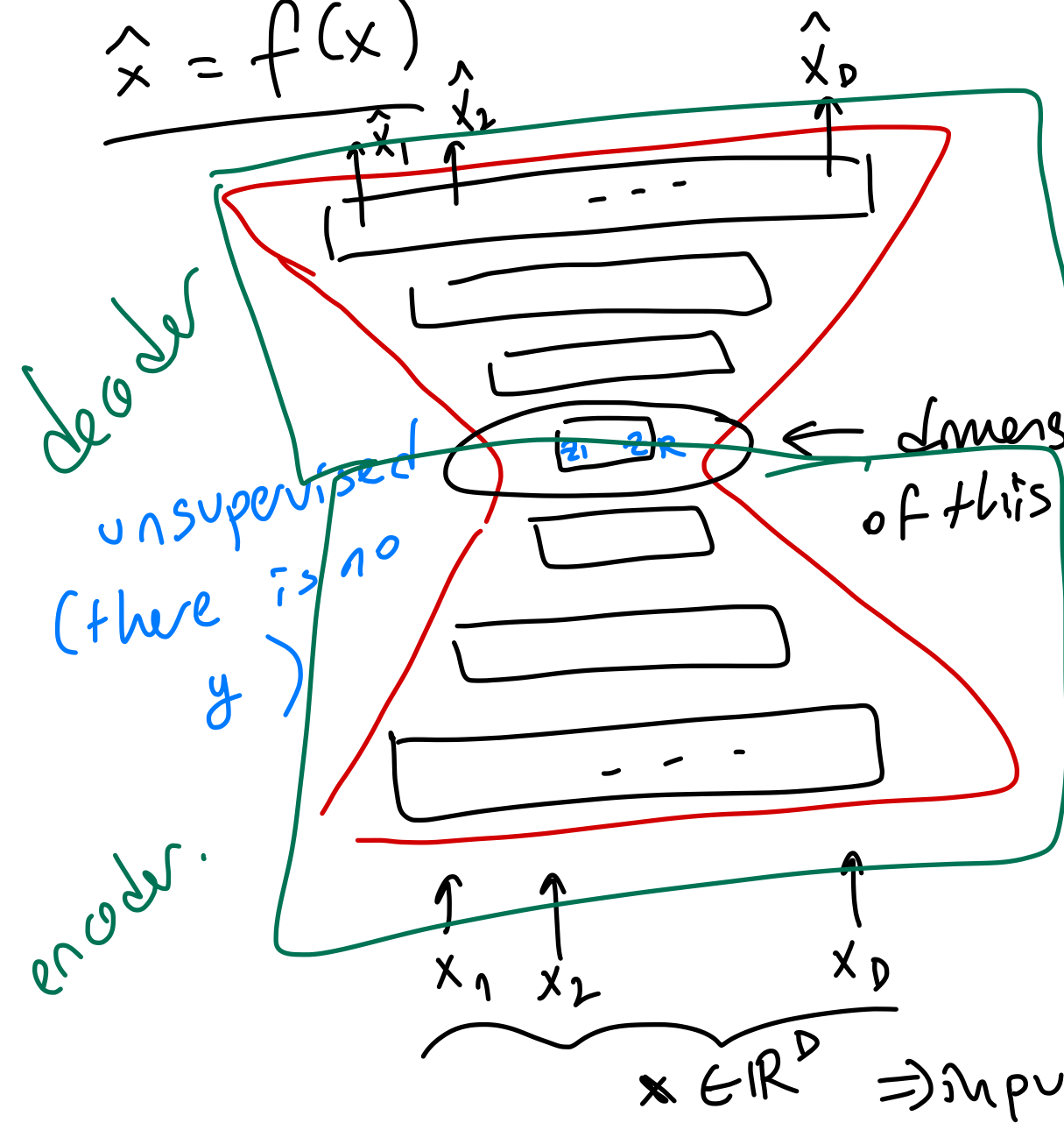


Autoencoders

$$\hat{y}_t = f(\underbrace{y_{t-1}, y_{t-2}, \dots, y_{t-10}}_{\text{autoregressive}})$$

$$\hat{x} = f(x)$$

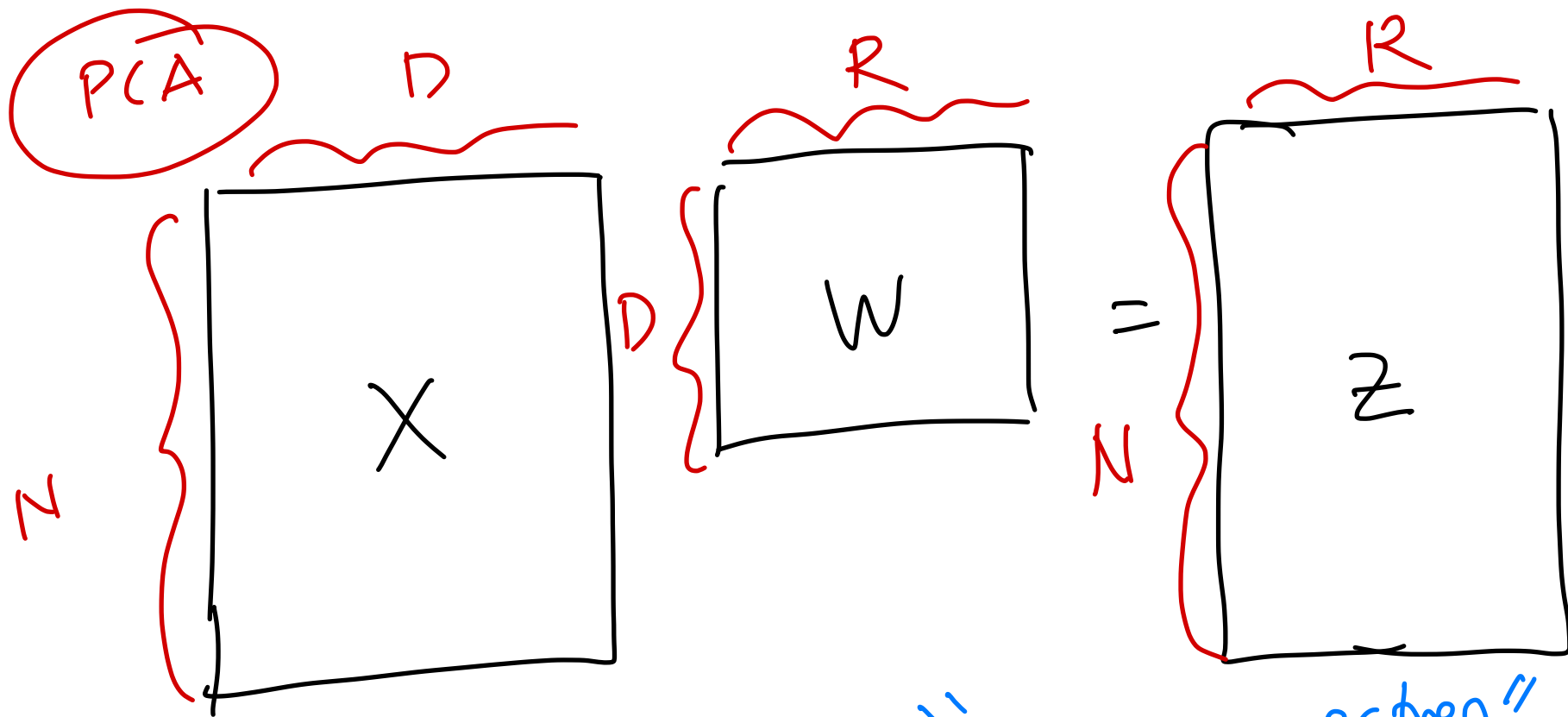


They are similar to dimensionality reduction algorithms.

$$R \ll D$$

$$x \in \mathbb{R}^D \xrightarrow{\text{encoder}} z \in \mathbb{R}^R \xrightarrow{\text{decoder}} \hat{x} \in \mathbb{R}^D$$

$x \in \mathbb{R}^D \Rightarrow$ input vector

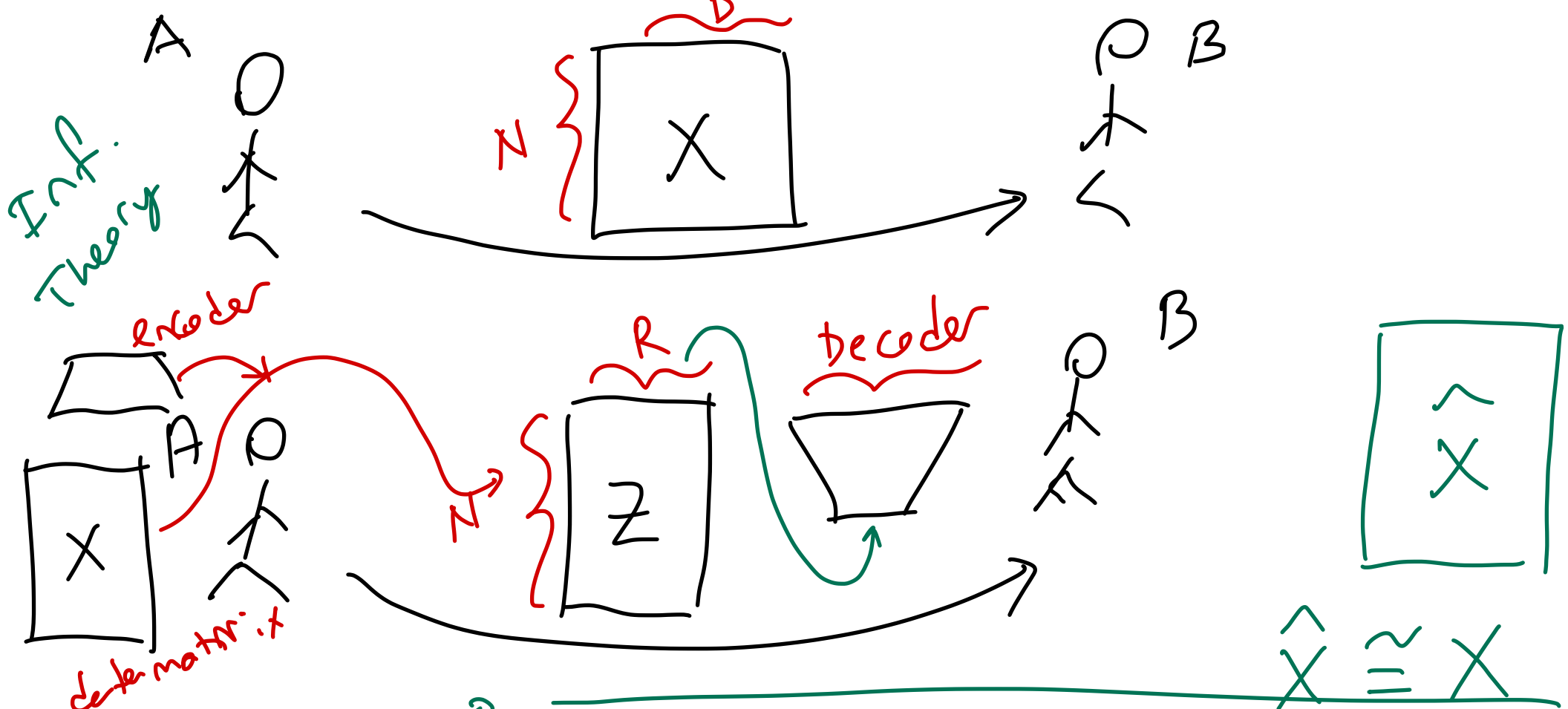


"Linear projection"

Loss Function (Reconstruction Error)

the difference between x & \hat{x} .

$$\hat{X} \approx X \Rightarrow \text{sse} \Rightarrow \frac{1}{ND} \sum_{i=1}^N \sum_{d=1}^D (X_{id} - \hat{X}_{id})^2$$



Visualization

if $R=2$ or $R=3$

\Downarrow

We can use Z to visualize data.

Multi output where

regression
 $y_i = x_i$

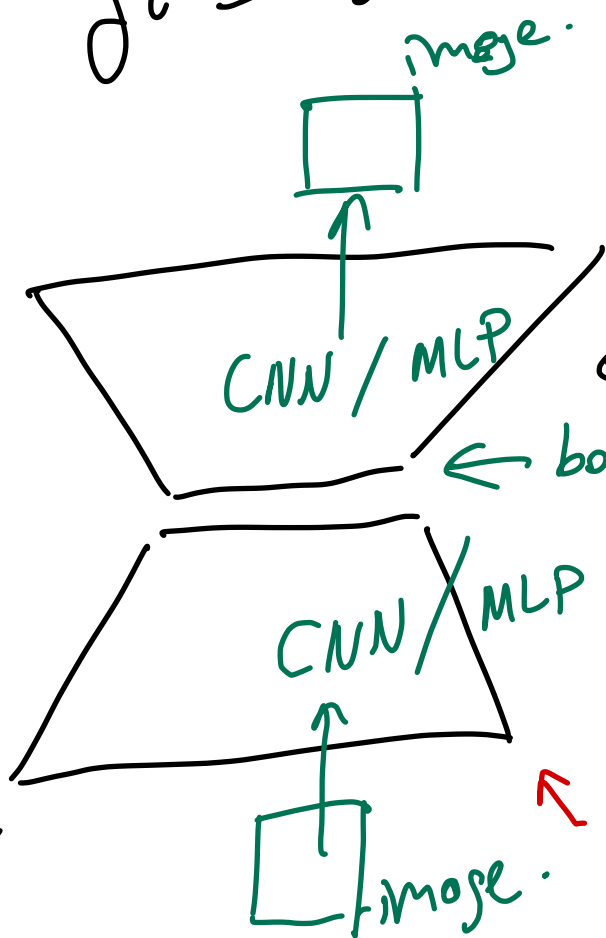
$$\{(x_i, y_i)\}_{i=1}^N$$

$$x_i \in \mathbb{R}^D$$

$$y_i \in \mathbb{R}^Q$$

$$x_i \in \mathbb{R}^D$$

autoencoder model

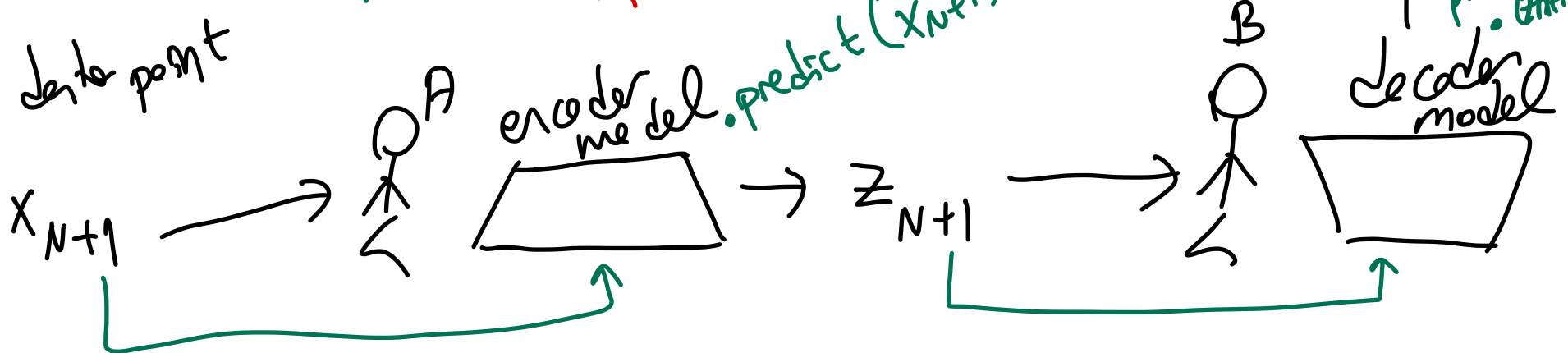


decoder model

encoder model

reconstructed version of x_{N+1}

new data point



build encoder model

build decoder model

combine them into autoencoder model

compile & fit autoencoder model.

call predict of encoder model (A)

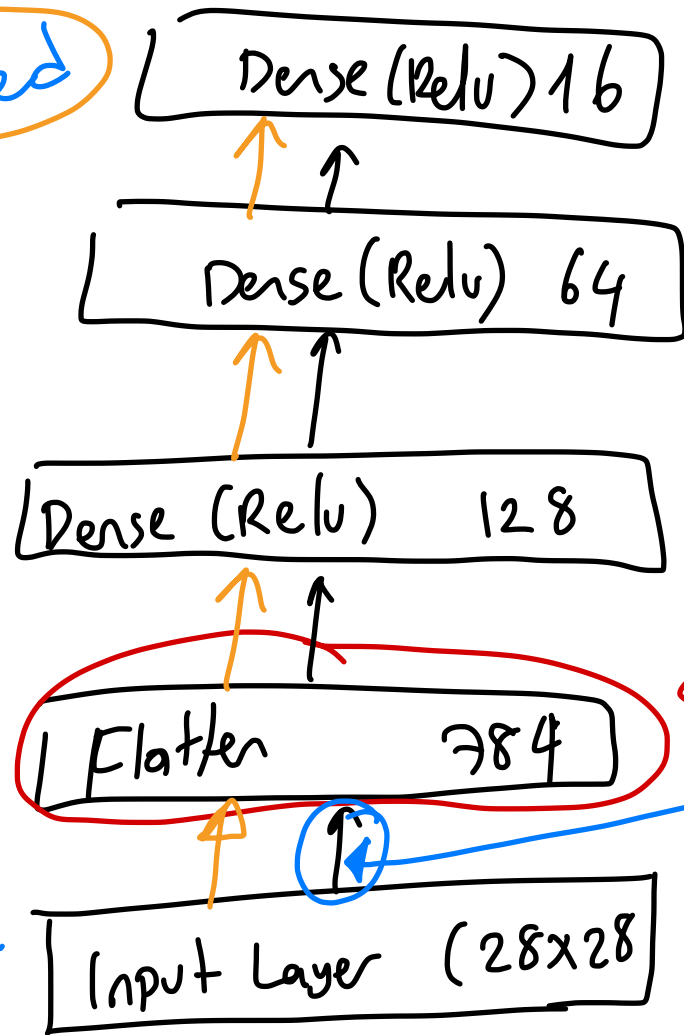
call predict of decoder model (B)

$\underline{x_i} \Rightarrow z_i \Rightarrow (z_i + \text{add noise}) \Rightarrow \text{decoder}$

\Downarrow
perturbed version
of x_i .

decoder_Model = Model(inputs = decoder_input, outputs = decoded)

decoder → Input Layer (16)



Layers.Flatten()(inputlayer)

encoder_model = Model(inputs = inputLayer, outputs = encoded)