AWR1xxx Radar Interface Control Document

Revision 0.97

TEXAS INSTRUMENTS

September 13, 2018

Contents

AWR1xxx Radar
Interface Control Document
Revision 0.97 - September 13, 2018

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Revision History

Revision	Date	Description
0.97	13.09.2018	

1. Added a new parameter CASCADING_PINOUT_CFG in AWR_CHAN_CONF_SET_SB in Section 5.2.1 on page 43.

2. Added a new parameter PA LDO disable in AWR_RF_LDO_BYPASS_SB API in Section 5.11.6 on page 132.

3. Added new APIs AWR_PHASE_SHIFTER_CAL_DATA_SAVE_SB in page 57 and AWR_PHASE_SHIFTER_CAL_DATA_RE-STORE_SB in page 56.

4. Added a new parameter LDO_SC_MONITORING_EN in AWR_MONITOR_ANALOG_ENABLES_CONF_SB in page 257.

5. Fixed the length for the SBLKID AWR_DEV_CONFIGURA-TION_SET_SB in page 208.

6. Added a note in AWR_CHIRP_CONF_SET_SB in page 66 that dither parameters are only additive to the programmed parameters in AWR_PROFILE_CONF_SB.

7. Updated the valid range of SFx_PERIOD parameter in AWR_ADVANCED_FRAME_CONF_SB in page 72 to 1.342 s.

8. Added a note below AWR_SUBFRAME_START_CONF_SB on page 107 indicating that watchdog feature is not available when software based sub-frame trigger mode is used.

9. Added new parameters in AWR_MONITOR_PMCLKLO_IN-TERNAL_ANALOG_SIGNALS_CONF_SB in page 290 for 20 GHz sync signal monitoring. Also updated AWR_MONITOR_PMCLKLO_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB in page 180 with 20 GHz monitoring report.

10. Added parameters in AWR_MONITOR_TXn_BPM_CONF_SB in page numbers 170, 171 and 172 for phase shifter monitoring. Also updated AWR_MONITOR_TXn_BPM_REPORT_AE_SB in pages 170, 171 and 172 for phase shifter monitoring reports.

11. Added a note in page 83 indicating that programmble filter APIs should not be issued when frames are ongoing.

12. Updated the mapping of PGA_GAIN_INDEX numbers to gain values in AWR_RF_PSLOOPBACK_CFG_SB in page 135.

13. Added a note after AWR_BPM_CHIRP_CONF_SET_SB in page 111 and AWR_PERCHIRPPHASESHIFT_CONF_SB in page 80 indicating when the BPM and phase shifters are applied.

14. Added TX_CAL_EN_CFG parameter in AWR_PROFILE_CONF_SET_SB in page 59.

15. Added a note in AWR_RF_INIT_CALIBRATION_CONF_SB in page 52 indicating that if TX boot time calibration is disabled, no other backoff other than 0 dB is supported.

16. Added the monitoring duration of TX phase shifter in Table 9.3 in page 317.

17. Added a new API AWR_RF_DIEID_GET_SB in page 118 which reads the Die ID of the device.

18. Added a note in section AWR_LOOPBACK_BURST_CONF_SET_SB in page 93 indicating that when using loopback burst, the corresponding sub-frame in advanced frame configuration should use SFx_NUM_UNIQUE_CHIRPS_PER_BURST as 1.

19. Corrected the sequence of issuing APIs in page 237 - loopback burst config API should be issued after profile config API.

20. Updated error code 49 in Table 6.1 to include the maximum sampling rate based on device variant.

21. Added a note in page 318 explaining the watchdog clearing window calculation by the firmware.

22. Added a note in page 87 indicating if user has not enabled any one time calibrations, but if calibration report is enabled, then after issuing the AWR_RUN_TIME_CALIBRA-TION_CONF_AND_TRIGGER_SB API, the firmware will immediately sent out a calibration report.

23. Added the RFLDOBYPASS_EN API after AWR_ADCOUT_CONF_SET_SB in Table 5.22.1, Table 5.22.3, Table 5.153 and Table 5.154.

24. Added a note after AWR_FRAME_CONF_SET_SB indicating the pulse width requirements of the SYNC_IN pulse in hardware triggered mode.

25. Added a new parameter CHIRP_ROW_SELECT in AWR_DYN_CHIRP_CONF_SET_SB API in page 98 to enable faster configuration of chirps dynamically.

26. Updated the definition of REPORTING_MODE in AWR_MSS_LATENTFAULT_TEST_CONF_SB and AWR_MSS_PERIODICTESTS_CONF_SB APIs in pages 202 and 203.

27. Added new error code 159 to indicate incorrect CHIRP_ROW_SELECT value and updated error code 135 to account for CHIRP_ROW_SELECT values.

28. Added new error codes 1040, 1041, 1042, 1043, 1044, 1045, 1046, 1047, 1048 and 1050 in Table 6.2 in page 251.

29. Added examples of PMIC clock configuration in Section 5.16.9 in page 198.

30. Added a note in AWR_ANALOG_FAULT_INJECTION_CONF_SB in page 299 under SUPPLY_LDO_FAULT indicating that this fault ineffective under LDO_BYPASS condition.

31. Added a note about when to stop the frames when using subframe trigger or hardware trigger mode in page 106.

32. Updated font type to Helvetica.

33. Added a note about usage of CW CZ mode in page 69.

34. Added a note about TX3 gain and phase imbalance offset wrt. TX1 and TX2 in page 274.

35. Added a note about inter-burst idle time requirement in page 47.

36. Added a note about Noise figure Values reporting in NF Monitoring report AE in page 158.

37. Added a note in MSS powerup done AE in page 223.

38. Added a note about Tx output Power backoff in profile config API in page 59.

39. Added a note about Tx output Power monitoring in page 162.

40. Added a note about Programmable filter tap start index selection in page 81.

41. Added a note in AWR_AE_MSS_BOOTERRORSTATUS_SB AE in page 231.

42. Updated runtime VCO calibration time in page 315.

43. Updated VCO control voltage monitor upper threshold in page 182.

1 Introduction

1.1 Scope

The xWR1243, xWR1642 and xWR1843 products are highly-integrated 77GHz CMOS automotive radar devices. The devices integrate all of the RF and Analog functionality, including VCO, PLL, PA, LNA, Mixer and ADC for multiple TX/RX channels into a single chip. The xWR1243 is an RF transceiver device and it includes 4 receiver channels and 3 transmit channels in a single chip. The xWR1243 also supports multi-chip cascading. The xWR1642/xWR1843 is a radar-on-a-chip device, which includes 4 receive channels and 2 transmit channels and additionally an integrated DSP for radar signal processing.

Both devices include a built-in BIST (Built-in Self-Test) processor, which is responsible to configure the RF/Analog and digital front-end in real-time, as well as to periodically schedule calibration and functional safety monitoring. This enables the mm-Wave front-end to be self-contained and capable of adapting itself to handle temperature and aging effects, and to enable significant ease-of-use from an external host perspective.

This document contains the Interface Control Specification for communications on the serial interface (SPI) between the Radar device and the external host processor. The same protocol is used in xWR16xx when the messages are sent to Radar Control subsystem (BIST subsystem) from the MCU subsystem (Master subsystem).

1.2 Intended Audience

The intended audience for this document is firmware, host software, and validation engineers needing to understand the format and contents of all communications between the Radar device and the host processor.

2 AWR1xxx Communications Overview

2.1 Communication Link Description

The xWR12xx radar device communicates with the external host processor using the SPI inter-face. The radar device is configured and controlled from the external host processor by sending commands to xWR12xx device over SPI.

The xWR16xx radar device is configured and controlled using the internal MCU (Master subsys-tem) and it communicates with an external ECU using the CAN interface.

This document only talks about the communication protocol between radar device and external host processor using SPI in xWR12xx. In xWR16xx, the same protocol is used to communicate between the BIST subsystem and Master subsystem.

2.2 Communication Link configuration

2.2.1 SPI

This interface is synchronous. The interface includes four signals (SPICLK, SPICS, and Data In and Data Out) and supports clock rates up to 40 MHz. The xWR12xx radar device is always the SPI slave and the external host processor will be the SPI master.

2.2.2 Mailbox

This interface includes a SRAM and an interrupt line from Master subsystem to BIST subsystem. A reverse channel which includes a different SRAM and a different interrupt line from the BIST subsystem to Master subsystem is used for responses which originate from BIST subsystem.
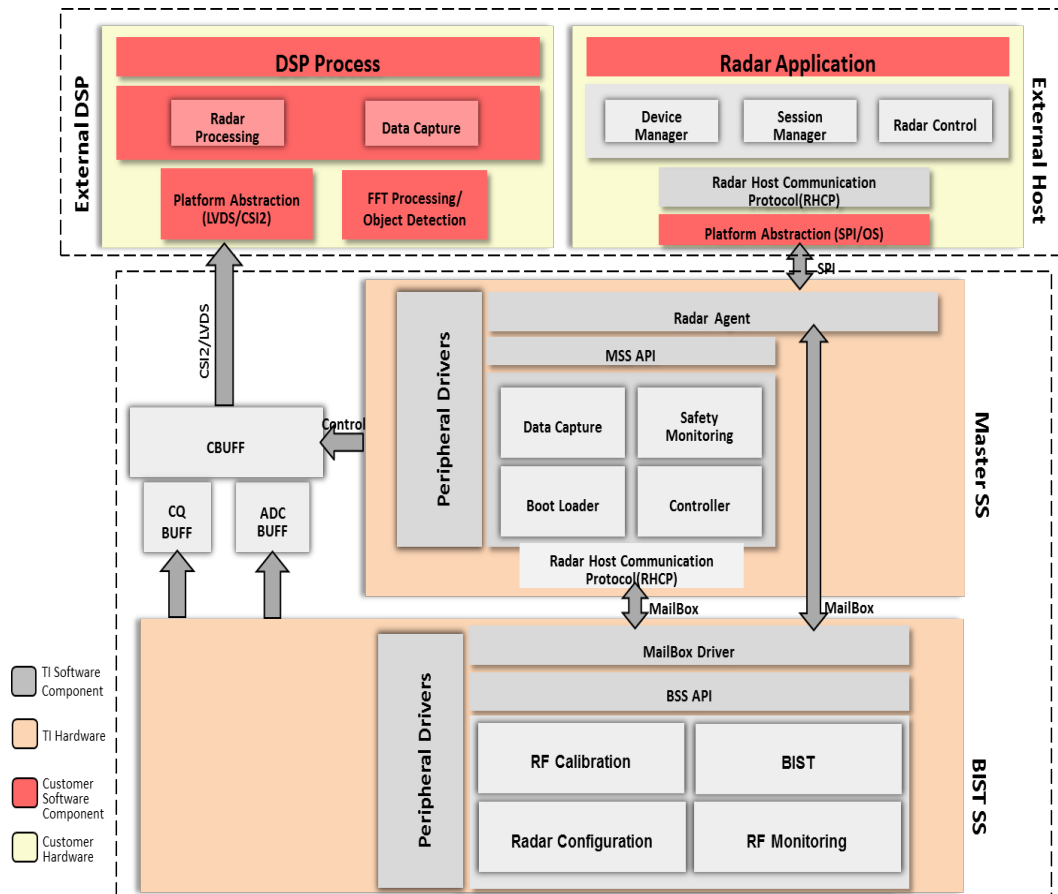
Figure 2.1: xWR12xx Software Architecture
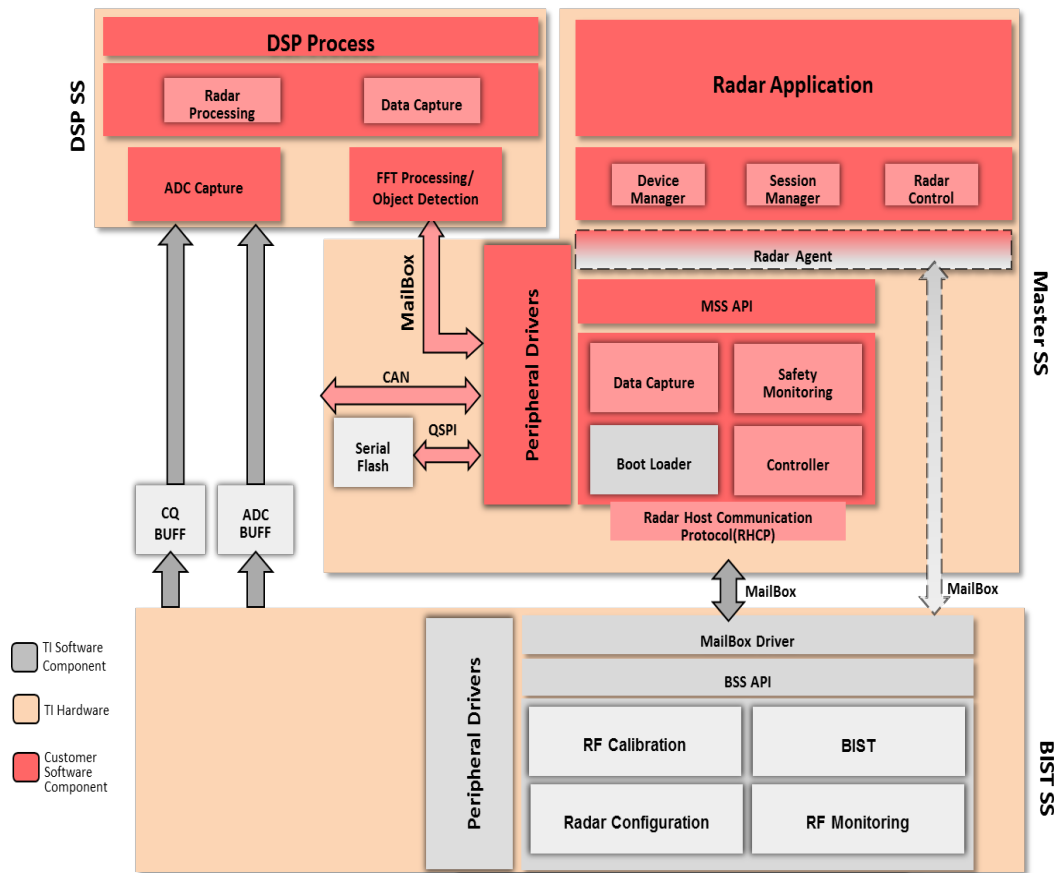
Figure 2.2: xWR16xx Software Architecture

2.3 Radar Message Structure
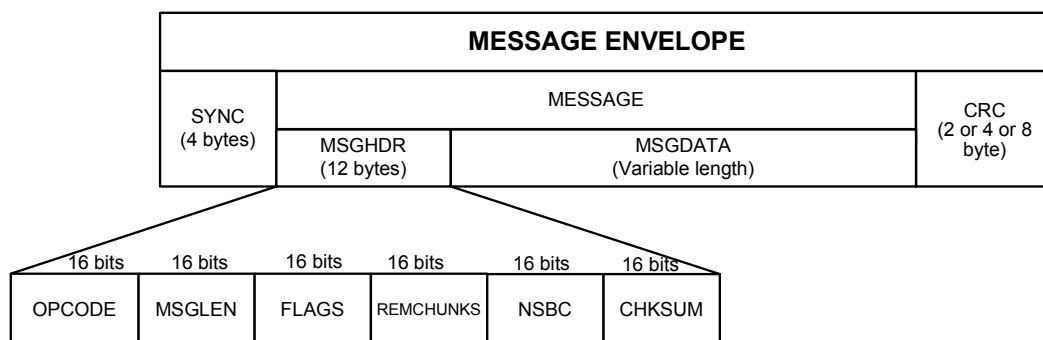
Figure 2.3: Radar Message Structure

Each message is sent in a message envelope, which starts with four special bytes called a sync pattern. Next, the message envelope contains the actual message and a CRC converted to a stream of bytes. Figure 2.3 defines the general form of radar messages. All communication messages between external host processor and the radar device will follow this message format. Each message consists of a 12-byte message header, variable length message data followed by a variable length CRC.

NOTE:	The CRC and all the fields in the message headers and message data that are larger than one byte are sent in little-endian byte order i.e. the least significant byte is sent first.

A message envelope contains only one message.

2.3.1 SYNC

SYNC is a unique 4 byte pattern which marks the start of the message. It can take one of the following 3 values, in memory all the bytes are stored in little endian format (least significant byte first).

Table 2.1: Possible SYNC values and their usage

SYNC word value	Description
0x43211234	Messages from master to slave indicating a new command
0x87655678	Messages from external host to device indicating the host is now ready to receive a message from the device This pattern is defined as CNYS in this document.
0xABCDDCBA	Messages from slave to master

2.3.2 MSGHDR

Figure 2.4 defines the content of the message header. Each radar message must begin with this 12 byte message header in little endian format.

OPCODE	LENGTH	FLAGS	REMCHUNKS	NSBC	CHKSUM
(16 bits)	(16 bits)	(16 bits)	(16 bits)	(16 bits)	(16 bits)

Figure 2.4: Message Header Format

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
MSGID										MSGTYPE		DIRECTION			

Figure 2.5: OPCODE Format

OPCODE

The OPCODE is unique for a given message type. Figure 2.5 defines the OPCODE format.

Bits	Field	Description
[3:0]	DIRECTION	Direction of command
		0000 Invalid
		0001 Communication between Host to BSS
		0010 Communication between BSS to Host
		0011 Communication between Host to DSS
		0100 Communication between DSS to Host
		0101 Communication between Host to Master
		0110 Communication between Master to Host
		0111 Communication between BSS to Master
		1000 Communication between Master to BSS
		1001 Communication between BSS to DSS
		1010 Communication between DSS to BSS
		1011 Communication between Master to DSS
		1100 Communication between DSS to Master
		1101 RESERVED
		1110 RESERVED
		1111 RESERVED
[5:4]	MSGTYPE	Message type
		00 COMMAND
		01 RESPONSE (ACK or ERROR)
		10 NACK
		11 ASYNC
[15:6]	MSGID	Message ID
		0x00 AWR_ERROR_MSG
		0x01 RESERVED
		0x02 RESERVED
		0x03 RESERVED
		0x04 AWR_RF_STATIC_CONF_SET_MSG
		0x05 AWR_RF_STATIC_CONF_GET_MSG
		0x06 AWR_RF_INIT_MSG
		0x07 RESERVED
		0x08 AWR_RF_DYNAMIC_CONF_SET_MSG
		0x09 AWR_RF_DYNAMIC_CONF_GET_MSG
		0x0A AWR_RF_FRAME_TRIG_MSG
		0x0B RESERVED

		0x0C	AWR_RF_ADVANCED_FEATURES_CONF_SET_MSG
		0x0D	RESERVED
		0x0E	AWR_RF_MONITORING_CONF_SET_MSG
		0x0F	RESERVED
		0x10	RESERVED
		0x11	AWR_RF_STATUS_GET_MSG
		0x12	RESERVED
		0x13	AWR_RF_MONITORING_REPORT_GET_MSG
		0x14	RESERVED
		0x15	RESERVED
		0x16	AWR_RF_MISC_CONF_SET_MSG
		0x17	AWR_RF_MISC_CONF_GET_MSG
		0x18	RESERVED
		0x19	RESERVED
		0x80	AWR_RF_ASYNC_EVENT_MSG1
		0x81	AWR_RF_ASYNC_EVENT_MSG2
		0x200	AWR_DEV_RFPOWERUP_MSG
		0x201	RESERVED
		0x202	AWR_DEV_CONF_SET_MSG
		0x203	AWR_DEV_CONF_GET_MSG
		0x204	AWR_DEV_FILE_DOWNLOAD_MSG
		0x205	RESERVED
		0x206	AWR_DEV_FRAME_CONFIG_APPLY_MSG
		0x207	AWR_DEV_STATUS_GET_MSG
		0x208	RESERVED
		0x209	RESERVED
		0x20A	RESERVED
		0x20B	RESERVED
		0x20C	RESERVED
		0x20D	RESERVED
		0x280	AWR_DEV_ASYNC_EVENT_MSG

LENGTH

The length field contains the length of the message in bytes including the message header, message data and CRC. Note that length field does not include the length of the sync field. The minimum length of the message is 12 bytes and maximum is 252 bytes. The message length minus CRC length must also be a multiple of 4 bytes.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RESERVED				LEN											
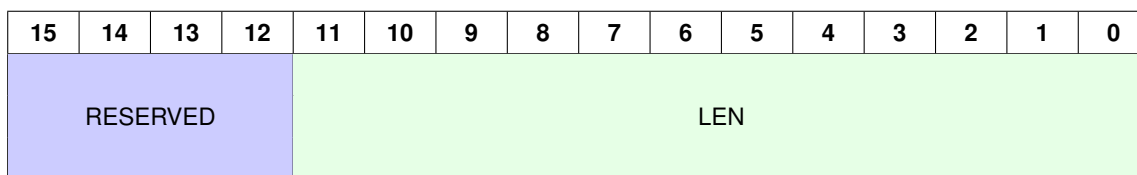
Figure 2.6: MSGLEN Format

Table 2.3: MSGLEN field descriptions

Bits	Field	Description
[11:0]	LEN	Message length in bytes (It includes message header, message data and CRC)
[15:12]	RESERVED	Keep these bits as 0s

FLAGS

The FLAGS is used to control the communication between the radar device and external host

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
SEQNUM				CRCLEN		CRCREQ		PROTOCOL VERSION				ACQREQ		RETRY	
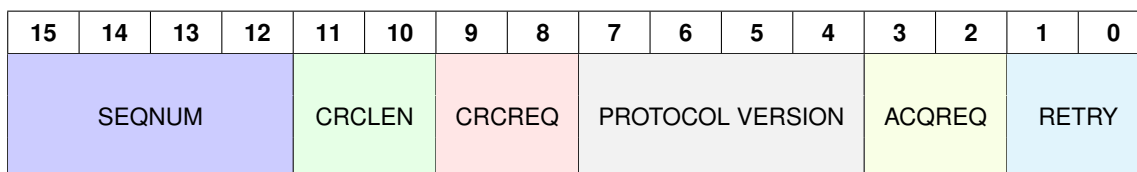
Figure 2.7: FLAGS Format

Table 2.4: FLAGS field description

Bits	Field	Description	
[1:0]	RETRY	RETRY Value	
		00	New message
		11	Retransmitted message
		01	RESERVED
		10	RESERVED
[3:2]	ACKREQ	Acknowledgement Request type	
		00	Acknowledgement is requested for the current message
		11	Acknowledgement is not requested for the current message
		01	RESERVED
		10	RESERVED

Table 2.4 – continued from previous page

[7:4]	PROTOCOL VERSION	Version number of the protocol that is used to communicate with the device (4 bits)
[9:8]	CRCREQ	CRC request type 00 CRC is appended to the message 11 CRC is not appended to the message 01 RESERVED 10 RESERVED
[11:10]	CRCLEN	Length of CRC appended to the message 00 16-bit CRC 01 32-bit CRC 10 64-bit CRC 11 RESERVED
[15:12]	SEQNUM	4 bit sequence number of the message. Sequence number is reset to 0 after a device boot and each new message has the incremented sequence number. Whenever the same message is retransmitted, the sequence number is not incremented.

> **NOTE:** It is recommended to always append CRC to the message to prevent any message integrity issues

REMCHUNKS

If the message length is larger than 256 bytes, then it is split into multiple chunks of sizes less than 256 bytes. When this field is non-zero, this field indicates the number of remaining chunks that are to be expected.

NSBC

The message may contain several configuration sub blocks with structure as defined in Figure 2.3. The NSBC field indicates the total number sub blocks inside the message data.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RESERVED					NSBC										

Figure 2.8: NSBC Format

Table 2.5: NSBC field description

Bits	Field	Description
[10:0]	NSBC	Number of sub blocks in the message
[15:11]	RESERVED	Keep these bits as 0s

CHKSUM

The message header is protected by a 16-bit checksum to enable the receiver to check the integrity of the message header. The checksum is computed on MSGHDR only (MSGID, MSGLEN, FLAGS, REMCHUNKS and NSBC fields). Note that SYNC field is not included in checksum calculation.

Checksum is 16-bit one's complement of the one's complement sum of all 16-bit words in the message header (Ref. https://tools.ietf.org/html/rfc1071).

For e.g., suppose the message header contents looks like this

Table 2.6: Checksum computation example

Field	Value
OPCODE	0x0281
MSGLEN	0x0800
FLAGS	0x040C
REMCHUNKS	0x0000
NSBC	0x0001
CHKSUM	0xF171

The receiver will compute the checksum as follows 0x0281 + 0x0800 = 0x0A81.

Then, 0x0A81 + 0x040C = 0x0E8D.

Then, 0x0E8D + 0x0000 = 0x0E8D.

Then, 0x0E8D + 0x0001 = 0x0E8E.

Ones complement of 0x0E8E is 0xF171 which matches with the received checksum.

2.3.3 MSGDATA

The message data contains the actual message specific data for the message. The message data contains sub blocks with structure as defined in Figure 2.9. More than one sub block can be appended in the MSGDATA to reduce the overall communication latency. The total number of sub blocks in MSGDATA is indicated in the NSBC field in the MSGHDR.

All data fields are aligned so that their offset in message is a multiple of the field size in bytes. For e.g. a 32 bit field in the message will be aligned to a 4 byte boundary and a 16 bit field will be aligned to a 2 byte boundary. This makes it possible to create a structure definition for the message for easy data access in most environments.

Any reserved (currently unused) fields in the messages should be always set as 0 when sent and ignored when received. This way those fields may be taken to use in later interface versions without modifying all old software.

All data structure in sub-blocks assumed to be in little endian format. For big endian Host system byte swap is required to match with defined protocol.

MSGDATA		
SBLKID	SBLKLEN	SBLKDATA
(16 bits)	(16 bits)	(Variable length)

Figure 2.9: Message Sub block structure

SBLKID   Unique ID of the sub block

SBLKLEN   Length of the sub block in bytes

SBLKDATA   Data corresponding to the sub block

2.3.4 CRC

This is a CRC which is appended to the message data to protect the integrity of the message. The CRC is computed on all the bytes in the MSGHDR and MSGDATA. Note that SYNC is not included in CRC calculation.

3 different types of CRCs can be used – 16 bit, 32 bit or 64 bit. The choice of the CRC type is indicated in the FLAGS field in the MSGHDR.

The polynomials used for each type of CRC calculation are

Table 2.7: CRC types and their polynomials

CRC type	Polynomial	Remarks
16 bit	$x^{16} + x^{12} + x^5 + 1$	16-bit CRC-CCITT
32 bit	$x^{32}+x^{26}+x^{23}+x^{22}+x^{16}+x^{12}+x^{11}+x^{10}+x^8+x^7+x^5+x^4+x^2+x+1$	CRC-32 (used in Ethernet)
64 bit	$x^{64}+x^4+x^3+x+1$	CRC-64-ISO (HDLC)

3 Message Processing

3.1 Communication protocol

When requested by the message transmitter, all correctly formatted radar messages are acknowledged by the receiver. This request for an acknowledgement is specified in FLAGS field of the MSGHDR (message header) field (see Section 2.3.2). A correctly formatted message is one that is formatted properly with a SYNC, MSGHDR, MSGDATA and CRC and that passes the CRC test when received. If an incorrectly formatted message is received, the radar device responds with a NACK message (MSGTYPE field in the MSGHDR set to NACK response). If a correctly formatted message is received, and after processing the message no errors are encountered, the radar device responds with an ACK response. In case of errors on a correctly formatted message, the radar device responds with an ERROR response.

The ACK response is a radar message which contains SYNC, MSGHDR, MSGDATA and CRC. In case the MSGTYPE was COMMAND_GET the MSGDATA for ACK response will contain the parameter values read by the radar device.

The NACK response is a radar message with only SYNC, MSGHDR and CRC. It does not contain MSGDATA.

For most commands the radar device prepares the acknowledgments and response packets immediately on reception. In certain cases, higher priority events in the system delay the execution of external communication function. The response time to command is a function of:

- Speed of the selected communication channel

- Although typical radar command/response occurs within a few hundreds of microseconds, it is recommended that host software wait up to 1 millisecond for response or acknowledgment before timing out on nonresponse.

The radar communication protocol is defined as follows

1. The host sends a message to the radar device requesting an acknowledgement. Host sets a timeout period of 1 ms for a response from the radar device.

2. The radar device checks the CHKSUM field for Message header validity and checks the MSGDATA field for correctness and also computes the CRC of the message and compares it with the received CRC.

   - If the computed CHKSUM does not match the received CHKSUM, the radar device does not send any response. The transmitter will timeout and eventually resend the command again with RETRY flag set

- If the CRC matches and all parameters are valid/correct, the radar device sends an ACK to the host

- If the CRC matches, but any parameter in the message is invalid/incorrect, then the radar device sends an ERROR response to the host

- If the CRC does not match, the radar device sends a NACK response to the host

3. On reception of the ACK, the host can send the next command to the radar device.

4. If the host receives a NACK from the radar device within the timeout period, it sends the message again without the RETRY flag set.

5. If the host does not receive any response from the radar device within the timeout period then it sends the same command with the RETRY flag set.

3.2 Communication Sequence

3.2.1 Command/Response Sequence (Host)

1. Host prepares the message as defined by protocol in Section 2.3

2. Host writes the message to the communication channel and starts Retry Timer ($\sim$1 ms)

3. Host then waits for HOST IRQ high Interrupt

    a. If IRQ is received, go to Step 4

    b. If Retry Time expires, Enable Retry Flag and go to Step 2

4. Host writes CNYS (SYNC word = 0x5678 0x8765) and Dummy bytes (0xFFFF 0xFFFF 0xFFFF 0xFFFF 0xFFFF 0xFFFF) on communication channel

5. Host waits for low on Host IRQ line

    a. If Host IRQ line is low, go to Step 6

    b. If Retry Time expires, Flag Error

6. Host reads the header from communication channel

7. Host checks the validity of header (verify checksum)

    a. If header is valid, parse the header and go to Step 8

    b. If header is invalid, ignore the header and go to Step 3

8. Host reads the payload from communication channel

9. Host checks the validity of the message (verify CRC)

    a. If message is valid, process the message

    b. If message is invalid, go to Step 2

14

3.2.2 Flow Diagram (Host) – Command/Response
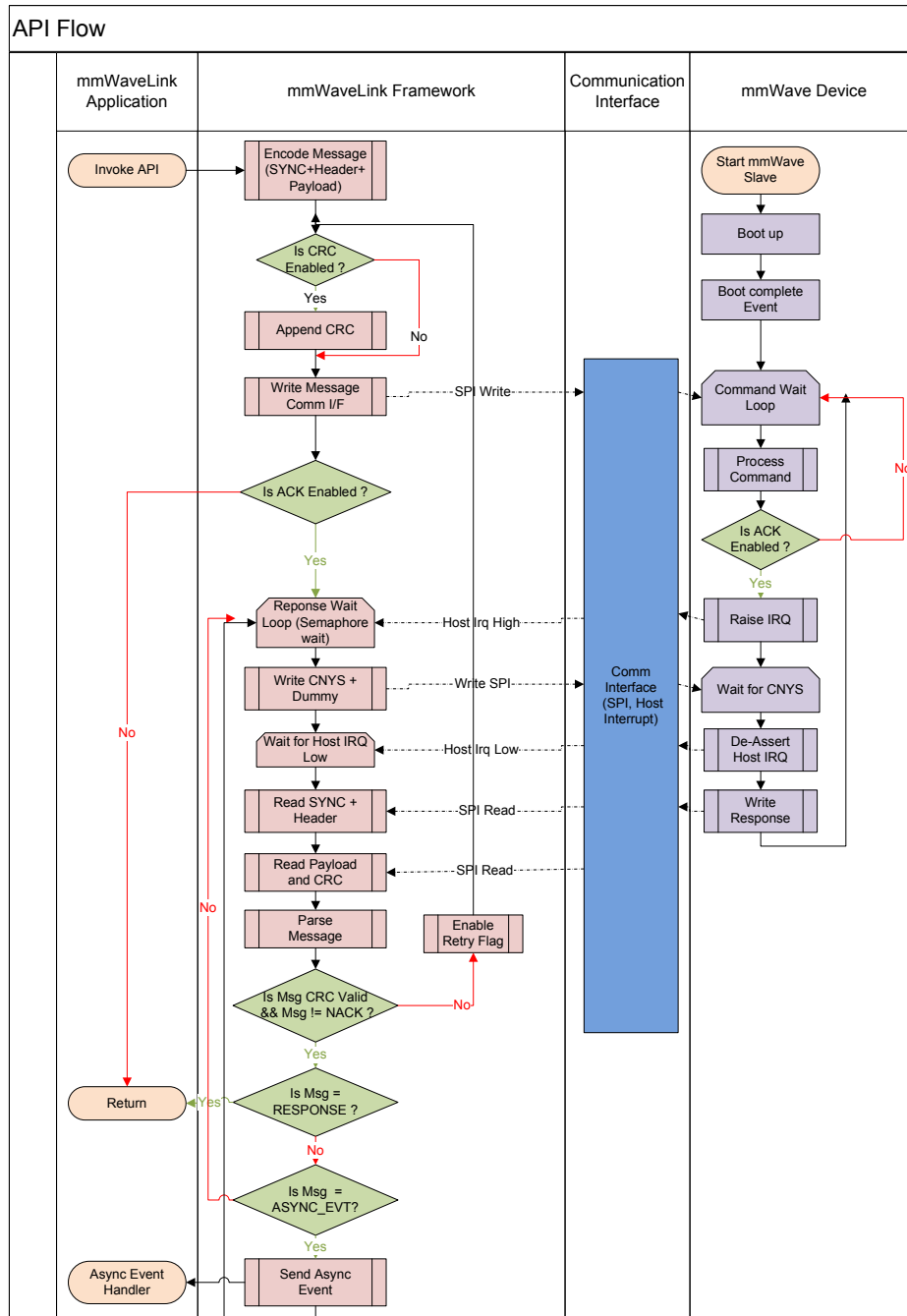
Figure 3.1: Flow Diagram (API)

3.2.3 Flow Diagram (Host) – Bootup/ Asynchronous Event
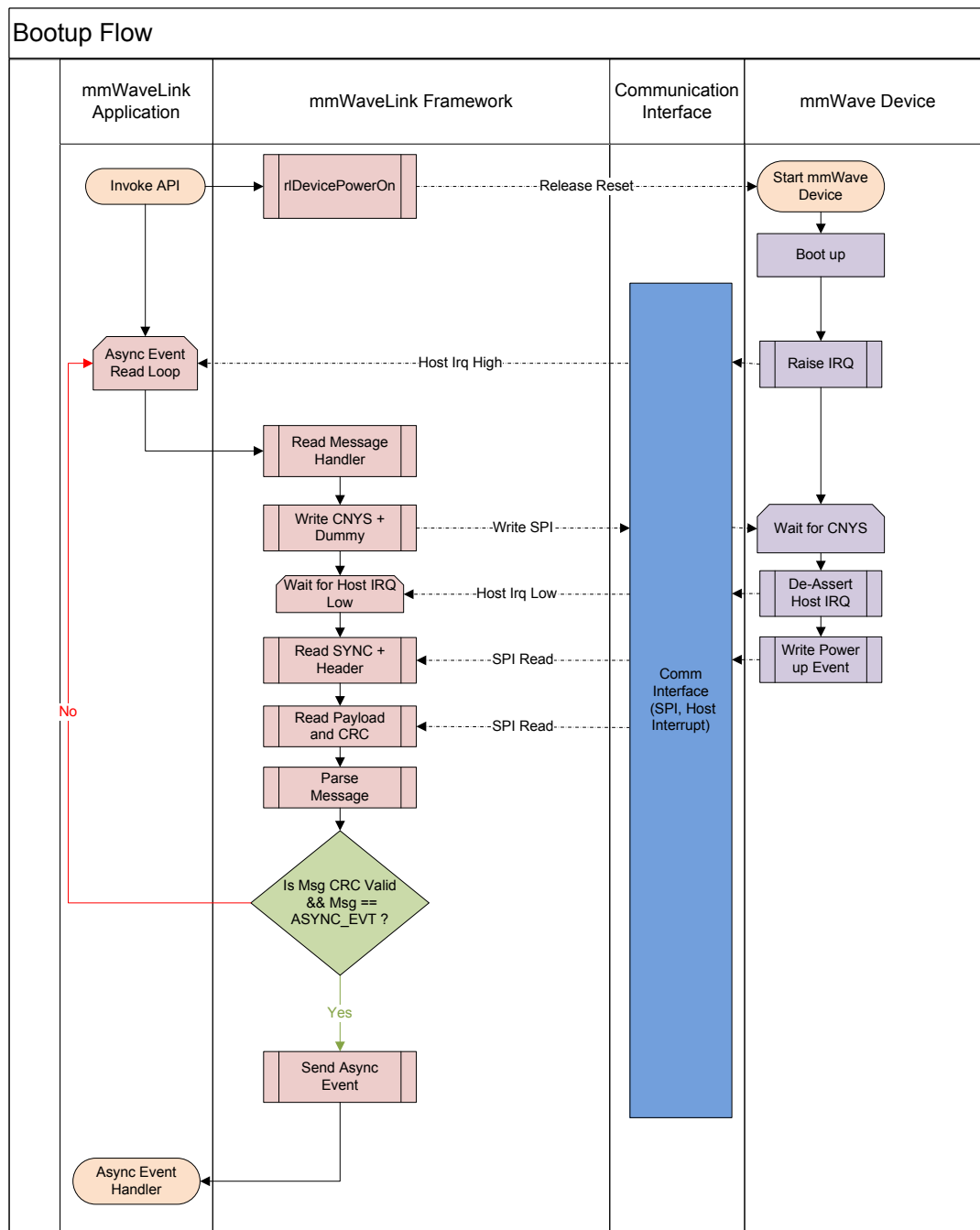
Figure 3.2: Flow Diagram (Asynchronous Events)

3.2.4 SPI Message Sequence – Command/Response
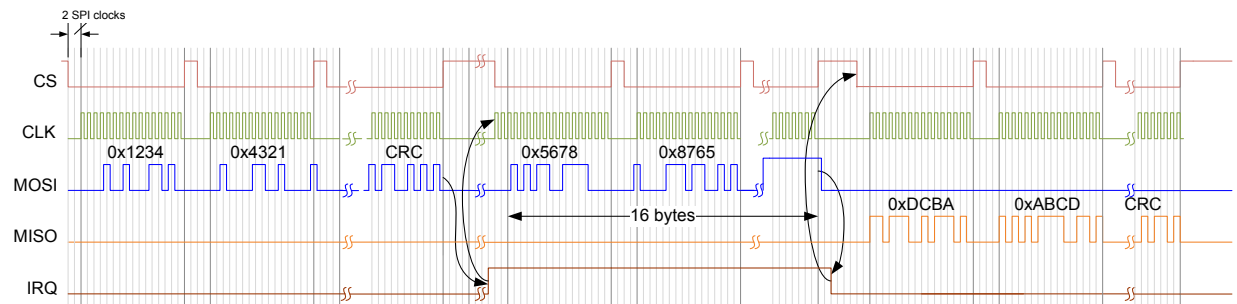
Figure 3.3: SPI Message Sequence

NOTE:	
	1. Host should ensure that there is a delay of at least 2 SPI clocks between CS going low and start of SPI clock
	2. Host should ensure that CS is toggled for every 16 bits of transfer via SPI
	3. There should be a delay of at least 2 SPI Clocks between consecutive CS
	4. SPI needs to be operated at Mode 0 (Phase 0, Polarity 0)
	5. SPI word length should be 16 bit (Half word)

4 Radar Interface Messages Descriptions

This section describes all the radar interface messages that are used in communication with the radar transceiver.

4.1 Summary of all messages and their associated sub-blocks

Table 4.1: Summary of all Radar messages and their associated sub blocks

Radar Messages	Associated sub-blocks
AWR_ACK_MSG	NA
AWR_NACK_MSG	NA
AWR_ERROR_MSG	AWR_RESP_ERROR_SB
AWR_RF_STATIC_CONF_SET_MSG	AWR_CHAN_CONF_SET_SB
	AWR_ADCOUT_CONF_SET_SB
	AWR_LOWPOWERMODE_CONF_SET_SB
	AWR_DYNAMICPOWERSAVE_CONF_SET_SB
	AWR_HIGHSPEEDINTFCLK_CONF_SET_SB
	AWR_RF_DEVICE_CFG_SB
	AWR_RF_RADAR_MISC_CTL_SB
	AWR_CAL_MON_FREQUENCY_LIMITS_SB
	AWR_RF_INIT_CALIBRATION_CONF_SB
	AWR_CAL_MON_FREQUENCY_TX_POWER_LIMITS_SB
	AWR_CAL_DATA_RESTORE_SB
	AWR_PHASE_SHIFTER_CAL_DATA_RESTORE_SB
AWR_RF_STATIC_CONF_GET_MSG	AWR_CAL_DATA_SAVE_SB
	AWR_PHASE_SHIFTER_CAL_DATA_SAVE_SB
AWR_RF_INIT_MSG	AWR_RF_INIT_SB
AWR_RF_DYNAMIC_CONF_SET_MSG	AWR_PROFILE_CONF_SET_SB
	AWR_CHIRP_CONF_SET_SB
	AWR_FRAME_CONF_SET_SB
	AWR_CONT_STREAMING_MODE_CONF_SET_SB
	AWR_CONT_STREAMING_MODE_EN_SB

Table 4.1 – continued from previous page

Radar Messages	Associated sub-blocks
	AWR_ADVANCED_FRAME_CONF_SB
	AWR_PERCHIRPPHASESHIFT_CONF_SB
	AWR_PROG_FILT_COEFF_RAM_SET_SB
	AWR_PROG_FILT_CONF_SET_SB
	AWR_CALIB_MON_TIME_UNIT_CONF_SB
	AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB
	AWR_INTER_RX_GAIN_PHASE_CONTROL_SB
	AWR_RX_GAIN_TEMPLUT_SET_SB
	AWR_TX_GAIN_TEMPLUT_SET_SB
	AWR_LOOPBACK_BURST_CONF_SET_SB
	AWR_DYN_CHIRP_CONF_SET_SB
	AWR_DYN_PERCHIRP_PHASESHIFTER_CONF_SB
	AWR_DYN_CHIRP_ENABLE_SB
	AWR_INTERCHIRP_BLOCKCONTROLS_SB
	AWR_SUBFRAME_START_CONF_SB
AWR_RF_DYNAMIC_CONF_GET_MSG	AWR_PROFILE_CONF_GET_SB
	AWR_CHIRP_CONF_GET_SB
	AWR_FRAME_CONF_GET_SB
	AWR_ADVANCED_FRAME_CONF_GET_SB
	AWR_RX_GAIN_TEMPLUT_GET_SB
	AWR_TX_GAIN_TEMPLUT_GET_SB
AWR_RF_FRAME_TRIG_MSG	AWR_FRAMESTARTSTOP_CONF_SB
AWR_RF_ADVANCED_FEATURES_CONF_SET_MSG	AWR_BPM_COMMON_CONF_SET_SB
	AWR_BPM_CHIRP_CONF_SET_SB
AWR_RF_MONITORING_CONF_SET_MSG	AWR_MONITOR_RF_DIG_LATENTFAULT_CONF_SB
	AWR_MONITOR_RF_DIG_PERIODIC_CONF_SB
	AWR_MONITOR_ANALOG_ENABLES_CONF_SB
	AWR_MONITOR_TEMPERATURE_CONF_SB
	AWR_MONITOR_RX_GAIN_PHASE_CONF_SB
	AWR_MONITOR_RX_NOISE_FIGURE_CONF_SB
	AWR_MONITOR_RX_IFSTAGE_CONF_SB
	AWR_MONITOR_TX0_POWER_CONF_SB
	AWR_MONITOR_TX1_POWER_CONF_SB
	AWR_MONITOR_TX2_POWER_CONF_SB

Table 4.1 – continued from previous page

Radar Messages	Associated sub-blocks
	AWR_MONITOR_TX0_BALLBREAK_CONF_SB
	AWR_MONITOR_TX1_BALLBREAK_CONF_SB
	AWR_MONITOR_TX2_BALLBREAK_CONF_SB
	AWR_MONITOR_TX_GAIN_PHASE_MISMATCH_CONF_SB
	AWR_MONITOR_TX0_BPM_CONF_SB
	AWR_MONITOR_TX1_BPM_CONF_SB
	AWR_MONITOR_TX2_BPM_CONF_SB
	AWR_MONITOR_SYNTHESIZER_FREQUENCY_CONF_SB
	AWR_MONITOR_EXTERNAL_ANALOG_SIGNALS_CONF_SB
	AWR_MONITOR_TX0_INTERNAL_ANALOG_SIGNALS_CONF_SB
	AWR_MONITOR_TX1_INTERNAL_ANALOG_SIGNALS_CONF_SB
	AWR_MONITOR_TX2_INTERNAL_ANALOG_SIGNALS_CONF_SB
	AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_CONF_SB
	AWR_MONITOR_PMCLKLO_INTERNAL_ANALOG_SIGNALS_CONF_SB
	AWR_MONITOR_GPADC_INTERNAL_ANALOG_SIGNALS_CONF_SB
	AWR_MONITOR_PLL_CONTROL_VOLTAGE_SIGNALS_CONF_SB
	AWR_MONITOR_DUAL_CLOCK_COMP_CONF_SB
	AWR_MONITOR_RX_SATURATION_DETECTOR_CONF_SB
	AWR_MONITOR_SIG_IMG_MONITOR_CONF_SB
	AWR_MONITOR_RX_MIXER_IN_POWER_CONF_SB
	AWR_ANALOG_FAULT_INJECTION_CONF_SB
AWR_RF_MONITORING_REPORT_GET_MSG	AWR_RF_DFE_STATISTICS_REPORT_GET_SB
AWR_RF_STATUS_GET_MSG	AWR_RF_VERSION_GET_SB
	AWR_RF_CPUFAULT_STATUS_GET_SB
	AWR_RF_ESMFAULT_STATUS_GET_SB
	AWR_RF_DIEID_GET_SB
	AWR_RF_BOOTUPBIST_STATUS_GET_SB
	AWR_RF_TEST_SOURCE_CONFIG_SET_SB
	AWR_RF_TEST_SOURCE_ENABLE_SET_SB

AWR_RF_MISC_CONF_SET_MSG

Table 4.1 – continued from previous page

Radar Messages	Associated sub-blocks
	AWR_RF_LDO_BYPASS_SB
	AWR_RF_PALOOPBACK_CFG_SB
	AWR_RF_PSLOOPBACK_CFG_SB
	AWR_RF_IFLOOPBACK_CFG_SB
	AWR_RF_GPADC_CFG_SET_SB
AWR_RF_MISC_CONF_GET_MSG	AWR_RF_TEMPERATURE_GET_SB
AWR_RF_ASYNC_EVENT_MSG1	AWR_AE_RF_CPUFAULT_SB
	AWR_AE_RF_ESMFAULT_SB
	AWR_AE_RF_INITCALIBSTATUS_SB
	AWR_AE_RF_FRAME_TRIGGER_RDY_SB
	AWR_AE_RF_GPADC_RESULT_DATA_SB
	AWR_FRAME_END_AE_SB
	AWR_ANALOGFAULT_AE_SB
	AWR_CAL_MON_TIMING_FAIL_REPORT_AE_SB
	AWR_RUN_TIME_CALIBRATION_SUMMARY_REPORT_AE_SB
	AWR_MONITOR_RF_DIG_LATENTFAULT_REPORT_AE_SB
	AWR_MONITOR_REPORT_HEADER_AE_SB
	AWR_MONITOR_RF_DIG_PERIODIC_REPORT_AE_SB
	AWR_MONITOR_TEMPERATURE_REPORT_AE_SB
	AWR_MONITOR_RX_GAIN_PHASE_REPORT_AE_SB
	AWR_MONITOR_RX_NOISE_FIGURE_REPORT_AE_SB
	AWR_MONITOR_RX_IFSTAGE_REPORT_AE_SB
	AWR_MONITOR_TX0_POWER_REPORT_AE_SB
	AWR_MONITOR_TX1_POWER_REPORT_AE_SB
	AWR_MONITOR_TX2_POWER_REPORT_AE_SB
	AWR_MONITOR_TX0_BALLBREAK_REPORT_AE_SB
	AWR_MONITOR_TX1_BALLBREAK_REPORT_AE_SB
AWR_RF_ASYNC_EVENT_MSG2	AWR_MONITOR_TX2_BALLBREAK_REPORT_AE_SB
	AWR_MONITOR_TX_GAIN_PHASE_MISMATCH_REPORT_AE_SB
	AWR_MONITOR_TX0_BPM_REPORT_AE_SB
	AWR_MONITOR_TX1_BPM_REPORT_AE_SB
	AWR_MONITOR_TX2_BPM_REPORT_AE_SB
	AWR_MONITOR_SYNTHESIZER_FREQUENCY_REPORT_AE_SB

Continued on next page

Table 4.1 – continued from previous page

Radar Messages	Associated sub-blocks
	AWR_MONITOR_EXTERNAL_ANALOG_SIGNALSREPORT_AE_SB
	AWR_MONITOR_TX0_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB
	AWR_MONITOR_TX1_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB
	AWR_MONITOR_TX2_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB
	AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB
	AWR_MONITOR_PMCLKLO_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB
	AWR_MONITOR_GPADC_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB
	AWR_MONITOR_PLL_CONTROL_VOLTAGE_REPORT_AE_SB
	AWR_MONITOR_DUAL_CLOCK_COMP_REPORT_AE_SB
	AWR_MONITOR_RX_MIXER_IN_POWER_REPORT_AE_SB
AWR_DEV_RFPOWERUP_MSG	AWR_DEV_RFPOWERUP_SB
AWR_DEV_CONF_SET_MSG	AWR_DEV_MCUCLOCK_CONF_SET_SB
	AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB
	AWR_DEV_RX_DATA_PATH_CONF_SET_SB
	AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB
	AWR_DEV_RX_DATA_PATH_CLK_SET_SB
	AWR_DEV_LVDS_CFG_SET_SB
	AWR_DEV_RX_CONTSTREAMING_MODE_CONF_SET_SB
	AWR_DEV_CSI2_CFG_SET_SB
	AWR_DEV_PMICCLOCK_CONF_SET_SB
	AWR_MSS_LATENTFAULT_TEST_CONF_SB
	AWR_MSS_PERIODICTESTS_CONF_SB
	AWR_DEV_TESTPATTERN_GEN_SET_SB
	AWR_DEV_CONFIGURATION_SET_SB
AWR_DEV_CONF_GET_MSG	AWR_DEV_MCUCLOCK_GET_SB
	AWR_DEV_RX_DATA_FORMAT_CONF_GET_SB
	AWR_DEV_RX_DATA_PATH_CONF_GET_SB
	AWR_DEV_RX_DATA_PATH_LANEEN_GET_SB
	AWR_DEV_RX_DATA_PATH_CLK_GET_SB
	AWR_DEV_LVDS_CFG_GET_SB

Table 4.1 – continued from previous page

Radar Messages	Associated sub-blocks
	AWR_DEV_RX_CONTSTREAMING_MODE_CONF_GET_SB
	AWR_DEV_CSI2_CFG_GET_SB
	AWR_DEV_PMICCLOCK_CONF_GET_SB
	AWR_MSS_LATENTFAULT_TEST_CONF_GET_SB
	AWR_MSS_PERIODICCONF_GET_SB
	AWR_DEV_TESTPATTERN_GEN_GET_SB
AWR_DEV_FILE_DOWNLOAD_MSG	AWR_DEV_FILE_DOWNLOAD_SB
AWR_DEV_FRAME_CONFIG_APPLY_MSG	AWR_DEV_FRAME_CONFIG_APPLY_SB
	AWR_DEV_ADV_FRAME_CONFIG_APPLY_SB
AWR_DEV_STATUS_GET_MSG	AWR_MSSVERSION_GET_SB
	AWR_MSSCPUFAULT_STATUS_GET_SB
	AWR_MSSESMFAULT_STATUS_GET_SB
AWR_DEV_ASYNC_EVENT_MSG	AWR_AE_DEV_MSSPOWERUPDONE_SB
	AWR_AE_DEV_RFPOWERUPDONE_SB
	AWR_AE_MSS_CPUFAULT_SB
	AWR_AE_MSS_ESMFAULT_SB
	AWR_AE_MSS_BOOTERRORSTATUS_SB
	AWR_AE_MSS_LATENTFAULT_TESTREPORT_SB
	AWR_AE_MSS_PERIODICTEST_STATUS_SB
	AWR_AE_MSS_RFERROR_STATUS_SB
	AWR_AE_MSS_VMON_ERRORSTATUS_SB
	AWR_AE_MSS_ADC_DATA_SB

4.2 AWR_ACK_MSG

The AWR_ACK_MSG is sent by the radar transceiver on a successful reception of a command after its CRC check.

Field Name	Number of bytes	Description
SYNC	4	Value = 0xABCDDCBA
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 01 b15:6 MSGID Same as MSGID in the command
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
CRC	Variable	Based on CRCLEN field in FLAGS

4.3 AWR_NACK_MSG

The AWR_NACK_MSG is sent by the radar transceiver if the CRC check of the command fails.

Field Name	Number of bytes	Description
SYNC	4	Value = 0xABCDDCBA
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 10 b15:6 MSGID Same as MSGID in the command
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
CRC	Variable	Based on CRCLEN field in FLAGS

4.4 AWR_ERROR_MSG

The AWR_RF_ERROR_MSG is sent by the radar transceiver on finding errors in the command send by host.

Field Name	Number of bytes	Description
SYNC	4	Value = 0xABCDDCBA
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 01 b15:6 MSGID 0x00
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_RESP_ERROR_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.5 AWR_RF_STATIC_CONF_SET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x04
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_CHAN_CONF_SET_SB AWR_ADCOUT_CONF_SET_SB

		AWR_LOWPOWERMODE_CONF_SET_SB
		AWR_DYNAMICPOWERSAVE_CONF_SET_SB
		AWR_HIGHSPEEDINTFCLK_CONF_SET_SB
		AWR_RF_DEVICE_CFG_SB
		AWR_RF_RADAR_MISC_CTL_SB
		AWR_CAL_MON_FREQUENCY_LIMITS_SB
		AWR_RF_INIT_CALIBRATION_CONF_SB
		AWR_CAL_MON_FREQUENCY_TX_POWER_LIMITS_SB
		AWR_CAL_DATA_RESTORE_SB
		AWR_PHASE_SHIFTER_CAL_DATA_RESTORE_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.6 AWR_RF_STATIC_CONF_GET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x05
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_CAL_DATA_SAVE_SB AWR_PHASE_SHIFTER_CAL_DATA_SAVE_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.7 AWR_RF_INIT_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x06
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_RF_INIT_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.8 AWR_RF_DYNAMIC_CONF_SET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x08
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_PROFILE_CONF_SET_SB AWR_CHIRP_CONF_SET_SB

		AWR_FRAME_CONF_SET_SB
		AWR_CONT_STREAMING_MODE_CONF_SET_SB
		AWR_CONT_STREAMING_MODE_EN_SB
		AWR_ADVANCED_FRAME_CONF_SB
		AWR_PERCHIRPPHASESHIFT_CONF_SB
		AWR_PROG_FILT_COEFF_RAM_SET_SB
		AWR_PROG_FILT_CONF_SET_SB
		AWR_CALIB_MON_TIME_UNIT_CONF_SB
		AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB
		AWR_INTER_RX_GAIN_PHASE_CONTROL_SB
		AWR_RX_GAIN_TEMPLUT_SET_SB
		AWR_TX_GAIN_TEMPLUT_SET_SB
		AWR_LOOPBACK_BURST_CONF_SET_SB
		AWR_DYN_CHIRP_CONF_SET_SB
		AWR_DYN_PERCHIRP_PHASESHIFTER_CONF_SB
		AWR_DYN_CHIRP_ENABLE_SB
		AWR_INTERCHIRP_BLOCKCONTROLS_SB
		AWR_SUBFRAME_START_CONF_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.9 AWR_RF_DYNAMIC_CONF_GET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x09
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message

CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks
		AWR_PROFILE_CONF_GET_SB
		AWR_CHIRP_CONF_GET_SB
		AWR_FRAME_CONF_GET_SB
		AWR_ADVANCED_FRAME_CONF_GET_SB
		AWR_RX_GAIN_TEMPLUT_GET_SB
		AWR_TX_GAIN_TEMPLUT_GET_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.10 AWR_RF_FRAME_TRIG_MSG

Field Name	Number of bytes	Description		
SYNC	4	Value = 0x43211234		
OPCODE	2	Bits	Variable name	Value
		b3:0	DIRECTION	See Table 2.2
		b5:4	MSGTYPE	00
		b15:6	MSGID	0x0A
MSGLEN	2	Length of the message in bytes (do not include sync length)		
FLAGS	2	See Section 2.3.2		
REMCHUNKS	2	Value = 0		
NSBC	2	Number of sub blocks contained in the message		
CHKSUM	2	See Section 2.3.2		
MSGDATA	Variable	Supported sub blocks AWR_FRAMESTARTSTOP_CONF_SB		
CRC	Variable	Based on CRCLEN field in FLAGS		

4.11 AWR_RF_ADVANCED_FEATURES_CONF_SET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x0C
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_BPM_COMMON_CONF_SET_SB AWR_BPM_CHIRP_CONF_SET_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.12 AWR_RF_MONITORING_CONF_SET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x0E
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_MONITOR_RF_DIG_LATENTFAULT_CONF_SB

		AWR_MONITOR_RF_DIG_PERIODIC_CONF_SB
		AWR_MONITOR_ANALOG_ENABLES_CONF_SB
		AWR_MONITOR_TEMPERATURE_SONF_SB
		AWR_MONITOR_RX_GAIN_PHASE_CONF_SB
		AWR_MONITOR_RX_NOISE_FIGURE_CONF_SB
		AWR_MONITOR_RX_IFSTAGE_CONF_SB
		AWR_MONITOR_TX0_POWER_CONF_SB
		AWR_MONITOR_TX1_POWER_CONF_SB
		AWR_MONITOR_TX2_POWER_CONF_SB
		AWR_MONITOR_TX0_BALLBREAK_CONF_SB
		AWR_MONITOR_TX1_BALLBREAK_CONF_SB
		AWR_MONITOR_TX2_BALLBREAK_CONF_SB
		AWR_MONITOR_TX_GAIN_PHASE_MISMATCH_CONF_SB
		AWR_MONITOR_TX0_BPM_CONF_SB
		AWR_MONITOR_TX1_BPM_CONF_SB
		AWR_MONITOR_TX2_BPM_CONF_SB
		AWR_MONITOR_SYNTHESIZER_FREQUENCY_CONF_SB
		AWR_MONITOR_EXTERNAL_ANALOG_SIGNALS_CONF_SB
		AWR_MONITOR_TX0_INTERNAL_ANALOG_SIGNALS_CONF_SB
		AWR_MONITOR_TX1_INTERNAL_ANALOG_SIGNALS_CONF_SB
		AWR_MONITOR_TX2_INTERNAL_ANALOG_SIGNALS_CONF_SB
		AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_CONF_SB
		AWR_MONITOR_PMCLKLO_INTERNAL_ANALOG_SIGNALS_CONF_SB
		AWR_MONITOR_GPADC_INTERNAL_ANALOG_SIGNALS_CONF_SB
		AWR_MONITOR_PLL_CONTROL_VOLTAGE_SIGNALS_CONF_SB
		AWR_MONITOR_DUAL_CLOCK_COMP_CONF_SB
		AWR_MONITOR_RX_SATURATION_DETECTOR_CONF_SB
		AWR_MONITOR_SIG_IMG_MONITOR_CONF_SB
		AWR_MONITOR_RX_MIXER_IN_POWER_CONF_SB
		AWR_ANALOG_FAULT_INJECTION_CONF_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.13 AWR_RF_STATUS_GET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x11
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_RF_VERSION_GET_SB AWR_RF_CPUFAULT_STATUS_GET_SB AWR_RF_ESMFAULT_STATUS_GET_SB AWR_RF_DIEID_GET_SB AWR_RF_BOOTUPBIST_STATUS_GET_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.14 AWR_RF_MONITORING_REPORT_GET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x13

MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_RF_DFE_STATISTICS_REPORT_GET_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.15 AWR_RF_MISC_CONF_SET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x16
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_RF_TEST_SOURCE_CONFIG_SET_SB AWR_RF_TEST_SOURCE_ENABLE_SET_SB AWR_RF_LDO_BYPASS_SB AWR_RF_PALOOPBACK_CFG_SB AWR_RF_PSLOOPBACK_CFG_SB AWR_RF_IFLOOPBACK_CFG_SB AWR_RF_GPADC_CFG_SET_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.16 AWR_RF_MISC_CONF_GET_MSG

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x17
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_RF_TEMPERATURE_GET_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.17 AWR_RF_ASYNC_EVENT_MSG1

The AWR_RF_ASYNC_EVENT_MSG1 is sent by the radar transceiver to the host. This message indicates that specific events have occurred within the device.

Field Name	Number of bytes	Description
SYNC	4	Value = 0xABCDDBCA
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 11 b15:6 MSGID 0x80
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks

		AWR_AE_RF_CPUFAULT_SB
		AWR_AE_RF_ESMFAULT_SB
		AWR_AE_RF_INITCALIBSTATUS_SB
		AWR_AE_RF_FRAME_TRIGGER_RDY_SB
		AWR_AE_RF_GPADC_RESULT_DATA_SB
		AWR_FRAME_END_AE_SB
		AWR_ANALOGFAULT_AE_SB
		AWR_CAL_MON_TIMING_FAIL_REPORT_AE_SB
		AWR_RUN_TIME_CALIBRATION_SUMMARY_REPORT_AE_SB
		AWR_MONITOR_RF_DIG_LATENTFAULT_REPORT_AE_SB
		AWR_MONITOR_REPORT_HEADER_AE_SB
		AWR_MONITOR_RF_DIG_PERIODIC_REPORT_AE_SB
		AWR_MONITOR_TEMPERATURE_REPORT_AE_SB
		AWR_MONITOR_RX_GAIN_PHASE_REPORT_AE_SB
		AWR_MONITOR_RX_NOISE_FIGURE_REPORT_AE_SB
		AWR_MONITOR_RX_IFSTAGE_REPORT_AE_SB
		AWR_MONITOR_TX0_POWER_REPORT_AE_SB
		AWR_MONITOR_TX1_POWER_REPORT_AE_SB
		AWR_MONITOR_TX2_POWER_REPORT_AE_SB
		AWR_MONITOR_TX0_BALLBREAK_REPORT_AE_SB
		AWR_MONITOR_TX1_BALLBREAK_REPORT_AE_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.18 AWR_RF_ASYNC_EVENT_MSG2

The AWR_RF_ASYNC_EVENT_MSG2 is sent by the radar transceiver to the host. This message indicates that specific events have occurred within the device.

Field Name	Number of bytes	Description		
SYNC	4	Value = 0xABCDDBCA		
OPCODE	2	Bits	Variable name	Value
		b3:0	DIRECTION	See Table 2.2
		b5:4	MSGTYPE	11
		b15:6	MSGID	0x81

MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_MONITOR_TX2_BALLBREAK_REPORT_AE_SB AWR_MONITOR_TX_GAIN_PHASE_MISMATCH_REPORT_AE_SB AWR_MONITOR_TX0_BPM_REPORT_AE_SB AWR_MONITOR_TX1_BPM_REPORT_AE_SB AWR_MONITOR_TX2_BPM_REPORT_AE_SB AWR_MONITOR_SYNTHESIZER_FREQUENCY_REPORT_AE_SB AWR_MONITOR_EXTERNAL_ANALOG_SIGNALSREPORT_AE_SB AWR_MONITOR_TX0_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB AWR_MONITOR_TX1_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB AWR_MONITOR_TX2_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB AWR_MONITOR_PMCLKLO_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB AWR_MONITOR_GPADC_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB AWR_MONITOR_PLL_CONTROL_VOLTAGE_REPORT_AE_SB AWR_MONITOR_DUAL_CLOCK_COMP_REPORT_AE_SB AWR_MONITOR_RX_MIXER_IN_POWER_REPORT_AE_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.19 AWR_DEV_RFPOWERUP_MSG

The AWR_DEV_RFPOWERUP_MSG is sent by the host to the MSS. This message indicates that BSS can now be powered up.

Field Name	Number of bytes	Description
SYNC	4	Value = 0xABCDDBCA
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x200
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_DEV_RFPOWERUP_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.20 AWR_DEV_CONF_SET_MSG

The AWR_DEV_CONF_SET_MSG is sent by the host to the radar transceiver. This message indicates that specific events have occurred within the device.

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x202
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_DEV_MCUCLOCK_CONF_SET_SB

		AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB
		AWR_DEV_RX_DATA_PATH_CONF_SET_SB
		AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB
		AWR_DEV_RX_DATA_PATH_CLK_SET_SB
		AWR_DEV_LVDS_CFG_SET_SB
		AWR_DEV_RX_CONTSTREAMING_MODE_CONF_SET_SB
		AWR_DEV_CSI2_CFG_SET_SB
		AWR_DEV_PMICCLOCK_CONF_SET_SB
		AWR_MSS_LATENTFAULT_TEST_CONF_SB
		AWR_MSS_PERIODICTESTS_CONF_SB
		AWR_DEV_TESTPATTERN_GEN_SET_SB
		AWR_DEV_CONFIGURATION_SET_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.21 AWR_DEV_CONF_GET_MSG

The AWR_DEV_CONF_GET_MSG is sent by the host to the radar transceiver to read back the configuration values.

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x203
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_DEV_MCUCLOCK_GET_SB AWR_DEV_RX_DATA_FORMAT_CONF_GET_SB AWR_DEV_RX_DATA_PATH_CONF_GET_SB

		AWR_DEV_RX_DATA_PATH_LANEEN_GET_SB
		AWR_DEV_RX_DATA_PATH_CLK_GET_SB
		AWR_DEV_LVDS_CFG_GET_SB
		AWR_DEV_RX_CONTSTREAMING_MODE_CONF_GET_SB
		AWR_DEV_CSI2_CFG_GET_SB
		AWR_DEV_PMICCLOCK_CONF_GET_SB
		AWR_MSS_LATENTFAULT_TEST_CONF_GET_SB
		AWR_MSS_PERIODICCONF_GET_SB
		AWR_DEV_TESTPATTERN_GEN_GET_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.22 AWR_DEV_FILE_DOWNLOAD_MSG

The AWR_DEV_FILE_DOWNLOAD_MSG is sent by the host to MSS. This message sends a file to be written into the device.

Field Name	Number of bytes	Description		
SYNC	4	Value = 0x43211234		
OPCODE	2	Bits	Variable name	Value
		b3:0	DIRECTION	See Table 2.2
		b5:4	MSGTYPE	00
		b15:6	MSGID	0x204
MSGLEN	2	Length of the message in bytes (do not include sync length)		
FLAGS	2	See Section 2.3.2		
REMCHUNKS	2	Value = 0		
NSBC	2	Number of sub blocks contained in the message		
CHKSUM	2	See Section 2.3.2		
MSGDATA	Variable	Supported sub blocks AWR_DEV_FILE_DOWNLOAD_SB		
CRC	Variable	Based on CRCLEN field in FLAGS		

4.23 AWR_DEV_FRAME_CONFIG_APPLY_MSG

The AWR_DEV_FRAME_CONFIG_APPLY_MSG is sent by the host to MSS. This message indicates to MSS to apply all the regular framing mode configurations related to ADC buffer and CBUFF.

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x206
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_DEV_FRAME_CONFIG_APPLY_SB AWR_DEV_ADV_FRAME_CONFIG_APPLY_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.24 AWR_DEV_STATUS_GET_MSG

The AWR_DEV_STATUS_GET_MSG is sent by the host to MSS to get some status information from the device.

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 00 b15:6 MSGID 0x207
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks

		AWR_MSSVERSION_GET_SB
		AWR_MSSCPUFAULT_STATUS_GET_SB
		AWR_MSSESMFAULT_STATUS_GET_SB
CRC	Variable	Based on CRCLEN field in FLAGS

4.25 AWR_DEV_ASYNC_EVENT_MSG

The AWR_DEV_ASYNC_EVENT_MSG is sent by the radar transceiver to the host. This message indicates that specific events have occurred within the device.

Field Name	Number of bytes	Description
SYNC	4	Value = 0x43211234
OPCODE	2	Bits Variable name Value b3:0 DIRECTION See Table 2.2 b5:4 MSGTYPE 11 b15:6 MSGID 0x280
MSGLEN	2	Length of the message in bytes (do not include sync length)
FLAGS	2	See Section 2.3.2
REMCHUNKS	2	Value = 0
NSBC	2	Number of sub blocks contained in the message
CHKSUM	2	See Section 2.3.2
MSGDATA	Variable	Supported sub blocks AWR_AE_DEV_MSSPOWERUPDONE_SB AWR_AE_DEV_RFPOWERUPDONE_SB AWR_AE_MSS_CPUFAULT_SB AWR_AE_MSS_ESMFAULT_SB AWR_AE_MSS_BOOTERRORSTATUS_SB AWR_AE_MSS_LATENTFAULT_TESTREPORT_SB AWR_AE_MSS_PERIODICTEST_STATUS_SB AWR_AE_MSS_RFERROR_STATUS_SB AWR_AE_MSS_VMON_ERRORSTATUS_SB AWR_AE_MSS_ADC_DATA_SB
CRC	Variable	Based on CRCLEN field in FLAGS

5 Radar Functional APIs

This section describes all the radar interface sub blocks that are used in messages for communicating with the radar transceiver. Some of the sub blocks are status responses from the radar device.

5.1 Sub block related to AWR_ERROR_MSG

5.1.1 Sub block 0x0000 – AWR_RESP_ERROR_SB

This sub block contains the error response for an API command.
Table 5.1 describes the contents of this sub block.

Table 5.1: AWR_RESP_ERROR_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x0000	
SBLKLEN	2	Value = 8	
API_RESP	2	0x0001	ERROR_CMD: Incorrect MSGID
		0x0002	ERROR_CMD: No Sub block found in the MSG
		0x0003	ERROR_CMD: Incorrect Sub block ID
		0x0004	ERROR_CMD: Incorrect Sub block Length
		0x0005	ERROR_CMD: Incorrect Sub block data
		0x0006	ERROR_PROC: Error in processing the command
		0x0007	ERROR_FILECRCMISMATCH: File CRC mismatched
		0x0008	ERROR_FILETYPEMISMATCH: File type mismatched w.r.t. magic number
		0x0009 - 0xFFFF	See Section 6 for details on error codes from each API

API_RESP_ER-ROR_SBC_ID	2	0x0000 Sub-Block ID in which Error Occurred for sub – block related errors 0xFFFF

5.2 Sub blocks related to AWR_RF_STATIC_CONF_SET_MSG

5.2.1 Sub block 0x0080 – AWR_CHAN_CONF_SET_SB

This sub block contains static device configurations (applicable for the given power cycle) - how many RX and TX channels are needed for operation. It also defines static configurations related to whether the sensor uses a single xWR1xxx or multiple xWR1xxx chips to realize a larger antenna array (multiple is applicable only in xWR12xx). Table 5.2 describes the contents of this sub block.

Table 5.2: AWR_CHAN_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0080
SBLKLEN	2	Value = 12

RX_CHAN_EN	2	This field specifies which RX channels are to be enabled
		Bit Description
		b0 RX_CHAN0_EN
		    0 Disable RX Channel 0
		    1 Enable RX Channel 0
		b1 RX_CHAN1_EN
		    0 Disable RX Channel 1
		    1 Enable RX Channel 1
		b2 RX_CHAN2_EN
		    0 Disable RX Channel 2
		    1 Enable RX Channel 2
		b3 RX_CHAN3_EN
		    0 Disable RX Channel 3
		    1 Enable RX Channel 3
		b15:4 RESERVED
		    0b000000000000

Continued on next page

Table 5.2 – continued from previous page

TX_CHAN_EN	2	This field specifies which TX channels are to be enabled
		Bit Description
		b0 TX_CHAN0_EN
		0 Disable TX Channel 0
		1 Enable TX Channel 0
		b1 TX_CHAN1_EN
		0 Disable TX Channel 1
		1 Enable TX Channel 1
		b2 TX_CHAN2_EN
		0 Disable TX Channel 2
		1 Enable TX Channel 2
		b15:3 RESERVED
		0b000000000000
CASCADING_CFG	2	This field specifies the cascading configuration.
		Value Description
		0x0000 SINGLECHIP: Single xWR1xxx sensor application
		0x0001 MULTICHIP_MASTER: Multiple xWR12xx sensor application. This xWR12xx is the master chip and generates LO and conveys to other xWR12xx's in the sensor. This is applicable only in xWR12xx.
		0x0002 MULTICHIP_SLAVE: Multiple xWR12x sensor application. This AWR12xx is a slave chip and uses LO conveyed to it by the master xWR12xx in the sensor. This is applicable only in xWR12xx.
		MULTICHIP_MASTER and MULTICHIP_SLAVE are in general referred to as MULTICHIP applications, where larger antenna array sizes are possible in comparison with SINGLECHIP cases.

Table 5.2 – continued from previous page

		Bit	Description
CASCADING_PINOUTCFG	2	b0	FM_CW_CLKOUT_MASTER_DIS Applicable only in MUTICHIP_MASTER device. Default value is 0 0 Enable FM_CW_CLKOUT on master 1 Disable FM_CW_CLKOUT on master
		b1	FM_CW_SYNCOUT_MASTER_DIS Applicable only in MULTICHIP_MASTER device. Default value is 0 0 Enable FM_CW_SYNCOUT on master 1 Disable FM_CW_SYNCOUT on master
		b2	FM_CW_CLKOUT_SLAVE_EN Applicable only in MULTICHIP_SLAVE device. Default value is 0 0 Disable FM_CW_CLKOUT on slave 1 Enable FM_CW_CLKOUT on slave
		b3	FM_CW_SYNCOUT_SLAVE_EN Applicable only in MULTICHIP_SLAVE device. Default value is 0 0 Disable FM_CW_SYNCOUT on slave 1 Enable FM_CW_SYNCOUT on slave
		b4	INTLO_MASTER_EN Applicable only in MULTICHIP_MASTER device. Default value is 0 0 Use externally looped back LO 1 Use internal LO in master Note that the externally looped-back LO mode is useful when length-matching the 20 GHz path between master and slave device.
		b5	OSCCLKOUT_MASTER_DIS Applicable only in MULTICHIP_MASTER device. Default value is 0 0 Enable OSCCLKOUT in master 1 Disable OSCCLKOUT in master
		b15:6	RESERVED

5.2.2 Sub block 0x0082 – AWR_ADCOUT_CONF_SET_SB

This sub block contains static device configurations (applicable for the given power cycle) - regarding the data format of the ADC output (including the digital filtering).
Table 5.3 describes the contents of this sub block.

Table 5.3: AWR_ADCOUT_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0082
SBLKLEN	2	Value = 12

NUM_ADC_BITS	1	Bit Description
		
		b1:0 Value Definition
		      00 12 bits
		      01 14 bits
		      10 16 bits
		      Other RESERVED
		b7:2 RESERVED
		      0b000000

FULL_SCALE_ REDUCTION_ FACTOR	1	Number of bits to reduce ADC full scale by Valid range: 0 to (16 − Number of ADC bits) For e.g. for 12 bit ADC output, this field can take values 0, 1, 2 or 3 For 14 bit ADC output, this field can take values 0, 1 or 2 For 16 bit ADC output, this field can take only value 0 **Example:** If the user desires 12 bit ADC output, then the digital front end (DFE) chain drops 4 LSBs before placing the data in ADC buffer (DFE output is 16 bits wide). If the user sets FULL_SCALE_REDUCTION_FACTOR as 1, then the DFE will drop only 3 LSBs but still restricting the data in ADC buffer to be within $\pm 2^{12}$. This allows wider ADC swings in smaller signal conditions.

ADC_OUT_FMT	2	Bits Description
		
		b1:0 Value Definition
		      00 Real
		      01 Complex 1x (image band filtered out)
		      10 Complex 2x (image band visible)
		      11 Pseudo Real
		b15:2 RESERVED
		      0b00000000000000

RESERVED	2	0x0000
RESERVED	2	0x0000

5.2.3 Sub block 0x0083 – AWR_LOWPOWERMODE_CONF_SET_SB

This sub block contains static device configurations (applicable for this power cycle) - Sigma Delta ADC root sampling clock rate (reducing rate to half to save power in small IF bandwidth applications).
Table 5.4 describes the contents of this sub block.

Table 5.4: AWR_LOWPOWERMODE_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0083
SBLKLEN	2	Value = 8
RESERVED	2	0x0000
LP_ADC_MODE	2	Value Definition 0x00 Regular ADC mode 0x01 Low power ADC mode

NOTE:	Low power ADC mode is mandatory on a 5 MHz part variant (for e.g. xWR1642).

5.2.4 Sub block 0x0084 – AWR_DYNAMICPOWERSAVE_CONF_SET_SB

This sub block defines static device configuration - whether to enable dynamic power saving during inter-chirp IDLE times by turning off various circuits e.g. TX, RX, LO Distribution blocks. If Idle time + Tx start time < 10us or Idle time < 3.5us then inter-chirp dynamic power save option will be disabled, in that case, 15us of inter-burst idle time will be utilized to configure sequencer LO, TX and RX signal timings by firmware.
Table 5.4 describes the contents of this sub block.

Table 5.5: AWR_DYNAMICPOWERSAVE_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0084
SBLKLEN	2	Value = 8

Table 5.5 – continued from previous page

BLOCK_CFG	2	Bits	Definition
		b0	Enable power save by switching off TX during inter-chirp IDLE period
			0 Disable
			1 Enable
			Default value: 1 (power saving is enabled)
		b1	Enable power save by switching off RX during inter-chirp IDLE period
			0 Disable
			1 Enable
			Default value: 1 (power saving is enabled)
		b2	Enable power save by switching off LO Distribution blocks during inter-chirp IDLE period
			0 Disable
			1 Enable
			Default value: 1 (power saving is enabled)
		b15:3	RESERVED
			0b0000000000000
RESERVED	2	0x0000	

5.2.5 Sub block 0x0085 – AWR_HIGHSPEEDINTFCLK_CONF_SET_SB

This sub block contains static device configurations (applicable for the given power cycle) - regarding high speed interface clock rates which are related to sending the ADC data from AWR device to the host in either LVDS or CSI2 format.

Table 5.6 describes the contents of this sub block.

Table 5.6: AWR_HIGHSPEEDINTFCLK_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0085
SBLKLEN	2	Value = 8

Table 5.6 – continued from previous page

HSICLKRATE_CODE	2	This field indicates the high speed interface input clock rate, needed by the LVDS or CSI2 module. It should be N times the final serial data rate, where $N = 2$ in DDR mode and $N = 1$ in SDR mode. Bit 15:5 = Reserved (all 0). Bit 3:0 are to be set based on desired rate as follows: (see sub-table below) For example, for 900 Mbps output rate with DDR, choose Bit3:0=0b1101, and for 450 Mbps output rate with SDR, choose Bit3:0=0b0110.
RESERVED	2	0x0000

	b1:0 00	b1:0 01	b1:0 10	b1:0 11
b3:2 00	Reserved	800 MHz	400 MHz	200 MHz
b3:2 01	Reserved	900 MHz	450 MHz	225 MHz
b3:2 10	Reserved	1200 MHz	600 MHz	300 MHz
b3:2 11	Reserved	1800 MHz	Reserved	Reserved

5.2.6 Sub block 0x0086 – AWR_RF_DEVICE_CFG_SB

This sub block configures the direction of async event from BSS. Typically async events are sent to MSS. With this API, the user can configure the destination of async event.
Table 5.7 describes the contents of this sub block.

Table 5.7: AWR_RF_DEVICE_CFG_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0086
SBLKLEN	2	Value = 16

Table 5.7 – continued from previous page

RF_AE_DIREC-TION	4	Bits	Definition
		b1:0	ASYNC_EVENT_DIR
			00 BSS to MSS
			01 BSS to HOST
			10 BSS to DSS
			11 RESERVED
			The ASYNC_EVENT_DIR controls the direction for following ASYNC_EVENTS
			1. CPU_FAULT
			2. ESM_FAULT
			3. ANALOG_FAULT
			All other ASYNC_EVENTs are sent to the subsystem which issues the API
			Default value: 0b00
		b3:2	MONITORING_ASYNC_EVENT_DIR
			00 BSS to MSS
			01 BSS to HOST
			10 BSS to DSS
			11 RESERVED
			Default value: 0b00
		b31:4	RESERVED
			0x0000000
AE_CONTROL	1	Bits	Definition
		b0	FRAME_START_ASYNC_EVENT_DIS
			0 Frame Start async event enable
			1 Frame Start async event disable
			Default value: 0
		b1	FRAME_STOP_ASYNC_EVENT_DIS
			0 Frame Stop async event enable
			1 Frame Stop async event disable
			Default value: 0
		b7:2	RESERVED
			0b000000
RESERVED	2	0x0000	

Continued on next page

Table 5.7 – continued from previous page

BSS_DIG_CTRL	1	Bits	Definition	
		b0	WDT_DISABLE	
			0	Keep watchdog disabled
			1	Enable watch dog
		b7:1	RESERVED	
			0b0000000	
ASYNC_EVENT_CRC_CONFIG	1	Value	Description	
		0	16 bit CRC for BSS async events	
		1	32 bit CRC for BSS async events	
		2	64 bit CRC for BSS async events	
RESERVED	3	0x000000		

5.2.7 Sub block 0x0087 – AWR_RF_RADAR_MISC_CTL_SB

This sub block controls miscellaneous global RF controls for e.g. per-chirp phase shifter global control.

Table 5.8 describes the contents of this sub block.

Table 5.8: AWR_RF_MISC_CTL_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x0087	
SBLKLEN	2	Value = 12	
RF_MISC_CTL	4	Bits	Definition
		b0	PERCHIRP_PHASESHIFTER_EN
			0 Per chirp phase shifter is disabled
			1 Per chirp phase shifter is enabled
			This control is applicable only in devices which support phase shifter (refer data sheet). For other devices, this is a RESERVED bit and should be set to 0.
			Default value: 0
		b31:1	RESERVED
			0b000_0000_0000_0000_0000_0000_0000_0000
RESERVED	4	0x00000000	

5.2.8 Sub block 0x0088 – AWR_CAL_MON_FREQUENCY_LIMITS_SB

This sub block sets the limits for RF frequency transmission.
Table 5.9 describes the contents of this sub block.

Table 5.9: AWR_CAL_MON_FREQUENCY_LIMITS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0088
SBLKLEN	2	Value = 16
FREQ_LIMIT_LOW	2	The sensor's lower frequency limit for calibrations and monitoring is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 100 MHz Valid range: 760 to 810 Default value: 760
FREQ_LIMIT_HIGH	2	The sensor's higher frequency limit for calibrations and monitoring is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 100 MHz Valid range: 760 to 810 Default value: 810 **NOTE:** FREQ_LIMIT_HIGH should be strictly greater than FREQ_LIMIT_LOW Examples: For an LRR device deployed in the US, one might typically configure FREQ_LIMIT_LOW to 760 and FREQ_LIMIT_HIGH to 770.
RESERVED	8	RESERVED 0x0000_0000_0000_0000

5.2.9 Sub block 0x0089 – AWR_RF_INIT_CALIBRATION_CONF_SB

This sub block configures device to perform boot time calibration.
Table 5.10 describes the contents of this sub block.

Table 5.10: AWR_RF_INIT_CALIBRATION_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0089
SBLKLEN	2	Value = 16

Table 5.10 – continued from previous page

RF_INIT_CALIB_ENABLE_MASK	4	Normally, upon receiving RF INIT message, the BSS performs all relevant initial calibrations. This step can be disabled by the host by setting the corresponding calibration bit in this field to 0x0. If disabled, the host needs to send the INJECT CALIB DATA message so that the BSS can operate using the calibration data thus injected.
		Internal/Debug use: Each of these calibrations can be selectively disabled by issuing this message before RF INIT message.
		Bit Definition
		b0 RESERVED
		b1 RESERVED
		b2 RESERVED
		b3 RESERVED
		b4 Enable LODIST calibration
		b5 Enable RX ADC DC offset calibration
		b6 Enable HPF cutoff calibration
		b7 Enable LPF cutoff calibration
		b8 Enable Peak detector calibration
		b9 Enable TX power calibration
		b10 Enable RX gain calibration
		b11 Enable TX Phase calibration (Device dependent feature, please refer data sheet)
		b12 Enable RX IQMM calibration
		b31:13 RESERVED
		0b000_0000_0000_0000_0000
		Default value: 0x1FF0
		NOTE: If TX power calibration is disabled, then backoff other than 0 dB is not supported
RESERVED	4	0x00000000
RESERVED	4	0x00000000

5.2.10 Sub block 0x008A – AWR_CAL_MON_FREQUENCY_TX_POWER_LIMITS_SB

This sub block sets the limits for RF frequency transmission for each TX and also TX power limits.

Table 5.11: AWR_CAL_MON_FREQUENCY_TX_POWER_LIMITS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x008A
SBLKLEN	2	Value = 28
FREQ_LIMIT_LOW_TX0	2	The sensor's lower frequency limit for calibrations and monitoring for TX0 is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 10 MHz Valid range: 7600 to 8100 Default value: 7600
FREQ_LIMIT_LOW_TX1	2	The sensor's lower frequency limit for calibrations and monitoring for TX1 is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 10 MHz Valid range: 7600 to 8100 Default value: 7600
FREQ_LIMIT_LOW_TX2	2	The sensor's lower frequency limit for calibrations and monitoring for TX2 is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 10 MHz Valid range: 7600 to 8100 Default value: 7600
FREQ_LIMIT_HIGH_TX0	2	The sensor's higher frequency limit for calibrations and monitoring for TX0 is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 10 MHz Valid range: 7600 to 8100 Default value: 8100 **NOTE:** FREQ_LIMIT_HIGH_TXn should be strictly greater than FREQ_LIMIT_LOW_TXn
FREQ_LIMIT_HIGH_TX1	2	The sensor's higher frequency limit for calibrations and monitoring for TX1 is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 10 MHz Valid range: 7600 to 8100 Default value: 8100 **NOTE:** FREQ_LIMIT_HIGH_TXn should be strictly greater than FREQ_LIMIT_LOW_TXn

Continued on next page

Table 5.11 – continued from previous page

FREQ_LIMIT_HIGH_TX2	2	The sensor's higher frequency limit for calibrations and monitoring for TX2 is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 10 MHz Valid range: 7600 to 8100 Default value: 8100 **NOTE:** FREQ_LIMIT_HIGH_TXn should be strictly greater than FREQ_LIMIT_LOW_TXn
TX0_POWER_BACKOFF	1	TX0 output power back off 1 LSB = 1 dB Valid values: 0, 3, 6, 9 Default value: 0
TX1_POWER_BACKOFF	1	TX1 output power back off 1 LSB = 1 dB Valid values: 0, 3, 6, 9 Default value: 0
TX2_POWER_BACKOFF	1	TX2 output power back off 1 LSB = 1 dB Valid values: 0, 3, 6, 9 Default value: 0
RESERVED	1	0x00
RESERVED	2	0x0000
RESERVED	2	0x0000
RESERVED	2	0x0000
RESERVED	2	0x0000

5.2.11 Sub block 0x008B – AWR_CAL_DATA_RESTORE_SB

This sub block restores the calibration data which was stored previously using the AWR_CAL_DATA_SAVE_SB command. The async event AWR_AE_RF_INITCALIBSTATUS_SB will be issued after this API indicating that the calibration data is applied.

Table 5.12: AWR_CAL_DATA_RESTORE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x008B
SBLKLEN	2	Value = 232
RESERVED	2	0x0000
CHUNK_ID	2	Index of the current chunk

Table 5.12 – continued from previous page

CAL_DATA	224	Calibration data which was stored in non-volatile memory

5.2.12 Sub block 0x008C – AWR_PHASE_SHIFTER_CAL_DATA_RESTORE_SB

This sub block restores the calibration data which was stored previously using the AWR_PHASE_SHIFTER_CAL_DATA_SAVE_SB command.

Table 5.13: AWR_PHASE_SHIFTER_CAL_DATA_RESTORE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x008C
SBLKLEN	2	Value = 136
TX_INDX	1	Index of the transmit channel for which the following data applies
CAL_APPLY	1	Set this to 1 after applying calibration data from all transmitters. This bit will indicate to the firmware to start the correction process.
OBS_PHSHIFT_DATA	128	Observed phase shift corresponding to each desired phase shift. Index n corresponds to desired phase shift of $n \times 5.625°$. For e.g. {| | n | **Desired phase shift** | **Observed phase shift is injected in the following bytes** | | 0 | 0.000° | byte[1], byte[0] | | 1 | 5.625° | byte[3], byte[2] | | 2 | 11.250° | byte[5], byte[4] | | 3 | 16.875° | byte[7], byte[6] | | ⋮ | ⋮ | | | 63 | 354.375° | byte[127], byte[126] |} 1 LSB $= 360°/2^{10}$
RESERVED	2	0x0000

The OBS_PHSHIFT_DATA cell contains the following sub-table:

n	Desired phase shift	Observed phase shift is injected in the following bytes
0	0.000°	byte[1], byte[0]
1	5.625°	byte[3], byte[2]
2	11.250°	byte[5], byte[4]
3	16.875°	byte[7], byte[6]
⋮	⋮	
63	354.375°	byte[127], byte[126]

1 LSB $= 360°/2^{10}$

5.3 Sub blocks related to AWR_RF_STATIC_CONF_GET_MSG

5.3.1 Sub block 0x00A0 – 0x00AA – RESERVED

5.3.2 Sub block 0x00AB – AWR_CAL_DATA_SAVE_SB

This sub block reads the calibration data from the device which can be injected later using the AWR_CAL_DATA_RESTORE_SB command.

Table 5.14: AWR_CAL_DATA_SAVE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x00AB
SBLKLEN	2	Value = 8
RESERVED	2	0x0000
CHUNK_ID	2	Index of the requested chunk Valid values: 0 to NUM_CHUNKS - 1

Response to the above command will contain the calibration data which is formatted as shown below

Table 5.15: AWR_CAL_DATA_SAVE_SB response packet contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x00AB
SBLKLEN	2	Value = 232
NUM_CHUNKS	2	Total number of calibration data chunks
CHUNK_ID	2	Current chunk number
CAL_DATA	224	Calibration data

5.3.3 Sub block 0x00AC – AWR_PHASE_SHIFTER_CAL_DATA_SAVE_SB

This sub block reads the phase shifter calibration data from the device which can be injected later using the AWR_PHASE_SHIFTER_CAL_DATA_RESTORE_SB command.

Table 5.16: AWR_PHASE_SHIFTER_CAL_DATA_SAVE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x00AC
SBLKLEN	2	Value = 8
TX_INDX	1	Index of the transmitter channel for which the phase shift is desired
RESERVED	3	0x000000

Response to the above command will contain the phase shifter calibration data which is formatted as shown below

Table 5.17: AWR_PHASE_SHIFTER_CAL_DATA_SAVE_SB response packet contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x00AC
SBLKLEN	2	Value = 136
TX_INDX	1	Index of the transmitter channel for which the following phase shift values applies
RESERVED	1	0x00
OBS_PHSHIFT_DATA	128	Observed phase shift corresponding to each desired phase shift. Index n corresponds to desired phase shift of $n \times 5.625°$. For e.g. | n	Desired phase shift	Observed phase shift is read in the following bytes
0	0.000°	byte[1], byte[0]
1	5.625°	byte[3], byte[2]
2	11.250°	byte[5], byte[4]
3	16.875°	byte[7], byte[6]
⋮	⋮	
63	354.375°	byte[127], byte[126] | 1 LSB = $360°/2^{10}$
RESERVED	2	0x0000

5.4 Sub blocks related to AWR_RF_INIT_MSG

5.4.1 Sub block 0x00C0 – AWR_RF_INIT_SB

This sub block, needed to be initially issued, triggers one time calibrations such as those related to APLL and synthesizer. The BSS processor is woken up upon receiving this sub block, the RF analog and digital baseband sections are initialized.
Table 5.18 describes the content of this sub block.

Table 5.18: AWR_RF_INIT_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x00C0
SBLKLEN	2	Value = 4

NOTE:	This sub block will be acknowledged immediately but an async event AWR_AE_RF_INITCALIBSTATUS_SB from BSS will indicate that the RF initialization is complete. No commands shall be sent to BSS till the async event is received.

5.5 Sub blocks related to AWR_RF_DYNAMIC_CONF_SET_MSG

5.5.1 Sub block 0x0100 – AWR_PROFILE_CONF_SET_SB

This sub block contains FMCW radar chirp profiles or properties (FMCW slope, chirp duration, TX power etc.). Since the device supports multiple profiles, each profile is defined in this sub block. Internal RF and analog calibrations may be triggered upon receiving this sub block and ASYNC_EVENT response sent once completed.

NOTE:	This API can be issued dynamically to change profile parameters. Few parameters which cannot be changed are

1. PF_NUM_ADC_SAMPLES

2. PF_DIGITAL_OUTPUT_SAMPLING_RATE

3. Programmable filter coefficients in xWR1642 or xWR1843

Table 5.19 describes the contents of this sub block.

Table 5.19: AWR_PROFILE_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0100
SBLKLEN	2	Value = 48
PF_INDX	2	The profile index for which the rest of the fields are applicable for

PF_VCO_SE-LECT	1	Bit Description
		
		b0 FORCE_VCO_SEL
		
		    0 Use internal VCO selection
		
		    1 Forced external VCO selection
		
		b1 VCO_SEL
		
		    0 VCO1 (76 - 78 GHz)
		
		    1 VCO2 (77 – 81 GHz)
		
		NOTE: There is an overlap region of 77-78 GHz in which any of the VCOs can be used, for other regions use only the VCO which can work in that region. For e.g. for 76-77 GHz use only VCO1 and for 78-81GHz use only VCO2, for 77-78 GHz, any VCO can be used. Also note that users should not inter-mix chirps from different VCOs within the same frame.
		
		b7:2 RESERVED
		
		    0b000000

PF_CALLUT_UPDATE	1	Bit Description
		
		b0 RETAIN_TXCAL_LUT
		
		    0 Update TX calibration LUT
		
		    1 Do not update TX calibration LUT
		
		b1 RETAIN_RXCAL_LUT
		
		    0 Update RX calibration LUT and update RX IQMM correction
		
		    1 Do not update RX calibration LUT
		
		b7:2 RESERVED (set it to 0b000000)
		
		If PF_TX_OUTPUT_POWER_BACKOFF is changed then set RETAIN_TXCAL_LUT to 0, else set it to 1 and if PF_RX_GAIN or if sweep bandwidth is changed, then set RETAIN_RXCAL_LUT to 0 else set them to 1

Continued on next page

Table 5.19 – continued from previous page

PF_FREQ_START_CONST	4	Start frequency for this profile 1 LSB = $3.6e9/2^{26}$ Hz $\approx$ 53.644 Hz Valid range: 0x5471C71B to 0x5A000000
PF_IDLE_TIME_CONST	4	Idle time for each profile 1 LSB = 10 ns Valid range: 0 to 524287
PF_ADC_START_TIME_CONST	4	Time of starting of ADC capture relative to the knee of the ramp 1 LSB = 10 ns Valid range: 0 to 4095
PF_RAMP_END_TIME	4	End of ramp time relative to the knee of the ramp 1 LSB = 10 ns Valid range: 0 to 500000 Ensure that the total frequency sweep is either within 76-78 GHz or 77-81 GHz
PF_TX_OUT-PUT_POWER_BACKOFF	4	Bits Description b7:0 TX0 output power back off b15:8 TX1 output power back off b23:16 TX2 output power back off b31:24 RESERVED (set it to 0x00) This field defines how much the transmit power should be reduced from the maximum. 1 LSB = 1 dB **NOTE:** For best inter-TX channel matching performance, same chirp profile and same TX backoff value should be used for all the TXs that are used in beam-forming

PF_TX_PHASE_SHIFTER	4	Bits Description
		b1:0 RESERVED (set it to 0b00)
		b7:2 TX0 phase shift value
		       1 LSB = $360°/2^6 \approx 5.625°$
		b9:8 RESERVED (set it to 0b00)
		b15:10 TX1 phase shift value
		       1 LSB = $360°/2^6 \approx 5.625°$
		b17:16 RESERVED (set it to 0b00)
		b23:18 TX2 phase shift value
		       1 LSB = $360°/2^6 \approx 5.625°$
		b31:24 RESERVED
		       0x00
		This field defines the additional phase shift to be introduced on each transmitter output.

Table 5.19 – continued from previous page

PF_FREQ_SLOPE_CONST	2	Frequency slope for each profile is encoded in 2 bytes (16 bit signed number) 1 LSB = $3.6e9 \times 900/2^{26}$ Hz ≈ 48.279 kHz/μs Valid range: -2072 to 2072
PF_TX_START_TIME	2	Time of start of transmitter relative to the knee of the ramp 1 LSB = 10 ns Valid range: -4096 to 4095 Positive numbers refer to start of TX after knee of the ramp and negative numbers refer to start of TX before the knee of the ramp
PF_NUM_ADC_SAMPLES	2	Number of ADC samples to capture in a chirp for each RX Valid range: 2 to MAX_NUM_SAMPLES, where MAX_NUM_SAMPLES is such that all the enabled RX channels' data fits into 16 kB memory in xWR1243/xWR1443 or 32 kB memory in xWR1642/xWR1843, with each sample consuming 2 bytes for real ADC output case and 4 bytes for complex 1x and complex 2x ADC output cases. For example in xWR1243/ xWR1443 when the ADC buffer size is 16 kB
		<table><tr><th>Number of RX chains</th><th>ADC format</th><th>MAX_NUM_ SAMPLES</th></tr><tr><td>4</td><td>Complex</td><td>1024</td></tr><tr><td>4</td><td>Real</td><td>2048</td></tr><tr><td>2</td><td>Complex</td><td>2048</td></tr><tr><td>2</td><td>Real</td><td>4096</td></tr></table>
PF_DIGITAL_OUTPUT_SAM-PLING_RATE	2	ADC Sampling rate for this profile is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 1 ksps Valid range 2000 to 37500
PF_HPF1_COR-NER_FREQ	1	HPF1 corner frequency for each profile is encoded in 1 byte Value HPF1 corner frequency definition 0x00 175 kHz 0x01 235 kHz 0x02 350 kHz 0x03 700 kHz
PF_HPF2_COR-NER_FREQ	1	HPF2 corner frequency for each profile is encoded in 1 byte

Table 5.19 – continued from previous page

		Value	HPF2 corner frequency definition
		0x00	350 kHz
		0x01	700 kHz
		0x02	1.4 MHz
		0x03	2.8 MHz
TX_CAL_EN_CFG	2	Number of transmitters to turn on during TX power calibration. During actual operation, if more than 1 TXs are enabled during the chirp, then enabling the same TXs during calibration will have better TX output power accuracy	
		Bit	Definition
		b2:0	TX enabled during TX0 calibration b0 - TX0, b1 - TX1, b2 - TX2
		b5:3	TX enabled during TX1 calibration b3 - TX0, b4 - TX1, b5 - TX2
		b8:6	TX enabled during TX2 calibration b6 - TX0, b7 - TX1, b8 - TX2
		b14:9	RESERVED
		b15	Enable multi TX enable during TX power calibration If this bit is not set, only 1 TX is enabled during the TX power calibration. For e.g. during TX0 calibration, only TX0 will be enabled; during TX1 calibration, only TX1 will be enabled and so on
PF_RX_GAIN	2	Bit	Definition
		b5:0	RX_GAIN This field defines RX gain for each profile. 1 LSB = 1 dB Valid values: all even values from 24 to 52
		b7:6	RF_GAIN_TARGET
			Value RF gain target
			00 30 dB
			01 34 dB
			10 RESERVED
			11 26 dB
		b15:8	RESERVED (set it to 0x00)

Continued on next page

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		The total RX gain is achieved as a sum of RF gain and IF amplifiers gain. The RF Gain target (30 dB, 34 dB and 26 dB) allows the user to control the RF gain independently from the total RX gain, thus giving flexibility to the user to trade-off linearity vs. noise figure. Out of multiple gain settings for the RF stages, the firmware calibration algorithm uses the one that makes the RF gain as close as possible to the user programmed RF Gain Target.
RESERVED	2	0x0000

Table 5.20: Note on maximum sampling rate

NOTE:				
	The maximum sampling rate supported is limited based on the information in the table below			

When device supports 15 MHz IF bandwidth (refer device data sheet)

	Real/Pseudo Real	Complex1x	Complex2x
Regular ADC mode	37.5 Msps	18.75 Msps	37.5 Msps
Low power ADC mode	18.75 Msps	9.375 Msps	18.75 Msps

When device supports 10 MHz IF bandwidth (refer device data sheet)

	Real/Pseudo Real	Complex1x	Complex2x
Regular ADC mode	25 Msps	12.5 Msps	25 Msps
Low power ADC mode	18.75 Msps	9.375 Msps	18.75 Msps

When device supports 5 MHz IF bandwidth (refer device data sheet)

	Real/Pseudo Real	Complex1x	Complex2x
Regular ADC mode	12.5 Msps	6.25 Msps	12.5 Msps
Low power ADC mode	12.5 Msps	6.25 Msps	12.5 Msps

- The IF bandwidth here refers to the IF frequency of the farthest reflection desired to be detected

- Typically, the IF frequency range preserved well in the receiver baseband is $0.9 \times$ Sampling Rate in Complex 1x and $0.45 \times$ Sampling Rate in Complex 2x and Real/Pseudo Real.

- The maximum sampling rates are also subject to restrictions from LVDS/CSI2 interface rate and ADC bits configurations. Typically in Complex2x mode, the maximum sampling rate would be 25 Msps

5.5.2 Sub block 0x0101 – AWR_CHIRP_CONF_SET_SB

This sub block contains chirp to chirp variations on top of the chirp profiles defined in the AWR_PROFILE_CONF_SET_SB. E.g. which profile is to be used for each chirp in a frame, and small dithers in FMCW start frequency and idle time for each chirp are possible to be defined here. The dithers used in this configuration sub block are only additive on top of programmed parameters in AWR_PROFILE_CONF_SET_SB.

Table 5.21 describes the contents of this sub block.

Table 5.21: AWR_CHIRP_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0101
SBLKLEN	2	Value = 24
CHIRP_START_INDX	2	Valid range 0 to 511
CHIRP_END_INDX	2	Valid range CHIRP_START_INDX to 511
PROFILE_INDX	2	Valid range 0 to 3
RESERVED	2	0x0000
CHIRP_FREQ_START_VAR	4	1 LSB = $3.6e9/2^{26} \approx 53.644$ Hz Valid range: 0 to 8388607
CHIRP_FREQ_SLOPE_VAR	2	1 LSB = $3.6e9 \times 900/2^{26} \approx 48.279$ kHz Valid range: 0 to 63
CHIRP_IDLE_TIME_VAR	2	Idle time of each chirp is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 10 ns Valid range: 0 to 4095
CHIRP_ADC_START_TIME_VAR	2	ADC start time of each chirp is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 10 ns Valid range: 0 to 4095
CHIRP_TX_EN	2	TX enable selection Bit Definition b0 TX0 Enable b1 TX1 Enable b2 TX2 Enable b15:3 RESERVED 0b0_0000_0000_0000 **NOTE:** Maximum number of TXs that can be turned on in a chirp depends on the device data sheet specification

5.5.3 Sub block 0x0102 – AWR_FRAME_CONF_SET_SB

This sub block defines a frame, i.e. a sequence of chirps to be transmitted subsequently, the no. of frames to be transmitted, frame periodicity and how to trigger them.
Table 5.22 describes the contents of this sub block.

Table 5.22: AWR_FRAME_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0102
SBLKLEN	2	Value = 28
RESERVED	2	May use to indicate Frame mode or Continuous chirping mode of operation.
CHIRP_START_INDX	2	Valid range 0 to 511
CHIRP_END_INDX	2	Valid range CHIRP_START_INDX to 511
NUM_LOOPS	2	Number of times to repeat from CHIRP_START_INDX to CHIRP_END_INDX in each frame Valid range 1 to 255
NUM_FRAMES	2	Number of frames to transmit This field is ignored and internally assumed as 1 if this xWR1xxx is configured as MULTICHIP_SLAVE in AWR_CHAN_CONF_SB. 16 bit unsigned number Valid range: 0 to 65535 (0 for infinite frames)
RESERVED	2	0x0000
FRAME_PERIOD-ICITY	4	1 LSB = 5 ns Valid range: 40000 + (1 chirp duration) to 268400000 This is the frame repetition period.

Table 5.22 – continued from previous page

TRIGGER_SE-LECT	2	Value	Definition
		0x0001	SWTRIGGER (Software API based triggering): Frame is triggered upon receiving AWR_FRAMESTARTSTOP_CONF_SB. There could be several tens of micro seconds uncertainty in triggering. This mode is not applicable if this xWR1xx is configured as MULTICHIP_SLAVE in AWR_CHAN_CONF_SB.
		0x0002	HWTRIGGER (Hardware SYNC_IN based triggering): Each frame is triggered by rising edge of pulse in SYNC_IN pin, after receiving AWR_FRAMESTARTSTOP_CONF_SB (this is to prevent spurious transmission). W.r.t. the SYNC_IN pulse, the actual transmission has 5ns uncertainty in SINGLECHIP and only a 300 ps uncertainty (due to tight inter-chip synchronization needed) in MULTICHIP sensor applications as defined in AWR_CHAN_CONF_SB.
RESERVED	2	0x0000	
FRAME_TRIG-GER_DELAY	4	Optional time delay from the SYNC_IN trigger to the occurrence of frame chirps. Applicable only in SINGLECHIP sensor applications, as defined in AWR_CHAN_CONF_SB. It is recommended only for staggering the transmission of multiple radar sensors around the car for interference avoidance, if needed. Typical range is 0 to few tens of micro seconds. Units: 1 LSB = 5 ns	

NOTE1:	If hardware triggered mode is used, the SYNC_IN pulse width should be less than the ON time of the frame (in case of legacy frame config mode) or the ON time of the burst (in case of advanced frame config mode). Also, the minimum pulse width of SYNC_IN should be 25 ns.
NOTE2:	If frame trigger delay is used with hardware triggered mode, then external SYNC_IN pulse periodicity should take care of the configured frame trigger delay and frame periodicity. The external pulse should be issued only after the sum total of frame trigger delay and frame periodicity. See figure below
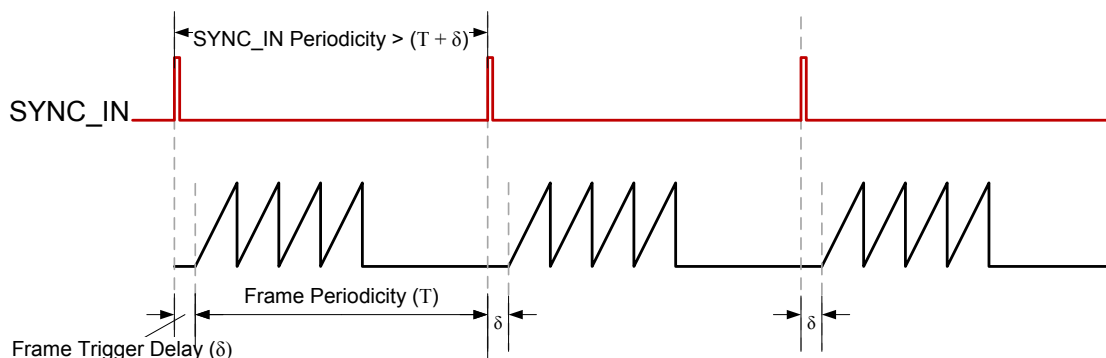
Figure 5.1: Frame trigger delay in case of external hardware trigger

NOTE:	The inter-frame blank time should be at least 250 μs. (100 μs for frame preparation and 150 μs for any calibration updates to hardware)
	Add 150 μs to inter-frame blank time for test source configuration if test source is enabled.

5.5.4 Sub block 0x0103 – AWR_CONT_STREAMING_MODE_CONF_SET_SB

This sub block contains configuration needed to enable continuous streaming mode from the device.

Table 5.23 describes the contents of this sub block.

Table 5.23: AWR_CONT_STREAMING_MODE_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0103
SBLKLEN	2	Value = 24
PF_FREQ_START_CONST	4	Frequency start for each profile is encoded in 4 bytes (32 bit unsigned number) 1 LSB = $3.6e9/2^{26}$ Hz ≈ 53.644 Hz Valid range: 0 to 0x7FFFFFFF

Table 5.23 – continued from previous page

PF_TX_OUT-PUT_POWER_BACKOFF	4	Bits	Description
		b7:0	TX0 output power back off
		b15:8	TX1 output power back off
		b23:16	TX2 output power back off
		b31:24	RESERVED (set it to 0x00) This field defines how much the transmit power should be reduced from the maximum. 1 LSB = 1 dB
PF_TX_PHASE_SHIFTER	4	Bits	Description
		b1:0	RESERVED (set it to 0b00)
		b7:2	TX0 phase shift value 1 LSB $= 360°/2^6 \approx 5.625°$
		b9:8	RESERVED (set it to 0b00)
		b15:10	TX1 phase shift value 1 LSB $= 360°/2^6 \approx 5.625°$
		b17:16	RESERVED (set it to 0b00)
		b23:18	TX2 phase shift value 1 LSB $= 360°/2^6 \approx 5.625°$
		b31:24	RESERVED 0x00 This field defines the additional phase shift to be introduced on each transmitter output.
PF_DIGITAL_OUTPUT_SAM-PLING_RATE	2	ADC Sampling rate for each profile is encoded in 2 bytes (16 bit unsigned number) 1 LSB = 1 ksps Valid range 2000 to 37500	
PF_HPF1_COR-NER_FREQ	1	HPF1 corner frequency for each profile is encoded in 1 byte	
		Value	HPF1 corner frequency definition
		0x00	175 kHz
		0x01	235 kHz
		0x02	350 kHz
		0x03	700 kHz

Table 5.23 – continued from previous page

PF_HPF2_COR-NER_FREQ	1	HPF2 corner frequency for each profile is encoded in 1 byte Value HPF2 corner frequency definition 0x00 350 kHz 0x01 700 kHz 0x02 1.4 MHz 0x03 2.8 MHz

PF_RX_GAIN	1	This field defines RX gain for continuous streaming mode.
		
		Bit Definition
		
		5:0 RX_GAIN
		        This field defines RX gain for each profile.
		        1 LSB = 1 dB
		        Valid values: all even values from 24 to 52
		
		7:6 RF_GAIN_TARGET
		        Value RF gain target
		
		        00 30 dB
		
		        01 34 dB
		
		        10 RESERVED
		
		        11 26 dB
		
		The total RX gain is achieved as a sum of RF gain and IF amplifiers gain. The RF Gain target (30 dB, 34 dB and 26 dB) allows the user to control the RF gain independently from the total RX gain, thus giving flexibility to the user to trade-off linearity vs. noise figure. Out of multiple gain settings for the RF stages, the firmware calibration algorithm uses the one that makes the RF gain as close as possible to the user programmed RF Gain Target.

VCO_SELECT	1	Bit Description
		
		b0 FORCE_VCO_SEL
		        0 Use internal VCO selection
		
		        1 Forced external VCO selection
		
		b1 VCO_SEL
		        0 VCO1 (76 - 78 GHz)
		
		        1 VCO2 (77 - 81 GHz)
		
		b7:2 RESERVED
		        0b00_0000

RESERVED	2	0x0000

NOTE:	Continuous streaming (CW) mode is useful for RF lab characterization and debug. In this mode, the device is configured to transmit a single continuous wave (CW - 0 slope) tone at a specific RF frequency continuously.

5.5.5 Sub block 0x0104 – AWR_CONT_STREAMING_MODE_EN_SB

This sub block contains configuration needed to enable continuous streaming mode from the device.

Table 5.24 describes the contents of this sub block.

Table 5.24: AWR_CONT_STREAMING_MODE_EN_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0104
SBLKLEN	2	Value = 8
CONT_STREAM-ING_EN	2	Value Definition 0x0000 Disable continuous streaming mode 0x0001 Enable continuous streaming mode
RESERVED	2	0x0000

5.5.6 Sub block 0x0105 – AWR_ADVANCED_FRAME_CONF_SB

This sub block contains advanced frame configuration options.

Table 5.25 describes the contents of this sub block.

Table 5.25: AWR_ADVANCED_FRAME_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0105
SBLKLEN	2	Value = 152
NUM_SUB-FRAMES	1	Number of sub frames enabled in this frame Valid range: 1 to 4

Continued on next page

Table 5.25 – continued from previous page

FORCE_SINGLE_ PROFILE	1	Value	Definition
		0x0	The profile index set in Chirp Config API message governs which profile is used when that chirp is transmitted
		0x1	The profile index indicated in Chirp Config message is ignored and all the chirps in each sub frame use a single profile as indicated by that sub frame's profile index set in this message.
LOOPBACK_CFG	1	Bit	Definition
		b0	LOOPBACK_CFG_EN
			0 Disable
			1 Enable
		b2:1	SUB_FRAME_ID Sub frame ID for which the loopback configuration applies
		b7:3	RESERVED
SUB_ FRAMETRIG- GER	1	0	Disabled (default)
		1	Enabled (Need to trigger each sub-frame either by SW in software triggered mode or HW in hardware triggered mode)
SF1_PROFILE_ INDX	2	This is applicable only if FORCE_SINGLE_PROFILE is set to 1. Please refer to that field for description. Valid range: 0 to 3 Not applicable for loop-back sub-frame	
SF1_CHIRP_ START_INDX	2	Start index of the first chirp for the first burst in sub frame 1 Valid range: 0 to 511 Not applicable for loop-back sub-frame	
SF1_NUM_ UNIQUE_ CHIRPS_PER_ BURST	2	Number of unique chirps per burst Valid range: 1 to 512 Not applicable for loop-back sub-frame	
SF1_NUM_ LOOPS_PER_ BURST	2	Number of times to loop through the unique chirps in each burst, without gaps, using HW. Valid range: 1 to 255	

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Table 5.25 – continued from previous page

SF1_BURST_PERIOD	4	BURST_PERIOD ≥(NUM_LOOPS_PER_BURST×(Sum total of all unique chirp times per burst) + *InterBurstBlankTime*, where *InterBurstBlankTime* is primarily for sensor calibration / monitoring, thermal control, and some minimum time needed for triggering next burst. InterBurstBlankTime ≥ 100 μs With loopback enabled, InterBurstBlankTime ≥ 350 μs **NOTE:** Across bursts, if the value (Sum total of all unique chirp times per burst), is not a constant, then the actual available blank time can vary and needs to be accounted for. 1 LSB = 5 ns Valid range: 100 μs to 1.342 s
SF1_CHIRP_START_INDX_OFFSET	2	The chirp start index for each burst is determined as the chirp start index of the previous burst plus SFx_START_INDX_OFFSET × BURST_INDX i.e. CHIRP_START_INDX = SFx_CHIRP_START_INDX + (SFx_CHIRP_START_INDX_OFFSET × BURST_INDEX) Valid range: 0 to 511 A value of 0 can be used to repeat the same set of unique chirps across bursts. Non-zero values allow spanning a larger number of unique chirps (across bursts). Not applicable for loop-back sub-frame
SF1_NUM_BURSTS	2	Number of bursts constituting this sub frame Valid range: 1 to 512 Not applicable for loop-back sub-frame
SF1_NUM_OUTER_LOOPS	2	Number of times to loop over the set of above defined bursts, for this sub frame. Valid range: 1 to 64 Not applicable for loop-back sub-frame
RESERVED	2	0x0000

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SF1_PERIOD	4	PERIOD $\geq$ Sum total time of all bursts + *InterSubFrameBlankTime*, where, Sum total time of all bursts = Num Outer Loops * Num Bursts * Burst Period. *InterSubFrameBlankTime* is primarily for sensor calibration/monitoring, thermal control, transferring out any safety monitoring data if requested, hardware reconfiguration for next sub frame, retriggering of next SF. InterSubFrameBlankTime $\geq$ 100 μs With loopback enabled, InterSubFrameBlankTime $\geq$ 350 μs Add 150 μs to *InterSubFrameBlankTime* for test source configuration if test source is enabled. 1 LSB = 5 ns Valid range 100 μs to 1.342 s
RESERVED	4	0x00000000
RESERVED	4	0x00000000
SF2_PROFILE_INDX	2	This is applicable only if FORCE_SINGLE_PROFILE is set to 1. Please refer to that field for description. Valid range: 0 to 3
SF2_CHIRP_START_INDX	2	Start index of the first chirp for the first burst in sub frame 2 Valid range: 0 to 511
SF2_NUM_UNIQUE_CHIRPS_PER_BURST	2	Number of unique chirps per burst Valid range: 1 to 512
SF2_NUM_LOOPS_PER_BURST	2	Number of times to loop through the unique chirps in each burst, without gaps, using HW. Valid range: 1 to 255
SF2_BURST_PERIOD	4	BURST_PERIOD $\geq$ (NUM_LOOPS_PER_BURST)*(Sum total of all unique chirp times per burst) + *InterBurstBlankTime*, where *InterBurstBlankTime* is primarily for sensor calibration / monitoring, thermal control, and some minimum time needed for triggering next burst. InterBurstBlankTime $\geq$ 100 μs With loopback enabled, InterBurstBlankTime $\geq$ 350 μs **NOTE:** Across bursts, if the value (Sum total of all unique chirp times per burst), is not a constant, then the actual available blank time can vary and needs to be accounted for. 1 LSB = 5 ns

Table 5.25 – continued from previous page

SF2_CHIRP_START_INDX_OFFSET	2	The chirp start index for each burst is determined as the chirp start index of the previous burst plus SFx_START_INDX_OFFSET * BURST_INDX i.e. CHIRP_START_INDX = SFx_CHIRP_START_INDX + (SFx_CHIRP_START_INDX_OFFSET $\times$ BURST_INDEX) Valid range: 0 to 511 A value of 0 can be used to repeat the same set of unique chirps across bursts. Non-zero values allow spanning a larger number of unique chirps (across bursts).
SF2_NUM_BURSTS	2	Number of bursts constituting this sub frame Valid range: 1 to 512
SF2_NUM_OUTER_LOOPS	2	Number of times to loop over the set of above defined bursts, for this sub frame. Valid range: 1 to 64
RESERVED	2	0x0000
SF2_PERIOD	4	PERIOD $\geq$ Sum total time of all bursts + *InterSubFrameBlankTime*, Where, Sum total time of all bursts = Num Outer Loops * Num Bursts * Burst Period. *InterSubFrameBlankTime* is primarily for sensor calibration / monitoring, thermal control, transferring out any safety monitoring data if requested, hardware reconfiguration for next sub frame, retriggering of next SF. *InterSubFrameBlankTime* $\geq$ 100 μs With loopback enabled, InterSubFrameBlankTime $\geq$ 350 μs Add 150 μs to *InterSubFrameBlankTime* for test source configuration if test source is enabled. 1 LSB = 5 ns Valid range: 100 μs to 1.342 s
RESERVED	4	0x00000000
RESERVED	4	0x00000000
SF3_PROFILE_INDX	2	This is applicable only if FORCE_SINGLE_PROFILE is set to 1. Please refer to that field for description. Valid range: 0 to 3
SF3_CHIRP_START_INDX	2	Start index of the first chirp in this sub frame Valid range: 0 to 511
SF3_NUM_UNIQUE_CHIRPS_PER_BURST	2	Number of unique chirps per burst Valid range: 1 to 512

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SF3_NUM_LOOPS_PER_BURST	2	Number of times to loop through the unique chirps in each burst, without gaps, using HW. Valid range: 1 to 255
SF3_BURST_PERIOD	4	BURST_PERIOD ≥(NUM_LOOPS_PER_BURST)*(Sum total of all unique chirp times per burst) + *InterBurstBlankTime*, where *InterBurstBlankTime* is primarily for sensor calibration / monitoring, thermal control, and some minimum time needed for triggering next burst. InterBurstBlankTime ≥ 100 μs With loopback enabled, InterBurstBlankTime ≥ 350 μs **NOTE:** Across bursts, if the value (Sum total of all unique chirp times per burst), is not a constant, then the actual available blank time can vary and needs to be accounted for. 1 LSB = 5 ns
SF3_CHIRP_START_INDX_OFFSET	2	The chirp start index for each burst is determined as the chirp start index of the previous burst plus SFx_START_INDX_OFFSET * BURST_INDX i.e. CHIRP_START_INDX = SFx_CHIRP_START_INDX + (SFx_CHIRP_START_INDX_OFFSET × BURST_INDEX) Valid range: 0 to 511 A value of 0 can be used to repeat the same set of unique chirps across bursts. Non-zero values allow spanning a larger number of unique chirps (across bursts).
SF3_NUM_BURSTS	2	Number of bursts constituting this sub frame Valid range: 1 to 512
SF3_NUM_OUTER_LOOPS	2	Number of times to loop over the set of above defined bursts, for this sub frame. Valid range: 1 to 64
RESERVED	2	0x0000

Table 5.25 – continued from previous page

SF3_PERIOD	4	PERIOD $\geq$ Sum total time of all bursts + *InterSubFrameBlankTime*, Where, Sum total time of all bursts = Num Outer Loops * Num Bursts * Burst Period. *InterSubFrameBlankTime* is primarily for sensor calibration / monitoring, thermal control, transferring out any safety monitoring data if requested, hardware reconfiguration for next sub frame, retriggering of next SF. *InterSubFrameBlankTime* $\geq$ 100 μs With loopback enabled, InterSubFrameBlankTime $\geq$ 350 μs Add 150 μs to *InterSubFrameBlankTime* for test source configuration if test source is enabled. 1 LSB = 5 ns Valid range: 100 μs to 1.342 s
RESERVED	4	0x00000000
RESERVED	4	0x00000000
SF4_PROFILE_INDX	2	This is applicable only if FORCE_SINGLE_PROFILE is set to 1. Please refer to that field for description. Valid range: 0 to 3
SF4_CHIRP_START_INDX	2	Start index of the first chirp in this sub frame Valid range: 0 to 511
SF4_NUM_UNIQUE_CHIRPS_PER_BURST	2	Number of unique chirps per burst Valid range: 1 to 512
SF4_NUM_LOOPS_PER_BURST	2	Number of times to loop through the unique chirps in each burst, without gaps, using HW. Valid range: 1 to 255
SF4_BURST_PERIOD	4	BURST_PERIOD $\geq$ (NUM_LOOPS_PER_BURST)*(Sum total of all unique chirp times per burst) + *InterBurstBlankTime*, where *InterBurstBlankTime* is primarily for sensor calibration / monitoring, thermal control, and some minimum time needed for triggering next burst. InterBurstBlankTime $\geq$ 100 μs With loopback enabled, InterBurstBlankTime $\geq$ 350 μs **NOTE:** Across bursts, if the value (Sum total of all unique chirp times per burst), is not a constant, then the actual available blank time can vary and needs to be accounted for. 1 LSB = 5 ns

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SF4_CHIRP_START_INDX_OFFSET	2	The chirp start index for each burst is determined as the chirp start index of the previous burst plus SFx_START_INDX_OFFSET * BURST_INDX i.e. CHIRP_START_INDX = SFx_CHIRP_START_INDX + (SFx_CHIRP_START_INDX_OFFSET $\times$ BURST_INDEX) Valid range: 0 to 511 A value of 0 can be used to repeat the same set of unique chirps across bursts. Non-zero values allow spanning a larger number of unique chirps (across bursts).
SF4_NUM_BURSTS	2	Number of bursts constituting this sub frame Valid range: 1 to 512
SF4_NUM_OUTER_LOOPS	2	Number of times to loop over the set of above defined bursts, for this sub frame. Valid range: 1 to 64
RESERVED	2	0x0000
SF4_PERIOD	4	SF_PERIOD $\geq$ Sum total time of all bursts + *InterSubFrameBlankTime*, where, Sum total time of all bursts = Num Outer Loops * Num Bursts * Burst Period. *InterSubFrameBlankTime* is primarily for sensor calibration / monitoring, thermal control, transferring out any safety monitoring data if requested, hardware reconfiguration for next sub frame, retriggering of next SF. *InterSubFrameBlankTime* $\geq$ 100 μs With loopback enabled, InterSubFrameBlankTime $\geq$ 350 μs Add 150 μs to *InterSubFrameBlankTime* for test source configuration if test source is enabled. 1 LSB = 5 ns Valid range: 100 μs to 1.342 s
RESERVED	4	0x00000000
RESERVED	4	0x00000000
NUM_FRAMES	2	Number of frames to transmit (1 frame = all enabled sub frames). If set to 0, frames are transmitted endlessly till Frame Stop message is received. Valid range: 0 to 65535

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TRIGGER_SE-LECT	2	0x0001 SWTRIGGER (Software API based triggering): Frame is triggered upon receiving AWR_FRAMESTARTSTOP_CONF_SB. There could be several tens of micro seconds uncertainty in triggering. This mode is not applicable if this xWR1xx is configured as MULTICHIP_SLAVE in AWR_CHAN_CONF_SB.
		0x0002 HWTRIGGER (Hardware SYNC_IN based triggering): Each frame is triggered by rising edge of pulse in SYNC_IN pin, after receiving AWR_FRAMESTARTSTOP_CONF_SB (this is to prevent spurious transmission). w.r.t. the SYNC_IN pulse, the actual transmission has 5ns uncertainty in SINGLECHIP and only a 300 ps uncertainty (due to tight inter-chip synchronization needed) in MULTICHIP sensor applications as defined in AWR_CHAN_CONF_SB.
FRAME_TRIG-GER_DELAY	4	Optional time delay from the SYNC_IN trigger to the occurrence of frame chirps. Applicable only in SINGLECHIP sensor applications, as defined in AWR_CHAN_CONF_SB. It is recommended only for staggering the transmission of multiple radar sensors around the car for interference avoidance, if needed. Typical range is 0 to few tens of micro seconds. Units: 1 LSB = 5 ns
RESERVED	4	0x00000000
RESERVED	4	0x00000000

NOTE: If hardware trigger mode is used with advanced frame configuration with SUBFRAMETRIGGER = 0, then the trigger should be issued for each burst. With SUBFRAMETRIGGER = 1, then the trigger needs to be issued for each sub-frame.

5.5.7 Sub block 0x0106 – AWR_PERCHIRPPHASESHIFT_CONF_SB

This sub block defines static phase shift configurations per chirp in each of the TXs. The API is applicable only in xWR1243P. This API will be honored after enabling PERCHIRP_PHASESHIFTER_EN in AWR_RF_RADAR_MISC_CTL_SB.

Table 5.26 describes the contents of this sub block.

Table 5.26: AWR_PERCHIRPPHASESHIFT_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0106
SBLKLEN	2	Value = 12
CHIRP_START_INDX	2	Start index of the chirp for configuring the phase shifter Valid range 0 to 511
CHIRP_END_INDX	2	End index of the chirp for configuring the phase shifter Valid range 0 to 511

TX0_PHASE_SHIFTER	1	TX0 phase shift value
		Bits TX0 phase shift definition
		b1:0 RESERVED (set it to 0b00)
		b7:2 TX0 phase shift value
		        1 LSB $= 360°/2^6 = 5.625°$
		        Valid range: 0 to 63

TX1_PHASE_SHIFTER	1	TX1 phase shift value
		Bits TX1 phase shift definition
		b1:0 RESERVED (set it to 0b00)
		b7:2 TX1 phase shift value
		        1 LSB $= 360°/2^6 = 5.625°$
		        Valid range: 0 to 63

TX2_PHASE_SHIFTER	1	TX2 phase shift value
		Bits TX2 phase shift definition
		b1:0 RESERVED (set it to 0b00)
		b7:2 TX2 phase shift value
		        1 LSB $= 360°/2^6 = 5.625°$
		        Valid range: 0 to 63

RESERVED	1	0x00

NOTE: Phase shifters are applied at the knee of the ramp.

5.5.8 Sub block 0x0107 – AWR_PROG_FILT_COEFF_RAM_SET_SB

This sub block can be used to program the coefficients for the external programmable filter. The API is applicable only in xWR1642 or xWR1843.

Note that the programmable filter is applicable in Complex 1X and Real-only output modes for sampling rates under 6.25 Msps (Complex 1X) and under 12.5 Msps (Real). This is to allow for a trade-off between digital filter chain setting time and close-in anti-alias attenuation. A real-coefficient FIR with up to 26 taps (16-bit coefficients) is supported in the Complex 1X output

mode, and a real-coefficient FIR with up to 20 taps (16-bit coefficients) in supported in the Real output mode

NOTE:	This API should be issued before AWR_PROFILE_CONF_SET_SB.

Table 5.27 describes the contents of this sub block.

Table 5.27: AWR_PROG_FILT_COEFF_RAM_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0107
SBLKLEN	2	Value = 212
COEFF_ARRAY	208	The array of coefficients for the programmable filter, across all profiles, to be stored in the coefficient RAMS. Each tap is a 16-bit signed <1.15, s> number. The exact set of taps to be used for a given profile can be specified through AWR_PROG_FILT_CONF_SB **NOTE:** All the filter taps across profiles are to be provided in one shot. There is a HW constraint that each profile's filter taps should start at four 32-bit word aligned address (i.e., the coefficients corresponding to any profile should start at array index which is a multiple of 8). Unused coefficients shall be initialized to zero.

5.5.9 Sub block 0x0108 – AWR_PROG_FILT_CONF_SET_SB

This sub block can be used to configure the coefficients for the external programmable filter and associate them to a certain profile. The API is applicable only in xWR1642 or xWR1843. This API should be issued before AWR_PROFILE_CONF_SET_SB.
Table 5.28 describes the contents of this sub block.

Table 5.28: AWR_PROG_FILT_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0108
SBLKLEN	2	Value = 8
PROFILE_INDX	1	This field indicates the profile Index for which this configuration applies.

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PROG_FILT_ COEFF_START_ INDEX	1	The index of the first coefficient of the programmable filter taps corresponding to this profile in the coefficient RAM programmed using AWR_PROG_FILT_COEFF_SET_SB **NOTE:** The profile's filter tap start index shall be 8 tap aligned (four 32-bit word aligned address).
PROG_FILT_ LENGTH	1	The length (number of taps) of the filter corresponding to this profile. Together with the previous field, this determines the set of coefficients picked up from the coefficient RAM to form the filter taps for this profile. **NOTE:** This has to be an even number. For odd-length filters, a 0 (zero) tap needs to be appended at the end to make the length even. This is a HW constraint.
PROG_FILT_ FREQ_SHIFT_ FACTOR	1	Relevant only for the Complex 1x output mode with the programmable filter. Determines the magnitude of the frequency shift do be done before filtering using the real-coefficient programmable filter. 1 LSB = 0.01 × Fs shift, where Fs is the output sampling rate, specified as PF_DIGITAL_OUTPUT_SAMPLING_RATE in AWR_PROFILE_CONF_SET_SB

NOTE1:	PROG_FILT_COEFF_START_INDEX should be 8 tap aligned (four 32-bit word aligned address)
NOTE2:	Programmable filter APIs (AWR_PROG_FILT_COEFF_RAM_SET_SB and AWR_PROG_FILT_CONF_SET_SB) should not be issued when frames are ongoing.

5.5.10 Sub block 0x0109 – AWR_CALIB_MON_TIME_UNIT_CONF_SB

This API sub block is used to set calibration and monitoring time unit.

Table 5.29: AWR_CALIB_MON_TIME_UNIT_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0109
SBLKLEN	2	Value = 12

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CALIB_MON_TIME_UNIT	2	Defines the basic time unit, in terms of which calibration and/or monitoring periodicities are to be defined. If any monitoring functions are desired and enabled, the monitoring infrastructure automatically inherits this time unit as the period over which the various monitors are cyclically executed; so this should be set to the desired FTTI. For calibrations, a separate CALIB_PERIODICITY can be specified, as a multiple of this time unit, in AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB **NOTE:** Even though calibrations many not be desired every time unit, every time unit shall be made long enough to include active chirping time, time required for all enabled calibrations and monitoring functions. 1 LSB = Duration of one frame Recommendation: See examples in Section 9 Default value: 100
NUM_OF_CAS-CADED_DEV	1	Applicable only in cascaded mode. In non-cascaded mode set this to 1 Default value: 1
DEVICE_ID	1	Applicable only in cascaded mode. In non-cascaded mode set this to 0 Default value: 0
RESERVED	4	0x0000_0000

5.5.11 Sub block 0x010A – AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB

This API is used to trigger one time calibrations instantaneously or schedule periodic run time time calibrations which will be scheduled by the firmware while framing during any available idle slot of 200 μs.

Table 5.30: AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x010A
SBLKLEN	2	Value = 24

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Table 5.30 – continued from previous page

ONE_TIME_ CALIB_ENABLE_ MASK	4	Upon receiving this trigger message, one time calibration of various RF/analog aspects are triggered if the corresponding bits in this field are set to 1. The response is in the form of an asynchronous event sent to the host. The calibrations, if enabled, are performed after the completion of any ongoing calibration cycle, and the calibration results take effect from the frame that begins after the asynchronous event response is sent from the BSS. APLL and SYNTH calibrations are done always internally irrespective of bits are enabled or not, the time required for these calibrations must be allocated.

Bit	Definition
b0	RESERVED
b1	RESERVED
b2	RESERVED
b3	RESERVED
b4	LODIST_CALIBRATION_EN
b5	RESERVED
b6	RESERVED
b7	RESERVED
b8	PD_CALIBRATION_EN
b9	TX_POWER_CALIBRATION_EN
b10	RX_GAIN_CALIBRATION_EN
b11	RESERVED
b12	RESERVED
b31:13	RESERVED 0b0000_0000_0000_0000_000

Default value: 0

Table 5.30 – continued from previous page

PERICODIC_ CALIB_ENABLE_ MASK	4	Automatic periodic triggering of calibrations of various RF/analog aspects can be set up by the host issuing this message with corresponding bits in this field set to 1.

Bit   Definition

b0   RESERVED

b1   RESERVED

b2   RESERVED

b3   RESERVED

b4   LODIST_CALIBRATION_EN

b5   RESERVED

b6   RESERVED

b7   RESERVED

b8   PD_CALIBRATION_EN

b9   TX_POWER_CALIBRATION_EN

b10   RX_GAIN_CALIBRATION_EN

b11   RESERVED

b12   RESERVED

b31:13   RESERVED

APLL and SYNTH calibrations are done always internally (at a periodicity of 1 second) irrespective of bits are enabled or not, the time required for these calibrations must be allocated. Refer to Table 9.2 for the duration of run time calibrations

Default value: 0

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Table 5.30 – continued from previous page

CALIBRATION_PERIODICITY	4	This field is applicable only for those calibrations which are enabled to be done periodically in the PERIODIC_CALIB_ENABLE_MASK field. This field indicates the desired periodicity of calibrations. If this field is set to N, the results of the first calibration (based on ONE_TIME_CALIB_ENABLE_MASK) are applicable for the first N CALIB_MON_TIME_UNITs. The results of the next calibration are applicable for the next N CALIB_MON_TIME_UNITs, and so on. **Recommendation:** Set CALIBRATION_PERIODICITY such that frequency of calibrations is greater than or equal to 1 second. 1 LSB = 1 CALIB_MON_TIME_UNIT, as specified in AWR_CALIB_MON_TIME_UNIT_CONF_SB. If the user does not wish to receive calibration reports when periodic calibrations are not enabled, then the user should set CALIBRATION_PERIODICITY to 0 Default value: 0

ENABLE_CAL_REPORT	1	Bit Definition
		
		 b0 ENABLE_SUMMARY_REPORT
		        0 Summary reports are disabled
		        1 Summary reports are enabled
		 Default value: 0
		
		 b7:1 RESERVED
		 NOTE1: If calibration reports are enabled, the reports will be sent every 1 second whenever internal calibrations (APLL and SYNTH) are triggered and at every CALIBRATION_PERIODICITY when the user enabled calibrations are triggered.
		 NOTE2: If user has not enabled any one time calibrations, but if calibration report is enabled, then after issuing this API, the firmware will attempt to run the APLL and SYNTH calibrations and the calibration report will be immediately sent out.

RESERVED	1	0x00

Table 5.30 – continued from previous page

TX_POWER_ CAL_MODE	1	Bit	Definition
		b0	TX_POWER_CAL_MODE
			0 Update TX gain setting from LUT and do a closed loop calibration (OLPC + CLPC)
			1 Update TX gain settings from LUT only (OLPC only) OLPC: Open Loop Power Control. In this mode the TX stage codes are set based on a coarse measurement and a LUT generated for every temperature and the stage codes are picked from the LUT CLPC: Closed Loop Power Control. In this mode the TX stage codes are picked from the coarse LUT as generated in OLPC step. Later the TX power is measured and the TX stage codes are corrected to achieve the desired TX power accuracy. Default value: 0
		b7:1	RESERVED
RESERVED	1	0x00	
RESERVED	4	0x00000000	

> **NOTE:** The API AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_ SB should be issued when the device is not framing

5.5.12 Sub block 0x010B – AWR_INTER_RX_GAIN_PHASE_CONTROL_SB

This API can be used to induce different gain/phase offsets on the different RXs, for inter-RX mismatch compensation.

Table 5.31: AWR_INTER_RX_GAIN_PHASE_CONTROL_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x010B
SBLKLEN	2	Value = 28
PROFILE_INDX	1	This field indicates the profile Index for which this configuration applies.
RESERVED	3	0x000000

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Table 5.31 – continued from previous page

DIGITAL_GAIN	4	One byte per RX (8-bit signed number) Bits Assignment b7:0 RX0 digital gain b15:8 RX1 digital gain b23:16 RX2 digital gain b31:24 RX3 digital gain 1 LSB = 0.1 dB Valid Range: -120 to 119
DIGITAL_PHASE_SHIFT	8	Two bytes per RX Bits Assignment b15:0 RX0 digital phase shift b31:16 RX1 digital phase shift b47:32 RX2 digital phase shift b63:48 RX3 digital phase shift 1 LSB = $360°/2^{16} \approx 0.0055°$ Valid Range: 0 to 65535 **NOTE:** This field is NOT applicable when ADC_OUT_FMT is 00 (real output)
RESERVED	8	0x00000000

5.5.13 Sub block 0x010C – AWR_RX_GAIN_TEMPLUT_SET_SB

This API can be used to overwrite the RX gain temperature LUT used in firmware. This API should be issued after profile configuration API.

Table 5.32: AWR_RX_GAIN_TEMPLUT_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x010C
SBLKLEN	2	Value = 28
PROFILE_INDX	1	This field indicates the profile Index for which this configuration applies.
RESERVED	1	0x00

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Table 5.32 – continued from previous page

RX_GAIN_CODE	19	Byte0:	RX gain code for temperature $<$-30 °C
		Byte1:	RX gain code for temperature [-30, -20) °C
		Byte2:	RX gain code for temperature [-20, -10) °C
		Byte3:	RX gain code for temperature [-10, 0) °C
		Byte4:	RX gain code for temperature [0, 10) °C
		Byte5:	RX gain code for temperature [10, 20) °C
		Byte6:	RX gain code for temperature [20, 30) °C
		Byte7:	RX gain code for temperature [30, 40) °C
		Byte8:	RX gain code for temperature [40, 50) °C
		Byte9:	RX gain code for temperature [50, 60) °C
		Byte10:	RX gain code for temperature [60, 70) °C
		Byte11:	RX gain code for temperature [70, 80) °C
		Byte12:	RX gain code for temperature [80, 90) °C
		Byte13:	RX gain code for temperature [90, 100) °C
		Byte14:	RX gain code for temperature [100, 110) °C
		Byte15:	RX gain code for temperature [110, 120) °C
		Byte16:	RX gain code for temperature [120, 130) °C
		Byte17:	RX gain code for temperature [130, 140) °C
		Byte18:	RX gain code for temperature $\geq$140 °C
		Each byte is encoded as follows	
		Bits	Definition
		b4:0	IF_GAIN_CODE
			IF gain is IF_GAIN_CODE $\times 2 - 6$ dB
			Valid values: 0 to 17
			1 LSB = 2 dB
		b7:5	RF_GAIN_CODE
			Value RF Gain
			0 Maximum RF gain
			1 Maximum RF gain $-$ 2 dB
			2 Maximum RF gain $-$ 4 dB
			3 Maximum RF gain $-$ 6 dB
			4 Maximum RF gain $-$ 8 dB
RESERVED	1	0x00	
RESERVED	2	0x0000	

5.5.14 Sub block 0x010D – AWR_TX_GAIN_TEMPLUT_SET_SB

This API can be used to overwrite the TX gain temperature LUT used in firmware. This API should be issued after profile configuration API.

Table 5.33: AWR_TX_GAIN_TEMPLUT_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x010D
SBLKLEN	2	Value = 68
PROFILE_INDX	1	This field indicates the profile Index for which this configuration applies
RESERVED	1	0x00
TX0_GAIN_CODE	19	Byte0: TX0 gain code for temperature $<$-30 °C
		Byte1: TX0 gain code for temperature [-30, -20) °C
		Byte2: TX0 gain code for temperature [-20, -10) °C
		Byte3: TX0 gain code for temperature [-10, 0) °C
		Byte4: TX0 gain code for temperature [0, 10) °C
		Byte5: TX0 gain code for temperature [10, 20) °C
		Byte6: TX0 gain code for temperature [20, 30) °C
		Byte7: TX0 gain code for temperature [30, 40) °C
		Byte8: TX0 gain code for temperature [40, 50) °C
		Byte9: TX0 gain code for temperature [50, 60) °C
		Byte10: TX0 gain code for temperature [60, 70) °C
		Byte11: TX0 gain code for temperature [70, 80) °C
		Byte12: TX0 gain code for temperature [80, 90) °C
		Byte13: TX0 gain code for temperature [90, 100) °C
		Byte14: TX0 gain code for temperature [100, 110) °C
		Byte15: TX0 gain code for temperature [110, 120) °C
		Byte16: TX0 gain code for temperature [120, 130) °C
		Byte17: TX0 gain code for temperature [130, 140) °C
		Byte18: TX0 gain code for temperature $\geq$140 °C
		Each byte is encoded as follows
		Bits Definition
		b5:0 STG_CODE Higher values for higher gain
		b7:6 RESERVED
RESERVED	1	0x00

Table 5.33 – continued from previous page

TX1_GAIN_CODE	19	Byte0:	TX1 gain code for temperature $<$-30 °C
		Byte1:	TX1 gain code for temperature [-30, -20) °C
		Byte2:	TX1 gain code for temperature [-20, -10) °C
		Byte3:	TX1 gain code for temperature [-10, 0) °C
		Byte4:	TX1 gain code for temperature [0, 10) °C
		Byte5:	TX1 gain code for temperature [10, 20) °C
		Byte6:	TX1 gain code for temperature [20, 30) °C
		Byte7:	TX1 gain code for temperature [30, 40) °C
		Byte8:	TX1 gain code for temperature [40, 50) °C
		Byte9:	TX1 gain code for temperature [50, 60) °C
		Byte10:	TX1 gain code for temperature [60, 70) °C
		Byte11:	TX1 gain code for temperature [70, 80) °C
		Byte12:	TX1 gain code for temperature [80, 90) °C
		Byte13:	TX1 gain code for temperature [90, 100) °C
		Byte14:	TX1 gain code for temperature [100, 110) °C
		Byte15:	TX1 gain code for temperature [110, 120) °C
		Byte16:	TX1 gain code for temperature [120, 130) °C
		Byte17:	TX1 gain code for temperature [130, 140) °C
		Byte18:	TX1 gain code for temperature $\geq$140 °C
		Each byte is encoded as follows	
		Bits	Definition
		b5:0	STG_CODE
			Higher values for higher gain
		b7:6	RESERVED
RESERVED	1	0x00	

Table 5.33 – continued from previous page

TX2_GAIN_CODE	19	Byte0:	TX2 gain code for temperature $<$-30 °C
		Byte1:	TX2 gain code for temperature [-30, -20) °C
		Byte2:	TX2 gain code for temperature [-20, -10) °C
		Byte3:	TX2 gain code for temperature [-10, 0) °C
		Byte4:	TX2 gain code for temperature [0, 10) °C
		Byte5:	TX2 gain code for temperature [10, 20) °C
		Byte6:	TX2 gain code for temperature [20, 30) °C
		Byte7:	TX2 gain code for temperature [30, 40) °C
		Byte8:	TX2 gain code for temperature [40, 50) °C
		Byte9:	TX2 gain code for temperature [50, 60) °C
		Byte10:	TX2 gain code for temperature [60, 70) °C
		Byte11:	TX2 gain code for temperature [70, 80) °C
		Byte12:	TX2 gain code for temperature [80, 90) °C
		Byte13:	TX2 gain code for temperature [90, 100) °C
		Byte14:	TX2 gain code for temperature [100, 110) °C
		Byte15:	TX2 gain code for temperature [110, 120) °C
		Byte16:	TX2 gain code for temperature [120, 130) °C
		Byte17:	TX2 gain code for temperature [130, 140) °C
		Byte18:	TX2 gain code for temperature $\geq$140 °C
		Each byte is encoded as follows	
		Bits	Definition
		b5:0	STG_CODE Higher values for higher gain
		b7:6	RESERVED
RESERVED	1	0x00	
RESERVED	2	0x0000	

5.5.15 Sub block 0x010E – AWR_LOOPBACK_BURST_CONF_SET_SB

This API can be used to introduce loopback chirps within the functional frames. This loopback chirps will be introduced only if advanced frame configuration is used where user can define which sub-frame contains loopback chirps. The following loopback configuration will apply to one burst and user can program up to 16 different loopback configurations in 16 different bursts of a given sub-frame. User has to ensure that the corresponding sub-frame is defined in AWR_ADVANCED_FRAME_CONF_SB and sufficient time is given to allow the loopback bursts to be transmitted.

NOTE1:	If user desires to enable loopback chirps within functional frames, then this API should be issued after AWR_PROFILE_CONF_SET_SB	
NOTE2:	Only profile based phase shifter is supported in loopback configuration. Per-chirp phase shifter if enabled will not be reflected in loopback chirps.	
NOTE3:	For the sub-frame in which loopback is desired, user should set SFx_NUM_UNIQUE_CHIRPS_PER_BURST as 1 and can use SFx_NUM_LOOPS_PER_BURST for multiple chirps in the burst.	

Table 5.34: AWR_LOOPBACK_BURST_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x010E
SBLKLEN	2	Value = 48
LOOPBACK_SEL	1	Value Definition 0 No loopback 1 IF loopback 2 PS loopback 3 PA loopback Others RESERVED
BASE_PROFILE_INDX	1	Base profile used for loopback chirps Valid values 0 to 3
BURST_INDX	1	Indicates the index of the burst in the loopback sub-frame for which this configuration applies Valid values 0 to 15
RESERVED	1	0x00
FREQ_CONST	4	Start frequency for loopback. The start frequency configured here should be within profile's sweep bandwidth. 1 LSB = $3.6e9/2^{26}$ Hz ≈ 53.644 Hz Valid range: 0x5471C71B to 0x5A000000
SLOPE_CONST	2	Frequency slope for loopback burst (32 bit signed number) 1 LSB = $3.6e9 \times 900/2^{26} \approx 48.279$ kHz/μs Valid range: -2072 to 2072
RESERVED	2	0x0000

Continued on next page

Table 5.34 – continued from previous page

TX_BACKOFF	4	Bits	Definition
		b7:0	TX0 back off 1 LSB = 1 dB
		b15:8	TX1 back off 1 LSB = 1 dB
		b23:16	TX2 back off 1 LSB = 1 dB
		b31:24	RESERVED
RX_GAIN	2	Bits	Definition
		b5:0	RX_GAIN This field defines RX gain for each profile 1 LSB = 1 dB Valid values: all even values from 24 to 52
		b7:6	RF_GAIN_TARGET Value RF gain target 00 30 dB 01 34 dB 10 RESERVED 11 26 dB
		b15:8	RESERVED
TX_ENABLE	1	Bits	Definition
		b0	TX0 Enable
		b1	TX1 Enable
		b2	TX2 Enable
		b7:3	RESERVED
RESERVED	1	0x00	

Table 5.34 – continued from previous page

BPM_CONFIG	2	Bit	Definition
		b0	CONST_BPM_VAL_TX0_OFF Value of Binary Phase Shift value for TX0, during idle time
		b1	CONST_BPM_VAL_TX0_ON Value of Binary Phase Shift value for TX0, during chirp
		b2	CONST_BPM_VAL_TX1_OFF For TX1
		b3	CONST_BPM_VAL_TX1_ON For TX1
		b4	CONST_BPM_VAL_TX2_OFF For TX2
		b5	CONST_BPM_VAL_TX2_ON For TX2
		b15:6	RESERVED
DIGITAL_COR-RECTION_DIS-ABLE	2	Bits	Digital corrections
		b0	IQMM correction disable (only for PS and PA loopback, for IF loopback IQMM is disabled by firmware) 0 - Enable, 1 - Disable
		b1	Inter-RX Gain and Phase correction disable 0 - Enable, 1 - Disable
		b15:2	RESERVED
IF_LOOPBACK_FREQ	1	Value	IF Loopback frequency	Value	IF Loopback frequency
		0	180 kHz	8	4.02 MHz
		1	240 kHz	9	5 MHz
		2	360 kHz	10	6 MHz
		3	720 kHz	11	8.03 MHz
		4	1 MHz	12	9 MHz
		5	2 MHz	13	10 MHz
		6	2.5 MHz	255-14	RESERVED
		7	3 MHz		
IF_LOOPBACK_MAG	1	1 LSB = 10 mV Valid range: 1 to 63			

Table 5.34 – continued from previous page

PS1_PGA_GAIN_INDEX	1	Value	PGA gain value	Value	PGA gain value
		0	PGA is OFF	15	-3 dB
		1	-22 dB	16	-2 dB
		2	-16 dB	17	-1 dB
		3	-15 dB	18	0 dB
		4	-14 dB	19	1 dB
		5	-13 dB	20	2 dB
		6	-12 dB	21	3 dB
		7	-11 dB	22	4 dB
		8	-10 dB	23	5 dB
		9	-9 dB	24	6 dB
		10	-8 dB	25	7 dB
		11	-7 dB	26	8 dB
		12	-6 dB	27	9 dB
		13	-5 dB	255-28	RESERVED
		14	-4 dB		
PS2_PGA_GAIN_INDEX	1	Value	PGA gain value	Value	PGA gain value
		0	PGA is OFF	15	-3 dB
		1	-22 dB	16	-2 dB
		2	-16 dB	17	-1 dB
		3	-15 dB	18	0 dB
		4	-14 dB	19	1 dB
		5	-13 dB	20	2 dB
		6	-12 dB	21	3 dB
		7	-11 dB	22	4 dB
		8	-10 dB	23	5 dB
		9	-9 dB	24	6 dB
		10	-8 dB	25	7 dB
		11	-7 dB	26	8 dB
		12	-6 dB	27	9 dB
		13	-5 dB	255-28	RESERVED
		14	-4 dB		

Table 5.34 – continued from previous page

PS␣LOOPBACK␣FREQ	4	Phase shifter loop back frequency in kHz 1 LSB = 1 kHz Bits Definition b15:0 TX0 Loopback Frequency [b31:16] TX1 Loopback Frequency
RESERVED	4	RESERVED
PA␣LOOPBACK␣FREQ	2	This value is a 100 MHz divider which sets the loopback frequency For e.g. for a 1 MHz frequency, set this to 100 For a 2 MHz frequency, set this to 50 **NOTE:** To ensure no leakage of signal power, user has to ensure that 100MHz/LOOPBACK␣FREQ is an integer multiple of bin width For e.g. if user choses 25Msps sampling rate and 2048 samples/chirp, then LOOPBACK␣FREQ of 64 (=1.5625 MHz) will ensure no leakage
RESERVED	2	0x0000
RESERVED	2	0x0000
RESERVED	2	0x0000

5.5.16 Sub block 0x010F – AWR␣DYN␣CHIRP␣CONF␣SET␣SB

This API can be used to dynamically change the chirp configuration while frames are on-going. The configuration will be stored in software and the new configuration will be applied after receiving the AWR␣DYN␣CHIRP␣ENABLE␣SB API.

Table 5.35: AWR␣DYN␣CHIRP␣CONF␣SET␣SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x010F
SBLKLEN	2	Value = 200

Table 5.35 – continued from previous page

CHIRP_ROW_SELECT	1	Bits	Description	
		b3:0	RESERVED	
		b7:4	If user does not wish to reconfigure all 3 chirp rows, then the following mode can be used to configure only one row per chirp which enables the user to configure 48 chirps in one API, effectively saving on the reconfiguration time. If CHIRP_ROW_SELECT[7:4] is non-zero, then the API parameters CHIRPx_R1, CHIRPx_R2 and CHIRPx_R3 for $1 \leq x \leq 16$ in this API would mean CHIRP$(3x-2)$_Ry, CHIRP$(3x-1)$_Ry and CHIRP$(3x)$_Ry where y is as per the below table	
			Value	Definition
			0b0000	Enables all 3 chirp rows to be reconfigured
			0b0001	Enables only chirp row 1 to be reconfigured
			0b0010	Enables only chirp row 2 to be reconfigured
			0b0011	Enables only chirp row 3 to be reconfigured
			Others	RESERVED
CHIRP_SEG-MENT_SELECT	1	Valid range 0 to 31. Indicates the segment of the chirp RAM that the 16 chirp definitions in this sub block map to		
PROGRAM_MODE	2	Bits	Description	
		b0	Value	Definition
			0	Program the new configuration when AWR_DYN_CHIRP_ENABLE API is issued
			1	Program the new configuration immediately **NOTE:** User has to ensure that the chirps which are being reconfigured are not the ones which are currently in use for chirping
		b15:1	RESERVED	

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Table 5.35 – continued from previous page

CHIRP1_R1	4	Bits	Definition
		b3:0	PROFILE_INDX Valid range 0 to 3
		b7:4	RESERVED
		b13:8	FREQ_SLOPE_VAR 1 LSB = $3.6e9 \times 900/2^{26} \approx 48.279$ kHz Valid range: 0 to 63
		b15:14	RESERVED
		b18:16	TX_ENABLE
			Bit Definition
			b0 TX0 Enable
			b1 TX1 Enable
			b2 TX2 Enable
		b23:19	RESERVED
		b29:24	BPM_CONSTANT_BITS
			Bit Definition
			b0 CONST_BPM_VAL_TX0_OFF Value of Binary Phase Shift value for TX0, during idle time
			b1 CONST_BPM_VAL_TX0_ON Value of Binary Phase Shift value for TX0, during chirp
			b2 CONST_BPM_VAL_TX1_OFF For TX1
			b3 CONST_BPM_VAL_TX1_ON For TX1
			b4 CONST_BPM_VAL_TX2_OFF For TX2
			b5 CONST_BPM_VAL_TX2_ON For TX2
		b31:30	RESERVED
CHIRP1_R2	4	Bits	Definition
		b22:0	FREQ_START_VAR 1 LSB = $3.6e9/2^{26} \approx 53.644$ Hz Valid range: 0 to 8388607
		b31:23	RESERVED

Continued on next page

Table 5.35 – continued from previous page

CHIRP1_R3	4	Bits	Definition
		b11:0	IDLE_TIME_VAR 1 LSB = 10 ns Valid range: 0 to 4095
		b15:12	RESERVED
		b27:16	ADC_START_TIME_VAR 1 LSB = 10 ns Valid range: 0 to 4095
		b31:28	RESERVED
CHIRP2_R1	4	See description for CHIRP1_R1	
CHIRP2_R2	4	See description for CHIRP1_R2	
CHIRP2_R3	4	See description for CHIRP1_R3	
. . .	. . .	. . .	
CHIRP16_R1	4	See description for CHIRP1_R1	
CHIRP16_R2	4	See description for CHIRP1_R2	
CHIRP16_R3	4	See description for CHIRP1_R3	

5.5.17 Sub block 0x0110 – AWR_DYN_PERCHIRP_PHASESHIFTER_CONF_SET_SB

This API can be used to dynamically change the per-chirp phase shifter configuration (applicable only in xWR1243P) while frames are on-going. The configuration will be stored in software and the new configuration will be applied after receiving the AWR_DYN_CHIRP_ENABLE_SB API.

Table 5.36: AWR_DYN_PERCHIRP_PHASESHIFTER_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0110
SBLKLEN	2	Value = 56
RESERVED	1	0x00
CHIRP_SEG-MENT_SELECT	1	Indicates the segment of the chirp RAM that the 16 chirp definitions in this sub block map to. Valid range 0 to 31
CHIRP1_TX0_PHASE_SHIFTER	1	TX0 phase shift value Bits TX0 phase shift definition b1:0 RESERVED (set it to 0b00) b7:2 TX0 phase shift value 1 LSB = $360°/2^6 = 5.625°$ Valid range: 0 to 63

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Table 5.36 – continued from previous page

CHIRP1_TX1_ PHASE_SHIFTER	1	TX1 phase shift value
		
		Bits TX1 phase shift definition
		
		b1:0 RESERVED (set it to 0b00)
		
		b7:2 TX1 phase shift value
		       1 LSB = $360°/2^6 = 5.625°$
		       Valid range: 0 to 63

CHIRP1_TX2_ PHASE_SHIFTER	1	TX2 phase shift value
		
		Bits TX1 phase shift definition
		
		b1:0 RESERVED (set it to 0b00)
		
		b7:2 TX1 phase shift value
		       1 LSB = $360°/2^6 = 5.625°$
		       Valid range: 0 to 63

CHIRP2_TX0_ PHASE_SHIFTER	1	See description for CHIRP1_TX0_PHASE_SHIFTER
CHIRP2_TX1_ PHASE_SHIFTER	1	See description for CHIRP2_TX1_PHASE_SHIFTER
CHIRP2_TX2_ PHASE_SHIFTER	1	See description for CHIRP3_TX2_PHASE_SHIFTER
. . .	. . .	. . .
CHIRP16_TX0_ PHASE_SHIFTER	1	See description for CHIRP1_TX0_PHASE_SHIFTER
CHIRP16_TX1_ PHASE_SHIFTER	1	See description for CHIRP2_TX1_PHASE_SHIFTER
CHIRP16_TX2_ PHASE_SHIFTER	1	See description for CHIRP3_TX2_PHASE_SHIFTER

PROGRAM_ MODE	2	Bits Description
		
		b0 Value Definition
		
		       0 Program the new configuration when AWR_DYN_CHIRP_ENABLE API is issued
		
		       1 Program the new configuration immediately
		       NOTE: User has to ensure that the chirps which are being reconfigured are not the ones which are currently in use for chirping
		
		b15:1 RESERVED

5.5.18 Sub block 0x0111 – AWR_DYN_CHIRP_ENABLE_SB

This API can be used to trigger the copy of chirp configuration from software to hardware. The copy will be performed at the end of the ongoing frame.

Table 5.37: AWR_DYN_CHIRP_ENABLE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0111
SBLKLEN	2	Value = 8
RESERVED	4	0x00000000

NOTE: HW reconfiguration time (as shown in the figure below) is around 200 μs. User has to ensure that AWR_DYN_CHIRP_ENABLE_SB API is issued at least 200 μs before the start of the next frame
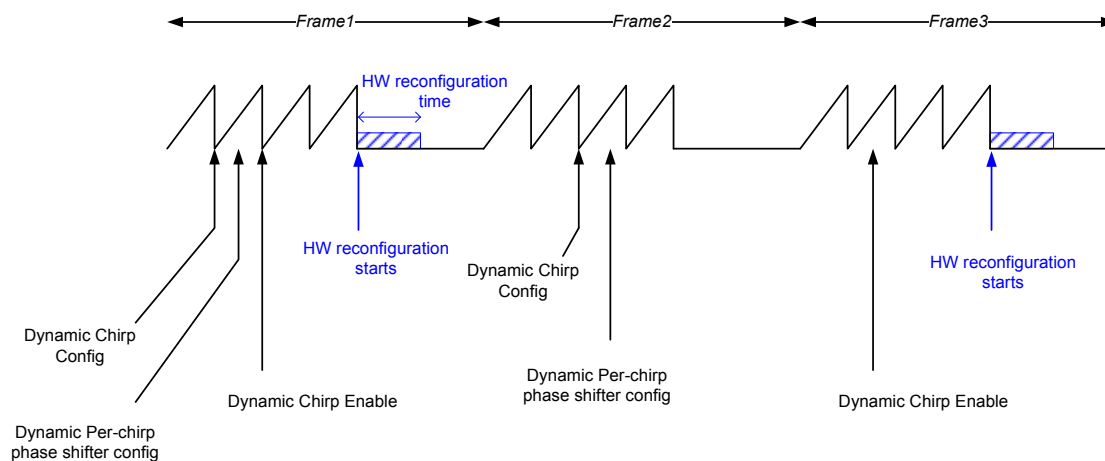
Figure 5.2: Dynamic chirp configuration use case timing diagram

5.5.19 Sub block 0x0112 – AWR_INTERCHIRP_BLOCKCONTROLS_SB

This API can be used to program the inter-chip turn on and turn off times or various RF blocks.

Table 5.38: AWR_INTERCHIRP_BLOCKCONTROLS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0112
SBLKLEN	2	Value = 44
RX02_RF_TURN_OFF_TIME	2	Time to wait after ramp end before turning off RX0 and RX2 RF stages. 1 LSB = 10 ns Valid range: -1024 to 1023
RX13_RF_TURN_OFF_TIME	2	Time to wait after ramp end before turning off RX1 and RX3 RF stages. 1 LSB = 10 ns Valid range: -1024 to 1023
RX02_BB_TURN_OFF_TIME	2	Time to wait after ramp end before turning off RX0 and RX2 baseband stages. 1 LSB = 10 ns Valid range: -1024 to 1023
RX13_BB_TURN_OFF_TIME	2	Time to wait after ramp end before turning off RX1 and RX3 baseband stages. 1 LSB = 10 ns Valid range: -1024 to 1023
RX02_RF_PRE_ENABLE_TIME	2	Time before TX Start Time when RX0 and RX2 RF stages are to be put in fast-charge state. 1 LSB = 10 ns Valid range: -1024 to 1023
RX13_RF_PRE_ENABLE_TIME	2	Time before TX Start Time when RX1 and RX3 RF stages are to be put in fast-charge state. 1 LSB = 10 ns Valid range: -1024 to 1023
RX02_BB_PRE_ENABLE_TIME	2	Time before TX Start Time when RX1 and RX3 baseband stages are to be put in fast-charge state. 1 LSB = 10 ns Valid range: -1024 to 1023
RX13_BB_PRE_ENABLE_TIME	2	Time before TX Start Time when RX2 and RX4 baseband stages are to be put in fast-charge state. 1 LSB = 10 ns Valid range: -1024 to 1023
RX02_RF_TURN_ON_TIME	2	Time before TX Start Time when RX1 and RX3 RF stages are to be enabled. 1 LSB = 10 ns Valid range: -1024 to 1023

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RX13_RF_TURN_ON_TIME	2	Time before TX Start Time when RX2 and RX4 RF stages are to be enabled. 1 LSB = 10 ns Valid range: -1024 to 1023
RX02_BB_TURN_ON_TIME	2	Time before TX Start Time when RX1 and RX3 baseband stages are to be enabled. 1 LSB = 10 ns Valid range: -1024 to 1023
RX13_BB_TURN_ON_TIME	2	Time before TX Start Time when RX2 and RX4 baseband stages are to be enabled. 1 LSB = 10 ns Valid range: -1024 to 1023
RX_LO_CHAIN_TURN_OFF_TIME	2	Time to wait after ramp end before turning off RX LO chain. 1 LSB = 10 ns Valid range: -1024 to 1023
TX_LO_CHAIN_TURN_OFF_TIME	2	Time to wait after ramp end before turning off TX LO chain. 1 LSB = 10 ns Valid range: -1024 to 1023
RX_LO_CHAIN_TURN_ON_TIME	2	Time before TX Start Time when the RX LO chain is to be enabled. 1 LSB = 10 ns Valid range: -1024 to 1023
TX_LO_CHAIN_TURN_ON_TIME	2	Time before TX Start Time when the TX LO chain is to be enabled. 1 LSB = 10 ns Valid range: -1024 to 1023
RESERVED	4	0x00000000
RESERVED	4	0x00000000

NOTE:	The minimum inter-chirp time should be greater than maximum of the following

1. abs(RX02_RF_TURN_OFF_TIME) + max(abs(RX02_RF_PRE_ENABLE_TIME), abs(RX02_RF_TURN_ON_TIME))

2. abs(RX13_RF_TURN_OFF_TIME) + max(abs(RX13_RF_PRE_ENABLE_TIME), abs(RX13_RF_TURN_ON_TIME))

3. abs(RX02_BB_TURN_OFF_TIME) + max(abs(RX02_BB_PRE_ENABLE_TIME), abs(RX02_BB_TURN_ON_TIME))

4. abs(RX13_BB_TURN_OFF_TIME) + max(abs(RX13_BB_PRE_ENABLE_TIME), abs(RX13_BB_TURN_ON_TIME))

5. abs(RX_LO_TURN_OFF_TIME) + abs(RX_LO_TURN_ON_TIME)

6. abs(TX_LO_TURN_OFF_TIME) + abs(TX_LO_TURN_ON_TIME)

5.5.20 Sub block 0x0113 – AWR_SUBFRAME_START_CONF_SB

This API can be used to trigger each sub-frame individually in software triggered mode. This API takes effect only when the advanced frame configuration indicates that each sub-frame needs to be individually triggered by the user.

Table 5.39: AWR_SUBFRAME_START_CONF_SB contents

Field Name	Number of bytes	Description		
SBLKID	2	Value = 0x0113		
SBLKLEN	2	Value = 8		
START_CMD	2	Bits	Definition	
		b15:0	Value	Definition
			0x0000	No effect
			0x0001	Trigger next sub-frame in software triggered sub-frame mode
RESERVED	2	0x0000		

NOTE1:		If the user wishes to trigger each sub-frame independently, then after advanced frame config, the FRAME START command should be issued once using AWR_FRAMESTARTSTOP_CONF_SB. This does not start any sub-frames but it will prepare the hardware for sub-frame trigger. Next any subsequent sub-frame trigger will start the sub-frames
NOTE2:		If the user wishes to use sub-frame trigger, he has to ensure that sub-frame trigger command is issued $k \cdot N$ times where k is the number of sub-frames in each frame and N is the number of frames. If the user wishes to stop frames in between, then he has to issue the FRAME STOP command (using AWR_FRAMESTARTSTOP_CONF_SB) only after $k \cdot M$ triggers of sub-frame trigger command (where M is an integer). i.e. FRAME STOP command can be issued only at frame boundaries
NOTE3:		If software based sub-frame trigger mode is chosen by the user, watchdog feature will not be available. User has to ensure that the watchdog is disabled before enabling the software based sub-frame trigger mode.
NOTE4:		If sub-frame trigger or hardware trigger mode is used to trigger the frames/sub-frames and if frames need to be stopped before the specified number of frames, then the the FRAME_STOP command using AWR_FRAMESTARTSTOP_CONF_SB API should be issued while the frame is on-going. If the frames are stopped while the device is idle, it can lead to errors.

5.6 Sub blocks related to AWR_RF_DYNAMIC_CONF_GET_SB

5.6.1 Sub block 0x0120 – AWR_PROFILE_CONF_GET_SB

This sub block reads the parameters of a given profile. The profile details are available as part of the acknowledgment. The structure is same as AWR_PROFILE_CONF_SET_SB
Table 5.40 describes the contents of this sub block.

Table 5.40: AWR_PROFILE_CONF_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0120
SBLKLEN	2	Value = 8

Continued on next page

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PROFILE_INDX	2	Valid range 0 to 3 Index of the profile which is to be read
RESERVED	2	0x0000

5.6.2 Sub block 0x0121 – AWR_CHIRP_CONF_GET_SB

This sub block reads the parameters of a given chirp. The profile details are available as part of the acknowledgement. The structure is same as AWR_CHIRP_CONF_SET_SB
Table 5.41 describes the contents of this sub block.

Table 5.41: AWR_CHIRP_CONF_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0121
SBLKLEN	2	Value = 8
CHIRP_START_INDX	2	Valid range 0 to 511 Starting index of the chirp which is to be read
CHIRP_END_INDX	2	Valid range 0 to 511 Ending index of the chirp which is to be read

5.6.3 Sub block 0x0122 – AWR_FRAME_CONF_GET_SB

This sub block reads the parameters of the configured frame. The profile details are available as part of the acknowledgement. The structure is same as AWR_FRAME_CONF_SET_SB
Table 5.42 describes the contents of this sub block.

Table 5.42: AWR_FRAME_CONF_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0122
SBLKLEN	2	Value = 4

5.6.4 Sub block 0x0123 – RESERVED

5.6.5 Sub block 0x0124 – RESERVED

5.6.6 Sub block 0x0125 – AWR_ADV_FRAME_CONF_GET_SB

This sub block reads the parameters of the configured frame. The profile details are available as part of the acknowledgement. The structure is same as AWR_ADVANCED_FRAME_CONF_SET_SB
Table 5.43 describes the contents of this sub block.

Table 5.43: AWR_ADV_FRAME_CONF_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0125
SBLKLEN	2	Value = 4

5.6.7 Sub block 0x0126 – RESERVED

5.6.8 Sub block 0x0127 – RESERVED

5.6.9 Sub block 0x0128 – RESERVED

5.6.10 Sub block 0x0129 – RESERVED

5.6.11 Sub block 0x012A – RESERVED

5.6.12 Sub block 0x012B – RESERVED

5.6.13 Sub block 0x012C – AWR_RX_GAIN_TEMPLUT_GET_SB

This API is issued to read the temperature based RX gain LUT used by the firmware. This API should be issued after the profile configuration API. The acknowledgement packet sent in response to this API will contain the LUT. The structure is same as AWR_RX_GAIN_LUT_SET_SB.

Table 5.44: AWR_RX_GAIN_TEMPLUT_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x012C
SBLKLEN	2	Value = 8
PROFILE_INDX	1	Profile index for which the RX gain LUT is desired
RESERVED	3	0x000000

5.6.14 Sub block 0x012D – AWR_TX_GAIN_TEMPLUT_GET_SB

This API is issued to read the temperature based TX gain LUT used by the firmware. This API should be issued after the profile configuration API. The acknowledgement packet sent in response to this API will contain the LUT. The structure is same as AWR_TX_GAIN_LUT_SET_SB.

Table 5.45: AWR_TX_GAIN_TEMPLUT_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x012D
SBLKLEN	2	Value = 8
PROFILE_INDX	1	Profile index for which the TX gain LUT is desired
RESERVED	3	0x000000

5.7 Sub blocks related to AWR_FRAME_TRIG_MSG

5.7.1 Sub block 0x0140 – AWR_FRAMESTARTSTOP_CONF_SB

This sub block starts or stops transmission of frames.
Table 5.46 describes the contents of this sub block.

Table 5.46: AWR_FRAMESTARTSTOP_CONF_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x0140	
SBLKLEN	2	Value = 8	
START_STOP_CMD	2	Value	Definition
		0x0000	Stop the transmission of frames after the current frame is over
		0x0001	Trigger a frame in software triggered mode. In hardware SYNC_IN triggered mode, this command allows subsequent SYNC_IN trigger to be honored
RESERVED	2	0x0000	

5.8 Sub blocks related to AWR_RF_ADVANCED_FEATURES_CONF_ SET_MSG

5.8.1 Sub block 0x0180 – AWR_BPM_COMMON_CONF_SET_SB

This API sub block defines static configurations related to BPM (Binary Phase Modulation) feature in each of the TXs. E.g. the source of the BPM pattern (one constant value for each chirp as defined, or intra-chirp pseudo random BPM pattern as found by a programmable LFSR or a programmable sequence inside each chirp), are defined here.
Table 5.47 describes the contents of this sub block.

Table 5.47: AWR_BPM_COMMON_CONF_SET_SB contents

Field Name	Number of bytes	Description		
SBLKID	2	Value = 0x0180		
SBLKLEN	2	Value = 20		
BPM_MODE_CFG	2	Bits	Description	
		b1:0	BPM_SRC_SEL (select source of BPM pattern)	
			Value	Definition
			00	CHIRP_CONFIG_BPM (refer to AWR_BPM_CHIRP_CONF_SB)
			01	RESERVED
			10	RESERVED
			11	RESERVED
		b15:2	RESERVED	
RESERVED	2	0x0000		
RESERVED	2	0x0000		
RESERVED	2	0x0000		
RESERVED	4	0x00000000		
RESERVED	4	0x00000000		

5.8.2 Sub block 0x0181 – AWR_BPM_CHIRP_CONF_SET_SB

This sub block defines static configurations related to BPM (Binary Phase Modulation) feature in each of the TXs.
Table 5.48 describes the contents of this sub block.

Table 5.48: AWR_BPM_CHIRP_CONF_SET_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x0181	
SBLKLEN	2	Value = 12	
CHIRP_START_INDX	2	Start index of the chirp for configuring the constant BPM Valid range 0 to 511	
CHIRP_END_INDX	2	End index of the chirp for configuring the constant BPM Valid range 0 to 511	
CONST_BPM_VAL	2	Bit	Definition
		b0	CONST_BPM_VAL_TX0_TXOFF Value of Binary Phase Shift value for TX0, when during idle time
		b1	CONST_BPM_VAL_TX0_TXON Value of Binary Phase Shift value for TX0, during chirp
		b2	CONST_BPM_VAL_TX1_TXOFF For TX1
		b3	CONST_BPM_VAL_TX1_TXON For TX1
		b4	CONST_BPM_VAL_TX2_TXOFF For TX2
		b5	CONST_BPM_VAL_TX2_TXON For TX2
		b15:6	RESERVED
RESERVED	2	0x0000	

NOTE: BPM values are applied at TX_START_TIME.

5.9 Sub blocks related to AWR_RF_STATUS_GET_MSG

5.9.1 Sub block 0x0220 – AWR_RF_VERSION_GET_SB

This sub block reads RF HW and FW versions. The information returned by the device will be in the format as given in AWR_RFVERSION_SB.
Table 5.49 describes the contents of the request sub block

Table 5.49: AWR_RF_VERSION_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0220
SBLKLEN	2	Value = 4

Response to AWR_RFVERSION_GET_SB

AWR_RFVERSION_SB sub block is sent by the radar device in response to AWR_RFVERSION_GET_SB. Note that SBLKID for both AWR_RFVERSION_GET_SB and AWR_RFVERSION_SB are same.

Table 5.50 describes the contents of the response sub block.

Table 5.50: AWR_RF_VERSION_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0220
SBLKLEN	2	Value = 20
HW_VARIANT	1	HW variant number
HW_VERSION_MAJOR	1	HW version major number
HW_VERSION_MINOR	1	HW version minor number
BSS_FW_VER-SION_MAJOR	1	BSS FW version major number
BSS_FW_VER-SION_MINOR	1	BSS FW version minor number
BSS_FW_VER-SION_BUILD	1	BSS FW version build number
BSS_FW_VER-SION_DEBUG	1	BSS FW version debug number
BSS_FW_VER-SION_YEAR	1	Year of BSS FW version release
BSS_FW_VER-SION_MONTH	1	Month of BSS FW version release
BSS_FW_VER-SION_DAY	1	Day of BSS FW version release
BSS_FW_VER-SION_PATCH_MAJOR	1	BSS FW version patch major number

Continued on next page

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BSS_FW_VER-SION_PATCH_MINOR	1	BSS FW version patch minor number	
BSS_FW_VER-SION_PATCH_YEAR	1	Year of BSS FW patch release	
BSS_FW_VER-SION_PATCH_MONTH	1	Month of BSS FW patch release	
BSS_FW_VER-SION_PATCH_DAY	1	Day of BSS FW patch release	
BSS_FW_PATCH_BUILD_DEBUG_VERSION	1	Bit	Definition
		b3:0	DEBUG version number
		b7:4	BUILD version number

5.9.2 Sub block 0x0221 – AWR_RF_CPUFAULT_STATUS_GET_SB

This sub block provides the RF BSS CPU fault information.
Table 5.51 describes the content of this sub block.

Table 5.51: AWR_RF_CPUFAULT_STATUS_GET_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0221
SBLKLEN	2	Value = 4

AWR_RF_CPUFAULT_STATUS_SB is sent in response to AWR_RF_CPUFAULT_STATUS_GET_SB.
Table 5.52 describes the content of AWR_RF_CPUFAULT_STATUS_SB

Table 5.52: AWR_RF_CPUFAULT_STATUS_GET_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0221
SBLKLEN	2	Value = 36

Table 5.52 – continued from previous page

FAULT_TYPE	1	Value	Definition
		0	RF Processor Undefined Instruction Abort
		1	RF Processor Instruction pre-fetch Abort
		2	RF Processor Data Access Abort
		3	RF Processor Firmware Fatal Error
		0x4 - 0xFE	RESERVED
		0xFF	No fault
RESERVED	1	0x00	
LINE_NUM	2	Valid only in case of FAULT type is 0x3, provides the firmware line number at which fatal error occurred.	
FAULT_LR	4	The instruction PC address at which Fault occurred	
FAULT_PREV_LR	4	The return address of the function from which fault function has been called (Call stack LR)	
FAULT_SPSR	4	The CPSR register value at which fault occurred	
FAULT_SP	4	The SP register value at which fault occurred	
FAULT_CAUSE_ADDRESS	4	The address access at which Fault occurred (valid only for fault type 0x0 to 0x2)	
FAULT_ERROR_STATUS	2	The status of Error (Error Cause type – valid only for fault type 0x0 to 0x2)	
		0x000	BACKGROUND_ERR
		0x001	ALIGNMENT_ERR
		0x002	DEBUG_EVENT
		0x00D	PERMISSION_ERR
		0x008	SYNCH_EXTER_ERR
		0x406	ASYNCH_EXTER_ERR
		0x409	SYNCH_ECC_ERR
		0x408	ASYNCH_ECC_ERR
FAULT_ERROR_SOURCE	1	The Source of the Error (Error Source type - valid only for fault type 0x0 to 0x2)	
		0x0	ERR_SOURCE_AXI_MASTER
		0x1	ERR_SOURCE_ATCM
		0x2	ERR_SOURCE_BTCM
FAULT_AXI_ERROR_TYPE	1	The AXI Error type (Error Source type - valid only for fault type 0x0 to 0x2)	
		0x0	AXI_DECOD_ERR
		0x1	AXI_SLAVE_ERR

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FAULT_ACCESS_TYPE	1	The Error Access type (Error Access type - valid only for fault type 0x0 to 0x2) 0x0 READ_ERR 0x1 WRITE_ERR
FAULT_RECOV-ERY_TYPE	1	The Error Recovery type (Error Recovery type - Valid only for fault type 0x0 to 0x2) 0x0 UNRECOVERY 0x1 RECOVERY
RESERVED	2	0x0000

5.9.3 Sub block 0x0222 – AWR_RF_ESMFAULT_STATUS_GET_SB

This sub block provides the information regarding additional RF sub system faults.
Table 5.53 describes the content of this sub block.

Table 5.53: AWR_RF_ESMFAULT_STATUS_GET_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0222
SBLKLEN	2	Value = 4

The response to above request is given in the AWR_RF_ESMFAULT_STATUS_SB.
Table 5.54 describes the contents of AWR_RF_ESMFAULT_STATUS_SB.

Table 5.54: AWR_RF_ESMFAULT_STATUS_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0222
SBLKLEN	2	Value = 12

Continued on next page

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ESM_GROUP1_ERRORS	4	Bit	Error Information
		b0	RAMPGEN_SB_ERROR
		b1	RESERVED
		b2	GPADC_RAM_SB_ERROR
		b3	VIM_RAM_SB_ERROR
		b4	DFE_SELFTEST_ERROR
		b5	VIM_SELFTEST_ERRROR
		b6	B0TCM_SB_ERROR
		b7	B1TCM_SB_ERROR
		b8	CCMR4_SELFTEST_ERROR
		b9	ATCM_SB_ERROR
		b10	RAMPGEN_SELFTEST_ERROR
		b11	RAMPGEN_PAR_SELFTST_ERROR
		b12	SEQ_EXT_SELFTEST_ERROR
		b13	SEQ_EXT_SB_ERROR
		b14	RESERVED
		b15	AGC_RAM_SB_ERROR
		b16	B1TCM_PAR_CHK_ERROR
		b17	B0TCM_PAR_CHK_ERROR
		b18	ATCM_PAR_CHK_ERROR
		b19	MB_MSS2BSS_SB_ERROR
		b20	MB_BSS2MSS_SB_ERROR
		b31:21	RESERVED

Table 5.54 – continued from previous page

ESM_GROUP2_ERRORS	4	Bit	Error Information
		b0	DFE_STC_ERROR
		b1	CR4_STC_ERROR
		b2	CCMR4_COMP_ERROR
		b3	B0TCM_DB_ERROR
		b4	B1TCM_DB_ERROR
		b5	ATCM_DB_ERROR
		b6	DCC_ERROR
		b7	SEQ_EXT_ERROR
		b8	SYNT_FREQ_MON_ERROR
		b9	DFE_PARITY_ERROR
		b10	RAMPGEN_DB_ERROR
		b11	BUBBLE_CORRECTION_FAIL
		b12	RAMPGEN_LOCSTEP_ERROR
		b13	RTI_RESET_ERROR
		b14	GPADC_RAM_DB_ERROR
		b15	VIM_COMP_ERROR
		b16	CR4_LIVE_LOCK_ERROR
		b17	WDT_NMI_ERROR
		b18	VIM_RAM_DB_ERROR
		b19	RAMPGEN_PAR_ERROR
		b20	SEQ_EXT_DB_ERROR
		b21	DMA_MPU_ERROR
		b22	AGC_RAM_DB_ERROR
		b23	CRC_COMP_ERROR
		b24	WAKEUP_STS_ERROR
		b25	SHORT_CIRCUIT_ERROR
		b26	B1TCM_PAR_ERROR
		b27	B0TCM_PAR_ERROR
		b28	ATCM_PAR_ERROR
		b29	MB_MSS2BSS_DB_ERROR
		b30	MB_BSS2MSS_DB_ERROR
		b31	CCC_ERROR

5.9.4 Sub block 0x0223 – AWR_RF_DIEID_GET_SB

This sub block provides the information regarding the Die ID of the device.

Table 5.55: AWR_RF_DIEID_GET_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0223
SBLKLEN	2	Value = 4

The response to above request is given in the AWR_RF_DIEID_STATUS_SB.
Table 5.56 describes the contents of AWR_RF_DIEID_STATUS_SB.

Table 5.56: AWR_RF_DIEID_STATUS_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0223
SBLKLEN	2	Value = 36
LOT_NO	4	Lot number
WAFER_NO	4	Wafer number
DEV_X	4	X cordinate of the die in the wafer
DEV_Y	4	Y cordinate of the die in the wafer
RESERVED	4	0x00000000
RESERVED	4	0x00000000
RESERVED	4	0x00000000
RESERVED	4	0x00000000

5.9.5 Sub block 0x0224 – AWR_RF_BOOTUPBIST_STATUS_GET_SB

This sub block provides the information regarding boot up self-test status.
Table 5.57 describes the content of this sub block.

Table 5.57: AWR_RF_BOOTUPBIST_STATUS_GET_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0224
SBLKLEN	2	Value = 4

The response of this sub block will be AWR_RF_BOOTUPBIST_STATUS_DATA_SB with content as shown in Table 5.58

Table 5.58: AWR_RF_BOOTUPBIST_STATUS_DATA_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0224
SBLKLEN	2	Value = 20
RF_POWERUP_BIST_STATUS_FLAGS	4	1 - PASS, 0 - FAIL
		Bit Status Information
		b0 ROM CRC check
		b1 CR4 and VIM lockstep test
		b2 RESERVED
		b3 VIM test
		b4 STC test of diagnostic
		b5 CR4 STC
		b6 CRC test
		b7 RAMPGEN memory ECC test
		b8 DFE Parity test
		b9 DFE memory ECC
		b10 RAMPGEN lockstep test
		b11 FRC lockstep test
		b12 DFE memory PBIST
		b13 RAMPGEN memory PBIST
		b14 PBIST test
		b15 WDT test
		b16 ESM test
		b17 DFE STC
		b18 RESERVED
		b19 ATCM, BTCM ECC test
		b20 ATCM, BTCM parity test
		b21 RESERVED
		b22 RESERVED
		b23 RESERVED
		b24 FFT test
		b25 RTI test
		b26 PCR test
		b31:27 RESERVED
POWERUP_TIME	4	RF BIST SS power up time 1 LSB = 5 ns

Table 5.58 – continued from previous page

RESERVED	4	0x00000000
RESERVED	4	0x00000000

5.10 Sub blocks related to AWR_RF_MONITORING_REPORT_GET_MSG

5.10.1 Sub block 0x0260 – AWR_RF_DFE_STATISTICS_REPORT_GET_SB

Table 5.59 describes the content of this sub block.

Table 5.59: AWR_RF_DFE_STATISTICS_REPORT_GET_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0260
SBLKLEN	2	Value = 4

The response of this sub block will be AWR_RF_DFE_STATISTICS_REPORT_SB with content as shown in Table 5.60

Table 5.60: AWR_RF_DFE_STATISTICS_REPORT_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x0260
SBLKLEN	2	Value = 196
PF0_RX0_ICH	2	Residual DC value in I chain for profile 0, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF0_RX0_QCH	2	Residual DC value in Q chain for profile 0, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF0_RX0_ISQ	2	RMS power in I chain for profile 0, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input

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Table 5.60 – continued from previous page

PF0_RX0_QSQ	2	RMS power in Q chain for profile 0, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF0_RX0_IQ-CORR	4	Cross correlation between I and Q chains for profile 0, RX channel 0 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF0_RX1_ICH	2	Residual DC value in I chain for profile 0, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF0_RX1_QCH	2	Residual DC value in Q chain for profile 0, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF0_RX1_ISQ	2	RMS power in I chain for profile 0, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF0_RX1_QSQ	2	RMS power in Q chain for profile 0, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF0_RX1_IQ-CORR	4	Cross correlation between I and Q chains for profile 0, RX channel 1 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF0_RX2_ICH	2	Residual DC value in I chain for profile 0, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF0_RX2_QCH	2	Residual DC value in Q chain for profile 0, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF0_RX2_ISQ	2	RMS power in I chain for profile 0, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input

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Table 5.60 – continued from previous page

PF0_RX2_QSQ	2	RMS power in Q chain for profile 0, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF0_RX2_IQ-CORR	4	Cross correlation between I and Q chains for profile 0, RX channel 2 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF0_RX3_ICH	2	Residual DC value in I chain for profile 0, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF0_RX3_QCH	2	Residual DC value in Q chain for profile 0, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF0_RX3_ISQ	2	RMS power in I chain for profile 0, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF0_RX3_QSQ	2	RMS power in Q chain for profile 0, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF0_RX3_IQ-CORR	4	Cross correlation between I and Q chains for profile 0, RX channel 3 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF1_RX0_ICH	2	Residual DC value in I chain for profile 1, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF1_RX0_QCH	2	Residual DC value in Q chain for profile 1, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF1_RX0_ISQ	2	RMS power in I chain for profile 1, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input

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Table 5.60 – continued from previous page

PF1_RX0_QSQ	2	RMS power in Q chain for profile 1, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF1_RX0_IQ-CORR	4	Cross correlation between I and Q chains for profile 1, RX channel 0 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF1_RX1_ICH	2	Residual DC value in I chain for profile 1, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF1_RX1_QCH	2	Residual DC value in Q chain for profile 1, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF1_RX1_ISQ	2	RMS power in I chain for profile 1, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF1_RX1_QSQ	2	RMS power in Q chain for profile 1, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF1_RX1_IQ-CORR	4	Cross correlation between I and Q chains for profile 1, RX channel 1 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF1_RX2_ICH	2	Residual DC value in I chain for profile 1, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF1_RX2_QCH	2	Residual DC value in Q chain for profile 1, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF1_RX2_ISQ	2	RMS power in I chain for profile 1, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input

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Table 5.60 – continued from previous page

PF1_RX2_QSQ	2	RMS power in Q chain for profile 1, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF1_RX2_IQ-CORR	4	Cross correlation between I and Q chains for profile 1, RX channel 2 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF1_RX3_ICH	2	Residual DC value in I chain for profile 1, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF1_RX3_QCH	2	Residual DC value in Q chain for profile 1, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF1_RX3_ISQ	2	RMS power in I chain for profile 1, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF1_RX3_QSQ	2	RMS power in Q chain for profile 1, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF1_RX3_IQ-CORR	4	Cross correlation between I and Q chains for profile 1, RX channel 3 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF2_RX0_ICH	2	Residual DC value in I chain for profile 2 RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF2_RX0_QCH	2	Residual DC value in Q chain for profile 2, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF2_RX0_ISQ	2	RMS power in I chain for profile 2, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input

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PF2_RX0_QSQ	2	RMS power in Q chain for profile 2, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF2_RX0_IQ-CORR	4	Cross correlation between I and Q chains for profile 2, RX channel 0 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF2_RX1_ICH	2	Residual DC value in I chain for profile 2, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF2_RX1_QCH	2	Residual DC value in Q chain for profile 2, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF2_RX1_ISQ	2	RMS power in I chain for profile 2, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF2_RX1_QSQ	2	RMS power in Q chain for profile 2, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF2_RX1_IQ-CORR	4	Cross correlation between I and Q chains for profile 2, RX channel 1 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF2_RX2_ICH	2	Residual DC value in I chain for profile 2, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF2_RX2_QCH	2	Residual DC value in Q chain for profile 2, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF2_RX2_ISQ	2	RMS power in I chain for profile 2, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input

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Table 5.60 – continued from previous page

PF2_RX2_QSQ	2	RMS power in Q chain for profile 2, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF2_RX2_IQ-CORR	4	Cross correlation between I and Q chains for profile 2, RX channel 2 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF2_RX3_ICH	2	Residual DC value in I chain for profile 2, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF2_RX3_QCH	2	Residual DC value in Q chain for profile 2, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF2_RX3_ISQ	2	RMS power in I chain for profile 2, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF2_RX3_QSQ	2	RMS power in Q chain for profile 2, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF2_RX3_IQ-CORR	4	Cross correlation between I and Q chains for profile 2, RX channel 3 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF3_RX0_ICH	2	Residual DC value in I chain for profile 3 RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF3_RX0_QCH	2	Residual DC value in Q chain for profile 3, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF3_RX0_ISQ	2	RMS power in I chain for profile 3, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input

Table 5.60 – continued from previous page

PF3_RX0_QSQ	2	RMS power in Q chain for profile 3, RX channel 0 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF3_RX0_IQ-CORR	4	Cross correlation between I and Q chains for profile 3, RX channel 0 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF3_RX1_ICH	2	Residual DC value in I chain for profile 3, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF3_RX1_QCH	2	Residual DC value in Q chain for profile 3, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF3_RX1_ISQ	2	RMS power in I chain for profile 3, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF3_RX1_QSQ	2	RMS power in Q chain for profile 3, RX channel 1 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF3_RX1_IQ-CORR	4	Cross correlation between I and Q chains for profile 3, RX channel 1 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF3_RX2_ICH	2	Residual DC value in I chain for profile 3, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF3_RX2_QCH	2	Residual DC value in Q chain for profile 3, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF3_RX2_ISQ	2	RMS power in I chain for profile 3, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input

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Table 5.60 – continued from previous page

PF3_RX2_QSQ	2	RMS power in Q chain for profile 3, RX channel 2 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF3_RX2_IQ-CORR	4	Cross correlation between I and Q chains for profile 3, RX channel 2 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input
PF3_RX3_ICH	2	Residual DC value in I chain for profile 3, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF3_RX3_QCH	2	Residual DC value in Q chain for profile 3, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit signed number 1 LSB = $1V/2^{15}$ referred to ADC input
PF3_RX3_ISQ	2	RMS power in I chain for profile 3, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF3_RX3_QSQ	2	RMS power in Q chain for profile 3, RX channel 3 (post DC and IQ mismatch correction) represented by a 16 bit unsigned number 1 LSB = $1V^2/2^{15}$ referred to ADC input
PF3_RX3_IQ-CORR	4	Cross correlation between I and Q chains for profile 3, RX channel 3 (post DC and IQ mismatch correction) represented by a 32 bit signed number 1 LSB = $1V^2/2^{30}$ referred to ADC input

5.11 Sub blocks related to AWR_RF_MISC_CONF_SET_MSG

5.11.1 Sub block 0x02C0 – RESERVED

5.11.2 Sub block 0x02C1 – RESERVED

5.11.3 Sub block 0x02C2 – AWR_RF_TEST_SOURCE_CONFIG_SET_SB

This sub block is used to configure the test source of BSS
Table 5.61 describes the content of this sub block.

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Table 5.61: AWR_RF_TEST_SOURCE_CONFIG_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x02C2
SBLKLEN	2	Value = 72
POSITION_VEC1	[2+2+2]	Relative position in Cartesian coordinate from radar to objects, [x, y, z] (all signed, though for y, only unsigned makes sense if forward looking: our radar is on y=0 plane). Object 0 [x,y,z] 1 LSB = 1 cm Valid Range: y: 0 to 32767 cm, x & z: $\pm$32767 cm
VELOCITY_VEC1	[2+2+2]	Relative velocity in Cartesian coordinate, similar to position vector (all signed) Object 0 1 LSB = 1 cm/s Valid Range = +/- 5000 (i.e. +/-180 kmph)
SIG_LEV_VEC1	[2]	Reflecting objects' signal level at ADC output, relative to ADC Full Scale 1 LSB = -0.1 dBFS Valid range: 0 to 950 The same field may be used to emulate enable/disable each object by programming appropriate levels.
BOUNDARY_MIN_VEC1	[2+2+2]	Boundary minimum limit for each of x, y, z. When the current position crosses this boundary, the emulator returns the corresponding coordinate to the originally programmed value. Object 1 [x,y,z] 1 LSB = 1 cm Valid Range: x: 0 to 32767 cm, y & z: $\pm$32767 cm
BOUNDARY_MAX_VEC1	[2+2+2]	Boundary maximum limit for each of x, y, z. When the current position crosses this boundary, the emulator returns the corresponding coordinate to the originally programmed value. Object 1 [x,y,z] 1 LSB = 1 cm Valid Range: x: 0 to 32767 cm, y & z: $\pm$32767 cm
POSITION_VEC2	[2+2+2]	Relative position in Cartesian coordinate from radar to objects, [x, y, z] (all signed, though for y, only unsigned makes sense if forward looking: our radar is on y=0 plane). Object 1 [x,y,z] 1 LSB = 1 cm Valid Range: y: 0 to 32767 cm, x & z: $\pm$32767 cm

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Table 5.61 – continued from previous page

VELOCITY_VEC2	[2+2+2]	Relative velocity in Cartesian coordinate, similar to position vector (all signed) Object 1 1 LSB = 1 cm/s Valid Range = +/- 5000 (i.e. +/-180 kmph)
SIG_LEV_VEC2	[2]	Reflecting objects' signal level at ADC output, relative to ADC Full Scale 1 LSB = -0.1 dBFS Valid range: 0 to 950 The same field may be used to emulate enable/disable each object by programming appropriate levels.
BOUNDARY_MIN_VEC2	[2+2+2]	Boundary minimum limit for each of x, y, z. When the current position crosses this boundary, the emulator returns the corresponding coordinate to the originally programmed value. Object 1 [x,y,z] 1 LSB = 1 cm Valid Range: x: 0 to 32767 cm, y & z: $\pm$32767 cm
BOUNDARY_MAX_VEC2	[2+2+2]	Boundary maximum limit for each of x, y, z. When the current position crosses this boundary, the emulator returns the corresponding coordinate to the originally programmed value. Object 1 [x,y,z] 1 LSB = 1 cm Valid Range: x: 0 to 32767 cm, y & z: $\pm$32767 cm
RX_ANT_POS_XZ	8	Receiver Antenna positions to be modeled. The radar is on y=0 plane. Only x and z coordinates to be provided. 1 LSB = Wavelength/8 Valid range = $\pm$15 wave lengths Byte 0: RX0 X coordinate (may be 0 as reference) Byte 1: RX0 Z (may be 0 as reference) Byte 2: RX1 X Byte 3: RX1 Z Byte 4: RX2 X Byte 5: RX2 Z Byte 6: RX3 X Byte 7: RX3 Z
RESERVED	6	RESERVED
RESERVED	2	Reserved for 4 bytes alignment

5.11.4 Sub block 0x02C3 – AWR_RF_TEST_SOURCE_ENABLE_SET_SB

This sub block is used to enable test source of BSS

Table 5.62 describes the content of this sub block.

Table 5.62: AWR_RF_TEST_SOURCE_ENABLE_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x02C3
SBLKLEN	2	Value = 8
TS_EN	2	Bit Definition b0 0 Disable (revert to normal functionality) 1 Enable (enter test source functionality) b15:1 RESERVED
RESERVED	2	0x0000

5.11.5 Sub block 0x02C4 – 0x02CB RESERVED

5.11.6 Sub block 0x02CC – AWR_RF_LDO_BYPASS_SB

This sub block enables LDO bypass option within BSS.

> **CAUTION:** Do not enable RF LDO bypass option when the PMIC is configured to supply 1.3V to VIN_13RF1 and VIN_13RF2 analog and RF power supply inputs. This may damage the device. Typically in TI EVMs, PMIC is configured to supply 1.3V to the RF supplies.

Table 5.63 describes the content of this sub block.

Table 5.63: AWR_RF_LDO_BYPASS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x02CC
SBLKLEN	2	Value = 8

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Table 5.63 – continued from previous page

RFLDO_BYPASS_EN	2	Bit	Description	
		b0	Value	Description
			0	RF LDO not bypassed
			1	RF LDO bypassed
		b1	Value	Description
			0	PA LDO enabled
			1	PA LDO disabled
			When simultaneous 3 TX are to be used, to avoid package reliability issues, VIN_13RF2 is shorted to VOUT_PA on the board and the PA LDO should be disabled.	
		b15:2	RESERVED	
		The usage of these configurations is as per the table below		

USECASE	LDO_BYPASS	PA_LDO_DISABLE
1.3V VIN_13RF1 and VIN_13RF2 supplies	0	0
1.0V VIN_13RF1 and VIN_13RF2 supplies	1	0
1.0V VIN_13RF1 and VIN_13RF2 supplies and VIN_13RF2 shorted to VOUT_PA	1	1

SUPPLY_MONITOR_IRDROP	1	IR drop is the voltage drop from the PMIC output to the device pin. The user should program the voltage drop in percentage units which will be used for adjusting the thresholds for measuring the external supplies.
		Value Description
		0 IR drop of 0%
		1 IR drop of 3%
		2 IR drop of 6%
		3 IR drop of 9%
IO_SUPPLY_INDICATOR	1	IO supply indicator for correct monitoring of IO supply
		Value Description
		0 3.3 V IO supply
		1 1.8 V IO supply

5.11.7 Sub block 0x02CD – AWR_RF_PALOOPBACK_CFG_SB

This sub block enables/disables PA loopback for all enabled profiles. This is used to debug both the TX and RX chains are working correctly.

Table 5.64 describes the content of this sub block.

NOTE:	If monitoring is enabled with the loopback APIs (subblock 0x02CD, 0x02CE, 0x02CF), then loopback will not work after montoring is complete. To use loopback with monitoring, use AWR_ADVANCED_FRAME_CONF_SB with AWR_LOOPBACK_BURST_CONF_SB.

Table 5.64: AWR_RF_PALOOPBACK_CFG_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x02CD
SBLKLEN	2	Value = 8
PA_LOOPBACK_FREQ	2	This value is a 100 MHz divider which sets the loopback frequency For e.g. for a 1 MHz frequency, set this to 100 For a 2 MHz frequency, set this to 50 **NOTE:** To ensure no leakage of signal power, user has to ensure that 100 MHz/LOOPBACK_FREQ is an integer multiple of bin width For e.g. if user choses 25 Msps sampling rate and 2048 samples/chirp, then LOOPBACK_FREQ of 64 (=1.5625 MHz) will ensure no leakage
PA_LOOPBACK_EN	1	Value Description 0 PA loopback is not enabled 1 PA loopback is enabled
RESERVED	1	0x00

5.11.8 Sub block 0x02CE – AWR_RF_PSLOOPBACK_CFG_SB

This sub block enables/disables PS (phase shifter) loopback for all enabled profiles. This is used to debug the TX (before the PA) and RX chains.

Table 5.65 describes the content of this sub block.

NOTE:	If monitoring is enabled with the loopback APIs (subblock 0x02CD, 0x02CE, 0x02CF), then loopback will not work after montoring is complete. To use loopback with monitoring, use AWR_ADVANCED_FRAME_CONF_SB with AWR_LOOPBACK_BURST_CONF_SB.

Table 5.65: AWR_RF_PSLOOPBACK_CFG_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x02CE
SBLKLEN	2	Value = 12
PS_LOOPBACK_FREQ	2	Loop back frequency in kHz 1 LSB = 1 kHz
RESERVED	2	0x0000
PS_LOOPBACK_EN	1	Value — Definition 0 — PS loopback is not enabled 1 — PS loopback is enabled
PS_LOOPBACK_TXID	1	Bit — Definition b0 — TX0 is used for loopback b1 — TX1 is used for loopback b7:2 — RESERVED
PGA_GAIN_INDEX	1	Value — PGA gain value / Value — PGA gain value 0 — PGA is OFF / 15 — -3 dB 1 — -22 dB / 16 — -2 dB 2 — -16 dB / 17 — -1 dB 3 — -15 dB / 18 — 0 dB 4 — -14 dB / 19 — 1 dB 5 — -13 dB / 20 — 2 dB 6 — -12 dB / 21 — 3 dB 7 — -11 dB / 22 — 4 dB 8 — -10 dB / 23 — 5 dB 9 — -9 dB / 24 — 6 dB 10 — -8 dB / 25 — 7 dB 11 — -7 dB / 26 — 8 dB 12 — -6 dB / 27 — 9 dB 13 — -5 dB / 255-28 — RESERVED 14 — -4 dB
RESERVED	1	0x00

5.11.9 Sub block 0x02CF – AWR_RF_IFLOOPBACK_CFG_SB

This sub block enables/disables IF loopback for all enabled profiles. This is used to debug the RX IF chain.

Table 5.66 describes the content of this sub block.

> **NOTE:** If monitoring is enabled with the loopback APIs (subblock 0x02CD, 0x02CE, 0x02CF), then loopback will not work after montoring is complete. To use loopback with monitoring, use AWR_ADVANCED_FRAME_CONF_SB with AWR_LOOPBACK_BURST_CONF_SB.

Table 5.66: AWR_RF_IFLOOPBACK_CFG_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x02CF	
SBLKLEN	2	Value = 8	
IF_LOOPBACK_FREQ	2	Value	IF Loopback frequency value
		0	180 kHz
		1	240 kHz
		2	360 kHz
		3	720 kHz
		4	1 MHz
		5	2 MHz
		6	2.5 MHz
		7	3 MHz
		8	4.017857 MHz
		9	5 MHz
		10	6 MHz
		11	8.035714 MHz
		12	9 MHz
		13	10 MHz
		65535-14	RESERVED
IF_LOOPBACK_EN	1	Value	Definition
		0	IF loopback is not enabled
		1	IF loopback is enabled
RESERVED	1	0x00	

5.11.10 Sub block 0x02D0 – AWR_RF_GPADC_CFG_SET_SB

This sub block enables the GPADC reads for external inputs (available only in xWR1642 or xWR1843).
Table 5.67 describes the content of this sub block.

Table 5.67: AWR_RF_GPADC_CFG_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x02D0
SBLKLEN	2	Value = 32
SIGNAL_INPUT_ENABLES	1	This field indicates the sets of externally fed DC signals which are to be monitored using GPADC. When each bit in this field is set, the corresponding signal is monitored. Bit Definition 0 ANALOGTEST1 1 ANALOGTEST2 2 ANALOGTEST3 3 ANALOGTEST4 4 ANAMUX 5 VSENSE Others RESERVED
SIGNAL_BUFFER_EN-ABLES	1	This field indicates the sets of externally fed DC signals which are to be buffered before being fed to the GPADC. When each bit in this field is set, the corresponding signal is buffered before the GPADC. Bit SIGNAL 0 ANALOGTEST1 1 ANALOGTEST2 2 ANALOGTEST3 3 ANALOGTEST4 4 ANAMUX Others RESERVED

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ANATEST1_CFG	2	Bit	Definition
		b7:0	Number of samples to collect 1 sample takes 1.6 μs
		b15:8	Settling time 1 LSB = 0.8 μs Valid range: 0 to 12 μs
		Valid programming condition: all the signals that are enabled should take a total of $<$ 100 μs including the programmed settling times and measurement time per enabled signal.	
ANATEST2_CFG	2	Bit	Definition
		b7:0	Number of samples to collect 1 sample takes 1.6 μs
		b15:8	Settling time 1 LSB = 0.8 μs Valid range: 0 to 12 μs
		Valid programming condition: all the signals that are enabled should take a total of $<$ 100 μs including the programmed settling times and measurement time per enabled signal.	
ANATEST3_CFG	2	Bit	Definition
		b7:0	Number of samples to collect 1 sample takes 1.6 μs
		b15:8	Settling time 1 LSB = 0.8 μs Valid range: 0 to 12 μs
		Valid programming condition: all the signals that are enabled should take a total of $<$ 100 μs including the programmed settling times and measurement time per enabled signal.	
ANATEST4_CFG	2	Bit	Definition
		b7:0	Number of samples to collect 1 sample takes 1.6 μs
		b15:8	Settling time 1 LSB = 0.8 μs Valid range: 0 to 12 μs
		Valid programming condition: all the signals that are enabled should take a total of $<$ 100 μs including the programmed settling times and measurement time per enabled signal.	

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ANAMUX_CFG	2	Bit	Definition
		b7:0	Number of samples to collect 1 sample takes 1.6 μs
		b15:8	Settling time 1 LSB = 0.8 μs Valid range: 0 to 12 μs
		Valid programming condition: all the signals that are enabled should take a total of $<$ 100 μs including the programmed settling times and measurement time per enabled signal.	
VSENSE_CFG	2	Bit	Definition
		b7:0	Number of samples to collect 1 sample takes 1.6 μs
		b15:8	Settling time 1 LSB = 0.8 μs Valid range: 0 to 12 μs
		Valid programming condition: all the signals that are enabled should take a total of $<$ 100 μs including the programmed settling times and measurement time per enabled signal.	
RESERVED	2	0x0000	
RESERVED	4	0x00000000	
RESERVED	4	0x00000000	
RESERVED	4	0x00000000	

The response to the AWR_RF_GPADC_CFG_SET_SB is an async event AWR_AE_RF_GPADC_RESULT_DATA_SB which contains the measured values for each of the enabled channels.

5.11.11 Sub block 0x02D1 – RESERVED

5.11.12 Sub block 0x02D2 – RESERVED

5.11.13 Sub block 0x02D3 – RESERVED

5.12 Sub blocks related to AWR_RF_MISC_CONF_GET_MSG

5.12.1 Sub block 0x02E0 to 0x2E9 – RESERVED

5.12.2 Sub block 0x02EA – AWR_RF_TEMPERATURE_GET_SB

This sub block provides the device temperature sensor information.
Table 5.68 describes the content of this sub block.

Table 5.68: AWR_RF_TEMPERATURE_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x02EA
SBLKLEN	2	Value = 4

AWR_RF_TEMPERATURE_DATA_SB sub block is sent by the radar device in response to AWR_RF_TEMPERATURE_GET_SB.

Table 5.69: AWR_RF_TEMPERATURE_DATA_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x02EA
SBLKLEN	2	Value = 28
TIME	4	BSS local Time from device power up 1 LSB = 1 ms
TEMP_RX0_SENS	2	RX0 temperature sensor reading (signed value) 1 LSB = 1°C
TEMP_RX1_SENS	2	RX1 temperature sensor reading (signed value) 1 LSB = 1°C
TEMP_RX2_SENS	2	RX2 temperature sensor reading (signed value) 1 LSB = 1°C
TEMP_RX3_SENS	2	RX3 temperature sensor reading (signed value) 1 LSB = 1°C
TEMP_TX0_SENS	2	TX0 temperature sensor reading (signed value) 1 LSB = 1°C
TEMP_TX1_SENS	2	TX1 temperature sensor reading (signed value) 1 LSB = 1°C
TEMP_TX2_SENS	2	TX2 temperature sensor reading (signed value) 1 LSB = 1°C
TEMP_PM_SENS	2	PM temperature sensor reading (signed value) 1 LSB = 1°C
TEMP_DIG1_SENS	2	Digital temperature sensor reading (signed value) 1 LSB = 1°C
TEMP_DIG2_SENS	2	Digital temperature sensor reading (signed value) [Applicable only in xWR1642 or xWR1843] 1 LSB = 1°C

5.13 Sub blocks related to AWR_RF_ASYNC_EVENT_MSG1

5.13.1 Sub block 0x1000 – RESERVED

5.13.2 Sub block 0x1001 – RESERVED

5.13.3 Sub block 0x1002 – AWR_AE_RF_CPUFAULT_SB

This sub block indicates CPU fault status of BIST SS.
Table 5.70 describes the content of this sub block.

Table 5.70: AWR_AE_RF_CPUFAULT_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1002
SBLKLEN	2	Value = 36
FAULT_TYPE	1	Value Definition 0 RF Processor Undefined Instruction Abort 1 RF Processor Instruction pre-fetch Abort 2 RF Processor Data Access Abort 3 RF Processor Firmware Fatal Error 0x4 - RESERVED 0xFE 0xFF No fault
RESERVED	1	0x00
LINE_NUM	2	Valid only in case of FAULT type is 0x3, provides the firmware line number at which fatal error occurred.
FAULT_LR	4	The instruction PC address at which Fault occurred
FAULT_PREV_LR	4	The return address of the function from which fault function has been called (Call stack LR)
FAULT_SPSR	4	The CPSR register value at which fault occurred
FAULT_SP	4	The SP register value at which fault occurred
FAULT_CAUSE_ADDRESS	4	The address access at which Fault occurred (valid only for fault type 0x0 to 0x2)

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FAULT_ERROR_STATUS	2	The status of Error (Error Cause type – valid only for fault type 0x0 to 0x2) 0x000 BACKGROUND_ERR 0x001 ALIGNMENT_ERR 0x002 DEBUG_EVENT 0x00D PERMISSION_ERR 0x008 SYNCH_EXTER_ERR 0x406 ASYNCH_EXTER_ERR 0x409 SYNCH_ECC_ERR 0x408 ASYNCH_ECC_ERR
FAULT_ERROR_SOURCE	1	The Source of the Error (Error Source type - valid only for fault type 0x0 to 0x2) 0x0 ERR_SOURCE_AXI_MASTER 0x1 ERR_SOURCE_ATCM 0x2 ERR_SOURCE_BTCM
FAULT_AXI_ER-ROR_TYPE	1	The AXI Error type (Error Source type - valid only for fault type 0x0 to 0x2) 0x0 AXI_DECOD_ERR 0x1 AXI_SLAVE_ERR
FAULT_ACCESS_TYPE	1	The Error Access type (Error Access type - valid only for fault type 0x0 to 0x2) 0x0 READ_ERR 0x1 WRITE_ERR
FAULT_RECOV-ERY_TYPE	1	The Error Recovery type (Error Recovery type - Valid only for fault type 0x0 to 0x2) 0x0 UNRECOVERY 0x1 RECOVERY
RESERVED	2	0x0000

5.13.4 Sub block 0x1003 – AWR_AE_RF_ESMFAULT_SB

This sub block indicates the status of any other faults in the BIST SS.
Table 5.71 describes the content of this sub block.

Table 5.71: AWR_AE_RF_ESMFAULT_STATUS_SB response contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x1003	
SBLKLEN	2	Value = 12	
ESM_GROUP1_ ERRORS	4	Bit	Error Information
		b0	RAMPGEN_SB_ERROR
		b1	RESERVED
		b2	GPADC_RAM_SB_ERROR
		b3	VIM_RAM_SB_ERROR
		b4	DFE_SELFTEST_ERROR
		b5	VIM_SELFTEST_ERRROR
		b6	B0TCM_SB_ERROR
		b7	B1TCM_SB_ERROR
		b8	CCMR4_SELFTEST_ERROR
		b9	ATCM_SB_ERROR
		b10	RAMPGEN_SELFTEST_ERROR
		b11	RAMPGEN_PAR_SELFTST_ERROR
		b12	SEQ_EXT_SELFTEST_ERROR
		b13	SEQ_EXT_SB_ERROR
		b14	RESERVED
		b15	AGC_RAM_SB_ERROR
		b16	B1TCM_PAR_CHK_ERROR
		b17	B0TCM_PAR_CHK_ERROR
		b18	ATCM_PAR_CHK_ERROR
		b19	MB_MSS2BSS_SB_ERROR
		b20	MB_BSS2MSS_SB_ERROR
		b31:21	RESERVED

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Table 5.71 – continued from previous page

ESM_GROUP2_ERRORS	4	Bit	Error Information
		b0	DFE_STC_ERROR
		b1	CR4_STC_ERROR
		b2	CCMR4_COMP_ERROR
		b3	B0TCM_DB_ERROR
		b4	B1TCM_DB_ERROR
		b5	ATCM_DB_ERROR
		b6	DCC_ERROR
		b7	SEQ_EXT_ERROR
		b8	SYNT_FREQ_MON_ERROR
		b9	DFE_PARITY_ERROR
		b10	RAMPGEN_DB_ERROR
		b11	BUBBLE_CORRECTION_FAIL
		b12	RAMPGEN_LOCSTEP_ERROR
		b13	RTI_RESET_ERROR
		b14	GPADC_RAM_DB_ERROR
		b15	VIM_COMP_ERROR
		b16	CR4_LIVE_LOCK_ERROR
		b17	WDT_NMI_ERROR
		b18	VIM_RAM_DB_ERROR
		b19	RAMPGEN_PAR_ERROR
		b20	SEQ_EXT_DB_ERROR
		b21	DMA_MPU_ERROR
		b22	AGC_RAM_DB_ERROR
		b23	CRC_COMP_ERROR
		b24	WAKEUP_STS_ERROR
		b25	SHORT_CIRCUIT_ERROR
		b26	B1TCM_PAR_ERROR
		b27	B0TCM_PAR_ERROR
		b28	ATCM_PAR_ERROR
		b29	MB_MSS2BSS_DB_ERROR
		b30	MB_BSS2MSS_DB_ERROR
		b31	CCC_ERROR

5.13.5 Sub block 0x1004 – AWR_AE_RF_INITCALIBSTATUS_SB

This sub block indicates the initial calibrations of RF BIST SS are complete.

Table 5.72 describes the content of this sub block.

Table 5.72: AWR_AE_RF_INITCALIBSTATUS_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1004
SBLKLEN	2	Value = 24
CALIBRATION_ STATUS	4	This field indicates the status of each calibration (0 – FAIL, 1 – PASS). If a particular calibration was not enabled, then its corresponding field should be ignored.
		Bit — Definition (0 – FAIL, 1 – PASS)
		b0 — RESERVED
		b1 — APLL tuning
		b2 — SYNTH VCO1 tuning
		b3 — SYNTH VCO2 tuning
		b4 — LODIST calibration
		b5 — RX ADC DC offset calibration
		b6 — HPF cutoff calibration
		b7 — LPF cutoff calibration
		b8 — Peak detector calibration
		b9 — TX Power calibration
		b10 — RX gain calibration
		b11 — TX Phase calibration
		b12 — RX IQMM calibration
		b31:13 — RESERVED

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Table 5.72 – continued from previous page

CALIBRATION_UPDATE	4	This field indicates if a particular calibration data has been updated in hardware. (0 – no update, 1 – updated)
		Bit Definition
		b0 RESERVED
		b1 APLL tuning
		b2 SYNTH VCO1 tuning
		b3 SYNTH VCO2 tuning
		b4 LODIST calibration
		b5 RX ADC DC offset calibration
		b6 HPF cutoff calibration
		b7 LPF cutoff calibration
		b8 Peak detector calibration
		b9 TX Power calibration
		b10 RX gain calibration
		b11 TX Phase calibration
		b12 RX IQMM calibration
		b31:13 RESERVED
TEMPERATURE	2	Measured temperature, based on average of temperature sensors near all enabled TX and RX channels at the time of calibration. 1 LSB = 1°C
RESERVED	2	0x0000
TIME_STAMP	4	This field indicates time stamp at the time of performing calibration updates. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)
RESERVED	4	0x00000000

5.13.6 Sub block 0x1005 – RESERVED

5.13.7 Sub block 0x1006 – RESERVED

5.13.8 Sub block 0x1007 – RESERVED

5.13.9 Sub block 0x1008 – RESERVED

5.13.10 Sub block 0x1009 – RESERVED

5.13.11 Sub block 0x100A – RESERVED

5.13.12 Sub block 0x100B – AWR_AE_RF_FRAME_TRIGGER_RDY_SB

This sub block indicates that the slave device is now ready to receive the external sync in for frame triggers. In SW triggered mode, this async event indicates that frames are triggered. Table 5.73 describes the content of this sub block.

Table 5.73: AWR_AE_RF_FRAME_TRIGGER_RDY_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x100B
SBLKLEN	2	Value = 4

5.13.13 Sub block 0x100C – AWR_AE_RF_GPADC_RESULT_DATA_SB

This sub block indicates that GPADC measurement is complete and it also contains the measured data of each of the enabled channels. The data for channels which are not enabled can be ignored.
Table 5.74 describes the content of this sub block.

Table 5.74: AWR_AE_RF_GPADC_RESULT_DATA_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x100C
SBLKLEN	2	Value = 76
ANATEST1_MIN_DATA	2	Minimum GPADC reading across the captured samples for ANATEST1 input 1 LSB = 1.8V/1024
ANATEST1_MAX_DATA	2	Maximum GPADC reading across the captured samples for ANATEST1 input 1 LSB = 1.8V/1024

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Table 5.74 – continued from previous page

ANATEST1_AVG_DATA	2	Average GPADC reading across the captured samples for ANATEST1 input 1 LSB = 1.8V/1024
ANATEST2_MIN_DATA	2	Minimum GPADC reading across the captured samples for ANATEST2 input 1 LSB = 1.8V/1024
ANATEST2_MAX_DATA	2	Maximum GPADC reading across the captured samples for ANATEST2 input 1 LSB = 1.8V/1024
ANATEST2_AVG_DATA	2	Average GPADC reading across the captured samples for ANATEST2 input 1 LSB = 1.8V/1024
ANATEST3_MIN_DATA	2	Minimum GPADC reading across the captured samples for ANATEST3 input 1 LSB = 1.8V/1024
ANATEST3_MAX_DATA	2	Maximum GPADC reading across the captured samples for ANATEST3 input 1 LSB = 1.8V/1024
ANATEST3_AVG_DATA	2	Average GPADC reading across the captured samples for ANATEST3 input 1 LSB = 1.8V/1024
ANATEST4_MIN_DATA	2	Minimum GPADC reading across the captured samples for ANATEST4 input 1 LSB = 1.8V/1024
ANATEST4_MAX_DATA	2	Maximum GPADC reading across the captured samples for ANATEST4 input 1 LSB = 1.8V/1024
ANATEST4_AVG_DATA	2	Average GPADC reading across the captured samples for ANATEST4 input 1 LSB = 1.8V/1024
ANAMUX_MIN_DATA	2	Minimum GPADC reading across the captured samples for ANAMUX input 1 LSB = 1.8V/1024
ANAMUX_MAX_DATA	2	Maximum GPADC reading across the captured samples for ANAMUX input 1 LSB = 1.8V/1024
ANAMUX_AVG_DATA	2	Average GPADC reading across the captured samples for ANAMUX input 1 LSB = 1.8V/1024
VSENSE_MIN_DATA	2	Minimum GPADC reading across the captured samples for VSENSE input 1 LSB = 1.8V/1024

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Table 5.74 – continued from previous page

VSENSE_MAX_DATA	2	Maximum GPADC reading across the captured samples for VSENSE input 1 LSB = 1.8V/1024
VSENSE_AVG_DATA	2	Average GPADC reading across the captured samples for VSENSE input 1 LSB = 1.8V/1024
RESERVED	2	0x0000
RESERVED	2	0x0000
RESERVED	2	0x0000
RESERVED	2	0x0000
RESERVED	4	0x00000000
RESERVED	4	0x00000000
RESERVED	4	0x00000000
RESERVED	4	0x00000000
RESERVED	4	0x00000000
RESERVED	4	0x00000000
RESERVED	4	0x00000000

5.13.14 Sub block 0x100E – RESERVED

5.13.15 Sub block 0x100D – RESERVED

5.13.16 Sub block 0x100E – RESERVED

5.13.17 Sub block 0x100F – AWR_FRAME_END_AE_SB

This sub block indicates end of the frames.
Table 5.75 describes the content of this sub block.

Table 5.75: AWR_FRAME_END_AE_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x100F
SBLKLEN	2	Value = 4

5.13.18 Sub block 0x1010 – AWR_ANALOGFAULT_AE_SB

This sub block indicates fault in analog supplies or LDO short circuit condition. Once a fault is detected the functionality cannot be resumed from then on and the sensor needs to be re-started.

Table 5.76: AWR_ANALOGFAULT_AE_SB response contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x1010	
SBLKLEN	2	Value = 16	
FAULT_TYPE	1	Value	Definition
		0	NO FAULT
		1	ANALOG_SUPPLY_FAULT
		Others	RESERVED
RESERVED	1	0x00	
RESERVED	2	0x0000	
FAULT_SIG	4	Bit	Definition
		b0	1.8V BB ANA supply fault detected
		b1	13V/1.0V RF supply fault detected
		b2	Synth VCO LDO short circuit detected
		b3	PA LDO short circuit detected
		b31:4	RESERVED
RESERVED	4	0x00000000	

5.13.19 Sub block 0x1011 – AWR_CAL_MON_TIMING_FAIL_REPORT_AE_SB

This sub block indicates any timing failure related to calibration or monitoring.
Table 5.77 describes the content of this sub block.

Table 5.77: AWR_CAL_MON_TIMING_FAIL_REPORT_AE_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1011
SBLKLEN	2	Value = 8

Continued on next page

Table 5.77 – continued from previous page

TIMING_FAIL-URE_CODE	2	Bit	Definition	
		b0	RESERVED	
		b1	0	No Failure
			1	Total monitoring and calibration time do not fit in one CALIB_MON_TIME_UNIT in AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER when ONE_TIME_CALIB is enabled
		b2	0	No Failure
			1	Total monitoring and calibration time do not fit in one CALIB_MON_TIME_UNIT in AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER when PERIODIC_CALIB is enabled
		b3	0	No Failure
			1	Runtime timing violation: Monitoring functions or calibrations could not be completed in one CALIB_MON_TIME_UNIT
		b15:4	RESERVED	
RESERVED	2	0x0000		

5.13.20 Sub block 0x1012 – AWR_RUN_TIME_CALIB_SUMMARY_REPORT_AE_SB

This sub block indicates the calibration status (one time or run time) if the calibration reports are enabled in the AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB.

> **NOTE:** The calibration report is sent if the calibrations are triggered due to temperature change or whenever the internal calibratons are triggered i.e. every 1 s

Table 5.78: AWR_RUN_TIME_CALIB_SYMMARY_REPORT_AE_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1012
SBLKLEN	2	Value = 24

Table 5.78 – continued from previous page

CALIBRATION_ ERROR_FLAG	4	This field indicates the status of each calibration. 1 - calibration is passed, 0 - calibration is failed or not enabled/performed at least once.
		Bit Definition
		b0 RESERVED
		b1 APLL tuning
		b2 SYNTH VCO1 tuning
		b3 SYNTH VCO2 tuning
		b4 LODIST calibration
		b5 RESERVED
		b6 RESERVED
		b7 RESERVED
		b8 PD calibration
		b9 TX power calibration
		b10 RX gain calibration
		b11 RESERVED
		b12 RESERVED
		b31:13 RESERVED
CALIBRATION_ UPDATE_STATUS	4	Each bit corresponding to a calibration indicates if each calibration resulted in a reconfiguration of RF is indicated by a value of 1 in the respective bit in this field. 0 – Analog/RF is not updated 1 – Analog/RF is updated after a respective calibration
		Bit Definition
		b0 RESERVED
		b1 APLL tuning
		b2 SYNTH VCO1 tuning
		b3 SYNTH VCO2 tuning
		b4 LODIST calibration
		b5 RESERVED
		b6 RESERVED
		b7 RESERVED
		b8 PD calibration
		b9 TX power calibration
		b10 RX gain calibration
		b11 RESERVED
		b12 RESERVED
		b31:13 RESERVED

Table 5.78 – continued from previous page

TEMPERATURE	2	Measured temperature, based on average of temperature sensors near all enabled TX and RX channels at the time of calibration. 1 LSB = 1°C
RESERVED	2	RESERVED
TIME_STAMP	4	This field indicates time stamp at the time of performing calibration updates. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)
RESERVED	4	0x00000000

5.13.21 Sub block 0x1013 – AWR_MONITOR_RF_DIG_LATENTFAULT_REPORT_AE_SB

This async event contains the status of digital monitoring for latent faults.

Table 5.79: AWR_MONITOR_RF_DIG_LATENTFAULT_REPORT_AE_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1013
SBLKLEN	2	Value = 8

Continued on next page

Table 5.79 – continued from previous page

DIG_MON_LATENT_FAULT_STATUS	4	1 – PASS, 0 – FAIL	
		Bit	Definition
		b0	RESERVED
		b1	CR4 and VIM lockstep test
		b2	RESERVED
		b3	VIM test
		b4	RESERVED
		b5	RESERVED
		b6	CRC test
		b7	RAMPGEN memory ECC test
		b8	DFE Parity test
		b9	DFE memory ECC test
		b10	RAMPGEN lockstep test
		b11	FRC lockstep test
		b12	RESERVED
		b13	RESERVED
		b14	RESERVED
		b15	RESERVED
		b16	ESM test
		b17	DFE STC
		b18	RESERVED
		b19	ATCM, BTCM ECC test
		b20	ATCM, BTCM parity test
		b21	RESERVED
		b22	RESERVED
		b23	RESERVED
		b24	FFT test
		b25	RTI test
		b26	PCR test
		b31:27	RESERVED

5.13.22 Sub block 0x1014 – RESERVED

5.13.23 Sub block 0x1015 – AWR_MONITOR_REPORT_HEADER_AE_SB

The report header includes common information across all enabled monitors like current FTTI number and current temperature.

Table 5.80: AWR_MONITORING_REPORT_HEADER_AE_SB response contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1015
SBLKLEN	2	Value = 12
FTTI_COUNT	4	FTTI free running counter value, incremented every CAL_MON_TIME_UNIT
AVG_TEMPERA-TURE	2	Average temperature at which was monitoring performed
RESERVED	2	0x0000

5.13.24 Sub block 0x1016 – AWR_MONITOR_RF_DIG_PERIODIC_REPORT_AE_SB

This async event is sent periodically to indicate the status of periodic digital monitoring tests.

Table 5.81: AWR_MONITOR_RF_DIG_PERIODIC_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1016
SBLKLEN	2	Value = 12
RF_DIG_MON_PERIODIC_STA-TUS	4	1 – PASS, 0 – FAIL **Bit Monitoring type** b0 PERIODIC_CONFIG_REGISTER_READ b1 ESM_MONITORING b2 DFE_STC b3 FRAME_TIMING_MONITORING b31:4 RESERVED
TIMESTAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.13.25 Sub block 0x1017 – AWR_MONITOR_TEMPERATURE_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured temperature near various RF analog and digital modules. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.82: AWR_MONITORING_TEMPERATURE_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1017
SBLKLEN	2	Value = 36
STATUS_FLAGS	2	Status flags indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_ANA_TEMP_MIN b1 STATUS_ANA_TEMP_MAX b2 STATUS_DIG_TEMP_MIN b3 STATUS_DIG_TEMP_MAX b4 STATUS_TEMP_DIFF_THRESH b15:5 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
TEMP_VALUES	20	The measured onchip temperature is reported here. Byte numbers corresponding to different temperature sensors reported in this field are here: Bytes Temperature sensor 1:0 TEMP_RX0 3:2 TEMP_RX1 5:4 TEMP_RX2 7:6 TEMP_RX3 9:8 TEMP_TX0 11:10 TEMP_TX1 13:12 TEMP_TX2 15:14 TEMP_PM 17:16 TEMP_DIG1 19:18 TEMP_DIG2 (Applicable only in xWR1642 or xWR1843) 1 LSB = 1°C, signed number
RESERVED	4	0x00000000

Table 5.82 – continued from previous page

TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.13.26 Sub block 0x1018 – AWR_MONITOR_RX_GAIN_PHASE_REPORT_AE_SB

This sub block is a monitoring report which the AWR device sends to the host, containing the measured RX gain and phase values. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.83: AWR_MONITOR_RX_GAIN_PHASE_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1018
SBLKLEN	2	Value = 72
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_RX_GAIN_ABS b1 STATUS_RX_GAIN_MISMATCH b2 STATUS_RX_GAIN_FLATNESS b3 STATUS_RX_PHASE_MISMATCH b15:4 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies.
RESERVED	3	0x000000

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Table 5.83 – continued from previous page

RX_GAIN_VALUE	24	The measured RX gain for each enabled channel, at each enabled RF frequency (i.e., lowest, center and highest in the profile's RF band) is reported here. Byte numbers corresponding to different RX and RF, in this field are here: 　　　　RF1　　RF2　　RF3 RX0　　1:0　　9:8　　17:16 RX1　　3:2　　11:10　19:18 RX2　　5:4　　13:12　21:20 RX3　　7:6　　15:14　23:22 1 LSB = 0.1 dB Only the entries of enabled RF Frequencies and enabled RX channels are valid.
RX_PHASE_VALUE	24	The measured RX phase for each enabled channel, at each enabled RF frequency is reported here. Byte numbers corresponding to different RX and RF, in this field are here: 　　　　RF1　　RF2　　RF3 RX0　　1:0　　9:8　　17:16 RX1　　3:2　　11:10　19:18 RX2　　5:4　　13:12　21:20 RX3　　7:6　　15:14　23:22 1 LSB = $360°/2^{16}$ Only the entries of enabled RF Frequencies and enabled RX channels are valid. **NOTE:** These phases include an unknown bias common to all RX channels.
RESERVED	4	0x00000000
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.13.27 Sub block 0x1019 – AWR_MONITOR_RX_NOISE_FIGURE_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured RX noise figure values corresponding to the full IF band of a profile. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.84: AWR_MONITOR_RX_NOISE_FIGURE_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1019
SBLKLEN	2	Value = 52
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit**　　**STATUS_FLAG for monitor** b0　　　STATUS_RX_NOISE_FIGURE b15:1　　RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies.
RESERVED	3	0x000000
RX_NOISE_FIG-URE_VALUE	24	The measured RX input referred for each enabled channel, at each enabled RF frequency is reported here. Byte numbers corresponding to different RX and RF, in this field are here: 　　　　RF1　　RF2　　RF3 RX0　　1:0　　9:8　　17:16 RX1　　3:2　　11:10　　19:18 RX2　　5:4　　13:12　　21:20 RX3　　7:6　　15:14　　23:22 1 LSB = 0.1 dB Only the entries of enabled RF Frequencies and enabled RX channels are valid.
RESERVED	4	0x00000000
RESERVED	4	0x00000000
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

NOTE:	The noise monitor reports the real receivers' noise figure. In complex receiver modes (i.e., complex 1x, complex 2x and pseudo real), the system noise figure is 3dB lower (better) than the reported number

5.13.28 Sub block 0x101A – AWR_MONITOR_RX_IFSTAGE_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured RX IF filter attenuation values at the given IF frequencies. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.85: AWR_MONITOR_RX_IFSTAGE_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x101A
SBLKLEN	2	Value = 48
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_RX_HPF_ERROR b1 STATUS_RX_LPF_ERROR b2 STATUS_RX_IFA_GAIN_ERROR b15:3 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies.
RESERVED	3	0x000000

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Table 5.85 – continued from previous page

HPF_CUTOFF_FREQ_ERROR_VALUE	8	The deviations of RX IFA HPF cutoff frequency from the ideally expected values for all the enabled RX channels are reported here.

HPF_CUTOFF_FREQ_ERROR = 100*(Measured Cutoff Frequency / Expected Cutoff Frequency) – 100, for RX IF filter in the HPF region.

Byte numbers corresponding to measured cutoff frequency error on different RX channels, in this field are here:

	I channel	Q channel
RX0	0	4
RX1	1	5
RX2	2	6
RX3	3	7

1 LSB = 1%, signed number
Applicable only for the enabled channels.

LPF_CUTOFF_FREQ_ERROR_VALUE	8	The deviations of RX IFA LPF cutoff frequency from the ideally expected values for all the enabled RX channels are reported here.

LPF_CUTOFF_FREQ_ERROR = 100×(Measured Cutoff Frequency / Expected Cutoff Frequency) – 100, for RX IF filter in the LPF region.

Byte numbers corresponding to measured cutoff frequency error on different RX channels, in this field are here:

	I channel	Q channel
RX0	0	4
RX1	1	5
RX2	2	6
RX3	3	7

1 LSB = 1%, signed number
Applicable only for the enabled channels.

Table 5.85 – continued from previous page

RX_IFA_GAIN_ ERROR_VALUE	8	The deviations of RX IFA Gain from the ideally expected values for all the enabled RX channels are reported here. Byte numbers corresponding to measured cutoff frequency error on different RX channels and HPF/LPF, in this field are here: I channel Q channel RX0 0 4 RX1 1 5 RX2 2 6 RX3 3 7 1 LSB = 0.1 dB, signed number Applicable only for the enabled channels.
IFA_GAIN_EXP	1	Expected IFA gain 1 LSB = 1 dB
RESERVED	3	0x000000
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.13.29 Sub block 0x101B – AWR_MONITOR_TX0_POWER_REPORT_AE_SB

NOTE:	The TX[0:2] power monitoring accuracy degrades at high TX backoffs and is unreliable for backoffs higher than 20dB.

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX power values during an explicit monitoring chirp. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.86: AWR_MONITOR_TX0_POWER_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x101B
SBLKLEN	2	Value = 24

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Table 5.86 – continued from previous page

STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_ABS_ERR b1 STATUS_FLATNESS_ERR b15:2 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
RESERVED	3	0x000000
TX_POWER_VALUE	6	The measured TX power for each enabled channel, at each enabled RF frequency is reported here. Byte numbers corresponding to different TX and RF, in this field are here: RF1 RF2 RF3 TX0 1:0 3:2 5:4 (other bytes are reserved) 1 LSB = 0.1 dBm, signed number Only the entries of enabled RF Frequencies and enabled RX channels are valid.
RESERVED	2	0x0000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.13.30 Sub block 0x101C – AWR_MONITOR_TX1_POWER_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX power values during an explicit monitoring chirp. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.87: AWR_MONITOR_TX1_POWER_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x101C
SBLKLEN	2	Value = 24
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_ABS_ERR b1 STATUS_FLATNESS_ERR b15:2 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
RESERVED	3	0x000000
TX_POWER_VALUE	6	The measured TX power for each enabled channel, at each enabled RF frequency is reported here. Byte numbers corresponding to different TX and RF, in this field are here: RF1 RF2 RF3 TX1 1:0 3:2 5:4 (other bytes are reserved) 1 LSB = 0.1 dBm, signed number Only the entries of enabled RF Frequencies and enabled RX channels are valid.
RESERVED	2	0x0000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.13.31 Sub block 0x101D – AWR_MONITOR_TX2_POWER_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX power values during an explicit monitoring chirp. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.88: AWR_MONITOR_TX2_POWER_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x101D
SBLKLEN	2	Value = 24
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_ABS_ERR b1 STATUS_FLATNESS_ERR b15:2 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
RESERVED	3	0x000000
TX_POWER_ VALUE	6	The measured TX power for each enabled channel, at each enabled RF frequency is reported here. Byte numbers corresponding to different TX and RF, in this field are here: RF1 RF2 RF3 TX2 1:0 3:2 5:4 (other bytes are reserved) 1 LSB = 0.1 dBm, signed number Only the entries of enabled RF Frequencies and enabled RX channels are valid.
RESERVED	2	0x0000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.13.32 Sub block 0x101E – AWR_MONITOR_TX0_BALLBREAK_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX reflection coefficient's magnitude values, meant for detecting TX ball break. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.89: AWR_MONITOR_TX0_BALLBREAK_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x101E
SBLKLEN	2	Value = 20
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit**　　　**STATUS_FLAG for monitor** b0　　　STATUS_TX0_BALLBREAK b15:1　　RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
TX_REFL_CO-EFF_VALUE	2	The TX reflection coefficient's magnitude for this channel is reported here. 1 LSB = 0.1 dB, signed number
RESERVED	2	0x0000
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.13.33 Sub block 0x101F – AWR_MONITOR_TX1_BALLBREAK_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX reflection coefficient's magnitude values, meant for detecting TX ball break. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.90: AWR_MONITOR_TX1_BALLBREAK_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x101F
SBLKLEN	2	Value = 20

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STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_TX0_BALLBREAK b15:1 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
TX_REFL_CO-EFF_VALUE	2	The TX reflection coefficient's magnitude for this channel is reported here. 1 LSB = 0.1 dB, signed number
RESERVED	2	0x0000
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14 Sub blocks related to AWR_RF_ASYNC_EVENT_MSG2

5.14.1 Sub block 0x1020 – AWR_MONITOR_TX2_BALLBREAK_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX reflection coefficient's magnitude values, meant for detecting TX ball break. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.91: AWR_MONITOR_TX2_BALLBREAK_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1020
SBLKLEN	2	Value = 20

Table 5.91 – continued from previous page

STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit**　　**STATUS_FLAG for monitor** b0　　　STATUS_TX0_BALLBREAK b15:1　　RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
TX_REFL_CO-EFF_VALUE	2	The TX reflection coefficient's magnitude for this channel is reported here. 1 LSB = 0.1 dB, signed number
RESERVED	2	0x0000
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.2 Sub block 0x1021 – AWR_MONITOR_TX_GAIN_PHASE_MISMATCH_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX gain and phase mismatch values during an explicit monitoring chirp. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.92: AWR_MONITOR_TX_GAIN_PHASE_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1021
SBLKLEN	2	Value = 60

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Table 5.92 – continued from previous page

STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_TX_GAIN_MISMATCH b1 STATUS_TX_PHASE_MISMATCH b15:2 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
RESERVED	3	0x000000
TX_GAIN_VALUE	18	The measured TX PA loopback tone power at the RX ADC input, for each enabled TX channel, at each enabled RF frequency is reported here. Byte numbers corresponding to different TX and RF, in this field are here: RF1 RF2 RF3 TX0 1:0 7:6 13:12 TX1 3:2 9:8 15:14 TX2 5:4 11:10 17:16 1 LSB = 0.1dBm, signed number Only the entries of enabled RF Frequencies and enabled TX channels are valid.
TX_PHASE_VALUE	18	The measured TX phase for each enabled channel, at each enabled RF frequency is reported here. Byte numbers corresponding to different TX and RF, in this field are here: RF1 RF2 RF3 TX0 1:0 7:6 13:12 TX1 3:2 9:8 15:14 TX2 5:4 11:10 17:16 1 LSB = $360°/2^{16}$ Only the entries of enabled RF Frequencies and enabled TX channels are valid. **NOTE:** these phases include an unknown bias common to all TX channels.
RESERVED	4	0x00000000

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Table 5.92 – continued from previous page

RESERVED	4	0x00000000
TIMESTAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.3 Sub block 0x1022 – AWR_MONITOR_TX0_BPM_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX0 BPM error values. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.93: AWR_MONITOR_TX0_BPM_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1022
SBLKLEN	2	Value = 20
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_TX0_BPM_PHASE b1 STATUS_TX0_BPM_AMPLITUDE b15:2 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
PH_SHIFTER_MON_VAL2_MSB	1	MSB of the monitored phase shift for PH_SHIFTER_MON2 for TX0 When combined with PH_SHIFTER_MON_VAL2_LSB, this represents the phase shift value in 16 bits. PH_SHIFTER_MON_VAL2 = PH_SHIFTER_MON_VAL2_MSB $\times 2^8$ + PH_SHIFTER_MON_VAL2_LSB
PH_SHIFTER_MON_VAL1	2	Monitored phase shift for PH_SHIFTER_MON1 for TX0 1 LSB = $360°/2^{16}$

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Table 5.93 – continued from previous page

TX_BPM_PHASE_DIFF_VALUE	2	The TX output phase difference between the two BPM settings (phase for TX BPM setting 0 – phase for TX BPM setting 1) is reported here. 1 LSB = $360°/2^{16}$
TX_BPM_AMPLITUDE_DIFF_VALUE	1	The deviation of the TX output amplitude difference between the two BPM settings (amplitude for TX BPM setting 0 – amplitude for TX BPM setting 1) from the ideal 0dB is reported here. 1 LSB = 0.1 dB, signed number
PH_SHIFTER_MON_VAL2_LSB	1	LSB of the monitored phase shift for PH_SHIFTER_MON2 for TX0 When combined with PH_SHIFTER_MON_VAL2_MSB, this represents the phase shift value in 16 bits. PH_SHIFTER_MON_VAL2 = PH_SHIFTER_MON_VAL2_MSB $\times 2^8$ + PH_SHIFTER_MON_VAL2_LSB 1 LSB = $360°/2^{16}$
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.4 Sub block 0x1023 – AWR_MONITOR_TX1_BPM_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX1 BPM error values. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.94: AWR_MONITOR_TX1_BPM_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1023
SBLKLEN	2	Value = 20
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_TX1_BPM_PHASE b1 STATUS_TX1_BPM_AMPLITUDE b15:2 RESERVED 0 – FAIL or check wasn't done 1 – PASS

Table 5.94 – continued from previous page

ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
PH_SHIFTER_MON_VAL2_MSB	1	MSB of the monitored phase shift for PH_SHIFTER_MON2 for TX1 When combined with PH_SHIFTER_MON_VAL2_LSB, this represents the phase shift value in 16 bits. PH_SHIFTER_MON_VAL2 = PH_SHIFTER_MON_VAL2_MSB $\times 2^8$ + PH_SHIFTER_MON_VAL2_LSB
PH_SHIFTER_MON_VAL1	2	Monitored phase shift for PH_SHIFTER_MON1 for TX1 1 LSB = $360°/2^{16}$
TX_BPM_PHASE_DIFF_VALUE	2	The TX output phase difference between the two BPM settings (phase for TX BPM setting 0 – phase for TX BPM setting 1) is reported here. 1 LSB = $360°/2^{16}$
TX_BPM_AMPLITUDE_DIFF_VALUE	1	The deviation of the TX output amplitude difference between the two BPM settings (amplitude for TX BPM setting 0 – amplitude for TX BPM setting 1) from the ideal 0dB is reported here. 1 LSB = 0.1 dB, signed number
PH_SHIFTER_MON_VAL2_LSB	1	LSB of the monitored phase shift for PH_SHIFTER_MON2 for TX0 When combined with PH_SHIFTER_MON_VAL2_MSB, this represents the phase shift value in 16 bits. PH_SHIFTER_MON_VAL2 = PH_SHIFTER_MON_VAL2_MSB $\times 2^8$ + PH_SHIFTER_MON_VAL2_LSB 1 LSB = $360°/2^{16}$
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.5 Sub block 0x1024 – AWR_MONITOR_TX2_BPM_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured TX2 BPM error values. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.95: AWR_MONITOR_TX2_BPM_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1024
SBLKLEN	2	Value = 20
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit**　　　**STATUS_FLAG for monitor** b0　　　STATUS_TX2_BPM_PHASE b1　　　STATUS_TX2_BPM_AMPLITUDE b15:2　　RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
PH_SHIFTER_ MON_VAL2_MSB	1	MSB of the monitored phase shift for PH_SHIFTER_MON2 for TX2 When combined with PH_SHIFTER_MON_VAL2_LSB, this represents the phase shift value in 16 bits. PH_SHIFTER_MON_VAL2 = PH_SHIFTER_MON_VAL2_MSB $\times 2^8$ + PH_SHIFTER_MON_VAL2_LSB
PH_SHIFTER_ MON_VAL1	2	Monitored phase shift for PH_SHIFTER_MON1 for TX2 1 LSB = $360°/2^{16}$
TX_BPM_PHASE_ DIFF_VALUE	2	The TX output phase difference between the two BPM settings (phase for TX BPM setting 0 – phase for TX BPM setting 1) is reported here. 1 LSB = $360°/2^{16}$
TX_BPM_AM-PLITUDE_DIFF_ VALUE	1	The deviation of the TX output amplitude difference between the two BPM settings (amplitude for TX BPM setting 0 – amplitude for TX BPM setting 1) from the ideal 0dB is reported here. 1 LSB = 0.1 dB, signed number
PH_SHIFTER_ MON_VAL2_LSB	1	LSB of the monitored phase shift for PH_SHIFTER_MON2 for TX0 When combined with PH_SHIFTER_MON_VAL2_MSB, this represents the phase shift value in 16 bits. PH_SHIFTER_MON_VAL2 = PH_SHIFTER_MON_VAL2_MSB $\times 2^8$ + PH_SHIFTER_MON_VAL2_LSB 1 LSB = $360°/2^{16}$

Table 5.95 – continued from previous page

TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.6 Sub block 0x1025 – AWR_MONITOR_SYNTHESIZER_FREQUENCY_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing information related to measured frequency error during the chirp. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.96: AWR_MONITOR_SYNTH_FREQUENCY_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1025
SBLKLEN	2	Value = 32
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_SYNTH_FREQ_ERR b15:1 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
RESERVED	3	0x000000
MAX_FRE-QUENCY_ER-ROR_VALUE	4	This field indicates the maximum instantaneous frequency error measured during the chirps for which frequency monitoring has been enabled in the previous monitoring period. Bits Parameter b31:0 Maximum frequency error value, signed number. 1 LSB = 1 kHz.

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FREQUENCY_FAILURE_COUNT	4	This field indicates the number of times during chirping in the previous monitoring period in which the measured frequency error violated the allowed threshold. Frequency error threshold violation is counted every 10 ns.
		Bits Parameter
		b31:19 RESERVED
		b18:0 Failure count, unsigned number
RESERVED	4	0x00000000
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.7 Sub block 0x1026 – AWR_MONITOR_EXTERNAL_ANALOG_SIGNALS_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the external signal voltage values measured using the GPADC. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.97: AWR_MONITOR_EXTERNAL_ANALOG_SIGNALS_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1026
SBLKLEN	2	Value = 28

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Table 5.97 – continued from previous page

STATUS_FLAGS	2	Status flags indicating pass fail results corresponding to various threshold checks under this monitor. Bit Definition b0 STATUS_ANALOGTEST1 b1 STATUS_ANALOGTEST2 b2 STATUS_ANALOGTEST3 b3 STATUS_ANALOGTEST4 b4 STATUS_ANAMUX b5 STATUS_VSENSE b15:6 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
EXTERNAL_ANA-LOG_SIGNAL_VALUES	12	MEASURED_VALUE Bytes SIGNAL 1:0 ANALOGTEST1 3:2 ANALOGTEST2 5:4 ANALOGTEST3 7:6 ANALOGTEST4 9:8 ANAMUX 11:10 VSENSE 1 LSB = 1.8V/1024
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.8 Sub block 0x1027 – AWR_MONITOR_TX0_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing information about Internal TX0 internal analog signals. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.98: AWR_MONITOR_TX0_INTERNAL_ANALOG_SIGNALS_REPORT_AE_
SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1027
SBLKLEN	2	Value = 16
STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_SUPPLY_TX0 b1 STATUS_DCBIAS_TX0 b15:2 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
RESERVED	3	0x000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.9 Sub block 0x1028 – AWR_MONITOR_TX1_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing information about Internal TX1 internal analog signals. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.99: AWR_MONITOR_TX1_INTERNAL_ANALOG_SIGNALS_REPORT_AE_
SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1028
SBLKLEN	2	Value = 16

Table 5.99 – continued from previous page

STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor.
		Bit **STATUS_FLAG for monitor** b0 STATUS_SUPPLY_TX1 b1 STATUS_DCBIAS_TX1 b15:2 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
RESERVED	3	0x000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.10 Sub block 0x1029 – AWR_MONITOR_TX2_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing information about Internal TX2 internal analog signals. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.100: AWR_MONITOR_TX2_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1029
SBLKLEN	2	Value = 16

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Table 5.100 – continued from previous page

STATUS_FLAGS	2	Status flag indicating pass fail results corresponding to various threshold checks under this monitor. **Bit**　　**STATUS_FLAG for monitor** b0　　STATUS_SUPPLY_TX2 b1　　STATUS_DCBIAS_TX2 b15:2　　RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
RESERVED	3	0x000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.11 Sub block 0x102A – AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_ REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing information about Internal RX internal analog signals. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.101: AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_REPORT_ AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x102A
SBLKLEN	2	Value = 16

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STATUS_FLAGS	2	Status flags indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_SUPPLY_RX0 b1 STATUS_SUPPLY_RX1 b2 STATUS_SUPPLY_RX2 b3 STATUS_SUPPLY_RX3 b4 STATUS_DCBIAS_RX0 b5 STATUS_DCBIAS_RX1 b6 STATUS_DCBIAS_RX2 b7 STATUS_DCBIAS_RX3 b8 STATUS_PWRDET_RX0 b9 STATUS_PWRDET_RX1 b10 STATUS_PWRDET_RX2 b11 STATUS_PWRDET_RX3 b15:12 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
RESERVED	3	0x000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.12 Sub block 0x102B – AWR_MONITOR_PMCLKLO_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing information about Internal PM, CLK and LO subsystems' internal analog signals. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.102: AWR_MONITOR_PM_CLK_LO_INTERNAL_ANALOG_SIGNALS_
REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x102B
SBLKLEN	2	Value = 16
STATUS_FLAGS	2	Status flags indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_SUPPLY_PMCLKLO b1 STATUS_DCBIAS_PMCLKLO b2 STATUS_LVDS_PMCLKLO (Use this status bit only if LVDS is used, else ignore this) b3 STATUS_SYNC_20G b15:4 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PROFILE_INDX	1	Profile Index for which this monitoring report applies
SYNC_20G_POWER	1	Monitored 20 GHz signal power, signed number Unit: 1 LSB = 0.5 dBm
RESERVED	2	0x000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.13 Sub block 0x102C – AWR_MONITOR_GPADC_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing information about the measured value of the GPADC input DC signals whose measurements were enabled. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.103: AWR_MONITOR_GPADC_INTERNAL_ANALOG_SIGNALS_
REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x102C
SBLKLEN	2	Value = 20
STATUS_FLAGS	2	Status flags indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_GPADC_REF1 b1 STATUS_GPADC_REF2 b15:2 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
GPADC_REF1_VALUE	2	The measured GPADC outputs corresponding to internal DC signal (GPADC_REF1, expected level 0.45V) is reported here. 1 LSB = 1.8V/1024
GPADC_REF2_VALUE	2	The measured GPADC outputs corresponding to internal DC signal (GPADC_REF2, expected level 1.2V) is reported here. 1 LSB = 1.8V/1024
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.14 Sub block 0x102D – AWR_MONITOR_PLL_CONTROL_VOLTAGE_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured PLL control voltage values during explicit monitoring chirps. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.104: AWR_MONITOR_PLL_CONTROL_VOLTAGE_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x102D
SBLKLEN	2	Value = 32
STATUS_FLAGS	2	Status flags indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_APLL_VCTRL b1 STATUS_SYNTH_VCO1_VCTRL_MAX_FREQ b2 STATUS_SYNTH_VCO1_VCTRL_MIN_FREQ b3 STATUS_SYNTH_VCO1_SLOPE b4 STATUS_SYNTH_VCO2_VCTRL_MAX_FREQ b5 STATUS_SYNTH_VCO2_VCTRL_MIN_FREQ b6 STATUS_SYNTH_VCO2_SLOPE b15:7 RESERVED 0 – FAIL or check wasn't done 1 – PASS
ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
PLL_CONTROL_VOLTAGE_VALUES	16	The measured values of PLL control voltage levels and Synthesizer VCO slopes are reported here. Byte numbers corresponding to different control voltage values reported in this field are here: **Bytes** **SIGNAL** **1 LSB** 1:0 APLL_VCTRL 1 mV 3:2 SYNTH_VCO1_VCTRL_MAX_FREQ 1 mV 5:4 SYNTH_VCO1_VCTRL_MIN_FREQ 1 mV 7:6 SYNTH_VCO1_SLOPE 1 MHz/V 9:8 SYNTH_VCO2_VCTRL_MAX_FREQ 1 mV 11:10 SYNTH_VCO2_VCTRL_MIN_FREQ 1 mV 13:12 SYNTH_VCO2_SLOPE 1 MHz/V 15:14 RESERVED RESERVED

Table 5.104 – continued from previous page

		Only the fields corresponding to the enabled monitors are valid. The failure thresholds are based on the following: Valid VCTRL values are [140 to 1400] mV. Valid VCO1_SLOPE values are [1760 to 2640] MHz/V. Valid VCO2_SLOPE values are [3520 to 5280] MHz/V. **NOTE:** The VCOx_SLOPE should be ignored when synth fault is injected.
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.15 Sub block 0x102E – AWR_MONITOR_DUAL_CLOCK_COMP_REPORT_AE_SB

This API is a monitoring report API which the AWR device sends to the host, containing information about the relative frequency measurements. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.105: AWR_MONITOR_DUAL_CLOCK_COMP_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x102E
SBLKLEN	2	Value = 32
STATUS_FLAGS	2	Status flags indicating pass fail results corresponding to various threshold checks under this monitor. **Bit** **STATUS_FLAG for monitor** b0 STATUS_CLK_PAIR0 b1 STATUS_CLK_PAIR1 b2 STATUS_CLK_PAIR2 b3 STATUS_CLK_PAIR3 b4 STATUS_CLK_PAIR4 b5 STATUS_CLK_PAIR5 b15:6 RESERVED 0 – FAIL or check wasn't done 1 – PASS

Continued on next page

Table 5.105 – continued from previous page

ERROR_CODE	2	Indicates any error reported during monitoring Value of 0 indicates no error
FREQ_MEAS_VALUES	16	The measured clock frequencies from the enabled clock pair measurements are reported here. Byte numbers corresponding to different frequency measurement values reported in this field are here: **Bytes CLOCK PAIR MEASURED CLOCK FREQUENCY** 1:0 0 BSS_600M 3:2 1 BSS_200M 5:4 2 BSS_100M 7:6 3 GPADC_10M 9:8 4 RCOSC_10M 11:10 5 RAMPGEN_100M 15:12 RESERVED RESERVED 1 LSB = 0.1 MHz, unsigned number
RESERVED	4	0x00000000
TIME_STAMP	4	This field indicates when the last monitoring in the enabled set was performed. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)

5.14.16 Sub block 0x1031 – AWR_MONITOR_RX_MIXER_IN_POWER_REPORT_AE_SB

This API is a Monitoring Report API which the AWR device sends to the host, containing the measured RX mixer input voltage swing values. The AWR device sends this to host at the programmed periodicity or when failure occurs, as programmed by the configuration API SB.

Table 5.106: AWR_MONITOR_RX_MIXER_IN_POWER_REPORT_AE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x1031
SBLKLEN	2	Value = 24

Table 5.106 – continued from previous page

STATUS_FLAGS	2	**Bit**	**STATUS_FLAG for monitor**
		b0	STATUS_MIXER_IN_POWER_RX0
		b1	STATUS_MIXER_IN_POWER_RX1
		b2	STATUS_MIXER_IN_POWER_RX2
		b3	STATUS_MIXER_IN_POWER_RX3
		b15:4	RESERVED
		0 – FAIL or check wasn't done	
		1 – PASS	
ERROR_CODE	2	Internal sanity check violations are reported here. Value = 0: No error Other values: Error (see error code definition matrix)	
PROFILE_INDX	1	Profile Index for which this monitoring report applies	
RESERVED	3	0x000000	
RX_MIXER_IN_ VOLTAGE_VALUE	4	The measured RX mixer input voltage swing values are reported here. The byte location of the value for each receivers is tabulated here:	
		Receiver **Byte Location**	
		RX0 0	
		RX1 1	
		RX2 2	
		RX3 3	
		1 LSB = 1800 mV/256, unsigned number Only the entries of enabled RX channels are valid.	
RESERVED	4	0x00000000	
TIME_STAMP	4	When this monitoring began is indicated here. 1 LSB = 1 millisecond (time stamp rolls over upon exceeding allotted bit width)	

5.15 Sub blocks related to AWR_DEV_RFPOWERUP_MSG

5.15.1 Sub block 0x4000 – AWR_DEV_RFPOWERUP_SB

This sub block is a command to power up the BSS
5.107 describes the content of this sub block.

Table 5.107: AWR_DEV_POWERUP_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4000
SBLKLEN	2	Value = 4

5.16 Sub blocks related to AWR_DEV_CONF_SET_MSG

5.16.1 Sub block 0x4040 – AWR_DEV_MCUCLOCK_CONF_SET_SB

This sub block contains the configurations to setup the desired frequency of the MCU Clock that is output from the device.
Table 5.108 describes the contents of this sub block.

Table 5.108: AWR_DEV_MCUCLOCK_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4040
SBLKLEN	2	Value = 8
MCUCLOCK_CTRL	1	This field controls the enable-disable of the MCU clock. Value Description 0x0 Disable MCU clock 0x1 Enable MCU clock
MCUCLOCK_SRC	1	This field specifies the source of the MCU clock. Applicable only in case of MCU clock enable. Else ignored. Value Description 0x0 XTAL (as connected to the device) 0x2 600MHz PLL divided clock
SRCCLOCK_DIV	1	This field specifies the division factor to be applied to source clock. Applicable only in case of MCU clock enable. Else ignored. Value Description 0x0 Divide by 1 0x1 Divide by 2 . . . . . . 0xFF Divide by 256
RESERVED	1	0x00

5.16.2 Sub block 0x4041 – AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB

This sub block contains the configuration of the data format of the samples received over the receive chain to be transferred out to an external host over the configured data path (LVDS or CSI2).
Table 5.109 describes the content of this sub block.

Table 5.109: AWR_DEV_RX_DATA_FORMAT_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4041
SBLKLEN	2	Value = 16

RX_CHAN_EN	2	Bits Definition
		b0 RX_CHAN0_EN
		      0 Disable RX Channel 0
		      1 Enable RX Channel 0
		b1 RX_CHAN0_EN
		      0 Disable RX Channel 1
		      1 Enable RX Channel 1
		b2 RX_CHAN0_EN
		      0 Disable RX Channel 2
		      1 Enable RX Channel 2
		b3 RX_CHAN0_EN
		      0 Disable RX Channel 3
		      1 Enable RX Channel 3
		b15:4 RESERVED

NUM_ADC_BITS	2	Bits Definition
		b1:0 00 12 bits
		         01 14 bits
		         10 16 bits
		         Other Reserved
		b15:2 RESERVED

ADC_OUT_FMT	2	Bits Definition
		b1:0 00 Real
		         01 Complex
		         Other Reserved
		b15:2 RESERVED

Continued on next page

Table 5.109 – continued from previous page

IQ_SWAP_SEL	1	Bits	Definition
		b1:0	To swap the IQ samples (if complex format)
			00 Sample interleave mode – I first
			01 Sample interleave mode – Q first
			Other Reserved
		b7:2	RESERVED
CHAN_INTER-LEAVE	1	Bits	Definition
		b1:0	Channel interleaving of the samples stored in the ADC buffer to be transferred out on the data path.
			00 Interleaved mode of storage
			01 Non-interleaved mode of storage
			Other Reserved
		b7:2	RESERVED
RESERVED	4	0x00000000	

5.16.3 Sub block 0x4042 – AWR_DEV_RX_DATA_PATH_CONF_SET_SB

This sub block contains the configurations of the data path to transfer the captured ADC samples received over the receive chain to be transferred out to an external host.
Table 5.110 describes the content of this sub block.

Table 5.110: AWR_DEV_RX_DATA_PATH_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4042
SBLKLEN	2	Value = 12
DATA_INTF_SEL	1	This field specifies the data path selected to transfer the Radar info. Value Description 0x0 CSI2 interface select 0x1 LVDS interface select 0x2 SPI interface selected (applicable when a large inter-frame time is provided to transfer the data over the SPI)

Continued on next page

Table 5.110 – continued from previous page

DATA_TRANS_FMT_PKT0	1	Bits	Description	
		b5:0	Packet 0 content selection	
			Value	Definition
			000001	ADC
			000110	CP_ADC (See note at the bottom of this table)
			001001	ADC_CP
			110110	CP_ADC_CQ (See note at the bottom of this table)
		b7:6	Packet 0 virtual channel number **(valid only for CSI2)**	
			Value	Definition
			00	Virtual channel number 0 (Default)
			01	Virtual channel number 1
			10	Virtual channel number 2
			11	Virtual channel number 3
DATA_TRANS_FMT_PKT1	1	Bits	Description	
		b5:0	Packet 1 content selection	
			Value	Definition
			000000	Suppress packet 1 transmission
			001110	CP_CQ (See note at the bottom of this table)
			001011	CQ_CP (See note at the bottom of this table)
		b7:6	Packet 1 virtual channel number **(valid only for CSI2)**	
			Value	Definition
			00	Virtual channel number 0 (Default)
			01	Virtual channel number 1
			10	Virtual channel number 2
			11	Virtual channel number 3

Continued on next page

Table 5.110 – continued from previous page

CQ_CONFIG	1	This specifies the data size of CQ samples on the lanes
		Bits Description b1:0 Value Definition
		00 12 bit
		01 14 bit
		10 16 bit
		11 RESERVED
		b7:2 RESERVED
		NOTE: The CQ size can be configured only if CQ and ADC data is sent in separate packets. When ADC and CQ is sent in the same packet, then CQ size will be same as ADC data size.
CQ0_TRANS_SIZE	1	Number of samples (in 16 bit halfwords) of CQ0 data to be transferred. Valid range [32 halfwords to 128 halfwords] Value 0 = Disabled.
		NOTE: Ensure that the number of halfwords specified are a multiple of the number of lanes selected.
CQ1_TRANS_SIZE	1	Number of samples (in 16 bit halfwords) of CQ1 data to be transferred. Valid range [32 halfwords to 128 halfwords] Value 0 = Disabled.
		NOTE: Ensure that the number of halfwords specified are a multiple of the number of lanes selected.
CQ2_TRANS_SIZE	1	Number of samples (in 16 bit halfwords) of CQ2 data to be transferred. Valid range [32 halfwords to 128 halfwords] Value 0 = Disabled.
		NOTE: Ensure that the number of halfwords specified are a multiple of the number of lanes selected.
RESERVED	1	0x00

NOTE1:	CP is Chirp Parameter information which is defined for each RX as follows
	Bit Description
	b11:0 Chirp number
	In legacy frame configuration, chirp number for starts from 1 and increments for each chirp within the frame and resets to 0 for the next frame.
	In advanced frame configuration chirp number starts from 1 and increments for each chirp within the burst and resets to 0 for the next burst.
	b15:12 RESERVED
	b17:16 Channel number
	The receive channel number which is encoded as
	00 RX0
	01 RX1
	10 RX2
	11 RX3
	b21:18 Profile number
	The profile number to which the chirp belongs
	b31:22 RESERVED
NOTE2:	CQ is Chirp Quality information which is defined in Section 8

5.16.4 Sub block 0x4043 – AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB

This sub block contains the configurations to enables the lanes of the LVDS/CSI2 path to transfer Radar information to an external host.
Table 5.111 describes the content of this sub block.

Table 5.111: AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4043
SBLKLEN	2	Value = 8

Table 5.111 – continued from previous page

LANE_EN	2	Bits	Description
		b0	LANE0_EN
			0 Disable lane 0
			1 Enable lane 0
		b1	LANE1_EN
			0 Disable lane 1
			1 Enable lane 1
		b2	LANE2_EN
			0 Disable lane 2
			1 Enable lane 2
		b3	LANE3_EN
			0 Disable lane 3
			1 Enable lane 3
		b15:4	RESERVED
RESERVED	2	0x0000	

5.16.5 Sub block 0x4044 – AWR_DEV_RX_DATA_PATH_CLK_SET_SB

This sub block contains the clock configurations for data transfer on the LVDS/CSI2 lanes.
Table 5.112 describes the content of this sub block.

Table 5.112: AWR_DEV_RX_DATA_PATH_CLK_SET_SB contents

Field Name	Number of bytes	Description		
SBLKID	2	Value = 0x4044		
SBLKLEN	2	Value = 8		
LANE_CLK_CFG (Selection valid only for LVDS. For CSI2, DDR is used always)	1	Bits	Description	
		b0	BIT_CLK_SEL	
			0	SDR clock
			1	DDR clock (Only valid value for CSI2)
		b7:1	RESERVED	

Continued on next page

Table 5.112 – continued from previous page

DATA_RATE	1	Data rate selection
		Value Description
		0000b 900 Mbps (DDR only)
		0001b 600 Mbps (DDR only)
		0010b 450 Mbps (SDR, DDR)
		0011b 400 Mbps (DDR only)
		0100b 300 Mbps (SDR, DDR)
		0101b 225 Mbps (DDR only)
		0110b 150 Mbps (DDR only)
		Others RESERVED
RESERVED	2	0x0000

5.16.6 Sub block 0x4045 – AWR_DEV_LVDS_CFG_SET_SB

This sub block contains the configurations of the LVDS lanes.
Table 5.113 describes the content of this sub block.

Table 5.113: AWR_DEV_LVDS_CFG_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4045
SBLKLEN	2	Value = 8
LANE_FMT_MAP	2	LANE0 Format Map. The mapping of the data on the lanes is depicted in the figure below
		0x0000 Format map 0
		0x0001 Format map 1
LANE_PARAM_CFG	2	Bit Description
		b0 MSB_FIRST
		0 Disable (LSB First)
		1 Enable (MSB First)
		b1 Packet End Pulse Enable
		0 Disable
		1 Enable
		b2 CRC Enable
		0 Disable
		1 Enable
		b15:3 RESERVED

The mapping of the 8 sample (8*16 = 128 bit) information onto the serial interface lanes is determined by the LANE_FMT_MAP parameter. The choice of format map translating to the transfer of data on the lanes is depicted in the image below (the x axis represents time – hence the samples are as available on the lanes in time and the receiver will receive the samples in the reverse order as depicted below).
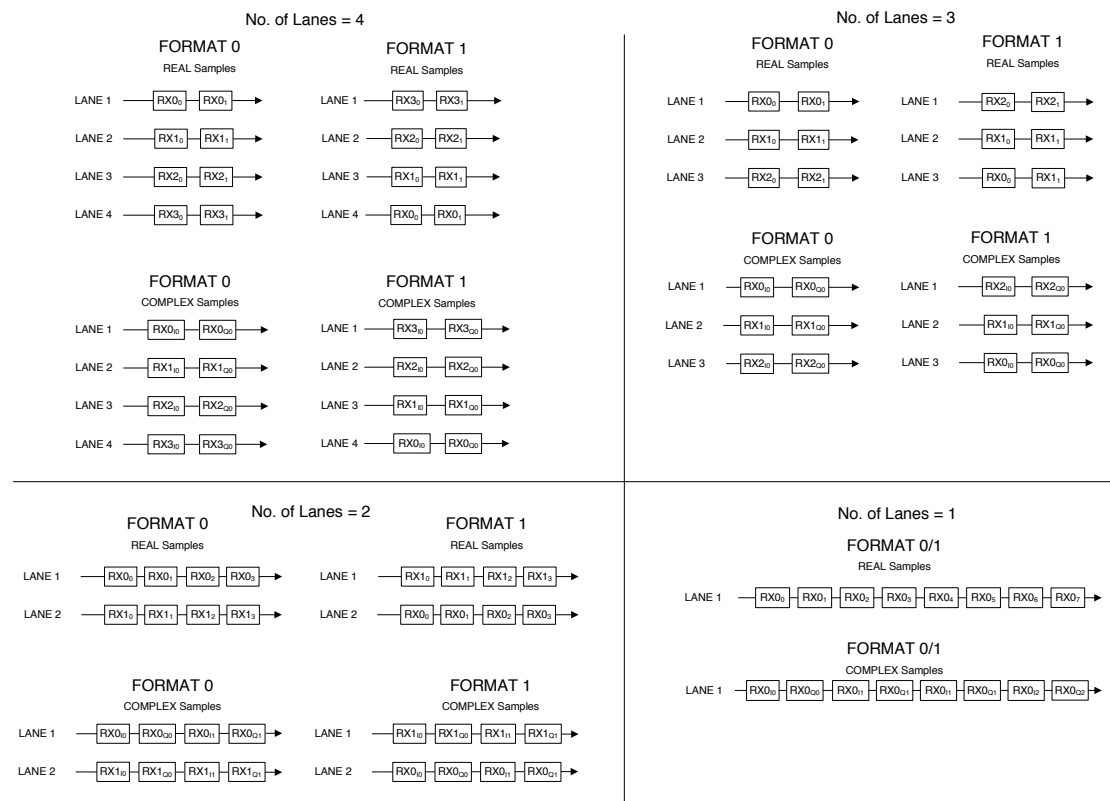
Figure 5.3: Lane formats and the order of receiving the data from the lanes

5.16.7 Sub block 0x4046 – AWR_DEV_RX_CONTSTREAMING_MODE_CONF_SET_SB

This sub block contains the configurations of the data path to transfer the captured ADC samples continuously without any break to an external host.
Table 5.114 describes the content of this sub block.

Table 5.114: AWR_DEV_RX_CONTSTREAMING_MODE_CFG_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4046
SBLKLEN	2	Value = 8
CONT_STREAM-ING_MODE	2	Continuous streaming mode enable
		Value Description
		0x0 Continuous streaming mode data transfer disable
		0x1 Continuous streaming mode data transfer enable
RESERVED	2	0x0000

5.16.8 Sub block 0x4047 – AWR_DEV_CSI2_CFG_SET_SB

This sub block contains the various configurations of the parameters of the CSI2 module. Table 5.115 describes the content of this sub block.

Table 5.115: AWR_DEV_CSI2_CFG_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4047
SBLKLEN	2	Value = 12

Continued on next page

Table 5.115 – continued from previous page

LANE_POS_POL_SEL	4	Bits	Definition
		b2:0	DATA_LANE0_POS Valid values (Should be a unique position if lane 0 is enabled, ignored if lane 0 is not enabled): 000b – Unused, 001b – Position 1 (default), 010b – Position 2, 011b – Position 3, 100b – Position 4, 101b – Position 5
		b3	DATA_LANE0_POL 0b – PLUSMINUS pin order, 1b – MINUSPLUS pin order
		b6:4	DATA_LANE1_POS Valid values (Should be a unique position if lane 1 is enabled, ignored if lane 1 is not enabled): 000b – Unused, 001b – Position 1, 010b – Position 2 (default), 011b – Position 3, 100b – Position 4, 101b – Position 5
		b7	DATA_LANE1_POL 0b – PLUSMINUS pin order, 1b – MINUSPLUS pin order
		b10:8	DATA_LANE2_POS Valid values (Should be a unique position if lane 2 is enabled, ignored if lane 2 is not enabled): 000b – Unused, 001b – Position 1, 010b – Position 2, 011b – Position 3, 100b – Position 4 (default), 101b – Position 5
		b11	DATA_LANE2_POL 0b – PLUSMINUS pin order, 1b – MINUSPLUS pin order
		b14:12	DATA_LANE3_POS Valid values (Should be a unique position if lane 3 is enabled, ignored if lane 3 is not enabled): 000b – Unused, 001b – Position 1, 010b – Position 2, 011b – Position 3, 100b – Position 4, 101b – Position 5 (default)
		b15	DATA_LANE3_POL 0b – PLUSMINUS pin order, 1b – MINUSPLUS pin order
		b18:16	CLOCK_POS Valid values (Should be a unique position): 0000b – Unused, 001b – Unused, 010b – Position 2, 011b – Position 3 (default), 100b – Position 4
		b19	CLOCK_POL 0b – PLUSMINUS pin order, 1b – MINUSPLUS pin order
		b31:20	RESERVED

Table 5.115 – continued from previous page

RESERVED	4	0x00000000

5.16.9 Sub block 0x4048 – AWR_DEV_PMICCLOCK_CONF_SET_SB

This sub block contains the configurations to setup the desired frequency of the PMIC Clock that is output from the device. The configurations also allow setting up the dither values for the clock. Table 5.116 describes the contents of this sub block.

Table 5.116: AWR_DEV_PMICCLOCK_CONF_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4048
SBLKLEN	2	Value = 16
PMICCLOCK_CTRL	1	This field controls the enable-disable of the PMIC clock. Value Description 0x0 Disable PMIC clock 0x1 Enable PMIC clock
PMICCLOCK_SRC	1	This field specifies the source of the PMIC clock. Applicable only in case of PMIC clock enable. Else ignored. Value Description 0x0 XTAL (as connected to the device) 0x2 600 MHz PLL divided clock
SRCCLOCK_DIV	1	This field specifies the division factor to be applied to source clock. Applicable only in case of PMIC clock enable. Else ignored. Value Description 0x0 Divide by 1 0x1 Divide by 2 . . . . . . 0xFF Divide by 256

Table 5.116 – continued from previous page

MODE_SELECT	1	This field specifies the mode of operation for the PMIC clock generation. Applicable only in case of PMIC clock enable. Else ignored.

Value Description

0x0 Continuous mode (free running mode where the frequency change/jump is triggered based on configured number of PMIC clock ticks)

0x1 Chirp-to-Chirp staircase mode (frequency change/jump is triggered at every chirp boundary)

FREQ_SLOPE	4	Applicable only in case of PMIC clock enable. Else ignored.

Bit Description

b25:0 Frequency slope value to be applied in [7.18] unsigned format 1 LSB = $1/2^{18}$

b31:26 RESERVED

In continuous mode this value is accumulated every PMIC clock tick with the seed as MIN_NDIV_VAL till MAX_NDIV_VAL is reached

In the stair case mode this value is accumulated every chirp with the seed as MIN_NDIV_VAL till MAX_NDIV_VAL is reached

MIN_NDIV_VAL	1	Applicable only in case of PMIC clock enable. Else ignored. Minimum allowed divider value (depends upon the highest desired clock frequency)
MAX_NDIV_VAL	1	Applicable only in case of PMIC clock enable. Else ignored. Maximum allowed divider value (depends upon the lowest desired clock frequency)
CLK_DITHER_EN	1	Applicable only in case of PMIC clock enable and frequency slope is non-zero. Else ignored. This field controls the enable-disable of the clock dithering. Adds a pseudo random real number (0 or 1) to the accumulated divide value. Hence it brings a random dithering of 1 LSB.

Value Description

0x0 Clock dithering disabled

0x1 Clock dithering enabled

RESERVED	1	0x00

Example 1. PMIC clock with no slope in continuous mode

Objective: To configure the PMIC clock at frequency of 2 MHz with no slope.
Configurations:

1. PMICCLK_SRC = 0x2 (600 MHz PLL divided clock)

2. SRCCLOCK_DIV = 29, Reference clock = 600 MHz /(29 + 1) = 20 MHz

3. MIN_NDIV_VAL = MAX_NDIV_VAL = 10 (Computed as 20 MHz/2.0 MHz)

4. FREQ_SLOPE = 0

With the above configuration, the PMIC clock frequency would be PMIC clock = (20 MHz / 10) = 2 MHz

Example 2. Dithered PMIC clock with slope in chirp-to-chirp staircase mode
Objective: To configure a dithered PMIC clock at frequencies ranging from 2 MHz to 2.5 MHz over 32 chirps.
Configurations:

1. PMICCLK_SRC = 0x2 (600 MHz PLL divided clock)

2. SRCCLOCK_DIV = 2, Reference clock = 600 MHz /(2 + 1) = 200 MHz

3. MODE_SELECT = 1

4. FREQ_SLOPE = 169125 (Computed as $(\mathrm{MAX\_NDIV\_VAL} - \mathrm{MIN\_NDIV\_VAL}) \times 2^{18}/31$)

5. MIN_NDIV_VAL = 80 (Computed as 200 MHz/2.5 MHz)

6. MAX_NDIV_VAL = 100 (Computed as 200 MHz/2.0 MHz)

7. CLK_DITHER_EN = 1

With the above configuration, the PMIC clock frequency would be vary between (200 MHz / 80) and (200 MHz / 100) in steps of $200\,\mathrm{MHz}/\lfloor(80 + (N \times \mathrm{FREQ\_SLOPE}/2^{18} + X))\rfloor$ where

- N = Chirp number

- X = random fractional value in the range (0, 1) that adds the dither

The PMIC clock frequency is determined by the clock divider value which starts with a value of 100, providing a PMIC clock of 2 MHz for the 1st chirp, decrementing the divider by FREQ_SLOPE/2^{18} = 0.64516 every chirp and finally reaching a value of 20 for the 32nd chirp providing a PMIC clock of 2.5 MHz.

Table 5.117: PMIC clock frequency across chirps in chirp-to-chirp staircase mode in an example when PMIC clock varies from 2 MHz to 2.5 MHz in 32 chirps

Chirp Number	PMIC Clock Frequency (MHz)	Calculation
1	2.50000	$200/(80 + 0 \times 169125/2^{18})$
2	2.48000	$200/(80 + 1 \times 169125/2^{18})$
3	2.46032	$200/(80 + 2 \times 169125/2^{18})$
4	2.44094	$200/(80 + 3 \times 169125/2^{18})$
5	2.42188	$200/(80 + 4 \times 169125/2^{18})$
6	2.40310	$200/(80 + 5 \times 169125/2^{18})$
7	2.38462	$200/(80 + 6 \times 169125/2^{18})$
8	2.36641	$200/(80 + 7 \times 169125/2^{18})$
9	2.34848	$200/(80 + 8 \times 169125/2^{18})$
10	2.33083	$200/(80 + 9 \times 169125/2^{18})$
11	2.31343	$200/(80 + 10 \times 169125/2^{18})$
12	2.29630	$200/(80 + 11 \times 169125/2^{18})$
13	2.27941	$200/(80 + 12 \times 169125/2^{18})$
14	2.26277	$200/(80 + 13 \times 169125/2^{18})$
15	2.24638	$200/(80 + 14 \times 169125/2^{18})$
16	2.23022	$200/(80 + 15 \times 169125/2^{18})$
17	2.21429	$200/(80 + 16 \times 169125/2^{18})$
18	2.19858	$200/(80 + 17 \times 169125/2^{18})$
19	2.18310	$200/(80 + 18 \times 169125/2^{18})$
20	2.16783	$200/(80 + 19 \times 169125/2^{18})$
21	2.15278	$200/(80 + 20 \times 169125/2^{18})$
22	2.13793	$200/(80 + 21 \times 169125/2^{18})$
23	2.12329	$200/(80 + 22 \times 169125/2^{18})$
24	2.10884	$200/(80 + 23 \times 169125/2^{18})$
25	2.09459	$200/(80 + 24 \times 169125/2^{18})$
26	2.08054	$200/(80 + 25 \times 169125/2^{18})$
27	2.06667	$200/(80 + 26 \times 169125/2^{18})$
28	2.05298	$200/(80 + 27 \times 169125/2^{18})$
29	2.03947	$200/(80 + 28 \times 169125/2^{18})$
30	2.02614	$200/(80 + 29 \times 169125/2^{18})$
31	2.01299	$200/(80 + 30 \times 169125/2^{18})$
32	2.00000	$200/(80 + 31 \times 169125/2^{18})$

Example 3. Dithered PMIC clock with slope in continuous mode

Objective: To configure a dithered PMIC clock at frequencies ranging from 2 MHz to 2.5 MHz over 100 μs.

Configurations:

1. PMICCLK_SRC = 0x2 (600 MHz PLL divided clock)

2. SRCCLOCK_DIV = 2, Reference clock = 600 MHz /(2 + 1) = 200 MHz

3. MODE_SELECT = 0

4. FREQ_SLOPE = 23302 (Computed as $(\text{MAX\_NDIV\_VAL}-\text{MIN\_NDIV\_VAL})\cdot 2^{18}/(100\ \mu s\cdot (2.5\ \text{MHz} + 2\ \text{MHz})/2))$

5. MIN_NDIV_VAL = 80 (Computed as 200 MHz/2.5 MHz)

6. MAX_NDIV_VAL = 100 (Computed as 200 MHz/2.0 MHz)

7. CLK_DITHER_EN = 1

With the above configuration, the PMIC clock frequency would be PMIC clock would vary between = (200 MHz / 80) to (200 MHz / 100) in steps of $(200\ \text{MHz}/\lfloor(80 + (N \times 23302/2^{18} + X))\rfloor)$ where

- N = Iteration count that ticks every PMIC clock. The average value of PMIC clock here is $\sim$ 2.25 MHz. Hence the iteration count ticks every (1/2.25 MHz) $\sim 0.444\ \mu$s.

- X = random fractional value in the range (0, 1) that adds the dither

The PMIC clock frequency is determined by the clock divider which starts with a value of 100, on the 1st PMIC clock period, providing a PMIC clock of 2 MHz, decrementing the divider value by $23303/2^{18}$ = 0.08889 every PMIC clock period of 1/2.25 MHz $\sim 0.444\ \mu$s, finally reaching a value of 80 on 225th PMIC clock period, providing a PMIC clock of 2.5 MHz. Hence, the frequency varies from [2 MHz, 2.5 MHz] over 225 PMIC clock periods or $225 \times 0.444\ \mu$s or $\sim 100\ \mu$s.

5.16.10 Sub block 0x4049 – AWR_MSS_PERIODICTESTS_CONF_SB

This sub block is used to trigger the periodic tests in MSS.
Table 5.118 describes the content of this sub block.

Table 5.118: AWR_MSS_PERIODICTESTS_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4049
SBLKLEN	2	Value = 16

Continued on next page

Table 5.118 – continued from previous page

PERIODICITY	4	Periodicity at which tests need to be run 1 LSB = 1 ms Minimum value is 40 ms
TEST_EN	4	1 – Enable, 0 – Disable Bit Monitoring type b0　　PERIODIC_CONFG_REGISTER_READ_EN b1　　ESM_MONITORING_EN b31:2　　RESERVED
REPORTING_MODE	1	Controls when the AWR device sends the report corresponding to the periodic tests to the host. A report generically refers to both success/failure status flags. Value　　Definition 0　　Report is sent every monitoring period 1　　Report is sent only on a failure
RESERVED	3	0x000000

5.16.11 Sub block 0x404A – AWR_MSS_LATENTFAULT_TEST_CONF_SB

This sub block is used to trigger the periodic tests in MSS.
Table 5.119 describes the content of this sub block.

Table 5.119: AWR_MSS_LATENTFAULT_TEST_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x404A
SBLKLEN	2	Value = 16

Continued on next page

Table 5.119 – continued from previous page

TEST_EN_1	4	Bits	Definition
		b0	MibSPI self-test
		b1	DMA self-test
		b2	RESERVED
		b3	RTI self-test
		b4	ESM self-test
		b5	EDMA self-test
		b6	CRC self-test
		b7	VIM self-test
		b8	RESERVED
		b9	Mailbox self-test
		b10	LVDS pattern generation test
		b11	CSI2 pattern generation test
		b12	Generating NERROR
		b13	MibSPI single bit error test
		b14	MibSPI double bit error test
		b15	DMA Parity error
		b16	TCMA RAM single bit errors
		b17	TCMB RAM single bit errors
		b18	TCMA RAM double bit errors
		b19	TCMB RAM double bit errors
		b20	TCMA RAM parity errors.
		b21	TCMB RAM parity errors.
		b22	RESERVED
		b23	RESERVED
		b24	DMA MPU Region tests
		b25	MSS Mailbox single bit errors
		b26	MSS Mailbox double bit errors
		b27	BSS Mailbox single bit errors
		b28	BSS Mailbox double bit errors
		b29	EDMA MPU test
		b30	EDMA parity test
		b31	CSI2 parity test

Continued on next page

Table 5.119 – continued from previous page

TEST_EN_2	4	Bits	Definition
		b0	DCC self-test
		b1	DCC fault insertion test
		b2	PCR fault generation test
		b3	VIM RAM parity test
		b4	SCI boot time test
		b31:5	RESERVED
REPORTING_ MODE	1	Value	Definition
		0	Report is sent after test completion
		1	Report is send only upon a failure
TEST_MODE	1	Value	Definition
		0	Production mode. Latent faults are tested and any failures are reported
		1	Characterization mode. Faults are injected and failures are reported which allows testing of the failure reporting
RESERVED	2	0x0000	

5.16.12 Sub block 0x404B – AWR_DEV_TESTPATTERN_GEN_SET_SB

This sub block contains the configurations to setup the test pattern to be generated and transferred over the selected high speed interface (LVDS/CSI2). This command has to be issued after the data path configurations commands are issued. This can be used to perform a sanity test of the high speed interface connectivity and correct reception.
Table 5.120 describes the contents of this sub block.

Table 5.120: AWR_DEV_TESTPATTERN_GEN_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x404B
SBLKLEN	2	Value = 48
TESTPATTERN_ GEN_CTRL	1	This field controls the enable-disable of the generation of the test pattern. Value Description 0x0 Disable test pattern generation 0x1 Enable test pattern generation

Continued on next page

Table 5.120 – continued from previous page

TESTPATTERN_ GEN_TIMING	1	Number of system clocks (200 MHz) between successive samples for the test pattern gen. Applicable only in case of Test pattern enable. Else ignored.
TESTPATTERN_ PKT_SIZE	2	Number of ADC samples to capture for each RX Valid range: 64 to MAX_NUM_SAMPLES, Where MAX_NUM_SAMPLES is such that all the enabled RX channels' data fits into 16 kB memory, with each sample consuming 2 bytes for real ADC output case and 4 bytes for complex 1x and complex 2x ADC output cases. For example in xWR1243/xWR1443 when the ADC buffer size is 16 kB **Number of RX chains** / **ADC format** / **MAX_NUM_ SAMPLES** 4 / Complex / 1024 4 / Real / 2048 2 / Complex / 2048 2 / Real / 4096
NUM_TESTPAT-TERN_PKTS	4	Number of test pattern packets to send For infinite packets set it to 0
TESTPATTERN_ RX0_ICFG	4	This field specifies the values for Rx0, I channel. Applicable only in case of test pattern enable. Else ignored. Bits — Description b15:0 — Start offset value to be used for the first sample for the test pattern data b31:16 — Value to be added for each successive sample for the test pattern data
TESTPATTERN_ RX0_QCFG	4	This field specifies the values for Rx0, Q channel. Applicable only in case of test pattern enable. Else ignored. Bits — Description b15:0 — Start offset value to be used for the first sample for the test pattern data b31:16 — Value to be added for each successive sample for the test pattern data

Table 5.120 – continued from previous page

TESTPATTERN_RX1_ICFG	4	This field specifies the values for Rx1, I channel. Applicable only in case of test pattern enable. Else ignored.
		Bits **Description**
		b15:0 Start offset value to be used for the first sample for the test pattern data
		b31:16 Value to be added for each successive sample for the test pattern data
TESTPATTERN_RX1_QCFG	4	This field specifies the values for Rx1, Q channel. Applicable only in case of test pattern enable. Else ignored.
		Bits **Description**
		b15:0 Start offset value to be used for the first sample for the test pattern data
		b31:16 Value to be added for each successive sample for the test pattern data
TESTPATTERN_RX2_ICFG	4	This field specifies the values for Rx2, I channel. Applicable only in case of test pattern enable. Else ignored.
		Bits **Description**
		b15:0 Start offset value to be used for the first sample for the test pattern data
		b31:16 Value to be added for each successive sample for the test pattern data
TESTPATTERN_RX2_QCFG	4	This field specifies the values for Rx2, Q channel. Applicable only in case of test pattern enable. Else ignored.
		Bits **Description**
		b15:0 Start offset value to be used for the first sample for the test pattern data
		b31:16 Value to be added for each successive sample for the test pattern data
TESTPATTERN_RX3_ICFG	4	This field specifies the values for Rx3, I channel. Applicable only in case of test pattern enable. Else ignored.
		Bits **Description**
		b15:0 Start offset value to be used for the first sample for the test pattern data
		b31:16 Value to be added for each successive sample for the test pattern data

Continued on next page

Table 5.120 – continued from previous page

TESTPATTERN_RX3_QCFG	4	This field specifies the values for Rx3, Q channel. Applicable only in case of test pattern enable. Else ignored.
		Bits Description
		b15:0 Start offset value to be used for the first sample for the test pattern data
		b31:16 Value to be added for each successive sample for the test pattern data
RESERVED	4	0x00000000

> **NOTE:** This test pattern can be used only in LVDS testing and bring-up

5.16.13 Sub block 0x404C – AWR_DEV_CONFIGURATION_SET_SB

This API is used to configure the CRC type for the async events from MSS. The default is 16 bit CRC if this API is not issued. The first async event after MSS powerup will have a 16 bit CRC.

Table 5.121: AWR_DEV_CONFIGURATION_SET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x404C
SBLKLEN	2	Value = 16
ASYNC_EVENT_CRC_CFG	1	Value Description
		0 16 bit CRC for MSS async events
		1 32 bit CRC for MSS async events
		2 64 bit CRC for MSS async events
RESERVED1	1	0x00
RESERVED2	2	0x0000
RESERVED3	4	0x00000000
RESERVED4	4	0x00000000

5.17 Sub blocks related to AWR_DEV_CONF_GET_MSG

5.17.1 Sub block 0x4060 – AWR_DEV_MCUCLOCK_GET_SB

This API is used to read the MCU clock configuration. Response packet structure will be same as AWR_DEV_MCUCLOCK_SET_SB

<p style="text-align:center">**Table 5.122:** AWR_DEV_MCUCLOCK_GET_SB contents</p>

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4060
SBLKLEN	2	Value = 4

5.17.2 Sub block 0x4061 – AWR_DEV_RX_DATA_FORMAT_CONF_GET_SB

This API is used to read the RX data format configuration. Response packet structure will be same as AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB

<p style="text-align:center">**Table 5.123:** AWR_DEV_RX_DATA_FORMAT_CONF_GET_SB contents</p>

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4061
SBLKLEN	2	Value = 4

5.17.3 Sub block 0x4062 – AWR_DEV_RX_DATA_PATH_CONF_GET_SB

This API is used to read the RX data path configuration. Response packet structure will be same as AWR_DEV_RX_DATA_PATH_CONF_SET_SB

<p style="text-align:center">**Table 5.124:** AWR_DEV_RX_DATA_PATH_CONF_GET_SB contents</p>

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4062
SBLKLEN	2	Value = 4

5.17.4 Sub block 0x4063 – AWR_DEV_RX_DATA_PATH_LANEEN_GET_SB

This API is used to read the RX data path lane enable configuration. Response packet structure will be same as AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB

<p style="text-align:center">**Table 5.125:** AWR_DEV_RX_DATA_PATH_LANEEN_GET_SB contents</p>

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4063
SBLKLEN	2	Value = 4

5.17.5 Sub block 0x4064 – AWR_DEV_RX_DATA_PATH_CLK_GET_SB

This API is used to read the RX data path clock configuration. Response packet structure will be same as AWR_DEV_RX_DATA_PATH_CLK_SET_SB

Table 5.126: AWR_DEV_RX_DATA_PATH_CLK_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4064
SBLKLEN	2	Value = 4

5.17.6 Sub block 0x4065 – AWR_DEV_LVDS_CFG_GET_SB

This API is used to read the LVDS configuration. Response packet structure will be same as AWR_DEV_LVDS_CFG_SET_SB

Table 5.127: AWR_DEV_LVDS_CFG_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4065
SBLKLEN	2	Value = 4

5.17.7 Sub block 0x4066 – AWR_DEV_RX_CONTSTREAMING_MODE_CONF_GET_SB

This API is used to read the continuous streaming mode configuration. Response packet structure will be same as AWR_DEV_RX_CONTSTREAMING_MODE_CONF_SET_SB

Table 5.128: AWR_DEV_RX_CONTSTREAMING_CONF_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4066
SBLKLEN	2	Value = 4

5.17.8 Sub block 0x4067 – AWR_DEV_CSI2_CFG_GET_SB

This API is used to read the CSI2 configuration. Response packet structure will be same as AWR_DEV_CSI2_CFG_SET_SB

Table 5.129: AWR_DEV_CSI2_CFG_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4067
SBLKLEN	2	Value = 4

5.17.9 Sub block 0x4068 – AWR_DEV_PMICCLOCK_CONF_GET_SB

This API is used to read the PMIC clock configuration. Response packet structure will be same as AWR_DEV_PMICCLOCK_CONF_SET_SB

Table 5.130: AWR_DEV_PMICCLOCK_CONF_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4068
SBLKLEN	2	Value = 4

5.17.10 Sub block 0x4069 – AWR_MSS_LATENTFAULT_TEST_CONF_GET_SB

This API is used to read the MSS latent fault test configuration. Response packet structure will be same as AWR_MSS_LATENTFAULT_TEST_CONF_SET_SB

Table 5.131: AWR_MSS_LATENTFAULT_CONF_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4069
SBLKLEN	2	Value = 4

5.17.11 Sub block 0x406A – AWR_MSS_PERIODICTESTS_CONF_GET_SB

This API is used to read the MSS periodic tests configuration. Response packet structure will be same as AWR_MSS_PERIODICTESTS_CONF_SET_SB

Table 5.132: AWR_MSS_PERIODICTESTS_CONF_GET_SB contents

Field Name	Number of bytes	Description

SBLKID	2	Value = 0x406A
SBLKLEN	2	Value = 4

5.17.12 Sub block 0x406B – AWR_DEV_TESTPATTERN_GEN_GET_SB

This API is used to read the test pattern generation configuration. Response packet structure will be same as AWR_DEV_TESTPATTERN_GEN_SET_SB

Table 5.133: AWR_DEV_TESTPATTERN_GEN_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x406B
SBLKLEN	2	Value = 4

5.18 Sub blocks related to AWR_DEV_FILE_DOWNLOAD_MSG

5.18.1 Sub block 0x4080 – AWR_DEV_FILE_DOWNLOAD_SB

This sub block is used to send the file in chunks/parts for download into RAM.
Table 5.134 describes the content of this sub block.

Table 5.134: AWR_DEV_FILE_DOWNLOAD_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x4080
SBLKLEN	2	Value = Variable
FILE_TYPE	4	Value Description 0x0 FILETYPE_BSS_BUILD 0x1 FILETYPE_CALIB_DATA 0x2 FILETYPE_CONFIG_INFO 0x3 FILETYPE_MSS_BUILD
FILE_LENGTH	4	Length of File
FILE_CONTENT	Variable	Content of File, may split into multiple chunks.

NOTE:	In the first chunk of file, FILE_TYPE and FILE_LENGTH is available and then first chunk onward these two fields will not be part of SB content

5.19 Sub blocks related to AWR_DEV_FRAME_CONFIG_APPLY_MSG

5.19.1 Sub block 0x40C0 – AWR_DEV_FRAME_CONFIG_APPLY_SB

This sub block is used to indicate to MSS to apply all the device configurations in the hardware. Table 5.135 describes the content of this sub block.

Table 5.135: AWR_DEV_FRAME_CONFIG_APPLY_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x40C0
SBLKLEN	2	Value = 12
NUM_CHIRPS	4	Number of chirps per frame
HALF_WORDS_ PER_CHIRP	2	Number of half words in ADC buffer per chirp Example 1: In real mode, if number of ADC samples per chirp is 256 then this value will be 256 Example 2: In complex1x or complex2x modes, if number of ADC samples per chirp is 256 then this value will be 512
RESERVED	2	0x0000

5.19.2 Sub block 0x40C1 – AWR_DEV_ADV_FRAME_CONFIG_APPLY_SB

This sub block is used to indicate to MSS to apply all the advanced frame configuration configurations in the hardware.
Table 5.136 describes the content of this sub block.

Table 5.136: AWR_DEV_ADV_FRAME_CONFIG_APPLY_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x40C1
SBLKLEN	2	Value = 40
NUM_SUB-FRAMES	1	Number of sub frames enabled in this frame Valid range: 1 to 4
RESERVED	3	0x00
SF1_TOT_NUM_ CHIRPS	4	Number of chirps in sub frame 1

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Table 5.136 – continued from previous page

SF1_NUM_ADC_SAMPLES_PER_DATA_PKT	2	Number of half words (16 bits) of ADC samples per data packet in sub-frame 1 Example 1: In real mode, if number of ADC samples per chirp in subframe1 is 256 then this value will be 256 Example 2: In complex1x or complex2x modes, if number of ADC samples per chirp in subframe1 is 256 then this value will be 512 In xWR12xx: Program this as the same as number of ADC samples in each chirp of this sub frame (required to be the same) Exception: Can do #chirps based ping-pong as in xWR16xx (see below), if CP/CQ are not needed. Useful for chirp stitching use case. In xWR16xx: The ADC samples corresponding to one or more chirps can be grouped and sent to the DSP as a single packet. Program this as the number of half words of ADC samples per packet. Ensure that in one sub frame, there is integer number of such packets. Maximum size of a data packet: (16384 - 1) half words.
SF1_PROC_NUM_CHIRPS_PER_DATA_PKT	1	Number of chirps per data packet to process at a time in sub-frame 1. In xWR12xx: Program this as 1. Exception: Can be > 1 as in 16xx if CP/CQ is not needed. Useful for chirp stitching use case. In xWR16xx: The ADC samples corresponding to one or more chirps can be grouped and sent to the DSP as a single packet. Program this as the corresponding number of chirps per packet. Maximum value = 8. Note on maximum size: 8 chirps for CP and BPM.
RESERVED	1	0x00
SF2_TOT_NUM_CHIRPS	4	Number of chirps in sub-frame 2
SF2_NUM_ADC_SAMPLES_PER_DATA_PKT	2	Number of ADC Samples per data packet in sub-frame 2 Same conditions apply as in sub-frame 1.
SF2_PROC_NUM_CHIRPS_PER_DATA_PKT	1	Number of chirps per data packet to process at a time in sub-frame 2 Same conditions apply as in sub-frame 1.
RESERVED	1	0x00
SF3_TOT_NUM_CHIRPS	4	Number of chirps in sub-frame3

Table 5.136 – continued from previous page

SF3_NUM_ADC_SAMPLES_PER_DATA_PKT	2	Number of ADC samples per data packet in sub-frame 3 Same conditions apply as in sub-frame 1.
SF3_PROC_NUM_CHIRPS_PER_DATA_PKT	1	Number of chirps per data packet to process at a time in sub-frame 3 Same conditions apply as in sub-frame 1.
RESERVED	1	0x00
SF4_TOT_NUM_CHIRPS	4	Number of chirps in sub-frame4
SF4_NUM_ADC_SAMPLES_PER_DATA_PKT	2	Number of ADC samples per data packet in sub-frame 4 Same conditions apply as in sub-frame 1.
SF4_PROC_NUM_CHIRPS_PER_DATA_PKT	1	Number of chirps per data packet to process at a time in sub-frame 4 Same conditions apply as in sub-frame 1.
RESERVED	1	0x00

5.20 Sub blocks related to AWR_DEV_STATUS_GET_MSG

5.20.1 Sub block 0x40E0 – AWR_MSSVERSION_GET_SB

This sub block reads MSS FW version. The information returned by the device will be in the format as given in AWR_MSSVERSION_SB.
Table 5.137 describes the contents of the request sub block

Table 5.137: AWR_MSSVERSION_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x40E0
SBLKLEN	2	Value = 4

Response to AWR_MSSVERSION_GET_SB
AWR_MSSVERSION_SB sub block is sent by the radar device in response to AWR_MSSVERSION_GET_SB. Note that SBLKID for both AWR_MSSVERSION_GET_SB and AWR_MSSVERSION_SB are same.
Table 5.138 describes the contents of the response sub block.

Table 5.138: AWR_MSSVERSION_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x40E0
SBLKLEN	2	Value = 20
HW_VARIANT	1	HW variant number
HW_VERSION_MAJOR	1	HW version major number
HW_VERSION_MINOR	1	HW version minor number
MSS_FW_VERSION_MAJOR	1	MSS FW version major number
MSS_FW_VERSION_MINOR	1	MSS FW version minor number
MSS_FW_VERSION_BUILD	1	MSS FW version build number
MSS_FW_VERSION_DEBUG	1	MSS FW version debug number
MSS_FW_VERSION_YEAR	1	Year of MSS FW version release
MSS_FW_VERSION_MONTH	1	Month of MSS FW version release
MSS_FW_VERSION_DAY	1	Day of MSS FW version release
MSS_FW_VERSION_PATCH_MAJOR	1	MSS FW version patch major number
MSS_FW_VERSION_PATCH_MINOR	1	MSS FW version patch minor number
MSS_FW_VERSION_PATCH_YEAR	1	Year of MSS FW patch release
MSS_FW_VERSION_PATCH_MONTH	1	Month of MSS FW patch release
MSS_FW_VERSION_PATCH_DAY	1	Day of MSS FW patch release

Table 5.138 – continued from previous page

MSS_FW_PATCH_ BUILD_DEBUG_ VERSION	1	Bit	Definition
		b3:0	DEBUG version number
		b7:4	BUILD version number

5.20.2 Sub block 0x40E1 – AWR_MSSCPUFAULT_STATUS_GET_SB

This sub block provides the MSS CPU fault information.
Table 5.139 describes the content of this sub block.

Table 5.139: AWR_MSSVERSION_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x40E1
SBLKLEN	2	Value = 4

Response to AWR_MSSCPUFAULT_STATUS_GET_SB
AWR_MSSCPUFAULT_STATUS_SB is sent in response to AWR_MSSCPUFAULT_STATUS_GET_ SB.
Table 5.140 describes the content of AWR_MSSCPUFAULT_STATUS_SB

Table 5.140: AWR_MSSCPUFAULT_STATUS_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x40E1	
SBLKLEN	2	Value = 36	
FAULT_TYPE	1	Value	Definition
		0	MSS Processor Undefined Instruction Abort
		1	MSS Processor Instruction pre-fetch Abort
		2	MSS Processor Data Access Abort
		3	MSS Processor Firmware Fatal Error
		0x4-0xFF	Reserved
RESERVED	1	0x00	
LINE_NUM	2	Valid only in case of FAULT type is 0x3, provides the firmware line number at which fatal error occurred.	
FAULT_LR	4	The instruction PC address at which Fault occurred	

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Table 5.140 – continued from previous page

FAULT_PREV_LR	4	The return address of the function from which fault function has been called (Call stack LR)
FAULT_SPSR	4	The CPSR register value at which fault occurred
FAULT_SP	4	The SP register value at which fault occurred
FAULT_CAUSE_ADDRESS	4	The address access at which Fault occurred (valid only for fault type 0x0 to 0x2)
FAULT_ERROR_STATUS	2	The status of Error (Error Cause type - valid only for fault type 0x0 to 0x2) 0x000 BACKGROUND_ERR 0x001 ALIGNMENT_ERR 0x002 DEBUG_EVENT 0x00D PERMISSION_ERR 0x008 SYNCH_EXTER_ERR 0x406 ASYNCH_EXTER_ERR 0x409 SYNCH_ECC_ERR 0x408 ASYNCH_ECC_ERR
FAULT_ERROR_SOURCE	1	The Source of the Error (Error Source type - valid only for fault type 0x0 to 0x2) 0x0 ERR_SOURCE_AXI_MASTER 0x1 ERR_SOURCE_ATCM 0x2 ERR_SOURCE_BTCM
FAULT_AXI_ER-ROR_TYPE	1	The AXI Error type (Error Source type - valid only for fault type 0x0 to 0x2) 0x0 AXI_DECOD_ERR 0x1 AXI_SLAVE_ERR
FAULT_ACCESS_TYPE	1	The Error Access type (Error Access type - valid only for fault type 0x0 to 0x2) 0x0 READ_ERR 0x1 WRITE_ERR
FAULT_RECOV-ERY_TYPE	1	The Error Recovery type (Error Recovery type - Valid only for fault type 0x0 to 0x2) 0x0 UNRECOVERY 0x1 RECOVERY
RESERVED	2	0x0000

5.20.3 Sub block 0x40E2 – AWR_MSSESMFAULT_STATUS_GET_SB

This sub block provides the information regarding additional Master sub system faults. Table 5.141 describes the content of this sub block.

Table 5.141: AWR_MSSESMFAULT_STATUS_GET_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x40E2
SBLKLEN	2	Value = 4

The Response to above request is given in the AWR_MSSESMFAULT_STATUS_SB.
Table 5.142 describes the contents of AWR_MSSESMFAULT_STATUS_SB.

Table 5.142: AWR_MSSESMFAULT_STATUS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x40E2
SBLKLEN	2	Value = 20

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Table 5.142 – continued from previous page

ESM_GROUP1_ERRORS	4	Bits	Definition
		b0	NERROR in sync
		b1	RESERVED
		b2	DMA MPU Region tests
		b3	DMA Parity error
		b4	RESERVED
		b5	RESERVED
		b6	Access error interrupt from FFT ACC
		b7	CSI TX FIFO Parity Err
		b8	TPCC parity error
		b9	CBUF ECC single bit error
		b10	RESERVED
		b11	RESERVED
		b12	RESERVED
		b13	Error response from the Peripheral when a DMA transfer is done
		b14	RESERVED
		b15	VIM RAM double bit errors
		b16	RESERVED
		b17	MibSPI double bit error test
		b18	ECC error on CBUFF
		b19	RESERVED
		b20	VIM RAM single bit errors
		b21	RESERVED
		b22	RESERVED
		b23	RESERVED
		b24	RESERVED
		b25	MibSPI single bit error test
		b26	TCMB RAM single bit errors
		b27	STC error
		b28	TCMB RAM single bit errors
		b29	TPTC0 read to protected memory
		b30	DCC compare error
		b31	CR4F self-test error.(test of error path by error forcing)

Table 5.142 – continued from previous page

ESM_GROUP2_ERRORS	4	Bits	Definition
		b0	TCMA RAM single bit errors
		b1	RESERVED
		b2	RESERVED
		b3	TPTC0 write to protected memory
		b4	RESERVED
		b5	RESERVED
		b6	Access error interrupt from FFT ACC
		b7	VIM Self-Test Error
		b8	RESERVED
		b9	RESERVED
		b10	RESERVED
		b11	RESERVED
		b12	QSPI not able to perform the Write to FLASH
		b13	RESERVED
		b14	RESERVED
		b15	RESERVED
		b16	RESERVED
		b17	RESERVED
		b18	RESERVED
		b19	RESERVED
		b20	RESERVED
		b21	RESERVED
		b22	RESERVED
		b23	RESERVED
		b24	RESERVED
		b25	RESERVED
		b26	BSS Mailbox single bit errors
		b27	BSS Mailbox double bit errors
		b28	MSS Mailbox single bit errors
		b29	MSS Mailbox double bit errors
		b30	RESERVED
		b31	RESERVED
RESERVED	4	0x00000000	
RESERVED	4	0x00000000	

5.21 Sub blocks related to AWR␣DEV␣ASYNC␣EVENT␣MSG

5.21.1 Sub block 0x5000 – AWR␣AE␣DEV␣MSSPOWERUPDONE␣SB

This sub block indicates that Master SS power up is now complete. It also indicates the status of boot up tests done by Master SS. This async event is sent when host IRQ is enabled. Table 5.143 describes the contents of this sub block

Table 5.143: AWR␣AE␣DEV␣MSSPOWERUPDONE␣SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x5000
SBLKLEN	2	Value = 24
MSS␣POWERUP␣ TIME	4	Master SS power up time 1 LSB = 5 ns
MSS␣POWERUP␣ STATUS	8	Refer to Table 6.3 for bit map details

BOOTTEST_STATUS	8	1 – PASS, 0 – FAIL	
		Bit	Definition
		b0	MibSPI self-test
		b1	DMA self-test
		b2	Watchdog self-test
		b3	RTI self-test
		b4	ESM self-test
		b5	EDMA self-test
		b6	CRC self-test
		b7	VIM self-test
		b8	MPU self-test
		b9	Mailbox self-test
		b10	LVDS pattern generation test
		b11	CSI2 pattern generation test
		b12	NERROR generation test
		b13	MibSPI single bit error test
		b14	MibSPI double bit error test
		b15	DMA Parity error test
		b16	TCMA RAM single bit error test
		b17	TCMB RAM single bit error test
		b18	TCMA RAM double bit error test
		b19	TCMB RAM double bit error test
		b20	TCMA RAM parity error test
		b21	TCMB RAM parity error test
		b22	VIM lockstep test
		b23	CCM R4 lockstep test
		b24	DMA MPU region test
		b25	MSS Mailbox single bit error test
		b26	MSS Mailbox double bit error test
		b27	BSS Mailbox single bit error test
		b28	BSS Mailbox double bit error test
		b29	EDMA MPU test
		b30	EDMA parity test
		b31	CSI2 parity test
		b32	PBIST (VIM RAM/TCM RAM/MibSPI SRAM/Mailbox/EDMA/DMA/CSI2)
		b33	LBIST (VIM/CR4)
		b63:34	RESERVED

NOTE:	The functional APIs shall be sent to radar device only after receiving AWR_AE_DEV_MSSPOWERUPDONE_SB Async-event after power cycle.

5.21.2 Sub block 0x5001 – AWR_AE_DEV_RFPOWERUPDONE_SB

This sub block indicates that BIST SS power up is now complete.
Table 5.144 describes the contents of this sub block

Table 5.144: AWR_AE_DEV_RFPOWERUPDONE_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x5001
SBLKLEN	2	Value = 20

Table 5.144 – continued from previous page

BSS_POWERUP_BIST_STATUS_FLAGS	4	1 – PASS, 0 – FAIL	
		Bit	Status Information
		b0	ROM CRC check
		b1	CR4 and VIM lockstep test
		b2	RESERVED
		b3	VIM test
		b4	STC test of diagnostic
		b5	CR4 STC
		b6	CRC test
		b7	RAMPGEN memory ECC test
		b8	DFE Parity test
		b9	DFE memory ECC
		b10	RAMPGEN lockstep test
		b11	FRC lockstep test
		b12	DFE memory PBIST
		b13	RAMPGEN memory PBIST
		b14	PBIST test
		b15	WDT test
		b16	ESM test
		b17	DFE STC
		b18	RESERVED
		b19	ATCM, BTCM ECC test
		b20	ATCM, BTCM parity test
		b21	RESERVED
		b22	RESERVED
		b23	RESERVED
		b24	FFT test
		b25	RTI test
		b26	PCR test
		b31:27	RESERVED
POWERUP_TIME	4	RF BIST SS Power up time 1 LSB = 5 ns	
RESERVED	4	0x00000000	
RESERVED	4	0x00000000	

5.21.3 Sub block 0x5002 – AWR_AE_MSS_CPUFAULT_SB

This sub block indicates CPU fault status of Master SS.
Table 5.145 describes the content of this sub block.

Table 5.145: AWR_AE_MSS_CPUFAULT_STATUS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x5002
SBLKLEN	2	Value = 36
FAULT_TYPE	1	0 MSS Processor Undefined Instruction Abort 1 MSS Processor Instruction pre-fetch Abort 2 MSS Processor Data Access Abort 3 MSS Processor Firmware Fatal Error 0x4-0xFF Reserved
RESERVED	1	0x00
LINE_NUM	2	Valid only in case of FAULT type is 0x3, provides the firmware line number at which fatal error occurred.
FAULT_LR	4	The instruction PC address at which Fault occurred
FAULT_PREV_LR	4	The return address of the function from which fault function has been called (Call stack LR)
FAULT_SPSR	4	The CPSR register value at which fault occurred
FAULT_SP	4	The SP register value at which fault occurred
FAULT_CAUSE_ADDRESS	4	The address access at which Fault occurred (valid only for fault type 0x0 to 0x2)
FAULT_ERROR_STATUS	2	The status of Error (Error Cause type - valid only for fault type 0x0 to 0x2) 0x000 BACKGROUND_ERR 0x001 ALIGNMENT_ERR 0x002 DEBUG_EVENT 0x00D PERMISSION_ERR 0x008 SYNCH_EXTER_ERR 0x406 ASYNCH_EXTER_ERR 0x409 SYNCH_ECC_ERR 0x408 ASYNCH_ECC_ERR

Continued on next page

Table 5.145 – continued from previous page

FAULT_ERROR_SOURCE	1	The Source of the Error (Error Source type - valid only for fault type 0x0 to 0x2)
		0x0 ERR_SOURCE_AXI_MASTER
		0x1 ERR_SOURCE_ATCM
		0x2 ERR_SOURCE_BTCM
FAULT_AXI_ERROR_TYPE	1	The AXI Error type (Error Source type - valid only for fault type 0x0 to 0x2)
		0x0 AXI_DECOD_ERR
		0x1 AXI_SLAVE_ERR
FAULT_ACCESS_TYPE	1	The Error Access type (Error Access type - valid only for fault type 0x0 to 0x2)
		0x0 READ_ERR
		0x1 WRITE_ERR
FAULT_RECOVERY_TYPE	1	The Error Recovery type (Error Recovery type - Valid only for fault type 0x0 to 0x2)
		0x0 UNRECOVERY
		0x1 RECOVERY
RESERVED	2	0x0000

5.21.4 Sub block 0x5003 – AWR_AE_MSS_ESMFAULT_STATUS_SB

This sub block indicates any other faults inside the MSS.

Table 5.146 describes the content of this sub block.

Table 5.146: AWR_AE_MSS_ESMFAULT_STATUS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x5003
SBLKLEN	2	Value = 12

Continued on next page

Table 5.146 – continued from previous page

ESM_GROUP1_ERRORS	4	Bits	Definition
		b0	NERROR in sync
		b1	RESERVED
		b2	DMA MPU Region tests
		b3	DMA Parity error
		b4	RESERVED
		b5	RESERVED
		b6	Access error interrupt from FFT ACC
		b7	CSI TX FIFO Parity Err
		b8	TPCC parity error
		b9	CBUF ECC single bit error
		b10	RESERVED
		b11	RESERVED
		b12	RESERVED
		b13	Error response from the Peripheral when a DMA transfer is done
		b14	RESERVED
		b15	VIM RAM double bit errors
		b16	RESERVED
		b17	MibSPI double bit error test
		b18	ECC error on CBUFF
		b19	RESERVED
		b20	VIM RAM single bit errors
		b21	RESERVED
		b22	RESERVED
		b23	RESERVED
		b24	RESERVED
		b25	MibSPI single bit error test
		b26	TCMB RAM single bit errors
		b27	STC error
		b28	TCMB RAM single bit errors
		b29	TPTC0 read to protected memory
		b30	DCC compare error
		b31	CR4F self-test error.(test of error path by error forcing)

Table 5.146 – continued from previous page

ESM_GROUP2_ ERRORS	4	Bits	Definition
		b0	TCMA RAM single bit errors
		b1	RESERVED
		b2	RESERVED
		b3	TPTC0 write to protected memory
		b4	RESERVED
		b5	RESERVED
		b6	Access error interrupt from FFT ACC
		b7	VIM Self-Test Error
		b8	RESERVED
		b9	RESERVED
		b10	RESERVED
		b11	RESERVED
		b12	QSPI not able to perform the Write to FLASH
		b13	RESERVED
		b14	RESERVED
		b15	RESERVED
		b16	RESERVED
		b17	RESERVED
		b18	RESERVED
		b19	RESERVED
		b20	RESERVED
		b21	RESERVED
		b22	RESERVED
		b23	RESERVED
		b24	RESERVED
		b25	RESERVED
		b26	BSS Mailbox single bit errors
		b27	BSS Mailbox double bit errors
		b28	MSS Mailbox single bit errors
		b29	MSS Mailbox double bit errors
		b30	RESERVED
		b31	RESERVED
RESERVED	4	0x00000000	

5.21.5 Sub block 0x5004 – RESERVED

5.21.6 Sub block 0x5005 – AWR_AE_MSS_BOOTERRORSTATUS_SB

This sub block indicates error status of MSS when booted over SPI. This async event is sent after the bootup over SPI is complete.
Table 5.147 describes the content of this sub block.

Table 5.147: AWR_AE_MSS_BOOTERRORSTATUS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x5005
SBLKLEN	2	Value = 24
MSS_POWERUP_TIME	4	Master SS power up time 1 LSB = 5 ns
MSS_POWERUP_STATUS	8	Refer to Table 6.3 for bit map details

Continued on next page

Table 5.147 – continued from previous page

BOOTTEST_STATUS	8	1 – PASS, 0 – FAIL	
		Bit	Definition
		b0	MibSPI self-test
		b1	DMA self-test
		b2	Watchdog self-test
		b3	RTI self-test
		b4	ESM self-test
		b5	EDMA self-test
		b6	CRC self-test
		b7	VIM self-test
		b8	MPU self-test
		b9	Mailbox self-test
		b10	LVDS pattern generation test
		b11	CSI2 pattern generation test
		b12	NERROR generation test
		b13	MibSPI single bit error test
		b14	MibSPI double bit error test
		b15	DMA Parity error test
		b16	TCMA RAM single bit error test
		b17	TCMB RAM single bit error test
		b18	TCMA RAM double bit error test
		b19	TCMB RAM double bit error test
		b20	TCMA RAM parity error test
		b21	TCMB RAM parity error test
		b22	VIM lockstep test
		b23	CCM R4 lockstep test
		b24	DMA MPU region test
		b25	MSS Mailbox single bit error test
		b26	MSS Mailbox double bit error test
		b27	BSS Mailbox single bit error test
		b28	BSS Mailbox double bit error test
		b29	EDMA MPU test
		b30	EDMA parity test
		b31	CSI2 parity test
		b32	PBIST (VIM RAM/TCM RAM/MibSPI SRAM/Mailbox/EDMA/DMA/CSI2)
		b33	LBIST (VIM/CR4)
		b63:34	RESERVED

Table 5.147 – continued from previous page

NOTE:	The functional APIs shall be sent to radar device only after receiving AWR_AE_MSS_BOOTERRORSTATUS_SB Async-event after power-cycle.

5.21.7 Sub block 0x5006 – AWR_AE_MSS_LATENTFAULT_TESTREPORT_SB

This sub block indicates the test status report of the latent fault tests.
Table 5.148 describes the content of this sub block.

Table 5.148: AWR_AE_MSS_LATENTFAULT_TESTREPORT_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x5006
SBLKLEN	2	Value = 16

Table 5.148 – continued from previous page

TEST_STATUS_FLAG1	4	1 – PASS, 0 - FAIL	
		Bits	Definition
		b0	MibSPI self-test
		b1	DMA self-test
		b2	Reserved
		b3	RTI self-test
		b4	ESM self-test
		b5	EDMA self-test
		b6	CRC self-test
		b7	VIM self-test
		b8	Reserved
		b9	Mailbox self-test
		b10	LVDS pattern generation test
		b11	CSI2 pattern generation test
		b12	Generating NERROR
		b13	MibSPI single bit error test
		b14	MibSPI double bit error test
		b15	DMA Parity error
		b16	TCMA RAM single bit errors
		b17	TCMB RAM single bit errors
		b18	TCMA RAM double bit errors
		b19	TCMB RAM double bit errors
		b20	TCMA RAM parity errors.
		b21	TCMB RAM parity errors.
		b22	Reserved
		b23	Reserved
		b24	DMA MPU Region tests
		b25	MSS Mailbox single bit errors
		b26	MSS Mailbox double bit errors
		b27	BSS Mailbox single bit errors
		b28	BSS Mailbox double bit errors
		b29	EDMA MPU test
		b30	EDMA parity test
		b31	CSI2 parity test

Table 5.148 – continued from previous page

TEST_STATUS_FLAG2	4	Bits	Definition
		b0	DCC self-test
		b1	DCC fault insertion test
		b2	PCR fault generation test
		b3	VIM RAM parity test
		b4	SCI boot time test
		b31:5	RESERVED
RESERVED	4	0x00000000	

5.21.8 Sub block 0x5007 – AWR_AE_MSS_PERIODICTEST_STATUS_SB

This sub block indicates test status of the periodic tests.
Table 5.149 describes the content of this sub block.

Table 5.149: AWR_AE_MSS_PERIODICTEST_STATUS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x5007
SBLKLEN	2	Value = 12
TEST_STATUS_FLAG	4	1 – PASS, 0 – FAIL
		Bits Definition
		b0 Periodic read back of static registers
		b1 ESM self-test
		b31:2 RESERVED
RESERVED	4	0x00000000

5.21.9 Sub block 0x5008 – AWR_AE_MSS_RFERROR_STATUS_SB

This sub block indicates the RF error status.
Table 5.150 describes the content of this sub block.

Table 5.150: AWR_AE_MSS_RFERROR_STATUS_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x5008

Table 5.150 – continued from previous page

SBLKLEN	2	Value = 12	
ERROR_STATUS_FLAG	4	Value	Definition
		0	No fault
		1	BSS FW assert
		2	BSS FW abort
		3	BSS ESM GROUP1 ERROR
		4	BSS ESM GROUP2 ERROR
		Others	RESERVED
RESERVED	4	0x00000000	

5.21.10 Sub block 0x5009 – AWR_AE_MSS_VMON_ERRORSTATUS_SB

This sub block indicates fault in analog supplies or LDO short circuit condition. Once a fault is detected the functionality cannot be resumed from then on and the sensor needs to be re-started.

Table 5.151: AWR_AE_MSS_VMON_ERRORSTATUS_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x5009	
SBLKLEN	2	Value = 16	
FAULT_TYPE	1	Value	Definition
		0	NO FAULT
		1	ANALOG_SUPPLY_FAULT
		Others	RESERVED
RESERVED	1	0x00	
RESERVED	2	0x0000	
FAULT_SIG	4	Bit	Definition
		b0	VDDIN under voltage indication
		b1	VDDIN over voltage indication
		b2	VIN_18CLK supply fault
		b3	VIOIN supply fault (Unable to resolve between 1.8V and 3.3V)
		b4	VIN_SRAM under voltage indication
		b5	VIOIN_18 supply fault
		b6	APLL_VCO_LDO short circuit
		b31:7	RESERVED

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Table 5.151 – continued from previous page

RESERVED	4	0x00000000

5.21.11 Sub block 0x500A – AWR_AE_MSS_ADC_DATA_SB

This async event is in response to the command which indicates ADC data needs to be transferred over SPI. This async event contains the ADC data followed by more such async events for additional data.

Table 5.152: AWR_AE_MSS_ADC_DATA_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x500A
SBLKLEN	2	Value = Variable (max = 226)
REMCHUNKS	2	Number of remaining chunks expected. (Remaining length / 220 bytes)
ADC_DATA	Variable (4 - 220 bytes)	ADC data captured by the MMIC

5.21.12 Sub block 0x500B – RESERVED

5.22 Brief notes on the order of issuing API SBs

5.22.1 Single device mode

This section briefly describes in which order to issue the various API SBs defined in this document for a single device.

1. Power up the device

2. Wait for AWR_AE_MSSPOWERUPDONE_SB

3. AWR_DEV_RFPOWERUP_SB

4. Wait for AWR_AE_RFPOWERUPDONE_SB

5. AWR_RF_MISC_CONF_SET_MSG

6. AWR_RF_STATIC_CONF_SET_MSG
    a. AWR_CHAN_CONF_SET_SB
    b. AWR_ADCOUT_CONF_SET_SB

    c. AWR_RF_LDO_BYPASS_SB with RFLDOBYPASS_EN set to 1 if RF supply is 1.0 V

    d. AWR_LOWPOWERMODE_CONF_SET_SB

    e. AWR_DYNAMICPOWERSAVE_CONF_SET_SB

7. Data path configurations

    a. AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB

    b. AWR_DEV_RX_DATA_PATH_CONF_SET_SB

    c. AWR_DEV_RX_DATA_PATH_LANE_EN_SB

    d. AWR_DEV_RX_DATA_PATH_CLK_SET_SB

    e. AWR_HIGHSPEEDINTFCLK_CONF_SET_SB

    f. AWR_DEV_LVDS_CFG_SET_SB / AWR_DEV_CSI2_CFG_SET_SB

8. AWR_RF_INIT_MSG

    a. AWR_RFINIT_SB: This triggers very basic calibrations and RF initializations

    b. Wait for AWR_AE_RF_INITCALIBSTATUS_SB

9. AWR_RF_DYNAMIC_CONF_SET_MSG

    a. AWR_PROG_FILT_COEFF_RAM_SET_SB (Applicable only in xWR1642 or xWR1843)

    b. AWR_PROG_FILT_CONF_SET_SB (Applicable only in xWR1642 or xWR1843)

    c. AWR_PROFILE_CONF_SET_SB

    d. AWR_CHIRP_CONF_SET_SB

    e. AWR_LOOPBACK_BURST_CONF_SET_SB

    f. AWR_FRAME_CONF_SET_SB or AWR_ADVANCED_FRAME_CONF_SB (if using loop-back burst)

    g. AWR_CALIB_MON_TIME_UNIT_CONF_SB with CALIB_MON_TIME_UNIT value set to a value such that the total frame idle time across multiple CALIB_MON_TIME_UNITs is sufficient for all calibrations and monitoring. See Section 9 for details on calibration and monitoring durations.

    h. AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB (set all ONE_TIME_CALIB_ENABLE_MASK and set ENABLE_CAL_REPORT = 1)

    i. Wait for AWR_RUN_TIME_CALIBRATION_SUMMARY_REPORT_AE_SB

    j. AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB (set all RUN_TIME_CALIB_ENABLE_MASK and set ENABLE_CAL_REPORT = 0 to avoid receiving periodic async events)

    k. AWR_DEV_FRAME_CONFIG_APPLY_MSG

10. AWR_RF_FRAME_TRIG_MSG

a. AWR_FRAMESTARTSTOP_CONF_SB in Start mode: after this, frames get transmitted

11. AWR_RF_FRAME_TRIG_MSG

a. AWR_FRAMESTARTSTOP_CONF_SB in Stop mode: after this, frames are stopped
The AWR_RF_FRAME_TRIG_MSG may be issued multiple times for multiple sets of frames.

5.22.2 Cascaded device mode

This section briefly describes in which order to issue the various API SBs defined in this document for master and slave devices in a cascaded configuration.

When using cascaded devices, the reference clock is provided by master to slave. So unless master is powered-up and clock is available from master to slave, the slave device cannot be powered up.

Table 5.153: Sequence of APIs to be issued to master and slave devices in cascaded mode configuration for FMCW mode measurements

Sl. No	Master device sequence	Slave device sequence
1	Power up master device	
2	Wait for AWR_AE_DEV_MSSPOWERUP-DONE_SB	
3	AWR_DEV_RFPOWERUP_SB	
4	Wait for AWR_AE_DEV_RFPOWERUP-DONE_SB	
5	AWR_CHAN_CONF_SET_SB with CAS-CADING_CFG = 0x0001. This will enable the reference clock for slave device	
6		Power on slave device
7		Wait for AWR_AE_DEV_MSSPOWERUP-DONE_SB
8		AWR_DEV_RFPOWERUP_SB
9		Wait for AWR_AE_DEV_RFPOWERUP-DONE_SB
10		AWR_CHAN_CONF_SET_SB with CAS-CADING_CFG = 0x0002.
11	AWR_ADCOUT_CONF_SET_SB	AWR_ADCOUT_CONF_SET_SB
12	AWR_RF_LDO_BYPASS_SB with RFLDOBYPASS_EN = 1 if RF supply is 1.0V	AWR_RF_LDO_BYPASS_SB with RFLDOBYPASS_EN = 1 if RF supply is 1.0V

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13	AWR_LOWPOWERMODE_CONF_SET_SB	AWR_LOWPOWERMODE_CONF_SET_SB
14	AWR_DYNAMICPOWERSAVE_CONF_SET_SB	AWR_DYNAMICPOWERSAVE_CONF_SET_SB
15	AWR_RF_INIT_SB	AWR_RF_INIT_SB
16	Wait for AWR_AE_RF_INITALIBSTATUS_SB	Wait for AWR_AE_RF_INITALIBSTATUS_SB
17	AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB	AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB
18	AWR_DEV_RX_DATA_PATH_CONF_SET_SB	AWR_DEV_RX_DATA_PATH_CONF_SET_SB
19	AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB	AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB
20	AWR_HIGHSPEEEDINTFCLK_CONF_SET_SB	AWR_HIGHSPEEEDINTFCLK_CONF_SET_SB
21	AWR_DEV_RX_DATA_PATH_CLK_SET_SB	AWR_DEV_RX_DATA_PATH_CLK_SET_SB
22	AWR_DEV_LVDS_CFG_SET_SB/AWR_DEV_CSI2_CFG_SET_SB	AWR_DEV_LVDS_CFG_SET_SB/AWR_DEV_CSI2_CFG_SET_SB
23	AWR_PROFILE_CONF_SET_SB	AWR_PROFILE_CONF_SET_SB
24	AWR_CHIRP_CONF_SET_SB	AWR_CHIRP_CONF_SET_SB
25	AWR_FRAME_CONF_SET_SB with TRIGGER_SELECT = 0x0001	AWR_FRAME_CONF_SET_SB with TRIGGER_SELECT = 0x0002
26	AWR_DEV_FRAME_CONFIG_APPLY_MSG	AWR_DEV_FRAME_CONFIG_APPLY_MSG
27		AWR_FRAMESTARTSOP_CONF_SB with STARTSTOP_CMD = 0x0001
28		Wait for AWR_AE_RF_FRAME_TRIGGER_RDY_SB
29	AWR_FRAMESTARTSOP_CONF_SB with STARTSTOP_CMD = 0x0001	
30	Wait for AWR_AE_RF_FRAME_TRIGGER_RDY_SB	

5.22.3 Continuous streaming mode (in single device case)

This section briefly describes in which order to issue the various API SBs defined in this document to enable continuous streaming mode on a single device

1. Power up the device

2. Wait for AWR_AE_MSSPOWERUPDONE_SB

3. AWR_DEV_RFPOWERUP_SB

4. Wait for AWR_AE_RFPOWERUPDONE_SB

5. AWR_RF_MISC_CONF_SET_MSG

6. AWR_RF_STATIC_CONF_SET_MSG

   a. AWR_CHAN_CONF_SET_SB

   b. AWR_ADCOUT_CONF_SET_SB

   c. AWR_RF_LDO_BYPASS_SB with RFLDOBYPASS_EN set to 1 if RF supply is 1.0V

   d. AWR_LOWPOWERMODE_CONF_SET_SB

   e. AWR_DYNAMICPOWERSAVE_CONF_SET_SB

7. AWR_RF_STATIC_CONF_SET_MSG

8. Data path configurations

   a. AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB

   b. AWR_DEV_RX_DATA_PATH_CONF_SET_SB

   c. AWR_DEV_RX_DATA_PATH_LANE_EN_SB

   d. AWR_DEV_RX_DATA_PATH_CLK_SET_SB

   e. AWR_HIGHSPEEDINTFCLK_CONF_SET_SB

   f. AWR_DEV_LVDS_CFG_SET_SB / AWR_DEV_CSI2_CFG_SET_SB

9. AWR_RF_INIT_MSG

   a. AWR_RFINIT_SB: This triggers very basic calibrations and RF initializations

   b. Wait for AWR_AE_RF_INITCALIBSTATUS_SB

10. AWR_CONT_STREAMING_MODE_CONF_SET_SB

11. AWR_DEV_RX_CONTSTREAMING_MODE_CONF_SET_SB

12. AWR_CONT_STREAMING_MODE_EN_SB with CONT_STREAMING_EN = 0x0001 to start continuous streaming

13. AWR_CONT_STREAMING_MODE_EN_SB with CONT_STREAMING_EN = 0x0000 to stop continuous streaming

14. Repeat steps 9-11 for a different configuration

5.22.4 Continuous streaming (CW) mode (in cascaded device case)

Table 5.154: Sequence of APIs to be issued to master and slave devices in cascaded mode for CW mode measurements

Sl. No	Master device sequence	Slave device sequence
1	Power up master device	
2	Wait for AWR_AE_DEV_MSSPOWERUP-DONE_SB	
3	AWR_DEV_RFPOWERUP_SB	
4	Wait for AWR_AE_DEV_RFPOWERUP-DONE_SB	
5	AWR_CHAN_CONF_SET_SB with CAS-CADING_CFG = 0x0001. This will enable the reference clock for slave device	
6		Power on slave device
7		Wait for AWR_AE_DEV_MSSPOWERUP-DONE_SB
8		AWR_DEV_RFPOWERUP_SB
9		Wait for AWR_AE_DEV_RFPOWERUP-DONE_SB
10		AWR_RF_LDO_BYPASS_SB with RFLDOBYPASS_EN = 1 if RF supply is 1.0V
11		AWR_CHAN_CONF_SET_SB with CAS-CADING_CFG = 0x0002.
12	AWR_ADCOUT_CONF_SET_SB	AWR_ADCOUT_CONF_SET_SB
13	AWR_RF_LDO_BYPASS_SB with RFLDOBYPASS_EN = 1 if RF supply is 1.0V	
14	AWR_LOWPOWERMODE_CONF_SET_SB	AWR_LOWPOWERMODE_CONF_SET_SB
15	AWR_DYNAMICPOWERSAVE_CONF_SET_SB	AWR_DYNAMICPOWERSAVE_CONF_SET_SB
16	AWR_RF_INIT_SB	AWR_RF_INIT_SB
17	Wait for AWR_AE_RF_INITALIBSTATUS_SB	Wait for AWR_AE_RF_INITALIBSTATUS_SB
18	AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB	AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB
19	AWR_DEV_RX_DATA_PATH_CONF_SET_SB	AWR_DEV_RX_DATA_PATH_CONF_SET_SB
20	AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB	AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB

Continued on next page

Table 5.154 – continued from previous page

21	AWR_HIGHSPEEEDINTFCLK_CONF_SET_SB	AWR_HIGHSPEEEDINTFCLK_CONF_SET_SB
22	AWR_DEV_RX_DATA_PATH_CLK_SET_SB	AWR_DEV_RX_DATA_PATH_CLK_SET_SB
23	AWR_DEV_LVDS_CFG_SET_SB/AWR_DEV_CSI2_CFG_SET_SB	AWR_DEV_LVDS_CFG_SET_SB/AWR_DEV_CSI2_CFG_SET_SB
24	AWR_CONT_STREAMING_MODE_CONF_SET_SB	
25	AWR_CONT_STREAMING_MODE_EN_SB with CONT_STREAMING_EN = 0x0001 to start continuous streaming	
26		AWR_CONT_STREAMING_MODE_CONF_SET_SB with the same RF frequency configuration as in master device
27		AWR_CONT_STREAMING_MODE_EN_SB with CONT_STREAMING_EN = 0x0001 to start continuous streaming
28		AWR_CONT_STREAMING_MODE_EN_SB with CONT_STREAMING_EN = 0x0000 to stop continuous streaming
29	AWR_CONT_STREAMING_MODE_EN_SB with CONT_STREAMING_EN = 0x0000 to stop continuous streaming	
30	Repeat steps 24-29 for a different CW mode configuration	

6 API Error Codes

<p align="center">Table 6.1: BSS API error codes</p>

	1	Incorrect API MSGID
	2	Sub block not found in the MSG
	3	Incorrect Sub block ID
Applicable to all API sub blocks	4	Incorrect Sub block length
	5	Incorrect Sub block data
	6	Error in processing the command
	7	Binary file CRC mismatch error
	8	Binary file type mismatch w.r.t. magic number
AWR_ FRAMESTARTSTOP_ CONF_SB	20	Frames are already started when the FRAME_START command was issued
	21	Frames are already stopped when the FRAME_STOP command was issued
	22	No valid frame configuration API was issued and frames are started
	23	START_STOP_CMD parameter is out of range
AWR_CHAN_CONF_SET_ SB	24	RX_CHAN_EN parameter is out of range (Max range may vary based on device variant)
	25	TX_CHAN_EN parameter is out of range (Max range may vary based on device variant)
	26	CASCADING_CFG parameter is out of range [0, 2]
	282	Device variant does not allow cascading but API is issued to enable cascading mode
AWR_ADCOUT_CONF_ SET_SB	27	NUM_ADC_BITS parameter is out of range [0, 2]
	28	ADC_OUT_FMT parameter is out of range [0, 3]
	127	FULL_SCALE_REDUCTION_FACTOR is > 0 for 16 bit ADC, or > 2 for 14 bit ADC mode or > 4 for 12 bit ADC mode
AWR_LOWPOWERMODE_ CONF_SET_SB	29	LP_ADC_MODE parameter is out of range [0, 1]
	156	Regular ADC mode is used on a 5 MHz part variant device
AWR_DYNAMICPOW-ERSAVE_CONF_SET_ SB	30	BLOCK_CFG parameter is out of range [0, 7]
AWR_ HIGHSPEEDINTFCLK_ CONF_SET_SB	31	HSICLKRATECODE[1:0] is 0

Table 6.1 – continued from previous page

	32	RESERVED
	33	HSICLKRATECODE[3:2] is 3 and HSICLKRATECODE[1:0] is 2
	34	HSICLKRATECODE[3:2] is 3 and HSICLKRATECODE[1:0] is 2
AWR_PROFILE_CONF_SET_SB	35	PF_INDX is $\geq$ 4
	36	PF_FREQ_START_CONST is not within [76, 81] GHz
	37	PF_IDLE_TIME_CONST $>$ 5.24 ms
	38	Maximum DFE spill time $>$ PF_IDLE_TIME_CONST
	39	PF_ADC_START_TIME_CONST $>$ 4095
	40	PF_RAMP_END_TIME $>$ 524287
	41	PF_RAMP_END_TIME $<$ PF_ADC_START_TIME_CONST + ADC_SAMPLING_TIME (ADC_SAMPLING_TIME is time taken to sample NUM_ADC_SAMPLES)
	42	PF_TX_OUTPUT_POWER_BACKOFF for TX0 $>$ 30
	43	PF_TX_OUTPUT_POWER_BACKOFF for TX1 $>$ 30
	44	PF_TX_OUTPUT_POWER_BACKOFF for TX2 $>$ 30
	45	RESERVED
	46	Ramp end frequency is not within [76, 81] GHz
	47	Absolute value of TX_START_TIME is $>$ 38.45 μs
	48	Number of ADC samples is not within [64, 8192]
	49	Output sampling rate is not within [2, MaxSamplingRate] Msps. See Table 5.20 for the MaxSamplingRate.
	50	HPF1 corner frequency is $>$ 700 kHz
	51	HPF2 corner frequency is $>$ 2.8 MHz
	52	PF_RX_GAIN is not within [24, 52] dB or PF_RX_GAIN is an odd number
	53	RESERVED
	54	RESERVED
	55	RESERVED
	56	RESERVED
	57	RESERVED
	58	RESERVED
AWR_CHIRP_CONF_SET_SB	59	CHIRP_START_INDX $\geq$ 512
	60	CHIRP_END_INDX $\geq$ 512
	61	CHIRP_START_INDX $>$ CHIRP_END_INDX

Continued on next page

Table 6.1 – continued from previous page

	62	PROFILE_INDX $\geq$ 4
	63	If the profile corresponding to PROFILE_INDX is not defined
	64	CHIRP_FREQ_START_VAR $>$ 8388607
	65	CHIRP_FREQ_SLOPE_VAR $>$ 63
	66	Chirp start frequency is outside [76, 78] GHz if the selected VCO is VCO1 or Chirp start frequency is outside [77, 81] GHz if the selected VCO is VCO2 or Chirp end frequency is outside [76, 78] GHz if the selected VCO is VCO1 or Chirp end frequency is outside [77, 81] GHz if the selected VCO is VCO2 or Chirp bandwidth is greater than maximum allowed as per device data sheet or Maximum chirp frequency is greater than maximum allowed as per device data sheet
	67	CHIRP_IDLE_TIME_VAR $>$ 4095
	68	CHIRP_ADC_START_TIME_VAR $>$ 4095
	69	RAMP_END_TIME $<$ ADC_START_TIME + ADC_SAMPLING_TIME
	70	CHIRP_TX_EN $>$ maximum simultaneous TX allowed as per device data sheet
	71	CHIRP_TX_EN indicates to enable a TX which is not enabled in AWR_CHAN_CONF_SET_SB
AWR_FRAME_CONF_SET_SB	72	CHIRP_START_INDX $\geq$ 512
	73	CHIRP_END_INDX $\geq$ 512
	74	CHIRP_START_INDX $>$ CHIRP_END_INDX
	75	Chirp used in the frame is not configured by AWR_CHIRP_CONF_SET_SB
	76	One of the profiles used in the frame is not configured by AWR_PROF_CONF_SET_SB
	77	NUM_LOOPS is outside [1, 255]
	78	RESERVED
	79	FRAME_PERIODICITY is outside [100 μs, 1.342 s]
	80	FRAME_ON_TIME $<$ FRAME_PERIODICITY
	81	TRIGGER_SELECT is outside [1, 2]
	82	FRAME_TRIGGER_DELAY $>$ 100 μs
	83	API is issued when frames are ongoing

Table 6.1 – continued from previous page

AWR_ADVANCED_ FRAME_CONF_SET_ SB	84	NUM_SUBFRAMES is outside [1, 4]
	85	FORCE_SINGLE_PROFILE is outside [0, 1]
	86	FORCE_SINGLE_PROFILE $\geq$ 4
	87	Profile defined by FORCE_SINGLE_PROFILE is not defined
	88	SFx_CHIRP_START_INDX $\geq$ 512
	89	SFx_NUM_UNIQUE_CHIRPS_PER_BURST is outside the range [1, 512]
	90	Chirp used in the frame is not configured by AWR_CHIRP_ CONF_SET_SB
	91	One of the profiles used in the frame is not configured by AWR_PROF_CONF_SET_SB
	92	SFx_NUM_LOOPS_PER_BURST is outside the range [1, 255]
	93	SFx_BURST_PERIOD is outside the range [100 μs, 1.342 s]
	94	Burst ON time is > BURST_PERIOD
	95	SFx_CHIRP_START_INDX_OFFSET $\geq$ 512
	96	SFx_CHIRP_START_INDX $\geq$ 512 or SFx_CHIRP_START_ INDX + SFx_NUM_UNIQUE_CHIRPS_PER_BURST $-$ 1 is $\geq$ 512
	97	SFx_NUM_BURSTS is outside the range [1, 512]
	98	SFx_NUM_OUTER_LOOPS is outside the range [1, 64]
	99	SFx_PERIOD is outside the range [100 μs, 1.342 s]
	100	Subframe on time > SFx_PERIOD or when TESTSOURCE is enabled, SubFrame Idle time is < 150 μs
	101	RESERVED
	102	TRIGGER_SELECT is outside the range [1, 2]
	103	FRAME_TRIGGER_DELAY is > 100 μs
	104	API is issued when frames are on going
AWR_RF_TEST_SOURCE_ CONFIG_SET_SB	105	POSITION_VECx[y] < 0
	106	RESERVED
	107	VELOCITY_VECx[x] > 5000 or VELOCITY_VECx[y] > 5000 or VELOCITY_VECx[z] > 5000
	108	SIG_LEV_VECx > 950
	109	RX_ANT_POS_XZ[Bytex] > 120
	110	RESERVED

Table 6.1 – continued from previous page

AWR_PROG_FILT_CONF_SET_SB	111	PROG_FILT_COEFF_START_INDEX is an odd number
	112	PROFILE_INDX $\geq$ 4
	126	DFE mode is pseudo real
AWR_PROG_FILT_COEFF_RAM_SET_SB	113	API is issued for a non xWR1642/xWR1843 device
	126	DFE mode is pseudo real
AWR_RF_RADAR_MISC_CTL_SB	114	API is issued for a non xWR1243 device
AWR_PERCHIRPPHASESHIFT_CONF_SB	115	CHIRP_START_INDX $\geq$ 512
	116	CHIRP_END_INDX $\geq$ 512
	117	CHIRP_START_INDX $>$ CHIRP_END_INDX
AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB	118	Boot time calibrations are not done so cannot run runtime calibrations
AWR_CAL_MON_FREQUENCY_LIMITS_SB	119	FREQ_LIMIT_HIGH $<$ 76 GHz or FREQ_LIMIT_HIGH $>$ 81 GHz or FREQ_LIMIT_LOW $>$ FREQ_LIMIT_HIGH
AWR_CALIB_MON_TIME_UNIT_CONF_SB	120	CALIB_MON_TIME_UNIT $\leq$ 0
AWR_RUN_TIME_CALIBRATION_CONF_AND_TRIGGER_SB	121	CALIBRATION_PERIODICITY = 0
	122	API is issued when continuous streaming mode is on
	123	RX gain run time calibration was requested but boot time calibration was not performed
	124	LO distribution run time calibration was requested but boot time calibration was not performed
	125	TX power run time calibration was requested but boot time calibration was not performed
AWR_LOOPBACK_BURST_CONF_SET_SB	132	LOOPBACK_SEL is $>$ 3
	133	BURST_INDX $\geq$ 16
	134	Burst is not valid but loopback is enabled for this burst
AWR_DYN_CHIRP_CONF_SET_SB	135	CHIRP_SEGMENT_SELECT $>$ 31 if CHIRP_ROW_SELECT = 0 or CHIRP_SEGMENT_SELECT $>$ 11 if CHIRP_ROW_SELECT != 0
	159	CHIRP_ROW_SELECT $>$ 3
AWR_DYN_PER_CHIRP_PHASESHIFTER_CONF_SB	136	CHIRP_SEGMENT_SELECT $>$ 31

Table 6.1 – continued from previous page

AWR_CAL_DATA_RE-STORE_SB	137	CHUNK_ID $\geq$ NUM_CHUNKS
	138	CAL_DATA is invalid
AWR_INTERCHIRP_BLOCKCONTROLS_SB	139	RX02_RF_TURN_OFF_TIME is not within the range [-1024, 1023]
	140	RX13_RF_TURN_OFF_TIME is not within the range [-1024, 1023]
	141	RX02_BB_TURN_OFF_TIME is not within the range [-1024, 1023]
	142	RX13_BB_TURN_OFF_TIME is not within the range [-1024, 1023]
	143	RX02_RF_PREENABLE_TIME is not within the range [-1024, 1023]
	144	RX13_RF_PREENABLE_TIME is not within the range [-1024, 1023]
	145	RX02_BB_PREENABLE_TIME is not within the range [-1024, 1023]
	146	RX13_BB_PREENABLE_TIME is not within the range [-1024, 1023]
	147	RX02_RF_TURN_ON_TIME is not within the range [-1024, 1023]
	148	RX13_RF_TURN_ON_TIME is not within the range [-1024, 1023]
	149	RX02_BB_TURN_ON_TIME is not within the range [-1024, 1023]
	150	RX13_BB_TURN_ON_TIME is not within the range [-1024, 1023]
	151	RX_LO_TURN_OFF_TIME is not within the range [-1024, 1023]
	152	TX_LO_TURN_OFF_TIME is not within the range [-1024, 1023]
	153	RX_LO_TURN_ON_TIME is not within the range [-1024, 1023]
	154	TX_LO_TURN_ON_TIME is not within the range [-1024, 1023]
AWR_SUBFRAME_START_CONF_SB	155	Sub-frame start command is issued but the frame is not configured for sub frame trigger mode
	250	Device type is not ASILB
	251	Fault injection API or Digital latent fault API is issued when frames are ongoing
Common to all monitoring configuration APIs	252	Invalid reporting mode

Continued on next page

Table 6.1 – continued from previous page

	253	Configured profile ID is not within [0, 3]
	254	Monitoring profile ID is not configured yet
	260	Invalid RF bit mask
	281	Analog monitoring is not supported
	290	Monitoring chirp error
AWR_MONITOR_RF_DIG_ LATENTFAULT_CONF_SB	251	API is issued when frames are on-going
AWR_MONITORING_ EXTERNAL_ANALOG_ SIGNALS_CONF_SB	255	Settling time is configured is more than 12 μs
AWR_MONITOR_RX_ INTERNAL_ANALOG_ SIGNALS_CONF_SB	256	None of the RXs are enabled
AWR_MONITOR_TX0_ INTERNAL_ANALOG_ SIGNALS_CONF_SB	257	TX0 is not enabled
AWR_MONITOR_TX1_ INTERNAL_ANALOG_ SIGNALS_CONF_SB	258	TX1 is not enabled
AWR_MONITOR_TX2_ INTERNAL_ANALOG_ SIGNALS_CONF_SB	259	TX2 is not enabled
-	261	RESERVED
-	262	RESERVED
AWR_MONITOR_TXn_ BALLBREAK_CONF_SB	263	Monitored TX channel is not enabled
AWR_MONITOR_RX_ GAIN_PHASE_CONF_SB	264	Monitored RX channel is not enabled
AWR_MONITOR_RX_ NOISE_FIGURE_CONF_ SB		
AWR_MONITOR_RX_ GAIN_PHASE_CONF_SB	265	TX selected for RX gain phase monitor is TX2 (Only TX0 or TX1 is allowed)
	291	PD power level is less than -40dBm (Used for RX Gain Monitor)
	295	PGA Gain used for monitoring is incorrect
AWR_MONITOR_RX_ SATURATION_ DETECTOR_CONF_SB	266	SAT_MON_SEL is not in [0, 3]
	267	SAT_MON_PRIMARY_TIME_SLICE_DURATION is less than 0.64 μs or greater than ADC sampling time
	268	SAT_MON_NUM_SLICES is 0 or greater than 127

Continued on next page

Table 6.1 – continued from previous page

	283	RX saturation monitor is not supported
AWR_MONITOR_SIG_IMG_MONITOR_CONF_SB	269	SIG_IMG_MON_NUM_SLICES is 0 or greater than 127
	270	NUM_SAMPLES_PER_PRIMARY_TIME_SLICE is odd, or less than 4 in Complex1x mode or less than 8 in non-Complex1x modes or greater than NUM_ADC_SAMPLES
	280	Signal and image band monitor is not supported
AWR_ANALOG_FAULT_INJECTION_CONF_SB	279	LDO fault inject is requested but LDOs are bypassed
AWR_MONITOR_TXn_POWER_CONF_SB AWR_MONITOR_TXn_BALLLBREAK_CONF_SB AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_CONF_SB	294	PD Reading incorrect (RF OFF reading higher than RF ON reading)
AWR_MONITOR_RX_GAIN_PHASE_CONF_SB AWR_MONITOR_TX_GAIN_PHASE_CONF_SB AWR_MONITOR_TXn_BPM_CONF_SB	292	ADC power level higher than +7 dBm or lower than -9.5 dBm
AWR_MONITOR_RX_NOISE_FIGURE_CONF_SB	293	Low RX noise figure (Noise Figure is less than 0 dB)

Table 6.2: MSS API error codes (Applicable only in xWR1243)

	1	Incorrect API MSGID
	2	Sub block not found in the MSG
	3	Incorrect Sub block ID
	4	Incorrect Sub block length
Applicable to all API sub blocks	5	Incorrect Sub block data
	6	Error in processing the command
	7	Binary file CRC mismatch error
	8	Binary file type mismatch w.r.t. magic number
AWR_DEV_RX_DATA_FORMAT_CONF_SET_SB	1001	RX_CHAN_EN > 0xF
	1002	NUM_ADC_BITS > 2
	1003	ADC_OUT_FMT > 1

Table 6.2 – continued from previous page

	1004	IQ_SWAP_SEL > 1
	1005	CHAN_INTERLEAVE > 1
AWR_DEV_RX_DATA_PATH_CONF_SET_SB	1006	DATA_INTF_SEL > 1
	1007	DATA_TRANS_FMT_PKT0 [5:0] not a valid value. Valid set {0x1, 0x6, 0x9, 0x36}
	1008	DATA_TRANS_FMT_PKT1 [5:0] not a valid value. Valid set {0x0, 0xD, 0xB}
	1050	CQ_CONFIG is out of range
AWR_DEV_RX_DATA_PATH_LANEEN_SET_SB	1009	LANE_EN > 0xF
	1010	Reserved
AWR_DEV_RX_DATA_PATH_CLK_SET_SB	1011	LANE_CLK_CFG > 1
	1012	LANE_CLK_CFG != 1 for CSI2
	1013	DATA_RATE - Invalid combination of data rate and DDR or SDR operation
AWR_DEV_LVDS_CFG_SET_SB	1014	LANE_FMT_MAP > 1
	1015	LANE_PARAM_CFG > 7
AWR_DEV_RX_CONTSTREAMING_MODE_CONF_SET_SB	1016	CONT_STREAMING_MODE > 1
	1017	CONT_STREAMING_MODE already in requested mode
AWR_DEV_CSI2_CFG_SET_SB	1018	LANE_POS_POL_SEL [DATA_LANE0_POS] >5
	1019	LANE_POS_POL_SEL [DATA_LANE1_POS] >5
	1020	LANE_POS_POL_SEL [DATA_LANE2_POS] >5
	1021	LANE_POS_POL_SEL [DATA_LANE3_POS] >5
	1022	LANE_POS_POL_SEL [CLOCK_POS] is outside the range [2,4]
AWR_DEV_FRAME_CONFIG_APPLY_SB	1023	HALF_WORDS_PER_CHIRP is outside the range [64, 8192]
AWR_DEV_ADV_FRAME_CONFIG_APPLY_SB	1024	NUM_SUBFRAMES is outside the range [1,4]
	1025	SF1_TOT_NUM_CHIRPS is outside the range [1, 0xFFFF]
	1026	SF1_NUM_ADC_SAMPLES_PER_DATA_PKT is outside the range [64, 8192]
	1027	SF1_PROC_NUM_CHIRPS_PER_DATA_PKT != 1

Table 6.2 – continued from previous page

	1028	SF2_TOT_NUM_CHIRPS is outside the range [1, 0xFFFF], if NUM_SUBFRAMES ≥ 2
	1029	SF2_NUM_ADC_SAMPLES_PER_DATA_PKT is outside the range [64, 8192], if NUM_SUBFRAMES ≥ 2
	1030	SF2_PROC_NUM_CHIRPS_PER_DATA_PKT != 1, if NUM_SUBFRAMES ≥2
	1031	SF3_TOT_NUM_CHIRPS is outside the range [1, 0xFFFF], if NUM_SUBFRAMES ≥3
	1032	SF3_NUM_ADC_SAMPLES_PER_DATA_PKT is outside the range [64, 8192], if NUM_SUBFRAMES ≥ 3
	1033	SF3_PROC_NUM_CHIRPS_PER_DATA_PKT != 1, if NUM_SUBFRAMES ≥3
	1034	SF4_TOT_NUM_CHIRPS is outside the range [1, 0xFFFF], if NUM_SUBFRAMES == 4
	1035	SF4_NUM_ADC_SAMPLES_PER_DATA_PKT is outside the range [64, 8192], if NUM_SUBFRAMES == 4
	1036	SF4_PROC_NUM_CHIRPS_PER_DATA_PKT != 1, if NUM_SUBFRAMES == 4
AWR_DEV_MCUCLOCK_CONF_SET_SB	1040	MCUCLOCK_CTRL is out of range
	1041	MCUCLOCK_SRC is out of range
AWR_DEV_PMICCLOCK_CONF_SET_SB	1042	PMICCLOCK_CTRL is out of range
	1043	PMICCLOCK_SRC is out of range
	1044	MODE_SELECT is out of range
	1045	FREQ_SLOPE is out of range
	1046	CLK_DITHER_EN is out of range
AWR_DEV_TESTPAT-TERN_GEN_SET_SB	1047	TESTPATTERN_GEN_CTRL is out of range
	1048	DATA_INTF_SEL (Data interface selected in AWR_DEV_RX_DATA_PATH_CONF_SET_SB) is SPI

6.1 Error codes for boot on SPI

Table 6.3: Bit field describing the error status during boot on SPI

Error description	Error code	Error code bit position
CERT_AUTH_FAILURE	0x00000001	BIT0
CERT_PARSER_FAILURE	0x00000002	BIT1
RPRC_IMG1_AUTH_FAILURE	0x00000004	BIT2
RPRC_IMG2_AUTH_FAILURE	0x00000008	BIT3
RPRC_IMG3_AUTH_FAILURE	0x00000010	BIT4
RPRC_HDR_NOT_FOUND	0x00000020	BIT5
METAHEADER_NOT_FOUND	0x00000040	BIT6
SW_ANTIROLLBACK_CHK_FAILURE	0x00000080	BIT7
EFUSE_INTEGRITY_FAILURE	0x00000100	BIT8
CERT_FIELD_VALIDITY_FAILURE	0x00000200	BIT9
CERT_FIELD_INVALID_AUTH_KEY_INDEX	0x00000400	BIT10
CERT_FIELD_INVALID_HASH_TYPE	0x00000800	BIT11
CERT_FIELD_INVALID_SUBSYSTEM	0x00001000	BIT12
CERT_FIELD_INVALID_DECRYPT_KEY_INDEX	0x00002000	BIT13
CERT_FIELD_CEK_EFUSE_MISMATCH	0x00004000	BIT14
CERT_FIELD_CEK1_EFUSE_MISMATCH	0x00008000	BIT15
CERT_FIELD_CEK2_EFUSE_MISMATCH	0x00010000	BIT16
CERT_FIELD_INVALID_SUBSYSTEM_BANK_ALLO-CATION	0x00020000	BIT17
CERT_FIELD_INVALID_TOTAL_BANKS_ALLOCATION	0x00040000	BIT18
RPRC_PARSER_FILE_LENGTH_MISMATCH	0x00080000	BIT19
RPRC_PARSER_MSS_FILE_OFFSET_MISMATCH	0x00100000	BIT20
RPRC_PARSER_BSS_FILE_OFFSET_MISMATCH	0x00200000	BIT21
RPRC_PARSER_DSS_FILE_OFFSET_MISMATCH	0x00400000	BIT22
CERT_FIELD_INVALID_DECRYPT_KEY	0x00800000	BIT23
CERT_FIELD_INVALID_AUTH_KEY	0x01000000	BIT24
HS_DEVICE_CERT_NOT_PRESENT	0x02000000	BIT25
TEST_PORT_ENABLING_FAILED	0x04000000	BIT26
SHARED_MEM_ALLOC_FAILED	0x08000000	BIT27
MSSIMAGE_NOT_FOUND	0x10000000	BIT28
METAHEADER_NUMFILES_ERROR	0x20000000	BIT29
METAHEADER_CRC_FAILURE	0x40000000	BIT30

7 Radar Monitoring APIs

AWR monitoring can be configured through a set of API sub blocks defined in this section. Note that these APIs cover the RF/Analog related monitoring mechanisms. There are separate monitoring mechanisms for the digital logic (including the processor, memory, etc.) which are internal to the device and not explicitly enabled through these APIs.

The monitoring APIs are structured as follows. There are common configuration APIs that control the overall periodicity of monitoring, as well as, enable/disable control for each monitoring mechanism. Then, for each monitoring mechanism there is an individual API to allow the customer to set an appropriate threshold for declaring failure from that monitoring. Also, for each monitoring mechanism, there is an individual API to report soft (raw) values from that monitoring.

NOTE:	Each monitor can perform monitoring on only one profile at a time. Though it is possible that different monitors can monitor different profiles simultaneously.

7.1 Common Configurations and Reports

This section covers the APIs corresponding to the common configurations and reports.

NOTE:	Except for RX saturation monitor and RX signal and image band monitor, any monitor described in this section is not applicable for an IWR device

7.1.1 Sub block 0x01C0 – AWR_MONITOR_RF_DIG_LATENTFAULT_CONF_SB

This API SB contains the consolidated configuration of all digital monitoring. This is issued by the host to the AWR device.

The enabled monitoring functions are executed when the API is issued. The scheduling of these monitoring should be handled in the external application. Report of these monitoring will be available in the async event AWR_MONITOR_RF_DIG_LATENTFAULT_REPORT_AE_SB.

Table 7.1: AWR_MONITOR_RF_DIG_LATENTFAULT_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01C0

Continued on next page

Table 7.1 – continued from previous page

SBLKLEN	2	Value = 16	
DIG_MONITOR-ING_ENABLES	4	1 – Enable, 0 – Disabled	
		Bit	Definition
		b0	RESERVED
		b1	CR4 and VIM lockstep test
		b2	RESERVED
		b3	VIM test
		b4	RESERVED
		b5	RESERVED
		b6	CRC test
		b7	RAMPGEN memory ECC
		b8	DFE Parity test
		b9	DFE memory ECC
		b10	RAMPGEN lockstep test
		b11	FRC lockstep test of diagnostic
		b12	RESERVED
		b13	RESERVED
		b14	RESERVED
		b15	RESERVED
		b16	ESM test
		b17	DFE STC
		b18	RESERVED
		b19	ATCM, BTCM ECC test
		b20	ATCM, BTCM parity test
		b21	RESERVED
		b22	RESERVED
		b23	RESERVED
		b24	FFT test
		b25	RTI test
		b26	PCR test
		b31:27	RESERVED
TEST_MODE	1	Value	Definition
		0	Production mode. Latent faults are tested and any failures are reported
		1	Characterization mode. Faults are injected and failures are reported which allows testing of the failure reporting path

RESERVED	3	0x000000
RESERVED	4	0x00000000

7.1.2 Sub block 0x01C1 – AWR_MONITOR_RF_DIG_PERIODIC_CONF_SB

This API SB contains the consolidated configuration of all periodic digital monitoring within radar sub-system. This is issued by the host to the AWR device.

The enabled monitoring functions are executed periodically and reports are sent based on reporting mode. Report of these monitoring will be available in the async event AWR_MONITOR_ RF_DIG_PERIODIC_REPORT_AE_SB.

Table 7.2: AWR_MONITOR_RF_DIG_PERIODIC_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01C1
SBLKLEN	2	Value = 16
REPORTING_ MODE	1	Value Definition 0 Report is sent every monitoring period 1 Report is sent only on a failure 2 RESERVED
RESERVED	3	0x000000
PERIODIC_DIG_ MON_EN	4	1 – Enable, 0 – Disable Bit Monitoring type b0 PERIODIC_CONFG_REGISTER_READ_EN b1 ESM_MONITORING_EN b2 DFE_STC_EN b3 FRAME_TIMING_MONITORING_EN b31:4 RESERVED
RESERVED	4	0x00000000

7.1.3 Sub block 0x01C2 – AWR_MONITOR_ANALOG_ENABLES_CONF_SB

This API SB contains the consolidated configuration of all analog monitoring. This is issued by the host to the AWR device.

The enabled monitoring functions are executed with a periodicity of CAL_MON_TIME_UNITS number of logical frames. The host should ensure that all the enabled monitors can be completed in the available inter-frame times, based on the monitoring durations (to be provided separately).

Table 7.3: AWR_MONITOR_ANALOG_ENABLES_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01C2
SBLKLEN	2	Value = 12
ANA_MONITOR-ING_ENABLES	4	If any bit in this field is set to 1, the associate monitors are enabled. The configurations and reports of each monitors are described in respective sub sections. Bit Definition b0 TEMPERATURE_MONITOR b1 RX_GAIN_PHASE_MONITOR b2 RX_NOISE_FIGURE_MONITOR b3 RX_IFSTAGE_MONITOR b4 TX0_POWER_MONITOR b5 TX1_POWER_MONITOR b6 TX2_POWER_MONITOR b7 TX0_BALLBREAK_MONITOR b8 TX1_BALLBREAK_MONITOR b9 TX2_BALLBREAK_MONITOR b10 TX_GAIN_PHASE_MISMATCH_MONITOR b11 TX0_BPM_MONITOR b12 TX1_BPM_MONITOR b13 TX2_BPM_MONITOR b14 SYNTH_FREQ_MONITOR b15 EXTERNAL_ANALOG_SIGNALS_MONITOR b16 INTERNAL_TX0_SIGNALS_MONITOR b17 INTERNAL_TX1_SIGNALS_MONITOR b18 INTERNAL_TX2_SIGNALS_MONITOR b19 INTERNAL_RX_SIGNALS_MONITOR b20 INTERNAL_PMCLKLO_SIGNALS_MONITOR b21 INTERNAL_GPADC_SIGNALS_MONITOR b22 PLL_CONTROL_VOLTAGE_MONITOR b23 DCC_CLOCK_FREQ_MONITOR b24 RX_SATURATION_DETECTOR_MONITOR b25 RX_SIG_IMG_BAND_MONITOR b26 RX_MIXER_INPUT_POWER_MONITOR b31:27 RESERVED

LDO_SC_MONI-TORING_EN	4	If any bit in this field is set to 1, the associated monitors are enabled. There are no reports for these monitors. If there is any fault, the async event AWR_ANALOGFAULT_AE_SB will be sent.
		Bit Description
		b0 APLL LDO short circuit monitoring enable 0 – disable, 1 – enable
		b1 SYNTH VCO LDO short circuit monitoring enable 0 – disable, 1 – enable
		b2 PA LDO short circuit monitoring enable 0 – disable, 1 – enable
		b31:3 RESERVED

7.2 Temperature Monitor

This section contains API SBs that configure the on chip temperature monitors and report the soft results from the monitor. The corresponding monitors are collectively named TEMPERATURE_MONITOR. These monitors observe the temperature near various RF analog and digital modules using temperature sensors and GPADC and compare them against configurable thresholds. The report is sent as an async event AWR_MONITOR_TEMPERATURE_REPORT_AE_SB.

7.2.1 Sub block 0x01C3 – AWR_MONITOR_TEMPERATURE_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to temperature monitoring. Report of this monitoring will be available in the async event AWR_MONITOR_TEMPERATURE_REPORT_AE_SB.

Table 7.4: AWR_MONITOR_TEMPERATURE_CONF_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x01C3	
SBLKLEN	2	Value = 24	
REPORTING_MODE	1	Value	Definition
		0	Report is sent every monitoring period without threshold check
		1	Report is send only upon a failure (after checking for thresholds)
		2	Report is sent every monitoring period with threshold check

Table 7.4 – continued from previous page

RESERVED	1	0x00
ANA_TEMP_THRESH_MIN	2	The temperatures read from near the sensors near the RF analog modules are compared against a minimum threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is outside this (minimum, maximum) range). 1 LSB = 1°C, signed number Valid range: -99°C to 199°C
ANA_TEMP_THRESH_MAX	2	The temperatures read from near the sensors near the RF analog modules are compared against a maximum threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is outside this (minimum, maximum) range). 1 LSB = 1°C, signed number Valid range: -99°C to 199°C
DIG_TEMP_THRESH_MIN	2	The temperatures read from near the sensor near the digital module are compared against a minimum threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is outside this (minimum, maximum) range). 1 LSB = 1°C, signed number Valid range: -99°C to 199°C
DIG_TEMP_THRESH_MAX	2	The temperatures read from near the sensor near the digital module are compared against a maximum threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is outside this (minimum, maximum) range). 1 LSB = 1°C, signed number Valid range: -99°C to 199°C
TEMP_DIFF_THRESH	2	The maximum difference across temperatures read from all the enabled sensors is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if the measured difference exceeds this field). 1 LSB = 1°C, unsigned number Valid range: 0°C to 100°C
RESERVED	4	0x00000000
RESERVED	4	0x00000000

7.3 RX Gain and Phase Monitor

This section contains API SBs that configure the monitors of receiver gain and phase. The corresponding monitors are collectively named RX_GAIN_PHASE_MONITOR. The report is sent

as an async event AWR_MONITOR_RX_GAIN_PHASE_REPORT_AE_SB.

7.3.1 Sub block 0x01C4 – AWR_MONITOR_RX_GAIN_PHASE_CONF_SB

This is a monitoring configuration API which the host sends to the AWR device, containing information related to RX gain and phase monitoring.

Table 7.5: AWR_MONITOR_RX_GAIN_PHASE_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01C4
SBLKLEN	2	Value = 72
PROFILE_INDX	1	This field indicates the profile Index for which this monitoring configuration applies.
RF_FREQ_BIT-MASK	1	This field indicates the RF frequencies inside the profile's RF band at which to measure the required parameters. When each bit in this field is set, the measurement at the corresponding RF frequency is enabled w.r.t. the profile's RF band.
		Bit number RF frequency RF name
		b0 Lowest RF frequency in profile's sweep bandwidth RF1
		b1 Center RF frequency in profile's sweep bandwidth RF2
		b2 Highest RF frequency in profile's sweep bandwidth RF3
		The RF name column is mentioned here to set the convention for the purpose of reporting and describing many monitoring packets.
RESERVED	1	0x00
TX_SEL	1	Value Definition
		0 TX0 is used for generating loopback signal for RX gain measurement
		1 TX1 is used for generating loopback signal for RX gain measurement

Continued on next page

Table 7.5 – continued from previous page

RX_GAIN_ ABS_ERROR_ THRESH	2	The magnitude of difference between the programmed and measured RX gain for each enabled channel at each enabled RF frequency, is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). Before the comparison, the measured gains for each RF and RX are adjusted by subtracting the offset given in the RX_GAIN_MISMATCH_OFFSET_VALUE field 1 LSB = 0.1 dB Valid range: 0 to 60 (0 to 6dB)
RX_GAIN_MIS- MATCH_THRESH	2	The magnitude of difference between measured RX gains across the enabled channels at each enabled RF frequency is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if the measurement is above this threshold). Before the comparison, the measured gains for each RF and RX are adjusted by subtracting the offset given in the RX_GAIN_MISMATCH_OFFSET_VALUE field. 1 LSB = 0.1 dB Valid range: 0 to 60 (0 to 6dB)
RX_GAIN_FLAT- NESS_ERROR_ THRESH	2	The magnitude of measured RX gain flatness error, for each enabled channel, is compared against this threshold. The flatness error for a channel is defined as the peak to peak variation across RF frequencies. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). Before the comparison, the measured gains for each RF and RX are adjusted by subtracting the offset given in the RX_GAIN_MISMATCH_OFFSET_VALUE field. 1 LSB = 0.1 dB Valid range: 0 to 60 (0 to 6dB) This flatness check is applicable only if multiple RF Frequencies are enabled, i.e., RF_FREQ_BITMASK has bit numbers 0,1,2 set.

Table 7.5 – continued from previous page

RX_PHASE_MIS-MATCH_THRESH	2	The magnitude of measured RX phase mismatch across the enabled channels at each enabled RF frequency is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). Before the comparison, the measured phases for each RF and RX are adjusted by subtracting the offset given in the RX_PHASE_MISMATCH_OFFSET_VALUE field. 1 LSB = $360°/2^{16}$. Valid range: corresponding to $0°$ to $20°$.
RX_GAIN_MIS-MATCH_OFF-SET_VALUE	24	The offsets to be subtracted from the measured RX gain for each RX and RF before the relevant threshold comparisons are given here. Byte numbers corresponding to different RX and RF, in this field are here: RF1 RF2 RF3 RX0 1:0 9:8 17:16 RX1 3:2 11:10 19:18 RX2 5:4 13:12 21:20 RX3 7:6 15:14 23:22 1 LSB = 0.1 dB, signed number Only the entries of enabled RF Frequencies and enabled RX channels are considered.
RX_PHASE_MISMATCH_OFFSET_VALUE	24	The offsets to be subtracted from the measured RX phase for each RX and RF before the relevant threshold comparisons are given here. RF1 RF2 RF3 RX0 1:0 9:8 17:16 RX1 3:2 11:10 19:18 RX2 5:4 13:12 21:20 RX3 7:6 15:14 23:22 1 LSB = $360°/2^{16}$, unsigned number Only the entries of enabled RF Frequencies and enabled RX channels are considered.
RESERVED	4	0x00000000
RESERVED	4	0x00000000

7.4 RX Noise Monitor

This section contains API SBs that configure the monitor of receiver noise, and report the soft results from the monitor. The corresponding monitor is named RX_NOISE_FIGURE_MONITOR. The report is sent as an async event AWR_MONITOR_RX_NOISE_FIGURE_REPORT_AE_SB.

7.4.1 Sub block 0x01C5 – AWR_MONITOR_RX_NOISE_FIGURE_CONF_SB

This is a monitoring configuration API which the host sends to the AWR device, containing information related to RX noise monitoring of a profile.

Table 7.6: AWR_MONITOR_RX_NOISE_FIGURE_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01C5
SBLKLEN	2	Value = 16
PROFILE_INDX	1	This field indicates the profile Index for which this monitoring configuration applies.
RF_FREQ_BIT-MASK	1	This field indicates the exact RF frequencies inside the profile's RF band at which to measure the required parameters. When each bit in this field is set, the measurement at the corresponding RF frequency is enabled w.r.t. the profile's RF band. <table><tr><td>Bit number</td><td>RF frequency</td><td>RF name</td></tr><tr><td>b0</td><td>Lowest RF frequency in profile's sweep bandwidth</td><td>RF1</td></tr><tr><td>b1</td><td>Center RF frequency in profile's sweep bandwidth</td><td>RF2</td></tr><tr><td>b2</td><td>Highest RF frequency in profile's sweep bandwidth</td><td>RF3</td></tr></table> The RF name column is mentioned here to set the convention for the purpose of reporting and describing many monitoring packets.
RESERVED	2	0x0000
REPORTING_MODE	1	<table><tr><td>Value</td><td>Definition</td></tr><tr><td>0</td><td>Report is sent every monitoring period without threshold check</td></tr><tr><td>1</td><td>Report is send only upon a failure (after checking for thresholds)</td></tr><tr><td>2</td><td>Report is sent every monitoring period with threshold check</td></tr></table>
RESERVED	1	0x00

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| RX_NOISE_FIG-URE_THRESH-OLD | 2 | The measured RX input referred noise figure at the enabled RF frequencies, for all channels, is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). 1 LSB = 0.1 dB Valid range: 0 to 300 |
| RESERVED | 4 | 0x00000000 |

7.5 RX IF Stage Monitor

This section contains API SBs that configure the monitors of receiver IF filter attenuation, and report the soft results from the monitor. The corresponding monitor is named RX_IFSTAGE_MONITOR. The report is sent as an async event AWR_MONITOR_RX_IFSTAGE_REPORT_AE_SB.

7.5.1 Sub block 0x01C6 – AWR_MONITOR_RX_IFSTAGE_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to RX IF filter attenuation monitoring. The report is sent as as an async event AWR_MONITOR_RX_IFSTAGE_REPORT_AE_SB.

Table 7.7: AWR_MONITOR_RX_IFSTAGE_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01C6
SBLKLEN	2	Value = 20
PROFILE_INDX	1	This field indicates the Profile Index for which this monitoring configuration applies.
REPORTING_MODE	1	Value Definition 0 Report is sent every monitoring period without threshold check 1 Report is send only upon a failure (after checking for thresholds) 2 Report is sent every monitoring period with threshold check
RESERVED	2	0x0000
RESERVED	2	0x0000

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Table 7.7 – continued from previous page

HPF_CUTOFF_FREQ_ERROR_THRESH	2	The absolute values of RX IF HPF cutoff percentage frequency errors are compared against the corresponding thresholds given in this field. The comparison results are part of the monitoring report message (Error bit is set if the absolute value of the errors exceeds respective thresholds). 1 LSB = 1%, unsigned number Valid range: 1% to 99%
LPF_CUTOFF_FREQ_ERROR_THRESH	2	The absolute values of RX IF LPF cutoff percentage frequency errors are compared against the corresponding thresholds given in this field. The comparison results are part of the monitoring report message (Error bit is set if the absolute value of the errors exceeds respective thresholds). 1 LSB = 1%, unsigned number Valid range: 1% to 99%
IFA_GAIN_ER-ROR_THRESH	2	The absolute deviation of RX IFA Gain from the expected gain for each enabled RX channel is compared against the thresholds given in this field. The comparison result is part of the monitoring report message (Error bit is set if the absolute value of the errors exceeds respective thresholds). 1 LSB = 0.1 dB, unsigned number Valid range: 0 to 60 (0 to 6dB)
RESERVED	4	0x00000000

7.6 TX Power Monitor

This section contains API SBs that configure the monitors of transmitter output power, and report the soft results from the monitor. The corresponding monitors are collectively named TXn_POWER_MONITOR where n is the TX channel number.

7.6.1 Sub block 0x01C7 – AWR_MONITOR_TX0_POWER_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX0 power monitoring. Absolute TX power and flatness across RF frequencies are monitored here. The report is sent as an async event AWR_MONITOR_TX0_POWER_REPORT_AE_SB.

Table 7.8: AWR_MONITOR_TX0_POWER_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01C7
SBLKLEN	2	Value = 20
PROFILE_INDX	1	This field indicates the Profile Index for which this monitoring configuration applies.
RF_FREQ_BIT-MASK	1	This field indicates the exact RF frequencies inside the profile's RF band at which to measure the required parameters. When each bit in this field is set, the measurement at the corresponding RF frequency is enabled w.r.t. the profile's RF band.
		Bit number RF frequency RF name
		b0 Lowest RF frequency in profile's sweep bandwidth RF1
		b1 Center RF frequency in profile's sweep bandwidth RF2
		b2 Highest RF frequency in profile's sweep bandwidth RF3
		The RF Name column is mentioned here to set the convention for the purpose of reporting and describing many monitoring packets.
RESERVED	2	0x0000
REPORTING_MODE	1	Value Definition
		0 Report is sent every monitoring period without threshold check
		1 Report is send only upon a failure (after checking for thresholds)
		2 Report is sent every monitoring period with threshold check
RESERVED	1	0x00
TX_POWER_ABSOLUTE_ERROR_THRESH	2	The magnitude of difference between the programmed and measured TX power for each enabled channel at each enabled RF frequency, is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). 1 LSB = 0.1 dBm Valid range: 0 to 60 (0 to 6dB)

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Table 7.8 – continued from previous page

TX_POWER_ FLATNESS_ER- ROR_THRESH	2	The magnitude of measured TX power flatness error, for each enabled channel, is compared against this threshold. The flatness error for a channel is defined as the peak to peak variation across RF frequencies. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). 1 LSB = 0.1 dB Valid range: 0 to 60 (0 to 6dB) This flatness check is applicable only if multiple RF Frequencies are enabled.
RESERVED	2	0x0000
RESERVED	4	0x00000000

7.6.2 Sub block 0x01C8 – AWR_MONITOR_TX1_POWER_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX1 power monitoring. Absolute TX power and flatness across RF frequencies are monitored here. The report is sent as an async event AWR_MONITOR_TX1_POWER_REPORT_AE_SB.

Table 7.9: AWR_MONITOR_TX1_POWER_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01C8
SBLKLEN	2	Value = 20
PROFILE_INDX	1	This field indicates the Profile Index for which this monitoring configuration applies.

Table 7.9 – continued from previous page

RF_FREQ_BIT-MASK	1	This field indicates the exact RF frequencies inside the profile's RF band at which to measure the required parameters. When each bit in this field is set, the measurement at the corresponding RF frequency is enabled w.r.t. the profile's RF band. Bit number — RF frequency — RF name b0 — Lowest RF frequency in profile's sweep bandwidth — RF1 b1 — Center RF frequency in profile's sweep bandwidth — RF2 b2 — Highest RF frequency in profile's sweep bandwidth — RF3 The RF Name column is mentioned here to set the convention for the purpose of reporting and describing many monitoring packets.
RESERVED	2	0x0000
REPORTING_MODE	1	Value — Definition 0 — Report is sent every monitoring period without threshold check 1 — Report is send only upon a failure (after checking for thresholds) 2 — Report is sent every monitoring period with threshold check
RESERVED	1	0x00
TX_POWER_ABSOLUTE_ERROR_THRESH	2	The magnitude of difference between the programmed and measured TX power for each enabled channel at each enabled RF frequency, is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). 1 LSB = 0.1 dBm Valid range: 0 to 60 (0 to 6dB)
TX_POWER_FLATNESS_ERROR_THRESH	2	The magnitude of measured TX power flatness error, for each enabled channel, is compared against this threshold. The flatness error for a channel is defined as the peak to peak variation across RF frequencies. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). 1 LSB = 0.1 dB Valid range: 0 to 60 (0 to 6dB) This flatness check is applicable only if multiple RF Frequencies are enabled.
RESERVED	2	0x0000

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Table 7.9 – continued from previous page

RESERVED	4	0x00000000

7.6.3 Sub block 0x01C9 – AWR_MONITOR_TX2_POWER_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX2 power monitoring. Absolute TX power and flatness across RF frequencies are monitored here. The report is sent as an async event AWR_MONITOR_TX2_POWER_REPORT_AE_SB.

Table 7.10: AWR_MONITOR_TX2_POWER_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01C9
SBLKLEN	2	Value = 20
PROFILE_INDX	1	This field indicates the Profile Index for which this monitoring configuration applies.
RF_FREQ_BIT-MASK	1	This field indicates the exact RF frequencies inside the profile's RF band at which to measure the required parameters. When each bit in this field is set, the measurement at the corresponding RF frequency is enabled w.r.t. the profile's RF band. Bit number RF frequency RF name b0 Lowest RF frequency in profile's sweep bandwidth RF1 b1 Center RF frequency in profile's sweep bandwidth RF2 b2 Highest RF frequency in profile's sweep bandwidth RF3 The RF Name column is mentioned here to set the convention for the purpose of reporting and describing many monitoring packets.
RESERVED	2	0x0000
REPORTING_MODE	1	Value Definition 0 Report is sent every monitoring period without threshold check 1 Report is send only upon a failure (after checking for thresholds) 2 Report is sent every monitoring period with threshold check

Table 7.10 – continued from previous page

RESERVED	1	0x00
TX_POWER_ABSOLUTE_ER-ROR_THRESH	2	The magnitude of difference between the programmed and measured TX power for each enabled channel at each enabled RF frequency, is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). 1 LSB = 0.1 dBm Valid range: 0 to 60 (0 to 6dB)
TX_POWER_FLATNESS_ER-ROR_THRESH	2	The magnitude of measured TX power flatness error, for each enabled channel, is compared against this threshold. The flatness error for a channel is defined as the peak to peak variation across RF frequencies. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). 1 LSB = 0.1 dB Valid range: 0 to 60 (0 to 6dB) This flatness check is applicable only if multiple RF Frequencies are enabled.
RESERVED	2	0x0000
RESERVED	4	0x00000000

7.7 TX Ball Break Monitor

This section contains API SBs that configure the monitors of transmitter balls and impedance matching. The corresponding monitors are collectively named TXn_BALLBREAK_MONITOR where n is the TX channel number.

TX ball break detection is performed through measurement of TX reflection coefficient's magnitude. The breakage of a TX ball is detected by observing high reflection magnitude.

7.7.1 Sub block 0x01CA – AWR_MONITOR_TX0_BALLBREAK_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX ball break detection.
This API SB controls the thresholds for the reflection coefficient magnitude check and the parameters for the reflection coefficient error distance check (variation from values at the time of factory calibration). The report is sent as an async event AWR_MONITOR_TX0_BALLBREAK_REPORT_AE_SB.

Table 7.11: AWR_MONITOR_TX0_BALLBREAK_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01CA
SBLKLEN	2	Value = 16
REPORTING_MODE	1	Value Definition 0 Report is sent every monitoring period without threshold check 1 Report is send only upon a failure (after checking for thresholds) 2 Report is sent every monitoring period with threshold check
RESERVED	1	0x00
TX_REFL_CO-EFF_THRESH	2	The TX reflection coefficient's magnitude for each enabled channel is compared against the threshold given here. The comparison result is part of the monitoring report message (Error bit is set if the measurement is higher than this threshold, with the units of both quantities being the same). 1 LSB = 0.1 dB, signed number Valid range: -90 to -250
RESERVED	4	0x00000000
RESERVED	4	0x00000000

7.7.2 Sub block 0x01CB – AWR_MONITOR_TX1_BALLBREAK_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX ball break detection.

This API SB controls the thresholds for the reflection coefficient magnitude check and the parameters for the reflection coefficient error distance check (variation from values at the time of factory calibration). The report is sent as an async event AWR_MONITOR_TX1_BALLBREAK_REPORT_AE_SB.

Table 7.12: AWR_MONITOR_TX1_BALLBREAK_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01CB
SBLKLEN	2	Value = 16

Table 7.12 – continued from previous page

REPORTING_ MODE	1	Value	Definition
		0	Report is sent every monitoring period without threshold check
		1	Report is send only upon a failure (after checking for thresholds)
		2	Report is sent every monitoring period with threshold check
RESERVED	1	0x00	
TX_REFL_CO- EFF_THRESH	2	The TX reflection coefficient's magnitude for each enabled channel is compared against the threshold given here. The comparison result is part of the monitoring report message (Error bit is set if the measurement is higher than this threshold, with the units of both quantities being the same). 1 LSB = 0.1 dB, signed number Valid range: -90 to -250	
RESERVED	4	0x00000000	
RESERVED	4	0x00000000	

7.7.3 Sub block 0x01CC – AWR_MONITOR_TX2_BALLBREAK_CONF_SB

This API is a monitoring monfiguration API which the host sends to the AWR device, containing information related to TX ball break detection.

This API SB controls the thresholds for the reflection coefficient magnitude check and the parameters for the reflection coefficient error distance check (variation from values at the time of factory calibration). The report is sent as an async event AWR_MONITOR_TX2_BALLBREAK_REPORT_ AE_SB.

Table 7.13: AWR_MONITOR_TX2_BALLBREAK_CONF_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x01CC	
SBLKLEN	2	Value = 16	
REPORTING_ MODE	1	Value	Definition
		0	Report is sent every monitoring period without threshold check
		1	Report is send only upon a failure (after checking for thresholds)
		2	Report is sent every monitoring period with threshold check

Continued on next page

Table 7.13 – continued from previous page

RESERVED	1	0x00
TX_REFL_CO-EFF_THRESH	2	The TX reflection coefficient's magnitude for each enabled channel is compared against the threshold given here. The comparison result is part of the monitoring report message (Error bit is set if the measurement is higher than this threshold, with the units of both quantities being the same). 1 LSB = 0.1 dB, signed number Valid range: -90 to -250
RESERVED	4	0x00000000
RESERVED	4	0x00000000

7.8 TX Gain and Phase Mismatch Monitoring

This section contains API SBs that configure the monitors of transmitter gain and phase mismatches, and report the soft results from the monitor. The corresponding monitors are collectively named TX_GAIN_PHASE_MISMATCH_MONITOR.

This monitor needs the operation of at least one RX channel. It also needs to use the RX in complex mode. Therefore, if all channels are disabled as per AWR_CHAN_CONF_SET_SB, this monitor automatically enables one RX channel. Further, this monitor automatically uses both I and Q channels of the receiver, irrespective of the ADC settings given by AWR_ADCOUT_CONF_SET_SB.

7.8.1 Sub block 0x01CD – AWR_MONITOR_TX_GAIN_PHASE_MISMATCH_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX gain and phase mismatch monitoring. The report is sent as an async event AWR_MONITOR_TX_GAIN_PHASE_REPORT_AE_SB.

Table 7.14: AWR_MONITOR_TX_GAIN_PHASE_MISMATCH_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01CD
SBLKLEN	2	Value = 56
PROFILE_INDX	1	This field indicates the Profile Index for which this monitoring configuration applies.

Table 7.14 – continued from previous page

RF_FREQ_BIT-MASK	1	This field indicates the exact RF frequencies inside the profile's RF band at which to measure the required parameters. When each bit in this field is set, the measurement at the corresponding RF frequency is enabled w.r.t. the profile's RF band.
		Bit number RF frequency RF name
		b0 Lowest RF frequency in profile's sweep bandwidth RF1
		b1 Center RF frequency in profile's sweep bandwidth RF2
		b2 Highest RF frequency in profile's sweep bandwidth RF3
		The RF Name column is mentioned here to set the convention for the purpose of reporting and describing many monitoring packets.
TX_EN	1	This field indicates the TX channels that should be compared for gain and phase balance. Setting the corresponding bit to 1 enables that channel for imbalance measurement.
		Bit number TX Channel
		b0 TX0
		b1 TX1
		b2 TX2
RX_EN	1	This field indicates the RX channels that should be enabled for TX to RX loopback measurement. Setting the corresponding bit to 1 enables that channel for imbalance measurement.
		Bit number RX Channel
		b0 RX0
		b1 RX1
		b2 RX2
		b3 RX3
RESERVED	1	0x00
RESERVED	1	0x00

Table 7.14 – continued from previous page

TX_GAIN_MIS-MATCH_THRESH	2	The magnitude of difference between measured TX powers across the enabled channels at each enabled RF frequency is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if the measurement is above this threshold). Before the comparison, the measured gains for each RF and RX are adjusted by subtracting the offset given in the TX_GAIN_MISMATCH_OFFSET_VALUE field. 1 LSB = 0.1 dB, unsigned number Valid range: 0 to 60 (0 to 6dB)
TX_PHASE_MIS-MATCH_THRESH	2	The magnitude of measured TX phase mismatch across the enabled channels at each enabled RF frequency is compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if any measurement is above this threshold). Before the comparison, the measured gains for each RF and RX are adjusted by subtracting the offset given in the TX_PHASE_MISMATCH_OFFSET_VALUE field. 1 LSB = $360°/2^{16}$, unsigned number Valid range: corresponding to $0°$ to $20°$.
TX_GAIN_MIS-MATCH_OFF-SET_VALUE	18	The offsets to be subtracted from the measured TX gain for each TX and RF before the relevant threshold comparisons are given here. Byte numbers corresponding to different RX and RF, in this field are here:

	RF1	RF2	RF3
TX0	1:0	7:6	13:12
TX1	3:2	9:8	15:14
TX2	5:4	11:10	17:16

Only the entries of enabled RF Frequencies and enabled TX channels are considered.

Table 7.14 – continued from previous page

TX_PHASE_ MISMATCH_ OFFSET_VALUE	18	The offsets to be subtracted from the measured TX phase for each TX and RF before the relevant threshold comparisons are given here. Byte numbers corresponding to different RX and RF, in this field are here:

<div style="margin-left:2em">

	RF1	RF2	RF3
TX0	1:0	7:6	13:12
TX1	3:2	9:8	15:14
TX2	5:4	11:10	17:16

1 LSB = $360°/2^{16}$.
Only the entries of enabled RF Frequencies and enabled TX channels are considered.

</div>

RESERVED	2	0x0000
RESERVED	4	0x00000000

> **NOTE:** The TX3 has a fixed offset of -8dB gain and -8 degree phase with respect to TX1 and TX2 by design, user has to compensate these values in the gain and phase offset fields of this API for TX3.

7.9 TX BPM Phase Monitor

This section contains API SBs that configure the monitors of transmitter binary phase modulation, and report the soft results from the monitor, for various TX channels. The corresponding monitors are collectively named TX0_BPM_MONITOR, TX1_BPM_MONITOR and TX2_BPM_MONITOR for the respective TX channels.

7.9.1 Sub block 0x01CE – AWR_MONITOR_TX0_BPM_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX0 BPM monitoring.
The report is sent as an async event AWR_MONITOR_TX0_BPM_REPORT_AE_SB.

Table 7.15: AWR_MONITOR_TX0_BPM_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01CE
SBLKLEN	2	Value = 20
PROFILE_INDX	1	This field indicates the Profile Index for which this monitoring configuration applies.

<div align="right">Continued on next page</div>

Table 7.15 – continued from previous page

PH_SHIFTER_MON_CFG	1	Bit	Definition
		b7	Phase shifter monitoring enabled
		b6	Phase shifter monitoring increment enabled
		b5:0	Phase shifter monitoring increment value 1 LSB = $5.625°$
PH_SHIFTER_MON1	1	Phase1 of the phase shifter of TX0 which needs to be monitored 1 LSB = $5.625°$	
PH_SHIFTER_MON2	1	Phase2 of the phase shifter of TX0 which needs to be monitored 1 LSB = $5.625°$	
REPORTING_MODE	1	Value	Definition
		0	Report is sent every monitoring period without threshold check
		1	Report is send only upon a failure (after checking for thresholds)
		2	Report is sent every monitoring period with threshold check
RX_EN	1	This field indicates the RX channels that should be enabled for TX to RX loopback measurement. Setting the corresponding bit to 1 enables that channel for imbalance measurement.	
		Bit number	RX Channel
		b0	RX0
		b1	RX1
		b2	RX2
		b3	RX3
TX_BPM_PHASE_ERROR_THRESH	2	The deviation of the TX output phase difference between the two BPM settings from the ideal $180°$ is compared against the threshold given here. The comparison result is part of the monitoring report message (Error bit is set if the measurement is higher than this threshold, with the units of both quantities being the same). 1 LSB = $360°/2^{16}$. Valid range: corresponding to $0°$ to $20°$.	

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Table 7.15 – continued from previous page

TX_BPM_AMPLI-TUDE_ERROR_THRESH	2	The deviation of the TX output amplitude difference between the two BPM settings is compared against the threshold given here. The comparison result is part of the monitoring report message (Error bit is set if the measurement is higher than this threshold, with the units of both quantities being the same). 1 LSB = 0.1 dB Valid range: 0 to 60 (0 to 6dB)
PH_SHIFTER_THRESH_MAX	2	Maximum threshold for the difference in the 2 configured phase shift values 1 LSB = 5.625°
PH_SHIFTER_THRESH_MIN	2	Minimum threshold for the difference in the 2 configured phase shift values 1 LSB = 5.625°
RESERVED	2	0x0000

7.9.2 Sub block 0x01CF – AWR_MONITOR_TX1_BPM_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX1 BPM monitoring. The report is sent as an async event AWR_MONITOR_TX1_BPM_REPORT_AE_SB.

Table 7.16: AWR_MONITOR_TX1_BPM_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01CF
SBLKLEN	2	Value = 20
PROFILE_INDX	1	This field indicates the Profile Index for which this monitoring configuration applies.
PH_SHIFTER_MON_CFG	1	Bit / Definition b7 — Phase shifter monitoring enabled b6 — Phase shifter monitoring increment enabled b5:0 — Phase shifter monitoring increment value 1 LSB = $5.625°$
PH_SHIFTER_MON1	1	Phase1 of the phase shifter of TX1 which needs to be monitored 1 LSB = $5.625°$
PH_SHIFTER_MON2	1	Phase2 of the phase shifter of TX1 which needs to be monitored 1 LSB = $5.625°$

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Table 7.16 – continued from previous page

REPORTING_ MODE	1	Value Definition
		0 Report is sent every monitoring period without threshold check
		1 Report is send only upon a failure (after checking for thresholds)
		2 Report is sent every monitoring period with threshold check
RX_EN	1	This field indicates the RX channels that should be enabled for TX to RX loopback measurement. Setting the corresponding bit to 1 enables that channel for imbalance measurement.
		Bit number RX Channel
		b0 RX0
		b1 RX1
		b2 RX2
		b3 RX3
TX_BPM_ PHASE_ERROR_ THRESH	2	The deviation of the TX output phase difference between the two BPM settings from the ideal $180°$ is compared against the threshold given here. The comparison result is part of the monitoring report message (Error bit is set if the measurement is higher than this threshold, with the units of both quantities being the same). 1 LSB = $360°/2^{16}$. Valid range: corresponding to $0°$ to $20°$.
TX_BPM_AMPLI-TUDE_ERROR_ THRESH	2	The deviation of the TX output amplitude difference between the two BPM settings is compared against the threshold given here. The comparison result is part of the monitoring report message (Error bit is set if the measurement is higher than this threshold, with the units of both quantities being the same). 1 LSB = 0.1 dB Valid range: 0 to 60 (0 to 6dB)
PH_SHIFTER_ THRESH_MAX	2	Maximum threshold for the difference in the 2 configured phase shift values 1 LSB = $5.625°$
PH_SHIFTER_ THRESH_MIN	2	Minimum threshold for the difference in the 2 configured phase shift values 1 LSB = $5.625°$
RESERVED	2	0x0000

7.9.3 Sub block 0x01D0 – AWR_MONITOR_TX2_BPM_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX2 BPM monitoring. The report is sent as an async event AWR_MONITOR_TX2_BPM_REPORT_AE_SB.

Table 7.17: AWR_MONITOR_TX2_BPM_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01D0
SBLKLEN	2	Value = 20
PROFILE_INDX	1	This field indicates the Profile Index for which this monitoring configuration applies.
PH_SHIFTER_MON_CFG	1	Bit Definition b7 Phase shifter monitoring enabled b6 Phase shifter monitoring increment enabled b5:0 Phase shifter monitoring increment value 1 LSB = $5.625°$
PH_SHIFTER_MON1	1	Phase1 of the phase shifter of TX2 which needs to be monitored 1 LSB = $5.625°$
PH_SHIFTER_MON2	1	Phase2 of the phase shifter of TX2 which needs to be monitored 1 LSB = $5.625°$
REPORTING_MODE	1	Value Definition 0 Report is sent every monitoring period without threshold check 1 Report is send only upon a failure (after checking for thresholds) 2 Report is sent every monitoring period with threshold check
RX_EN	1	This field indicates the RX channels that should be enabled for TX to RX loopback measurement. Setting the corresponding bit to 1 enables that channel for imbalance measurement. Bit number RX Channel b0 RX0 b1 RX1 b2 RX2 b3 RX3

Continued on next page

Table 7.17 – continued from previous page

TX_BPM_PHASE_ERROR_THRESH	2	The deviation of the TX output phase difference between the two BPM settings from the ideal 180° is compared against the threshold given here. The comparison result is part of the monitoring report message (Error bit is set if the measurement is higher than this threshold, with the units of both quantities being the same). 1 LSB = $360°/2^{16}$. Valid range: corresponding to 0° to 20°.
TX_BPM_AMPLI-TUDE_ERROR_THRESH	2	The deviation of the TX output amplitude difference between the two BPM settings is compared against the threshold given here. The comparison result is part of the monitoring report message (Error bit is set if the measurement is higher than this threshold, with the units of both quantities being the same). 1 LSB = 0.1 dB Valid range: 0 to 60 (0 to 6dB)
PH_SHIFTER_THRESH_MAX	2	Maximum threshold for the difference in the 2 configured phase shift values 1 LSB = 5.625°
PH_SHIFTER_THRESH_MIN	2	Minimum threshold for the difference in the 2 configured phase shift values 1 LSB = 5.625°
RESERVED	2	0x0000

7.10 Synthesizer Frequency Monitoring

This section contains API SBs that configure the monitors of synthesizer chirp frequency, and report the soft results from the monitor. The corresponding monitor is named SYNTH_FREQ_MONITOR.

7.10.1 Sub block 0x01D1 – AWR_MONITOR_SYNTHESIZER_FREQUENCY_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to synthesizer frequency monitoring during chirping. The report is sent as an async event AWR_MONITOR_SYNTH_FREQUENCY_REPORT_AE_SB.

Table 7.18: AWR_MONITOR_SYNTHESIZER_FREQUENCY_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01D1
SBLKLEN	2	Value = 16
PROFILE_INDX	1	This field indicates the Profile Index for which this monitoring configuration applies.
REPORTING_MODE	1	Value Definition 0 Report is sent every monitoring period without threshold check 1 Report is send only upon a failure (after checking for thresholds) 2 Report is sent every monitoring period with threshold check
FREQ_ERROR_THRESH	2	During the chirp, the error of the measured instantaneous chirp frequency w.r.t. the desired value is continuously compared against this threshold. The comparison result is part of the monitoring report message (Error bit is set if the measurement is above this threshold, ever during the previous monitoring period). 1 LSB = 10 kHz Valid range: 0 to 10000
MONITOR_START_TIME	1	This field determines when the monitoring starts in each chirp relative to the start of the ramp. 1 LSB = 0.2 μs, unsigned number Valid range: 0 to 25 μs
RESERVED	3	0x000000
RESERVED	4	0x00000000

7.11 External Analog Signals Monitor

This section contains API SBs that configure the monitors of external analog signals which are input to the device through pins ANALOGTEST1-4, ANAMUX and VSENSE (also called ADC1-6) and report the soft results from the monitor. The corresponding monitors are collectively named EXTERNAL_ANALOG_SIGNALS_MONITOR. These monitors observe various analog signals input on the pins ADC1-6 using a GPADC and compare them against internally fixed thresholds.

7.11.1 Sub block 0x01D2 – AWR_MONITORING_EXTERNAL_ANALOG_SIGNALS_ CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to external DC signals monitoring (available only in xWR1642 or xWR1843). The report is sent as an async event AWR_MONITOR_EXTERNAL_ANALOG_SIGNALSREPORT_ AE_SB.
Table 7.19 describes the content of this sub block.

Table 7.19: AWR_MONITOR_EXTERNAL_ANALOG_SIGNALS_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01D2
SBLKLEN	2	Value = 36
REPORTING_ MODE	1	Value Definition 0 Report is sent every monitoring period without threshold check 1 Report is send only upon a failure (after checking for thresholds) 2 Report is sent every monitoring period with threshold check
RESERVED	1	0x00
SIGNAL_INPUT_ ENABLES	1	This field indicates the sets of externally fed DC signals which are to be monitored using GPADC. When each bit in this field is set, the corresponding signal is monitored. The monitored signals are compared against programmed limits. The comparison result is part of the monitoring report message. Bit Location SIGNAL b0 ANALOGTEST1 b1 ANALOGTEST2 b2 ANALOGTEST3 b3 ANALOGTEST4 b4 ANAMUX b5 VSENSE Others RESERVED

Table 7.19 – continued from previous page

SIGNAL_BUFFER_EN-ABLES	1	This field indicates the sets of externally fed DC signals which are to be buffered before being fed to the GPADC. When each bit in this field is set, the corresponding signal is buffered before the GPADC. The monitored signals are compared against programmed limits. The comparison result is part of the monitoring report message.
		Bit SIGNAL
		b0 ANALOGTEST1
		b1 ANALOGTEST2
		b2 ANALOGTEST3
		b3 ANALOGTEST4
		b4 ANAMUX
		Others RESERVED
SIGNAL_SET-TLING_TIME	6	After connecting an external signal to the GPADC, the amount of time to wait for it to settle before taking GPADC samples is programmed in this field. For each signal, after that settling time, GPADC measurements take place for 6.4 μs (averaging 4 samples of the GPADC output). The byte locations of the settling times for each signal are tabulated here:
		Byte Location SIGNAL
		0 ANALOGTEST1
		1 ANALOGTEST2
		2 ANALOGTEST3
		3 ANALOGTEST4
		4 ANAMUX
		5 VSENSE
		1 LSB = 0.8 μs
		Valid range: 0 to 12 μs
		Valid programming condition: all the signals that are enabled should take a total of < 100 μs, including the programmed settling times and a fixed 6.4 μs of measurement time per enabled signal.

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Table 7.19 – continued from previous page

SIGNAL_THRESH	12	The external DC signals measured on GPADC are compared against these minimum and maximum thresholds. The comparison result is part of the monitoring report message (Error bit is set if any measurement is outside this (minimum, maximum) range).
		Byte Location Threshold SIGNAL
		0 Minimum ANALOGTEST1
		1 Minimum ANALOGTEST2
		2 Minimum ANALOGTEST3
		3 Minimum ANALOGTEST4
		4 Minimum ANAMUX
		5 Minimum VSENSE
		6 Maximum ANALOGTEST1
		7 Maximum ANALOGTEST2
		8 Maximum ANALOGTEST3
		9 Maximum ANALOGTEST4
		10 Maximum ANAMUX
		11 Maximum VSENSE
		1 LSB = 1.8V/256
		Valid range: 0 to 255
RESERVED	2	0x0000
RESERVED	4	0x00000000
RESERVED	4	0x00000000

7.12 Internal Analog Signals Monitor

This section contains API SBs that configure the monitors of internal analog signals in the RF analog modules and report the soft results from the monitor. The corresponding monitors are collectively named INTERNAL_ANALOG_SIGNALS_MONITOR. These monitors observe various analog nodes in the RF and analog modules using a GPADC and compare them against internally fixed thresholds.

The configuration API SBs are organized to address various analog circuits as follows:

1. TX0 Internal Analog Signals Monitoring

    a. This monitor is called INTERNAL_TX0_SIGNALS_MONITOR.

    b. Signal sets that are monitored: (SUPPLY_TX, PWRDET_TX)

2. TX1 Internal Analog Signals Monitoring

a. This monitor is called INTERNAL_TX1_SIGNALS_MONITOR

b. Signal sets that are monitored: (SUPPLY_TX, PWRDET_TX)

3. TX2 Internal Analog Signals Monitoring

a. This monitor is called INTERNAL_TX2_SIGNALS_MONITOR

b. Signal sets that are monitored: (SUPPLY_TX, PWRDET_TX)

4. RX Internal Analog Signals Monitoring

a. This monitor is called INTERNAL_RX_SIGNALS_MONITOR

b. Signal sets that are monitored: (SUPPLY_RX, PWRDET_RX, DCBIAS_RX)

5. PM CLK LO Internal Analog Signals Monitoring

a. This monitor is called INTERNAL_PMCLKLO_SIGNALS_MONITOR

b. Signal sets that are monitored: (SUPPLY_PMCLKLO, PWRDET_PMCLKLO, DCBIAS_PMCLKLO)

6. GPADC Internal Analog Signals Monitoring

a. This monitor is called INTERNAL_GPADC_SIGNALS_MONITOR

b. Signal sets that are monitored: (GPADC_REF1, GPADC_REF2)

The results are reported in the corresponding REPORT API SBs in this section.

7.12.1 Sub block 0x01D3 – AWR_MONITOR_TX0_INTERNAL_ANALOG_SIGNALS_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX0 Internal Analog Signals monitoring. The report is sent as an async event AWR_MONITOR_TX0_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB.

Table 7.20: AWR_MONITOR_TX0_INTERNAL_ANALOG_SIGNALS_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01D3
SBLKLEN	2	Value = 12
PROFILE_INDEX	1	The RF analog settings corresponding to this profile are used for monitoring the enabled signals, using test chirps (static frequency, at the center of the profile's RF frequency band).

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Table 7.20 – continued from previous page

REPORTING_MODE	1	Value	Definition
		0	RESERVED
		1	Report is send only upon a failure (after checking for thresholds)
		2	Report is sent every monitoring period with threshold check
RESERVED	2	0x0000	
RESERVED	4	0x00000000	

7.12.2 Sub block 0x01D4 – AWR_MONITOR_TX1_INTERNAL_ANALOG_SIGNALS_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX1 Internal Analog Signals monitoring. The report is sent as an async event AWR_MONITOR_TX1_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB.

Table 7.21: AWR_MONITOR_TX1_INTERNAL_ANALOG_SIGNALS_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01D4
SBLKLEN	2	Value = 12
PROFILE_INDEX	1	The RF analog settings corresponding to this profile are used for monitoring the enabled signals, using test chirps (static frequency, at the center of the profile's RF frequency band).
REPORTING_MODE	1	Value Definition
		0 RESERVED
		1 Report is send only upon a failure (after checking for thresholds)
		2 Report is sent every monitoring period with threshold check
RESERVED	2	0x0000
RESERVED	4	0x00000000

7.12.3 Sub block 0x01D5 – AWR_MONITOR_TX2_INTERNAL_ANALOG_SIGNALS_ CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to TX2 Internal Analog Signals monitoring. The report is sent as an async event AWR_MONITOR_TX2_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB.

Table 7.22: AWR_MONITOR_TX2_INTERNAL_ANALOG_SIGNALS_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01D5
SBLKLEN	2	Value = 12
PROFILE_INDEX	1	The RF analog settings corresponding to this profile are used for monitoring the enabled signals, using test chirps (static frequency, at the center of the profile's RF frequency band).
REPORTING_ MODE	1	Value Definition 0 RESERVED 1 Report is send only upon a failure (after checking for thresholds) 2 Report is sent every monitoring period with threshold check
RESERVED	2	0x0000
RESERVED	4	0x00000000

7.12.4 Sub block 0x01D6 – AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_ CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to RX Internal Analog Signals monitoring. The report is sent as an async event AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB.

Table 7.23: AWR_MONITOR_RX_INTERNAL_ANALOG_SIGNALS_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01D6
SBLKLEN	2	Value = 12

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Table 7.23 – continued from previous page

PROFILE_INDEX	1	The RF analog settings corresponding to this profile are used for monitoring the enabled signals, using test chirps (static frequency, at the center of the profile's RF frequency band).	
REPORTING_ MODE	1	Value	Definition
		0	RESERVED
		1	Report is send only upon a failure (after checking for thresholds)
		2	Report is sent every monitoring period with threshold check
RESERVED	2	0x0000	
RESERVED	4	0x00000000	

7.12.5 Sub block 0x01D7 – AWR_MONITOR_PMCLKLO_INTERNAL_ANALOG_SIGNALS_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to Power Management, Clock generation and LO distribution circuits' Internal Analog Signals monitoring. The report is sent as an async event AWR_MONITOR_PMCLKLO_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB.

Table 7.24: AWR_MONITOR_PMCLKLO_INTERNAL_ANALOG_SIGNALS_CONF_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x01D7	
SBLKLEN	2	Value = 12	
PROFILE_INDEX	1	The RF analog settings corresponding to this profile are used for monitoring the enabled signals, using test chirps (static frequency, at the center of the profile's RF frequency band).	
REPORTING_ MODE	1	Value	Definition
		0	RESERVED
		1	Report is send only upon a failure (after checking for thresholds)
		2	Report is sent every monitoring period with threshold check

Table 7.24 – continued from previous page

SYNC_20G_SIG_SEL	1	This field is relevant only in cascade configuration and not applicable in single chip case
		Value Definition
		0x00 20 GHz SYNC monitoring disabled
		0x01 SYNC_IN monitoring enabled
		0x02 SYNC_OUT monitoring enabled
		0x03 CLK_OUT monitoring enabled
SYNC_20G_MIN_THRESH	1	The minimum threshold value of monitoring, signed number Unit: 1 LSB = 1 dBm
SYNC_20G_MAX_THRESH	1	The maximum threshold value of monitoring, signed number Unit: 1 LSB = 1 dBm
RESERVED	3	0x000000

7.12.6 Sub block 0x01D8 – AWR_MONITOR_GPADC_INTERNAL_ANALOG_SIGNALS_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to GPADC Internal Analog Signals monitoring. During this monitor, only the relevant circuits are ensured to be ON. The monitored signals are compared against internally chosen valid limits. The comparison result is part of the consolidated monitoring report message (Error bit for any signal set is set to 1 if any measurement in that signal set is beyond valid limits). The report is sent as an async event AWR_MONITOR_GPADC_INTERNAL_ANALOG_SIGNALS_REPORT_AE_SB.

Table 7.25: AWR_MONITOR_GPADC_INTERNAL_ANALOG_SIGNALS_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01D8
SBLKLEN	2	Value = 12
REPORTING_MODE	1	Value Definition
		0 Report is sent every monitoring period without threshold check
		1 Report is send only upon a failure (after checking for thresholds)
		2 Report is sent every monitoring period with threshold check

RESERVED	3	0x000000
RESERVED	4	0x00000000

7.13 PLL Control Voltage Monitor

This section contains API SBs that configure the monitors of APLL and Synthesizer VCO control voltages and report the soft results from the monitor. The corresponding monitors are collectively named PLL_CONTROL_VOLTAGE_MONITOR. These monitors observe the VCO control voltages under various conditions using the GPADC and compare them against internally fixed thresholds. The transmitters are kept in OFF state during these measurements to avoid external emission.

7.13.1 Sub block 0x01D9 – AWR_MONITOR_PLL_CONTROL_VOLTAGE_SIGNALS_ CONF_SB

This is a monitoring configuration API which the host sends to the AWR device, containing information related to APLL and Synthesizer's control voltage signals monitoring. The report is sent as an async event AWR_MONITOR_PLL_CONTROL_VOLTAGE_REPORT_AE_SB.

Table 7.26: AWR_MONITOR_PLL_CONTROL_VOLTAGE_CONF_SB contents

Field Name	Number of bytes	Description	
SBLKID	2	Value = 0x01D9	
SBLKLEN	2	Value = 12	
REPORTING_ MODE	1	Value	Definition
		0	Report is sent every monitoring period without threshold check
		1	Report is send only upon a failure (after checking for thresholds)
		2	Report is sent every monitoring period with threshold check
RESERVED	1	0x00	

Continued on next page

Table 7.26 – continued from previous page

SIGNAL_EN-ABLES	2	This field indicates the sets of signals which are to be monitored. When each bit in this field is set, the corresponding signal set is monitored using test chirps. Rest of the RF analog may not be ON during these test chirps. The APLL VCO control voltage can be monitored. The Synthesizer VCO control voltage for both VCO1 and VCO2 can be monitored, while operating at their respective minimum and maximum frequencies, and their respective VCO slope (Hz/V) can be monitored if both frequencies are enabled for that VCO. The monitored signals are compared against internally chosen valid limits. The comparison results are part of the monitoring report message. Bit Location SIGNAL b0 APLL_VCTRL b1 SYNTH_VCO1_VCTRL b2 SYNTH_VCO2_VCTRL b15:3 RESERVED The synthesizer VCO extreme frequencies are: Synthesizer VCO Frequency Limits (Min, Max) VCO1 (76GHz, 78GHz) VCO2 (77GHz, 81GHz) Synthesizer measurements are done with TX switched off to avoid emissions. For the failure reporting, the internally chosen valid limits are (tentative): for the measured control voltage levels: 0.15V to 1.25V; for the synthesizer VCO slope: $\pm$20% of 1.1 GHz/V for VCO2 and 0.55GHz/V for VCO1.
RESERVED	4	0x00000000

7.14 Dual Clock Comparator Based Clock Frequency Monitor

This section contains API SBs that configure the Dual Clock Comparator based monitors of clocks in the BSS digital modules and report the soft results from the monitor. The corresponding monitors are collectively named DCC_CLOCK_FREQ_MONITOR. These monitors observe the relative frequency of various clock pairs and compare the measured relative frequency errors against internally fixed thresholds.

The various clock pairs that are monitored are defined here:

CLOCK PAIR	REFERENCE CLOCK	MEASURED CLOCK	ERROR THRESH-OLD (Tentative)
0	XTAL	BSS_600M	±0.25%
1	BSS_600M	BSS_200M	±0.25%
2	BSS_600M	BSS_100M	±0.25%
3	BSS_600M	GPADC_10M	±2.5%
4	BSS_600M	RCOSC_10M	±17.5%
5	BSS_600M	RAMPGEN_100M	±0.25%
RSVD	RSVD	RSVD	RSVD

The ideal frequencies of clocks involved in this monitor are given here:

Table 7.27: DCC Clock monitor pairs

CLOCK NAME	CLOCK FRE-QUENCY (MHz)	COMMENTS
XTAL	40	Crystal clock
BSS_600M	600	BSS root clock
BSS_200M	200	BSS processor clock
BSS_100M	100	BSS internal clock
GPADC_10M	10	GPADC clock used in monitoring and calibrations
RCOSC_10M	10 (±10%)	RC Oscillator clock
RAMPGEN_100M	100	Clock for Ramp Generator (timing engine) and Digital Front End.

7.14.1 Sub block 0x01DA – AWR_MONITOR_DUAL_CLOCK_COMP_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to the DCC based clock frequency monitoring. The report is sent as an async event AWR_MONITOR_DCC_DUAL_CLOCK_COMP_REPORT_AE_SB.

Table 7.28: AWR_MONITOR_DUAL_CLOCK_COMP_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01DA

Table 7.28 – continued from previous page

SBLKLEN	2	Value = 12
REPORTING_MODE	1	Value Definition
		0 Report is sent every monitoring period without threshold check
		1 Report is send only upon a failure (after checking for thresholds)
		2 Report is sent every monitoring period with threshold check
RESERVED	1	0x00
DCC_PAIR_EN-ABLES	2	This field indicates which pairs of clocks to monitor. When a bit in the field is set to 1, the firmware monitors the corresponding clock pair by deploying the hardware's Dual Clock Comparator in the corresponding DCC mode.
		Bit CLOCK PAIR
		b0 0
		b1 1
		b2 2
		b3 3
		b4 4
		b5 5
		b15:6 RESERVED
		The comparison results are part of the monitoring report message. The definition of the clock pairs and their error thresholds for failure reporting are given in the table below the message definition.
RESERVED	4	0x00000000

7.15 RX Saturation Detection Monitor

This section contains API SBs that configure the monitoring of RX analog saturation detectors, and report the results from the monitor. The corresponding monitors are collectively named RX_SATURATION_DETECTOR_MONITOR and RX_SIG_IMG_BAND_MONITOR. The report is available in CQ RAM.

7.15.1 Sub block 0x01DB – AWR_MONITOR_RX_SATURATION_DETECTOR_CONF_SB

This API is a monitoring configuration API which the host sends to the xWR device, containing information related to RX saturation detector monitoring. The report is available as CQ2 (part

of CQ) in CQ RAM every chirp. The application should transfer the report from CQ RAM every chirp.

Table 7.29: AWR_MONITOR_RX_SATURATION_DETECTOR_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01DB
SBLKLEN	2	Value = 24
PROFILE_INDX	1	This field indicates the profile index for which this monitoring configuration applies.
SAT_MON_SELECT	1	01 – Enable only the ADC saturation monitor 11 – Enable both the ADC and IFA1 saturation monitors
RESERVED	1	0x00
RESERVED	1	0x00
SAT_MON_PRIMARY_TIME_SLICE_DURATION	2	It specifies the duration of each (primary) time slice. 1 LSB = 0.16 μs. Valid range: 4 to floor(ADC sampling time us/0.16 μs) **NOTES:** The minimum allowed duration of each (primary) time slice is 4 LSBs = 0.64 μs. Also, the maximum number of (primary) time slices that will be monitored in a chirp is 64 so the recommendation is to set this value to correspond to (ADC sampling time / 64). If the slice is smaller, such that the ADC sampling time is longer than 64 primary slices, some regions of the valid duration of a chirp may go un-monitored.
SAT_MON_NUM_SLICES	2	Number of (primary + secondary) time slices to monitor. Valid range: 1 to 127 **NOTE:** Together with SAT_MON_PRIMARY_TIME_SLICE_DURATION, this determines the full duration of the ADC valid time that gets covered by the monitor
SAT_MON_RX_CHANNEL_MASK	1	Masks RX channels used for monitoring. In every slice, saturation counts for all unmasked channels are added together, and the total is capped to 127. The 8 bits are mapped (MSB->LSB) to: [RX3Q, RX2Q, RX1Q, RX0Q, RX3I, RX2I, RX1I, RX0I] 00000000 – All channels unmasked 11111111 – All channels masked
RESERVED	1	0
RESERVED	1	0
RESERVED	1	0

Table 7.29 – continued from previous page

RESERVED	4	0x00000000
RESERVED	4	0x00000000

7.15.2 Sub block 0x01DC – AWR_MONITOR_SIG_IMG_MONITOR_CONF_SB

This API is a monitoring configuration API which the host sends to the xWR device, containing information related to signal and image band energy. The report is available as CQ1 (part of CQ) in CQ RAM. The application should transfer the report every chirp.

Table 7.30: AWR_MONITOR_RX_SIG_IMG_MONITOR_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01DC
SBLKLEN	2	Value = 16
PROFILE_INDX	1	This field indicates the profile index for which this monitoring configuration applies.
SIG_IMG_MON_NUM_SLICES	1	Number of (primary + secondary) slices to monitor Valid range: 1 to 127
NUM_SAMPLES_PER_PRIMARY_TIME_SLICE	2	This field specifies the number of samples constituting each time slice. The minimum allowed value for this parameter is 4. Valid range: 4 to NUM_ADC_SAMPLES (see NOTE2 below) **NOTE1:** The maximum number of (primary) time slices that will be monitored in a chirp is 64, so our recommendation is that this value should at least equal (NUM_ADC_SAMPLES / 64). If the slice is smaller, such that the number of ADC samples per chirp is larger than 64 primary slices, some regions of the valid duration of a chirp may go un-monitored. **NOTE2:** In Complex1x mode, the minimum number of samples per slice is 4 and for other modes it is 8. Also note that number of samples should be an even number
RESERVED	4	0x00000000
RESERVED	4	0x00000000

7.16 RX mixer input power monitor

7.16.1 Sub block 0x01DD – AWR_MONITOR_RX_MIXER_IN_POWER_CONF_SB

This API is a monitoring configuration API which the host sends to the AWR device, containing information related to RX mixer input power monitoring. The report is sent as an async event AWR_MONITOR_RX_MIXER_IN_POWER_REPORT_AE_SB.

Table 7.31: AWR_MONITOR_MIXER_IN_POWER_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01DD
SBLKLEN	2	Value = 16
PROFILE_INDEX	1	The RF analog settings corresponding to this profile are used for monitoring RX mixer input power using test chirps (static frequency, at the center of the profile's RF frequency band).
REPORTING_MODE	1	Value Definition 0 Report is sent every monitoring period without threshold check 1 Report is send only upon a failure (after checking for thresholds) 2 Report is sent every monitoring period with threshold check
TX_EN	1	This field indicates if and which TX channels should be enabled while measuring RX mixer input power. Setting a bit to 1 enables the corresponding TX channel. Enabling a TX channel may help find reflection power while disabling may help find interference power. Bit number TX Channel b0 TX0 b1 TX1 b2 TX2
RESERVED	1	0x00

Continued on next page

Table 7.31 – continued from previous page

THRESHOLDS	2	The measured RX mixer input voltage swings during this monitoring is compared against the minimum and maximum thresholds configured in this field. The comparison result is part of the monitoring report message (Status bit is cleared if any measurement is outside this (minimum, maximum) range). Byte number Threshold 0 Minimum Threshold 1 Maximum Threshold Only the RX channels enabled in the static configuration APIs are monitored. 1 LSB = 1800 mV/256, unsigned number Valid range: 0 to 255, maximum threshold $\geq$ minimum threshold
RESERVED	2	0x00000000
RESERVED	4	0x00000000

7.17 Sub block 0x01DE – RESERVED

7.18 Analog Fault injection

7.18.1 Sub block 0x01DF – AWR_ANALOG_FAULT_INJECTION_CONF_SB

This API is a fault injection API which the host sends to the AWR device. It can be used to inject faults in the analog circuits to test the corresponding monitors. After the faults are injected, the regular monitors, when enabled will indicate the faults in their associated reports.

NOTE1:	This API should be issued when no frames are on-going.
NOTE2:	The fault injection should be tested by injecting one fault at a time.

Table 7.32: AWR_ANALOG_FAULT_INJECTION_CONF_SB contents

Field Name	Number of bytes	Description
SBLKID	2	Value = 0x01DF
SBLKLEN	2	Value = 24
RESERVED	1	0x00

Table 7.32 – continued from previous page

| RX_GAIN_DROP | 1 | Primary Fault: RX Gain
This field indicates which RX RF sections should have fault injected. If the fault is enabled, the RX RF gain drops significantly. The fault can be used to cause significant gain change, inter-RX gain imbalance and an uncontrolled amount of inter-RX phase imbalance.

Bit number   RX Channel
b0   RX0
b1   RX1
b2   RX2
b3   RX3
Others   RESERVED

For each bit, 1 = inject fault, 0 = remove injected fault |
| RX_PHASE_INV | 1 | Primary Fault: RX Phase
This field indicates which RX channels should have fault injected. If the fault is enabled, the RX phase gets inverted. The fault can be used to cause a controlled amount (180o) of inter-RX phase imbalance.

Bit number   RX Channel
b0   RX0
b1   RX1
b2   RX2
b3   RX3
Others   RESERVED

For each bit, 1 = inject fault, 0 = remove injected fault |

Table 7.32 – continued from previous page

RX_HIGH_NOISE	1	Primary Fault: RX Noise This field indicates which RX channels should have fault injected. If the fault is enabled, the RX IFA square wave loopback paths are engaged to inject high noise at RX IFA input. The fault can be used to cause significant RX noise floor elevation. Bit number RX Channel b0 RX0 b1 RX1 b2 RX2 b3 RX3 Others RESERVED For each bit, 1 = inject fault, 0 = remove injected fault
RX_IF_STAGES_ FAULT	1	Primary Fault: Cutoff frequencies of RX IFA HPF & LPF, IFA Gain. This field indicates which RX channels should have fault injected. If the fault is enabled, the RX IFA HPF cutoff frequency becomes very high (about 15MHz). The fault can be used to cause the measured inband IFA gain, HPF and LPF attenuations to vary from ideal expectations. Bit number RX Channel b0 RX0 b1 RX1 b2 RX2 b3 RX3 Others RESERVED For each bit, 1 = inject fault, 0 = remove injected fault **NOTE:** During the execution of RX_IFSTAGE_MONITOR, the RX_HIGH_NOISE faults are temporarily removed.

RX_LO_AMP_FAULT	1	Primary Fault: RX Mixer LO input swing reduction
		This field indicates which RX channels should have fault injected. If the fault is enabled, the RX mixer LO input swing is significantly reduced. The fault is primarily expected to be detected by RX_INTERNAL_ANALOG_SIGNALS_MONITOR (under PWRDET_RX category).
		Bit number RX Channel
		b0 RX0
		b1 RX1
		b2 RX2
		b3 RX3
		Others RESERVED
		For each bit, 1 = inject fault, 0 = remove injected fault
TX_LO_AMP_FAULT	1	Primary Fault: TX PA input signal generator turning off. This field indicates which TX channels should have fault injected. If the fault is enabled, the amplifier generating TX power amplifier's LO input signal is turned off. The fault is primarily expected to be detected by TX$<$n$>$_INTERNAL_ANALOG_SIGNALS_MONITOR (under DCBIAS category).
		Bit number Channel
		b0 TX0 and TX1
		b1 TX2 (applicable only if available in the device)
		Others RESERVED
		For each bit, 1 = inject fault, 0 = remove injected fault

Table 7.32 – continued from previous page

TX_GAIN_DROP	1	Primary Fault: TX Gain (power) This field indicates which TX RF sections should have fault injected. If the fault is enabled, the TX RF gain drops significantly. The fault can be used to cause significant TX output power change, inter-TX gain imbalance and an uncontrolled amount of inter-TX phase imbalance. Bit number Channel b0 TX0 b1 TX1 b2 TX2 Others RESERVED For each bit, 1 = inject fault, 0 = remove injected fault
TX_PHASE_INV	1	Primary Fault: TX Phase This field indicates if TX channels should have fault injected, along with some further programmability. If the fault is enabled, the TX BPM polarity (phase) is forced to a constant value as programmed. The fault can be used to cause a controlled amount (180 degree) of inter-TX phase imbalance as well as BPM functionality failure. Bit number TX Channel b0 TX_FAULT (Common for all TX channels) b1 RESERVED b2 RESERVED b3 TX0_BPM_VALUE b4 TX1_BPM_VALUE b5 TX2_BPM_VALUE Others RESERVED For each TXn_BPM_VALUE: Applicable only if TX_FAULT is enabled. Value = 0: force TX\<n\> BPM polarity to 0 Value = 1: force TX\<n\> BPM polarity to 1. **NOTE:** The TXn_BPM_VALUE takes effect only when TX_FAULT value is changed

Table 7.32 – continued from previous page

SYNTH_FAULT	1	Primary Fault: Synthesizer Frequency
		This field indicates which Synthesizer faults should be injected.
		SYNTH_VCO_OPENLOOP: If the fault is enabled, the synthesizer is forced in open loop mode with the VCO control voltage forced to a constant. In order to avoid out of band emissions in this faulty state, this fault is injected just before the PLL_CONTROL_VOLTAGE_MONITOR is executed and released just after its completion.
		SYNTH_FREQ_MON_OFFSET: If the fault is enabled, the synthesizer frequency monitor's ideal frequency ramp waveform is forced to be offset from the actual ramp waveform by a constant, causing monitoring to detect failures.
		Bit number Enable Fault
		b0 SYNTH_VCO_OPENLOOP
		b1 SYNTH_FREQ_MON_OFFSET
		Others RESERVED
		For each bit, 1 = inject fault, 0 = remove injected fault
SUPPLY_LDO_FAULT	1	This field indicates whether some LDO output voltage faults should be injected or not.
		Bit number Enable Fault
		b0 SUPPLY_LDO_RX_LODIST_FAULT
		Others RESERVED
		SUPPLY_LDO_RX_LODIST_FAULT: if enabled, the RX LO distribution sub system's LDO output voltage is slightly changed compared to normal levels to cause INTERNAL_PMCLKLO_SIGNALS_MONITOR to detect failure (under SUPPLY category).
		For each bit, 1 = inject fault, 0 = remove injected fault
		NOTE: This fault injection is ineffective under LDO bypass condition.

Table 7.32 – continued from previous page

MISC_FAULT	1	This field indicates whether a few miscellaneous faults should be injected or not. Bit number Enable Fault b0 GPADC_CLK_FREQ_FAULT Others RESERVED GPADC_CLK_FREQ_FAULT: if enabled, the GPADC clock frequency is slightly increased compared to normal usage to cause BSS DCC_CLOCK_FREQ_MONITOR to detect failure. For each bit, 1 = inject fault, 0 = remove injected fault
MISC_THRESH_FAULT	1	This field indicates whether faults should be forced in the threshold comparisons in the software layer of some monitors. If a fault is enabled, the logic in the min-max threshold comparisons used for failure detection is inverted, causing a fault to be reported. During these faults, no hardware fault condition is injected in the device. Bit number Enable Fault b0 GPADC_INTERNAL_SIGNALS_MONI-TOR Others RESERVED For each bit, 1 = inject fault, 0 = remove injected fault
RESERVED	3	0x000000
RESERVED	4	0x00000000

8 Chirp Parameters (CP) and Chirp Quality (CQ) data

8.1 Chirp Parameters data

Chirp parameter information is always updated in the CP registers DSS_REG_VBUSM__CPREG[0-3] for single chirp use case.

NOTE:	Chirp Number is always reset every burst by the hardware.

Figure 8.1: Chirp parameter information fields

	31	23	16 15	8 7	0
DSS_REG_VBUSM. CH0CPREG0	Byte 3	Byte 2	Byte 1	Byte 0	
DSS_REG_VBUSM. CH0CPREG1	Byte 7	Byte 6	Byte 5	Byte 4	
DSS_REG_VBUSM. CH0CPREG2	Byte 11	Byte 10	Byte 9	Byte 8	
DSS_REG_VBUSM. CH0CPREG3	Byte 15	Byte 14	Byte 13	Byte 12	

Figure 8.2: Chirp parameter information from DSS registers

For multichip use case, the CP data is available for up to 8 chirps in DSS_REG_VBUSM.CH[0-7]CPREG[0-3].

8.2 Chirp Quality data

Chirp quality information is divided into 3 parts

1. CQ0 – Wideband signal and image energy information (Reserved for future use)

2. CQ1 – RX signal and image band energy statistics

3. CQ2 – RX ADC and IF saturation information

CQ data will be available in CQ RAM which is a ping-pong memory when the CQ monitors are enabled. Currently supported CQ monitors are AWR_MONITOR_RX_SATURATION_DETECTOR_CONF_SB for CQ2 and AWR_MONITOR_SIG_IMG_MONITOR_CONF_SB for CQ1. CQ data will be refreshed every chirp by the hardware. User has to ensure that before the next chirp finishes, the current chirps' CQ data is either processed or transferred to a local memory for further processing.

> **NOTE:** CQ0 is not supported by firmware currently, but the CQ RAM will be updated for CQ0 data. Maximum size of CQ0 data is 256 bytes. Users should ignore the CQ RAM for CQ0.

The starting location (on 128 bit boundary) of each CQ data within the CQ memory can be configured by programming DSS_REG.CQCFG1[12:4] for CQ0, DSS_REG.CQCFG1[21:13] for CQ1 and DSS_REG.CQCFG1[30:22] for CQ2.
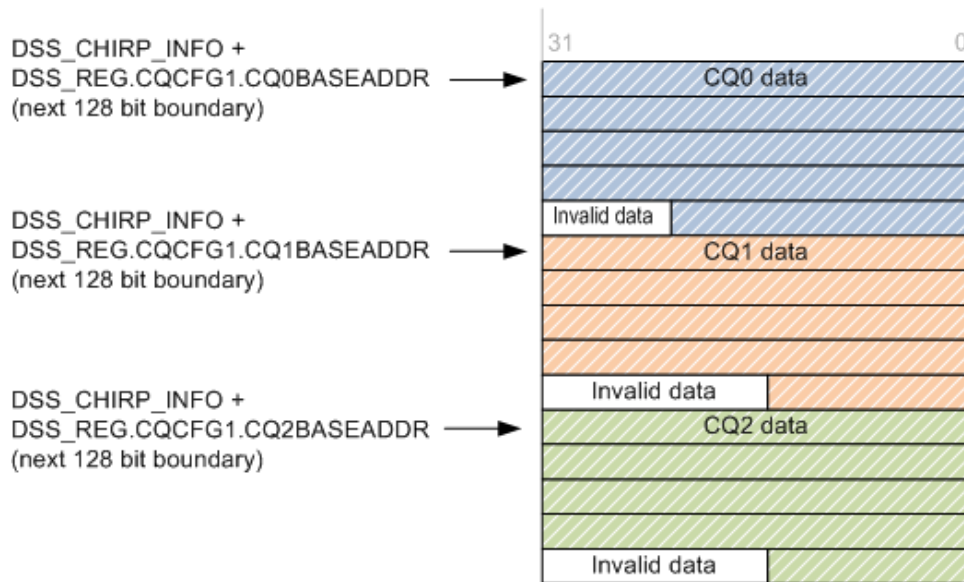
Figure 8.3: CQ data start address configuration in single chirp use case

For N-chirp use case, when user wishes to process N chirps simultaneously, then CQ0 for all N chirps will be concatenated together in memory. Similarly CQ1 and CQ2 for all N chirps will also be concatenated together.

> **NOTE:** When CQ data is concatenated in N-chirp use case, the CQ data for new chirp starts on the next 128 bit boundary.
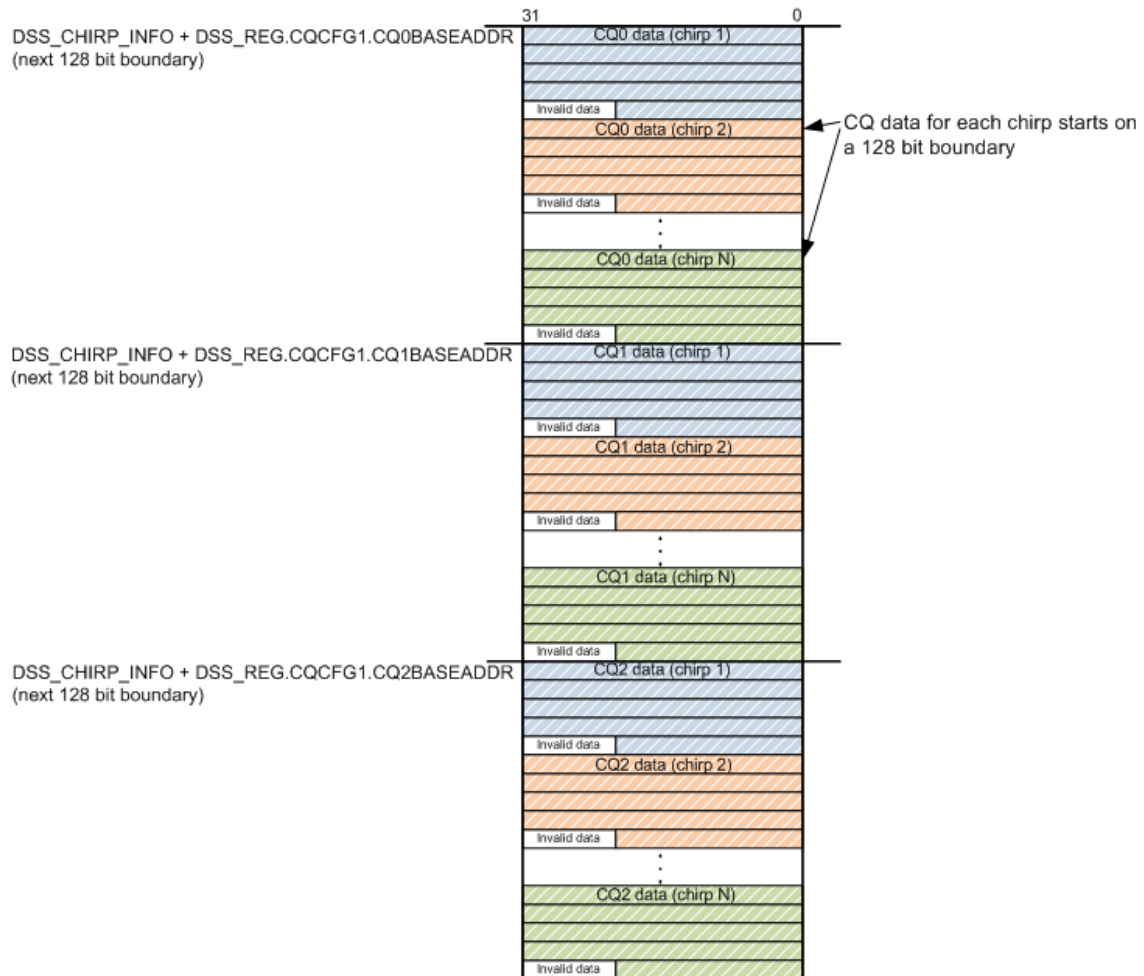
Figure 8.4: CQ data start address configuration in multi chirp use case

The CQDATAWIDTH parameter in DSS_REG.CQCFG1 defines the packing of the CQ data in the CQ memory in either 16-bit mode, 12-bit mode or in 14-bit mode.

8.2.1 CQ1

The signal band and image band are separated using a two-channel filter bank and the ADC sampling time duration is monitored in terms of primary and secondary time slices, as shown below.
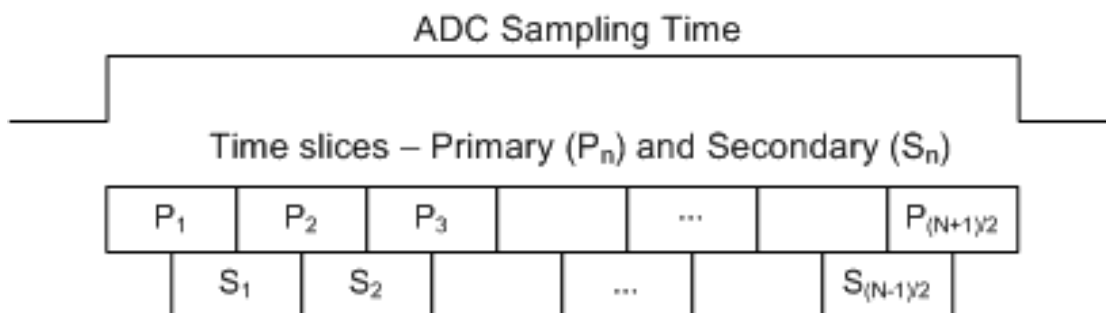
Figure 8.5: Time slices during RX signal and image band monitor and saturation monitor

For each of the two bands (signal and image), for each time slice, the input-referred average power in the slice in negative dBm is recorded as an 8-bit unsigned number, with 1 LSB = -0.5 dBm

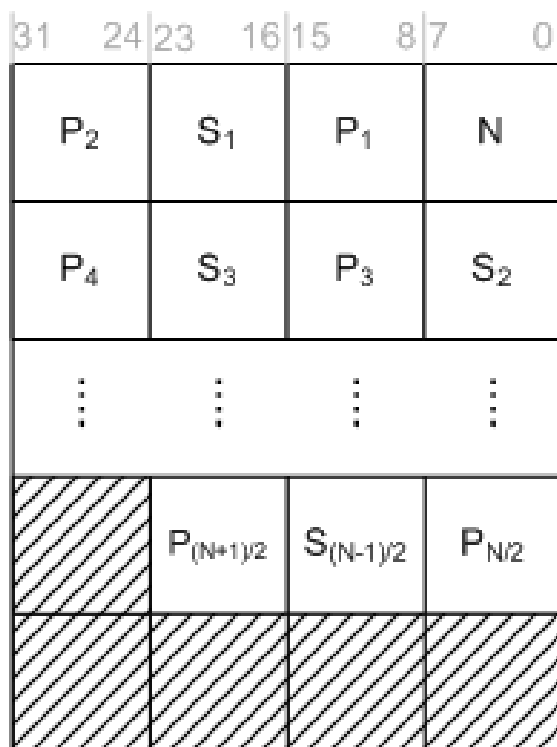CQ1 data is stored in memory as shown below (in 16-bit mode)
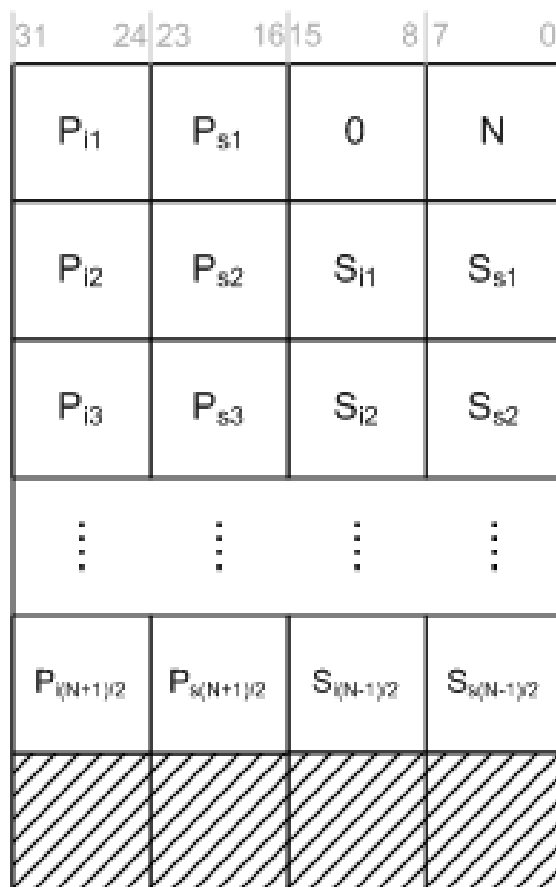
Figure 8.6: CQ1 data format in memory in 16-bit mode

N indicates the total number of primary and secondary slices which are monitored (maximum value of N is 127). P_{s,i_n} indicates the power of primary slice n for {signal, image} band and S_{s,i_n} indicates the power of secondary slice n for {signal, image} band. Each power is encoded in 8 bit unsigned number with each LSB representing -0.5 dBm.

Since maximum value of N is 127, the maximum size of CQ1 data in 16-bit mode is 256 bytes

> **NOTE:** In real output mode, since there is no image band visibility, only the signal band statistics will be meaningful.

Similarly, in 12-bit and 14-bit modes, the CQ1 data in CQ memory will be packed as shown below. Only the relevant bits in each 16 bits of memory (either 12 bits or 14 bits) are useful and other bits and not written by hardware.
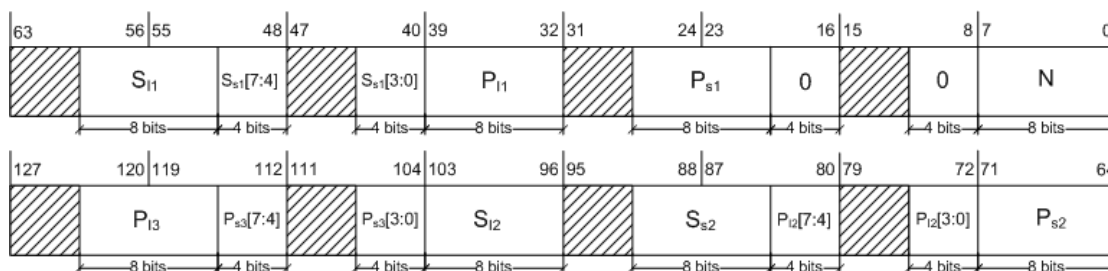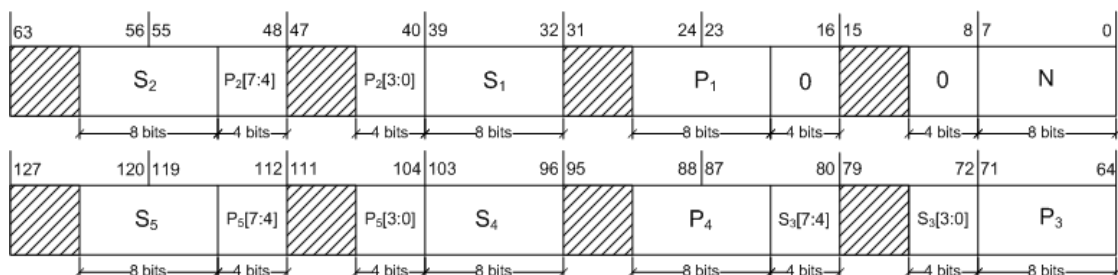
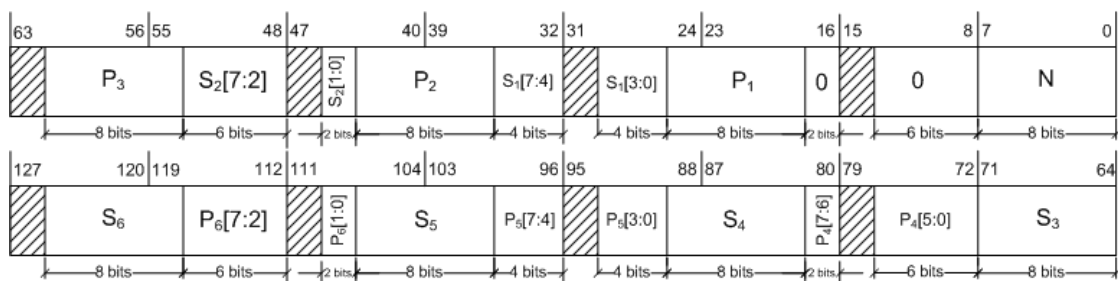**Figure 8.7:** CQ1 data format in memory in 12-bit mode
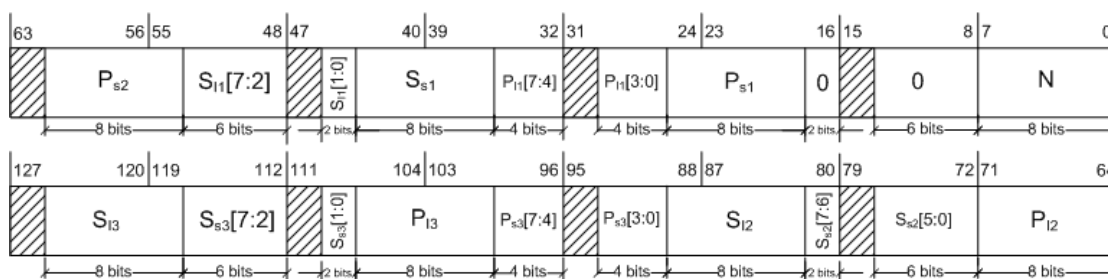
Figure 8.8: CQ1 data format in memory in 14-bit mode

8.2.2 CQ2

The analog to digital interface includes a 100 MHz bit stream indicating saturation events in the ADC/IF sections, for each channel. This one-bit indicator for each channel is monitored during the ADC sampling time duration in a time-sliced manner, as shown in Figure 8.5.

For each time slice, a saturation event count is recorded. This count is the sum of saturation event counts across all RX channels selected for monitoring, capped to a maximum count of 255 (8 bits). The saturation counts are stored in memory as shown below

Figure 8.9: CQ2 data format in memory in 16-bit mode

N indicates the total number of primary and secondary slices which are monitored (maximum value of N is 127). P_n indicates the accumulated saturation count for all enabled RX channels in primary slice n, S_n indicates the accumulated saturation count for all enabled RX channels in secondary slice n.

Since maximum value of N is 127, the maximum size of CQ2 data in 16-bit mode is 128 bytes.

Similarly, in 12-bit and 14-bit modes, the CQ2 data in CQ memory will be packed as shown below. Only the relevant bits in each 16 bits of memory (either 12 bits or 14 bits) are useful and other bits and not written by hardware.

Figure 8.10: CQ2 data format in memory in 12-bit mode

Figure 8.11: CQ2 data format in memory in 14-bit mode

9 Calibration and monitoring durations

9.1 Boot time calibration durations

Table 9.1: Duration of boot time calibrations

Sl. No.	Calibration	Duration (μs)
1	APLL	330
2	Synth VCO	1300
3	LO DIST	12
4	ADC DC	600
5	HPF cutoff	3500
6	LPF cut off	3200
7	Peak detector	4200
8	TX power (assumes 2 TX use-case)	6000
9	RX gain	2300
10	TX phase	40 000
11	RX IQMM	32 000

9.2 Run time calibration durations

Table 9.2 lists the duration of all run time calibrations. Note that the firmware performs calibrations in small chunks of 250 μs. User has to ensure that the total idle time in one CAL_MON_TIME_ UNIT is sufficient to fit the enabled calibrations.

To configure CALIB_MON_TIME_UNIT, user has to calculate the total available IDLE time in the frame and subtract 100 μs for every frame to allow for preparation of frame. The duration for all the enabled calibrations should be included and following software overheads should be added to that number

Table 9.2: Duration of run time calibrations

Sl. No.	Calibration	Duration (μs)
1	APLL	150
2	Synth VCO	350
3	LO DIST	30
4	Peak detector	500
5	TX power (assumes 1 TX, 1 profile)	800
6	RX gain	30
7	Application of calibration to hardware (This needs to be included always)	150

9.3 Monitoring duration

Table 9.3 lists the duration of all analog monitors and Table 9.4 lists the duration of all digital monitors

Table 9.3: Duration of analog monitors

Sl. No.	Monitors	Duration (μs)
1	RX gain phase (assumes 1 RF frequency)	1250
2	RX noise figure (assumes 1 RF frequency)	250
3	RX IF stage (assumes 1 RF frequency)	1000
4	TX power (assumes 1 TX, 1 RF frequency)	200
5	TX ballbreak (assumes 1 TX)	250
6	TX gain phase mismatch (assumes 1 TX, 1 RF frequency)	400
7	TX BPM (assumes 1 TX)	575
	- TX phase shifter (assumes 1 TX)	525
8	Synthesizer frequency	0
9	External analog signals (all 6 GPADC channels enabled)	150
10	TX Internal analog signals (assumes 1 TX)	200
11	RX internal analog signals	1700
12	PMCLKLO internal analog signals	400
13	GPADC internal signals	50
14	PLL control voltage	210
15	Dual clock comparator (assumes 6 clock comparators)	110
16	RX saturation detector	0
17	RX signal and image band monitor	0
18	RX mixer input power	350

Table 9.4: Duration of digital monitors

Sl. No.	Monitors	Duration (μs)
1	Periodic configuration register readback	100
2	ESM monitoring	50
3	DFE LBIST monitoring	1000
4	Frame timing monitoring	10

9.4 Software overheads

When the calibrations or monitorings are enabled, the software needs certain time for reading the temperature sensors, reading the DFE statistics, preparing the calibration or monitoring reports and to clear the watch dog. All these time durations should also be accounted when computing the CALIB_MON_TIME_UNIT. The details of the software overheards are given in the Table 9.5

Table 9.5: Software overheads every FTTI that should be accounted to program CALIB_MON_TIME_UNIT and CALIBRATION_PERIODICITY

Sl. No.	Software overhead	Duration (μs)
1	Periodic monitoring of stack usage	20
2	Minimum monitoring duration (report formation, digital energy monitor at the end of FTTI, temperature read every FTTI)	1000
3	Minimum calibration duration (report formation, temperature read every CAL_MON_TIME_UNIT)+	500
4	Idle time needed per FTTI for windowed watchdog	Frame period $\times$ CALIB_MON_TIME_UNIT/8 i.e.$\sim$12.5% of Frame period $\times$ CALIB_MON_TIME_UNIT is reserved for watchdog clearing time

9.4.1 Note on idle time for clearing the watchdog

The clearing window of the watch dog is 12.5% of total FTTI as shown in the figure below. One FTTI can have multiple frames in legacy frame configuration or in advanced frame configuration - each frame can have multiple sub-frames and each sub-frame can have multiple bursts.
The required idle time for clearing watch dog is absolute 12.5% of the overall FTTI interval, this 12.5% clearing window can have multiple frames or subframes or bursts. The granularity of the required watchdog idle time calculation is limited to sub-frame period.

Example

A user has enabled advanced frame configuration where each frame consists of 3 sub-frames and each sub-frame is of 5 ms duration. FTTI is configured as 25 frames. Each sub-frame contains 100 chirps, each chirp consisting of 4 μs idle time and 21 μs ramp time. i.e. duty cycle is 50%. The watchdog clearing window and time for calibration and monitoring is calculated as follows
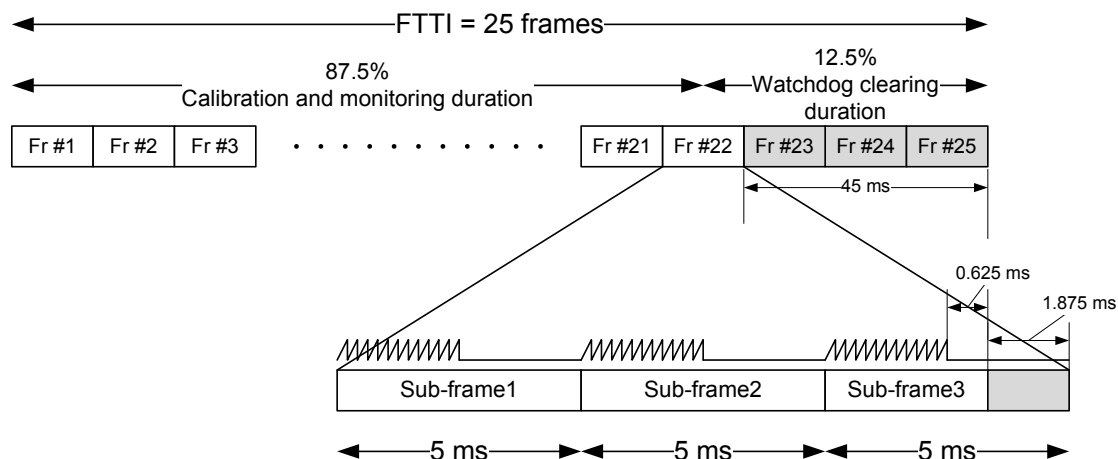
Figure 9.1: Watchdog idle time calculation

Frame duty cycle	=	50	%
Idle time per frame (50% of 15 ms)	=	7.5	ms
FTTI (15 ms $\times$ 25 frames)	=	375	ms
Available idle time per FTTI (50% of 375 ms)	=	187.5	ms
Ideal watchdog clearing window (12.5% of 375 ms)	=	46.875	ms

The calculated watchdog clearing window in firmware is as follows

$$\left. \begin{array}{l} \text{Duration of complete frames which can be fit in watchdog} \\ \text{clearing window} \left(\lceil 46.875/15 \rceil \times 15 \right) \end{array} \right\} = 45 \quad \text{ms}$$

$$\left. \begin{array}{l} \text{Fractional watchdog clearing time (which will be fit in the} \\ \text{sub-frame idle time) } \left(46.875 - (15 \times 3) \right) \end{array} \right\} = 1.875 \quad \text{ms}$$

$$\left. \begin{array}{l} \text{Time available for calibration/monitoring per FTTI ....} \\ \left(21 \text{ frames} \times 7.5 \text{ ms} \right) + \left(2 \text{ sub-frames} \times 2.5 \text{ ms} \right) + 0.625 \text{ ms} \end{array} \right\} = 163.125 \quad \text{ms}$$

The following examples show how the user can budget for calibration and monitoring time and configure the FTTI correctly.

Example 1

A user has enabled 2 TX, uses only 1 profile, frame configuration consists of 64 chirps, each chirp is of duration is 66 μs (56 μs ramp time and 10 μs chirp idle time) and frame periodicity is 10 ms. User has enabled all run time calibrations. None of the analog monitoring is enabled.

$$
\begin{array}{rcl}
\text{Frame duty cycle} & = & 42.24\% \\
\text{Idle time per frame (57.76\% of 10 ms)} & = & 5.776 \text{ ms} \\
\left.\begin{array}{r}\text{Idle time available for calibration/monitoring per frame} \\ (100 \ \mu\text{s is for frame preparation})\end{array}\right\} & = & 5.676 \text{ ms} \\
\left.\begin{array}{r}\text{Time needed for all run time calibrations.........} \\ 150 + 300 + 30 + 500 + (800 \times 2) + 30 + 150\end{array}\right\} & = & 2760 \ \mu\text{s} \\
\left.\begin{array}{r}\text{Minimum time for software overheads........} \\ 20 + 1000 + 500 + (10000 \times 1/8)\end{array}\right\} & = & 2770 \ \mu\text{s} \\
\left.\begin{array}{r}\text{Total time needed per frame for calibration} \\ 2760 \ \mu\text{s} + 2770 \ \mu\text{s}\end{array}\right\} & = & 5530 \ \mu\text{s}
\end{array}
$$

Total time needed per frame for calibration is 5.530 μs which is less than the frame idle time (5.676 ms) and hence this configuration will be honored by the MMIC device.

User can set CALIB_MON_TIME_UNIT to 1 and CALIBRATION_PERIODICITY as 100. With this setting calibrations are triggered once every 100 frames (i.e. once every 1 s)

Example 2

Consider another example where the frame configuration remains the same as in example 1, but frame periodicity is reduced to 8 ms.

Frame duty cycle	$=$	52.80%
Idle time per frame (47.20% of 8 ms)	$=$	3.776 ms
Idle time available for calibration/monitoring per frame $\left.\begin{array}{c} \\ \text{(100 } \mu\text{s is for frame preparation)} \end{array}\right\}$	$=$	3.676 ms
Time needed for all run time calibrations......... $\left.\begin{array}{c} \\ 150 + 300 + 30 + 500 + (800 \times 2) + 30 + 150 \end{array}\right\}$	$=$	2760 μs
Minimum time for software overheads........ $\left.\begin{array}{c} \\ 20 + 1000 + 500 + (8000 \times 1/8) \end{array}\right\}$	$=$	2520 μs
Total time needed per frame for calibration $\left.\begin{array}{c} \\ \text{2760 } \mu\text{s + 2520 } \mu\text{s} \end{array}\right\}$	$=$	5280 μs

Total time needed per frame for calibration is 5.280 μs which is more than the frame idle time (3.676 ms) and hence this configuration will **not** be honored by the MMIC device.

User can set CALIB_MON_TIME_UNIT to 2 and CALIBRATION_PERIODICITY as 63. With this setting calibrations are triggered once every 126 frames (i.e. once every 1.008 s)

Example 3

A user has enabled 2 TX, uses 2 profiles, frame configuration consists of 32 chirps, each chirp is of duration is 90 μs (80 μs ramp time and 10 μs chirp idle time) and frame periodicity is 6 ms. User has enabled all run time calibrations. None of the analog monitoring is enabled.

Frame duty cycle	=	48.00%
Idle time per frame (52.00% of 6 ms)	=	3.120 ms
Idle time available for calibration/monitoring per frame (100 μs is for frame preparation)	=	3.020 ms
Time needed for all run time calibrations............. $150 + 300 + 30 + 500 + (800 \times 2 \times 2) + 30 + 150$	=	4360 μs
Minimum time for software overheads........ $20 + 1000 + 500 + (6000 \times 1/8)$	=	2270 μs
Total time needed per frame for calibration 4360 μs + 2270 μs	=	6630 μs

Total time needed per frame for calibration is 6.630 μs which is more than the frame idle time (3.020 ms) and hence this configuration will **not** be honored by the MMIC device.

User can set CALIB_MON_TIME_UNIT to 3 and CALIBRATION_PERIODICITY as 56. With this setting, minimum required time is 8.13 ms and available idle time for calibration/monitoring is 9.06 ms and calibrations are triggered once every 168 frames (i.e. once every 1.008 s)

Example 4

A user has enabled 2 TX, uses 2 profiles, frame configuration consists of 32 chirps, each chirp is of duration is 90 μs (80 μs ramp time and 10 μs chirp idle time) and frame periodicity is 6 ms. User has enabled all run time calibrations. Analog monitorings which are enabled are (a) TX output power monitor for TX0 and TX1 (b) TX BPM monitor for TX0 and TX1 (c) RX gain phase monitor and (d) RX noise figure monitor. Each of the monitors are configured to be run for 1 profile and 3 RF frequencies (low, mid and high) as defined by the profile.

Frame duty cycle	$=$	48.00%
Idle time per frame (52.00% of 6 ms)	$=$	3.120 ms
Idle time available for calibration/monitoring per frame (100 μs is for frame preparation)	$=$	3.020 ms
Time needed for all run time calibrations............. $150 + 300 + 30 + 500 + (800 \times 2 \times 2) + 30 + 150$	$=$	4360 μs
Time needed for all monitoring.................................... $(1250 \times 3) + (250 \times 3) + (200 \times 3 \times 2) + (575 \times 2)$	$=$	6850 μs
Minimum time for software overheads........ $20 + 1000 + 500 + (6000 \times 1/8)$	$=$	2270 μs
Total time needed per frame for calibration and monitoring 4360 μs + 6850 μs + 2270 μs	$=$	13480 μs

Total time needed per frame for calibration is 13.480 μs which is more than the frame idle time (3.020 ms) and hence this configuration will **not** be honored by the MMIC device.

User can set CALIB_MON_TIME_UNIT to 6 and CALIBRATION_PERIODICITY as 28. With this setting, minimum required time for calibration and monitoring is 16.48 ms and available idle time for calibration/monitoring is 18.72 ms. Monitoring is triggered once in 6 frames and calibration is triggered once in 168 frames (i.e. once every 1.008 s)

9.5 Sample Application

For sample application please refer DFP (device firmware package) user guide document.