

# Solving (geophysical) inverse problems on GPUs with PyL $\begin{bmatrix} -1 & 1 \\ -1 & 1 \\ -1 & 1 \end{bmatrix}$ ps + CuPy

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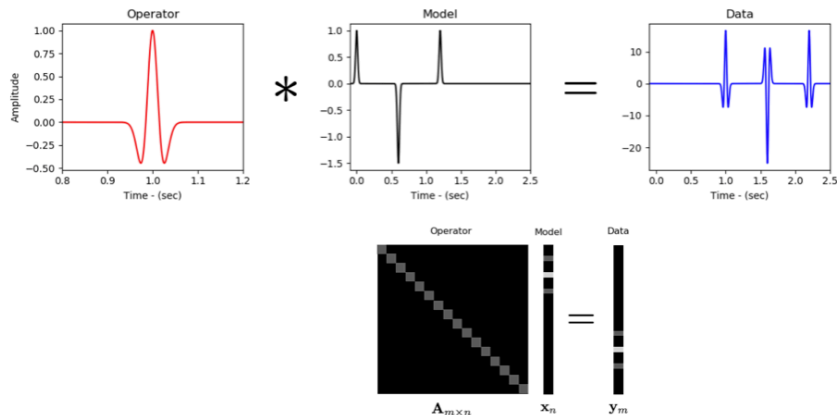


software  
underground presents

**Subsurface  
Rendezvous**

# Inverse Problems

$$y = Gx$$



## Numpy/scipy

```
# Model
x = np.*(nt)

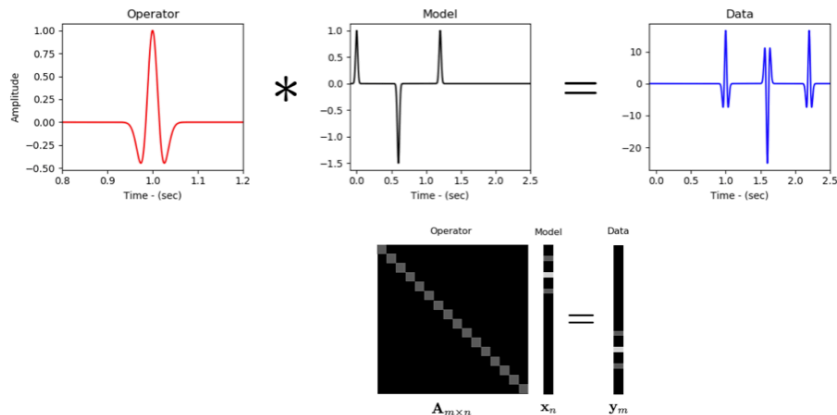
# Operator
G = convmtx(g, nt)

# Data
y = np.dot(G, x)

# Inverse
xinv = sp.sparse.linalg.*(G, y)
```

# Inverse Problems

$$y = Gx$$



## PyLops CPU

```
# Model
x = np.*(nt)

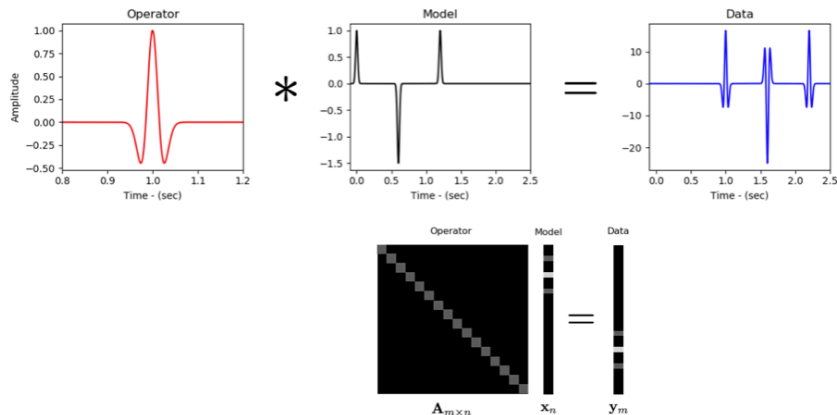
# Operator
G = Convolve1D(nt, g)

# Data
y = G * x

# Inverse
xinv = sp.sparse.linalg.*(G, x)
```

# Inverse Problems

$$y = Gx$$



## PyLops GPU

```
# Model
x = cp.*(nt)

# Operator
G = Convolve1D(nt, cp.asarray(g))

# Data
y = G * x

# Inverse
xinv = pyllops.optimization.*(G, x)
```

# History

PyL $\begin{bmatrix} -1 & 1 \\ -1 & 1 \\ -1 & 1 \end{bmatrix}$ ps

**Dec 2018:** PyLops v1.0.0  
(open-sourced)

PyL $\begin{bmatrix} \text{GPU} \end{bmatrix}$ ps

**June 2019:** PyLops-GPU  
v0.0.0



**Nov 2020:** CurveLops

**Nov 2020:** PyLops v1.12.0  
with CuPY integration



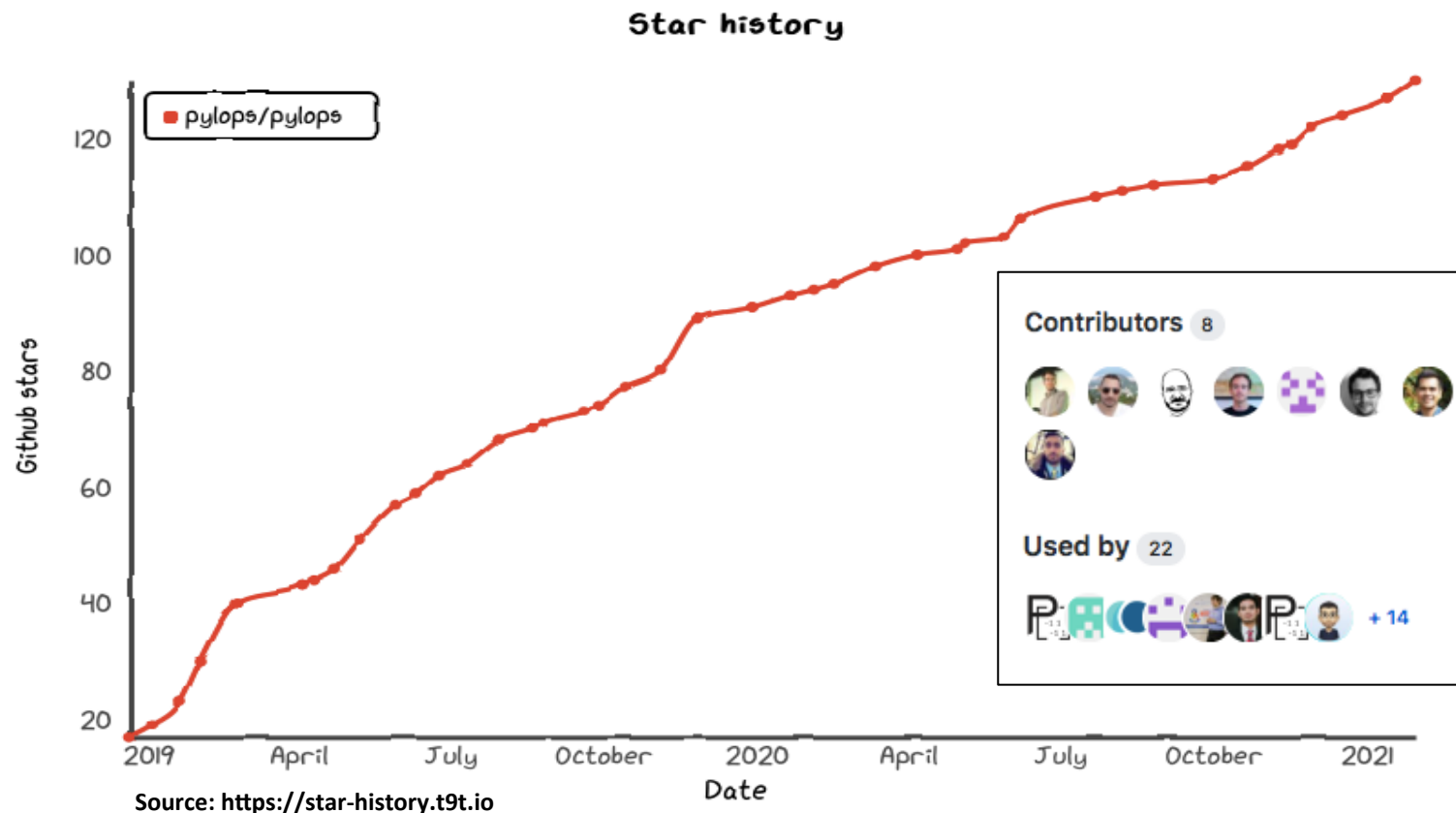
**April 2019:** PyLops v1.4.0  
on conda-forge

PyL $\begin{bmatrix} \text{distributed} \end{bmatrix}$ ps

**May 2019:** PyLops-  
Distributed v0.0.0

**Jan 2021:** PyProximal v0.0.0

# History



# Summary

*An entire ecosystem of tools to ease research in inverse problems*

-> +50 Operators (CPU + GPU)

-> Least-squares, L1 (sparsity), and Proximal solvers

-> Sparsity transforms (e.g., FFT, FFTN, DWT, Curvelet, Seislet)

-> Dask integration for distributed operators

-> PyTorch integration for Autograd (and GPU)

-> Visit: <https://github.com/PyLops>