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Pi Robot

Robot Cartography: ROS + SLAM In a much earlier article we looked at how Pi Robot might use omnidirectional video images and an artificial neural network to figure out which room he was in. The idea was that different places have different visual appearances and we could use these differences to determine where we were at any given moment.

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Simultaneous localization and mapping Wikipedia

In robotic mapping and navigation, simultaneous localization and mapping (SLAM) is the computational problem of constructing or updating a map of an unknown environment while simultaneously keeping track of an agent's location within it. While this initially appears to be a chicken-and-egg problem there are several algorithms known for solving it, at least approximately, in tractable time for

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