



The University of Texas at Austin  
Oden Institute for Computational  
Engineering and Sciences

**MARCH 2024**

# **PyDMD - DYNAMIC MODE DECOMPOSITION IN PYTHON**

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**MARCO TEZZELE**

Postdoctoral fellow, The University of Texas at Austin

# Main contributors and maintainers

Nicola Demo



Marco Tezzele



Francesco Andreuzzi



Sara Ichinaga



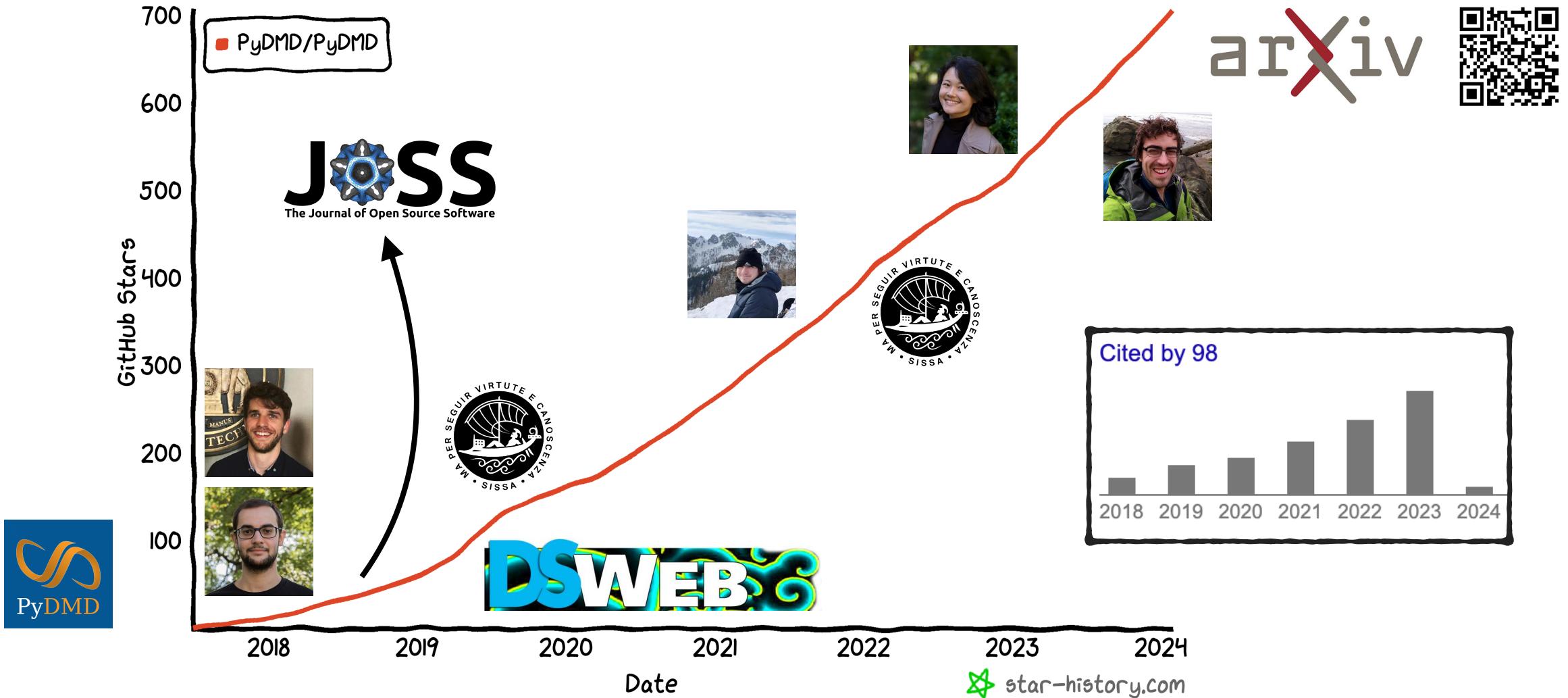
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# Historical perspective

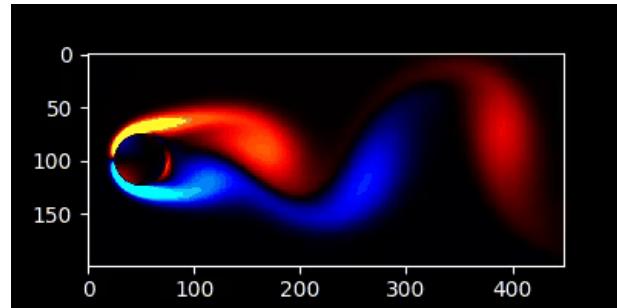


NUMFOCUS  
OPEN CODE = BETTER SCIENCE



# Dynamic mode decomposition at a glance

Collect data



Schmid, JFM 2010.

Rowley, Mezic, et al., JFM 2009.

Tu, Rowley, et al., JCD 2014.

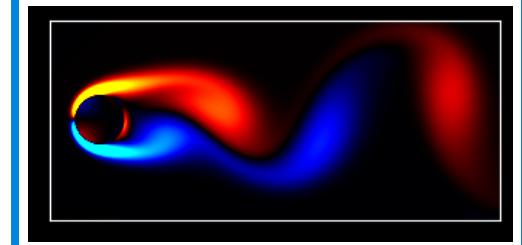
Kutz, Brunton, et al., SIAM 2016.

Build data matrices

$$X = \begin{bmatrix} | & | & & | \\ x_1 & x_2 & \dots & x_{m-1} \\ | & | & & | \end{bmatrix}$$

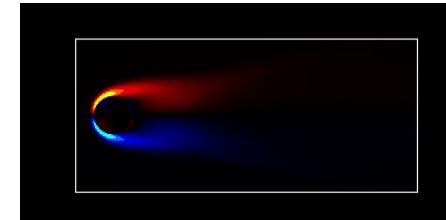
$$X' = \begin{bmatrix} | & | & & | \\ x_2 & x_3 & \dots & x_m \\ | & | & & | \end{bmatrix}$$

$$t = t_2$$

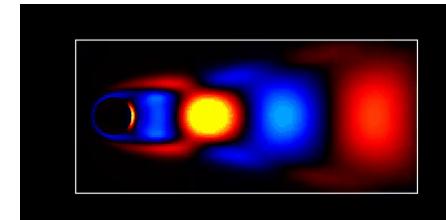


$$\begin{aligned} A &= X' X^\dagger \\ A\Phi &= \Phi\Lambda \end{aligned}$$

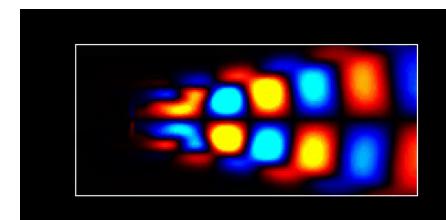
Obtain diagnostics



$$\begin{aligned} f_1 &= 0 \\ (\lambda_1, \varphi_1) \end{aligned}$$



$$\begin{aligned} f_2 &= 0.208 \\ (\lambda_2, \varphi_2) \end{aligned}$$



$$\begin{aligned} f_4 &= 0.416 \\ (\lambda_4, \varphi_4) \end{aligned}$$

$$x_{k+1} = \sum_{j=1}^r \varphi_j \lambda_j^k b_j = \Phi \Lambda^k b$$

# DMD algorithm

## 1. Collection of the snapshots

- Creation of two matrices: snapshots ( $\mathbf{X}$ ) and time-shifted snapshots ( $\mathbf{Y}$ )

## 2. Eigenvalues and modes computation

- Approximation of the operator  $\mathbf{A}$
- SVD of the snapshots matrix
- Reduction of the operator
- Eigendecomposition
- Computation of the modes

$$\mathbf{Y} \approx \mathbf{AX}$$

$$\mathbf{X} = \mathbf{U}\Sigma\mathbf{V}^*$$

$$\tilde{\mathbf{A}} = \mathbf{U}^*\mathbf{Y}\mathbf{V}\Sigma^{-1}$$

$$\tilde{\mathbf{A}}\mathbf{W} = \mathbf{W}\Lambda$$

$$\Phi = \mathbf{Y}\mathbf{V}\Sigma^{-1}\mathbf{W} \quad \Phi = \mathbf{U}\mathbf{W}$$

## 3. Reconstruction and future state predictions

- Computation of the amplitudes  $\mathbf{b}$
- Forecasting

$$\mathbf{b} = \Phi^\dagger \mathbf{x}_0$$

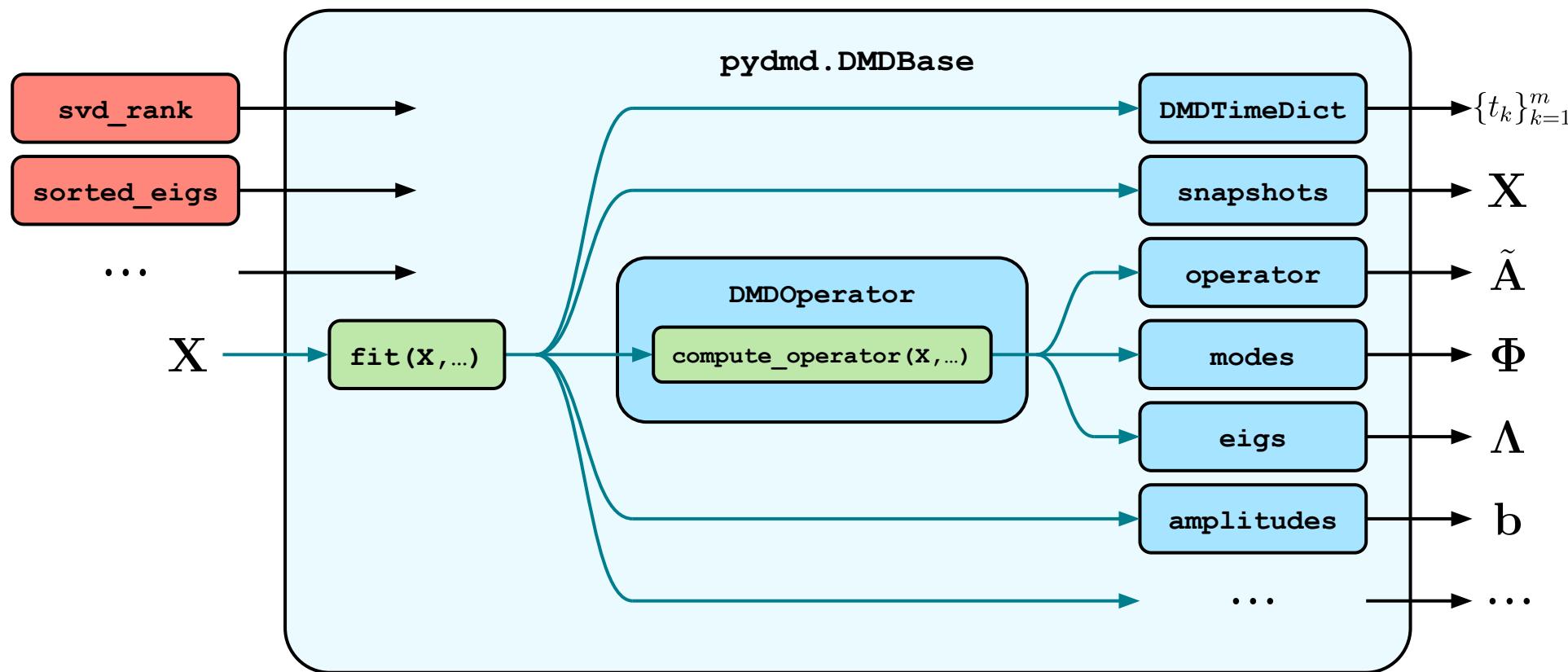
$$\mathbf{x}_k = \Phi \Lambda^k \mathbf{b}$$

# DMDBase class

## DMDBase

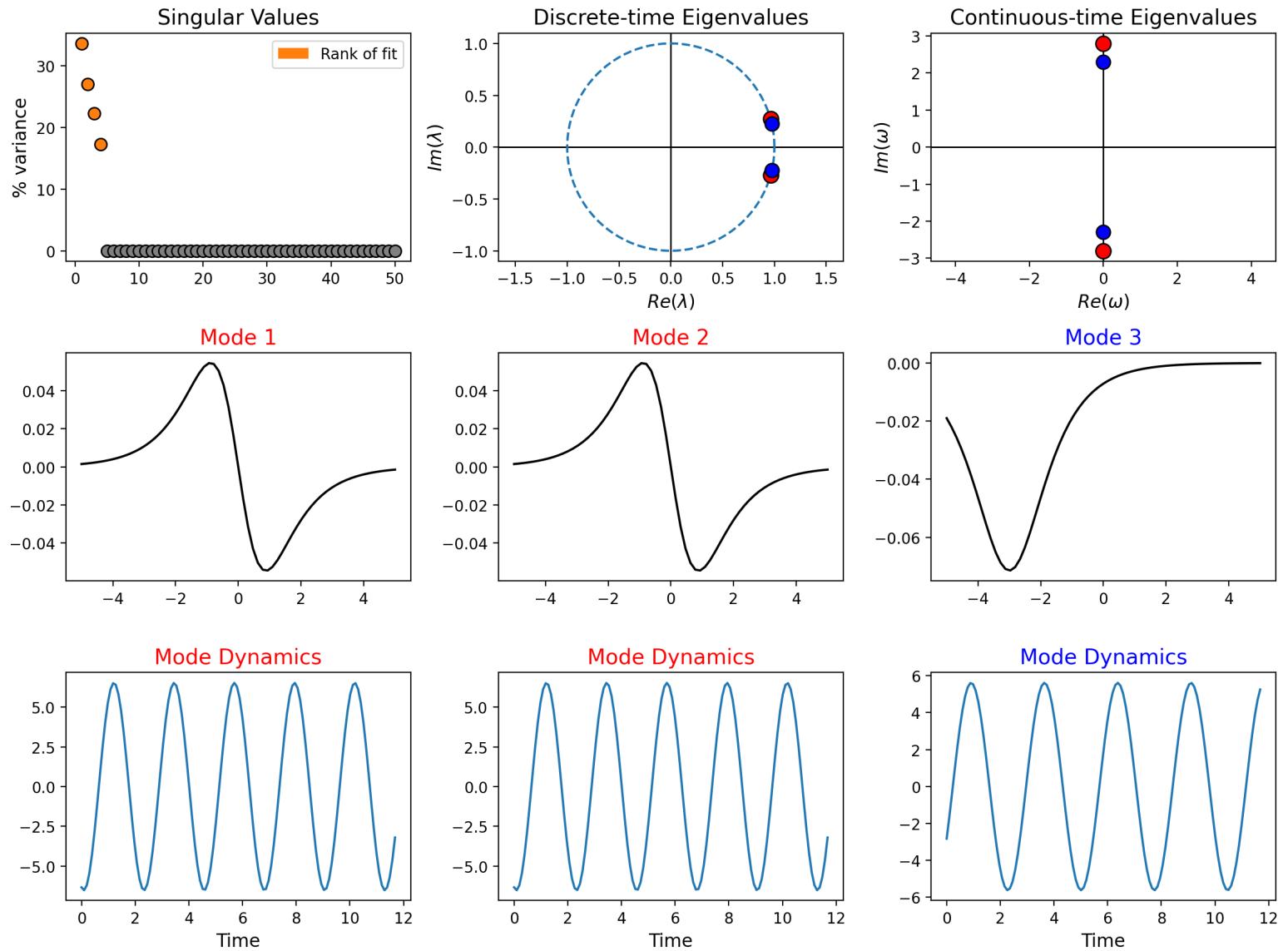
Base module for the DMD: `fit` method must be implemented in inherited classes

```
class DMDBase(svd_rank=0, tlsq_rank=0, exact=False, opt=False, rescale_mode=None,  
forward_backward=False, sorted_eigs=False, tikhonov_regularization=None) [source]
```

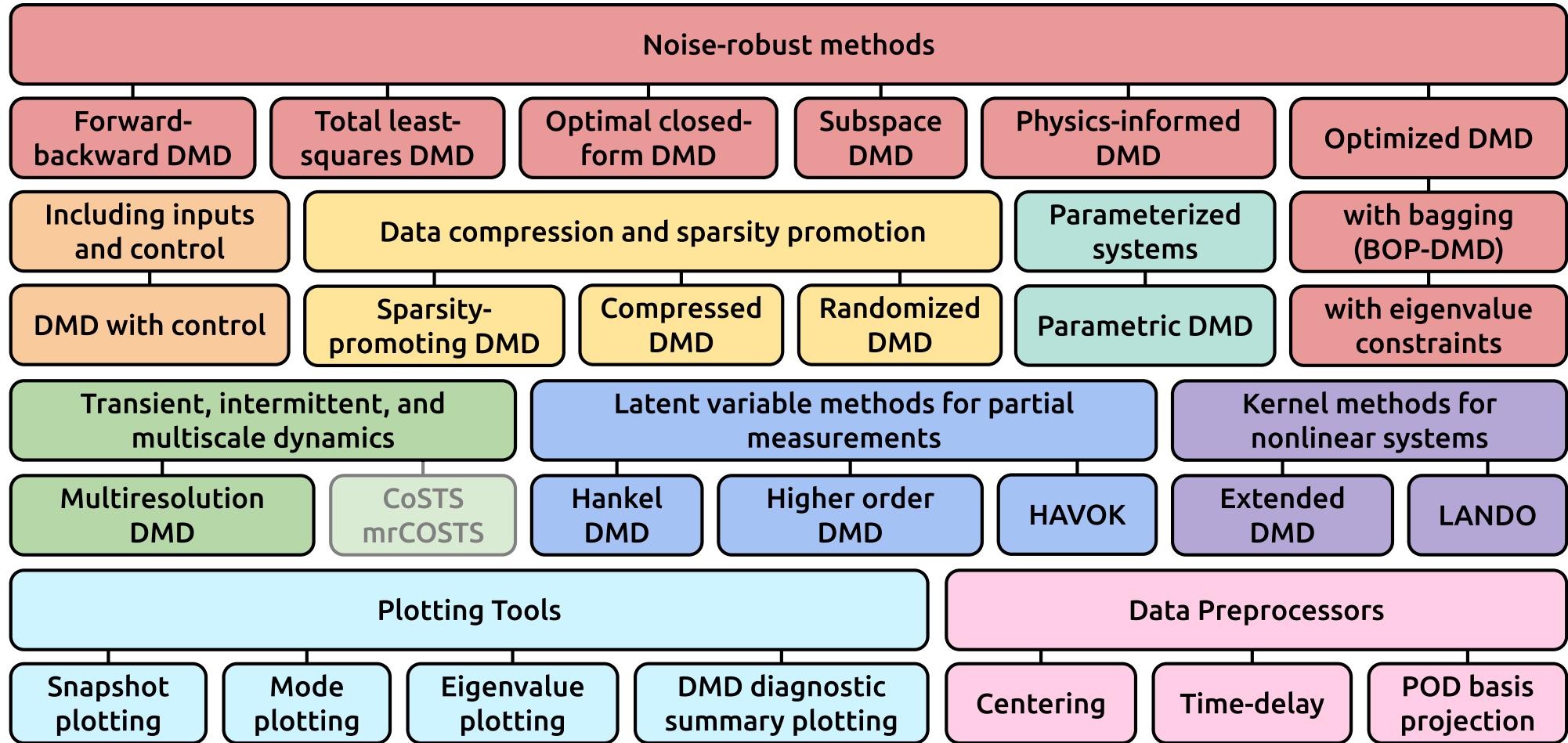


# Plotting capabilities for diagnostics and data exploration

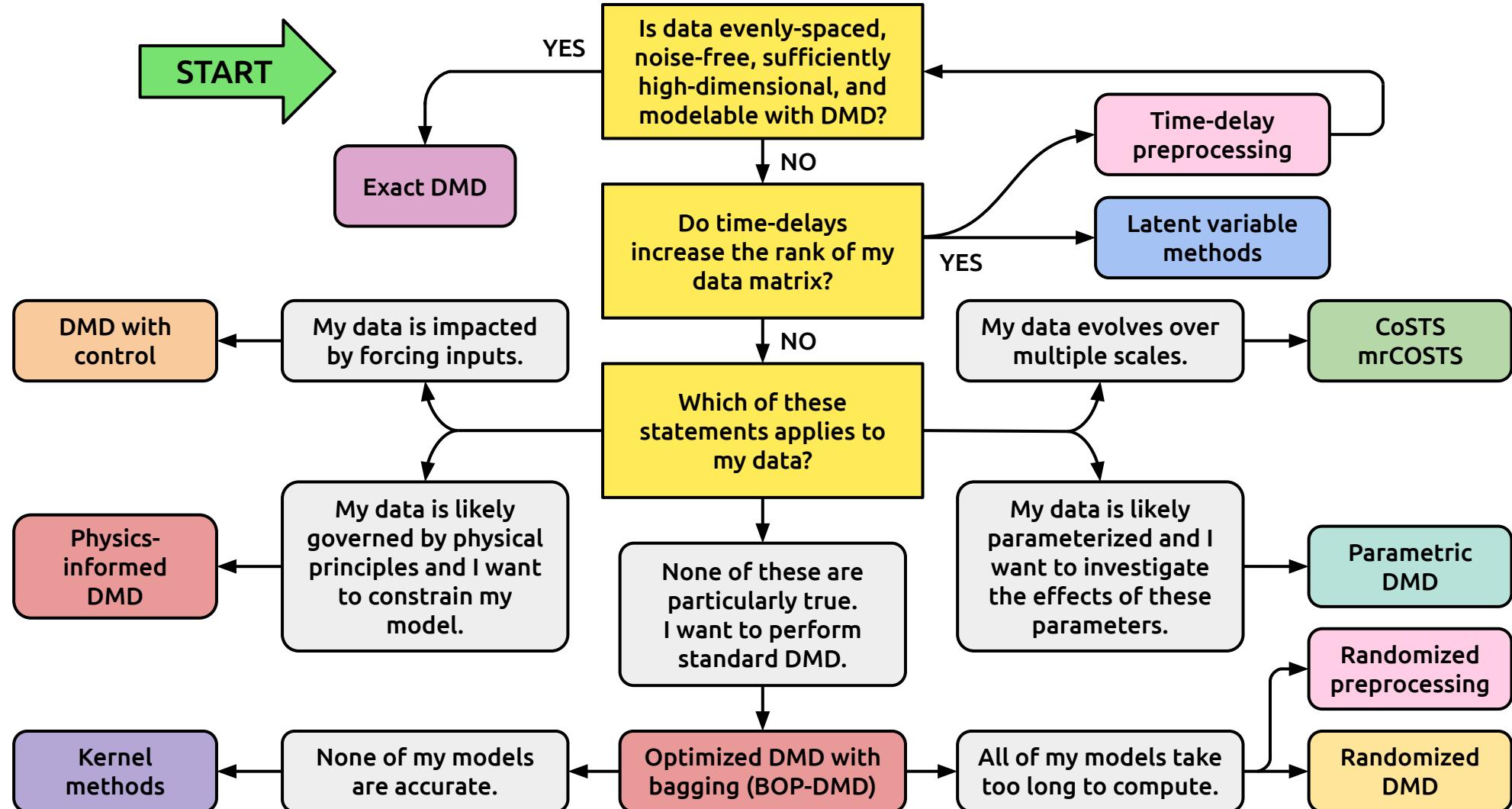
```
def plot_summary(  
    dmd,  
    *,  
    X=None,  
    y=None,  
    t=None,  
    d=1,  
    continuous=False,  
    snapshots_shape=None,  
    index_modes=(0, 1, 2),  
    filename=None,
```



# Current capabilities

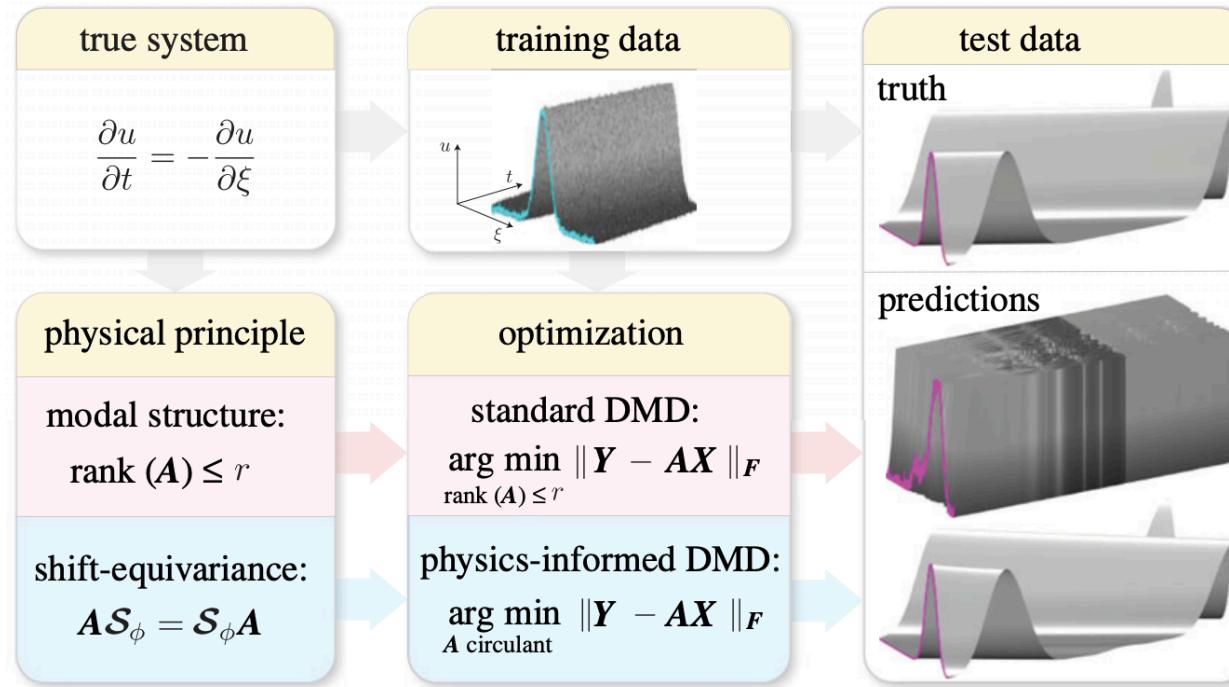


# Which method should you use?

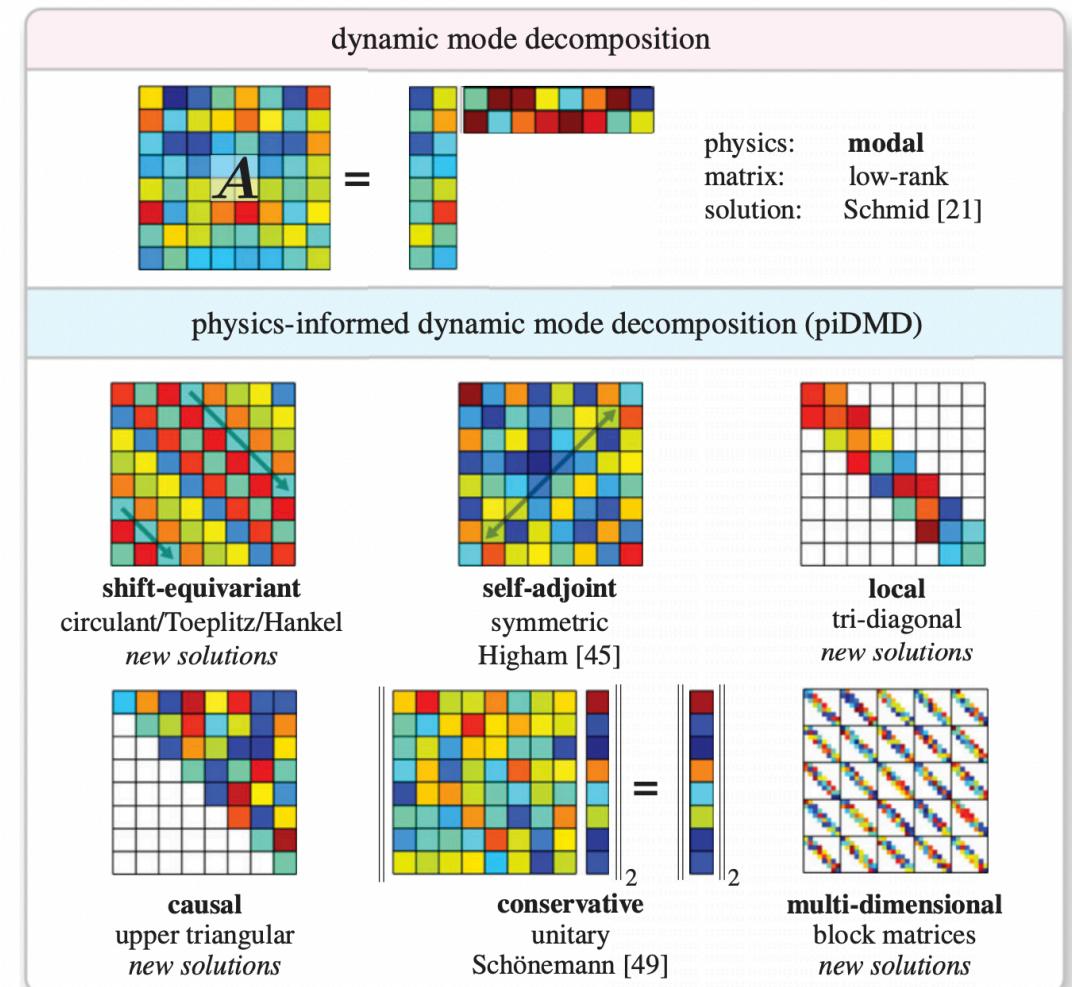


# Physics-informed DMD

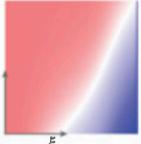
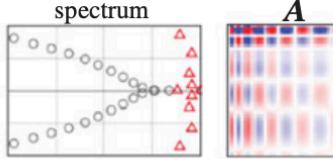
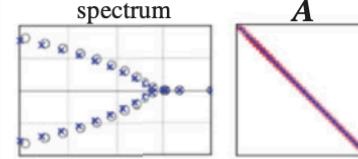
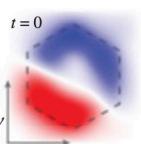
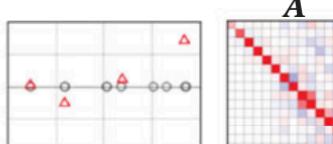
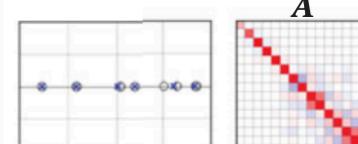
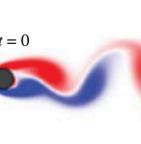
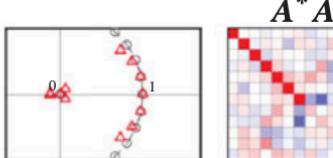
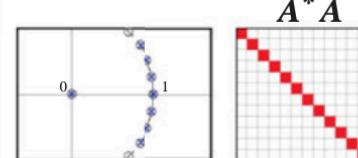
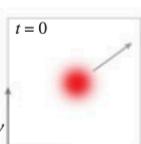
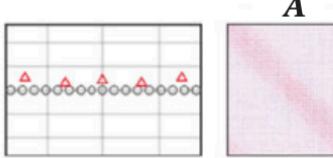
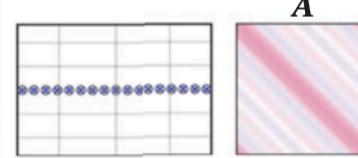
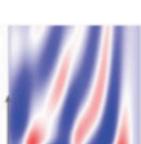
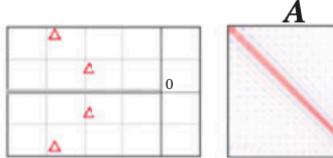
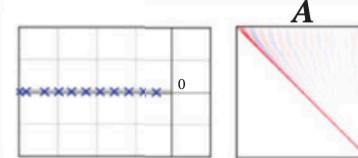
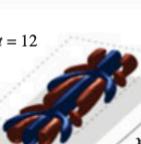
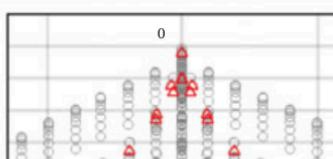
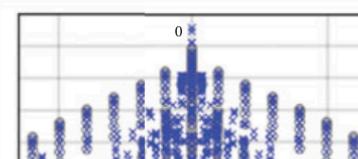
```
class PiDMD(manifold, manifold_opt=None, compute_A=False, svd_rank=-1, tlsq_rank=0, opt=False)
```



Baddoo et al., Proc. R. Soc. A, 2023



# Different system models result in different matrix structures you can impose

system	physics (matrix structure)	data	standard DMD	physics-informed DMD
advection-diffusion $\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial \xi^2} - v(\xi) \frac{\partial u}{\partial \xi}$	local (tri-diagonal)			
Schrödinger equation $i\hbar \frac{d}{dt}  \psi(t)\rangle = \hat{H}  \psi(t)\rangle$	self-adjoint (Hermitian)			
cylinder flow $\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = \frac{1}{Re} \nabla^2 \mathbf{u} - \nabla p$	conservative (unitary)			
two-dimensional advection $\frac{\partial \mathbf{u}}{\partial t} = -\mathbf{c} \cdot \nabla \mathbf{u}$	shift-equivariant (block circulant)			
Volterra integro-differential equation $\frac{\partial u}{\partial t} = \int_{-1}^{\xi} K(\xi, v) u(v, t) dv$	causal (upper triangular)			
channel flow $\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = \frac{1}{Re} \nabla^2 \mathbf{u} - \nabla p$	shift-equivariant (block circulant)			

# Code documentation

- [DMDBase](#)
- [DMD Operator](#)
- [DMD](#)
- [BOPDMD: Optimized DMD and Bagging, Optimized DMD](#)
- [Compressed DMD](#)
- [DMD Modes Tuner](#)
- [DMD with control](#)
- [Kernelized extended DMD](#)
- [Forward-backward DMD](#)
- [Hankel DMD](#)
- [Havok](#)
- [Higher-order DMD](#)
- [Multi-resolution DMD](#)

About



Python Dynamic Mode Decomposition

↗ [pydmd.github.io/PyDMD/](https://pydmd.github.io/PyDMD/)

- [OptDMD](#)
- [Parametric DMD](#)
- [Plotter](#)
- [Physics-informed DMD](#)
- [Randomized DMD](#)
- [Sparsity-promoting DMD](#)
- [Subspace DMD](#)
- [VarProDMD: Variable Projection for DMD](#)
- [Utilities](#)

# Tutorials



## Tutorials for the users (almost 20)

Name	Description	PyDMD used classes
Tutorial1 [ <a href="#">.ipynb</a> , <a href="#">.py</a> , <a href="#">.html</a> ]	Analyzing real, simple data sets with PyDMD	<code>pydmd.DMD</code> , <code>pydmd.BOPDMD</code>
Tutorial2 [ <a href="#">.ipynb</a> , <a href="#">.py</a> , <a href="#">.html</a> ]	advanced features of standard DMD	<code>pydmd.DMD</code>
Tutorial3 [ <a href="#">.ipynb</a> , <a href="#">.py</a> , <a href="#">.html</a> ]	multi-resolution DMD for transient phenomena	<code>pydmd.MrDMD</code>
Tutorial4 [ <a href="#">.ipynb</a> , <a href="#">.py</a> , <a href="#">.html</a> ]	compress DMD for computation speedup	<code>pydmd.CDMD</code>

...

## Tutorial for the developers

Name	Description	PyDMD used classes
Tutorial1 [ <a href="#">.ipynb</a> , <a href="#">.py</a> , <a href="#">.html</a> ]	implementing a new version of DMD	<code>pydmd.DMDBase</code>