This is the command to get the latest release of QuESTlink:

```
(* Import["https://qtechtheory.org/questlink.m"]; *)
```

but this notebook will instead use a developmental version of QuESTlink (for nicer **DrawCircuit** rendering)

Import[

"https://raw.githubusercontent.com/QTechTheory/QuESTlink/hardware-profiles/ Link/QuESTlink.m"]

The next command downloads the pre-compiled single-thread simulator. For significantly faster multithreaded and GPU simulation, recompile QuESTlink (see guide here) and use **CreateLo-calQuESTEnv[**]

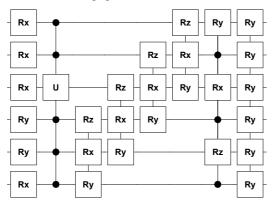
CreateDownloadedQuESTEnv[];

Preparing an ansatz

Here's how we could hard-code a 6 qubit, 12 parameter ansatz. The parameters are labelled $\theta[i]$ for convenience, but they could be any symbols we want $(\theta_i, \theta_i, \text{etc})$

Circuit[

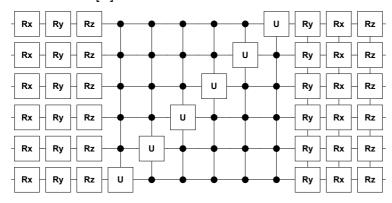
DrawCircuit[%]



More often, we wish to generate an ansatz programmatically.

$$\label{eq:nQ = 6; } \begin{split} nQ &= 6; \\ u &= Block\big[\{i=1\}, \; Flatten @ \left\{ \\ &\quad Table\big[g_{q-1}[\theta[i++]], \; \{q,\,nQ\}, \; \{g,\,\{Rx,\,Ry,\,Rz\}\}\big], \\ &\quad Table\big[C_{DeleteCases[Range[\theta,nQ-1],q]}\big[U_q\big[\left(\begin{matrix} Exp\big[\dot{\mathbf{i}}\,\theta[i++]\big] & 0 \\ 0 & 1 \end{matrix} \right) \big]\big], \; \{q,\,\theta,\,nQ-1\}\big], \\ &\quad Table\big[R[\theta[i++], \; Product[\sigma_{q-1},\,\{q,\,nQ\}]], \; \{\sigma,\,\{Y,\,X,\,Z\}\}\big]\big\}\big]; \\ n\theta &= Length[u]; \end{split}$$

DrawCircuit[u]



Since the parameters symbolic, we could study the ansatz operator analytically. Here's its first element, when every second parameter has value π .

$$\begin{array}{l} \text{u } \text{/.} \theta [_? \text{EvenQ}] \to \pi; \\ \text{CalcCircuitMatrix[%]} \text{// First // First} \\ - \text{i} \ \text{e}^{\frac{1}{2} \text{i} \theta [3] + \frac{1}{2} \text{i} \theta [9] + \frac{1}{2} \text{i} \theta [15] - \frac{1}{2} \text{i} \theta [27]} \cos \left[\frac{\theta [1]}{2}\right] \cos \left[\frac{\theta [5]}{2}\right] \\ \text{Cos} \left[\frac{\theta [7]}{2}\right] \cos \left[\frac{\theta [11]}{2}\right] \cos \left[\frac{\theta [13]}{2}\right] \cos \left[\frac{\theta [17]}{2}\right] \cos \left[\frac{\theta [25]}{2}\right] - \\ \text{i} \ \text{e}^{-\frac{1}{2} \text{i} \theta [3] - \frac{1}{2} \text{i} \theta [9] - \frac{1}{2} \text{i} \theta [15] - \frac{1}{2} \text{i} \theta [27]} \sin \left[\frac{\theta [1]}{2}\right] \sin \left[\frac{\theta [5]}{2}\right] \sin \left[\frac{\theta [7]}{2}\right] \\ \text{Sin} \left[\frac{\theta [11]}{2}\right] \sin \left[\frac{\theta [13]}{2}\right] \sin \left[\frac{\theta [17]}{2}\right] \sin \left[\frac{\theta [25]}{2}\right] \end{array}$$

Preparing a Hamiltonian

We could hard-code our own Hamiltonian...

$$h = .1 X_0 Y_1 Z_2 + .3 Y_0 X_2 - .4 Z_0 Z_1 Z_2;$$

CalcPauliSumMatrix[h] // Chop // MatrixForm

$$\begin{pmatrix} -0.4 & 0 & 0 & 0.-0.1 \, \dot{\mathbb{1}} & 0 & 0.-0.3 \, \dot{\mathbb{1}} & 0 & 0 \\ 0 & 0.4 & 0.-0.1 \, \dot{\mathbb{1}} & 0 & 0.+0.3 \, \dot{\mathbb{1}} & 0 & 0 & 0 \\ 0 & 0.+0.1 \, \dot{\mathbb{1}} & 0.4 & 0 & 0 & 0 & 0 & 0.-0.3 \, \dot{\mathbb{1}} \\ 0.+0.1 \, \dot{\mathbb{1}} & 0 & 0 & -0.4 & 0 & 0 & 0.+0.3 \, \dot{\mathbb{1}} & 0 \\ 0 & 0.-0.3 \, \dot{\mathbb{1}} & 0 & 0 & 0.4 & 0 & 0 & 0.+0.1 \, \dot{\mathbb{1}} \\ 0.+0.3 \, \dot{\mathbb{1}} & 0 & 0 & 0 & 0 & -0.4 & 0.+0.1 \, \dot{\mathbb{1}} & 0 \\ 0 & 0 & 0 & 0.-0.3 \, \dot{\mathbb{1}} & 0 & 0 & 0.-0.1 \, \dot{\mathbb{1}} & -0.4 & 0 \\ 0 & 0 & 0.+0.3 \, \dot{\mathbb{1}} & 0 & 0 & -0.1 \, \dot{\mathbb{1}} & 0 & 0.4 \end{pmatrix}$$

but more likely we'll want to produce one from a file of coefficients and Pauli strings. Here we download a 369-term 6-qubit Lithium Hydride Hamiltonian

```
h = GetPauliSumFromCoeffs[
                                                   "https://questlink.qtechtheory.org/demo_hamiltonian.txt"];
Length[h]
h[;; 30]
369
-6.52209 - 0.00168947 X_0 + 0.000335609 X_1 + 0.00233908 X_0 X_1 -
              0.00518865 \; X_2 - 2.32678 \times 10^{-6} \; X_0 \; X_2 - 0.00238276 \; X_1 \; X_2 - 0.000333484 \; X_0 \; X_1 \; X_2 + 0.00033484 \; X_0 \; X_1 \; X_2 + 0.00033484 \; X_0 \; X_1 \; X_2 + 0.00033484 \; X_0 \; X_1 \; X_2 + 0.0003484 \; X_0 \; X_1 \; X_2 + 0.000333484 \; X_0 \; X_1 \; X_2 + 0.0003484 \; X_0 \; X_1 \; X_1 \; X_2 + 0.0003484 \; X_0 \; X_1 \; X_1 \; X_2 + 0.0003484 \; X_0 \; X_1 \; X_1 \; X_2 + 0.0003484 \; X_0 \; X_1 \; X_1 \; X_2 + 0.0003484 \; X_1 \; X_2 \; X_2 \; X_2 + 0.0003484 \; X_1 \; X_2 \; X_2 \;
               \texttt{0.0561302} \; \texttt{X}_3 \; + \; \texttt{0.0000211588} \; \texttt{X}_0 \; \texttt{X}_3 \; + \; \texttt{0.0000198838} \; \texttt{X}_0 \; \texttt{X}_1 \; \texttt{X}_3 \; - \; \texttt{0.000133652} \; \texttt{X}_2 \; \texttt{X}_3 \; - \; \texttt{0.000133652} \; \texttt{X}_2 \; \texttt{X}_3 \; - \; \texttt{0.0000133652} \; \texttt{X}_3 \; + \; \texttt{0.0000198838} \; \texttt{X}_0 \; \texttt{X}_1 \; \texttt{X}_3 \; - \; \texttt{0.0000133652} \; \texttt{X}_2 \; \texttt{X}_3 \; - \; \texttt{0.0000198838} \; \texttt{X}_0 \; \texttt{X}_1 \; \texttt{X}_3 \; - \; \texttt{0.0000133652} \; \texttt{X}_2 \; \texttt{X}_3 \; - \; \texttt{0.0000198838} \; \texttt{X}_0 \; \texttt{X}_1 \; \texttt{X}_3 \; - \; \texttt{0.0000133652} \; \texttt{X}_2 \; \texttt{X}_3 \; - \; \texttt{0.0000133652} \; \texttt{0.0000133652} \; \texttt{0.0000133652} \; \texttt{0.0000136652} \; \texttt{0.0000136662} \; \texttt{0.00000166662} \; \texttt{0.0000016662} \; \texttt{0.0000016662} \; \texttt{0.0000016662} \; \texttt{0.00000166662} \; \texttt{0.00000
                 0.0000777401~X_2~X_5-0.0001908~X_1~X_2~X_5-0.00630859~X_3~X_5+0.0661688~X_4~X_5+0.0061688~X_4~X_5+0.0061688~X_4~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~X_5+0.0061688~
                  0.0000169999 \; X_0 \; X_4 \; X_5 \; + \; 0.00634842 \; X_0 \; X_1 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_2 \; X_4 \; X_5 \; - \; 0.000177071 \; X_5 \; X_6 \; X_6 \; - \; 0.000177071 \; X_5 \; X_6 \; X_6 \; - \; 0.000177071 \; X_5 \; - \; 0.00017071 \; X
                 0.00636179 \ X_1 \ X_2 \ X_4 \ X_5 + 0.00562722 \ X_3 \ X_4 \ X_5 - 0.000346402 \ Y_0 \ Y_1
```

We can determine its ground-state exactly, which we'll later compare to that which our variational algorithm estimates

```
gs = Min @ Eigenvalues @ CalcPauliSumMatrix[h]
-7.88074
```

Preparing quantum states

To perform numerical simulation of our ansatz, we need to create quantum registers, which are stored in the backend QuEST process.

```
\psi = CreateQureg[nQ];
InitPlusState[\psi];
GetQuregMatrix[\psi] // Chop
\{0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125,
     0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125,
     0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125,
     0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125,
      0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125
      0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125, 0.125
```

To apply our ansatz circuit to a state, we must replace the parameters with numerical values

```
ApplyCircuit[u /. \theta[_] \Rightarrow RandomReal[], \psi];
GetQuregMatrix[\psi]
\{0.0224731 + 0.111599 \pm, 0.00523535 - 0.0521917 \pm,
  -0.0111565 - 0.0767799 i, -0.00378012 + 0.00136288 i, 0.00123122 - 0.0731973 i,
  -0.00457615 + 0.00651081 i, 0.00978255 - 0.00067529 i,
  -0.0267522 - 0.0498707 i, -0.0235968 - 0.0586924 i, -0.0191137 - 0.00769477 i,
  -0.00438554 - 0.0141594 \pm, -0.00728107 - 0.0635589 \pm, -0.00530986 - 0.0091749 \pm,
  -0.0142068 - 0.0662965 \, i, -0.0103575 - 0.0461789 \, i, -0.00615036 - 0.134759 \, i,
  0.0153867 - 0.0281887 i, -0.0302696 + 0.0147383 i, -0.0151482 + 0.00568313 i,
  -0.0364413 - 0.0803933 \pm, -0.0157579 + 0.0110711 \pm, -0.0448814 - 0.0796178 \pm, -0.0110711 \pm, -0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.0144814 - 0.01448
  -0.0309596 - 0.0620335 \pm, -0.0692182 - 0.151883 \pm, -0.0319339 - 0.00383458 \pm,
  -0.0233075 - 0.111581 i, -0.0101306 - 0.0822589 i, -0.0323024 - 0.21812 i,
  -0.0189583 - 0.0844727 i, -0.0556178 - 0.218061 i, -0.0195894 - 0.167156 i,
  0.373976 + 0.176453 \pm, 0.0481885 - 0.116956 \pm, 0.0218496 - 0.0050421 \pm,
  0.0379506 - 0.0147816 i, -0.0269679 - 0.025903 i, 0.0375501 - 0.00818858 i,
  -0.0296966 - 0.0290688 \pm , -0.0344551 - 0.0168195 \pm , -0.0071038 - 0.0670466 \pm ,
  0.0193431 - 0.021617 i, -0.0122202 - 0.0328829 i, -0.0153121 - 0.016552 i,
  0.0102312 - 0.0824418 i, -0.01866 - 0.020663 i, 0.00323491 - 0.0849524 i,
  0.00804622 - 0.0662416 \pm 0.0994447 + 0.109923 \pm 0.0100959 - 0.000568641 \pm 0.000959 - 0.000568641 \pm 0.000959 - 0.000568641 \pm 0.000959 - 0.000568641 \pm 0.000959 - 0.000568641
  -0.0268904 - 0.0495882 i, -0.0245207 - 0.0355702 i, -0.0215095 - 0.099105 i,
  -0.0280162 - 0.0379397 \, i, -0.0312304 - 0.0979598 \, i, -0.0138876 - 0.0789094 \, i,
  0.17717 - 0.0295302 i, -0.0106074 - 0.0458956 i, -0.00641741 - 0.133966 i,
  0.00722081 - 0.101594 i, 0.237598 + 0.0403602 i, -0.00222075 - 0.103981 i,
  0.2454 - 0.000476521 \pm 0.171626 + 0.0649399 \pm 0.462416 - 0.101295 \pm
```

We must create a "working Qureg" **h \psi** to compute expected values. We see our starting state isn't especially close to the ground-state.

```
h\psi = CreateQureg[nQ];
CalcExpecPauliSum[\psi, h, h\psi]
-6.55243
```

We'll also need additional Quregs to keep track of our fixed input state $in\psi = |+\rangle$, and $n\theta$ derivative states $\mathbf{d}\psi[\mathbf{i}] = \left| \frac{\partial \psi}{\partial \theta[\mathbf{i}]} \right\rangle$ (where $\psi = \mathbf{u}(\theta) \ln \psi$)

```
in\psi = CreateQureg[nQ];
InitPlusState[inψ];
d\psi = CreateQuregs[nQ, n\theta];
```

Computing variational observables

Let's re-randomise the ansatz parameters.

```
v\theta = Table[\theta[i] \rightarrow RandomReal[], \{i, n\theta\}]
```

```
\{\theta[1] \rightarrow 0.302214, \theta[2] \rightarrow 0.701127, \theta[3] \rightarrow 0.250832,
 \theta[4] \rightarrow 0.366587, \theta[5] \rightarrow 0.184505, \theta[6] \rightarrow 0.134426, \theta[7] \rightarrow 0.2041,
 \theta \, [\, 8\, ] \, \rightarrow \, \textbf{0.869532} \, , \, \theta \, [\, 9\, ] \, \rightarrow \, \textbf{0.209075} \, , \, \theta \, [\, 10\, ] \, \rightarrow \, \textbf{0.221281} \, , \, \theta \, [\, 11\, ] \, \rightarrow \, \textbf{0.415592} \, ,
 \theta[12] \rightarrow 0.598776, \theta[13] \rightarrow 0.91903, \theta[14] \rightarrow 0.0748652, \theta[15] \rightarrow 0.824325,
  \theta[16] \rightarrow 0.0585614, \theta[17] \rightarrow 0.4362, \theta[18] \rightarrow 0.434674, \theta[19] \rightarrow 0.250115,
  \theta \text{[20]} \rightarrow \text{0.0151225, } \theta \text{[21]} \rightarrow \text{0.71593, } \theta \text{[22]} \rightarrow \text{0.408774, } \theta \text{[23]} \rightarrow \text{0.793994, }
  \theta[24] \rightarrow 0.943991, \theta[25] \rightarrow 0.711386, \theta[26] \rightarrow 0.455652, \theta[27] \rightarrow 0.0252188
```

We set each $\mathbf{d}\psi[\mathbf{i}] = \left| \frac{\partial \mathbf{u}}{\partial \theta[\mathbf{i}]} \mathbf{i} \mathbf{n}\psi \right\rangle$ for the given assignment of $\boldsymbol{\theta}$

CalcQuregDerivs[u, in ψ , v θ , d ψ];

The imaginary time 'tensor' is simply **Re**[$\langle \frac{\partial \psi}{\partial \theta[\mathbf{i}]} || \frac{\partial \psi}{\partial \theta[\mathbf{j}]} \rangle$]

$m = Re @ CalcInnerProducts[d\psi];$

m // Chop // MatrixForm

-						
0.25	0	-0.16127	0.25	0	-0.0458649	
0	0.25	0	0	0	0	
-0.16127	0	0.25	-0.16127	0	0.0295865	_
0.25	0	-0.16127	0.25	0	-0.0458649	
0	0	0	0	0.25	0	
-0.0458649	0	0.0295865	-0.0458649	0	0.25	− €
0.25	0	-0.16127	0.25	0	-0.0458649	
0	0	0	0	0	0	
-0.191007	0	0.123215	-0.191007	0	0.035042	_
0.25	0	-0.16127	0.25	0	-0.0458649	
0	0	0	0	0	0	
-0.100933	0	0.0651097	-0.100933	0	0.0185171	_
0.25	0	-0.16127	0.25	0	-0.0458649	
0	0	0	0	0	0	
-0.0186988	0	0.0120622	-0.0186988	0	0.00343048	− €
0.25	0	-0.16127	0.25	0	-0.0458649	
0	0	0	0	0	0	
-0.105625	0	0.0681363	-0.105625	0	0.0193779	-
-0.0512571	0.0213583	-0.0512571	-0.0512571	-0.00824045	0.0512571	− €
-0.167895	-0.000900317	0.167895	-0.167895	0.00233352	-0.167895	_
-0.0385019	-0.0124444	0.0385019	-0.0385019	0.00419934	0.00860778	− €
-0.114527	-0.0181217	0.114527	-0.114527	0.00807583	0.0226566	-
-0.14819	-0.0466023	0.14819	-0.14819	0.0293635	0.0392888	-
-0.0793218	-0.0358798	0.0793218	-0.0793218	0.015727	0.0224444	− €
-0.00813621	0.00265984	0	-0.00813621	0.00320796	0	- 0
0.039606	-0.0140054	0	0.039606	-0.00428338	0	e
0.0002884	0	-0.000447077	0.0002884	0	-0.00157201	0

We set $|\psi\rangle = u(\theta) |in\psi\rangle$, and $|h\psi\rangle = h |\psi\rangle$

ApplyCircuit[u /. $v\theta$, CloneQureg[ψ , $in\psi$]]; ApplyPauliSum[ψ , h, h ψ];

The energy gradient is then simply $\operatorname{Re}[\langle \psi | \mathbf{h} | \frac{\partial \psi}{\partial \theta [\mathbf{i}]} \rangle]$

$v = Re @ CalcInnerProducts[h\psi, d\psi];$

v // MatrixForm

```
-0.013409
-0.00539944
0.0379003
-0.013409
-0.0105197
0.0604042
 -0.013409
0.00468087
0.0250343
-0.013409
-0.0564997
0.00145499
-0.013409
-0.0671572
-0.0213131
-0.013409
-0.0855882
0.0411782
-0.0196398
-0.0389648
-0.010845
 0.022991
 0.0449788
0.000658498
0.00793236
```

-0.0329018 0.018517

A single iteration of imaginary time evolution would use these observables to update the parameters via $\mathbf{m} \Delta \theta = -\mathbf{v} \Delta \mathbf{t}$

```
\Delta\theta = \Delta t \text{ LinearSolve}[m, -v];
Δθ // MatrixForm
  -0.112232 \Delta t
  -0.247915 \Delta t
   1.37134 ∆t
  -0.112232 \Delta t
   0.191551 ∆t
   -1.42699 \Delta t
  -0.112232 \Delta t
  -0.0810106 \triangle t
  0.0389451 ∆t
  -0.112232 ∆t
   0.408794 ∆t
   -0.26508 ∆t
  -0.112232 ∆t
  0.501992 ∆t
 -0.0693181 \Delta t
  -0.112232 \ \triangle t
   0.741091 ∆t
  -0.583384 \Delta t
   1.50634 ∆t
   -1.15593 ∆t
  0.414318 ∆t
  -0.365748 \Delta t
  -0.275681 ∆t
  -0.706214 \Delta t
 -0.0677737 ∆t
   0.379378 ∆t
 -0.0555886 ∆t
```

hence the updated parameters, dependent on Δt , would be

```
v\theta[All, 2] += \Delta\theta
\{0.302214 - 0.112232 \, \Delta t, \, 0.701127 - 0.247915 \, \Delta t, \, 0.250832 + 1.37134 \, \Delta t, \, 0.250832 + 1.37144 \, \Delta t, \, 0.250824 \, \Delta 
     0.366587 - 0.112232 \Delta t, 0.184505 + 0.191551 \Delta t, 0.134426 - 1.42699 \Delta t,
     0.2041 - 0.112232 \Delta t, 0.869532 - 0.0810106 \Delta t, 0.209075 + 0.0389451 \Delta t,
      0.221281 - 0.112232 \Delta t, 0.415592 + 0.408794 \Delta t, 0.598776 - 0.26508 \Delta t,
      0.91903 - 0.112232 \, \triangle t, 0.0748652 + 0.501992 \, \triangle t, 0.824325 - 0.0693181 \, \triangle t,
      0.0585614 - 0.112232 \Delta t, 0.4362 + 0.741091 \Delta t, 0.434674 - 0.583384 \Delta t,
      0.250115 + 1.50634 \Delta t, 0.0151225 - 1.15593 \Delta t, 0.71593 + 0.414318 \Delta t,
      0.408774 - 0.365748 \Delta t, 0.793994 - 0.275681 \Delta t, 0.943991 - 0.706214 \Delta t,
      0.711386 - 0.0677737 \, \triangle t, \, 0.455652 + 0.379378 \, \triangle t, \, 0.0252188 - 0.0555886 \, \triangle t \}
```

Performing variational imaginary time

We simply repeat these steps to perform variational imaginary time minimization. We'll measure and record the energy at each iteration.

```
v\theta = Table[\theta[i] \rightarrow RandomReal[], \{i, n\theta\}];
\Delta t = .01;
nt = 100;
en = Table[
         (* compute imaginary time tensor *)
         CalcQuregDerivs[u, in\psi, v\theta, d\psi];
         m = Re @ CalcInnerProducts[d\psi];
         (* compute energy gradient *)
         ApplyCircuit[u /. v\theta, CloneQureg[\psi, in\psi]];
         ApplyPauliSum[\psi, h, h\psi];
         v = Re @ CalcInnerProducts[h\psi, d\psi];
         (* update parameters under imaginary time *)
         \Delta\theta = \Delta t \, Linear Solve[m, -v];
         v\theta[All, 2] += \Delta\theta;
         (* record the current energy *)
         CalcExpecPauliSum[\psi, h, h\psi],
         (* perform nt iterations *)
         nt
  ];
```

Here's how the energy evolved

ListLinePlot[en,

```
GridLines \rightarrow {{}, {{gs, Red}}},
      PlotRange → {gs, Automatic},
      AxesLabel → {"Iteration", "Energy"}]
 Energy
                                                  100 Iteration
            20
                     40
                               60
                                         80
-6.5
-7.0
-7.5
```

and the final energy, and its corresponding parameters

```
Row[{Last[en], " / ", gs}]
vθ
-7.27344 / -7.88074
\{\theta[1] \rightarrow 0.310389, \theta[2] \rightarrow 0.0898798, \theta[3] \rightarrow 1.48073, \theta[4] \rightarrow 0.0527977,
 \theta\texttt{[5]} \rightarrow \textbf{0.801902}, \, \theta\texttt{[6]} \rightarrow \textbf{0.262244}, \, \theta\texttt{[7]} \rightarrow \textbf{0.722303}, \, \theta\texttt{[8]} \rightarrow \textbf{1.53805},
 \theta[9] \to 0.913898, \theta[10] \to 0.26469, \theta[11] \to 1.53865, \theta[12] \to -0.483215,
 \theta[13] \rightarrow 0.0282503, \theta[14] \rightarrow 1.54369, \theta[15] \rightarrow 0.687921, \theta[16] \rightarrow 0.584671,
 \theta[17] \rightarrow 1.52099, \theta[18] \rightarrow 0.533196, \theta[19] \rightarrow 0.826099, \theta[20] \rightarrow -0.714602,
 \theta[21] \rightarrow -0.401971, \theta[22] \rightarrow 0.00317968, \theta[23] \rightarrow -0.189258,
 \theta[24] \rightarrow -0.157878, \theta[25] \rightarrow 1.5827, \theta[26] \rightarrow 1.0375, \theta[27] \rightarrow 0.231741
```