

## Section 2.8

Subspaces of  $\mathbf{R}^n$

# Motivation

Today we will discuss **subspaces** of  $\mathbf{R}^n$ .

# Motivation

Today we will discuss **subspaces** of  $\mathbf{R}^n$ .

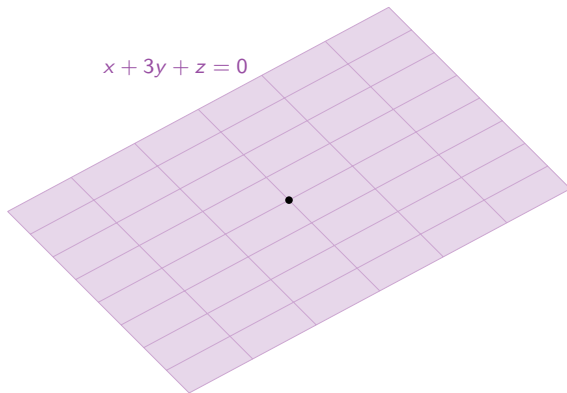
A subspace turns out to be the same as a span, except we don't know *which* vectors it's the span of.

# Motivation

Today we will discuss **subspaces** of  $\mathbf{R}^n$ .

A subspace turns out to be the same as a span, except we don't know *which* vectors it's the span of.

This arises naturally when you have, say, a plane through the origin in  $\mathbf{R}^3$  which is *not* defined (a priori) as a span, but you still want to say something about it.



# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ .

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ .

“not empty”

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ .
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ .

“not empty”

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ .
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ .

“not empty”

“closed under addition”



# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ .
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ .
3. If  $u$  is in  $V$  and  $c$  is in  $\mathbf{R}$ , then  $cu$  is in  $V$ .

“not empty”

“closed under addition”

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ .
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ .
3. If  $u$  is in  $V$  and  $c$  is in  $\mathbf{R}$ , then  $cu$  is in  $V$ .

“not empty”

“closed under addition”

“closed under  $\times$  scalars”

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ . "not empty"
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ . "closed under addition"
3. If  $u$  is in  $V$  and  $c$  is in  $\mathbf{R}$ , then  $cu$  is in  $V$ . "closed under  $\times$  scalars"

What does this mean?

- If  $v$  is in  $V$ , then all scalar multiples of  $v$  are in  $V$  by (3).

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ . "not empty"
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ . "closed under addition"
3. If  $u$  is in  $V$  and  $c$  is in  $\mathbf{R}$ , then  $cu$  is in  $V$ . "closed under  $\times$  scalars"

What does this mean?

- If  $v$  is in  $V$ , then all scalar multiples of  $v$  are in  $V$  by (3). That is, the line through  $v$  is in  $V$ .

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ . "not empty"
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ . "closed under addition"
3. If  $u$  is in  $V$  and  $c$  is in  $\mathbf{R}$ , then  $cu$  is in  $V$ . "closed under  $\times$  scalars"

What does this mean?

- ▶ If  $v$  is in  $V$ , then all scalar multiples of  $v$  are in  $V$  by (3). That is, the line through  $v$  is in  $V$ .
- ▶ If  $u, v$  are in  $V$ , then  $xu$  and  $yv$  are in  $V$  for scalars  $x, y$  by (3).

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ . "not empty"
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ . "closed under addition"
3. If  $u$  is in  $V$  and  $c$  is in  $\mathbf{R}$ , then  $cu$  is in  $V$ . "closed under  $\times$  scalars"

What does this mean?

- ▶ If  $v$  is in  $V$ , then all scalar multiples of  $v$  are in  $V$  by (3). That is, the line through  $v$  is in  $V$ .
- ▶ If  $u, v$  are in  $V$ , then  $xu$  and  $yv$  are in  $V$  for scalars  $x, y$  by (3). So  $xu + yv$  is in  $V$  by (2).

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ . "not empty"
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ . "closed under addition"
3. If  $u$  is in  $V$  and  $c$  is in  $\mathbf{R}$ , then  $cu$  is in  $V$ . "closed under  $\times$  scalars"

What does this mean?

- ▶ If  $v$  is in  $V$ , then all scalar multiples of  $v$  are in  $V$  by (3). That is, the line through  $v$  is in  $V$ .
- ▶ If  $u, v$  are in  $V$ , then  $xu$  and  $yv$  are in  $V$  for scalars  $x, y$  by (3). So  $xu + yv$  is in  $V$  by (2). So  $\text{Span}\{u, v\}$  is contained in  $V$ .

# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ . "not empty"
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ . "closed under addition"
3. If  $u$  is in  $V$  and  $c$  is in  $\mathbf{R}$ , then  $cu$  is in  $V$ . "closed under  $\times$  scalars"

What does this mean?

- ▶ If  $v$  is in  $V$ , then all scalar multiples of  $v$  are in  $V$  by (3). That is, the line through  $v$  is in  $V$ .
- ▶ If  $u, v$  are in  $V$ , then  $xu$  and  $yv$  are in  $V$  for scalars  $x, y$  by (3). So  $xu + yv$  is in  $V$  by (2). So  $\text{Span}\{u, v\}$  is contained in  $V$ .
- ▶ Likewise, if  $v_1, v_2, \dots, v_n$  are all in  $V$ , then  $\text{Span}\{v_1, v_2, \dots, v_n\}$  is contained in  $V$ .



# Definition of Subspace

## Definition

A **subspace** of  $\mathbf{R}^n$  is a subset  $V$  of  $\mathbf{R}^n$  satisfying:

1. The zero vector is in  $V$ . "not empty"
2. If  $u$  and  $v$  are in  $V$ , then  $u + v$  is also in  $V$ . "closed under addition"
3. If  $u$  is in  $V$  and  $c$  is in  $\mathbf{R}$ , then  $cu$  is in  $V$ . "closed under  $\times$  scalars"

What does this mean?

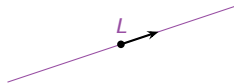
- ▶ If  $v$  is in  $V$ , then all scalar multiples of  $v$  are in  $V$  by (3). That is, the line through  $v$  is in  $V$ .
- ▶ If  $u, v$  are in  $V$ , then  $xu$  and  $yv$  are in  $V$  for scalars  $x, y$  by (3). So  $xu + yv$  is in  $V$  by (2). So  $\text{Span}\{u, v\}$  is contained in  $V$ .
- ▶ Likewise, if  $v_1, v_2, \dots, v_n$  are all in  $V$ , then  $\text{Span}\{v_1, v_2, \dots, v_n\}$  is contained in  $V$ .

A subspace  $V$  contains the span of any set of vectors in  $V$ .

# Examples

## Example

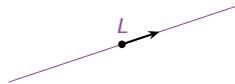
A line  $L$  through the origin: this contains the span of any vector in  $L$ .



# Examples

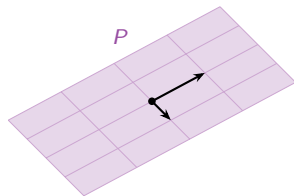
## Example

A line  $L$  through the origin: this contains the span of any vector in  $L$ .



## Example

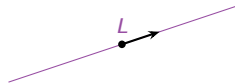
A plane  $P$  through the origin: this contains the span of any vectors in  $P$ .



# Examples

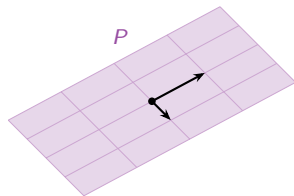
## Example

A line  $L$  through the origin: this contains the span of any vector in  $L$ .



## Example

A plane  $P$  through the origin: this contains the span of any vectors in  $P$ .



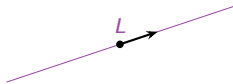
## Example

All of  $\mathbf{R}^n$ : this contains 0, and is closed under addition and scalar multiplication.

# Examples

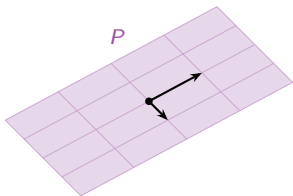
## Example

A line  $L$  through the origin: this contains the span of any vector in  $L$ .



## Example

A plane  $P$  through the origin: this contains the span of any vectors in  $P$ .



## Example

All of  $\mathbf{R}^n$ : this contains  $0$ , and is closed under addition and scalar multiplication.

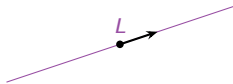
## Example

The subset  $\{0\}$ : this subspace contains only one vector.

# Examples

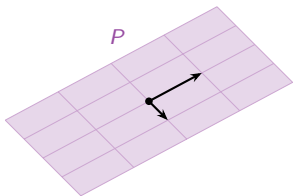
## Example

A line  $L$  through the origin: this contains the span of any vector in  $L$ .



## Example

A plane  $P$  through the origin: this contains the span of any vectors in  $P$ .



## Example

All of  $\mathbf{R}^n$ : this contains  $0$ , and is closed under addition and scalar multiplication.

## Example

The subset  $\{0\}$ : this subspace contains only one vector.

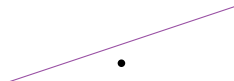
Note these are all pictures of spans! (Line, plane, space, etc.)

# Non-Examples

## Non-Example

A line  $L$  (or any other set) that doesn't contain the origin is not a subspace.

Fails:

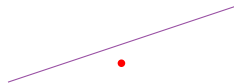


# Non-Examples

## Non-Example

A line  $L$  (or any other set) that doesn't contain the origin is not a subspace.

Fails: 1.



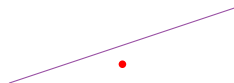


# Non-Examples

## Non-Example

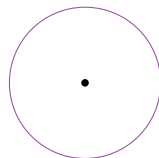
A line  $L$  (or any other set) that doesn't contain the origin is not a subspace.

Fails: 1.



## Non-Example

A circle  $C$  is not a subspace. Fails:

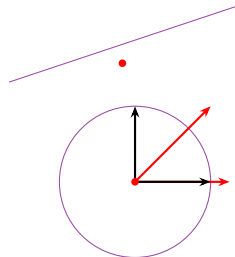


# Non-Examples

## Non-Example

A line  $L$  (or any other set) that doesn't contain the origin is not a subspace.

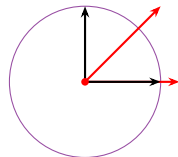
Fails: 1.



## Non-Example

A circle  $C$  is not a subspace. Fails:

1,2,3.



# Non-Examples

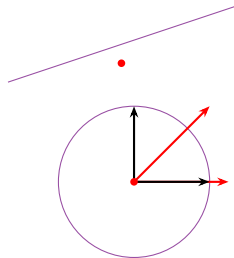
## Non-Example

A line  $L$  (or any other set) that doesn't contain the origin is not a subspace.

Fails: 1.

## Non-Example

A circle  $C$  is not a subspace. Fails: 1,2,3. Think: a circle isn't a "linear space."

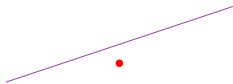


# Non-Examples

## Non-Example

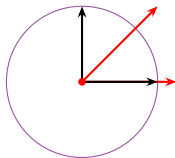
A line  $L$  (or any other set) that doesn't contain the origin is not a subspace.

Fails: 1.



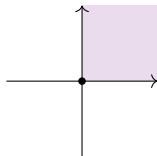
## Non-Example

A circle  $C$  is not a subspace. Fails: 1,2,3. Think: a circle isn't a "linear space."



## Non-Example

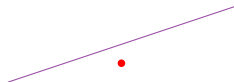
The first quadrant in  $\mathbf{R}^2$  is not a subspace. Fails:



# Non-Examples

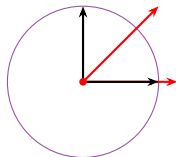
## Non-Example

A line  $L$  (or any other set) that doesn't contain the origin is not a subspace. Fails: 1.



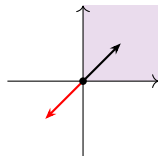
## Non-Example

A circle  $C$  is not a subspace. Fails: 1,2,3. Think: a circle isn't a "linear space."



## Non-Example

The first quadrant in  $\mathbf{R}^2$  is not a subspace. Fails: 3 only.

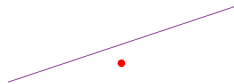


# Non-Examples

## Non-Example

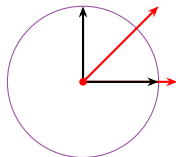
A line  $L$  (or any other set) that doesn't contain the origin is not a subspace.

Fails: 1.



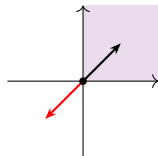
## Non-Example

A circle  $C$  is not a subspace. Fails: 1,2,3. Think: a circle isn't a "linear space."



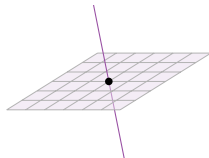
## Non-Example

The first quadrant in  $\mathbf{R}^2$  is not a subspace. Fails: 3 only.



## Non-Example

A line union a plane in  $\mathbf{R}^3$  is not a subspace. Fails:

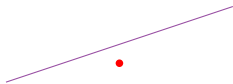


# Non-Examples

## Non-Example

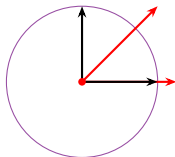
A line  $L$  (or any other set) that doesn't contain the origin is not a subspace.

Fails: 1.



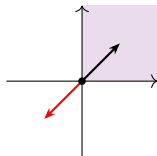
## Non-Example

A circle  $C$  is not a subspace. Fails: 1,2,3. Think: a circle isn't a "linear space."



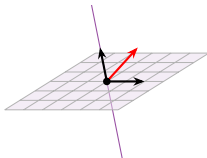
## Non-Example

The first quadrant in  $\mathbf{R}^2$  is not a subspace. Fails: 3 only.



## Non-Example

A line union a plane in  $\mathbf{R}^3$  is not a subspace. Fails: 2 only.



# Subsets and Subspaces

They aren't the same thing

A **subset** of  $\mathbf{R}^n$  is any collection of vectors whatsoever.



# Subsets and Subspaces

They aren't the same thing

A **subset** of  $\mathbf{R}^n$  is any collection of vectors whatsoever.

All of the non-examples are still subsets.

# Subsets and Subspaces

They aren't the same thing

A **subset** of  $\mathbf{R}^n$  is any collection of vectors whatsoever.

All of the non-examples are still subsets.

A **subspace** is a special kind of subset, which satisfies the three defining properties.

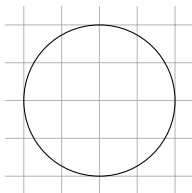
# Subsets and Subspaces

They aren't the same thing

A **subset** of  $\mathbf{R}^n$  is any collection of vectors whatsoever.

All of the non-examples are still subsets.

A **subspace** is a special kind of subset, which satisfies the three defining properties.



Subset: *yes*

Subspace: *no*

# Spans are Subspaces

## Theorem

Any  $\text{Span}\{v_1, v_2, \dots, v_n\}$  is a subspace.

# Spans are Subspaces

## Theorem

Any  $\text{Span}\{v_1, v_2, \dots, v_n\}$  is a subspace.

!!!

Every subspace is a span, and every span is a subspace.

# Spans are Subspaces

## Theorem

Any  $\text{Span}\{v_1, v_2, \dots, v_n\}$  is a subspace.

!!!

Every subspace is a span, and every span is a subspace.

## Definition

If  $V = \text{Span}\{v_1, v_2, \dots, v_n\}$ , we say that  $V$  is the subspace **generated by** or **spanned by** the vectors  $v_1, v_2, \dots, v_n$ .

Poll

Is the empty set  $\{\}$  a subspace? If not, which property(ies) does it fail?

Poll

Is the empty set  $\{\}$  a subspace? If not, which property(ies) does it fail?

The zero vector is not contained in the empty set, so it is *not* a subspace.



## Poll

Is the empty set  $\{\}$  a subspace? If not, which property(ies) does it fail?

The zero vector is not contained in the empty set, so it is *not* a subspace.

**Question:** What is the difference between  $\{\}$  and  $\{0\}$ ?

# Subspaces

## Verification

Let  $V = \left\{ \begin{pmatrix} a \\ b \end{pmatrix} \text{ in } \mathbf{R}^2 \mid ab = 0 \right\}$ . Let's check if  $V$  is a subspace or not.

# Subspaces

## Verification

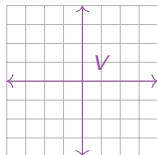
Let  $V = \left\{ \begin{pmatrix} a \\ b \end{pmatrix} \text{ in } \mathbf{R}^2 \mid ab = 0 \right\}$ . Let's check if  $V$  is a subspace or not.

We conclude that  $V$  is *not* a subspace.

# Subspaces

## Verification

Let  $V = \left\{ \begin{pmatrix} a \\ b \end{pmatrix} \text{ in } \mathbf{R}^2 \mid ab = 0 \right\}$ . Let's check if  $V$  is a subspace or not.



We conclude that  $V$  is *not* a subspace. A picture is above. (It doesn't look like a span.)

## Column Space and Null Space

An  $m \times n$  matrix  $A$  naturally gives rise to *two* subspaces.

# Column Space and Null Space

An  $m \times n$  matrix  $A$  naturally gives rise to *two* subspaces.

## Definition

- ▶ The **column space** of  $A$  is the subspace of  $\mathbf{R}^m$ —spanned by the columns of  $A$ . It is written  $\text{Col } A$ .

# Column Space and Null Space

An  $m \times n$  matrix  $A$  naturally gives rise to *two* subspaces.

## Definition

- ▶ The **column space** of  $A$  is the subspace of  $\mathbf{R}^m$  spanned by the columns of  $A$ . It is written  $\text{Col } A$ .

# Column Space and Null Space

An  $m \times n$  matrix  $A$  naturally gives rise to *two* subspaces.

## Definition

- ▶ The **column space** of  $A$  is the subspace of  $\mathbf{R}^m$  spanned by the columns of  $A$ . It is written  $\text{Col } A$ .
- ▶ The **null space** of  $A$  is the set of all solutions of the homogeneous equation  $Ax = 0$ :

$$\text{Nul } A = \{x \text{ in } \mathbf{R}^n \mid Ax = 0\}.$$

This is a subspace of  $\mathbf{R}^n$ .



# Column Space and Null Space

An  $m \times n$  matrix  $A$  naturally gives rise to *two* subspaces.

## Definition

- ▶ The **column space** of  $A$  is the subspace of  $\mathbf{R}^m$  spanned by the columns of  $A$ . It is written  $\text{Col } A$ .
- ▶ The **null space** of  $A$  is the set of all solutions of the homogeneous equation  $Ax = 0$ :

$$\text{Nul } A = \{x \text{ in } \mathbf{R}^n \mid Ax = 0\}.$$

This is a subspace of  $\mathbf{R}^n$ .

# Column Space and Null Space

An  $m \times n$  matrix  $A$  naturally gives rise to *two* subspaces.

## Definition

- ▶ The **column space** of  $A$  is the subspace of  $\mathbf{R}^m$  spanned by the columns of  $A$ . It is written  $\text{Col } A$ .
- ▶ The **null space** of  $A$  is the set of all solutions of the homogeneous equation  $Ax = 0$ :

$$\text{Nul } A = \{x \text{ in } \mathbf{R}^n \mid Ax = 0\}.$$

This is a subspace of  $\mathbf{R}^n$ .

The column space is defined as a span, so we know it is a subspace.

# Column Space and Null Space

An  $m \times n$  matrix  $A$  naturally gives rise to *two* subspaces.

## Definition

- ▶ The **column space** of  $A$  is the subspace of  $\mathbf{R}^m$  spanned by the columns of  $A$ . It is written  $\text{Col } A$ .
- ▶ The **null space** of  $A$  is the set of all solutions of the homogeneous equation  $Ax = 0$ :

$$\text{Nul } A = \{x \text{ in } \mathbf{R}^n \mid Ax = 0\}.$$

This is a subspace of  $\mathbf{R}^n$ .

The column space is defined as a span, so we know it is a subspace. It is the range (as opposed to the codomain) of the transformation  $T(x) = Ax$ .

## Column Space and Null Space

An  $m \times n$  matrix  $A$  naturally gives rise to *two* subspaces.

### Definition

- ▶ The **column space** of  $A$  is the subspace of  $\mathbf{R}^m$  spanned by the columns of  $A$ . It is written  $\text{Col } A$ .
- ▶ The **null space** of  $A$  is the set of all solutions of the homogeneous equation  $Ax = 0$ :

$$\text{Nul } A = \{x \text{ in } \mathbf{R}^n \mid Ax = 0\}.$$

This is a subspace of  $\mathbf{R}^n$ .

The column space is defined as a span, so we know it is a subspace. It is the range (as opposed to the codomain) of the transformation  $T(x) = Ax$ .

Check that the null space is a subspace:

# Column Space and Null Space

## Example

$$\text{Let } A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}.$$

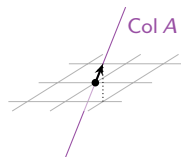
Let's compute the column space:

# Column Space and Null Space

## Example

$$\text{Let } A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}.$$

Let's compute the column space:

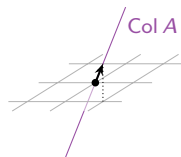


# Column Space and Null Space

## Example

$$\text{Let } A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}.$$

Let's compute the column space:



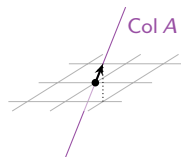
Let's compute the null space:

# Column Space and Null Space

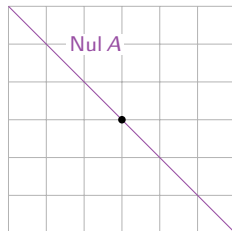
## Example

$$\text{Let } A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}.$$

Let's compute the column space:



Let's compute the null space:





## The Null Space is a Span

The column space of a matrix  $A$  is defined to be a span (of the columns).

## The Null Space is a Span

The column space of a matrix  $A$  is defined to be a span (of the columns).

The null space is defined to be the solution set to  $Ax = 0$ .

## The Null Space is a Span

The column space of a matrix  $A$  is defined to be a span (of the columns).

The null space is defined to be the solution set to  $Ax = 0$ . It is a subspace, so it is a span.

# The Null Space is a Span

The column space of a matrix  $A$  is defined to be a span (of the columns).

The null space is defined to be the solution set to  $Ax = 0$ . It is a subspace, so it is a span.

## Question

How to find vectors which span the null space?

# The Null Space is a Span

The column space of a matrix  $A$  is defined to be a span (of the columns).

The null space is defined to be the solution set to  $Ax = 0$ . It is a subspace, so it is a span.

## Question

How to find vectors which span the null space?

**Answer:** Parametric vector form!

# The Null Space is a Span

The column space of a matrix  $A$  is defined to be a span (of the columns).

The null space is defined to be the solution set to  $Ax = 0$ . It is a subspace, so it is a span.

## Question

How to find vectors which span the null space?

**Answer:** Parametric vector form! We know that the solution set to  $Ax = 0$  has a parametric form that looks like

$$x_3 \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 3 \\ 0 \\ 1 \end{pmatrix} \quad \begin{array}{l} \text{if, say, } x_3 \text{ and } x_4 \\ \text{are the free} \\ \text{variables.} \end{array}$$

# The Null Space is a Span

The column space of a matrix  $A$  is defined to be a span (of the columns).

The null space is defined to be the solution set to  $Ax = 0$ . It is a subspace, so it is a span.

## Question

How to find vectors which span the null space?

**Answer:** Parametric vector form! We know that the solution set to  $Ax = 0$  has a parametric form that looks like

$$x_3 \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 3 \\ 0 \\ 1 \end{pmatrix} \quad \text{if, say, } x_3 \text{ and } x_4 \text{ are the free variables. So} \quad \text{Nul } A = \text{Span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 3 \\ 0 \\ 1 \end{pmatrix} \right\}.$$

# The Null Space is a Span

The column space of a matrix  $A$  is defined to be a span (of the columns).

The null space is defined to be the solution set to  $Ax = 0$ . It is a subspace, so it is a span.

## Question

How to find vectors which span the null space?

**Answer:** Parametric vector form! We know that the solution set to  $Ax = 0$  has a parametric form that looks like

$$x_3 \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 3 \\ 0 \\ 1 \end{pmatrix} \quad \begin{array}{l} \text{if, say, } x_3 \text{ and } x_4 \\ \text{are the free} \\ \text{variables. So} \end{array} \quad \text{Nul } A = \text{Span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 3 \\ 0 \\ 1 \end{pmatrix} \right\}.$$

Refer back to the slides for §1.5 (Solution Sets).



# The Null Space is a Span

The column space of a matrix  $A$  is defined to be a span (of the columns).

The null space is defined to be the solution set to  $Ax = 0$ . It is a subspace, so it is a span.

## Question

How to find vectors which span the null space?

**Answer:** Parametric vector form! We know that the solution set to  $Ax = 0$  has a parametric form that looks like

$$x_3 \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 3 \\ 0 \\ 1 \end{pmatrix} \quad \begin{array}{l} \text{if, say, } x_3 \text{ and } x_4 \\ \text{are the free} \\ \text{variables. So} \end{array} \quad \text{Nul } A = \text{Span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 3 \\ 0 \\ 1 \end{pmatrix} \right\}.$$

Refer back to the slides for §1.5 (Solution Sets).

**Note:** It is much easier to define the null space first as a subspace, then find spanning vectors *later*, if we need them. This is one reason subspaces are so useful.

# The Null Space is a Span

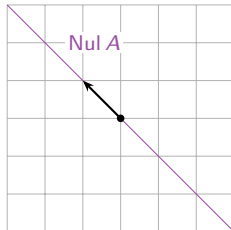
Example, revisited

Find vector(s) that span the null space of  $A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}$ .

# The Null Space is a Span

Example, revisited

Find vector(s) that span the null space of  $A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}$ .



# Subspaces

## Summary

How do you check if a subset is a subspace?

- ▶ Is it a span? Can it be written as a span?

# Subspaces

## Summary

How do you check if a subset is a subspace?

- ▶ Is it a span? Can it be written as a span?
- ▶ Can it be written as the column space of a matrix?

# Subspaces

## Summary

How do you check if a subset is a subspace?

- ▶ Is it a span? Can it be written as a span?
- ▶ Can it be written as the column space of a matrix?
- ▶ Can it be written as the null space of a matrix?

# Subspaces

## Summary

How do you check if a subset is a subspace?

- ▶ Is it a span? Can it be written as a span?
- ▶ Can it be written as the column space of a matrix?
- ▶ Can it be written as the null space of a matrix?
- ▶ Is it all of  $\mathbf{R}^n$  or the zero subspace  $\{0\}$ ?

# Subspaces

## Summary

How do you check if a subset is a subspace?

- ▶ Is it a span? Can it be written as a span?
- ▶ Can it be written as the column space of a matrix?
- ▶ Can it be written as the null space of a matrix?
- ▶ Is it all of  $\mathbf{R}^n$  or the zero subspace  $\{0\}$ ?
- ▶ Can it be written as a type of subspace that we'll learn about later (eigenspaces, ...)?



# Subspaces

## Summary

How do you check if a subset is a subspace?

- ▶ Is it a span? Can it be written as a span?
- ▶ Can it be written as the column space of a matrix?
- ▶ Can it be written as the null space of a matrix?
- ▶ Is it all of  $\mathbf{R}^n$  or the zero subspace  $\{0\}$ ?
- ▶ Can it be written as a type of subspace that we'll learn about later (eigenspaces, ...)?

If so, then it's automatically a subspace.

# Subspaces

## Summary

How do you check if a subset is a subspace?

- ▶ Is it a span? Can it be written as a span?
- ▶ Can it be written as the column space of a matrix?
- ▶ Can it be written as the null space of a matrix?
- ▶ Is it all of  $\mathbf{R}^n$  or the zero subspace  $\{0\}$ ?
- ▶ Can it be written as a type of subspace that we'll learn about later (eigenspaces, ...)?

If so, then it's automatically a subspace.

If all else fails:

# Subspaces

## Summary

How do you check if a subset is a subspace?

- ▶ Is it a span? Can it be written as a span?
- ▶ Can it be written as the column space of a matrix?
- ▶ Can it be written as the null space of a matrix?
- ▶ Is it all of  $\mathbf{R}^n$  or the zero subspace  $\{0\}$ ?
- ▶ Can it be written as a type of subspace that we'll learn about later (eigenspaces, ...)?

If so, then it's automatically a subspace.

If all else fails:

- ▶ Can you verify directly that it satisfies the three defining properties?

## Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

## Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

### Definition

Let  $V$  be a subspace of  $\mathbf{R}^n$ . A **basis** of  $V$  is a set of vectors  $\{v_1, v_2, \dots, v_m\}$  in  $V$  such that:

## Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

### Definition

Let  $V$  be a subspace of  $\mathbf{R}^n$ . A **basis** of  $V$  is a set of vectors  $\{v_1, v_2, \dots, v_m\}$  in  $V$  such that:

1.  $V = \text{Span}\{v_1, v_2, \dots, v_m\}$ , and

## Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

### Definition

Let  $V$  be a subspace of  $\mathbf{R}^n$ . A **basis** of  $V$  is a set of vectors  $\{v_1, v_2, \dots, v_m\}$  in  $V$  such that:

1.  $V = \text{Span}\{v_1, v_2, \dots, v_m\}$ , and
2.  $\{v_1, v_2, \dots, v_m\}$  is linearly independent.

## Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

### Definition

Let  $V$  be a subspace of  $\mathbf{R}^n$ . A **basis** of  $V$  is a set of vectors  $\{v_1, v_2, \dots, v_m\}$  in  $V$  such that:

1.  $V = \text{Span}\{v_1, v_2, \dots, v_m\}$ , and
2.  $\{v_1, v_2, \dots, v_m\}$  is linearly independent.

The number of vectors in a basis is the **dimension** of  $V$ , and is written  $\dim V$ .



## Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

### Definition

Let  $V$  be a subspace of  $\mathbf{R}^n$ . A **basis** of  $V$  is a set of vectors  $\{v_1, v_2, \dots, v_m\}$  in  $V$  such that:

1.  $V = \text{Span}\{v_1, v_2, \dots, v_m\}$ , and
2.  $\{v_1, v_2, \dots, v_m\}$  is linearly independent.

The number of vectors in a basis is the **dimension** of  $V$ , and is written  $\dim V$ .

Note the big  
red border here

## Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

### Definition

Let  $V$  be a subspace of  $\mathbf{R}^n$ . A **basis** of  $V$  is a set of vectors  $\{v_1, v_2, \dots, v_m\}$  in  $V$  such that:

1.  $V = \text{Span}\{v_1, v_2, \dots, v_m\}$ , and
2.  $\{v_1, v_2, \dots, v_m\}$  is linearly independent.

The number of vectors in a basis is the **dimension** of  $V$ , and is written  $\dim V$ .

Note the big  
red border here

**Why** is a basis the smallest number of vectors needed to span?

## Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

### Definition

Let  $V$  be a subspace of  $\mathbf{R}^n$ . A **basis** of  $V$  is a set of vectors  $\{v_1, v_2, \dots, v_m\}$  in  $V$  such that:

1.  $V = \text{Span}\{v_1, v_2, \dots, v_m\}$ , and
2.  $\{v_1, v_2, \dots, v_m\}$  is linearly independent.

The number of vectors in a basis is the **dimension** of  $V$ , and is written  $\dim V$ .

Note the big  
red border here

**Why** is a basis the smallest number of vectors needed to span?

Recall: *linearly independent* means that every time you add another vector, the span gets bigger.

## Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

### Definition

Let  $V$  be a subspace of  $\mathbf{R}^n$ . A **basis** of  $V$  is a set of vectors  $\{v_1, v_2, \dots, v_m\}$  in  $V$  such that:

1.  $V = \text{Span}\{v_1, v_2, \dots, v_m\}$ , and
2.  $\{v_1, v_2, \dots, v_m\}$  is linearly independent.

The number of vectors in a basis is the **dimension** of  $V$ , and is written  $\dim V$ .

Note the big  
red border here

**Why** is a basis the smallest number of vectors needed to span?

Recall: *linearly independent* means that every time you add another vector, the span gets bigger.

Hence, if we remove any vector, the span gets *smaller*: so any smaller set can't span  $V$ .

# Basis of a Subspace

What is the *smallest number* of vectors that are needed to span a subspace?

## Definition

Let  $V$  be a subspace of  $\mathbf{R}^n$ . A **basis** of  $V$  is a set of vectors  $\{v_1, v_2, \dots, v_m\}$  in  $V$  such that:

1.  $V = \text{Span}\{v_1, v_2, \dots, v_m\}$ , and
2.  $\{v_1, v_2, \dots, v_m\}$  is linearly independent.

The number of vectors in a basis is the **dimension** of  $V$ , and is written  $\dim V$ .

Note the big  
red border here

**Why** is a basis the smallest number of vectors needed to span?

Recall: *linearly independent* means that every time you add another vector, the span gets bigger.

Hence, if we remove any vector, the span gets *smaller*: so any smaller set can't span  $V$ .

## Important

A subspace has *many different* bases, but they all have the same number of vectors (see the exercises in §2.9).

## Bases of $\mathbf{R}^2$

### Question

What is a basis for  $\mathbf{R}^2$ ?

# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

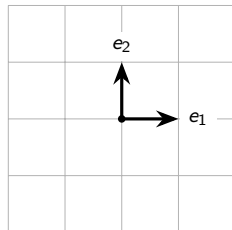
We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.

# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.  $\{e_1, e_2\}$  is one basis.





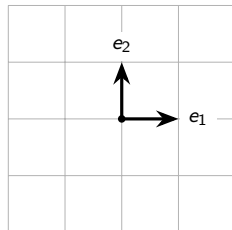
# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.  $\{e_1, e_2\}$  is one basis.

1. They span:  $\begin{pmatrix} a \\ b \end{pmatrix} =$



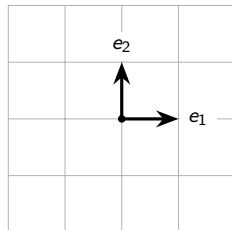
# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.  $\{e_1, e_2\}$  is one basis.

1. They span:  $\begin{pmatrix} a \\ b \end{pmatrix} = ae_1 + be_2$ .



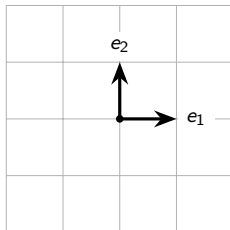
# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.  $\{e_1, e_2\}$  is one basis.

1. They span:  $\begin{pmatrix} a \\ b \end{pmatrix} = ae_1 + be_2$ .
2. They are linearly independent because they are not collinear.



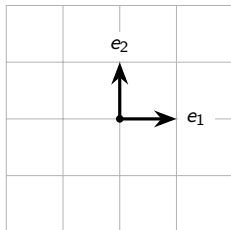
# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.  $\{e_1, e_2\}$  is one basis.

1. They span:  $\begin{pmatrix} a \\ b \end{pmatrix} = ae_1 + be_2$ .
2. They are linearly independent because they are not collinear.



## Question

What is another basis for  $\mathbf{R}^2$ ?

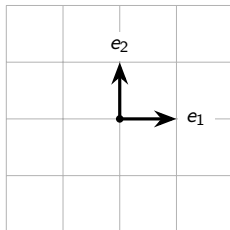
# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.  $\{e_1, e_2\}$  is one basis.

1. They span:  $\begin{pmatrix} a \\ b \end{pmatrix} = ae_1 + be_2$ .
2. They are linearly independent because they are not collinear.



## Question

What is another basis for  $\mathbf{R}^2$ ?

Any two nonzero vectors that are not collinear.

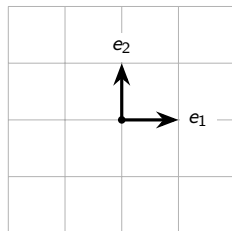
# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.  $\{e_1, e_2\}$  is one basis.

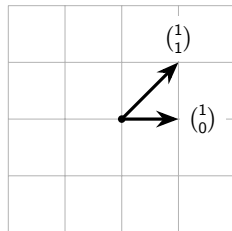
1. They span:  $\begin{pmatrix} a \\ b \end{pmatrix} = ae_1 + be_2$ .
2. They are linearly independent because they are not collinear.



## Question

What is another basis for  $\mathbf{R}^2$ ?

Any two nonzero vectors that are not collinear.  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$  is also a basis.



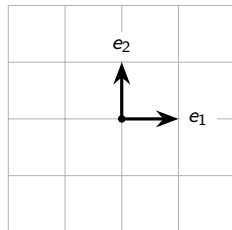
# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.  $\{e_1, e_2\}$  is one basis.

1. They span:  $\begin{pmatrix} a \\ b \end{pmatrix} = ae_1 + be_2$ .
2. They are linearly independent because they are not collinear.

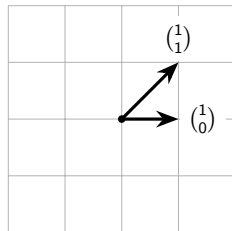


## Question

What is another basis for  $\mathbf{R}^2$ ?

Any two nonzero vectors that are not collinear.  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$  is also a basis.

1. They span:  $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$  has a pivot in every row.



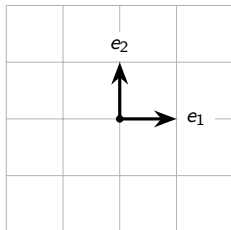
# Bases of $\mathbf{R}^2$

## Question

What is a basis for  $\mathbf{R}^2$ ?

We need two vectors that *span*  $\mathbf{R}^2$  and are *linearly independent*.  $\{e_1, e_2\}$  is one basis.

1. They span:  $\begin{pmatrix} a \\ b \end{pmatrix} = ae_1 + be_2$ .
2. They are linearly independent because they are not collinear.

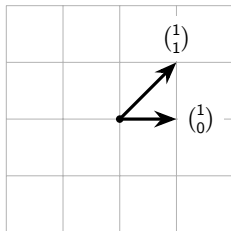


## Question

What is another basis for  $\mathbf{R}^2$ ?

Any two nonzero vectors that are not collinear.  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$  is also a basis.

1. They span:  $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$  has a pivot in every row.
2. They are linearly independent:  $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$  has a pivot in every column.





## Bases of $\mathbf{R}^n$

The unit coordinate vectors

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad \dots, \quad e_{n-1} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ 0 \end{pmatrix}, \quad e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$$

are a basis for  $\mathbf{R}^n$ .

## Bases of $\mathbf{R}^n$

The unit coordinate vectors

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad \dots, \quad e_{n-1} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ 0 \end{pmatrix}, \quad e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$$

are a basis for  $\mathbf{R}^n$ .

1. They span:  $I_n$  has a pivot in every row.

## Bases of $\mathbf{R}^n$

The unit coordinate vectors

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad \dots, \quad e_{n-1} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ 0 \end{pmatrix}, \quad e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$$

are a basis for  $\mathbf{R}^n$ .  The identity matrix has columns  $e_1, e_2, \dots, e_n$ .

1. They span:  $I_n$  has a pivot in every row.

## Bases of $\mathbf{R}^n$

The unit coordinate vectors

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad \dots, \quad e_{n-1} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ 0 \end{pmatrix}, \quad e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$$

are a basis for  $\mathbf{R}^n$ .  The identity matrix has columns  $e_1, e_2, \dots, e_n$ .

1. They span:  $I_n$  has a pivot in every row.
2. They are linearly independent:  $I_n$  has a pivot in every column.

## Bases of $\mathbf{R}^n$

The unit coordinate vectors

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad \dots, \quad e_{n-1} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ 0 \end{pmatrix}, \quad e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$$

are a basis for  $\mathbf{R}^n$ .  The identity matrix has columns  $e_1, e_2, \dots, e_n$ .

1. They span:  $I_n$  has a pivot in every row.
2. They are linearly independent:  $I_n$  has a pivot in every column.

In general:  $\{v_1, v_2, \dots, v_n\}$  is a basis for  $\mathbf{R}^n$  if and only if the matrix

$$A = \begin{pmatrix} | & | & & | \\ v_1 & v_2 & \cdots & v_n \\ | & | & & | \end{pmatrix}$$

has a pivot in every row and every column, i.e. if  $A$  is \_\_\_\_\_.

## Bases of $\mathbf{R}^n$

The unit coordinate vectors

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ 0 \end{pmatrix}, \quad \dots, \quad e_{n-1} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ 0 \end{pmatrix}, \quad e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$$

are a basis for  $\mathbf{R}^n$ .  The identity matrix has columns  $e_1, e_2, \dots, e_n$ .

1. They span:  $I_n$  has a pivot in every row.
2. They are linearly independent:  $I_n$  has a pivot in every column.

In general:  $\{v_1, v_2, \dots, v_n\}$  is a basis for  $\mathbf{R}^n$  if and only if the matrix

$$A = \begin{pmatrix} | & | & & | \\ v_1 & v_2 & \cdots & v_n \\ | & | & & | \end{pmatrix}$$

has a pivot in every row and every column, i.e. if  $A$  is *invertible*.

# Basis of a Subspace

## Example

### Example

Let

$$V = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \text{ in } \mathbf{R}^3 \mid x + 3y + z = 0 \right\} \quad \mathcal{B} = \left\{ \begin{pmatrix} -3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -3 \end{pmatrix} \right\}.$$

Verify that  $\mathcal{B}$  is a basis for  $V$ .

## Basis for $\text{Nul } A$

### Fact

The vectors in the parametric vector form of the general solution to  $Ax = 0$  always form a basis for  $\text{Nul } A$ .



## Basis for $\text{Nul } A$

### Fact

The vectors in the parametric vector form of the general solution to  $Ax = 0$  always form a basis for  $\text{Nul } A$ .

### Example

## Basis for Col $A$

Fact

The *pivot columns* of  $A$  always form a basis for Col  $A$ .

## Basis for Col $A$

Fact

The *pivot columns* of  $A$  always form a basis for Col  $A$ .

**Warning:** I mean the pivot columns of the *original* matrix  $A$ , not the row-reduced form.

## Basis for Col $A$

Fact

The *pivot columns* of  $A$  always form a basis for Col  $A$ .

**Warning:** I mean the pivot columns of the *original* matrix  $A$ , not the row-reduced form. (Row reduction changes the column space.)

## Basis for Col $A$

Fact

The *pivot columns* of  $A$  always form a basis for Col  $A$ .

**Warning:** I mean the pivot columns of the *original* matrix  $A$ , not the row-reduced form. (Row reduction changes the column space.)

Example

## Basis for Col $A$

### Fact

The *pivot columns* of  $A$  always form a basis for Col  $A$ .

**Warning:** I mean the pivot columns of the *original* matrix  $A$ , not the row-reduced form. (Row reduction changes the column space.)

Example

**Why?** End of §2.8, or ask in office hours.