

Section 2.2

The Inverse of a Matrix

The Definition of Inverse

Recall: The multiplicative inverse (or reciprocal) of a nonzero number a is the number b such that $ab = 1$. We define the inverse of a matrix in almost the same way.

Definition

Let A be an $n \times n$ square matrix. We say A is **invertible** (or **nonsingular**) if there is a matrix B of the same size, such that

$$AB = I_n \quad \text{and} \quad BA = I_n.$$

identity matrix

$$\begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{pmatrix}$$

In this case, B is the **inverse** of A , and is written A^{-1} .

Example

$$A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \quad B = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix}.$$

I claim $B = A^{-1}$. Check:

$$AB = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$
$$BA = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$



The 2×2 case

Let $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. The **determinant** of A is the number

$$\det(A) = \det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc.$$

Facts:

1. If $\det(A) \neq 0$, then A is invertible and $A^{-1} = \frac{1}{\det(A)} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$.
2. If $\det(A) = 0$, then A is not invertible.

Why 1?

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} = \begin{pmatrix} ad - bc & 0 \\ 0 & ad - bc \end{pmatrix} = \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

So we get the identity by dividing by $ad - bc$.

Example

$$\det \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = 1 \cdot 4 - 2 \cdot 3 = -2 \quad \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}^{-1} = -\frac{1}{2} \begin{pmatrix} 4 & -2 \\ -3 & 1 \end{pmatrix}.$$

Solving Linear Systems via Inverses

Solving $Ax = b$ by "dividing by A "

Theorem

If A is invertible, then $Ax = b$ has exactly one solution for every b , namely:

$$x = A^{-1}b.$$

Why? Divide by A !

$$\begin{aligned} Ax = b &\rightsquigarrow A^{-1}(Ax) = A^{-1}b \rightsquigarrow (A^{-1}A)x = A^{-1}b \\ &\rightsquigarrow I_n x = A^{-1}b \rightsquigarrow x = A^{-1}b. \end{aligned}$$

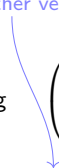
$I_n x = x$ for every x 

Example

Solve the system

$$\begin{array}{rcl} 2x + 3y + 2z & = & 1 \\ x & + & 3z = 1 \\ 2x + 2y + 3z & = & 1 \end{array}$$

using $\begin{pmatrix} 2 & 3 & 2 \\ 1 & 0 & 3 \\ 2 & 2 & 3 \end{pmatrix}^{-1} = \begin{pmatrix} -6 & -5 & 9 \\ 3 & 2 & -4 \\ 2 & 2 & -3 \end{pmatrix}.$

could be any other vector 

Answer: $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 & 3 & 2 \\ 1 & 0 & 3 \\ 2 & 2 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -6 & -5 & 9 \\ 3 & 2 & -4 \\ 2 & 2 & -3 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix}.$

Some Facts

Say A and B are invertible $n \times n$ matrices.

1. A^{-1} is invertible and its inverse is $(A^{-1})^{-1} = A$.
2. AB is invertible and its inverse is $(AB)^{-1} = \cancel{A^{-1}B^{-1}} B^{-1}A^{-1}$.

Why? $(B^{-1}A^{-1})AB = B^{-1}(A^{-1}A)B = B^{-1}I_nB = B^{-1}B = I_n$.

3. A^T is invertible and $(A^T)^{-1} = (A^{-1})^T$.

Why? $A^T(A^{-1})^T = (A^{-1}A)^T = I_n^T = I_n$.

Poll

If A, B, C are invertible $n \times n$ matrices, what is the inverse of ABC ?

- i. $A^{-1}B^{-1}C^{-1}$ ii. $B^{-1}A^{-1}C^{-1}$ iii. $C^{-1}B^{-1}A^{-1}$ iv. $C^{-1}A^{-1}B^{-1}$

It's (iii):

$$\begin{aligned}(ABC)(C^{-1}B^{-1}A^{-1}) &= AB(CC^{-1})B^{-1}A^{-1} = A(BB^{-1})A^{-1} \\ &= AA^{-1} = I_n.\end{aligned}$$

In general, a product of invertible matrices is invertible, and the inverse is the product of the inverses, in the *reverse order*.

Computing A^{-1}

Let A be an $n \times n$ matrix. Here's how to compute A^{-1} .

1. Row reduce the augmented matrix $(A \mid I_n)$.
2. If the result has the form $(I_n \mid B)$, then A is invertible and $B = A^{-1}$.
3. Otherwise, A is not invertible.

Example

$$A = \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & 2 \\ 0 & -3 & -4 \end{pmatrix}$$

Computing A^{-1}

Example

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 4 & 1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & -3 & -4 & 0 & 0 & 1 \end{array}\right) \quad \begin{array}{l} R_3 = R_3 + 3R_2 \\ \hline \end{array} \quad \left(\begin{array}{ccc|ccc} 1 & 0 & 4 & 1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & 0 & 2 & 0 & 3 & 1 \end{array}\right)$$

$$\begin{array}{l} R_1 = R_1 - 2R_3 \\ R_2 = R_2 - R_3 \\ \hline \end{array} \quad \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & -6 & -2 \\ 0 & 1 & 0 & 0 & -2 & -1 \\ 0 & 0 & 2 & 0 & 3 & 1 \end{array}\right)$$

$$\begin{array}{l} R_3 = R_3 \div 2 \\ \hline \end{array} \quad \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & -6 & -2 \\ 0 & 1 & 0 & 0 & -2 & -1 \\ 0 & 0 & 1 & 0 & 3/2 & 1/2 \end{array}\right)$$

$$\text{So } \left(\begin{array}{ccc} 1 & 0 & 4 \\ 0 & 1 & 2 \\ 0 & -3 & -4 \end{array}\right)^{-1} = \left(\begin{array}{ccc} 1 & -6 & -2 \\ 0 & -2 & -1 \\ 0 & 3/2 & 1/2 \end{array}\right).$$

$$\text{Check: } \left(\begin{array}{ccc} 1 & 0 & 4 \\ 0 & 1 & 2 \\ 0 & -3 & -4 \end{array}\right) \left(\begin{array}{ccc} 1 & -6 & -2 \\ 0 & -2 & -1 \\ 0 & 3/2 & 1/2 \end{array}\right) = \left(\begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array}\right)$$



Why Does This Work?

First answer: We can think of the algorithm as simultaneously solving the equations

$$Ax_1 = e_1 : \left(\begin{array}{ccc|ccc} 1 & 0 & 4 & 1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & -3 & -4 & 0 & 0 & 1 \end{array} \right)$$

$$Ax_2 = e_2 : \left(\begin{array}{ccc|ccc} 1 & 0 & 4 & 1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & -3 & -4 & 0 & 0 & 1 \end{array} \right)$$

$$Ax_3 = e_3 : \left(\begin{array}{ccc|ccc} 1 & 0 & 4 & 1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & -3 & -4 & 0 & 0 & 1 \end{array} \right)$$

Now note $A^{-1}e_i = A^{-1}(Ax_i) = x_i$, and x_i is the i th column in the augmented part. Also $A^{-1}e_i$ is the i th column of A^{-1} .

Second answer: Elementary matrices.

Elementary Matrices

Definition

An **elementary matrix** is a square matrix E which differs from I_n by one row operation.

There are three kinds, corresponding to the three elementary row operations:

scaling
($R_2 = 2R_2$)

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

row replacement
($R_2 = R_2 + 2R_1$)

$$\begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

swap
($R_1 \longleftrightarrow R_2$)

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Fact: if E is the elementary matrix for a row operation, then EA differs from A by the same row operation.

Example:

$$\begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & 2 \\ 0 & -3 & -4 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 4 \\ 2 & 1 & 10 \\ 0 & -3 & -4 \end{pmatrix}$$
$$\begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & 2 \\ 0 & -3 & -4 \end{pmatrix} \xrightarrow{R_2 = R_2 + 2R_1} \begin{pmatrix} 1 & 0 & 4 \\ 2 & 1 & 10 \\ 0 & -3 & -4 \end{pmatrix}$$

Elementary Matrices

Continued

Fact: if E is the elementary matrix for a row operation, then EA differs from A by the same row operation.

Consequence

Elementary matrices are invertible, and the inverse is the elementary matrix which un-does the row operation.

$$\begin{array}{cccc} R_2 = R_2 \times 2 & R_2 = R_2 \div 2 & R_2 = R_2 + 2R_1 & R_2 = R_2 - 2R_1 \\ \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}^{-1} & = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1 \end{pmatrix} & \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}^{-1} & = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \end{array}$$

$$\begin{array}{cc} R_1 \longleftrightarrow R_2 & R_1 \longleftrightarrow R_2 \\ \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}^{-1} & = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \end{array}$$

Why Does The Inversion Algorithm Work?

Second answer

Theorem

An $n \times n$ matrix A is invertible if and only if it is row equivalent to I_n . In this case, the sequence of row operations taking A to I_n also takes I_n to A^{-1} .

Why? Say the row operations taking A to I_n have elementary matrices E_1, E_2, \dots, E_k . So

$$\begin{aligned} \text{note the order!} \longrightarrow E_k E_{k-1} \cdots E_2 E_1 A &= I_n \\ \implies E_k E_{k-1} \cdots E_2 E_1 A A^{-1} &= A^{-1} \\ \implies E_k E_{k-1} \cdots E_2 E_1 I_n &= A^{-1}. \end{aligned}$$

This means if you do these same row operations to A and to I_n , you'll end up with I_n and A^{-1} . This is what you do when you row reduce the augmented matrix:

$$(A \mid I_n) \rightsquigarrow (I_n \mid A^{-1})$$