QF4102 Financial Modelling and Computation Assignment 3 $\,$

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1 Transformed Black-Scholes PDE model

Consider the **transformed** Black-Scholes PDE model:

$$\begin{cases} \frac{\partial u}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 u}{\partial x^2} + (r - q - \frac{\sigma^2}{2}) \frac{\partial u}{\partial x} - ru = 0, & x \in (-\infty, \infty), t \in [0, T) \\ u(x, T) = \varphi(x), \end{cases}$$

1.1 Derivation of fully implicit scheme

Evaluate partial derivatives at (x_n^i, t_n) where $t_n = n\Delta t, x_n^i = i\Delta x, n \in [0, \frac{T}{\Delta t}), i \in [-x_{max}, x_{max}], I_{max} = \frac{x_{max}}{\Delta x}$

Use the forward time finite difference formulae :
$$\left. \frac{\partial u}{\partial t} \right|_{(x_n^i,t_n)} = \frac{u_{n+1}^i - u_n^i}{\Delta t} + O(\Delta t)$$

Use the centred space finite difference formulae:
$$\frac{\partial u}{\partial x}\Big|_{(x_n^i, t_n)} = \frac{u_n^{i+1} - u_n^{i-1}}{2\Delta x} + O[(\Delta x)^2]$$

Use the centred space finite difference formulae :
$$\left. \frac{\partial^2 u}{\partial x^2} \right|_{(x_n^i,t_n)} = \frac{u_n^{i+1} - 2u_n^i + u_n^{i-1}}{(\Delta x)^2} + O[(\Delta x)^2]$$

The finite difference equation is hence:

$$\begin{split} \frac{u_{n+1}^i - u_n^i}{\Delta t} + O(\Delta t) + \frac{\sigma^2}{2} \frac{u_n^{i+1} - 2u_n^i + u_n^{i-1}}{(\Delta x)^2} + \left(r - q - \frac{\sigma^2}{2}\right) \frac{u_n^{i+1} - u_n^{i-1}}{2\Delta x} + O[(\Delta x)^2] - ru_n^i &= 0 \\ \frac{u_{n+1}^i - u_n^i}{\Delta t} + O(\Delta t) + O[(\Delta x)^2] &= -\frac{\sigma^2}{2} \frac{u_n^{i+1} - 2u_n^i + u_n^{i-1}}{(\Delta x)^2} - \left(r - q - \frac{\sigma^2}{2}\right) \frac{u_n^{i+1} - u_n^{i-1}}{2\Delta x} + ru_n^i \\ \frac{U_{n+1}^i - U_n^i}{\Delta t} &= rU_n^i - \frac{\sigma^2}{2} \frac{U_n^{i+1} - 2U_n^i + U_n^{i-1}}{(\Delta x)^2} - \left(r - q - \frac{\sigma^2}{2}\right) \frac{U_n^{i+1} - U_n^{i-1}}{2\Delta x} \\ U_{n+1}^i &= U_n^i + \Delta t \left[rU_n^i - \frac{\sigma^2}{2} \frac{U_n^{i+1} - 2U_n^i + U_n^{i-1}}{(\Delta x)^2} - \left(r - q - \frac{\sigma^2}{2}\right) \frac{U_n^{i+1} - U_n^{i-1}}{2\Delta x} \right] \\ U_{n+1}^i &= U_n^i (1 + r\Delta t) - \frac{\Delta t}{2(\Delta x)^2} \left[\sigma^2 (U_n^{i+1} - 2U_n^i + U_n^{i-1}) + \Delta x (r - q - \frac{\sigma^2}{2}) (U_n^{i+1} - U_n^{i-1}) \right] \end{split}$$

$$\begin{split} U_{n+1}^{i} &= U_{n}^{i-1} \big[\frac{\Delta t (r - q - \frac{\sigma^{2}}{2})}{2\Delta x} - \frac{\sigma^{2} \Delta t}{2(\Delta x)^{2}} \big] + U_{n}^{i} \big[1 + r\Delta t + \frac{\sigma^{2} \Delta t}{(\Delta x)^{2}} \big] + U_{n}^{i+1} \big[-\frac{\Delta t (r - q - \frac{\sigma^{2}}{2})}{2\Delta x} - \frac{\sigma^{2} \Delta t}{2(\Delta x)^{2}} \big] \\ U_{n+1}^{i} &= aU_{n}^{i-1} + bU_{n}^{i} + cU_{n}^{i+1}, \forall I_{min} + 1 \leq i \leq I_{max} - 1 \\ \text{where } a = \gamma - \frac{\alpha}{2}, b = \beta + \alpha, c = -\gamma - \frac{\alpha}{2}, \alpha = \frac{\sigma^{2} \Delta t}{(\Delta x)^{2}}, \beta = 1 + r\Delta t, \gamma = \frac{\Delta t (r - q - \frac{\sigma^{2}}{2})}{2\Delta x} \end{split}$$

The boundary conditions are as follows:

$$U_n^{I_{max}} = e^{-q(T-n\Delta t)} \exp(I_{max}\Delta x) - e^{-r(T-n\Delta t)}X, \text{ when the underlying value is very large at } \exp(I_{max}\Delta x)$$

$$U_n^{I_{min}} = 0, \text{ when the underlying value is very small at } \exp(I_{min}\Delta x)$$

With the values of $U_n^{I_{min}}$ and $U_n^{I_{max}}$ specified, we can express the FDE into matrix form.

More concisely, we can name the tridiagonal matrix A and the right hand side vector F to express the FDE in this form: $AU_n = U_{n+1} + F$, $U_n = A^{-1}(U_{n+1} + F)$

1.2 Finite Difference Scheme Algorithm on fully implicit scheme

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Data: S_0, X, r, T, \sigma, I, N, x_{max}
Result: c_{\text{IDS}}, Option Premium
\Delta t = \frac{T}{N}, \ \Delta x = \frac{x_{max}}{I};
\alpha = \frac{\Delta t (r - q - \frac{\sigma^2}{2})}{2\Delta x};
\beta = 1 + r\Delta t;
\gamma = \frac{\sigma^2 \Delta t}{2(\Delta x)^2};
a = \alpha - \gamma;
b = \beta + \alpha;
c = -\alpha - \gamma:
for i = -I + 1, -I + 2, \dots, I - 2, I - 1 do
 U_N^i = max(\exp(i\Delta x) - X, 0);
end
Generate a tridiagonal matrix A of dimension (2I-1)*(2I-1),
with A_i i = b, \forall i = 1, 2, \dots 2I - 1, A_i i - 1 = b, \forall i = 2, \dots 2I - 1, A_i i + 1 = b, \forall i = 1, 2, \dots 2I - 2.
for j = N - 1, N - 2, \dots, 0 do
     Generate a vector F of length (2I-1), with F_{2I-1}=c\exp(-r(T-j\Delta t))(S_{max}-X), F_i=0
    U_j = A^{-1}(U_{j+1} + F);
i_0 = round\left(\frac{\ln S_0}{\Delta x}\right);
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- 2 Valuation of digital call option
- 2.1 Algo