Section 6.5

Least Squares Problems

We now are in a position to solve the motivating problem of this third part of the course:

We now are in a position to solve the motivating problem of this third part of the course:

Problem

Suppose that Ax = b does not have a solution. What is the best possible approximate solution?

We now are in a position to solve the motivating problem of this third part of the course:

Problem

Suppose that Ax = b does not have a solution. What is the best possible approximate solution?

To say Ax = b does not have a solution means that b is not in Col A.

We now are in a position to solve the motivating problem of this third part of the course:

Problem

Suppose that Ax = b does not have a solution. What is the best possible approximate solution?

To say Ax = b does not have a solution means that b is not in Col A.

The closest possible \hat{b} for which $Ax = \hat{b}$ does have a solution is

We now are in a position to solve the motivating problem of this third part of the course:

Problem

Suppose that Ax = b does not have a solution. What is the best possible approximate solution?

To say Ax = b does not have a solution means that b is not in Col A.

The closest possible \hat{b} for which $Ax = \hat{b}$ does have a solution is $\hat{b} = \text{proj}_{Col A}(b)$.

We now are in a position to solve the motivating problem of this third part of the course:

Problem

Suppose that Ax = b does not have a solution. What is the best possible approximate solution?

To say Ax = b does not have a solution means that b is not in Col A.

The closest possible \hat{b} for which $Ax = \hat{b}$ does have a solution is $\hat{b} = \text{proj}_{Col A}(b)$.

Then $A\widehat{x} = \widehat{b}$ is a consistent equation.

We now are in a position to solve the motivating problem of this third part of the course:

Problem

Suppose that Ax = b does not have a solution. What is the best possible approximate solution?

To say Ax = b does not have a solution means that b is not in Col A.

The closest possible \widehat{b} for which $Ax = \widehat{b}$ does have a solution is $\widehat{b} = \operatorname{proj}_{\operatorname{Col} A}(b)$.

Then $A\widehat{x} = \widehat{b}$ is a consistent equation.

A solution \hat{x} to $A\hat{x} = \hat{b}$ is a least squares solution.

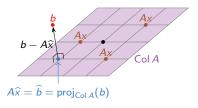
Let A be an $m \times n$ matrix.

Definition

A least squares solution to Ax = b is a vector \hat{x} in \mathbb{R}^n such that

$$||b - A\widehat{x}|| \le ||b - Ax||$$

for all x in \mathbb{R}^n .



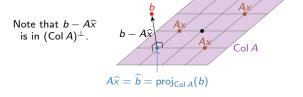
Let A be an $m \times n$ matrix.

Definition

A **least squares solution** to Ax = b is a vector \hat{x} in \mathbb{R}^n such that

$$||b - A\widehat{x}|| \le ||b - Ax||$$

for all x in \mathbb{R}^n .



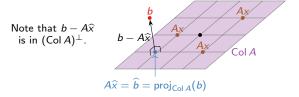
Let A be an $m \times n$ matrix.

Definition

A **least squares solution** to Ax = b is a vector \hat{x} in \mathbb{R}^n such that

$$||b - A\widehat{x}|| \le ||b - Ax||$$

for all x in \mathbb{R}^n .



In other words, a least squares solution \hat{x} solves Ax = b as closely as possible.

Let A be an $m \times n$ matrix.

Definition

A **least squares solution** to Ax = b is a vector \hat{x} in \mathbb{R}^n such that

$$||b - A\widehat{x}|| \le ||b - Ax||$$

for all x in \mathbb{R}^n .

In other words, a least squares solution \hat{x} solves Ax = b as closely as possible.

Equivalently, a least squares solution to Ax = b is a vector \hat{x} in \mathbb{R}^n such that

$$A\widehat{x} = \widehat{b} = \operatorname{proj}_{\operatorname{Col} A}(b).$$

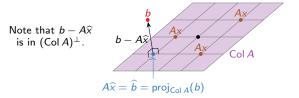
Let A be an $m \times n$ matrix.

Definition

A **least squares solution** to Ax = b is a vector \hat{x} in \mathbb{R}^n such that

$$||b - A\widehat{x}|| \le ||b - Ax||$$

for all x in \mathbb{R}^n .



In other words, a least squares solution \hat{x} solves Ax = b as closely as possible.

Equivalently, a least squares solution to Ax = b is a vector \hat{x} in \mathbb{R}^n such that

$$A\widehat{x} = \widehat{b} = \operatorname{proj}_{\operatorname{Col} A}(b).$$

This is because \hat{b} is the closest vector to b such that $A\hat{x} = \hat{b}$ is consistent.

Theorem

The least squares solutions to Ax = b are the solutions to $(A^TA)\hat{x} = A^Tb$.

Theorem

The least squares solutions to Ax = b are the solutions to $(A^TA)\hat{x} = A^Tb$.

This is just another Ax = b problem, but with a square matrix $A^T A!$

Theorem

The least squares solutions to Ax = b are the solutions to $(A^TA)\hat{x} = A^Tb$.

This is just another Ax = b problem, but with a *square* matrix $A^TA!$ Note we compute \widehat{x} directly, without computing \widehat{b} first.

Theorem

The least squares solutions to Ax = b are the solutions to $(A^T A)\hat{x} = A^T b$.

This is just another Ax = b problem, but with a *square* matrix $A^TA!$ Note we compute \widehat{x} directly, without computing \widehat{b} first.

Why is this true?

Theorem

The least squares solutions to Ax = b are the solutions to $(A^TA)\hat{x} = A^Tb$.

This is just another Ax = b problem, but with a *square* matrix $A^TA!$ Note we compute \widehat{x} directly, without computing \widehat{b} first.

Why is this true?

Alternative when A has orthogonal columns v_1, v_2, \ldots, v_n :

$$\widehat{b} = \operatorname{proj}_{\operatorname{Col} A}(b) = \sum_{i=1}^{n} \frac{b \cdot v_i}{v_i \cdot v_i} v_i$$

The right hand side equals $A\widehat{x}$, where $\widehat{x} = \left(\frac{b \cdot v_1}{v_1 \cdot v_1}, \frac{b \cdot v_2}{v_2 \cdot v_2}, \cdots, \frac{b \cdot v_n}{v_n \cdot v_n}\right)$.

Least Squares Solutions Example

Find the least squares solutions to Ax = b where:

$$A = \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{pmatrix} \qquad b = \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}.$$

Least Squares Solutions Example

Find the least squares solutions to Ax = b where:

$$A = \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{pmatrix} \qquad b = \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}.$$

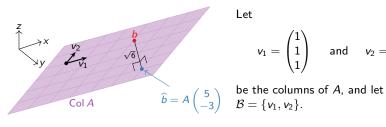
So the only least squares solution is $\hat{x} = \begin{pmatrix} 5 \\ -3 \end{pmatrix}$.

Least Squares Solutions Example, continued

How close did we get?

Example, continued

How close did we get?



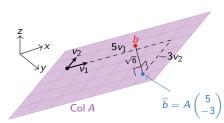
Let

$$v_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$
 and $v_2 = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$

$$\mathcal{B}=\{v_1,v_2\}$$

Example, continued

How close did we get?



Let

$$v_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$
 and $v_2 = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$

 $\widehat{b} = A \begin{pmatrix} 5 \\ -3 \end{pmatrix} \quad \text{be the columns of } A, \text{ and let} \\ \mathcal{B} = \{v_1, v_2\}.$

Note $\widehat{x} = {5 \choose -3}$ is just the \mathcal{B} -coordinates of \widehat{b} , in Col $A = \mathsf{Span}\{v_1, v_2\}$.

Least Squares Solutions Second example

Find the least squares solutions to Ax = b where:

$$A = \begin{pmatrix} 2 & 0 \\ -1 & 1 \\ 0 & 2 \end{pmatrix} \qquad b = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}.$$

Least Squares Solutions Second example

Find the least squares solutions to Ax = b where:

$$A = \begin{pmatrix} 2 & 0 \\ -1 & 1 \\ 0 & 2 \end{pmatrix} \qquad b = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}.$$

So the only least squares solution is $\hat{x} = \begin{pmatrix} 1/3 \\ -1/3 \end{pmatrix}$.

When does Ax = b have a *unique* least squares solution \hat{x} ?

When does Ax = b have a *unique* least squares solution \hat{x} ?

Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

When does Ax = b have a *unique* least squares solution \hat{x} ?

Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

1. Ax = b has a *unique* least squares solution for all b in \mathbb{R}^n .

When does Ax = b have a *unique* least squares solution \hat{x} ?

Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

- 1. Ax = b has a *unique* least squares solution for all b in \mathbb{R}^n .
- 2. The columns of A are linearly independent.

When does Ax = b have a *unique* least squares solution \hat{x} ?

Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

- 1. Ax = b has a *unique* least squares solution for all b in \mathbb{R}^n .
- 2. The columns of A are linearly independent.
- 3. $A^T A$ is invertible.

When does Ax = b have a *unique* least squares solution \hat{x} ?

Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

- 1. Ax = b has a *unique* least squares solution for all b in \mathbb{R}^n .
- 2. The columns of A are linearly independent.
- 3. $A^T A$ is invertible.

In this case, the least squares solution is $(A^TA)^{-1}(A^Tb)$.

When does Ax = b have a *unique* least squares solution \hat{x} ?

Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

- 1. Ax = b has a *unique* least squares solution for all b in \mathbb{R}^n .
- 2. The columns of A are linearly independent.
- 3. $A^T A$ is invertible.

In this case, the least squares solution is $(A^TA)^{-1}(A^Tb)$.

Why?

Uniqueness

When does Ax = b have a *unique* least squares solution \hat{x} ?

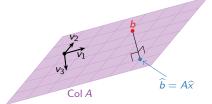
Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

- 1. Ax = b has a *unique* least squares solution for all b in \mathbb{R}^n .
- 2. The columns of A are linearly independent.
- 3. $A^T A$ is invertible.

In this case, the least squares solution is $(A^TA)^{-1}(A^Tb)$.

Why? If the columns of A are linearly dependent, then $A\widehat{x}=\widehat{b}$ has many solutions:



When does Ax = b have a *unique* least squares solution \hat{x} ?

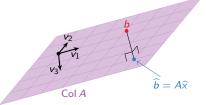
Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

- 1. Ax = b has a *unique* least squares solution for all b in \mathbb{R}^n .
- 2. The columns of A are linearly independent.
- 3. $A^T A$ is invertible.

In this case, the least squares solution is $(A^TA)^{-1}(A^Tb)$.

Why? If the columns of A are linearly dependent, then $A\widehat{x} = \widehat{b}$ has many solutions:

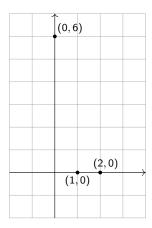


Note: A^TA is always a square matrix, but it need not be invertible.

Application

Data modeling: best fit line

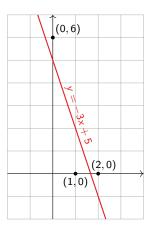
Find the best fit line through (0,6), (1,0), and (2,0).



Application

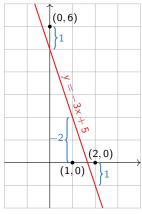
Data modeling: best fit line

Find the best fit line through (0,6), (1,0), and (2,0).



Data modeling: best fit line

Find the best fit line through (0,6), (1,0), and (2,0).



$$A \begin{pmatrix} 5 \\ -3 \end{pmatrix} - \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$$

Poll

What does the best fit line minimize?

- A. The sum of the squares of the distances from the data points to the line.
- B. The sum of the squares of the vertical distances from the data points to the line.
- C. The sum of the squares of the horizontal distances from the data points to the line.
- D. The maximal distance from the data points to the line.

Poll

What does the best fit line minimize?

- A. The sum of the squares of the distances from the data points to the line.
- B. The sum of the squares of the vertical distances from the data points to the line.
- C. The sum of the squares of the horizontal distances from the data points to the line.
- D. The maximal distance from the data points to the line.

Answer: B. See the picture on the previous slide.

Application Best fit ellipse

Find the best fit ellipse for the points (0,2), (2,1), (1,-1), (-1,-2), (-3,1).

Application Best fit ellipse

Find the best fit ellipse for the points (0,2), (2,1), (1,-1), (-1,-2), (-3,1).

The general equation for an ellipse is

$$x^2 + Ay^2 + Bxy + Cx + Dy + E = 0$$

Application Best fit ellipse

Find the best fit ellipse for the points (0,2), (2,1), (1,-1), (-1,-2), (-3,1).

The general equation for an ellipse is

$$x^2 + Ay^2 + Bxy + Cx + Dy + E = 0$$

So we want to solve:

Find the best fit ellipse for the points (0,2), (2,1), (1,-1), (-1,-2), (-3,1).

The general equation for an ellipse is

$$x^2 + Ay^2 + Bxy + Cx + Dy + E = 0$$

So we want to solve:

$$(0)^{2} + A(2)^{2} + B(0)(2) + C(0) + D(2) + E = 0$$

$$(2)^{2} + A(1)^{2} + B(2)(1) + C(2) + D(1) + E = 0$$

$$(1)^{2} + A(-1)^{2} + B(1)(-1) + C(1) + D(-1) + E = 0$$

$$(-1)^{2} + A(-2)^{2} + B(-1)(-2) + C(-1) + D(-2) + E = 0$$

$$(-3)^{2} + A(1)^{2} + B(-3)(1) + C(-3) + D(1) + E = 0$$

In matrix form:

$$\begin{pmatrix} 4 & 0 & 0 & 2 & 1 \\ 1 & 2 & 2 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 4 & 2 & -1 & -2 & 1 \\ 1 & -3 & -3 & 1 & 1 \end{pmatrix} \begin{pmatrix} A \\ B \\ C \\ D \\ E \end{pmatrix} = \begin{pmatrix} 0 \\ -4 \\ -1 \\ -1 \\ -9 \end{pmatrix}.$$

Best fit ellipse, continued

$$A = \begin{pmatrix} 4 & 0 & 0 & 2 & 1 \\ 1 & 2 & 2 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 4 & 2 & -1 & -2 & 1 \\ 1 & -3 & -3 & 1 & 1 \end{pmatrix} \qquad b = \begin{pmatrix} 0 \\ -4 \\ -1 \\ -1 \\ -9 \end{pmatrix}.$$

Best fit ellipse, continued

$$A = \begin{pmatrix} 4 & 0 & 0 & 2 & 1 \\ 1 & 2 & 2 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 4 & 2 & -1 & -2 & 1 \\ 1 & -3 & -3 & 1 & 1 \end{pmatrix} \qquad b = \begin{pmatrix} 0 \\ -4 \\ -1 \\ -1 \\ -9 \end{pmatrix}.$$

$$A^{T}A = \begin{pmatrix} 35 & 6 & -4 & 1 & 11 \\ 6 & 18 & 10 & -4 & 0 \\ -4 & 10 & 15 & 0 & -1 \\ 1 & -4 & 0 & 11 & 1 \\ 11 & 0 & -1 & 1 & 5 \end{pmatrix} \qquad A^{T}b = \begin{pmatrix} -18 \\ 18 \\ 19 \\ -10 \\ -15 \end{pmatrix}$$

Best fit ellipse, continued

$$A = \begin{pmatrix} 4 & 0 & 0 & 2 & 1 \\ 1 & 2 & 2 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 4 & 2 & -1 & -2 & 1 \\ 1 & -3 & -3 & 1 & 1 \end{pmatrix} \qquad b = \begin{pmatrix} 0 \\ -4 \\ -1 \\ -1 \\ -9 \end{pmatrix}.$$

$$A^{T}A = \begin{pmatrix} 35 & 6 & -4 & 1 & 11 \\ 6 & 18 & 10 & -4 & 0 \\ -4 & 10 & 15 & 0 & -1 \\ 1 & -4 & 0 & 11 & 1 \\ 11 & 0 & -1 & 1 & 5 \end{pmatrix} \qquad A^{T}b = \begin{pmatrix} -18 \\ 18 \\ 19 \\ -10 \\ -15 \end{pmatrix}.$$

Row reduce:

Best fit ellipse, continued

$$A = \begin{pmatrix} 4 & 0 & 0 & 2 & 1 \\ 1 & 2 & 2 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 4 & 2 & -1 & -2 & 1 \\ 1 & -3 & -3 & 1 & 1 \end{pmatrix} \qquad b = \begin{pmatrix} 0 \\ -4 \\ -1 \\ -1 \\ -9 \end{pmatrix}.$$

$$A^{T}A = \begin{pmatrix} 35 & 6 & -4 & 1 & 11 \\ 6 & 18 & 10 & -4 & 0 \\ -4 & 10 & 15 & 0 & -1 \\ 1 & -4 & 0 & 11 & 1 \\ 11 & 0 & -1 & 1 & 5 \end{pmatrix} \qquad A^{T}b = \begin{pmatrix} -18 \\ 18 \\ 19 \\ -10 \\ -15 \end{pmatrix}.$$

Row reduce:

Best fit ellipse:

$$x^{2} + \frac{16}{7}y^{2} - \frac{8}{7}xy + \frac{15}{7}x - \frac{6}{7}y - \frac{52}{7} = 0$$

Best fit ellipse, continued

$$A = \begin{pmatrix} 4 & 0 & 0 & 2 & 1 \\ 1 & 2 & 2 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 4 & 2 & -1 & -2 & 1 \\ 1 & -3 & -3 & 1 & 1 \end{pmatrix} \qquad b = \begin{pmatrix} 0 \\ -4 \\ -1 \\ -1 \\ -9 \end{pmatrix}.$$

$$A^{T}A = \begin{pmatrix} 35 & 6 & -4 & 1 & 11 \\ 6 & 18 & 10 & -4 & 0 \\ -4 & 10 & 15 & 0 & -1 \\ 1 & -4 & 0 & 11 & 1 \\ 11 & 0 & -1 & 1 & 5 \end{pmatrix} \qquad A^{T}b = \begin{pmatrix} -18 \\ 18 \\ 19 \\ -10 \\ -15 \end{pmatrix}.$$

Row reduce:

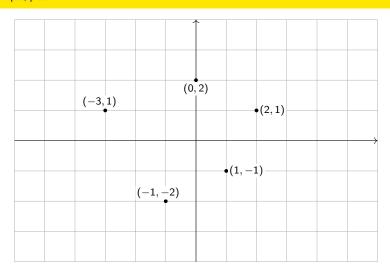
Best fit ellipse:

$$x^{2} + \frac{16}{7}y^{2} - \frac{8}{7}xy + \frac{15}{7}x - \frac{6}{7}y - \frac{52}{7} = 0$$

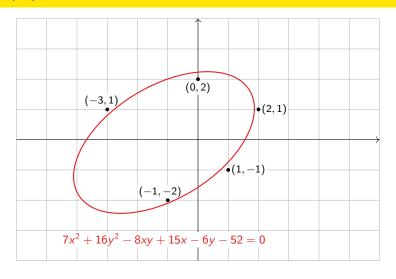
or

$$7x^2 + 16y^2 - 8xy + 15x - 6y - 52 = 0.$$

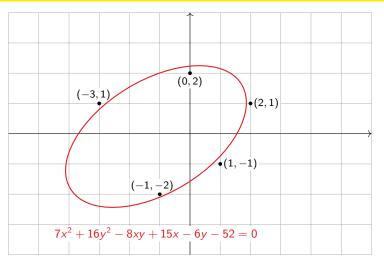
Application Best fit ellipse, picture



Application Best fit ellipse, picture



Application
Best fit ellipse, picture



Remark: Gauss invented the method of least squares to do exactly this: he predicted the (elliptical) orbit of the asteroid Ceres as it passed behind the sun in 1801.

Application Best fit parabola

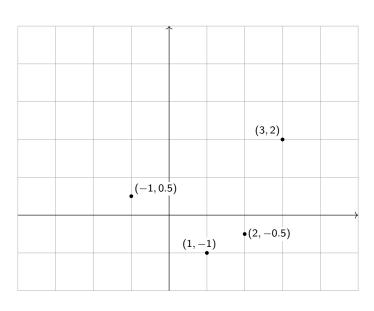
What least squares problem Ax = b finds the best parabola through the points (-1,0.5), (1,-1), (2,-0.5), (3,2)?

Application Best fit parabola

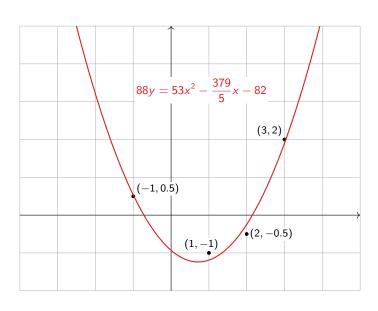
What least squares problem Ax = b finds the best parabola through the points (-1,0.5), (1,-1), (2,-0.5), (3,2)?

$$88y = 53x^2 - \frac{379}{5}x - 82$$

Application Best fit parabola, picture



Application Best fit parabola, picture



Application Best fit linear function

What least squares problem Ax = b finds the best linear function f(x, y) fitting the following data?

X	у	f(x,y)
1	0	0
0	1	1
-1	0	3
0	-1	4

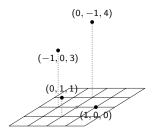
Best fit linear function

What least squares problem Ax = b finds the best linear function f(x, y) fitting the following data?

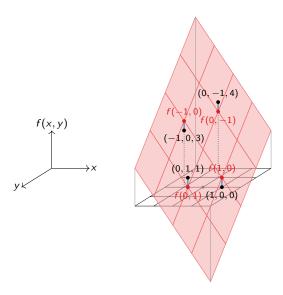
$$\begin{array}{c|ccccc} x & y & f(x,y) \\ \hline 1 & 0 & 0 \\ 0 & 1 & 1 \\ -1 & 0 & 3 \\ 0 & -1 & 4 \\ \hline \end{array}$$

Answer:
$$f(x,y) = -\frac{3}{2}x - \frac{3}{2}y + 2$$

Application Best fit linear function, picture



Best fit linear function, picture



Graph of $f(x,y) = -\frac{3}{2}x - \frac{3}{2}y + 2$