



Camera Image

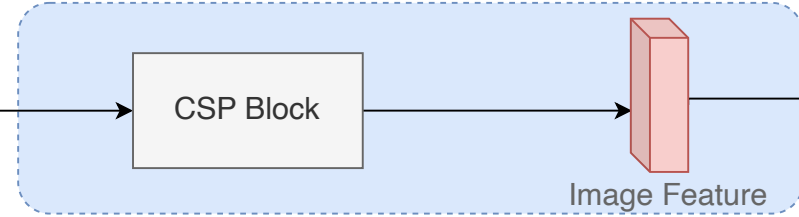
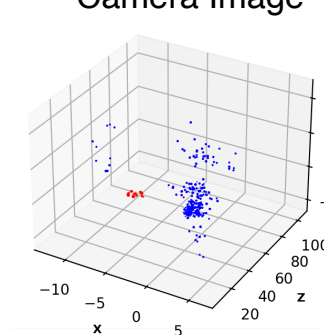
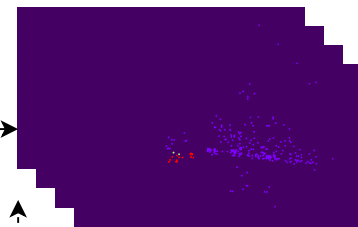


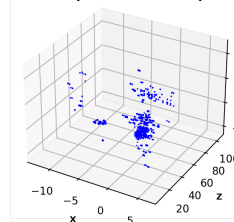
Image Stem Layer



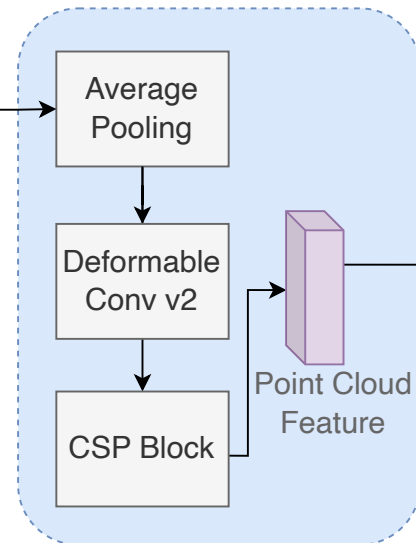
Radar Point Clouds
(1 frame)



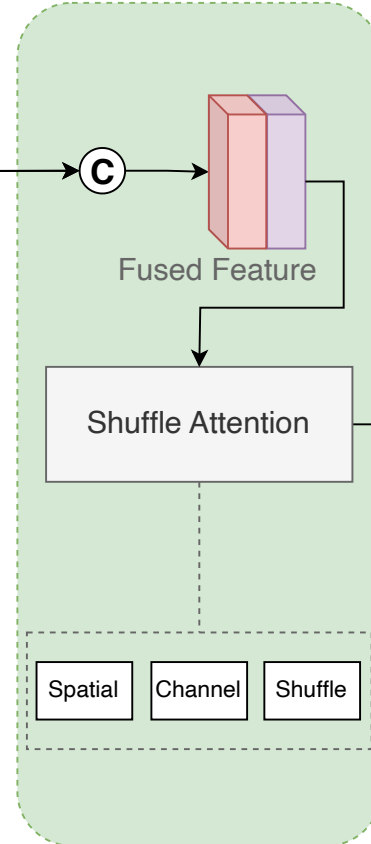
Radar REVP Map



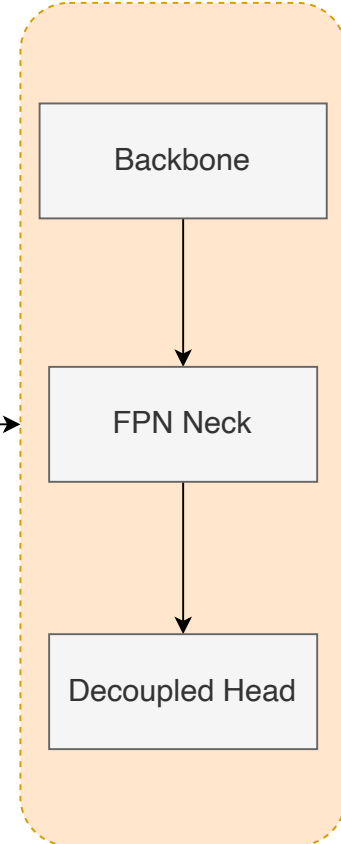
Radar Point Clouds
(3 frames)



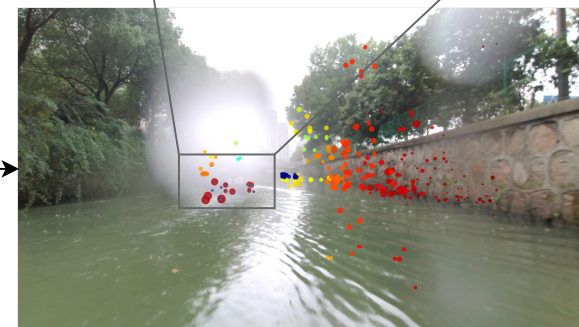
Point Cloud Stem Layer



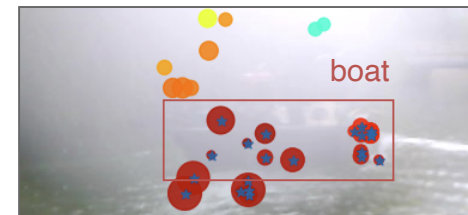
Feature Fusion



YOLOv8 Modules



Detection Results



boat