# Spiking Neural P system without delay simulator implementation using GPGPU

### **University of the Philippines Diliman:**

Francis Cabarle

Henry Adorna

**University of Seville:** 

Miguel Á. Martínez-del-Amor

### **Outline**

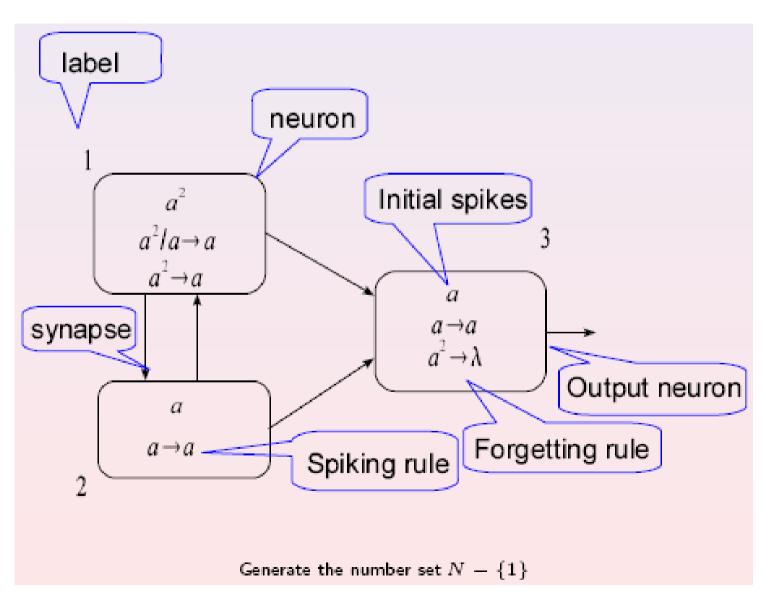
- Spiking Neural P systems (SNP)
- Matrix representation
- GPU computing
- Simulation algorithm
- Future work

### **SNP** system definition

$$\Pi = (O, \sigma_1, \ldots, \sigma_m, syn, in, out),$$

- 1)  $O = \{a\}$ , the singleton alphabet of spike a;
- 2)  $\sigma_i = (n_i, R_i), 1 \le i \le m$ , neurons, where:
  - 1) n<sub>i</sub>: initial number of spikes
  - 2) R<sub>i</sub>: a finite set of rules
    - 1) spiking rule:  $E/a^{c} \rightarrow a^{p}$ , E is a regular expression over a;
    - 2) forgetting rule:  $a^s \rightarrow \lambda$ , for  $s \ge 1$ ;
- 3) syn, synapses between neurons;
- 4) in, out  $\in \{1, 2, ..., m\}$ , the input and the output neurons.
- A global clock is used in the synchronous systems.

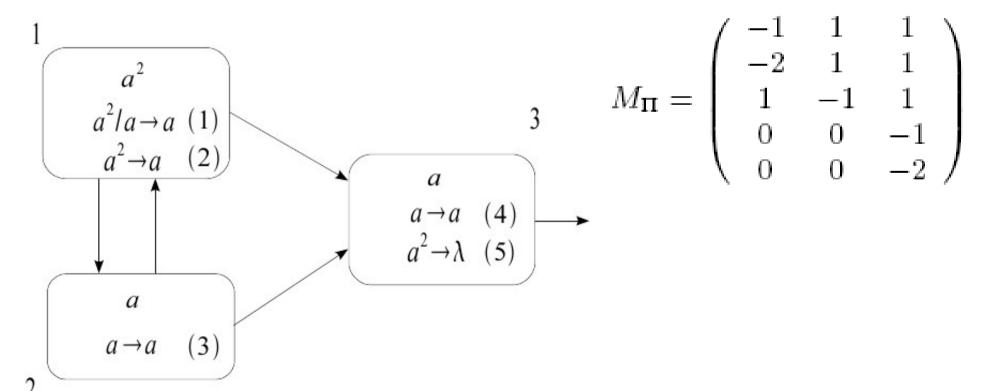
# Simple example of SNP



Xiangxiang Zeng

- Previous work by Xiangxiang Zeng et al. presented in:
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- Configuration vector  $(C_k)$ :  $C_0 = (2,1,1)$
- Spiking vectors (S<sub>k</sub>): (1,0,1,1,0),(0,1,1,1,0)
- Spiking transition matrix (M<sub>□</sub>):



Next configuration is calculated by:

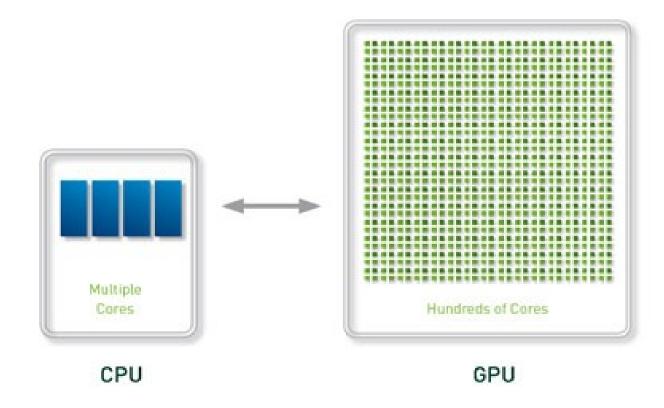
$$C_{k+1} = C_k + S_k * M_{\square}$$

- Matrix operations are very optimized on the GPU.
- A GPU based simulator for SNP system.



# **GPU** computing

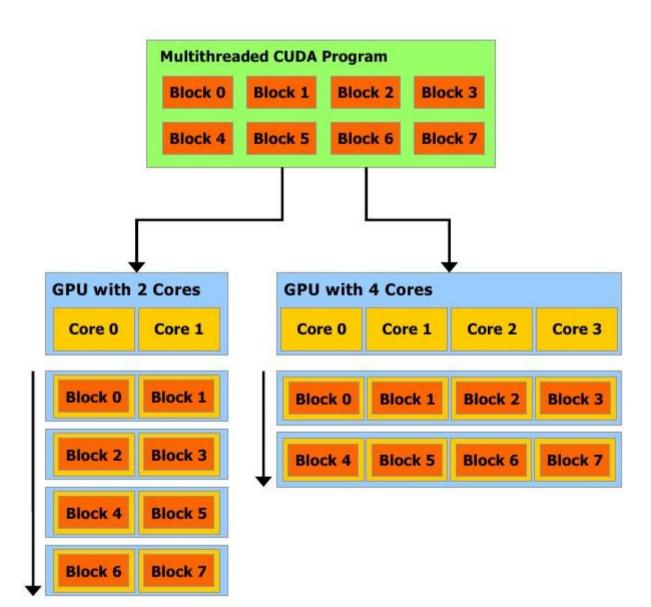
- GPGPU: techniques for using the GPU as a massively parallel co-processor.
- Host: the CPU vs Device: the GPU



# GPU computing: CUDA







# Simulation algorithm

- First version:
  - Rules of type  $E/a^c \rightarrow a^p$  where  $E=a^c$
  - Simulation of non-determinism
- Two stopping criteria:
  - Zero configuration vector
  - Repetition of configuration vectors
- Host side (python/C):
  - Read/write matrices and calculate spiking vectors
- Device side (CUDA):
  - Matrix addition and multiplication

# Simulation algorithm

- Overview:
  - I. Load inputs (Host):
    - Configuration vector: confVec
    - Transition matrix: M
    - Rule criteria: r
  - II. Calculate all spiking vectors (Host):
    - All possible spikVec from all configurations confVec
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  - IV. Repeat I, II and III until stopping criteria satisfies.

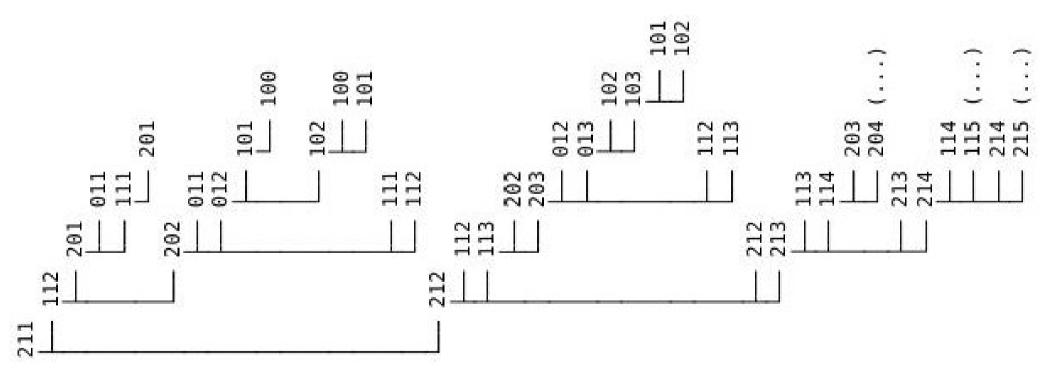
# Output of the simulator

The list of all possible configurations C<sub>k</sub>

```
allGenCk = ['2-1-1', '2-1-2', '1-1-2', '2-1-3', '1-1-3', '2-0-2', '2-0-1', '2-1-4', '1-1-4', '2-0-3', '1-1-1', '0-1-2', '0-1-1', '2-1-5', '1-1-5', '2-0-4', '0-1-3', '1-0-2', '1-0-1', '2-1-6', '1-1-6', '2-0-5', '0-1-4', '1-0-3', '1-0-0', '2-1-7', '1-1-7', '2-0-6', '0-1-5', '1-0-4', '2-1-8', '1-1-8', '2-0-7', '0-1-6', '1-0-5', '2-1-9', '1-1-9', '2-0-8', '0-1-7', '1-0-6', '2-1-10', '1-1-10', '2-0-9', '0-1-8', '1-0-7', '0-1-9', '1-0-8', '1-0-9']
```

# Output of the simulator

Tree of configurations:



### Future work

- To automatically generate the graphical tree of configurations.
- More general regular expressions.
- Simulate SNP system with delay.
- Backwards computation.
- Improve the CUDA code performance:
  - Byte-compiling the python code.
  - Use optimized algorithms for matrix multiplication.

### **THANKS FOR YOUR ATTENTION**

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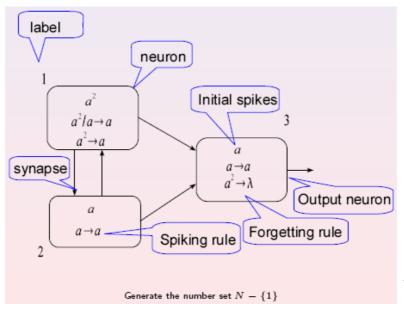
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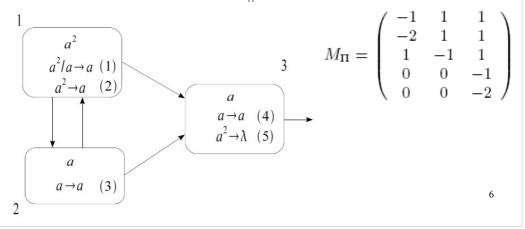
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- Spiking transition matrix (M<sub>n</sub>):



• Next configuration is calculated by:

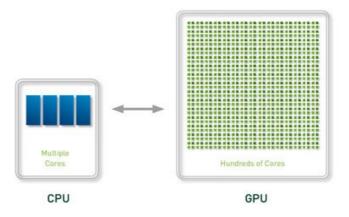
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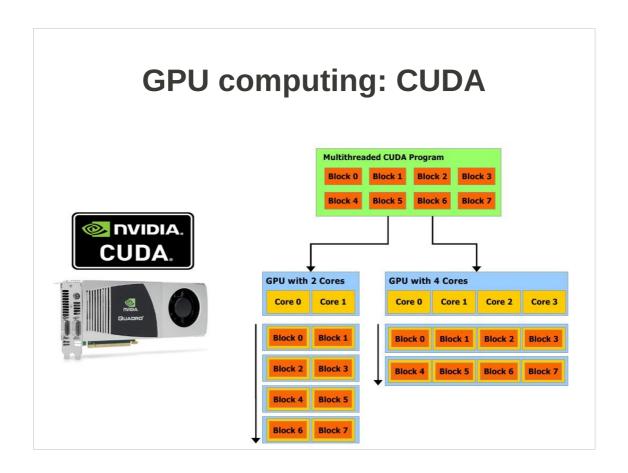
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- Device side (CUDA):
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- \* Repetition of configuration vectors => to prevent infinite loops.
- \* Host side (python/C):
- => Python (OOP language) for string manipulations.
- => produce All possible and valid spiking vectors
- \* Device side (CUDA):
- => outsourcing of highly repetitive work

### Simulation algorithm

- Overview:
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- II. => produce All possible and valid spiking vectors.
- $\Sigma = |\mathbf{r}|$ , total number of neurons

Ψ = |σV 1 ||σV 2 |...|σV n |, n ∈ N, n ≤ ∞ Where |σV n | means the total count of the number of rules in the nth neuron which satisfy the regular expresion E. Ψ gives the expected number of valid and possible Sks which should be produced in a given configuration.

#### **Output of the simulator**

• The list of all possible configurations  $C_k$ 

```
allGenCk = ['2-1-1', '2-1-2', '1-1-2', '2-1-3', '1-1-3', '2-0-2', '2-0-1', '2-1-4', '1-1-4', '2-0-3', '1-1-1', '0-1-2', '0-1-1', '2-1-5', '1-1-5', '2-0-4', '0-1-3', '1-0-2', '1-0-1', '2-1-6', '1-1-6', '2-0-5', '0-1-4', '1-0-3', '1-0-0', '2-1-7', '1-1-7', '2-0-6', '0-1-5', '1-0-4', '2-1-8', '1-1-8', '2-0-7', '0-1-6', '1-0-5', '2-1-9', '1-1-9', '2-0-8', '0-1-7', '1-0-6', '2-1-10', '1-1-10', '2-0-9', '0-1-8', '1-0-7', '0-1-9', '1-0-8', '1-0-9']
```

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# All possible Ck, else, infinite loops (as seen in the configuration tree next)

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• Tree of configurations:

#### **Future** work

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\* Use optimized algorithms for matrix multiplication => work on optimized algorithms for sparse matrix operations applied to GPGPUs

