第四章作业

1.数学推导

1.1 前向推导:

1.2 在末速度固定的

情况下:

$$\begin{array}{l} \text{ A i 展刊} \\ \text{ a} = -\frac{12}{7}(\text{Pif} - \text{VioT} - \text{Pio}) + \frac{6}{7^2}(\text{Vif} - \text{Vio}) \\ = \frac{12(\text{Pio} - \text{Pif})}{7^3} + \frac{6\text{Vir} - 6\text{Vio}}{7^2} \\ \end{array}$$

$$\beta_{i} = \frac{6}{T^{2}} c \beta_{i} + V_{i}o - P_{i}o - \frac{2}{T} (V_{i}f - V_{i}o)$$

$$= \frac{6c \beta_{i}f - P_{i}o}{T^{2}} - \frac{(4V_{i}o + 2V_{i}f)}{T} -$$

将 alpha i 和 beta i 带入 J

$$J = T + \frac{1}{3}T^{3}(a_{1}^{2} + a_{2}^{2} + a_{3}^{2})$$

$$+ T^{2}(a_{1}\beta_{1} + a_{2}\beta_{2} + a_{3}\beta_{3})$$

$$+ T(\beta_{1}^{2} + \beta_{3}^{2} + \beta_{3}^{2})$$

$$\int = T + \frac{1}{1} \left(\frac{3}{3} \underbrace{\frac{3}{1-1}} a_{i2}^{2} + \underbrace{\frac{3}{1-1}} \beta_{i1} a_{i2} + \underbrace{\frac{3}{1-1}} \beta_{i2}^{2} \right) \\
+ \frac{1}{1-2} \left(\frac{3}{3} \underbrace{\frac{3}{1-1}} a_{i1} a_{i2} + \underbrace{\frac{3}{1-1}} \beta_{i1} a_{i2} + \underbrace{\frac{3}{1-1}} \beta_{i1}^{2} a_{i1} + \underbrace{\frac{3}} \beta_{i1}^{2} a_{i1} + \underbrace{\frac{3}{1-1}} \beta_{i1}^{2} a_{i1} + \underbrace{\frac{3}{1$$

$$\frac{2J_{1}}{J_{2}} = \left(\frac{3}{3} + \frac{3}{4} + \frac{3$$

对J求对T的偏导

$$J = J_{1} = + J_{2} + J_{3} + J_{3} + J_{4}$$

$$\frac{\partial J}{\partial T} = -J_{1}T^{-2} - 2J_{2}T^{-3} - 3J_{3}T^{-4} + J_{4} = 0$$

$$T^{4} - J_{1}T^{-2} - 2J_{2}T^{-3}J_{3} = 0$$

求解 T 的四阶方程(companion matrix):

2.成果

