view frames Result Recorded at time: 13.947 world Broadcaster: /arm/robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 dummy_link Broadcaster: /arm/robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: /arm/robot state publisher Average rate: 50.201Buffer length: 4.98 Most recent transform: 13.933 Oldest transform: 8.953 plat link Broadcaster: /arm/robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 lock link Broadcaster: /arm/robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 13.933 Oldest transform: 8.953 shoulder link Broadcaster: /arm/robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 13.933 Oldest transform: 8.953 forearm link Broadcaster: /arm/robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 13.933 Oldest transform: 8.953 wrist link Broadcaster: /arm/robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 dummy eef