilde{\mathbf{x}} &= \begin{bmatrix} \operatorname{Re}\{\mathbf{x}^T\} & \operatorname{Im}\{\mathbf{x}^T\} \end{bmatrix}^T \\ \tilde{\mathbf{H}} &= \begin{bmatrix} \operatorname{Re}\{\mathbf{H}\} & -\operatorname{Im}\{\mathbf{H}\} \\ \operatorname{Im}\{\mathbf{H}\} & \operatorname{Re}\{\mathbf{H}\} \end{bmatrix}^T \end{split}$$

- \rightarrow QAM: $\tilde{\mathbf{x}}$ defines points in an $2N_T$ dimensional lattice
- QL decomposition: $\tilde{\mathbf{H}} = \mathbf{QL}$ with
 - orthogonal matrix $\mathbf{Q} \in \mathbb{R}^{2N_T \times 2N_T}$; $\mathbf{Q}\mathbf{Q}^T = \mathbf{I}$
 - and lower triangular matrix $\mathbf{L} \in \mathbb{R}^{2N_T \times 2N_T}$

$$\begin{aligned} ||\tilde{\mathbf{y}} - \mathbf{Q}\mathbf{L}\tilde{\mathbf{x}}||^2 &= ||\mathbf{Q}\mathbf{Q}^T(\tilde{\mathbf{y}} - \mathbf{Q}\mathbf{L}\tilde{\mathbf{x}})||^2 + ||(\mathbf{I} - \mathbf{Q}\mathbf{Q}^T)(\tilde{\mathbf{y}} - \mathbf{Q}\mathbf{L}\tilde{\mathbf{x}})||^2 \\ &= ||\mathbf{Q}(\mathbf{Q}^T\tilde{\mathbf{y}} - \mathbf{L}\tilde{\mathbf{x}})||^2 + ||(\mathbf{I} - \mathbf{Q}\mathbf{Q}^T)\tilde{\mathbf{y}} - \underbrace{(\mathbf{Q} - \mathbf{Q})}_{=0}\mathbf{L}\tilde{\mathbf{x}}||^2 \\ &= ||\mathbf{Q}^T\tilde{\mathbf{y}} - \mathbf{L}\tilde{\mathbf{x}}||^2 + \underbrace{||(\mathbf{I} - \mathbf{Q}\mathbf{Q}^T)\tilde{\mathbf{y}}||^2}_{\text{unabhängig von }\tilde{\mathbf{x}}} \end{aligned}$$

$$\begin{split} &\Rightarrow \underset{\tilde{\mathbf{x}} \in A^{2N_T}}{\operatorname{argmin}} ||\tilde{\mathbf{y}} - \tilde{\mathbf{H}} \tilde{\mathbf{x}}||^2 = \underset{\tilde{\mathbf{x}} \in A^{2N_T}}{\operatorname{argmin}} ||\underbrace{\mathbf{Q}^T \tilde{\mathbf{y}}}_{\tilde{\mathbf{y}}} - \mathbf{L} \tilde{\mathbf{x}}||^2 \\ &\text{where } A^{2N_T} \text{ contains all } M^{N_T} \text{ possible vectors } \tilde{\mathbf{x}} \end{split}$$

- Observation:
 - with

$$\mathbf{L} = \begin{bmatrix} l_{11} & 0 & \cdots & 0 \\ l_{21} & l_{22} & \ddots & \vdots \\ \vdots & \ddots & 0 \\ l_{2N_T 1} & \cdots & l_{2N_T 2N_T} \end{bmatrix}$$
$$\bar{\mathbf{y}} = \begin{bmatrix} \bar{y}_1 & \cdots & \bar{y}_{2N_T} \end{bmatrix}^T ; \quad \tilde{\mathbf{x}} = \begin{bmatrix} \tilde{x}_1 & \cdots & \tilde{x}_{2N_T} \end{bmatrix}$$

- we have

$$||\bar{\mathbf{y}} - \mathbf{L}\tilde{\mathbf{x}}||^2 = (\bar{y} - l_{11}\tilde{x}_1)^2 + (\bar{y}_2 - l_{21}\tilde{x}_1 - l_{22}\tilde{x}_2)^2 + (\bar{y}_3 - l_{31}\tilde{x}_1 - l_{32}\tilde{x}_2 - l_{33}\tilde{x}_3)^2 + \dots$$
(1)

 \rightarrow the *n*-th term in the above sum contains only $\tilde{x}_1, \tilde{x}_2, \dots, \tilde{x}_n$

Step 2 Sphere decoding algorithm

Define:

$$d(\tilde{\mathbf{x}}) = \sum_{n=1}^{2N_T} f_n(\tilde{\mathbf{x}}_n) \; ; \quad \text{with } f_n(\tilde{\mathbf{x}}_n) = \left(\bar{y}_n - \sum_{i=1}^n l_{ni}\tilde{x}_i\right)^2 \; ; \quad \tilde{\mathbf{x}}_n = \begin{bmatrix} \tilde{x}_1 & \dots & \tilde{x}_n \end{bmatrix}^T$$
$$d_n(\tilde{x}_n) = \sum_{m=1}^n f_n(\tilde{\mathbf{x}}_m)$$

Main Idea:

- Assume we know that $d(\tilde{\mathbf{x}}) \leq R$ holds for some $\tilde{\mathbf{x}}$, where R is the so called "sphere radius" \to any $\tilde{\mathbf{x}}$ with $d(\tilde{\mathbf{x}}) \geq R$ cannot be the ML solution and can be discarded
- since $d_{n+1}(\tilde{\mathbf{x}}'_n, \tilde{x}_{n+1}) \geq d_n(\tilde{\mathbf{x}}'_n)$, we can easily discard \mathbf{x}'_n and all possible $\tilde{\mathbf{x}} = \begin{bmatrix} \tilde{\mathbf{x}}'_n & \tilde{x}_{n+1} & \tilde{x}_{n+2} & \dots & \tilde{x}_{2N_T} \end{bmatrix}^T$ if we find $d_n(\tilde{\mathbf{x}}'_n) > R$ \Rightarrow we can exclude many possible vectors $\tilde{\mathbf{x}}$ without evaluating any metrics for them
- How to find a suitable R?
 - Initial $R: R = d(\tilde{\mathbf{x}}_{\text{subopt}})$ where $\tilde{\mathbf{x}}_{\text{subopt}}$ was obtained with some suboptimum receiver
 - R is updated as $R = R_{\text{new}} = d(\tilde{\mathbf{x}}_{\text{cand}})$ where $\tilde{\mathbf{x}}_{\text{cand}}$ is an $\tilde{\mathbf{x}}$ which yields $d(\tilde{\mathbf{x}}_{\text{cand}}) < R_{\text{old}} = R$
- \bullet Use tree structure to represent all possible $\tilde{\mathbf{x}}$

Example:

- Siehe dazu Abbildung 13 auf S. 39
- Assume $\tilde{\mathbf{x}}_{\text{subopt}} = \begin{bmatrix} -1 & -1 & -1 & 1 \end{bmatrix}^T$ $\Rightarrow d(\tilde{x}_{\text{subopt}} = 1 + 2 + 2 + 2 = 7 = R$
- For $\tilde{x}_1 = 1$ we find $d_2(1,1) = 5 + 3 = 8 > R$ and d(1,-1) = 5 + 4 > R \Rightarrow we don't have to calculate metrics for remaining branches, i.e., for nodes $19, \ldots, 31$
- For $\tilde{x}_1 = -1$ and $\tilde{x}_2 = 1$, we find that $d_3(-1, 1, -1) = 8 > R$ and $d_3(-1, 1, 1) = 9 > R$ \Rightarrow remaining branches emerging from nodes 6 and 7 can be discarded
- For the ML solution we find d(-1, -1, 1, -1) = 5 < R
- Different strategies exist, regarding in which order the nodes in the tree (points in the lattice) are investigated
 - Pohst strategy
 - Schnoir Enchner strategy
 - rich literature on lattice decoding algorithms
- Complexity of sphere decoding
 - worst-case complexity is still exponential in N_T
 - (for practical case:) for sufficiently high SNR, the average complexity is only polynomial in $N_T \Rightarrow$ efficient ML decoding



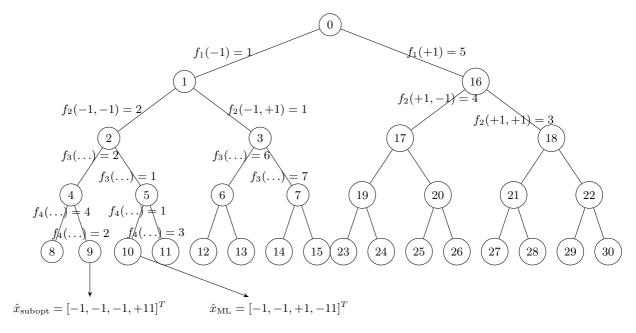


Abbildung 13: BPSK = 2, $N_T = 2$

- $\bullet\,$ sphere decoding has found application in many fields:
 - ML detection in MIMO and multiuser systems
 - precoding
 - source coding
 - multiple symbol differential detection