Non-Constant Acceleration

Kaylin Shanahan 2023

This is a Python notebook to estimate the velocity and displacement of a car over a period of 10 seconds. This will be done using Euler's technique, and display the results on graphs of the numerical and exact analytical solutions, and also print the value of displacement.

The car begins its acceleration from rest, but this acceleration is not constant. The acceleration of this car can be described by the following formula:

$$rac{d^2x}{dt^2} = a_{max}(1-e^{-rac{t}{ au}})$$

Where $a_{max}=4.0ms^{-2}$ and au=5.0s

The Euler programme in this case will be used to describe the situation with a car where the acceleration changes. X will be used to measure position (displacement), in relation to t, time.

By integrating the expression for acceleration once, we get an equation for velocity (v):

$$\frac{dx}{dt} = xa_{max}(1 - e^{-\frac{t}{\tau}})$$

Integrating this again, gives an expression for displacement (x):

$$x(t) = \frac{1}{2}x^2 a_{max}(1 - e^{-\frac{t}{\tau}})$$

Using these expressions, it is possible to find analytical solutions for velocity and displacement.

• Input the initial conditions

- Determine the number of steps required
- Initialise x and t values
- Calculate the velocity and displacement using the differential equation above, both numerically and analytically
- Output the x and t values
- Output a plot of the numerical and analytical solutions on a graph

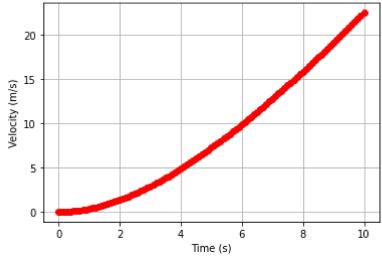
```
In [91]: # Solve for velocity and displacement of car with non-constant acceleration using Euler's technique
        # The 2nd order ODE is: d^2x/dt^2 = a \max(1 - np.exp(-t/tau))
        # Numpy is needed for the natuaral log and exponential function
        import numpy as np
        # Matplotlib is needed to plot graphs
        import matplotlib.pyplot as plt
        # Initial conditions
        # Time values required for programme
        N = int(t max/delta t) # Calculate the number of time jumps in minutes
        #Set up NumPy arrays to hold the displacemtent x, velocity v and time t values
        # We need one element more in each array, than the number of jumps
        x = np.zeros(N + 1)
        v = np.zeros(N + 1)
        t = np.zeros(N + 1)
        # Initialise the zeroth values
       x[0] = 0 # Initial displacement v[0] = 0 # Initial velocity
                       # Initial time
        t[0] = 0
```

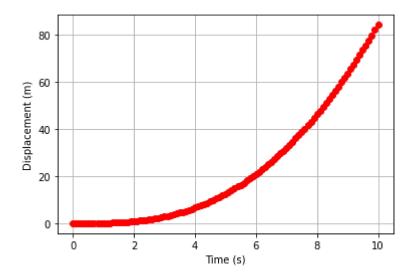
```
In [92]: # Use a for loop to step along the t-axis
for i in range(N):
    a = a_max * (1 - np.exp(-(t[i]/tau))) # Use the ODE to calculate the acceleration
    v[i+1] = v[i] + a * delta_t # Estimate v at the end of the interval
    x[i+1] = x[i] + v[i] * delta_t # Estimate x at the end of the interval
    t[i+1] = t[i] + delta_t # Calculate t at the end of the interval
```

```
In [93]: print("Displacement after 10 seconds = {0:8.2f} m".format(x[N]))
    print("Velocity after {0} seconds from Euler = {1:8.2f} m s^-1".format(t_max, v[N]))

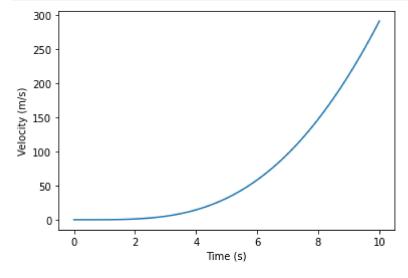
Displacement after 10 seconds = 84.20 m
    Velocity after 10 seconds from Euler = 22.53 m s^-1

In [94]: # Numerical solution for velocity
    # Plot the numerical solution as points
    plt.plot(t, v, "ro")
    plt.xlabel("Time (s)")
    plt.ylabel("Velocity (m/s)")
    plt.grid()
```





```
In [96]: # Analytical solution for velocity
# Plot the analytical solution as a line
# Use the same (N+1) t values
v_analytic = x * a_max * (1 - np.exp(- (t / tau)))
plt.xlabel("Time (s)")
plt.ylabel("Velocity (m/s)")
plt.plot(t, v_analytic)
plt.show()
```



In [98]: # Analytical solution for displacement
Plot the analytical solution as a line

```
# Use the same (N+1) t values
x_analytic = ((x/2)**2) * a_max * (1 - np.exp(- (t / tau)))
plt.xlabel("Time (s)")
plt.ylabel("Displacement (m)")
plt.plot(t, x_analytic)
plt.show()
```

