

# QRAAT

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## Abstract

This could eventually be our doc for QRAAT. For now, this just outlines configuration stuff for the prototype system. Build this doc with pdflatex (sudo apt-get install pdflatex).

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## 1 System specifications

QRAAT has two main components: the remote field computers, which implement the initial signal detection, and the server, which collects data from the field computers for higher order processing. Here we outline the structure of these two components.

### 1.1 RMG Remote

Each field computer is configured to run the software defined radio. These systems have 32-bit dual core processors, 2 GB of ram, and 8 GB solid-state

persistent memory. They run stock Ubuntu Server 12.04. Along with the SDR implemented in GNU Radio, each is configured to run an ssh server, minicom, ntpdate, and the various other necessities.

The initial signal processing software outputs files corresponding to pulses with the extension `.det`. These are stored on a temporary file system in memory, located at `/tmp/ramdisk/det_files`. The pulse data files are stored in a directory structure according to the minute in which they were recorded, for example:

```
/tmp/ramdisk/det_files/2013/03/22/15/20/03439743.det
```

The file name gives the second it was created with millisecond precision, i.e. `SSUUUUUU.det`. This is the last step on the field computers; these files are then collected by the server.

Each site has a user called `rmg` whose password—you guessed it—is `rmg`.

The QRAAT software is located in `/home/rmg/QRAAT`. We've set it up as a git repository that pulls from the RMG Server. To update the software, ssh to the site, switch to this directory, and type `'git pull'`. You will be prompted for the server's password.

The transmitter file is `/home/rmg/tx.csv`.

## 1.2 RMG Server

Along with managing the field computers and collecting data, the server is responsible for calibration and triangulation. The `rmg` script allows us to power the computer and RMG module on and off, cycle the RMG module power, start and stop the software defined radio, update the field computer's transmitter file, and collect `.dets`. The server has a file called `sitelist.csv` that stores various parameters and the status of the RMG remotes:

1. *Name* - of the site,
2. *CompIP* - hostname or IP address of the remote computer,
3. *PowerIP* - hostname or IP address of the network addressable power source,
4. *CompOutlet* - outlet number of the computer,
5. *RxOutlet* - outlet number of the RMG receiver module,
6. *PowerType* - power source type, e.g. Netbooter, PingBrother, or WebPowerSwitch, and finally
7. *Status* - is the site up, down, or active (SDR is running).

Following is a sample of a typical `sitelist.csv` file. Fields can be skipped if they aren't applicable to a particular site (e.g. `site1` runs on the same machine as the server), but they must be delimited by commas:

```
name,comp_ip,power_ip,comp_outlet,rx_outlet,powertype,status
site0,10.0.0.55,10.0.0.56,1,2,pingbrother,active
site1,localhost,,,,active
site2,10.2.1.55,10.2.1.56,1,2,netbooter,down
site10,10.10.1.55,10.10.1.56,1,2,webpowerswitch,up
```

`rmg` uses RSA encryption for ssh instead of prompting the user for a password each time. This is important since some of `rmg`'s routines, such as `rmg fetch`, make many ssh calls. The RMG remotes store the public part of the key and the server the private part.

We keep a copy of the software repository on the server from which the remote ocmputers pull; the server copy pulls directly from github.

## 2 Configuration

### 2.1 Field computers

The field computers were configured by building and installing the software on one system, creating an image from its harddrive, and copying this image to the other sites. To create the image, we first installed a stock copy of Ubuntu Server 12.04 on a 7.5 GB partition, leaving 512 MB for swap. We configured no automatic updates, since these computers spend the majority of their time not connected to the internet. After booting the system and updating, the first thing to do is install the following packages via `apt-get`:

1. `git-core` - clone our software repository from github,
2. `openssh-server` - each field site needs to run an ssh daemon,
3. `minicom` - serial interface to RMG receiver module, and
4. `ntpd` - remote computers will be clock synced to the server via `ntpd`.

#### 2.1.1 Building and installing the software

Clone the online repository to get things going:

```
$ git clone github.com/QRAAT/QRAAT.git
```

The first thing to build is GNU Radio along with the UHD driver. For convenience, we provide a copy of the gnuradio build script written by Marcus Leech. Type

```
$ QRAAT/build-gnuradio -v all
```

to start downloading and building. This may take a few hours; however, you'll only need to do this once. When the build finishes, it will output a couple post-install tasks. Make sure you do these. Next, building and installing the QRAAT software is essentially the same procedure, though it will take less than two minutes:

```
$ QRAAT/build-rmg -v install
```

Before testing your build, we need to setup communication with the RMG receiver's PIC interface. First we add a rule to `udev`<sup>1</sup> to set permissions for `/dev/ttyUSB0`, the serial interface for the RMG receiver. Create a new file:

```
$ sudo vi /etc/udev/rules.d/101-serial-usb.rules
```

and type the following line:

```
KERNEL=="ttyUSB0", MODE="0666"
```

To verify that this worked, we'll try to communicate with the PIC via minicom. Open up the minicom configuration screen. Under *Serial port setup*, set *Serial Device* to `/dev/ttyUSB0`. Set *Bps/Par/Bits* to 9600 8N1. Lastly, set *Hardware/Software Flow Control* to No. Restart minicom. See if you're able to communicate with it by typing "?".

### 2.1.2 Post-configuration

We don't want the RMG remotes to save their pulse data locally to disk; the files will be stored locally in memory. For this reason, we need to set up a ramdisk to be created at start up. Add the following line to the end of `/etc/fstab` (be careful!):

```
tmpfs /tmp/ramdisk tmpfs nodev,nosuid,mode=1777,size=1024M 0 0
```

1 GB is reasonable since the field computers have 2 GBs of ram.

If linux shutdowns uncleanly, e.g. the site loses power, the GRUB bootloader will wait for user input before rebooting the operating system. This is bad for headless systems, so we need to configure GRUB to timeout in this situation. Add the following to `/etc/default/grub`:

```
GRUB_RECORDFAIL_TIMEOUT=2
```

Then type `sudo update-grub`.

Up until now, we've been using the field computer with a monitor, keyboard, and ethernet connection to the internet. The last thing we have to do is

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<sup>1</sup>`udev` is a common domain on GNU/Linux systems used to handle new devices when they're plugged in. For instance, when you installed the GNU Radio, rules were installed for the USRP—a hardware component of the RMG receiver—and the UHD driver.

configure the network interface so that we can access it over ssh without a head. In `/etc/network/interfaces`, comment out the default ethernet interface and add a static IP address:

```
# auto eth0
# iface eth0 inet dhcp
auto eth0
iface eth0 inet static
    address 10.20.1.55
    netmask 255.0.0.0
```

To connect to the computer directly through an ethernet cable, just setup a static IP address on the host system in the same subnet. See the section on networking for details.

The next thing to do is change the system's hostname. This needs to be changed in two places: `/etc/hostname` and `/etc/hosts`.

Lastly, since we will be managing the power of this system remotely, we want to be able to shutdown and reboot the computer without typing in a sudo password. Type

```
$ sudo visudo
```

```
[TODO]
```

### 2.1.3 Creating an image

The preceeding configuration is time-consuming, though not difficult. For configuring many sites, it's best to create an image from a fully configured system and copying this to other sites. The simplest way to do this is with a Ubuntu live-USB. Plug a monitor, keyboard, and mouse into the FitPC and boot a live copy of Ubuntu on a thumbdrive. Grab a terminal and make sure the harddrive is unmounted. ("mount | grep "sda". Verify that `/dev/sda` is indeed the harddrive.) Plug in an external harddrive or thumbdrive that can fit the 8 GB file we're about to create. Change the directory to the external drive and run:

```
$ dd if=/dev/sda of=qraat.img bs=4K
```

To copy the image, boot another computer in the same way. Plug in the external drive, change to its directory, and type

```
$ dd if=qraat.img of=/dev/sda bs=4K
```

Both of these commands should take about 30 minutes. Once you've finished copying the image, you'll want to edit the hostname and network interfaces as described in the preceeding section.

## 2.2 Networking

Here are the configuration steps that need to be taken as of this writing (27 March).

### 2.2.1 West campus prototype

We won't have networking for this implementation. As they are the ethernet interfaces of the RMG remotes are configured with a static IP address 10.<site\_no>.1.55 and netmask 255.0.0.0. To connect to it, the simplest thing to do is create an interface in network manager. *Network Manager* → *Edit Connections...*, in the *Wired* tab, choose *Add*. In *IPv4 Settings*, choose *Method = Manual*. Add an address like 10.253.1.55 with netmask 255.0.0.0. You should be good to go.

### 2.2.2 Quail Ridge

There are two configuration steps for each field computer. First, the ethernet interface needs to be configured to use the Qurinet router as its gateway. In `/etc/network/interfaces`, you'll find an interface that is commented out. Uncomment this and comment out the old one.

```
# Default interface in Qurinet
auto eth0
iface eth0 inet static
    address 10.20.1.55
    netmask 255.255.0.0
    gateway 10.20.1.1
```

The second part is to make sure the git repository is pointed to the right place. In `/home/rmg/QRAAT/.git/config`, you'll find a line that reads

```
url = christopher@10.253.1.55:work/QRAAT # change me!
```

Change this to the correct worker and directory and you're set!