JavaScript is disabled on your browser.

* [Overview](http://docs.google.com/overview-summary.html)
* Package
* Class
* [Tree](http://docs.google.com/package-tree.html)
* [Index](http://docs.google.com/index-all.html)
* [Help](http://docs.google.com/help-doc.html)
* [Prev Package](http://docs.google.com/org/opencv/android/package-summary.html)
* [Next Package](http://docs.google.com/org/opencv/core/package-summary.html)
* [Frames](http://docs.google.com/index.html?org/opencv/calib3d/package-summary.html)
* [No Frames](http://docs.google.com/package-summary.html)
* [All Classes](http://docs.google.com/allclasses-noframe.html)

Package org.opencv.calib3d

* Class Summary

| Class | Description |
| --- | --- |
| [Calib3d](http://docs.google.com/org/opencv/calib3d/Calib3d.html) |  |
| [StereoBM](http://docs.google.com/org/opencv/calib3d/StereoBM.html) | Class for computing stereo correspondence using the block matching algorithm, introduced and contributed to OpenCV by K. |
| [StereoMatcher](http://docs.google.com/org/opencv/calib3d/StereoMatcher.html) | The base class for stereo correspondence algorithms. |
| [StereoSGBM](http://docs.google.com/org/opencv/calib3d/StereoSGBM.html) | The class implements the modified H. |

* [Overview](http://docs.google.com/overview-summary.html)
* Package
* Class
* [Tree](http://docs.google.com/package-tree.html)
* [Index](http://docs.google.com/index-all.html)
* [Help](http://docs.google.com/help-doc.html)
* [Prev Package](http://docs.google.com/org/opencv/android/package-summary.html)
* [Next Package](http://docs.google.com/org/opencv/core/package-summary.html)
* [Frames](http://docs.google.com/index.html?org/opencv/calib3d/package-summary.html)
* [No Frames](http://docs.google.com/package-summary.html)
* [All Classes](http://docs.google.com/allclasses-noframe.html)

Generated on 2021-04-02 03:15:03 / OpenCV 3.4.14