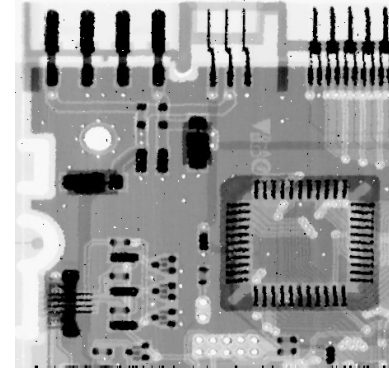
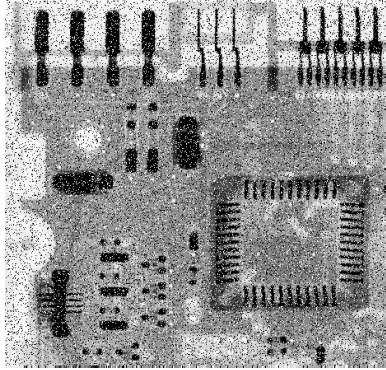
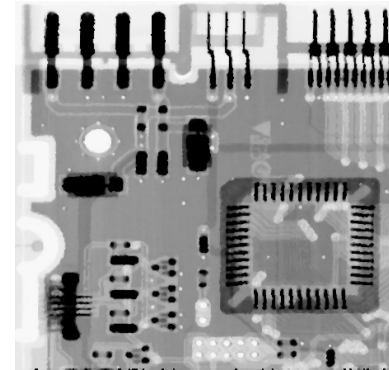
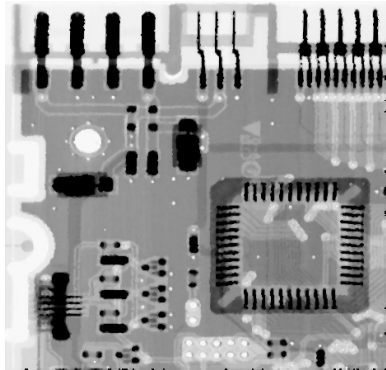


FIGURE 5.10 in textbook



(a) Image corrupted by salt and-pepper noise with probabilities $P_a=P_b=0.1$ (b) Result of one pass with a median filter of size 3×3



(c) Result of processing (b) with this filter.

(d) Result of processing (c) with this filter.