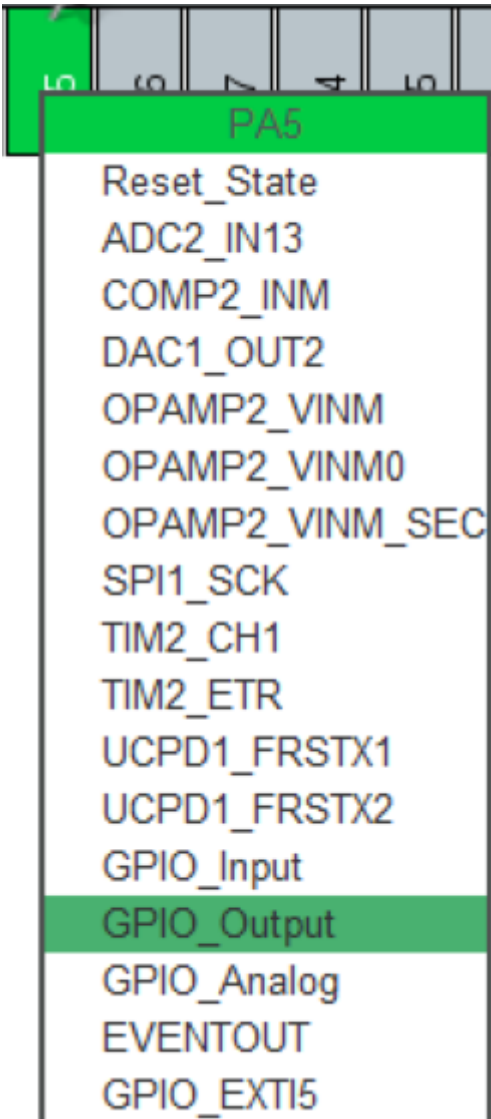


实验2：中断与GPIO

1. CubeMX配置

- 1. 配置LD2引脚PA5（虽然默认配置已经配置好了，但还是再做演示）



选中PA5引脚（具体每个GPIO引脚具有的功能可查看datasheet），选择 GPIO_output

Pin N...	Signal o...	GPIO ou...	GPIO m...	GPIO Pu...	Maximu...	Fast Mode	User Label	Modified
PA5	n/a	Low	Output ...	No pull-u...	Low	n/a	LD2 [gre...	✓
PC13	n/a	n/a	External...	No pull-u...	n/a	n/a	B1 [blue ...	✓

PA5 Configuration :

GPIO output level	Low
GPIO mode	Output Push Pull
GPIO Pull-up/Pull-down	No pull-up and no pull-down
Maximum output speed	Low
User Label	LD2 [green]

进入左侧System->GPIO界面，这里有所有选中的引脚，选择PA5，配置同默认配置

2. 配置PC13外部中断

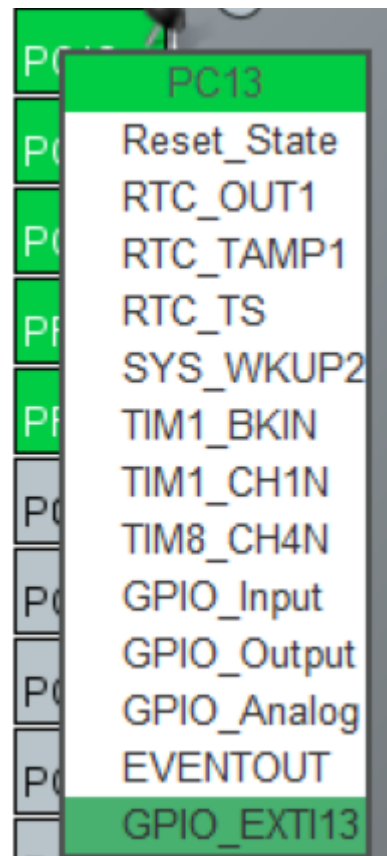
B1 [blue push button]

RCC_OSC32_IN

RCC_OSC32_OUT

RCC_OSC_IN

RCC_OSC_OUT



选择PC13, 选中功能GPIO_EXIT13

Pin N...	Signal o...	GPIO ou...	GPIO m...	GPIO Pu...	Maximu...	Fast Mode	User Label	Modified
PA5	n/a	Low	Output ...	No pull-u...	Low	n/a	LD2 [gre...	✓
PC13	n/a	n/a	External...	No pull-u...	n/a	n/a	B1 [blue ...	✓

PC13 Configuration :

GPIO mode

External Interrupt Mode with Rising edge trigger detection

GPIO Pull-up/Pull-down

No pull-up and no pull-down

User Label

B1 [blue push button]

同上配置PC13, 基本如默认配置

GPIO mode

External Interrupt Mode with Rising edge trigger detection

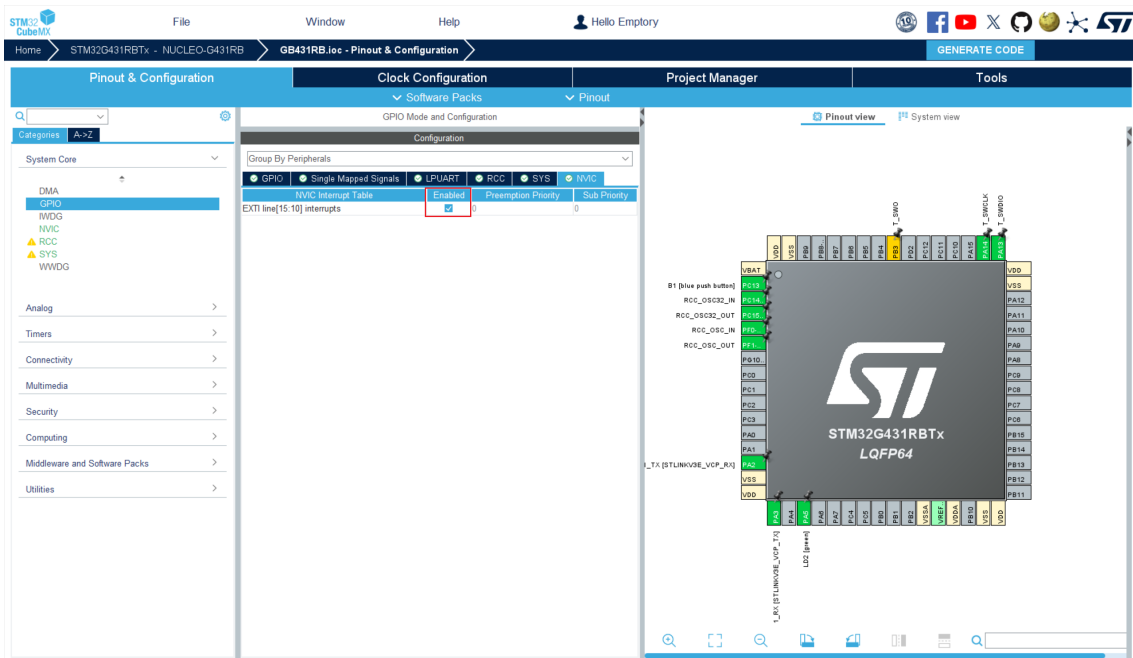
GPIO Pull-up/Pull-down

External Interrupt Mode with Rising edge trigger detection

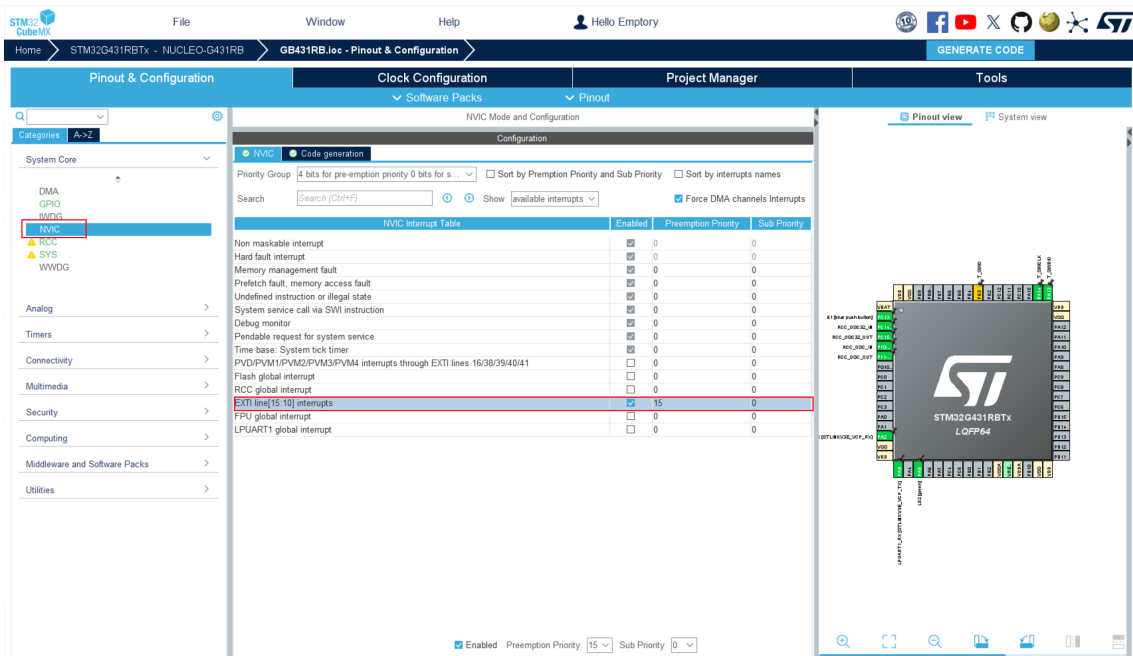
User Label

External Event Mode with Rising edge trigger detection

GPIO mode 可以自己选择别的mode试试



进入GPIO->NVIC中启用EXIT13的NVIC通道



进入NVIC，对EXTI13的NVIC通道优先级进行配置

优先级的数值越小，则优先级越高，也就是说优先级设置为0，那么优先级将是最高的，反之255优先级最小，但是这里只取4 bits，这也是可以再Priority Group中设置的

3. Generate Code后使用MDK进行编写

2. 可能用到的hal库函数

- ```

1 GPIO_PinState HAL_GPIO_ReadPin(GPIO_TypeDef *GPIOx, uint16_t GPIO_Pin)
2 /*
3 读取某GPIO引脚电平值
4 */
5 //示例
6 HAL_GPIO_ReadPin(B1_GPIO_Port,B1_Pin) == GPIO_PIN_SET

```

- ```

1  void HAL_GPIO_EXTI_Callback(uint16_t GPIO_Pin)
2  /*

```

```
3      外部中断函数
4      原型
5
6      __weak void HAL_GPIO_EXTI_Callback(uint16_t GPIO_Pin)
7
8      __weak标识符代表其可被user重载
9  */
10 //示例，只需在main.c或者其他文件处，调用HAL_GPIO_EXTI_Callback后重写具体函数内容
    即可
11 void HAL_GPIO_EXTI_Callback(uint16_t GPIO_Pin)
12 {
13     if(GPIO_Pin == B1_Pin)
14     {
15         HAL_Delay(10);
16         {
17             if(HAL_GPIO_ReadPin(B1_GPIO_Port,B1_Pin) == GPIO_PIN_SET)
18             {
19                 HAL_GPIO_TogglePin(LD2_GPIO_Port,LD2_Pin);
20             }
21         }
22     }
23 }
24 }
```