Optimization in the Loop

Implementing and Testing Scheduling Algorithms with SimuLTE

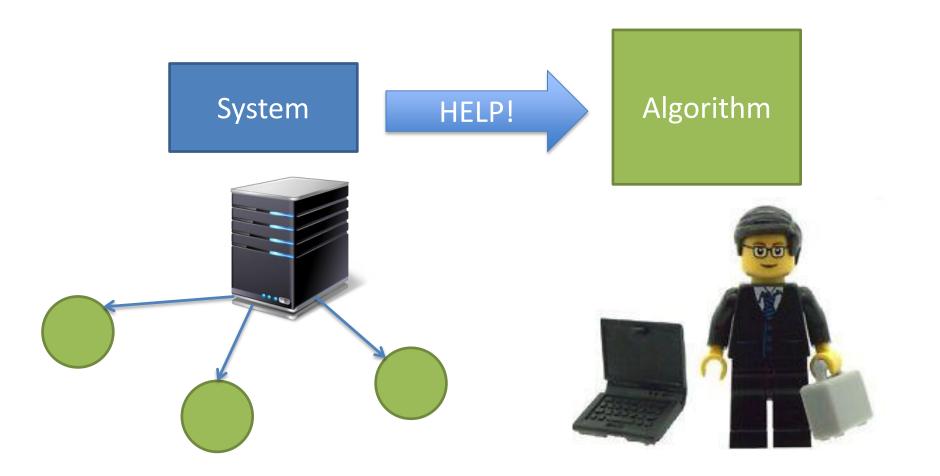
Antonio Virdis University of Pisa

- Prof. Giovanni Stea
- Giovanni Nardini

Outline

- Why Optimization
- Going into the Loop
- Methods
- Example

An everyday problem



Comparing Results

I'm better than you

Algorithm 1



system

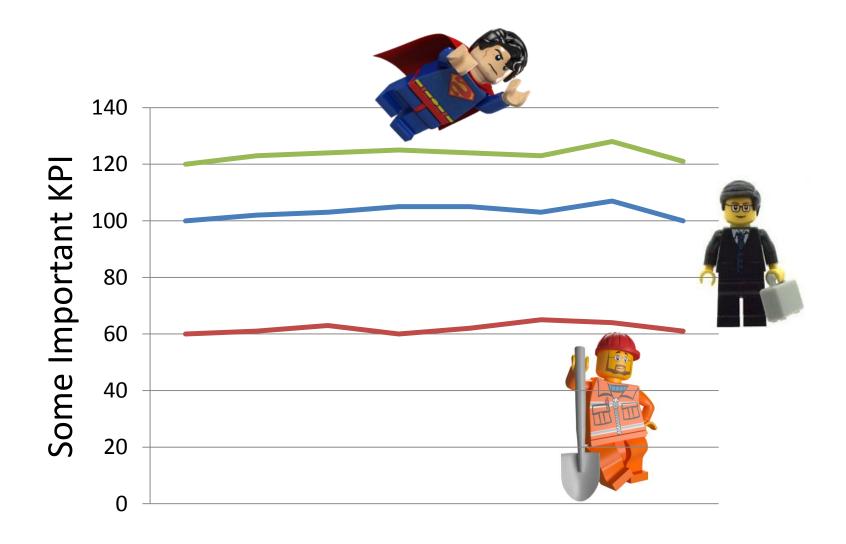
Algorithm 2



Comparing with the best



Comparing with the best



Comparing Results



I'm better than the optimum

system



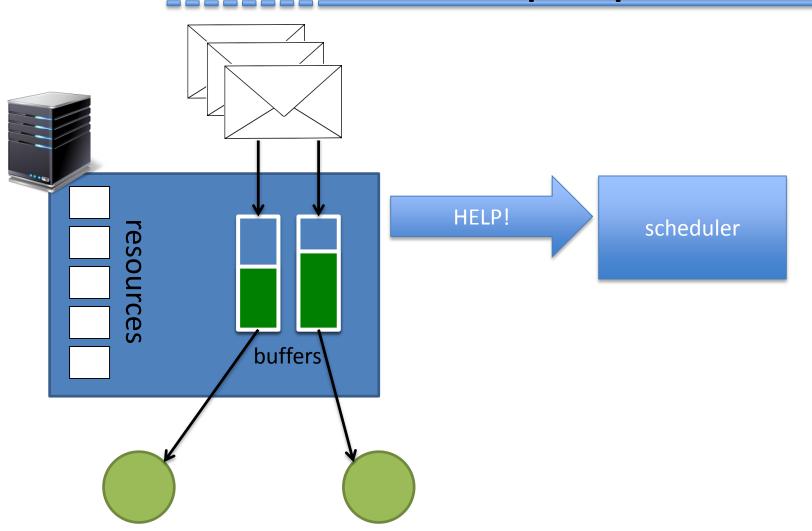
s t.

$$x_i + p_i \in M$$

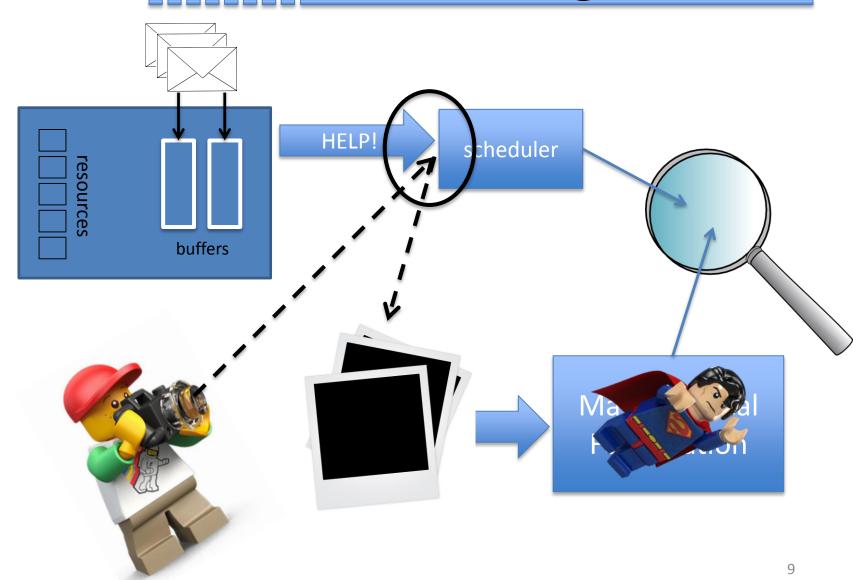
 $\max \mathring{a} = X_i$

• • •

A simple problem



Taking a Photo







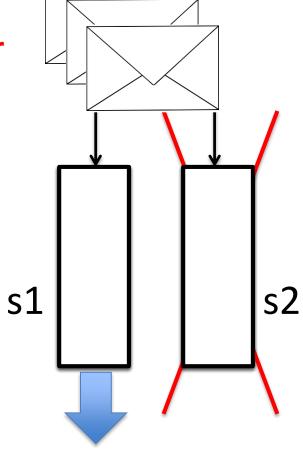
QUIZ

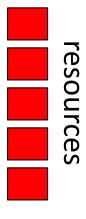
Quiz 1

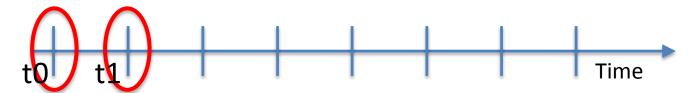


output speed

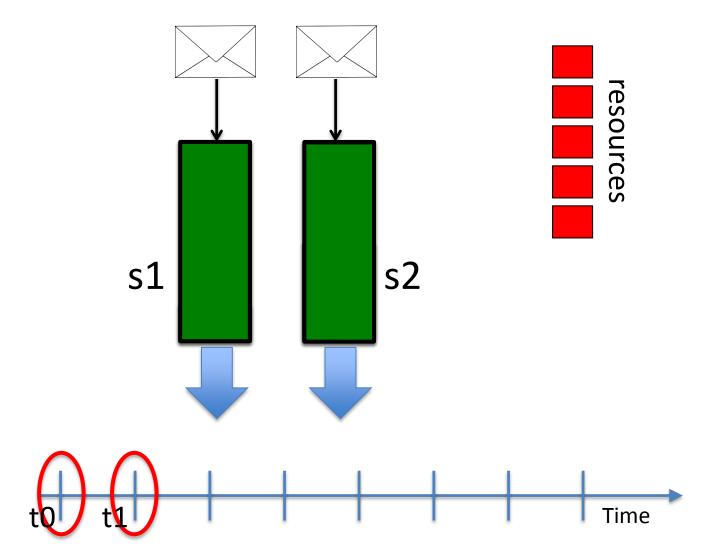
s1 > s2



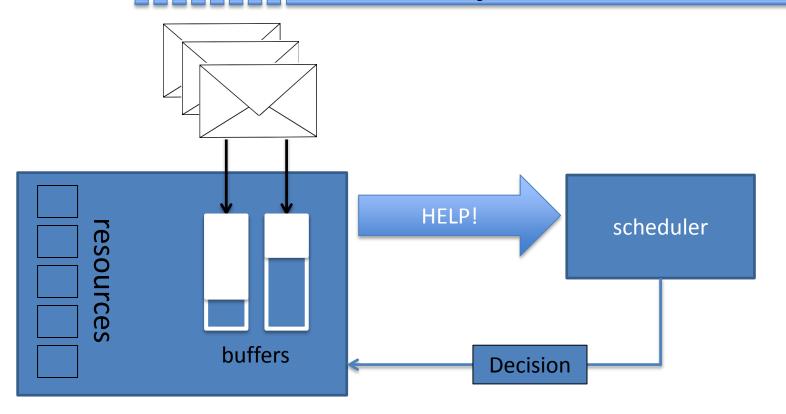




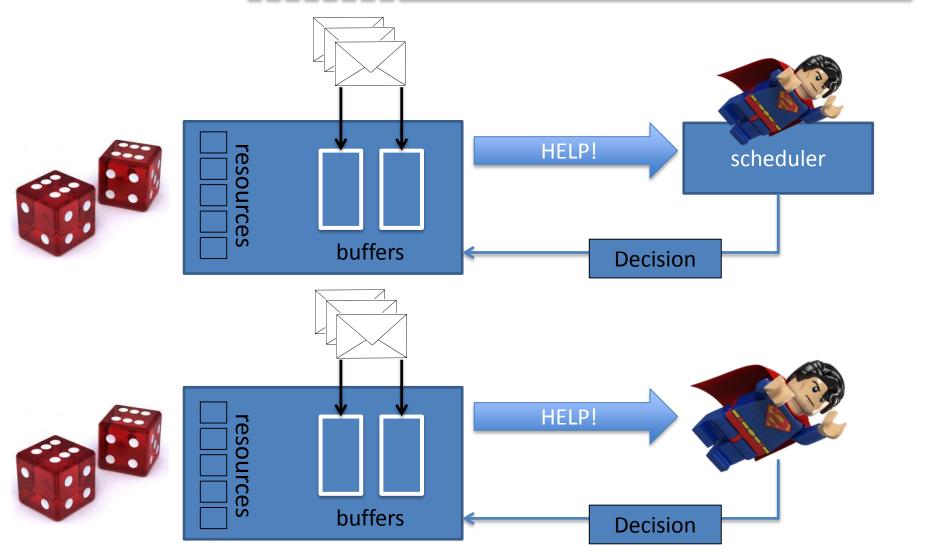
Finite Buffer: CBR



How does the system evolve



From outside to inside



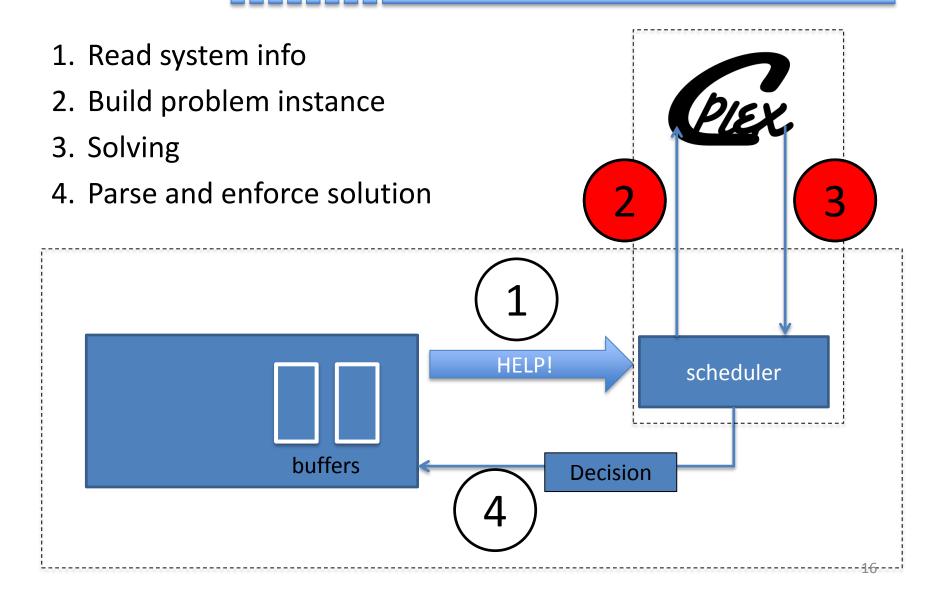
Going Into The Loop



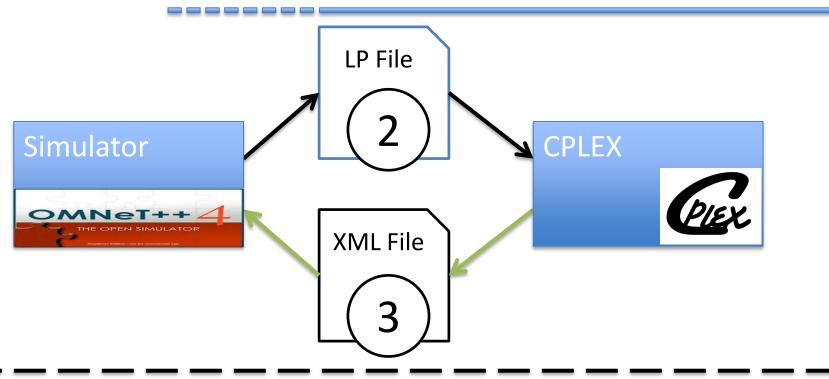




Overview



2 methods





LP file

²Building A problem File

$\max_{i} \bigwedge_{i}^{N} X_{i}$

```
for( i=0 ; i<N ; ++i )
   stream << "x" << i << " + ";</pre>
```

s t.

$$x_i + p_i \in M$$
 " i

• • •

```
for( i=0 ; i<N ; ++i )
```

XML file

(3) Reading Results

- XML Management
 - Built-in in OMNeT
 - Easy to implement manually

```
<variable
</pre>
index="0" value="0"/>
index="3" value="0"/>
index="4" value="141"/>
index="5" value="0"/>
index="5" value="0"/>
```

2° method: API

Idea: can we use CPLEX as an API?

- Callable Library: matrix-based C-written API

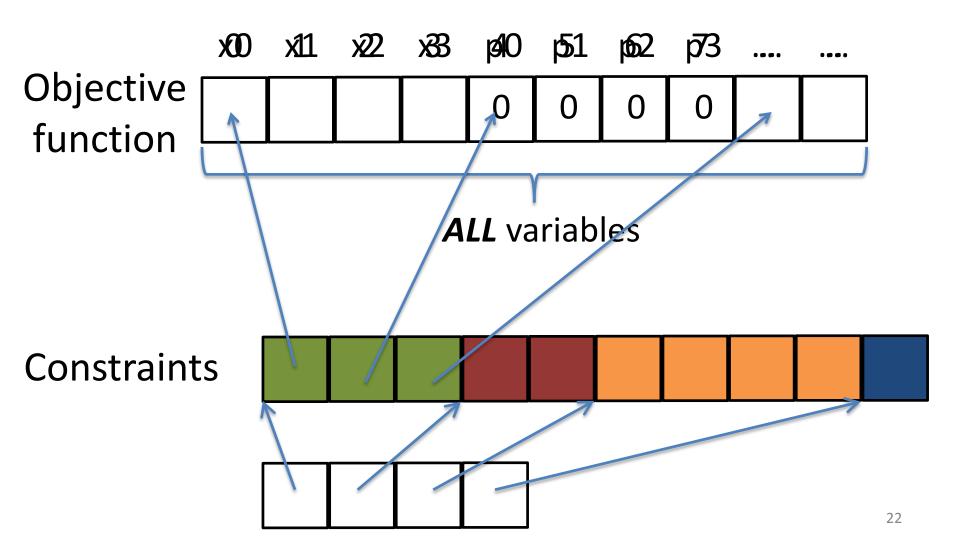
Concert Tecnology: a set of modeling objects
 (also) in C++

Including CPLEX

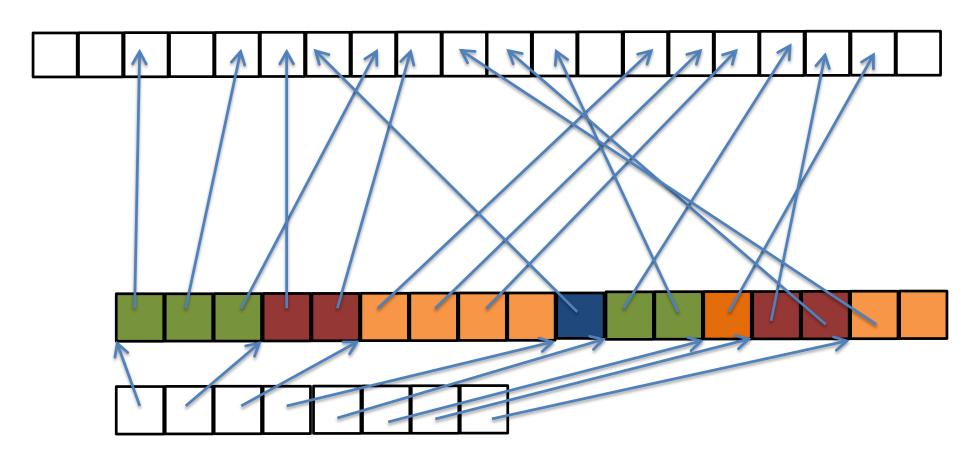
TELL OMNET:

- where the .h files are located
- where the dynamic libraries are located
- wich dynamic library to include
- enable the I_STD preprocessor macro
- Can be done via the *Project Properties* of OMNeT++

Matrix representation

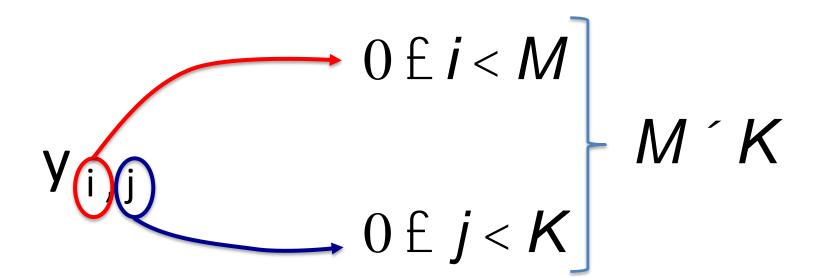


Matrix representation



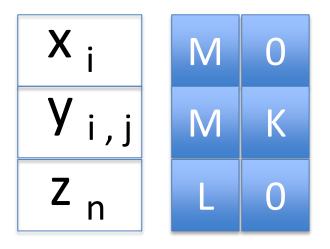
Custom C++ Interface

Generally variables are in the form:

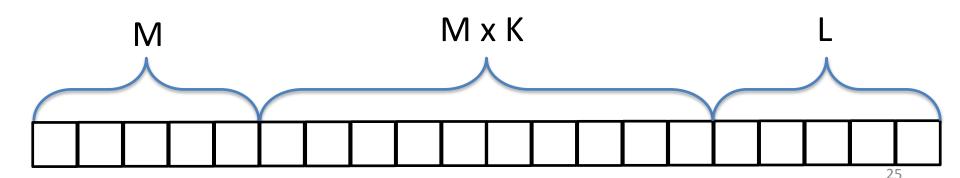


2° Method: variables

Name , #1st , #2nd

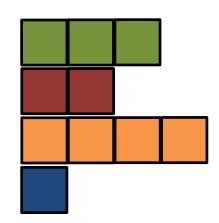


Access with local indexes

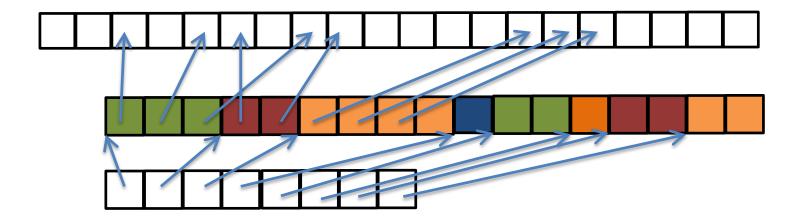


2° Method: constraints

Add constraints one by one usign *local indexes*



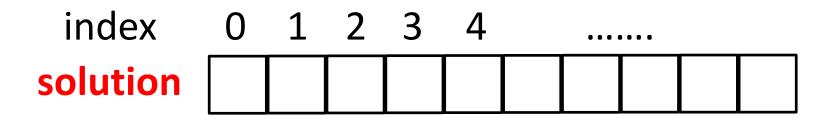
Build the problem at the end one-shot



Reading The Output

```
XML
```

```
<variable name="x0" index="0" value="51"/>
<variable name="x1" index="1" value="0"/>
<variable name="x2" index="2" value="141"/>
<variable name="x3" index="3" value="0"/>
<variable name="p0" index="4" value="141"/>
<variable name="p1" index="5" value="0"/>
```







$$X_i \ \widehat{l} \ \{0,1\}$$
 Binary values

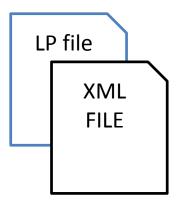


Quiz 2:

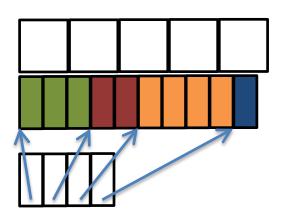
| x0 x1 x2 x3 | -> 0 -> 0 -> 1 | 2 | | <pre>> 0.0000000 > 0.0000000 1 0000000 0000000</pre> |
|------------------------|----------------------|------------------------|------------|---|
| x4 x5 x6 x7 | -> -> -> | Do not tr double va | | 000000 000000 000000 000000 |
| x8 x9 x10 x11 | -> 1 -> 1 -> 1 -> 0 | | <9 - <10 - | > 1.00000001 > 1.00000000 > 1.00000000 > 0.000000000 |

Pros and Cons

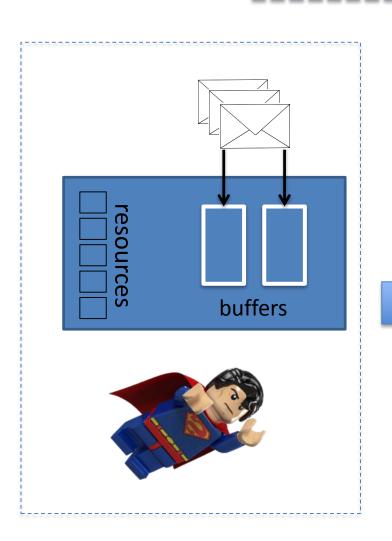
- Easy to build
- Generally slower



- Generally faster
- Requires API knowledge



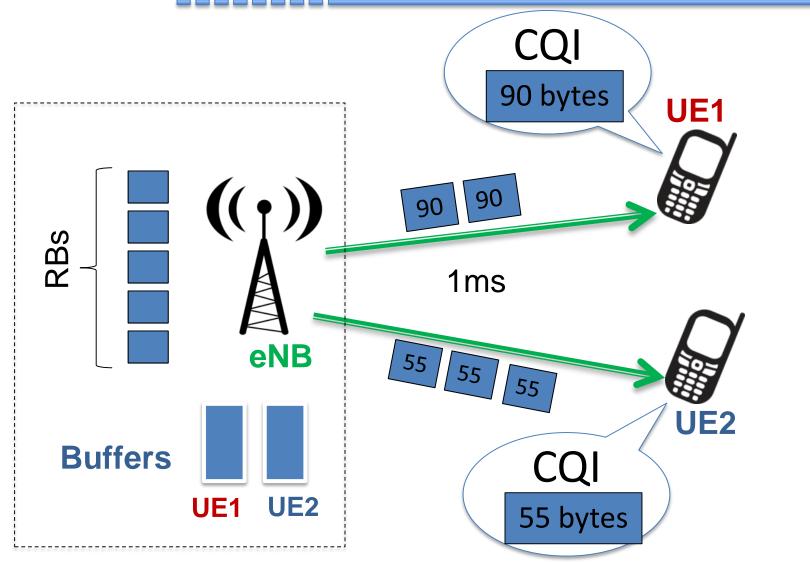
Optimization in SimuLTE



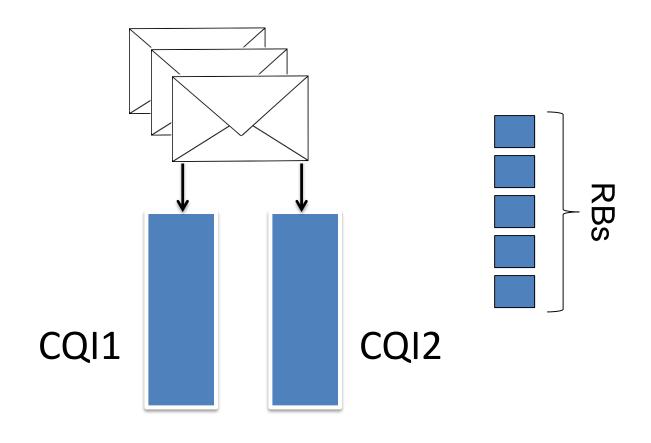




LTE

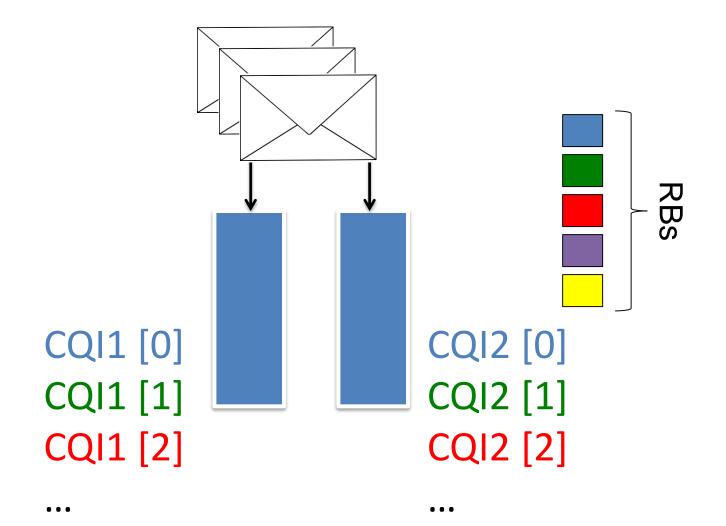


Resource allocation in LTE



Allocate **RB**s to **UE**s

Multi Band Scheduling

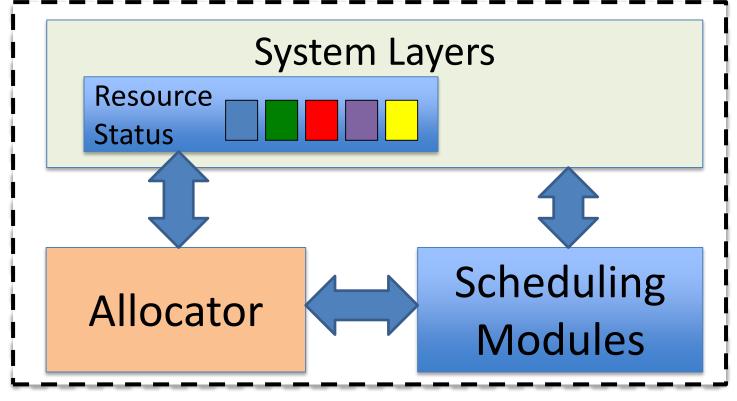


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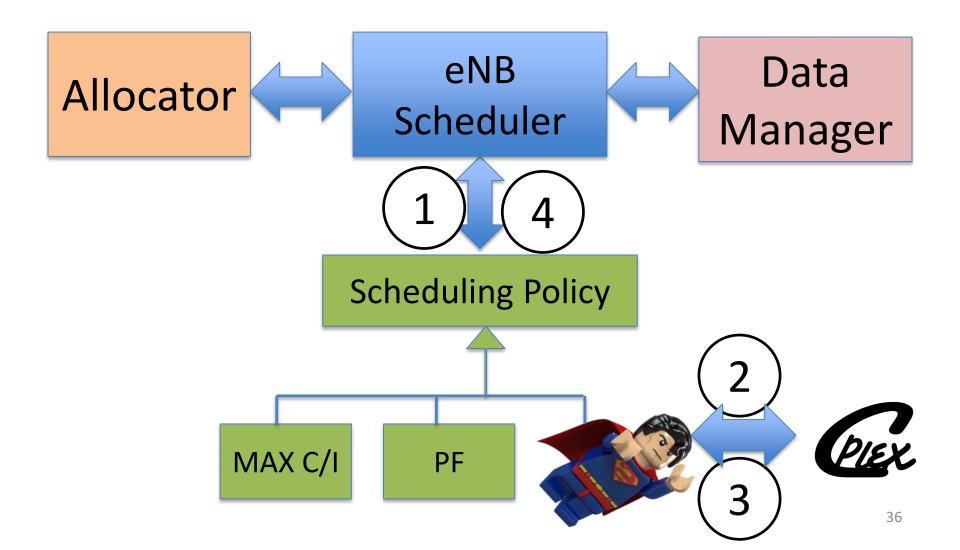
SimuLTE: Scheduling structure



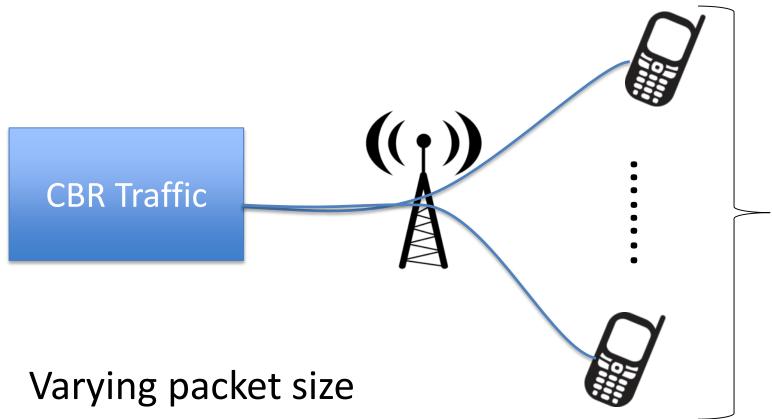
eNB



SimuLTE: Scheduler Hierarchy

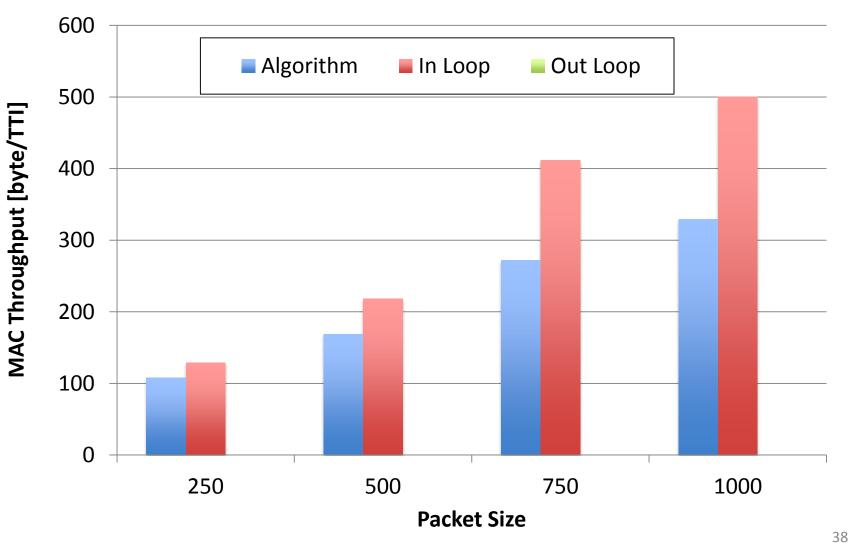


Simulation Scenario

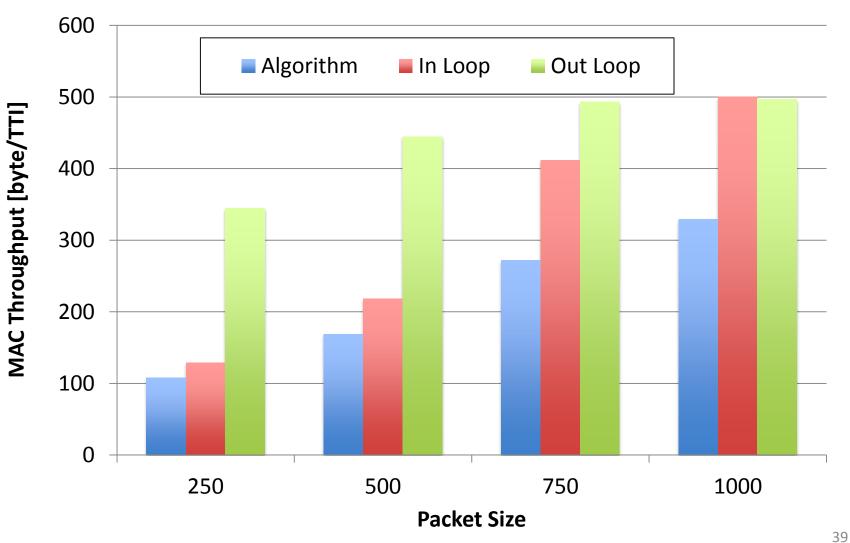


- Linear Mobility
- InLoop vs OutLoop

InLoop vs OutLoop



InLoop vs OutLoop





Any question while running for **dinner**?

Antonio Virdis

a.virdis@iet.unipi.it

simulte.com