

$$\hat{y}_{t+h} = y_T \quad y_1, \dots, y_T$$

$$\hat{y}_{t+h} = \frac{1}{T} \sum_{t=1}^T y_t$$

$$\alpha \in (0; 1)$$

$$\hat{y}_{T+1|T} = \alpha y_T + \alpha(1-\alpha)y_{T-1} + \alpha(1-\alpha)^2 y_{T-2} + \dots$$

$$\hat{y}_{T+1|T} = \alpha y_T + (1-\alpha)(\alpha y_{T-1} + \alpha(1-\alpha)y_{T-2} + \dots)$$

$$\hat{y}_{T+1|T} = \alpha y_T + (1-\alpha) \hat{y}_{T|T-1}$$

Weighted average form

$$\hat{y}_{2|1} = \alpha y_1 + (1-\alpha) \hat{y}_{1|0}$$

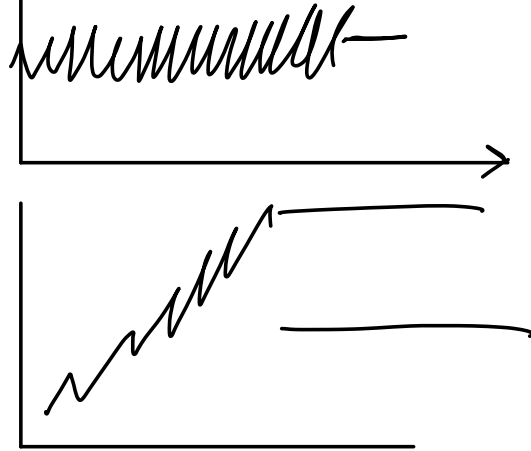
$$\hat{y}_{2|1} = \alpha y_1 + (1-\alpha) l_0$$

$$\hat{y}_{3|2} = \alpha y_2 + (1-\alpha) \hat{y}_{2|1}$$

⋮

$$\hat{y}_{T+1|T} = \alpha y_T + (1-\alpha) \hat{y}_{T|T-1}$$

$$\hat{y}_{T+1|T} = \sum_{j=0}^{T-1} \alpha(1-\alpha)^j y_{t-j} + (1-\alpha)^T l$$



Component form

Forecast eq $y_{t+h|t} = l_t$

Smoothing eq $l_t = \alpha y_t + (1-\alpha)l_{t-1}$

1) Прогноз - константа

2) α и l_0 - подобрать (задаются)

3) оптимизировать

$$\frac{1}{T} \sum (y_t - \hat{y}_{t|t-1})^2 \rightarrow \min_{\alpha, l_0}$$

Holt's linear trend

Forecast $y_{t+h|t} = l_t + h b_t$

Smoothing $l_t = \alpha y_t + (1-\alpha)(l_{t-1} + b_{t-1})$

Trend $b_t = \beta^*(l_t - l_{t-1}) + (1-\beta^*)b_{t-1}$

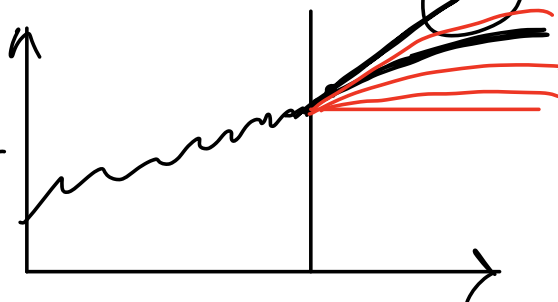
$\alpha, \beta^*, l_0, b_0$

$$0 < \phi < 1$$

$$y_{t+h|t} = l_t + \phi b_t + \phi^2 b_t + \dots$$

$$+ \dots \phi^h b_t =$$

$$l_t + (\phi + \phi^2 + \dots + \phi^h) b_t$$



$$l_t = \alpha y_t + (1-\alpha)(l_{t-1} + \phi b_{t-1})$$

$$b_t = \beta^*(l_t - l_{t-1}) + (1-\beta^*)\phi b_{t-1}$$

$[0.8; 0.98]$

$$y_{t+h|t} \xrightarrow{h \rightarrow \infty} l_t + \frac{\phi b_t}{1-\phi}$$

Seasonality
Holt-Winters

$$y_{t+h|t} = l_t + h b_t + S_{t+h-m(k+1)}$$

m - период сез.

$$k = \text{int} \left(\frac{h-1}{m} \right)$$

$$l_t = \alpha(y_t - S_{t-m}) + (1-\alpha)(l_{t-1} + b_{t-1})$$

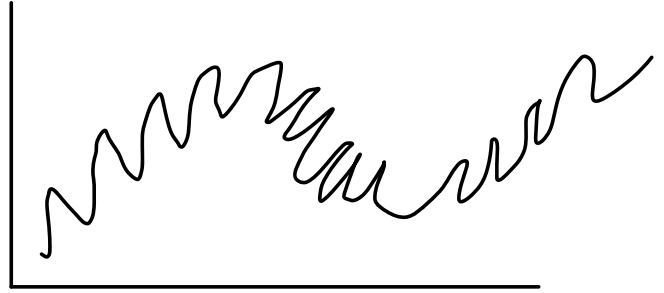
$$b_t = \beta^*(l_t - l_{t-1}) + (1-\beta^*)b_{t-1}$$

$$S_t = \gamma(y_t - l_{t-1} - b_{t-1}) + (1-\gamma)S_{t-m}$$

$$S_t = \gamma^*(y_t - l_t) + (1-\gamma^*)S_{t-m}$$

$$\gamma = \gamma^*(1-\alpha)$$

$$\alpha, \beta^*, \gamma, l_0, b_0, S_0^1, S_0^2, \dots, S_0^m$$



Гипотеза Аллора

$$\begin{cases} y_{t+h|t} = (l_t + h b_t) S_{t+h-m(k+1)} \\ l_t = \frac{\alpha y_t}{S_{t-m}} + (1-\alpha)(l_{t-1} + b_{t-1}) \\ b_t = \beta^*(l_t - l_{t-1}) + (1-\beta^*)b_{t-1} \\ S_t = \delta \frac{y_t}{l_{t-1} + b_{t-1}} + (1-\delta)S_{t-m} \end{cases}$$

Правила с параметрами

Simple exp smoothing \sim ETS(A NN)

$$\begin{cases} \hat{y}_{t+1|t} = l_t \\ l_t = \alpha y_t + (1-\alpha)l_{t-1} \end{cases}$$

$$l_t = l_{t-1} + \alpha(y_t - l_{t-1}) = l_{t-1} + \alpha(\underbrace{y_t - \hat{y}_{t|t-1}}_{\text{error}})$$

$$= l_{t-1} + d e_t$$

$$e_t = y_t - l_{t-1} = y_t - \hat{y}_{t|t-1}$$

$$y_t = \hat{y}_{t|t-1} + e_t$$

$$\begin{cases} y_t = l_{t-1} + \underbrace{e_t}_{\sim N(0, \sigma^2)} & \text{observation (meas)} \\ l_t = l_{t-1} + d \underbrace{e_t} & \text{state/transition} \end{cases}$$

$$\begin{aligned} y_{t+1|t} &= E(y_{t+1} | t) = E(\underbrace{l_t}_{\text{state}} + \underbrace{e_{t+1}}_{\text{noise}} | t) = \\ &= l_t \end{aligned}$$

$$e_t = \frac{y_t - \hat{y}_{t|t-1}}{\hat{y}_{t|t-1}}$$

$$\begin{cases} y_t = l_{t-1} (1 + e_t) \\ l_t = l_{t-1} (1 + d e_t) \end{cases}$$

ETS(AAN)

$$\begin{cases} y_t = l_{t-1} + b_{t-1} + \varepsilon_t \\ l_t = l_{t-1} + b_{t-1} + \alpha \varepsilon_t \\ b_t = b_{t-1} + \beta \varepsilon_t \end{cases}$$

\parallel
 $\alpha \beta^*$

$$\alpha, \beta, \gamma, \phi, l_0, b_0, s_0^1, \dots, s_0^m, \sigma^2$$

$$\text{Add} \quad \sum s_i = 0$$

$$\text{Mul} \quad \sum s_i = m$$