

Барман. 2023

N1.

$K \sim \text{const}$

$$y_t = \sum_{j=1}^K u_j \sin(\lambda_j t) + v_j \cos(\lambda_j t)$$

$$\lambda_j = \text{const}$$

$u_j, v_j$  независимы

$$\text{Var}(u_j) = \text{Var}(v_j) = 1$$

$$1) \gamma_h = \text{cov}(y_0, y_h) = \text{cov}(y_t, y_{t+h})$$

$$\gamma_h = \text{cov}\left(\sum u_j \overset{0}{\sin(\lambda_j 0)} + \overset{1}{v_j \cos(\lambda_j 0)}, \sum u_j \sin(\lambda_j h) + v_j \cos(\lambda_j h)\right) =$$

$$= \text{cov}\left(\sum v_j, \sum \cancel{u_j \sin(\lambda_j h)} + v_j \cos(\lambda_j h)\right) =$$

$\underbrace{\hspace{10em}}_{\text{незав}}$

$$\text{cov}\left(\sum v_j, \sum v_j \cos(\lambda_j h)\right) =$$

$$= \text{cov}\left(\underbrace{v_1 + v_2 + \dots + v_K}_{\text{незав}}, v_1 \cos(\lambda_1 h) + v_2 \cos(\lambda_2 h) + \dots + v_K \cos(\lambda_K h)\right)$$

$$= \underset{1}{\text{Var}(v_1)} \cdot \boxed{\sum \cos(\lambda_j h)} \quad \checkmark$$

2) аналог?

$$\text{cov}(y_{t+1}, y_{t-s}) =$$

$$\begin{aligned}
&= \text{cov}(\sum u_j \sin(\lambda_j t) + v_j \cos(\lambda_j t), \\
&\quad \sum u_j \sin(\lambda_j(t-s)) + v_j \cos(\lambda_j(t-s))) = \\
&\text{cov}(\sum u_j \sin(\lambda_j t), \sum u_j \sin(\lambda_j(t-s))) + \\
&\text{cov}(\sum v_j \cos(\lambda_j t), \sum v_j \cos(\lambda_j(t-s))) = \\
&= \sum \sin(\lambda_j t) \sin(\lambda_j(t-s)) + \\
&\quad \sum \cos(\lambda_j t) \cos(\lambda_j(t-s)) = \\
&\quad \sum \cos(\cancel{\lambda_j t} - \cancel{\lambda_j t} + \lambda_j s) = \sum \cos(\lambda_j s)
\end{aligned}$$

$$r_0 = K$$

$$\frac{dk}{r_0} = \frac{1}{K} \sum \cos(\lambda_j s)$$

$$E(y_t) = 0 \quad \boxed{y_t - \text{may.}}$$

3.

$$\begin{pmatrix} a_t \\ b_t \end{pmatrix} = \begin{pmatrix} 5 \\ 6 \end{pmatrix} + \begin{pmatrix} -2 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} a_{t-1} \\ b_{t-1} \end{pmatrix} + \begin{pmatrix} -1 & 2 \\ 2 & -4 \end{pmatrix} \begin{pmatrix} a_{t-2} \\ b_{t-2} \end{pmatrix} +$$

$$\det(I - \lambda \Phi_1 - \lambda^2 \Phi_2) \quad + \begin{pmatrix} u_t^a \\ u_t^b \end{pmatrix}$$

$$\begin{vmatrix} 1 & 0 & -\lambda \begin{pmatrix} 2 & 2 \\ 2 & 1 \end{pmatrix} - \lambda^2 \begin{pmatrix} -1 & 2 \\ 2 & -4 \end{pmatrix} \end{vmatrix} = 0$$

$$\begin{vmatrix} 1+2\lambda+\lambda^2 & -2\lambda-2\lambda^2 \\ -2\lambda-2\lambda^2 & 1-\lambda+4\lambda^2 \end{vmatrix} = 0$$

$$(1+2\lambda+\lambda^2)(1-\lambda+4\lambda^2) + 2(1+\lambda)\lambda = 0$$

$$\lambda_1, \lambda_2, \lambda_3, \lambda_4 \Rightarrow ? \quad \checkmark 1$$

(4)

$u_t$  — шум в линейном уравнении

$$u_t = \gamma_t \sigma_t, \quad \gamma_t \sim N(0, 1)$$

$$\sigma_t^2 = 3 + 0.1 u_{t-1}^2 \quad \gamma_t \text{ независим от}$$

$$u_{t-1}, \gamma_{t-1}, u_{t-2}, \gamma_{t-2} \dots$$

$$1) \text{Var}(u_t) = \text{Var}(\gamma_t \sigma_t)$$

$$E(u_t^2) - E(u_t)^2 = E(u_t^2) \quad 0 \quad \checkmark$$

$$E(u_t) = E(\gamma_t \sigma_t) = E(\gamma_t) E(\sigma_t) = 0$$

$$E(u_t^2) = E(\underbrace{\gamma_t^2}_{=1} \underbrace{\sigma_t^2}_{=3+0.1 u_{t-1}^2}) = \underbrace{E(\gamma_t^2)}_{=1} E(\sigma_t^2)$$

$$E(u_t^2) = E(\sigma_t^2) \quad \underbrace{E(\gamma_t^2)}_{=1} \quad \underbrace{E(\sigma_t^2)}_{=3+0.1 E(u_{t-1}^2)}$$

$$E(u_t^2) = E(3 + 0.1 u_{t-1}^2) \quad \checkmark \quad 0$$

$$E(u_t^2) = X$$

$$x = 3 + 0.1x \quad 0.9x = 3$$

$$x = \frac{3 \cdot 10}{9} = \frac{30}{9} = 3 \frac{1}{3} \checkmark$$

$$E(u_t^2) = E(\sigma_t^2)$$

$$u_t^2 = \sigma_t^2 + w_t \quad \leftarrow \text{нечисла}$$

$$E(w_t) = 0$$

набл

не наблюд

$$\sigma_t^2 = 3 + 0.1 u_{t-1}^2$$

$$u_t^2 - w_t = 3 + 0.1 u_{t-1}^2$$

$$\underbrace{u_t^2 = 3 + 0.1 u_{t-1}^2}_{AR(1)} + \underbrace{w_t}_{WN(?)}$$

$$E(w_t) = 0 \quad \checkmark$$

$$Var(w_t) = C$$

$$cov(w_t, w_k) = 0 \quad \forall k \neq t$$

$$cov(w_t, w_{t-1}) = E(w_t w_{t-1}) - \overset{0}{E(w_t)} E(w_{t-1}) =$$

$$= E((u_t^2 - \sigma_t^2)(u_{t-1}^2 - \sigma_{t-1}^2)) =$$

$$= E((\underbrace{u_t^2}_{t-1} \sigma_t^2 - \sigma_t^2)(\underbrace{u_{t-1}^2}_{t-2} \sigma_{t-1}^2 - \sigma_{t-1}^2)) =$$

$$= E(\underbrace{\sigma_t^2}_{t-2} \underbrace{\sigma_{t-1}^2}_{t-2} (\underbrace{u_t^2}_{t-1} - 1)(\underbrace{u_{t-1}^2}_{t-2} - 1)) =$$

$$= E(\underbrace{v_t^2 - 1}_{\text{Var}(v_t)}) E(\underbrace{\sigma_t^2 \sigma_{t-1}^2}_{\text{Var}(v_t)} | \underbrace{v_{t-1}^2 - 1}_{\text{Var}(v_t)}) = 0 \quad \square$$

$$\frac{1}{2} (E(v_t^2) - E(1))$$

$$\frac{1}{2} \text{Var}(v_t)$$

$$\text{Var}(w_t) = E(w_t^2) = E((u_t^2 - \sigma_t^2)^2) =$$

$$E((v_t^2 \sigma_t^2 - \sigma_t^2)^2) = E(\sigma_t^4 (v_t - 1)^2) =$$

$$E((3 + 0.1 u_{t-1}^2)^2 (v_{t-1}^2)) = \boxed{?}$$

$$E((u_t^2 - 3 - 0.1 u_{t-1}^2)^2)$$

$$E((X^2 - 3 - 0.1 X^2)^2) = C$$

$$\Delta t$$

$$y_1 = \mathcal{N}(0, 1) \quad E(y_1) = 0 \quad E(y_1^2 - 1) = 0$$

$$y_2 = \mathcal{N}(0, 1) \quad E(y_2) = 0 \quad E(y_2^2 - 1) = 0$$

5

$$y_t = u_t + 0.5 u_{t-1} \quad u_t \sim \mathcal{N}$$

$$\begin{cases} x_t = Fx_{t-1} + J_t \\ y_t = Gx_t + w_t \end{cases}$$

- скаляр

$x_0, (J_1, w_1), (J_2, w_2)$  - векторы

$F, G$  - матрицы

$$\begin{pmatrix} x_t \\ y_t \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x_{t-1} \\ y_{t-1} \end{pmatrix} + \begin{pmatrix} u_t \\ 0 \end{pmatrix}$$

$$y_t = (1, 0.5) \begin{pmatrix} x_t \\ y_t \end{pmatrix} + w_t$$

$$x_0 = \begin{pmatrix} u_0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} u_1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} u_2 \\ 0 \end{pmatrix} \quad 0 \quad 0$$

$J_1 \quad J_2 \quad w_1 \quad w_2$