

- Max Control Effort
- Optimal Control (OCP)
- OD-CLF-CBF-QP with $\nu \in [1, 1000]$ and $\alpha = 1$
- OD-CLF-CBF-QP with $\nu \in [1, 1000]$ and $\alpha = 0.05$
- OD-CLF-CBF-QP with $\nu \in [1, 1000]$ and $\alpha = 0.025$
- OD-CLF-CBF-QP with $\nu \in [1, 1000]$ and $\alpha = 0.015$
- Active Input Constraint

