

The Joy of *Finally* Learning

www.mldawn.com

#### OUTLINE OF THE TALK

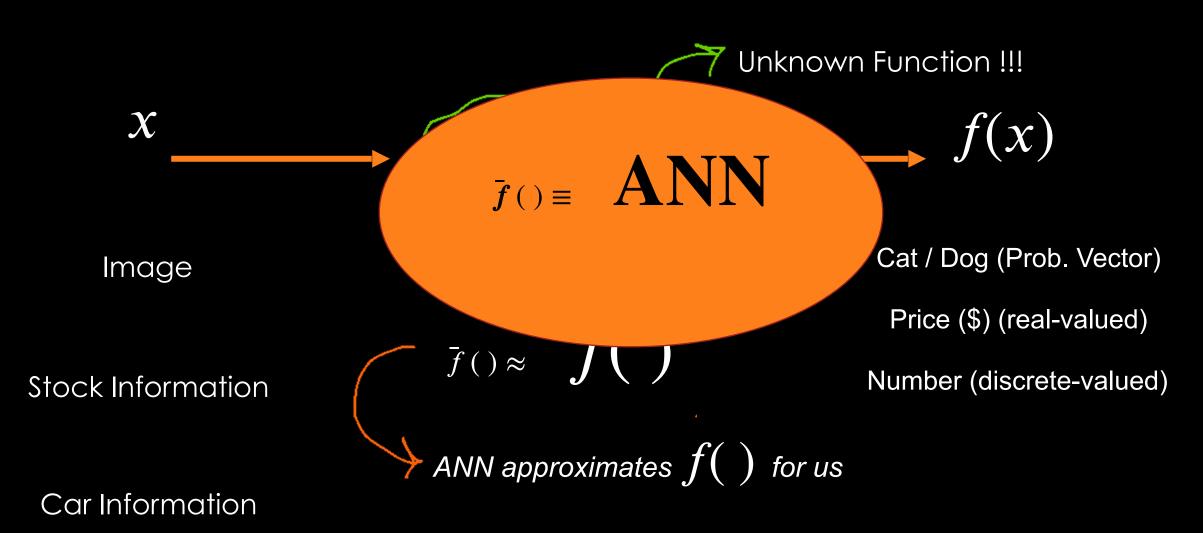
- What is an Artificial Neural Network (ANN)?
- What is a Perceptron?
- Bayes' Rule and Birth of Error Functions (with Derivations)
- The Birth of Binary-Cross Entropy Function (with Derivations)
- Forward Pass and Backward Pass in a Binary Classifier
- A Demo

#### WHAT IS A NEURAL NETWORK?

- An ANN is a function approximator!
  - What is a function?
  - Examples of functions: real-valued, discrete-valued, and vector-valued

- Applications of ANNs:
  - Recognizing hand-written characters
  - Recognizing spoken words
  - Recognizing faces

### WHAT IS A NEURAL NETWORK?



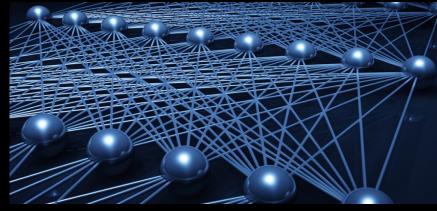
# ANN BIOLOGICAL MOTIVATION

- ANNs are inspired by Biological Learning Systems (BLS)
  - BLS: A massive interconnection of neurons



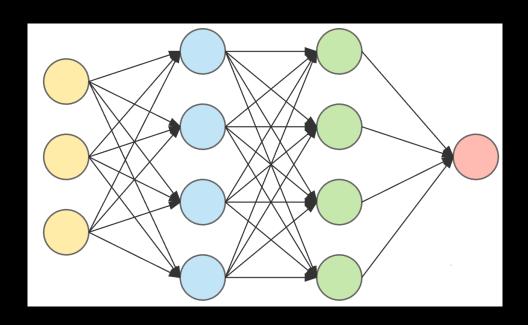
• Densely interconnected set of simple unites





### ANN BIOLOGICAL MOTIVATION

- For each unit in ANN:
  - **Possibly** several inputs
  - A Single real-valued output
- BLS processes are highly parallelized
  - Over nearly  $10^{11}$  neurons
- ANNs do NOT fully reflect a BLS
  - Output of neurons are different
- Researchers try to:
  - 1. Model BLS processes
  - 2. Develop effective ANNs (no regards to BLS compatibility)



# SIMPLESTANN

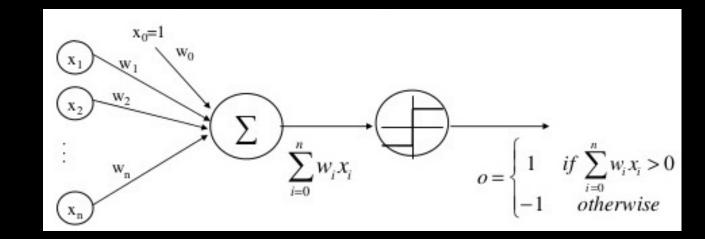
# APERCEPTRON

#### A type of ANN that is based on a unit called <u>perceptron</u>

- There is a rule about input/output of a perceptron:
  - Input: A vector of real-valued data
  - Linearly combine the components of the input

$$o(x_1, ..., x_n) = \begin{cases} if w_0 + w_1 x_1 + w_2 x_2 + ... + w_n x_n > 0 \\ -0 therwise \\ -1 \end{cases}$$

#### A PERCEPTRON



- What are the weights? What is that  $w_0$ ?
- Let's imagine an additional input

• 
$$x_0 = 1$$

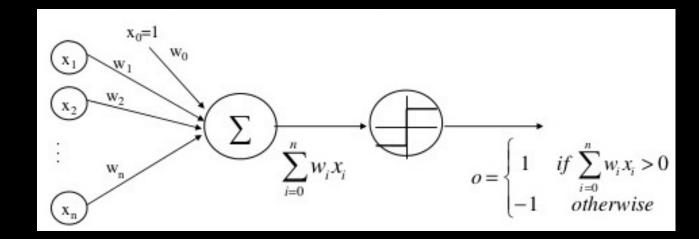
• This simplifies the inequality:

$$\sum_{i=0}^{n} w_i x_i > 0$$

- Or in vector form:  $\vec{w} \cdot \vec{x} > 0$
- Can we show the perceptron smarter?

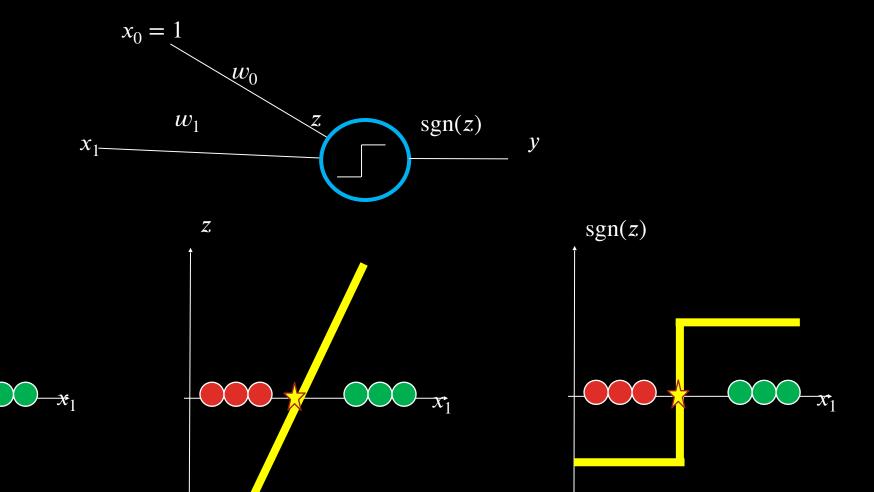
• 
$$o(\vec{x}) = \operatorname{sgn}(\vec{w} \cdot \vec{x})$$
  
• Where:  $\operatorname{sgn}(z) = \begin{cases} +1 & \text{if } z > 0 \\ -1 & \text{otherwise} \end{cases}$ 

#### A PERCEPTRON

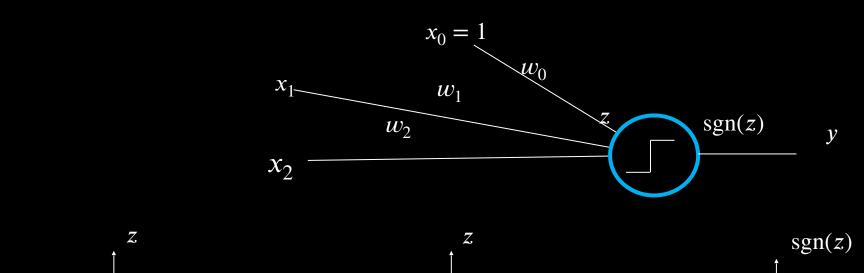


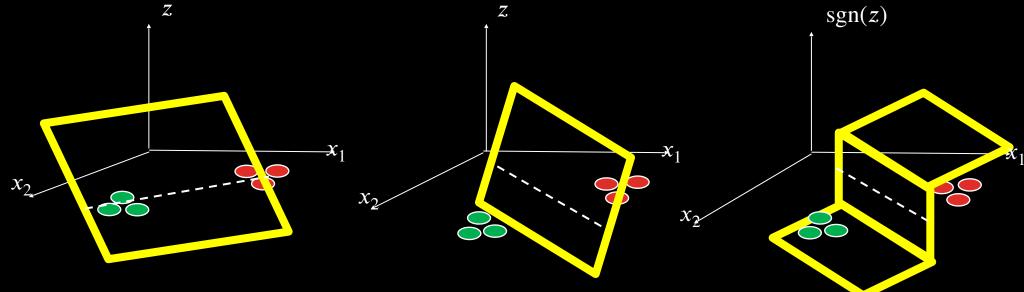
- Learning a perceptron = Choosing the weights
- The hypothesis space:  $H = \left\{ \vec{w} \mid \vec{w} \in R^{(n+1)} \right\}$

# A PERCEPTRON: A DEEPER LOOK



# A PERCEPTRON: A DEEPER LOOK





# THE BIRTH OF ERROR FUNCTIONS

DO I TRUST MY ANN?

# BAYES' RULE

- Let's assume the following notation:
  - M : Our Model
  - D: Our Evidence
- Then the Bayes' Rule:

$$P(M \mid D) = \frac{P(D \mid M)P(M)}{P(D)}$$

# TAKING THE LOGS(): A SIMPLIFICATION

 $\overline{lnP(M \mid D)} = \overline{lnP(D \mid M)} + \overline{lnP(M)} - \overline{lnP(D)}$ 

$$P(M \mid D) = \frac{P(D \mid M)P(M)}{P(D)} \xrightarrow{\log\left(\frac{a}{b}\right) = \log(a) - \log(b)} \ln P(M \mid D) = \ln\left[P(D \mid M)P(M)\right] - \ln P(D)$$

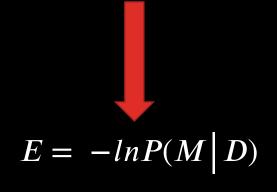
$$\log(a \times b) = \log(a) + \log(b)$$

# THE BAYESIAN MACHINERY (MAPE)

$$lnP(M \mid D) = ln P(D \mid M) + ln P(M) - lnP(D)$$

 $Maximize P(M \mid D) \equiv Minimize - P(M \mid D)$ 

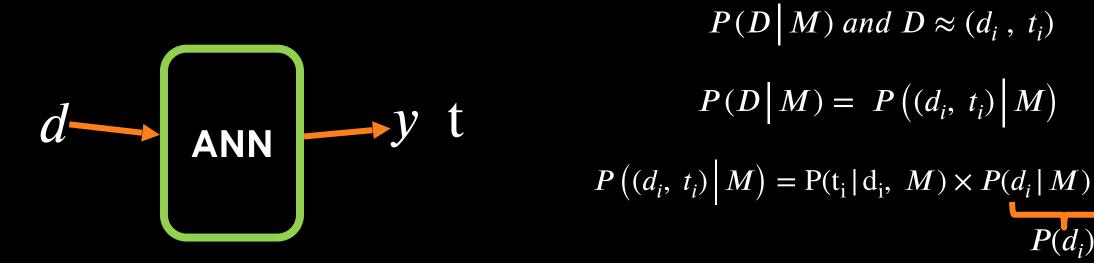
$$-lnP(M \mid D) = -ln P(D \mid M) - ln P(M) + lnP(D)$$



This is how Bayes' Rule connects to Error Functions

# MAPE AND ANNS: SUPERVISED LEARNING

- How can we apply the MAPE to an ANN with weights w?
- Let's assume that we have a set of examples (d<sub>i</sub>,t<sub>i</sub>) where d<sub>i</sub> is the i-th input and t<sub>i</sub>
  the corresponding target.
- Then we can rewrite the likelihood as:



# MAPE AND ANNS: SUPERVISED LEARNING

$$-lnP(M \mid D) = -ln P(D \mid M) - ln P(M) + lnP(D)$$

Model indeed means our weights W

$$-lnP(W|D) = -ln P(D|W) - ln P(W) + lnP(D)$$

$$P(t_i | d_i, W) \times P(d_i)$$

P(D) and  $P(d_i)$  are both independent of our weights W. Ignore them during Maximization

$$-lnP(W|D) = -\ln \prod_{i=1}^{N} \left[ P(t_i|d_i, W) \times P(d_i) \right] - \ln P(W) + \ln P(D)$$

$$-lnP(W|D) = -\sum_{i=1}^{N} \ln \left[ P(t_i|d_i, W) \times P(d_i) \right] - \ln P(W) + \ln P(D)$$

$$-lnP(W|D) = -\sum_{i=1}^{N} \ln \left[ P(t_i|d_i, W) \right] - \sum_{i=1}^{N} \ln P(d_i) - \ln P(W) + \ln P(D)$$

# MAPE AND ANNS : SUPERVISED LEARNING

$$-lnP(W|D) = -\sum_{i=1}^{N} \ln \left[ P(t_i | d_i, W) \right] - \ln P(\tilde{W}) \quad \text{Can be used for regularizing } W$$

$$to avoid overfitting$$

$$P(W) = \frac{1}{\sqrt{2\pi}\sigma} e^{\frac{-(w-\mu)^2}{2\sigma^2}} \quad \ln()$$

$$\approx -(w_1^2 + w_1^2 + \dots + w_N^2)$$

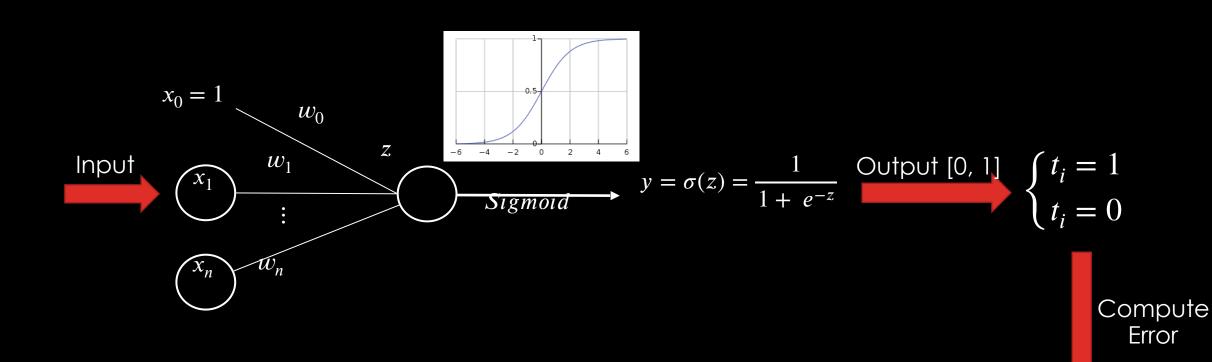
$$E = -\ln P(W|D) = -\sum_{i=1}^{N} \ln \left[ P(t_i | d_i, W) \right]$$

# BINARY CROSS-ENTROPY ERROR FUNCTION

THE DERIVATION

- We have 2 classes: Positive and Negative
- Binary Classification:
  - $t_i = 1$  means that  $x_i$  belongs to the **positive** class
  - $t_i = 0$  means that  $x_i$  belongs to the <u>negative</u> class
- Artificial Neural Networks (ANNs): Probabilistic approach
  - ANN computes the probability of the Positive Class:  $P(y_i=1 \mid x_i)$
  - Could a linear model work? Say,  $y = w^T x + b \rightarrow$  Not Bounded!

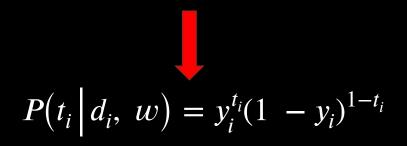
#### We need a Squasher!



Back-Propagation

- The output of our ANN is probability. Let's denote:
  - $y_i$ : Probability  $x_i$  belongs to the Positive class (i.e.,  $t_i = 1$ )
  - $(1 y_i)$ : Probability  $x_i$  belongs to the Negative class (i.e.,  $t_i = 0$ )

$$P(t_i | d_i, w) = \begin{cases} y_i & \text{if } t_i = 1\\ 1 - y_i & \text{if } t_i = 0 \end{cases}$$



Bernoulli Distribution

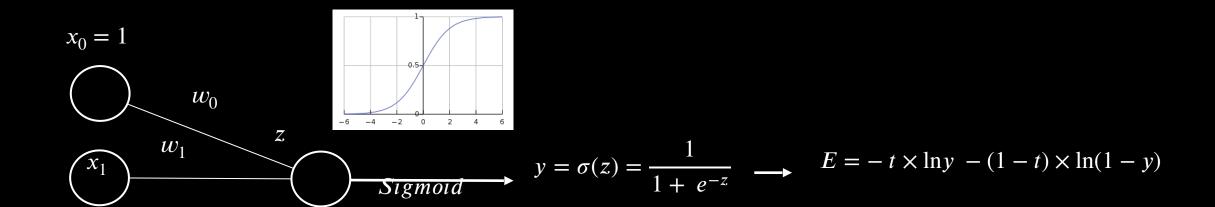
$$P(t_i | d_i, w) = y_i^{t_i} (1 - y_i)^{1-t_i}$$

$$E = -\sum_{i=1}^{N} \ln \left[ P(t_i | d_i, W) \right] = -\sum_{i=1}^{N} \ln \left[ y_i^{t_i} (1 - y_i)^{1 - t_i} \right]$$

$$= -\sum_{i=1}^{N} \left[ \ln y_i^{t_i} + \ln \left( 1 - y_i \right) \right]$$

$$E = -\sum_{i=1}^{N} [t_i \ln y_i + (1 - t_i) \ln(1 - y_i)]$$

### FORWARD PASS



$$Error = E(\sigma(Z)) = E(\sigma(w_1x_1 + w_0))$$

Binary Cross-Entropy Error 
Function

#### BACKWARD PASS

 $\frac{\partial E}{\partial w_1} = \frac{\partial E}{\partial y} \times \frac{\partial y}{\partial Z} \times \frac{\partial Z}{\partial w_1} = \left[ \frac{-t}{y} + \frac{(1-t)}{(1-y)} \right] \times y(1-y) \times x_1 = (y-t) \times x_1$ 

$$\frac{\partial E}{\partial w_1} = \frac{\partial E}{\partial y} \times \frac{\partial y}{\partial Z} \times \frac{\partial Z}{\partial w_0} = \left[ \frac{-t}{y} + \frac{(1-t)}{(1-y)} \right] \times y(1-y) \times x_0 = (y-t)$$

• So the learning rule for both our learnable parameters (i.e., weights) is as follows:

$$w_1 = w_1 - \eta \times \frac{\partial E}{\partial w_1} = w_1 - \eta \times [(y - t) \times x_1]$$
  
$$w_0 = w_0 - \eta \times \frac{\partial E}{\partial w_0} = w_0 - \eta \times (y - t)$$



The Joy of Finally Learning





@MLDawn2018



Mehran Bazargani



ML Dawn

Course Available at: <a href="https://www.mldawn.com/course/the-birth-of-error-functions/">https://www.mldawn.com/course/the-birth-of-error-functions/</a>

<u>Demo's Code: https://www.mldawn.com/binary-classification-from-scratch-using-numpy/</u>