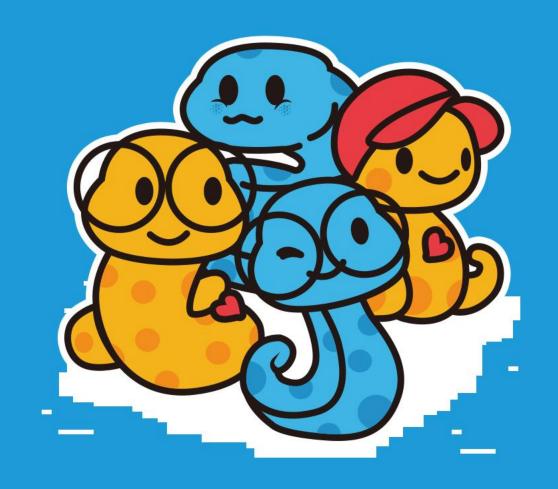
# PyCon China 2024

For Good . For fun. 2024/11/23 中国 上海





# Pytroch 模型优化部署背后的技术探究

杨权

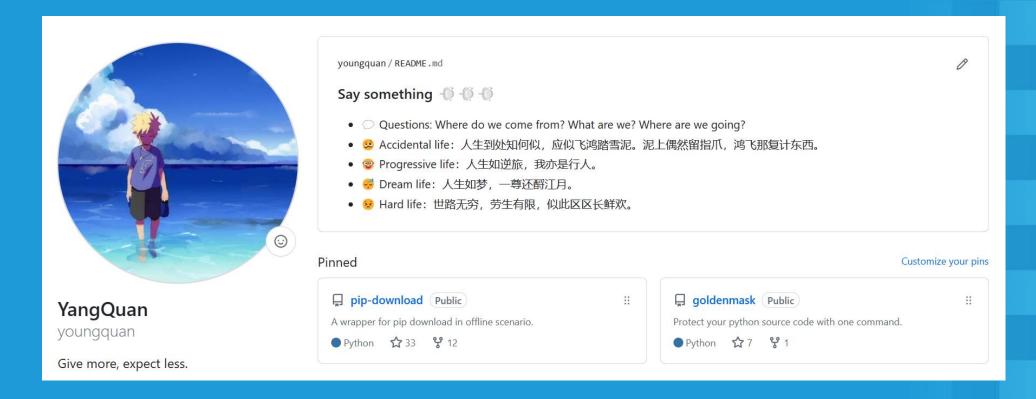


### 个人介绍

● 过去: 兰州大学、西安交通大学、中国电科

● 现在: 哈尔滨工业大学重庆研究院 机器视觉工程师

● 未来: XXX CTO ❷





# 技术背景





技术分析



技术应用

## 工业图像异常检测





- 1. Chen, Qiyu, et al. "A unified anomaly synthesis strategy with gradient ascent for industrial anomaly detection and localization." arXiv preprint arXiv:2407.09359 (2024).
- 2. Mousakhan, Arian, Thomas Brox, and Jawad Tayyub. "Anomaly detection with conditioned denoising diffusion models." arXiv preprint arXiv:2305.15956 (2023).

# 核心技术栈

训练

推理









**?** python™





# 技术背景



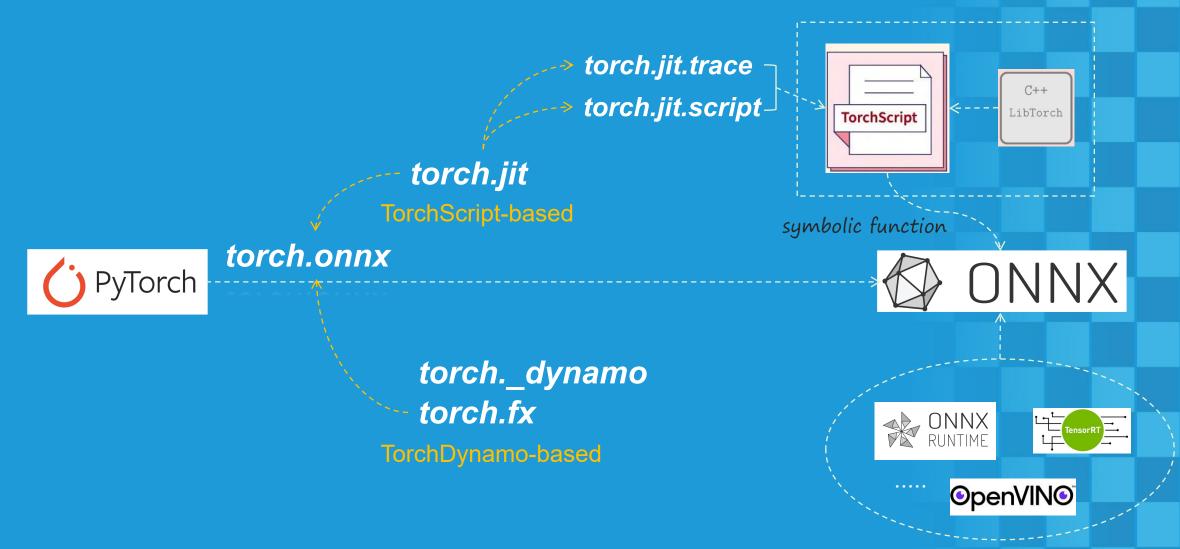


技术分析

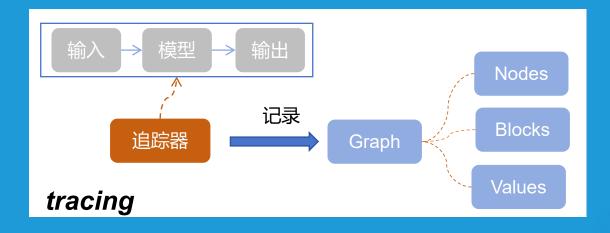


技术应用

# Pytorch模型部署技术路线

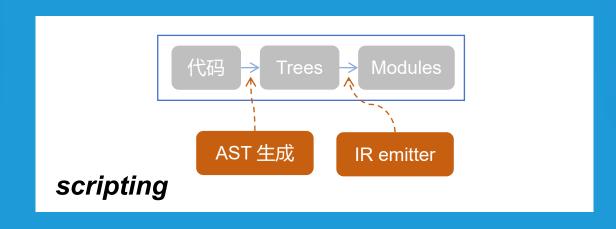


### torch.jit



#### **Eager Mode**

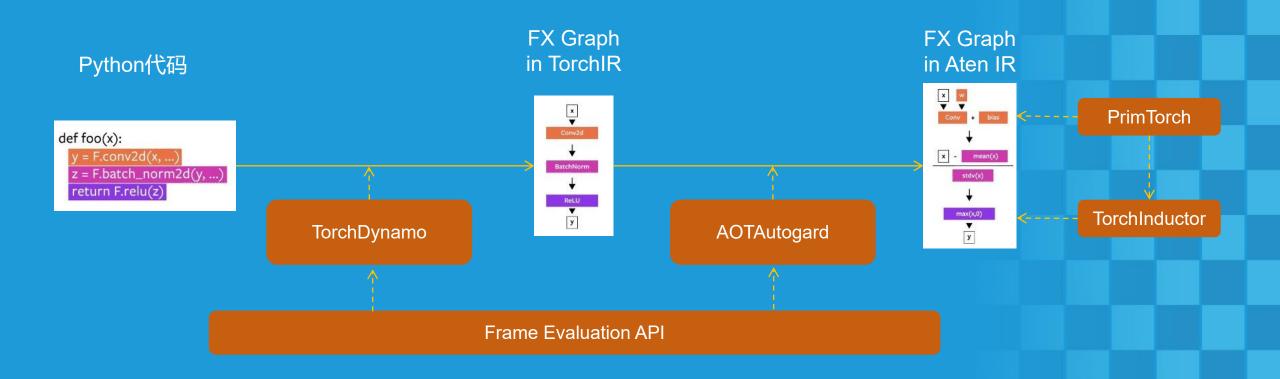
动态图



#### **Graph Mode**

静态图

### torch.\_dynamo + torch.fx





# 技术背景





技术分析



技术应用

```
torch.onnx.export(
        ddad,
        dummy_input,
        "ddad.onnx",
        verbose=True,
        input names=["img"],
        output names=["map"],
```

```
torch.onnx.errors.SymbolicValueError: Unsupported: ONNX export of
convolution for kernel of unknown shape. [Caused by the value
'43357 defined in (%43357 : Float(*, *, *, *, strides=[73728,
73728, 288, 1], requires_grad=0, device=cuda:0) =
onnx::Reshape[allowzero=0](%43332, %43356), scope: ddad.DDAD_ONNX::
# D:\yangquan\projects\DDAD\.venv\lib\site-
packages\kornia\filters\filter.py:126:0
```

```
input = input.view(-1, tmp kernel.size(0), input.size(-2), input.size(-1))
input = input.view(-1, tmp kernel.size(0), input.size(-2), input.size(-1))
When indexing into a tensor for reading, the following patterns are not
supported:
# Tensor indices that includes negative values.
```

data[torch.tensor([[1, 2], [2, -3]]), torch.tensor([-2, 3])]

# Workarounds: use positive index values.

```
def heat map(output, target, FE, config):
   output = output.to(config.model.device)
   target = target.to(config.model.device)
   i d = pixel distance(output, target)
   f d = feature distance((output), (target), FE, config)
    anomaly map = gaussian blur2d(
         anomaly_map, kernel_size=(kernel_size, kernel_size), sigma=(sigma, sigma)
```

```
input = input.view(-1, tmp_kernel.size(0),
input.size(-2), input.size(-1))
```

```
def forward(self, input tensor: torch.Tensor) -> torch.Tensor:
        batch, channel, height, width = input tensor.size()
            input tensor, self.kernel, groups=self.channels, padding=0, stride=1
        if self.padding == "same":
            out = output.view(batch, channel, height, width)
        else:
                batch, channel, height - self.height + 1, width - self.width + 1
                                                     *https://github.com/openvinotoolkit/anomalib
        return out
```

#### 实例二: GLASS

```
torch.onnx.errors.SymbolicValueError: Unsupported: ONNX export of operator
adaptive_avg_poolld, input size not accessible. Please feel free to request
support or submit a pull request on PyTorch GitHub:
https://github.com/pytorch/pytorch/issues [Caused by the value '770 defined in
(%770 : Float(*, *, *, strides=[1, 11943936, 1296], requires_grad=0,
device=cuda:0) = onnx::Reshape[allowzero=0](%features.3, %769), scope:
glass.GLASS::/common.Preprocessing::preprocessing/common.MeanMapper::preprocessi
ng_modules.1 # D:\yangquan\projects\GLASS\common.py:36:0
```

```
∨ glass.py 📮 💠
                                                                                                            +2 -2
                 features = features.reshape(
                                                                                 features = features.reshape(
162
                                                               162
                     features.shape[0], patch dims[0],
                                                                                     features.shape[0], patch dims[0],
163
                                                               163
       patch_dims[1], *_features.shape[2:]
                                                                      patch dims[1], * features.shape[2:]
164
                                                               164
                  features = features.permute(0, -3, -2,
                                                                                 features = features.permute(0, 3, 4, 5,
165
                                                               165 +
       -1, 1, 2)
                                                                      1, 2)
```

### TorchDynamo-based



#### youngquan commented yesterday

Contributor



#### Describe the bug

#### 1. Spaces in the Windows path:

I'm using Python installed in C:\Program Files\Python310. When running the compilation command, it fails because the path Program Files contains a space. The cl.exe compiler splits the path into two separate arguments, causing the build to fail.

#### 2. Virtual environment missing required library path:

I created a virtual environment using python -m venv venv. However, the build command doesn't include the necessary path to python310.lib, located in C:\Program Files\Python310\libs. This results in a failure to link against Python during the compilation process.



youngquan commented yesterday • edited •

Contributor

Fix the issue with torch.compile on Windows due to spaces in the path and virtual environment setup.

- 1. Wrap include paths in double quotes:
  - To handle paths with spaces, enclose the header file paths in double quotes. This ensures the compiler treats the entire path as a single argument.
- 2. Adapt library linkage to the virtual environment type:

Dynamically determine the correct library path based on the type of virtual environment being used, ensuring the linker can find and use the necessary libraries like python310.lib.

Fixes #141026

# 技术无关

- 配置环境好烦人…… ②
- 模型应用好麻烦…… ❸

- 给我一个可运行该算法的环境…… ☺️
- 帮我生成一个API接口...... 😂
- 把模型转成ONNX并提供运行代码...... ☺️

生成式AI时代



- 新的框架
- 新的语言
- 新的平台
- ......

谢谢!

