#### Convergence and all that

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#### Numerical computing and convergence



## A crash course in maximum likelihood estimation

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• Why



#### remember the sneak turtles 🐢



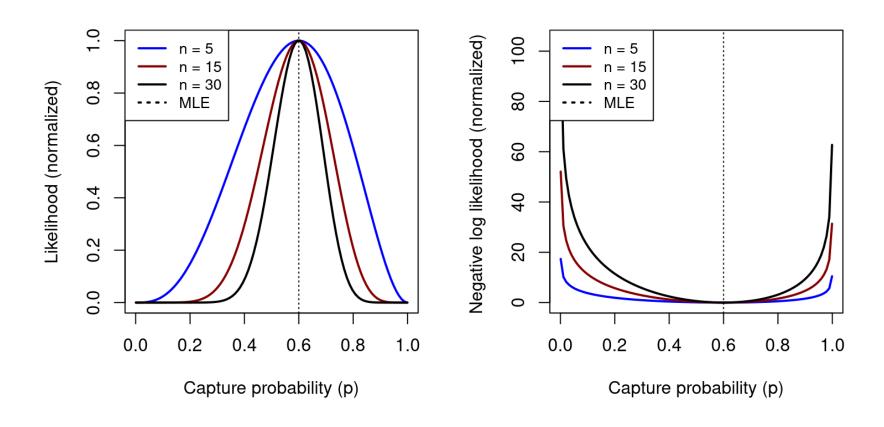


Figure 1. Left panel: Normalized likelihoods for a range of capture probabilities for each of three datasets with differing sample sizes. Right panel: visualizing the normalized negative log-likelihoods corresponding to the likelihoods on the left panel.

# Model fitting is (much) more challenging in multi-parameter settings

- High dimensional / many parameter models mean that we must find the minimum of a multi-dimensional surface
- Always need to check that your model is converged
- Convergence can rarely be proven, only disproven
- Because of this there are a number of checks that folks use to evaluate whether a model has converged on a unique solution

#### The Good, The Bad, and The ugly



Figure 2. The good, the bad, and the ugly negative log likelihood profiles adapted from Auger-Methe et al. 2021.

#### An real example of multiple minima

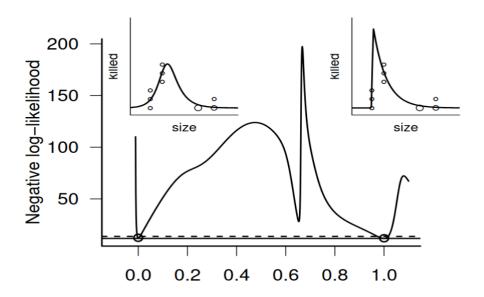


Figure 10: Likelihood slice connecting two negative log-likelihood minima for the modified logistic model of Vonesh and Bolker (2005). The x axis is on an arbitrary scale where x=0 and x=1 represent the locations of the two minima. Subplots show the fits of the curves to the frog predation data for the parameters at each minimum; the right-hand minimum is a slightly better fit (-L=11.77 (right) vs. 12.15 (left)). The horizontal solid and dashed lines show the minimum negative log-likelihood and the 95% confidence cutoff  $(-L+\chi_1^2(0.95)/2)$ . The 95% confidence region includes small regions around both x=0 and x=1.

## A minimum toolkit for evaluating convergence in MLE models

- Convergence message from nlminb()
- Hessian matrix is positive definite, i.e., it curves upward
- Standard errors are reasonable and not too large
- Absolute values of gradients of parameters are low < 1e-3</li>
- Parameters are not estimated near bounds
  - This is critical if you're using an old version of ADMB
- Multiple shooting AKA jitter test
- Likelihood profile

#### What if we fail convergence tests?

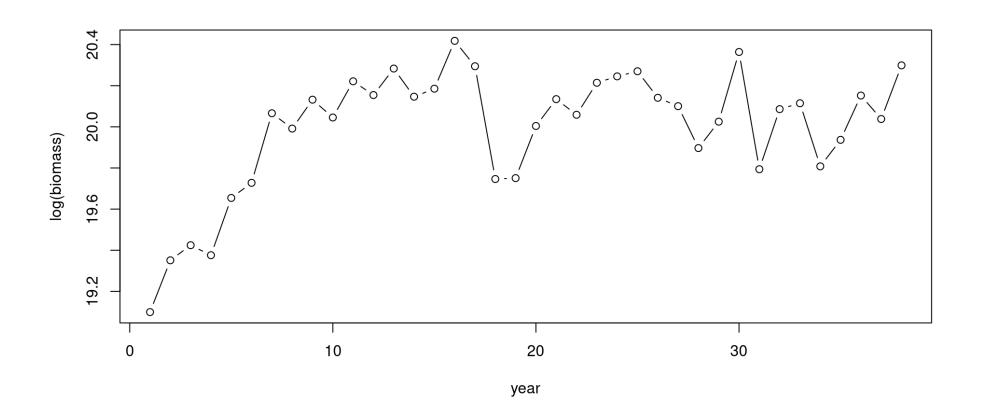
- Must get a model that converges before doing much of anything else
  - e.g., we aren't using "almost maximum likelihood estimation"
  - We certainly do not use the model to inform management

#### What if we fail convergence tests?



# A convergence diagnostic workflow with RTMB

#### Fit an arbitrary model



#### Fit an arbitrary model

```
1 obj <- MakeADFun(f, par, random = "log_d_t", silent = TRUE)</pre>
           2 opt <- nlminb(obj$par, obj$fn, obj$gr)</pre>
           3 opt
$par
   log d0
           log_sdp log_sdo alpha logit_rho
19.049941 -2.820671 -1.908811 4.664385 1.197744
$objective
[1] -13.77209
$convergence
\lceil 1 \rceil 0
$iterations
\lceil 1 \rceil 111
Sevaluations
function gradient
     150
               112
```

## Can we invert the Hessian matrix of the fixed effects?

#### Double check the gradients

```
1 obj$gr(opt$par) # gradients of each parameter
[1] -6.147670e-07 1.693861e-06 1.143878e-06 -1.044628e-04 -3.741121e-04
```

#### Double check the gradients

```
1 max(abs(obj$gr(opt$par))) # max gradient
[1] 0.0003741121

1 threshold <- 1e-3
2 max(abs(obj$gr(opt$par))) > threshold # bigger than threshold?
[1] FALSE
```

#### Parameters near bounds?

No (take it on faith for now)

#### Multiple shooting

- If we assume that we have solved to the MLE, that means that with small deviations from our maximum likelihood estimates nlminb() should be able to solve back to the exact same location
- This is sometimes called multiple shooting

## Automate multiple shooting via the jitter test

```
log_d0 log_sdp log_sdo alpha logit_rho
19.049941 -2.820671 -1.908811  4.664385  1.197744

1 opt$par + rnorm(length(opt$par), sd = 0.1) # jittered MLEs
log_d0 log_sdp log_sdo alpha logit_rho
18.968744 -2.919096 -1.953691  4.700522  1.364427

1 opt$par + rnorm(length(opt$par), sd = 0.1) # jittered MLEs
log_d0 log_sdp log_sdo alpha logit_rho
18.947640 -2.942257 -1.980536  4.604154  1.250253
```

## Automate multiple shooting via the jitter test

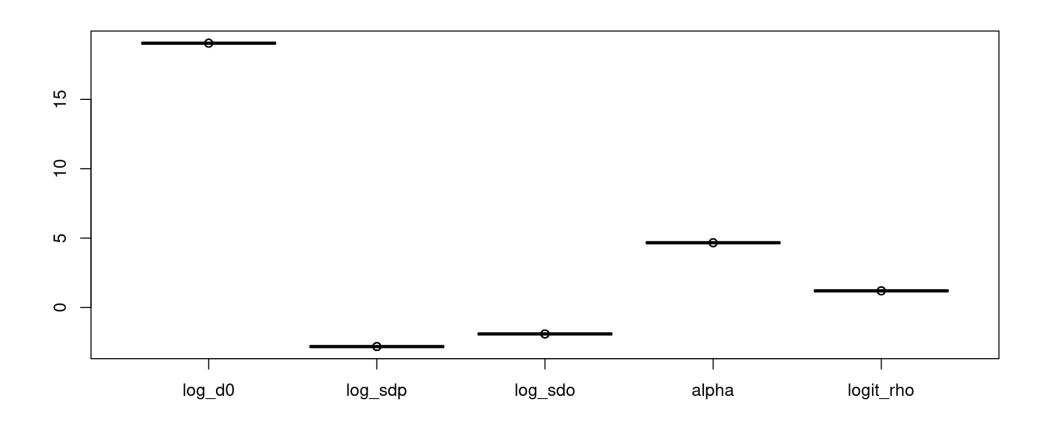
```
1 # write a function that jitters your solved MLEs and re-runs
2 do_one <- function() {
3    fit <- nlminb(opt$par + rnorm(length(opt$par), sd = 0.1),
4       obj$fn, obj$gr)
5    fit$par
6 }
7    set.seed(333) # cahill is only half evil
9 jit <- replicate(100, do_one()) # 100 iterations</pre>
```

#### Visualize jit

```
log_d0 log_sdp log_sdo alpha logit_rho
[1,] 19.04994 -2.820672 -1.908811 4.664383 1.197744
[2,] 19.04994 -2.820673 -1.908811 4.664381 1.197745
[3,] 19.04994 -2.820672 -1.908811 4.664384 1.197744
[4,] 19.04994 -2.820672 -1.908811 4.664384 1.197744
[5,] 19.04994 -2.820672 -1.908811 4.664384 1.197744
[6,] 19.04994 -2.820671 -1.908812 4.664386 1.197744
```

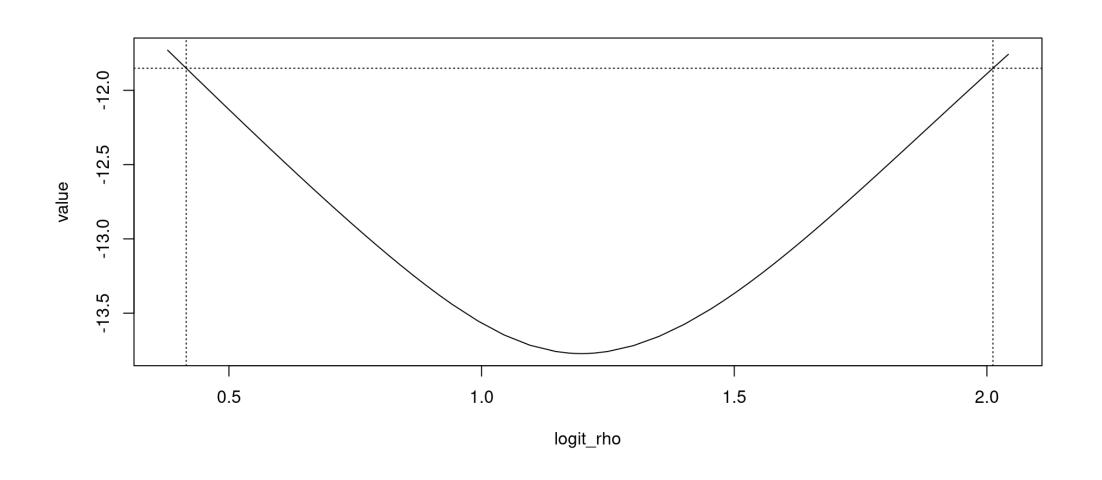
#### Visualize the jitter test

```
1 boxplot(t(jit))
```

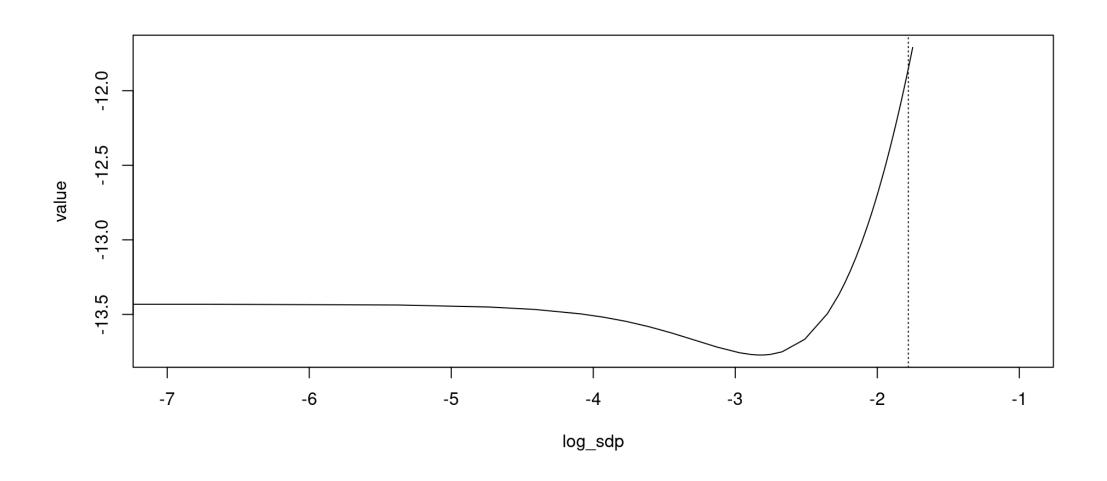


```
1 prof <- TMB::tmbprofile(obj, "logit_rho")</pre>
Profile value: -13.77209
Profile value: -13.77209
Profile value: -13.77209
Profile value: -13.77209
Profile value: -13.77208
Profile value: -13.77204
Profile value: -13.77188
Profile value: -13.77124
Profile value: -13.76867
Profile value: -13.7585
Profile value: -13.71902
Profile value: -13.65618
Profile value: -13.5728
Profile value: -13.47174
Profile value: -13.41546
Drofile value: 40 OFE70
```

1 plot(prof)



```
prof <- TMB::tmbprofile(obj, "log_sdp",</pre>
                                      range = c(-7, -1.5), h = 0.01
          3
Profile value: -13,77209
Profile value: -13.77201
Profile value: -13.77135
Profile value: -13.76785
Profile value: -13.75092
Profile value: -13.66666
Profile value: -13,49434
Profile value: -13.36755
Profile value: -13.29278
Profile value: -13.21001
Profile value: -13.11896
Profile value: -13.01935
Profile value: -12.91097
Profile value: -12.85342
Profile value: -12.79361
Drofila valuer 10 701E1
```



#### Wrapping up



#### References

- Auger-Méthé, M. et al. 2021. A guide to statespace modeling of ecological time series. Ecological Monographs 91(4): e01470. doi:10.1002/ecm.1470.
- Bolker, B. 2006. Ecological models and data in R.
- Thorson, J. and K. Kristensen. 2024. Spatiotemporal models for ecologists.
- Pawitawn, Y. In all likelihood: statistical modeling and inference using likelihood.